

1 **Characterization of Errors in Satellite-based HCHO/NO<sub>2</sub>**  
2 **Tropospheric Column Ratios with Respect to Chemistry, Column to**  
3 **PBL Translation, Spatial Representation, and Retrieval**  
4 **Uncertainties**

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40  
41 **Abstract.**

42 The availability of formaldehyde (HCHO) (a proxy for volatile organic compound  
43 reactivity) and nitrogen dioxide (NO<sub>2</sub>) (a proxy for nitrogen oxides) tropospheric columns from  
44 Ultraviolet-Visible (UV-Vis) satellites has motivated many to use their ratios to gain some insights  
45 into the near-surface ozone sensitivity. Strong emphasis has been placed on the challenges that  
46 come with transforming what is being observed in the tropospheric column to what is actually in  
47 the planetary boundary layer (PBL) and near the surface; however, little attention has been paid to

48 other sources of error such as chemistry, spatial representation, and retrieval uncertainties. Here  
49 we leverage a wide spectrum of tools and data to quantify those errors carefully.

50 Concerning the chemistry error, a well-characterized box model constrained by more than  
51 500 hours of aircraft data from NASA's air quality campaigns is used to simulate the ratio of the  
52 chemical loss of  $\text{HO}_2+\text{RO}_2$  (LROx) to the chemical loss of  $\text{NO}_x$  (LNOx). Subsequently, we  
53 challenge the predictive power of  $\text{HCHO}/\text{NO}_2$  ratios (FNRs), which are commonly applied in  
54 current research, at detecting the underlying ozone regimes by comparing them to LROx/LNOx.  
55 FNRs show a strongly linear ( $R^2=0.94$ ) relationship to LROx/LNOx, but only in the **logarithmic**  
56 scale. Following the baseline (i.e.,  $\ln(\text{LROx}/\text{LNOx}) = -1.0 \pm 0.2$ ) with the model and mechanism  
57 (CB06, r2) used for segregating  $\text{NO}_x$ -sensitive from VOC-sensitive regimes, we observe a broad  
58 range of FNR thresholds ranging from 1 to 4. The transitioning ratios strictly follow a Gaussian  
59 distribution with a mean and standard deviation of 1.8 and 0.4, respectively. This implies that FNR  
60 has an inherent 20% standard error (1-sigma) resulting from not accurately describing the ROx-  
61 HOx cycle. We calculate high ozone production rates ( $\text{PO}_3$ ) dominated by large  $\text{HCHO} \times \text{NO}_2$   
62 concentration levels, a new proxy for the abundance of ozone precursors. The relationship between  
63  $\text{PO}_3$  and  $\text{HCHO} \times \text{NO}_2$  becomes more pronounced when moving towards  $\text{NO}_x$ -sensitive regions  
64 due to non-linear chemistry; our results indicate that there is fruitful information in the  
65  $\text{HCHO} \times \text{NO}_2$  metric that has not been utilized in ozone studies. The vast amount of vertical  
66 information on  $\text{HCHO}$  and  $\text{NO}_2$  concentration from the air quality campaigns enables us to  
67 parameterize the vertical shapes of FNRs using a second-order rational function permitting an  
68 analytical solution for an altitude adjustment factor to partition the tropospheric columns to the  
69 PBL region. We propose a mathematical solution to the spatial representation error based on  
70 modeling isotropic semivariograms. **Based on summertime averaged data**, Ozone Monitoring  
71 Instrument (OMI) loses 12% of spatial information at its native resolution with respect to a high-  
72 resolution sensor like TROPOspheric Monitoring Instrument (TROPOMI) ( $>5.5 \times 3.5 \text{ km}^2$ ). A  
73 pixel with a grid size of  $216 \text{ km}^2$  fails at capturing  $\sim 65\%$  of the spatial information in FNRs at a  
74 50 km length scale comparable to the size of a large urban center (e.g., Los Angeles). We  
75 ultimately leverage a large suite of in-situ and ground-based remote sensing measurements to draw  
76 the error distributions of daily TROPOMI and OMI tropospheric  $\text{NO}_2$  and  $\text{HCHO}$  columns. At a  
77 68% confidence interval (1 sigma), errors pertaining to daily TROPOMI observations, either  
78  $\text{HCHO}$  or tropospheric  $\text{NO}_2$  columns, should be above  $1.2-1.5 \times 10^{16} \text{ molec.cm}^{-2}$  to attain 20-30%  
79 standard error in the ratio. This level of error is almost non-achievable with OMI, given its large  
80 error in  $\text{HCHO}$ .

81 The satellite column retrieval error is the largest contributor to the total error (40-90%) in  
82 the FNRs. Due to a stronger signal in cities, the total relative error (<50%) tends to be mild,  
83 whereas areas with low vegetation and anthropogenic sources (e.g., Rocky Mountains) are  
84 markedly uncertain (>100%). Our study suggests that continuing development in the retrieval  
85 algorithm and sensor design and calibration is essential to be able to advance the application of  
86 FNRs beyond a qualitative metric.

## 87 1. Introduction

88 Accurately representing the near-surface ozone ( $\text{O}_3$ ) sensitivity to its two major precursors,  
89 nitrogen oxides ( $\text{NO}_x$ ) and volatile organic compounds (VOCs), is an imperative step in  
90 understanding non-linear chemistry associated with ozone production rates in the atmosphere.  
91 While it is often tempting to characterize an airshed as  $\text{NO}_x$  or VOC-sensitive, both conditions are  
92 expected as VOC-sensitive (ozone production rates sensitive to VOC) conditions near  $\text{NO}_x$   
93 sources transition to  $\text{NO}_x$ -sensitive (ozone production rates sensitive to  $\text{NO}_x$ ) conditions

94 downwind as NO<sub>x</sub> dilutes. Thus, reducing the footprint of ozone production can mostly be  
95 achieved through NO<sub>x</sub> reductions. VOCs are key to determining both the location and peak in  
96 ozone production, which varies non-linearly to the NO<sub>x</sub> abundance. Thus, knowledge of the relative  
97 levels of NO<sub>x</sub> and VOCs informs the trajectory of ozone production and expectations of where  
98 peak ozone will occur as emissions change. While a large number of surface stations regularly  
99 monitor the near-surface ambient nitrogen dioxide (NO<sub>2</sub>) concentrations, the measurements of  
100 several VOCs with different reactivity rates with respect to hydroxyl (OH) are not routinely  
101 available. As such, our knowledge of where and when ozone production rates are elevated, and  
102 their quantitative dependence on a long list of ozone precursors, is fairly limited, except for  
103 observationally-rich air quality campaigns. This limitation has prompted several studies, such as  
104 Sillman et al. (1990), Tonnesen and Dennis (2000a,b), and Sillman and He (2002), to investigate  
105 if the ratio of certain measurable compounds can diagnose ozone regimes meaning if the ozone  
106 production rate is sensitive to NO<sub>x</sub> (i.e., NO<sub>x</sub>-sensitive) or VOC (i.e., VOC-sensitive). Sillman  
107 and He (2002) suggested that H<sub>2</sub>O<sub>2</sub>/HNO<sub>3</sub> was a robust, measurable ozone indicator as this ratio  
108 could well describe the chemical loss of HO<sub>2</sub>+RO<sub>2</sub> (LRO<sub>x</sub>) to the chemical loss of NO<sub>x</sub> (LNO<sub>x</sub>)  
109 controlling the O<sub>3</sub>-NO<sub>x</sub>-VOC chemistry (Kleinman et al., 2001). Nonetheless, both H<sub>2</sub>O<sub>2</sub> and  
110 HNO<sub>3</sub> measurements are limited to a few spatially-sparse air quality campaigns.

111 Formaldehyde (HCHO) is an oxidation product of VOCs, and its relatively short lifetime  
112 (~1-9 hr) makes the location of its primary and secondary sources rather identifiable (Seinfeld and  
113 Pandis, 2006; Fried et al., 2020). Fortunately, monitoring HCHO abundance in the atmosphere has  
114 been a key goal of many Ultraviolet-Visible (UV-Vis) viewing satellites for decades (Chance et  
115 al., 1991; Chance et al., 1997; Chance et al., 2000; González Abad et al., 2015; De Smedt et al.,  
116 2008, 2012, 2015, 2018, 2021) with reasonable spatial coverage. Additionally, the strong  
117 absorption of NO<sub>2</sub> in the UV-Vis range has permitted measurements of NO<sub>2</sub> columns from space  
118 (Martin et al., 2002; Boersma et al., 2004, 2007, 2018).

119 Advancements in satellite remote-sensing of these two key compounds have encouraged  
120 many studies to elucidate if the ratio of HCHO/NO<sub>2</sub> (hereafter FNR) could be a robust ozone  
121 indicator (Tonnesen and Dennis, 2000b; Martin et al., 2004; Duncan et al., 2010). Most studies  
122 using the satellite-based FNR columns attempted to provide a qualitative view of the underlying  
123 chemical regimes (e.g., Choi et al., 2012; Choi and Souri, 2015a,b; Jin and Holloway, 2015; Souri  
124 et al., 2017; Jeon et al., 2018; Lee et al., 2021). Relatively few studies (Duncan et al., 2010; Jin et  
125 al., 2017; Schroeder et al., 2017; Souri et al., 2020) have carefully tried to provide a quantitative  
126 view of the usefulness of the ratio. For the most part, the inhomogeneous vertical distribution of  
127 FNR in columns has been emphasized. Jin et al. (2017) and Schroeder et al. (2017) showed that  
128 differing vertical shapes of HCHO and NO<sub>2</sub> can cause the vertical shape of FNR not to be  
129 consistent throughout the troposphere leading to a variable relationship between what is being  
130 observed from the satellite and what is actually occurring in the lower atmosphere. Jin et al. (2017)  
131 calculated an adjustment factor to translate the column to the surface using a relatively coarse  
132 global chemical transport model. The adjustment factor showed a clear seasonal cycle stemming  
133 from spatial and temporal variability associated with the vertical sources and sinks of HCHO and  
134 NO<sub>2</sub>, in addition to the atmospheric dynamics. In a more data-driven approach, Schroeder et al.  
135 (2017) found that the detailed differences in the boundary layer vertical distributions of HCHO  
136 and NO<sub>2</sub> lead to a wide range of ambiguous ratios. Additionally, ratios were shown to shift on high  
137 ozone days, raising questions regarding the value of satellite averages over longer timescales. Our  
138 research aims to put together an integrated and data-driven mathematical formula to translate the

139 tropospheric column to the planetary boundary layer (PBL), exploiting the abundant aircraft  
140 measurements available during ozone seasons.

141 Using observationally-constrained box models, Souri et al. (2020) demonstrated that there  
142 was a fundamentally inherent uncertainty related to the ratio originating from the chemical  
143 dependency of HCHO on NO<sub>x</sub> (Wolfe et al., 2016). In VOC-rich (poor) environments, the  
144 transitioning ratios from NO<sub>x</sub>-sensitive to VOC-sensitive occurred in larger (smaller) values than  
145 the conventional thresholds defined in Duncan et al. (2010) due to an increased (dampened) HCHO  
146 production induced by NO<sub>x</sub>. To account for the chemical feedback and to prevent a wide range of  
147 thresholds on segregating NO<sub>x</sub>-sensitive from VOC-sensitive regions, Souri et al. (2020)  
148 suggested using a first-order polynomial matched to the ridgeline in P(O<sub>3</sub>) isopleths. Their study  
149 illuminated the fact that the ratio suffers from an inherit chemical complication. However, Souri  
150 et al. (2020) did not quantify the error, and their work was limited to a subset of atmospheric  
151 conditions. To challenge the predictive power of FNR from a chemistry perspective, we will take  
152 advantage of a large suite of datasets to make maximum use of varying meteorological and  
153 chemical conditions.

154 Not only are satellite-based column measurements unable to resolve the vertical  
155 information of chemical species in the tropospheric column, but they are also unable to resolve the  
156 horizontal spatial variability due to their spatial footprint. The larger the footprint is, the more  
157 horizontal information is blurred out. For instance, Souri et al. (2020) observed a substantial spatial  
158 variance (information) in FNR columns at the spatial resolution of 250×250 m<sup>2</sup> observed by an  
159 airborne sensor over Seoul, South Korea. It is intuitively clear that a coarse-resolution sensor  
160 would lose a large degree of spatial variance (information). This error, known as the spatial  
161 representation error, has not been studied with respect to FNR. We will leverage what we have  
162 learned from Souri et al. (2022), which modeled the spatial heterogeneity in discrete data using  
163 geostatistics, to quantify the spatial representation error in the ratio over an urban environment.

164 A longstanding challenge is to have a reliable estimate of the satellite retrieval errors of  
165 tropospheric column NO<sub>2</sub> and HCHO. Significant efforts have been made recently to assemble,  
166 analyze, and estimate the retrieval errors for two key satellite sensors, TROPOspheric Monitoring  
167 Instrument (TROPOMI) and Ozone Monitoring Instrument (OMI), using various in-situ  
168 measurements (Verhoelst et al., 2021; Vigouroux et al., 2020, Choi et al., 2020; Laughner et al.,  
169 2019; Zhu et al., 2020). This study will exploit paired comparisons from some of these new studies  
170 to propagate individual uncertainties in HCHO and NO<sub>2</sub> to the FNR errors.

171 The overarching science goal of this study is to address the fact that the accurate diagnosis  
172 of surface O<sub>3</sub> photochemical regimes is impeded by numerous uncertainty components, which will  
173 be addressed in the current paper, and can be classified into four major categories: i) inherent  
174 uncertainties associated with the approach of FNRs to diagnose local O<sub>3</sub> production and sensitivity  
175 regimes, ii) translation of tropospheric column satellite retrievals to represent PBL- or surface-  
176 level chemistry, iii) spatial representativity of ground pixels of satellite sensors, and iv)  
177 uncertainties associated with satellite-retrieved column-integrated concentrations of HCHO and  
178 NO<sub>2</sub>. We will address all of these sources of uncertainty using a broad spectrum of data and tools.

179 Our paper is organized into the following sections. Section 2 describes the chemical box  
180 model setup and data applied. Sections 3.1 to 3.4 deal with the chemistry aspects of FNRs and  
181 show the results from a box model. Section 3.5 introduces a data-driven framework to transform  
182 the FNR tropospheric columns to the PBL region. Section 3.6 offers a new way to quantify the  
183 spatial representation error in satellites. Section 3.7 deals with the satellite error characterization

184 and its impacts on the ratio. Section 3.8 summarizes the fractional contribution of each error to the  
185 combined error. Finally, Section 4 provides a summary and conclusions of the study.

## 186 **2. Photochemical Box Modeling and Aircraft Data Used**

187 To quantify the uncertainty of FNR from a chemistry perspective and to obtain several  
188 imperative parameters, including the calculated ozone production rates and the loss of  $\text{NO}_x$  ( $\text{LNO}_x$ )  
189 and  $\text{RO}_x$  ( $\text{LRO}_x$ ), we utilize the Framework for 0-D Atmospheric Modeling (F0AM) v4 (Wolfe et  
190 al., 2016). We adopt the Carbon Bond 6 (CB06, r2) chemical mechanism, and heterogenous  
191 chemistry is not considered in our simulations. The model is initialized with the measurements of  
192 several compounds, many of which constrain the model by being held constant for each timestep  
193 (see Table 1).

194 Figure 1 shows the map of data points from Deriving Information on Surface Conditions  
195 from Column and Vertically Resolved Observations Relevant to Air Quality (DISCOVER-AQ)  
196 Baltimore-Washington (2011), DISCOVER-AQ Houston-Texas (2013), DISCOVER-AQ  
197 Colorado (2014), and Korea United States Air Quality Study (KORUS-AQ) (2016).  
198 Meteorological inputs come from the observed pressure, temperature, and relative humidity. The  
199 measurements of photolysis rates are not available for all photolysis reactions; therefore, our initial  
200 guess of those rates comes from a look-up-table populated by the National Center for Atmospheric  
201 Research (NCAR) Tropospheric Ultraviolet And Visible (TUV) model calculations. These values  
202 are a function of solar zenith angle, total ozone column density, surface albedo, and altitude. We  
203 set the total ozone column and the surface albedo to fixed numbers of 325 (Dobson) DU and 0.15,  
204 respectively. The initial guess is then corrected by applying the ratio of observed photolysis rates  
205 of  $\text{NO}_2 + \text{hv}$  ( $j\text{NO}_2$ ) and/or  $\text{O}_3 + \text{hv}$  ( $j\text{O}^1\text{D}$ ) to the calculated ones to all  $j$ -values (i.e., wavelength-  
206 independent). If both observations of  $j\text{NO}_2$  and  $j\text{O}^1\text{D}$  are available, the correction factor is  
207 averaged. The KORUS-AQ campaign is the only one that provides  $j\text{O}^1\text{D}$  measurements; therefore,  
208 the use of the wavelength-independent correction factor based on the ratio of observed to  
209 calculated  $j\text{NO}_2$  values for all  $j$ -value is a potential source of error in the model especially when  
210 aerosols are present. The model calculations are based on the observations merged to a temporal  
211 resolution varying from 10 to 15 seconds. Each calculation was run for five consecutive days with  
212 an integration time of 1 hour to approach diel steady state. We test the number of solar cycles  
213 against ten days on the KORUS-AQ setup and observe no noticeable difference in simulated OH  
214 and HCHO (Figure S1), indicating that five solar cycles suffice. Some secondarily-formed species  
215 must be unconstrained for the purpose of model validation. Therefore, the concentrations of several  
216 secondarily-formed compounds, such as HCHO and PAN, are unconstrained. Nitric oxide (NO)  
217 and  $\text{NO}_2$  are also allowed to cycle while their sum (i.e.,  $\text{NO}_x$ ) is constrained. Because the model  
218 does not consider various physical loss pathways, including deposition and transport, which vary  
219 by time and space, we oversimplify their physical loss through a first-order dilution rate set to  
220  $1/86400-1/43200 \text{ s}^{-1}$  (i.e., 24- or 12-hr lifetime), which in turn prevents relatively long-lived  
221 species from accumulating over time. Our decision on unconstraining HCHO, a pivotal compound  
222 impacting the simulation of HOx, may introduce some systematic biases in the simulation of  
223 radicals determining ozone chemistry (Schroeder et al., 2020). Therefore, to mitigate the potential  
224 bias in HCHO, we set the dilution factor to maintain the campaign-averaged bias in the simulated  
225 HCHO with respect to observations of less than 5%. However, it is essential to recognize that  
226 HCHO can fluctuate freely for each point measurement because the dilution constraint is set to a  
227 fixed value for an individual campaign. Each time tag is independently simulated, meaning we do  
228 not initialize the next run using the simulated values from the previous one; this in turn, permits  
229 parallel computation. Regarding the KORUS-AQ campaign where HOx observations were

available, we only ran the model for data points with HO<sub>x</sub> measurements. Similar to Souri et al. (2020), we filled gaps in VOC observations with a bilinear interpolation method with no extrapolation allowed. In complex polluted atmospheric conditions such as that over Seoul, South Korea, Souri et al. (2020) observed that this simple treatment yielded comparable results with respect to the NASA LaRC model (Schroeder et al. 2020), which incorporated a more comprehensive data harmonization. Table 1 lists the major configuration along with the observations used for the box model.

Several parameters are calculated based on the box model outputs. LRO<sub>x</sub> is defined through the sum of primarily radical-radical reactions:

$$LRO_x = k_{HO_2+HO_2}[HO_2]^2 + \sum k_{RO_{2i}+HO_2}[RO_{2i}][HO_2] + \sum k_{RO_{2i}+RO_{2i}}[RO_{2i}]^2 \quad (1)$$

where  $k$  is the reaction rate constant. LNO<sub>x</sub> mainly occurs via the NO<sub>2</sub>+OH reaction:

$$LNO_x = k_{OH+NO_2+M}[OH][NO_2][M] \quad (2)$$

where M is a third body. We calculate P(O<sub>3</sub>) by subtracting the ozone loss pathways dictated by HO<sub>x</sub> (HO+HO<sub>2</sub>), NO<sub>2</sub>+OH, O<sub>3</sub> photolysis, ozonolysis, and the reaction of O(<sup>1</sup>D) with water vapor from the formation pathways through the removal of NO via HO<sub>2</sub> and RO<sub>2</sub>:

$$P(O_3) = k_{HO_2+NO}[HO_2][NO] + \sum k_{RO_{2i}+NO}[RO_{2i}][NO] - k_{OH+NO_2+M}[OH][NO_2][M] - P(RONO_2) - k_{HO_2+O_3}[HO_2][O_3] - k_{OH+O_3}[OH][O_3] - k_{O(^1D)+H_2O}[O(^1D)][H_2O] - L(O_3) + alkenes \quad (3)$$

### 3. Results and Discussion

#### 3.1. Box Model Validation

There are uncertainties associated with the box model (e.g., Brune et al., 2022; Zhang et al., 2021; Lee et al., 2021), which can be attributed to: i) the lack of inclusion of physical processes such as entrainment/detrainment and diffusion, ii) discounting the heterogeneous chemistry, iii) invalid assumption of the diel steady state in areas close to large emission sources or in photochemically less active environments (Thornton et al., 2002; Souri et al., 2021), iv) errors in the chemical mechanism and v) errors in the measurements. These limitations necessitate a thorough validation of the model using unconstrained observations. While models have been known for a long time not to be 100% accurate (Box, 1976), it is important to characterize whether the model can effectively represent reality. For instance, if the simulated HCHO is poorly correlated with observations and/or displayed large magnitude biases, it will be erroneous to assume that the sources of HCHO, along with relevant chemical pathways, are appropriate. It is important to acknowledge that the VOC constraints for these model calculations are incomplete, especially for the DISCOVER-AQ campaigns, which lacked comprehensive VOC observations. Nevertheless, we will show that the selected VOCs are sufficient to reproduce a large variance (>70%) in observed HCHO.

We diagnose the performance of the box model by comparing the simulated values of five compounds to observations: HCHO, NO, NO<sub>2</sub>, PAN, hydroperoxyl radical (HO<sub>2</sub>), and OH. Figure 2 depicts the scatterplot of the comparisons along with several statistics. HCHO observations are usually constrained in box models to improve the representation of HO<sub>2</sub> (Schroeder et al., 2017;

264 Souri et al., 2020; Brune et al., 2022); however, this constraint may mask the realistic  
265 characterization of the chemical mechanism with respect to the treatment of VOCs. Additionally,  
266 it is important to know if the sources of HCHO are adequate. Therefore, we detach the model from  
267 this constraint to perform a more fair and stringent validation.

268 Concerning HCHO, our model does have considerable skill at reproducing the variability  
269 of observed HCHO ( $R^2=0.73$ ). To evaluate if this agreement is accidentally caused by the choice  
270 of the dilution factor and to identify if our VOC treatment is inferior compared to the one adopted  
271 in the NASA LaRC (Schroeder et al., 2021), we conducted three sets of sensitivity tests for the  
272 KORUS-AQ campaign, including ones with and without considering a dilution factor and another  
273 one without  $\text{HNO}_3$  and  $\text{H}_2\text{O}_2$  constraints (Figure S2). The lack of consideration of a dilution factor  
274 results in no difference in the variance in HCHO captured by our model ( $R^2=0.81$ ). Our model  
275 without the dilution factor is still skillful at replicating the magnitude of HCHO with less than 12%  
276 bias. This is why the optimal dilution factor for each campaign is within 12 hr to 24 hr, which is  
277 not different from other box modeling studies (e.g., Brune et al., 2022; Miller and Brune, 2022).  
278 We observe no difference in the simulated HCHO when  $\text{HNO}_3$  and  $\text{H}_2\text{O}_2$  values are not  
279 constrained. The unconstrained NASA LaRC setup oversampled at 10-sec frequency captures 86%  
280 variance in the measurements, only slightly (6%) outperforming our result. However, the  
281 unconstrained NASA LaRC setup greatly underestimates the magnitude of HCHO compared to  
282 our model results.

283 The model performs well with regard to the simulation of NO ( $R^2=0.89$ ) and  $\text{NO}_2$  ( $R^2=0.99$ )  
284 in the logarithmic scale. Immediately evident is the underestimation of NO in highly polluted  
285 regions, contrary to an overestimation in clean ones. This discrepancy leads to an underestimation  
286 (overestimation) of NO/ $\text{NO}_2$  in polluted (clean) regions. The primary drivers of NO/ $\text{NO}_2$  are  $\text{jNO}_2$   
287 and  $\text{O}_3$ , both of which are constrained in the model. What can essentially deviate the partitioning  
288 between NO and  $\text{NO}_2$  from that of observations in polluted areas is the assumption of the diel  
289 steady state, which is rarely strictly valid where measurements are close to large emitters. The  
290 overestimation of NO in low  $\text{NO}_x$  areas is often blamed on the lack of chemical sink pathways of  
291 NO in chemical mechanisms (e.g., Newland et al., 2021). The relatively reasonable performance  
292 of PAN ( $R^2=0.63$ ) is possibly due to constraining some of the oxygenated VOCs, such as  
293 acetaldehyde. Xu et al. (2021) observed a strong dependency of PAN concentrations on NO/ $\text{NO}_2$   
294 ratios. Smaller NO/ $\text{NO}_2$  ratios are usually associated with larger PAN mixing ratios because NO  
295 can effectively remove peroxyacetyl radicals. We observe an overestimated PAN (0.27 ppbv),  
296 possibly due to an underestimation of NO/ $\text{NO}_2$ . Moreover, we should not rule out the impact of  
297 the first-order dilution factor, which was only empirically set in this study. For instance, if we  
298 ignore the dilution process for the KORUS-AQ campaign, the bias of the model in terms of PAN  
299 will increase by 33% resulting in poor performance ( $R^2=0.40$ ) (Figure S3). We notice that this  
300 poor performance primarily occurs for high altitude measurements where PAN is thermally stable  
301 (Figure S4); therefore, this does not impact the majority of rapid atmospheric chemistry occurring  
302 in the lower troposphere, such as the formation of HCHO. Schroeder et al. (2020) found that proper  
303 simulation of PAN in the polluted PBL during KORUS-AQ required a first-order loss rate based  
304 on thermal decomposition at the average PBL temperature, which was more realistic than the  
305 widely varying local PAN lifetimes associated with temperature gradients between the surface and  
306 the top of the PBL. This solution is computationally equivalent to the dilution rate used in this  
307 study.

308 KORUS-AQ was the only field campaign providing OH and  $\text{HO}_2$  measurements.  
309 Concerning  $\text{HO}_2$ , former studies such as Schroeder et al. (2017), Souri et al. (2020), and Brune et

310 al. (2022) managed to reproduce HO<sub>2</sub> mixing ratios with R<sup>2</sup> ranging from 0.6 to 0.7. The  
311 performance of our model (R<sup>2</sup>=0.66) is similar to these past studies, with nearly negligible biases  
312 (<1%). One may argue that the absence of the HO<sub>2</sub> uptake by aerosols is contributing to some of  
313 the discrepancies we observe in the HO<sub>2</sub> comparison. Brune et al. (2022) provided compelling  
314 evidence showing that considering the HO<sub>2</sub> uptake made their results significantly inconsistent  
315 with the observations suggesting that the HO<sub>2</sub> uptake might have been inconsequential during the  
316 campaign. Our model manages to reproduce 64% of the variance of observed OH outperforming  
317 the simulations presented in Souri et al. (2020) and Brune et al. (2022) by >10%. The slope (=  
318 1.03) is not too far from the identity line, indicating that our box model systematically  
319 overestimates OH by 0.62 10<sup>6</sup> cm<sup>-3</sup>. This may be attributed to a missing OH sink in the mechanism  
320 or the lack of inclusion of some VOCs. A sensitivity test involving removing the first-order  
321 dilution process demonstrates that the simulation of HOx is rather insensitive to this parameter  
322 (Figure S5). In general, the model performance is consistent, or outperforms, results from recent  
323 box modeling studies, indicating that it is at least roughly representative of the real-world ozone  
324 chemistry and sensitivity regimes.

### 325 **3.2. Can HCHO/NO<sub>2</sub> ratios fully describe the HOx-ROx cycle?**

326 Kleinman et al. (2001) demonstrated that LROx/LNOx is the most robust ozone regime  
327 indicator. Thus, the predictive power of FNR at detecting the underlying chemical conditions can  
328 be challenged by comparing FNR to LROx/LNOx. Ideally, if they show a strong degree of  
329 correspondence (i.e., R<sup>2</sup>=1.0), we can confidently say that FNR can realistically portray the  
330 chemical regimes. Any divergence of these two quantities indicates the inadequacy of the FNR  
331 indicator. Souri et al. (2020) observed a strong linear relationship between the logarithmic  
332 transformed FNR and those of LROx/LNOx. Our analysis in this study will be based on the  
333 simulated values to ensure that the relationship is coherent based on a realization from the well-  
334 characterized box model. As pointed out by Schroeder et al. (2017) and Souri et al. (2020), a  
335 natural logarithm of LROx/LNOx roughly equal to -1.0 (i.e., LROx/LNOx = 0.35-0.37)  
336 perceptibly separates VOC-sensitive from NOx-sensitive regimes, which would make this  
337 threshold the baseline of our analysis.

338 Figure 3 demonstrates the log-log relationship of LROx/LNOx and FNR, and P(O<sub>3</sub>), from  
339 all four air quality campaigns. The log-log relationships from each individual campaign are shown  
340 in Figure S6-S9. We overlay the LROx/LNOx baseline threshold along with two commonly used  
341 thresholds for FNR suggested by Duncan et al. (2010); they defined the VOC-sensitive regimes if  
342 FNR<1 and the NO<sub>x</sub>-sensitive ones if FNR>2. Any region undergoing a value between these  
343 thresholds is unlabeled and considered to be in a transitional regime. The size of each data point  
344 is proportional to the HCHO×NO<sub>2</sub> concentration magnitude. One striking finding from this plot is  
345 that there is indeed a strong linear relationship between the logarithmic-transformed LROx/LNOx  
346 and FNR (R<sup>2</sup>=0.91). A strong linear relationship between the two quantities in the log-log scale  
347 indicates a power law dependence (i.e.,  $y=ax^b$ ). A strong power law dependency means that these  
348 two quantities have a poor correlation at their low and high values. This is mainly caused by the  
349 fact that HCHO does not fully describe VOC reactivity rates **in environments with high and low**  
350 **VOC concentrations** (Souri et al., 2020). The question is, what range of FNR will fall in  
351  $\ln(\text{LROx/LNOx}) = -1.0 \pm 0.2$ ? Following the baseline, the transitioning ratios follow a normal  
352 distribution with a mean of 1.8, a standard deviation of 0.4, and a range from 1 to 4 (Figure S10).  
353 We define the chemical error in the application of FNR to separate the chemical regimes as the  
354 relative error standard deviation (i.e.,  $\sigma/\mu$ ) of the transitioning ratios leading to ~ 20%. These  
355 numbers are based on a single model realization and can change if a different mechanism is used;

356 nonetheless, the model has considerable skill at reproducing many different unconstrained  
357 compounds, especially OH, suggesting that it is a rather reliable realization. Comparing the  
358 transitioning FNRs to the NO<sub>2</sub> concentrations suggests no correlation ( $r=0.02$ ), whereas there is a  
359 linear correlation between the transitioning ratios and the HCHO concentrations ( $r=0.56$ ). This  
360 tendency reinforces the study of Souri et al. (2020), who, primarily due to the HCHO-NO<sub>2</sub>  
361 feedback, observed a larger FNR threshold in VOC-rich environments to be able to detect the  
362 chemical regimes.

363 **3.3. Large PO<sub>3</sub> rates occur in regions with large HCHO×NO<sub>2</sub> concentrations when  
364 moving toward NOx-sensitive regions**

365 A striking and perhaps intuitive tendency observed from Figure 3 is that large PO<sub>3</sub> rates  
366 are mostly tied to higher HCHO×NO<sub>2</sub>. But this relationship gradually weakens as we move  
367 towards VOC-sensitive regions (smaller LROx/LNOx ratios). This is a textbook example of non-  
368 linear ozone chemistry. In VOC-sensitive areas, PO<sub>3</sub> can be strongly inhibited by NO<sub>2</sub>+OH and  
369 the formation of organic nitrates despite the abundance of the precursors. In the application of  
370 remote-sensing of ozone precursors, the greatest unused metric describing the mass of the ozone  
371 precursors is HCHO×NO<sub>2</sub>. However, this metric should only be used in conjunction with FNR. To  
372 demonstrate this, based on what the baseline (LROx/LNOx) suggests against thresholds on FNRs  
373 defined by Duncan et al. (2010), we group the data into four regions: NOx-sensitive – NOx-  
374 sensitive, NOx-sensitive-transitional, VOC-sensitive-transitional, and VOC-sensitive-VOC-  
375 sensitive. A different perspective on this categorization is that the transitional regimes are a weaker  
376 characterization of the main regime; for instance, NOx-sensitive-transitional regions are less NOx-  
377 sensitive than NOx-sensitive – NOx-sensitive. Subsequently, the cumulative distribution functions  
378 (CDFs) of PO<sub>3</sub> and HCHO×NO<sub>2</sub> with respect to the aforementioned groups are calculated, which  
379 is shown in Figure 4. Regarding NOx-sensitive—NOx-sensitive regions, we see the PO<sub>3</sub> CDF very  
380 quickly converging to the probability of 100%, indicating that the distribution of PO<sub>3</sub> is skewed  
381 towards very low values. The median of PO<sub>3</sub> for this particular regime (where CDF = 50%) is only  
382 0.25 ppbv/hr. This agrees with previous studies such as Martin et al. (2002), Choi et al. (2012), Jin  
383 et al. (2017), and Souri et al. (2017), reporting that NOx-sensitive regimes dominate in pristine  
384 areas. The PO<sub>3</sub> CDFs between NOx-sensitive—transitional and VOC-sensitive—VOC-sensitive  
385 are not too distinct, whereas their HCHO×NO<sub>2</sub> CDFs are substantially different. The non-linear  
386 ozone chemistry suppresses PO<sub>3</sub> in highly VOC-sensitive areas such that those values are not too  
387 different from those in mildly polluted areas (NOx-sensitive—transitional). Perhaps the most  
388 interesting conclusion from this figure is that elevated PO<sub>3</sub> values (median = 4.6 ppbv/hr), a factor  
389 of two larger than two previous regimes, are mostly found in VOC-sensitive—transitional. This is  
390 primarily due to two causes: i) this particular regime is not strongly inhibited by the nonlinear  
391 chemistry, particularly NO<sub>2</sub>+OH, and ii) it is associated with abundant precursors evident in the  
392 median of HCHO×NO<sub>2</sub> being three times as large of those in NOx-sensitive—transitional. This  
393 tendency illustrates the notion of non-linear chemistry and how this may affect regulations. Simply  
394 knowing where the regimes are might not suffice to pinpoint the peak of PO<sub>3</sub>, as this analysis  
395 suggests that we need to consider both FNR and HCHO×NO<sub>2</sub>; both metrics are readily accessible  
396 from satellite remote-sensing sensors.

397 **3.4. Can we estimate PO<sub>3</sub> using the information from HCHO/NO<sub>2</sub> and HCHO×NO<sub>2</sub>?**

398 It may be advantageous to construct an empirical function fitted to these two quantities and  
399 elucidate the maximum variance (information) we can potentially gain to recreate PO<sub>3</sub>. After  
400 several attempts, we found a bilinear function ( $z=a_0+a_1x+a_2y+a_3xy$ ) to be a good fit without

401 overparameterization. Due to presence of extreme values in both FNR and  $\text{HCHO} \times \text{NO}_2$ , we use a  
 402 weighted least squares method for the curve fitting based on the distance of the fitted curve to the  
 403 data points (known as bi-squares weighting). The best fit with  $R^2$  equals to 0.94 and an RMSE of  
 404 0.60 ppbv/hr is:

$$405 \quad PO_3 = 0.74 - 0.09x - 0.02y + 0.25xy \quad (4)$$

406 where  $x$  and  $y$  are FNR (unitless) and  $\text{HCHO} \times \text{NO}_2$  (ppbv<sup>2</sup>), respectively. The residual of the fit is  
 407 shown in Figure S11. The gradients of  $PO_3$  with respect to  $x$  and  $y$  are:

$$408 \quad \frac{dPO_3}{dx} = 0.25y - 0.09 \quad (5)$$

$$409 \quad \frac{dPO_3}{dy} = 0.25x - 0.02 \quad (6)$$

410 An apparent observation arises from these equations that is the derivative of  $PO_3$  to each  
 411 metric depends on the other one underscoring their interconnectedness. For instance, Eq. (6)  
 412 suggests that larger FNRs ( $x$ ) result in a larger gradient of  $PO_3$  to the abundance of  $\text{HCHO} \times \text{NO}_2$   
 413 ( $y$ ). In very low FNRs, this gradient can become very small, rendering  $PO_3$  insensitive (or in  
 414 extreme cases, negatively correlated) to  $\text{HCHO} \times \text{NO}_2$ . This analysis provides encouraging results  
 415 about the future application of the satellite-derived  $\text{HCHO} \times \text{NO}_2$ ; however, the wide class of  
 416 problems relating to the application of satellite-derived FNR columns, such as satellite errors in  
 417 columns or the translation between columns to PBL is also present in Eq. (4), even in a more  
 418 pronounced way due to  $\text{HCHO} \times \text{NO}_2$  and  $\text{HCHO}^2$  ( $= xy$ ). This new perspective on  $PO_3$  estimation  
 419 deserves a separate study.

### 420 3.5. Altitude dependency and its parametrization

421 A lingering concern over the application of satellite-based FNR tropospheric columns is  
 422 that the vertical distribution of  $\text{HCHO}$  and  $\text{NO}_2$  are integrated **into** columns; thus, this vertical  
 423 information is permanently lost. Here, we provide insights **into** the vertical distribution of FNR  
 424 within the tropospheric column. This task requires information about the differences between i)  
 425 the vertical shape of  $\text{HCHO}$  and that of  $\text{NO}_2$  and ii) the vertical shape in the sensitivity of the  
 426 retrievals to the different altitude layers (described as scattering weights). Ideally, if both  
 427 compounds show an identically relative shape, the FNR columns will be valid for every air parcel  
 428 along the vertical path (i.e., a straight line). Previous studies such as Jin et al. (2017) and Schroeder  
 429 et al. (2017) observed a large degree of vertical inhomogeneity in both  $\text{HCHO}$  and  $\text{NO}_2$   
 430 concentrations suggesting that this ideal condition cannot be met. **We do not always have precise**  
 431 **observations of  $\text{HCHO}$  and  $\text{NO}_2$  vertical distributions**, but we can constitute some degree of  
 432 generalization by leveraging the measurements made during the aircraft campaigns. As for the  
 433 differences in the vertical shapes (i.e., the curvature) of the sensitivity of the retrievals between  
 434  $\text{HCHO}$  and  $\text{NO}_2$  channels (i.e.,  $\sim 340$  nm and  $\sim 440$  nm), under normal atmospheric and viewing  
 435 geometry conditions, several studies such as Nowlan et al. 2018 and Lorente et al. 2017 showed  
 436 small differences in the vertical shapes of the scattering weights **in the** first few kilometers altitude  
 437 above the surface where the significant fluctuations in FNRs usually take place. Therefore, our  
 438 analysis does not consider the varying vertical shapes in the scattering weights. However, this  
 439 assumption might not hold for excessive aerosol loading with variable extinction efficiency  
 440 between  $\sim 340$  nm and  $\sim 440$  nm wavelengths or extreme solar zenith angles.

441 Figure 5 demonstrates the violin plot of the afternoon ( $> 12:00$  LT) vertical distribution of  
 442  $\text{HCHO}$ ,  $\text{NO}_2$ , and FNR observed by NASA's aircraft during the four field campaigns analyzed in  
 443 this study superimposed by the simulated  $PO_3$  rates. The vertical layers are grouped into sixteen

441 altitudes ranging from 0.25 km to 7.75 km. Each vertical layer incorporates measurements  $\pm 0.25$   
 442 km of the mid-layer height. The observations do not follow a normal distribution, particularly in  
 443 the lower parts of the atmosphere; thus, medians are preferred to represent the central tendency.  
 444 While the largest PO<sub>3</sub> rates tend to occur in areas close to the surface (< 2 km agl), a nonnegligible  
 445 fraction of the elevated PO<sub>3</sub> rates are also observed in other parts of the atmosphere, such as in the  
 446 free troposphere.

447 Several intriguing features are observed in Figure 5: First, up to the 5.75 km range, which  
 448 encompasses the PBL area and a large portion of the free troposphere, NO<sub>2</sub> concentrations tend to  
 449 decrease quicker than those of HCHO in line with previous studies such as Schroeder et al. (2017),  
 450 Jin et al. (2017), Chan et al. (2019), and Ren et al. (2022). Second, above 5.75 km, HCHO levels  
 451 off, whereas NO<sub>2</sub> shows an increasing trend. Finally, due to their different vertical shapes, we  
 452 observe nonuniformities in the vertical distribution of FNR: they become more NO<sub>x</sub>-sensitive with  
 453 altitude up to a turning point at 5.75 km and then shift back to the VOC-sensitive direction.

454 It is attractive to model these shapes and apply parameterizations to understand how their  
 455 shapes will complicate the use of tropospheric column retrieval from satellites. First order rational  
 456 functions are a good candidate to use. Concerning the vertical dependency of HCHO and NO<sub>2</sub>, we  
 457 find reasonable fit ( $R^2=0.73$ ) as:

$$458 \quad HCHO, NO_2 = \frac{a_0 z + a_1}{z + a_2} \quad (7)$$

459 where  $z$  is altitude in km.  $a_i$  ( $i=0,1,2$ ) are fitting parameters. From this equation it is determined  
 that FNRs follow a second order rational function:

$$460 \quad f(z) = \frac{HCHO}{NO_2} = \frac{b_0 z^2 + b_1 z + b_2}{b_3 z^2 + b_4 z + b_5} \quad (8)$$

461 where  $b_i$  ( $i=0, \dots, 5$ ) are fitting parameters. One can effortlessly fit this function to different bounds  
 462 of the vertical distribution of FNR such as the 25<sup>th</sup> and 75<sup>th</sup> percentiles, and subsequently estimate  
 463 the first moment of the resultant polygon along  $z$  divided by the total area bounded to the polygon  
 (the centroid,  $G$ ) via:

$$464 \quad G(z_1, z_2) = \frac{1}{2A} \int_{z_1}^{z_2} f^2(z)_{75th} - f^2(z)_{25th} dz \quad (9)$$

465 where  $A$  is the area of the polygon bounded by the 75<sup>th</sup> percentiles,  $f(z)_{75th}$ , and the 25<sup>th</sup>  
 466 percentiles ( $f(z)_{25th}$ ) of FNR (shown in Figure 5 as solid black lines). We define an altitude  
 467 adjustment factor ( $f_{adj}$ ) such that one can translate an observed FNR tropospheric column ratios,  
 such as those retrieved from satellites, to a defined altitude and below that point ( $zt$ ) through:

$$468 \quad f_{adj} = \frac{G(0, z_t)}{G(0, 8 \text{ km})} \quad (10)$$

469 where  $zt$  can be interchanged to match the PBLH. This definition is more beneficial than using the  
 470 entire tropospheric column to the surface conversion (e.g., Jin et al., 2017) because ozone can form  
 471 in various vertical layers. Using the observations collected during the campaign, we estimate Eq.  
 472 (10) along with  $\pm 1\sigma$  boundaries shown in Figure 6. To determine the adjustment factor error, we  
 473 reestimate Eq.9 with  $\pm 1\sigma$  level in the coefficients obtained from Eq.8. The resultant error is shown  
 474 in the dashed red line in Figure 6. This error results from uncertainties associated with assuming  
 475 that the second-order rational function can explain the vertical distribution of FNRs. The shape of  
 476 the resulting adjustment factor is in line with the vertical distribution of FNR (see Figure 5): the  
 477 adjustment factor curve closer to the surface has values smaller than one, increases to values larger  
 478 than one in the mid-troposphere, and finally, converges to one near the top of **measured  
 concentrations**. If one picks out an altitude pertaining to a PBLH, one can easily apply  $f_{adj}$  to the

479 observed FNR columns to estimate the corresponding ratio for that specific PBLH. A more evolved  
480 PBLH (i.e., a large  $zt$ ) results in stronger vertical mixing, rendering  $f_{adj}$  closer to one. The standard  
481 error deviation of this conversion is around 19%. The relatively low fluctuations in the adjustment  
482 factor around one suggest that under the observed atmospheric conditions (clear-sky afternoon  
483 summers), the columnar tropospheric ratios do not poorly represent the chemical conditions in the  
484 PBL region.

485 It is beneficial to model this curve to make this data-driven conversion easier for future  
486 applications. A second-order polynomial can well describe ( $R^2=0.97$ ) this curve:

$$f_{adj} = az_t^2 + bz_t + c \quad a = -0.01, b = 0.15, c = 0.78 \quad (11)$$

487 Although Eq. (11) does not include observations above 8 km, the area bounded between  $f(z)_{75th}$   
488 and  $f(z)_{25th}$  in higher altitudes is too small to make a noticeable impact on this adjustment factor.

489 One may object that since we estimated the adjustment factor based on two boundaries  
490 (25<sup>th</sup> and 75<sup>th</sup> percentiles) of the data, we are no longer really dealing with 50% of features  
491 observed in the vertical shapes of FNR. This valid critique can be overcome by gradually relaxing  
492 the lower and upper limits and examining the resulting change in  $f_{adj}$ . When we reduce the lower  
493 limit in Eq. (9) from the 25<sup>th</sup> to 1<sup>st</sup> percentiles, the optimal curve is similar to the one shown in  
494 Figure 6 (Figure S12). However, when we extend the upper limit from the 75<sup>th</sup> percentile to greater  
495 values, we see the fit becoming less robust above the 80<sup>th</sup> percentile, indicating that the formulation  
496 applies to ~80% of the data. The reason behind the poor representation of the adjustment factor  
497 for the upper tail of the population is the extremely steep turning point between 5.5 and 6.0 km,  
498 necessitating a higher-order rational function to be used for Eq. (7) and Eq. (8). We prefer to limit  
499 this analysis to both boundaries and the order defined in Eq. (8) and Eq. (9) because extreme value  
500 predictions usually lack robustness.

501 A **caveat** with these results is that our analysis is limited to afternoon observations because  
502 we focus on afternoon low-orbiting sensors such as OMI and TROPOMI. Nonetheless, Schroeder  
503 et al. (2017) and Crawford et al. (2021) observed large diurnal variability in these profiles due to  
504 diurnal variability in sinks and sources of NO<sub>2</sub> and HCHO and atmospheric dynamics. The diurnal  
505 cycle has an important implication for geostationary satellites such as Tropospheric Emissions  
506 indeed: Monitoring of Pollution (TEMPO) (Chance et al., 2019). **Limiting the observations to**  
507 **morning time results in a smaller adjustment factor for altitudes close to the surface resulting from**  
508 **steeper vertical gradients of HCHO/NO<sub>2</sub>** (Figures S13 and S14). This tendency agrees with Jin et  
509 al. (2017), who observed a larger deviation from one in an adjustment factor used for the column-  
510 surface conversion in winter.

511 Another important caveat with our analysis is that it is based upon four air quality  
512 campaigns in warm seasons that avoid times/areas with convective transport; as such, our analysis  
513 needs to be made aware of the vertical shapes of FNR during convective activities and cold  
514 seasons. However, a few compelling assumptions can **minimize** these oversights: first, it is very  
515 atypical to encounter elevated ozone production rates during cold seasons with few exceptions  
516 (Ahmadov et al., 2015; Rappenglück et al., 2014); second, the notion of ozone regimes is only  
517 appropriate in photochemically active environments where the ROx-HOx cycle is active; an  
518 example of this can be found in Souri et al. (2021) who observed an enhancement of surface ozone  
519 in central Europe during a lockdown in April 2020 (up to 5 ppbv) compared to a baseline which  
520 was explainable by the reduced O<sub>3</sub> titration through NO in place of the photochemically induced  
521 production. An exaggerated extension to this example is the nighttime chemistry where NO-O<sub>3</sub>-  
522 NO<sub>2</sub> partitioning is the primary driver of negative ozone production rates; at night, the definition  
523 of NOx-sensitive or VOC-sensitive is meaningless, so **it** is in photochemically less active

environments; third, it is rarely advisable to use cloudy scenes in satellite UV-Vis gas retrievals due to the arguable assumption on Lambertian clouds and highly uncertain cloud optical centroid and albedo; accordingly, atmospheric convection occurring during storms or fires is commonly masked in satellite-based studies. Therefore, the limitations associated with the adjustment factor are mild compared to the advantages.

### 3.6. Spatial Heterogeneity

The spatial representation error resulting from unresolved processes and scales (Janić et al., 2016; Valin et al., 2011; Souri et al., 2022) refers to the amount of information lost due to satellite footprint or unresolved inputs used in satellite retrieval algorithms. Unfortunately, this source of error cannot be determined when we do not know the true state of the spatial variability. There is, however, a practical way to resolve this by conducting multi-scale intercomparisons of a coarse spatial resolution output against a finer one. Yet, despite the absence of the truth in this approach, we tend to find their comparisons useful in giving us an appreciation of the error.

We build the reference data on qualified pixels (`qa_value`> 0.75) of offline TROPOMI tropospheric NO<sub>2</sub> version 2.2.0 (van Geffen et al., 2021; Boersma et al., 2018) and total HCHO columns version 2.02.01 (De Smedt et al., 2018) oversampled at 3×3 km<sup>2</sup> in summer 2021 over the US. Figure 7 shows the map of those tropospheric columns as well as FNR. Encouragingly, the small footprint and relatively low detection limit of TROPOMI compared to its predecessor satellite sensors (e.g., OMI) enable us to have possibly one of the finest maps of HCHO over the US to date. Large values of HCHO columns are found in the southeast due to strong isoprene emissions (e.g., Zhu et al., 2016; Wells et al., 2020). Cities like Houston (Boeke et al., 2011; Zhu et al., 2014; Pan et al., 2015; Diao et al., 2016), Kansas City, Phoenix (Nunnermacker et al., 2004), and Los Angeles (de Gouw et al., 2018) also show pronounced enhancements of HCHO possibly due to anthropogenic sources. Expectedly, large tropospheric NO<sub>2</sub> columns are often confined to cities and some coal-fired power plants along the Ohio River basin. Concerning FNR, low values dominate cities, whereas high values are found in remote regions. An immediate tendency observed from these maps is that the length scale of HCHO columns is longer than that of NO<sub>2</sub>. This indicates that NO<sub>2</sub> columns are more heterogeneous. Because of this, we observe a large degree of spatial heterogeneity with respect to FNRs.

Here we limit our analysis to Los Angeles due to computational costs imposed by the subsequent experiment. To quantify the spatial representation errors caused by satellite footprint size, we upscale the FNRs by convolving the values with four low pass box filters with the size of 13×24, 36×36, 108×108, and 216×216 km<sup>2</sup>, shown in the first column of Figure 8. Subsequently, to extract the spatial variance (information), we follow the definition of the experimental semivariogram (Matheron, 1963):

$$\gamma(\mathbf{h}) = \frac{1}{2N(\mathbf{h})} \sum_{|x_i - x_j| - |\mathbf{h}| \leq \varepsilon} [Z(x_i) - Z(x_j)]^2 \quad (12)$$

where  $Z(x_i)$  (and  $Z(x_j)$ ) is discrete pixels of FNRs,  $N(\mathbf{h})$  is the number of paired pixels separated by the vector of  $\mathbf{h}$ . The  $|\cdot|$  operator indicates the length of a vector. The condition of  $|x_i - x_j| - |\mathbf{h}| \leq \varepsilon$  is to permit certain tolerance for differences in the length of the vector. Here, we ignore the directional dependence in  $\gamma(\mathbf{h})$  which makes the vector of  $\mathbf{h}$  scalar ( $h = |\mathbf{h}|$ ). Moreover, we bin  $\gamma$  values in 100 evenly-spaced intervals ranging from 0 to 5 degrees. To remove potential outliers (such as noise), it is wise to model the semivariogram using an empirical regression model. To model the semivariogram, we follow the stable Gaussian function used by Souri et al. (2022):

$$\gamma(h) = s(1 - e^{-(\frac{h}{r})^{c_0}}): c_0=1.5 \quad (13)$$

566 where  $r$  and  $s$  are fitting parameters. For the most part, geophysical quantities become spatially  
 567 uncorrelated at a certain distance called the range, and the variance associated with that distance  
 568 is called the sill. The fitting parameters,  $r$ , and  $s$ , describe these two quantities as long as the stable  
 569 Gaussian function can well fit to the shape of semivariogram. The semivariograms, and the fits,  
 570 associated with each map are depicted in the second column of Figure 8.

571 The modeled semivariograms suggest that a coarser field comes with a smaller sill,  
 572 implying a loss in the spatial information (variance). The length scale (i.e., the range) only sharply  
 573 increases at coarser footprints ( $>36 \times 36 \text{ km}^2$ ). This indicates that several coarse-resolution satellite  
 574 sensors, such as OMI ( $13 \times 24 \text{ km}^2$ ), are rather able to determine the length scales of FNR over a  
 575 major city such as Los Angeles. By leveraging the modeled semivariograms, we can effortlessly  
 576 determine the spatial representation error for specific scale (e.g.,  $h=10 \text{ km}$ ) through

$$e^2(h) = 1 - \frac{\gamma(h)}{\gamma_{ref}(h)} \quad (14)$$

577 where  $\gamma(h)$  and  $\gamma_{ref}(h)$  are the modeled semivariogram of the target and the reference fields ( $3 \times 3$   
 578  $\text{km}^2$ ). This equation articulates the amount of information lost in the target field compared to the  
 579 reference. Accordingly, the proposed formulation of the spatial representation error is relative.  
 580 **Figure 9 depicts the representation errors for various footprints.** For the most part, the OMI nadir  
 581 pixel ( $13 \times 24 \text{ km}^2$ ) only has a  $\sim 12\%$  loss of the spatial variance. On the contrary, a grid box with a  
 582 size of  $216 \times 216 \text{ km}^2$  fails at capturing  $\sim 65\%$  of the spatial information in FNR with a  $50 \text{ km}$  length  
 583 scale comparable to the extent of Los Angeles. The advantage of our method is that we can  
 584 mathematically describe the spatial representation error as a function of the length of our target.  
 585 The present method can be easily applied to other atmospheric compounds and locations. We have  
 586 named this method SpaTial Representation Error EstimaTor (STREET) which is publicly available  
 587 as an open-source package (Souri, 2022).

588 An oversight in the above experiment lies in its lack of appreciation of unresolved physical  
 589 processes in the satellite measurements: **a weak sensitivity of some retrievals to the near-surface**  
 590 **pollution due to the choice of spectral windows used for fitting** (Yang et al., 2014), using 1-D air  
 591 mass factor calculation instead of 3-D (Schwaerzel et al., 2020), and **neglecting** aerosol effect on  
 592 the light path are just **a few** examples to point out. To account for the unresolved processes, one  
 593 can recalculate Eqs. (12)-(14) using outputs from different retrieval frameworks, which is beyond  
 594 the scope of this study.

### 595 3.7. Satellite errors

#### 596 3.7.1. Concept

597 Two types of retrieval errors can affect our analysis: systematic errors (bias) and  
 598 unsystematic ones (random errors). In theory, it is very compelling to understand their differences.  
 599 In reality, the distinction between random and systematic errors is not as clear-cut as it seems. **For**  
 600 **example**, one may wish to establish the credibility of a satellite retrieval by comparing it to a sky-  
 601 radiance measurement over time. Because each measurement is made at a different time, their  
 602 comparison is not a repetition of the same experiment; each time, the atmosphere differs in some  
 603 aspects, so each comparison is unique. Adding more sky-radiance measurements will add new  
 604 experiments. For each paired data point, many unique issues contribute differently to errors; as  
 605 such, our problem is grossly under-determined (i.e., more unknowns for a given observation).

606 Here, we do not attempt to separate random from systematic errors in the subsequent analysis,  
607 thereby limiting this study to the total uncertainty.

608 We focus on analyzing the statistical errors drawn from the differences between the differences between the  
609 benchmark and the retrievals on daily basis. Two sensors are used for this analysis: TROPOMI  
610 and OMI. To propagate individual uncertainties in HCHO and NO<sub>2</sub> to FNRs, we follow an  
611 analytical approach involving Jacobians of the ratio to HCHO and NO<sub>2</sub>. Assuming that errors in  
612 HCHO and NO<sub>2</sub> are uncorrelated, the relative error of the ratio can be estimated by:

$$\frac{\sigma}{ratio} = \sqrt{\left(\frac{\sigma_{HCHO}}{HCHO}\right)^2 + \left(\frac{\sigma_{NO_2}}{NO_2}\right)^2} \quad (15)$$

613 where  $\sigma_{HCHO}$  and  $\sigma_{NO_2}$  are total uncertainties of HCHO and NO<sub>2</sub> observations. It is important to  
614 recognize that the errors in HCHO and NO<sub>2</sub> are not strictly uncorrelated due to assumptions made  
615 in their air mass factor calculations.

### 616 3.7.2. Error Distributions in TROPOMI and OMI

617 We begin our analysis with the error distribution of daily TROPOMI tropospheric NO<sub>2</sub>  
618 columns (v1.02.02) against 22 MAX-DOAS instruments from May to September in 2018-2021.  
619 The data are paired based on the criteria defined in Verhoelst et al. (2021). The spatial locations  
620 of the stations are mapped in Figure S15. Figure 10a shows the histogram of the TROPOMI minus  
621 the MAX-DOAS instruments. The first observation from this distribution is that it is skewed  
622 towards lower differences, evident in the skewness parameter around -4.6. As a result of the  
623 skewness, the median **should better represent** the central tendency which is around  $-1 \times 10^{15}$   
624 molec./cm<sup>2</sup>. In general, TROPOMI tropospheric NO<sub>2</sub> columns show a low bias. We fit a normal  
625 distribution to the data using the non-linear Levenberg-Marquardt method. This fitted normal  
626 distribution ( $R^2=0.94$ ) is used to approximate  $\sigma_{NO_2}$  for different confidence intervals, and to  
627 **minimize** blunders. To understand how much of these disagreements are caused by systematic  
628 errors as opposed to random errors, we redo the histogram using monthly-based observations  
629 (Figure S16). A slight change in the dispersions between the daily and the monthly-basis analysis  
630 indicates the significance of unresolved systematic (or relative) biases. This tendency suggests that  
631 when conducting the analysis on a monthly basis, the relative bias cannot be mitigated by  
632 averaging. Verhoelst et al. (2021) rigorously studied the potential root cause of some discrepancies  
633 between MAX-DOAS and TROPOMI. An important source of error stems from the fundamental  
634 differences in the vertical sensitivities of MAX-DOAS (more sensitive to the lower tropospheric  
635 region) and TROPOMI (more sensitive to the upper tropospheric area). This systematic error can  
636 only be mitigated using reliably high-resolution vertical shape factors instead of spatiotemporal  
637 averaging of the satellite data.

638 The error analysis for OMI follows the same methods applied for TROPOMI; however,  
639 with different benchmarks. We follow the comparisons made between the operational product  
640 version 3.1 and measured columns derived from NCAR's NO<sub>2</sub> measurements integrated along  
641 aircraft spirals during four NASA's air quality campaigns. More information regarding this data  
642 comparison can be found in Choi et al. (2020). Figure 10b shows the histogram of OMI minus the  
643 integrated spirals. Compared to TROPOMI, the OMI bias is worse by a factor of two. The standard  
644 deviation calculated from a Gaussian fit ( $2.31 \times 10^{15}$  molec./cm<sup>2</sup>) is not substantially different from  
645 that of TROPOMI ( $2.11 \times 10^{15}$  molec./cm<sup>2</sup>).

646 As for the error distribution of TROPOMI HCHO columns (version 1.1.(5-7)), we use 24  
647 FTIR measurements during the same time period based on the criteria specified in Vigouroux et

648 al. (2020). The stations are mapped in Figure S15. The frequency of the paired data is daily. Figure  
649 11a depicts the error distribution. The distribution is slightly broader compared to that of NO<sub>2</sub>,  
650 manifested in a larger standard deviation  $4.32 \times 10^{15}$  molec./cm<sup>2</sup>. This is primarily due to two facts:  
651 i) HCHO optical depths generally peak in the UV range (<380 nm), where the large optical depths  
652 of ozone and Rayleigh scattering result in weaker and noisier signals (Gonzalez Abad et al., 2019),  
653 and ii) the broader and stronger NO<sub>2</sub> optical depths in the ViS range (400-500 nm), where the  
654 signal-to-noise ratio is typically more outstanding, permit better quality retrievals. Similar to the  
655 NO<sub>2</sub>, we fit a normal distribution ( $R^2=0.90$ ) to specify  $\sigma_{HCHO}$  for different confidence intervals.

656 Concerning OMI HCHO columns from SAO version 3 (Gonzalez Abad et al., 2015), we  
657 follow the intercomparison approach proposed in Zhu et al. (2020). Based on this approach, the  
658 benchmarks come from GEOS-Chem simulated HCHO columns corrected by in-situ aircraft  
659 measurements. The measurements were made during ozone seasons from KORUS-AQ,  
660 DISCOVERs, FRAPPE, NOMADSS, and SENEX campaigns (see Table 1 in Zhu et al. 2020).  
661 OMI values ranging from  $-0.5 \times 10^{15}$  molec./cm<sup>2</sup> and  $1.0 \times 10^{17}$  molec./cm<sup>2</sup> with effective cloud  
662 fraction between 0.0 and 0.3, and SZA between 0 and 60 degrees are only considered in the  
663 comparison. Any pixels from OMI and grid boxes from the corrected GEOS-Chem simulation that  
664 fall into a polygon enclosing the campaign domain are used to create the error distribution shown  
665 in Figure 11b. The distribution has much denser data because the model output covers a large  
666 portion of the satellite swath. The error distribution suggests that OMI HCHO is inferior to  
667 TROPOMI evident in larger bias and standard deviation. The OMI bias is twice as large as that of  
668 TROPOMI. De Smedt et al. (2021) observed the same level of bias from their comparisons of  
669 OMI/TROPOMI with MAX-DOAS instruments (see Table 3 in their paper). Moreover, their OMI  
670 vs MAX-DOAS comparisons were severely scattered. Likewise, we observe the standard deviation  
671 of OMI from the fitted Gaussian function to be roughly five times as large of that TROPOMI. This  
672 can be primarily due to a weaker signal-to-noise (and sensor degradation) in OMI. It is because of  
673 this reason that OMI HCHO should be averaged over several months. Another possible reason for  
674 the large standard deviation is the fact that the benchmark arises from a modeling experiment  
675 whose ability at resolving spatiotemporal variations in HCHO may be uncertain. This partly leads  
676 to the performance of OMI to look poor.

### 677 3.7.3. *The impact of retrieval error on the ratio*

678 Following Eq. (15), we calculate the standard error for a wide range of NO<sub>2</sub> and HCHO  
679 columns at a 68% confidence interval (1 sigma) for both TROPOMI and OMI derived from the  
680 fitted Gaussian function to the histograms; the standard errors are shown in Figure 12. We observe  
681 smaller errors to be associated with larger tropospheric column concentrations. As for TROPOMI,  
682 either daily HCHO or tropospheric NO<sub>2</sub> columns should be above  $1.2-1.5 \times 10^{16}$  molec./cm<sup>2</sup> to  
683 achieve 20-30% standard error. The TROPOMI errors start diminishing the application of FNR  
684 when both measurements are below this threshold. Regarding OMI, it is nearly impossible to get  
685 the standard error below of 20-30% given its problematically large HCHO standard deviation. For  
686 50% error, the daily HCHO columns should be above  $3.2 \times 10^{16}$  molec./cm<sup>2</sup>. This range of error  
687 can also be achieved if OMI tropospheric NO<sub>2</sub> columns are above  $8 \times 10^{15}$  molec./cm<sup>2</sup>.

### 688 3.8. *The fractional errors to the combined error*

689 The ultimate task is to compile the aforementioned errors to gauge how each individual  
690 source of error contributes to the overall error. Although each error is different in nature, combined  
691 they explain the uncertainties of one quantity (FNR) and can be roughly considered independent;  
692 therefore, the combined error is given by:

$$\sigma_{total} = \sqrt{\sigma_{Col2PBL}^2 + \sigma_{SpatialRep}^2 + \sigma_{Retreival}^2} \quad (16)$$

693  $\sigma_{Col2PBL}$  is the error in the adjustment-factor defined in this study. We calculated a 26% standard  
 694 error for a wide range of PBLHs. Therefore,  $\sigma_{Col2PBL}$  equals to 26% of the observed ratio (i.e.,  
 695 magnitude dependent).  $\sigma_{SpatialRep}$  is more complex. It is a function of the footprint of the satellite  
 696 (or a model), the spatial variability of the reference field, which varies from environment to  
 697 environment, and the length scale of our target (e.g., a district, a city, or a state). Eq. (14) explicitly  
 698 quantifies this error. The product of the square root of that value and the observed ratio defines  
 699  $\sigma_{SpatialRep}$ . The last error depends on the magnitude of HCHO and NO<sub>2</sub> tropospheric columns. It  
 700 can be estimated from Eq. (15) times the observed ratio. We did not include the chemistry error in  
 701 Eq. (16) because it was suited only for segregating the chemical conditions; it does not describe  
 702 the level of uncertainties that comes with the observed columnar ratio. Figure 13 shows the total  
 703 relative error given the observed TROPOMI ratio seen in Figure 7. We consider the OMI spatial  
 704 representation error (13% variance loss) for this case that was computed in a city environment.  
 705 The retrieval errors are based on TROPOMI sigma values. Areas associated with relatively small  
 706 errors (<50%) are mostly seen in cities due to a stronger signal (smaller  $\sigma_{Retreival}$ ). Places with  
 707 low vegetation and anthropogenic sources (i.e., Rocky Mountains) possess the largest errors  
 708 (>100%).  
 709

710 To produce some examples of the fractional errors to the combined error, we focus on two  
 711 different environments with two different sets of HCHO and NO<sub>2</sub> columns. One represents a  
 712 heavily polluted area, and the other one is a moderately polluted region. We also include two  
 713 footprints: OMI (13×24 km<sup>2</sup>) and a 108×108 km<sup>2</sup> pixel. Finally, we calculate the percentage of  
 714 each error component for both OMI and TROPOMI sensors. Figure 14 shows the pie charts  
 715 describing the percentage of each individual error to the total error for TROPOMI. Unless the  
 716 footprint of the sensor is coarse enough (e.g., 108 km<sup>2</sup>) to give rise to the spatial representation  
 717 error dominance, the retrieval error stands out. New satellites are not expected to have very large  
 718 footprints; as such, retrieval errors appear to be the major obstacle to using FNR in a robust  
 719 manner. Figure 15 shows the same calculation but using OMI errors; the retrieval errors massively  
 720 surpass other errors. This motivates us to do one more experiment; we recalculate the HCHO error  
 721 distribution in OMI using monthly-averaged data instead of daily (Figure S17). This experiment  
 722 suggests a standard deviation of  $9.4 \times 10^{15}$  molec./cm<sup>2</sup>, with which we again observe the retrieval  
 723 error to be the largest contributor (>80%) of the combined error (Figure S18). A recent study  
 724 (Johnson et al., 2022) also suggests that retrieval errors can result in considerable disagreement  
 between FNRs from various sensors and retrieval frameworks.  
 725

#### 4. Summary

726 The main goal of this study was to characterize the errors associated with the ratio of  
 727 satellite-based HCHO to NO<sub>2</sub> columns, which has been widely used for ozone sensitivity studies.  
 728 From the realization of the complexity of the problem, we now know that four major errors should  
 729 be carefully quantified so that we can reliably represent the underlying ozone regimes. The errors  
 730 are broken down into i) the chemistry error, ii) the column to the PBL translation, iii) the spatial  
 731 representation error, and iv) the retrieval error. Each error has its own dynamics and has been  
 732 tackled differently by leveraging a broad spectrum of tools and data.  
 733

734 The chemistry error refers to the predictive power of the HCHO/NO<sub>2</sub> ratio (hereafter FNR)  
 in describing the HOx-ROx cycle, which can be well explained by the ratio of the chemical loss

735 of  $\text{HO}_2 + \text{RO}_2$  (LROx) to the chemical loss of NOx (LNOx). Because those chemical reactions are  
736 not directly observable, we set up a chemical box model constrained with a large suite of in-situ  
737 aircraft measurements collected during DISCOVER-AQs and KORUS-AQ campaigns ( $\sim 500$  hr  
738 of flight). Our box model showed a reasonable performance at recreating some unconstrained key  
739 compounds such as OH ( $R^2=0.64$ , bias=17%),  $\text{HO}_2$  ( $R^2=0.66$ , bias<1%), and HCHO ( $R^2=0.73$ ).  
740 Subsequently, we compared the simulated FNRs to LROx/LNOx. They showed a high degree of  
741 correspondence ( $R^2=0.93$ ) but only in the **logarithmic** scale; this indicated that FNRs do not fully  
742 describe the HOx-ROx cycle (*i.e.*, the sensitivity of ozone production rates to NOx and VOC) for  
743 heavily polluted environments and pristine ones. Following a robust baseline indicator  
744 ( $\ln(\text{LROx}/\text{LNOx}) = -1.0 \pm 0.2$ ) segregating NOx-sensitive from VOC-sensitive regimes, we  
745 observed a diverse range of FNR ranging from 1 to 4. These transitioning ratios had a Gaussian  
746 distribution with a mean of 1.8 and a standard deviation of 0.4. This implied that the relative  
747 standard error associated with the ratio from the chemistry perspective at a 68% confidence interval  
748 was 20%. Although this threshold with its error was based on a single model realization and can  
749 be different for a different chemical mechanism, it provided a useful universal baseline derived  
750 from various chemical and meteorological conditions. At a 68% confidence level, any uncertainty  
751 beyond 20% in the ozone regime identification from FNRs likely originates from other sources of  
752 error, such as the retrieval error.

753 Results from the box model showed that ozone production rates in extremely polluted  
754 regions (VOC-sensitive) were not significantly different from those in pristine ones (NOx-  
755 sensitive) due to non-linear chemical feedback mostly imposed by  $\text{NO}_2 + \text{OH}$ . Indeed, the largest  
756  $\text{PO}_3$  rates (median = 4.6 ppbv/hr) were predominantly seen in VOC-sensitive regimes tending  
757 towards the transitional regime. This was primarily caused by the abundance of ozone precursors  
758 (*i.e.*,  $\text{HCHO} \times \text{NO}_2$ ) and the diminished negative chemical feedback. We also revealed that  
759  $\text{HCHO} \times \text{NO}_2$  could be used as a sensible proxy for the ozone precursors' abundance. In theory,  
760 this metric, in conjunction with the ratio, provided reasonable estimates of  $\text{PO}_3$  rates (RMSE =  
761  $\pm 0.60$  ppbv/hr).

762 We then analyzed the afternoon vertical distribution of HCHO,  $\text{NO}_2$ , and their ratio  
763 observed from aircraft during the air quality campaigns binned to the near-surface to 8 km. For  
764 altitudes below 5.75 km, HCHO concentration steadily decreased with altitude but at a lower rate  
765 than  $\text{NO}_2$ . Above that altitude,  $\text{NO}_2$  concentrations stabilized and slightly increased due to  
766 lightning and stratospheric sources. The dissimilarity between the vertical shape of  $\text{NO}_2$  versus  
767 HCHO resulted in a **rather** non-linear shape of FNR. This non-linear shape necessitated a  
768 mathematical formulation to transform an observed columnar ratio to a ratio at a desired vertical  
769 height expanding from the surface. We fit a second-order rational function to the profile and  
770 formulated the altitude adjustment factor, which followed a second-order polynomial function  
771 starting from values below 1 for lower altitudes, following values above 1 for some high altitudes,  
772 and finally converging to 1 at 8 km. This behavior means that the ozone regime tends to get pushed  
773 **slightly** towards the VOC-sensitive regime near the surface for a given tropospheric columnar  
774 ratio. **This tendency was more pronounced in morning times when the non-linear shape of FNRs**  
775 **was stronger.** This data-driven adjustment factor exclusively derived from afternoon aircraft  
776 profiles during warm seasons in non-convective conditions had a standard error of **19%.**

777 An important error in the satellite-based observations stemmed from unresolved spatial  
778 variability in trace gas concentrations within a satellite pixel (Souri et al., 2022; Tang et al., 2021).  
779 The amount of unresolved spatial variability (the spatial representation error) can in principle be  
780 modeled if we base our reference on a distribution map made from a high spatial resolution dataset.

We modeled semivariograms (or spatial auto-correlation) computed for a reference map of FNR observed by TROPOMI at  $3 \times 3$  km $^2$  over Los Angeles. Subsequently, we coarsened the map to  $13 \times 24$ ,  $36 \times 36$ ,  $108 \times 108$ , and  $216 \times 216$  km $^2$  and modeled their semivariograms. As for  $13 \times 24$  km $^2$ , which is equivalent to the OMI nadir spatial resolution, around 12% of spatial information (variance) was lost due to its footprint. The larger the footprint, the bigger the spatial representation error. For instance, a grid box with a size of  $216 \times 216$  km $^2$  lost 65% of the spatial information in the ratio at a 50 km length scale. Our method is compelling to understand and easy to apply for other products and different atmospheric environments. Based on this approach, we developed an open-source package called SpaTial Representation Error EstimaTor (STREET) (Souri, 2022).

We presented estimates of retrieval errors associated with daily TROPOMI and OMI tropospheric NO<sub>2</sub> columns by comparing them against a large suite of MAX-DOAS (Verhoelst et al. 2021) and vertically-integrated measurements from aircraft spirals (Choi et al., 2020). Both products were smaller than the benchmark. Furthermore, they show a relatively consistent dispersion at a 68% confidence level ( $\sim 2 \times 10^{15}$  molec./cm $^2$ ) suggested by fitting a normal function ( $R^2 > 0.9$ ) to their error distributions. As for daily TROPOMI and OMI HCHO products, we used global FTIR observations (Vigouroux et al., 2020) and data-constrained GEOS-Chem outputs from multiple campaigns (Zhu et al., 2020), respectively. TROPOMI HCHO indeed outperforms OMI HCHO with respect to bias and dispersion on a daily basis. The standard deviation of OMI HCHO was found to be roughly five times as large compared to TROPOMI. While this error can be partly reduced by oversampling over a span of a month or a season, it is critical to recognize that ozone events are episodic; thus, daily observations should be the standard mean for understanding the chemical pathways for the formation of tropospheric ozone. After combining the daily biases from both HCHO and NO<sub>2</sub> TROPOMI comparisons, we concluded that either daily HCHO or tropospheric NO<sub>2</sub> columns should be above  $1.2-1.5 \times 10^{16}$  molec./cm $^2$  to achieve 20-30% standard error in the ratio. Due to the large error in daily OMI HCHO, it was nearly impossible to achieve 20-30% standard error given the observable range of HCHO and NO<sub>2</sub> columns over our planet. To reach 50% error using daily OMI data, HCHO columns should be above  $3.2 \times 10^{16}$  molec./cm $^2$  or tropospheric NO<sub>2</sub> columns should be above  $8 \times 10^{15}$  molec./cm $^2$ .

To build intuition in the significance of the errors above, we finally calculated the combined error in the ratio by linearly combining the root sum of the squares of the TROPOMI retrieval errors, the spatial representation error pertaining to OMI nadir footprint over a city-like environment, and the altitude adjustment error for a wide range of observed HCHO and NO<sub>2</sub> columns over the US. These observations were based on the TROPOMI in the summertime of 2021. The total errors were relatively mild (<50%) in cities due to a stronger signal, whereas they easily exceeded 100% in regions with low vegetation and anthropogenic sources (i.e., Rocky Mountains). The retrieval error was the dominant source of the combined error (40-90%).

All of these aspects highlight the necessity of improving the trace gas satellite retrieval algorithms in conjunction with sensor calibration, although with the realization that a better retrieval is somewhat limited by the advancements made in other disciplines, such as atmospheric modeling and molecular spectroscopy.

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860

## 861 **Data Access**

862 The FTIR and MAXDOAS data used in this publication were partly obtained from the Network  
863 for the Detection of Atmospheric Composition Change (NDACC) and are available through the  
864 NDACC website [www.ndacc.org](http://www.ndacc.org). The spatial representation error is estimated based on publicly  
865 available package, SpaTial Representation Error EstimaTor (STREET)  
866 (<https://github.com/ahsouri/STREET>). DISCOVER-AQ and KORUS-AQ aircraft data can be  
867 downloaded from <https://www-air.larc.nasa.gov/missions/discover-aq/discover-aq.html> and  
868 <https://www-air.larc.nasa.gov/missions/korus-aq/>. TROPOMI NO<sub>2</sub> and HCHO data can be  
869 downloaded from [https://disc.gsfc.nasa.gov/datasets/S5P\\_L2\\_NO2\\_1/summary](https://disc.gsfc.nasa.gov/datasets/S5P_L2_NO2_1/summary) and  
870 [https://disc.gsfc.nasa.gov/datasets/S5P\\_L2\\_HCHO\\_1/summary](https://disc.gsfc.nasa.gov/datasets/S5P_L2_HCHO_1/summary). The box model results can be  
871 obtained by contacting the corresponding author through [ahsouri@cfa.harvard.edu](mailto:ahsouri@cfa.harvard.edu).  
872

873 **Author contributions**  
874 AHS designed the research, analyzed the data, conducted the simulations, made all figures, and  
875 wrote the paper. MSJ, SP, XL, and KC helped with conceptualization, fundraising, and analysis.  
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877 measured various compounds during the air quality campaigns. JHC orchestrated all these  
878 campaigns and contributed to the model interpretation. TV, SC, and GP provided paired MAX-  
879 DOAS and TROPOMI tropospheric NO<sub>2</sub> observations. CV and BL provided paired FTIR and  
880 TROPOMI HCHO observations. SC and LL provided paired integrated aircraft spirals and OMI  
881 tropospheric NO<sub>2</sub> observations. LZ and SS provided the paired observations between the corrected  
882 GEOS-Chem HCHO and OMI HCHO columns. All authors contributed to the discussion and  
883 edited the paper.  
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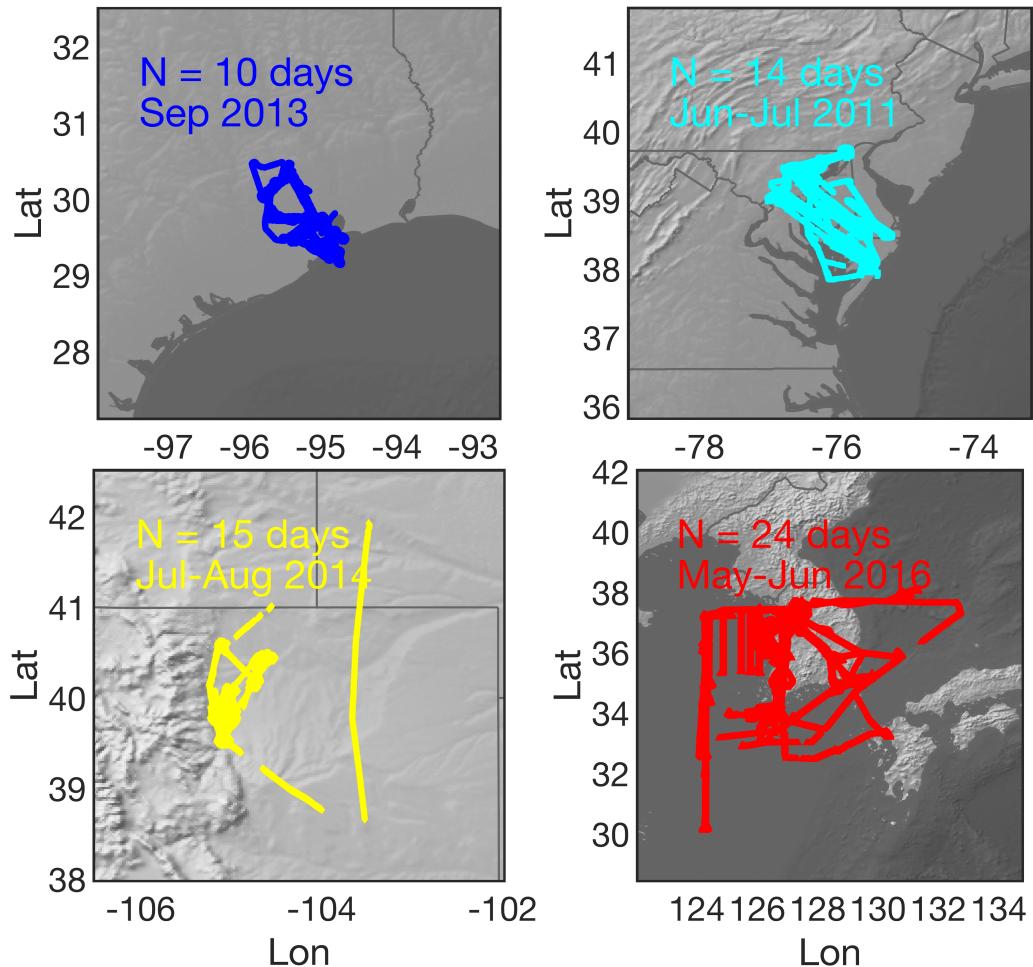
**Table1.** The box model configurations and inputs.

Temporal resolution of samples	10-15 sec
Time steps	1 hour
Number of solar cycles	5
Dilution constant	1/86400 -1/43200 (s <sup>-1</sup> )
Meteorological Inputs	Pressure, Temperature, and Relative Humidity
Photolysis frequencies estimates	LUT based on the NCAR TUV model calculations
Photolysis frequencies constraints (campaign#‡)	Measured jNO <sub>2</sub> (1-4) and jO <sup>1</sup> D (4)
Compounds (Instrument#†, campaign#‡) used for constraining the box model	H <sub>2</sub> (1, 4)§, CO (4, 1-4), NO <sub>x</sub> (2, 1-4), O <sub>3</sub> (2, 1-4), SO <sub>2</sub> (6, 4) , CH <sub>4</sub> (4, 1-4), HNO <sub>3</sub> (10, 1-4), Isoprene (9, 1-4), Monoterpenes (9, 1-4), Acetone (9, 1-4), Ethylene (1, 4), Ethane (1, 4), Methanol (9, 1-4), Propane (1, 4), Benzene (1 or 9, 2-4), Xylene (1 or 9, 1 and 4), Toluene (1 or 9, 1-4), Glyoxal (8, 4), Acetaldehyde (9, 1-4), Methyl vinyl ketone (9, 1-4), Methyl Ethyl Ketone (9, 2-4), Propene (1 or 9, 2 and 4), Acetic acid (9, 2-4), Glycolaldehyde (5, 4), H <sub>2</sub> O <sub>2</sub> (5, 4)
Unconstrained compounds (Instrument#†, campaign#‡) used for validation	HO <sub>2</sub> (3, 4), OH (3, 4), NO (2, 1-4), NO <sub>2</sub> (2, 1-4), PAN (10, 1-4), HCHO (7, 1-4)
Chemical Mechanism	CB06

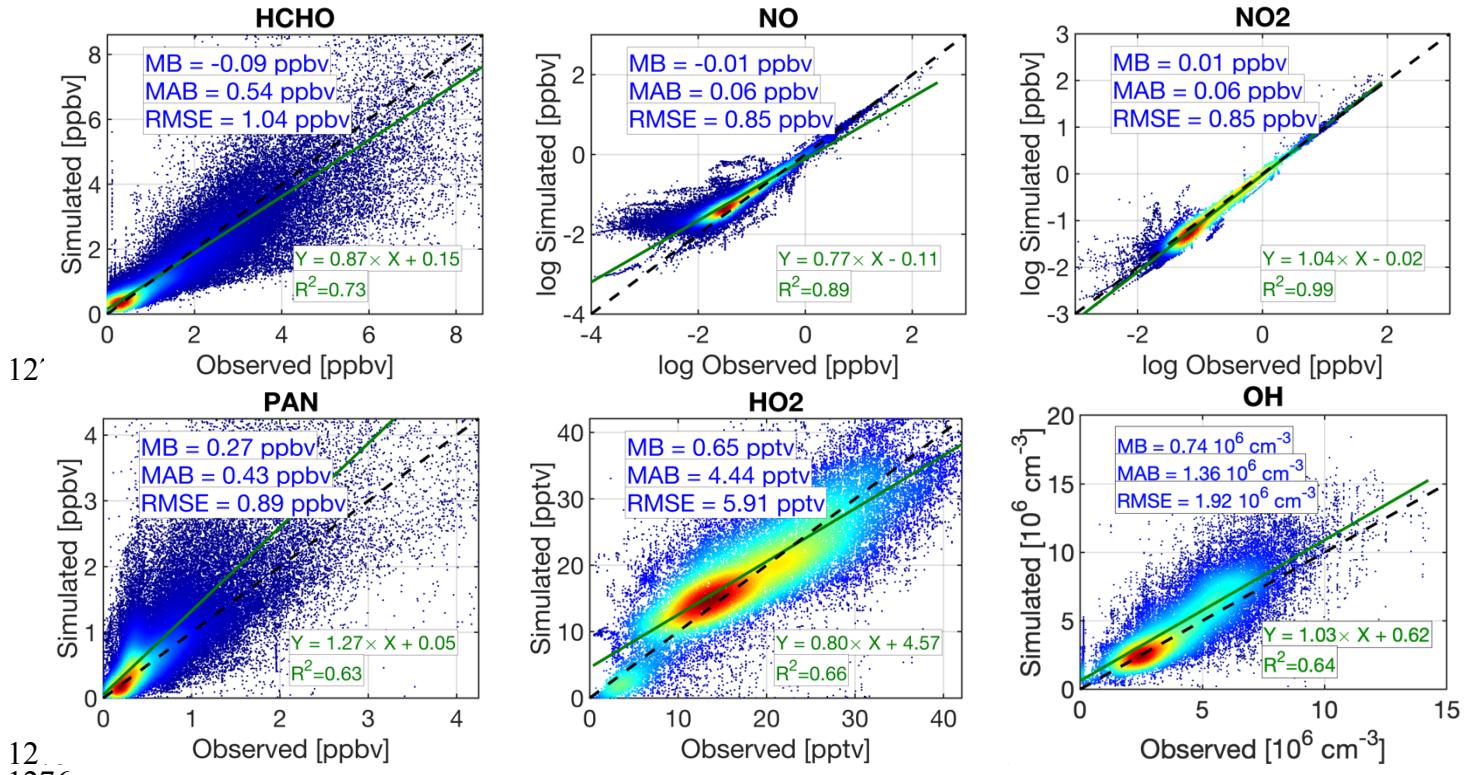
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1253 † (1) UC Irvine's Whole Air Sampler (WAS), (2) NCAR 4-Channel Chemiluminescence, (3) Penn  
1254 State's Airborne Tropospheric Hydrogen Oxides Sensor (ATHOS), (4) NASA Langley's DACOM  
1255 tunable diode laser spectrometer, (5) Caltech's single mass analyzer, (6) Georgia Tech's ionization  
1256 mass spectrometer, (7) The University of Colorado at Boulder's the Compact Atmospheric Multi-  
1257 species Spectrometer (CAMS), (8) Korean Airborne Cavity Enhances Spectrometer, (9)  
1258 University of Innsbruck's PTR-TOF-MS instrument, and (10) University of California, Berkeley's  
1259 TD-LIF.

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1261 ‡ (1) DISCOVER-Baltimore-Washington, (2) DISCOVER-Texas-Houston, (3) DISCOVER-  
1262 Colorado, and (4) KORUS-AQ  
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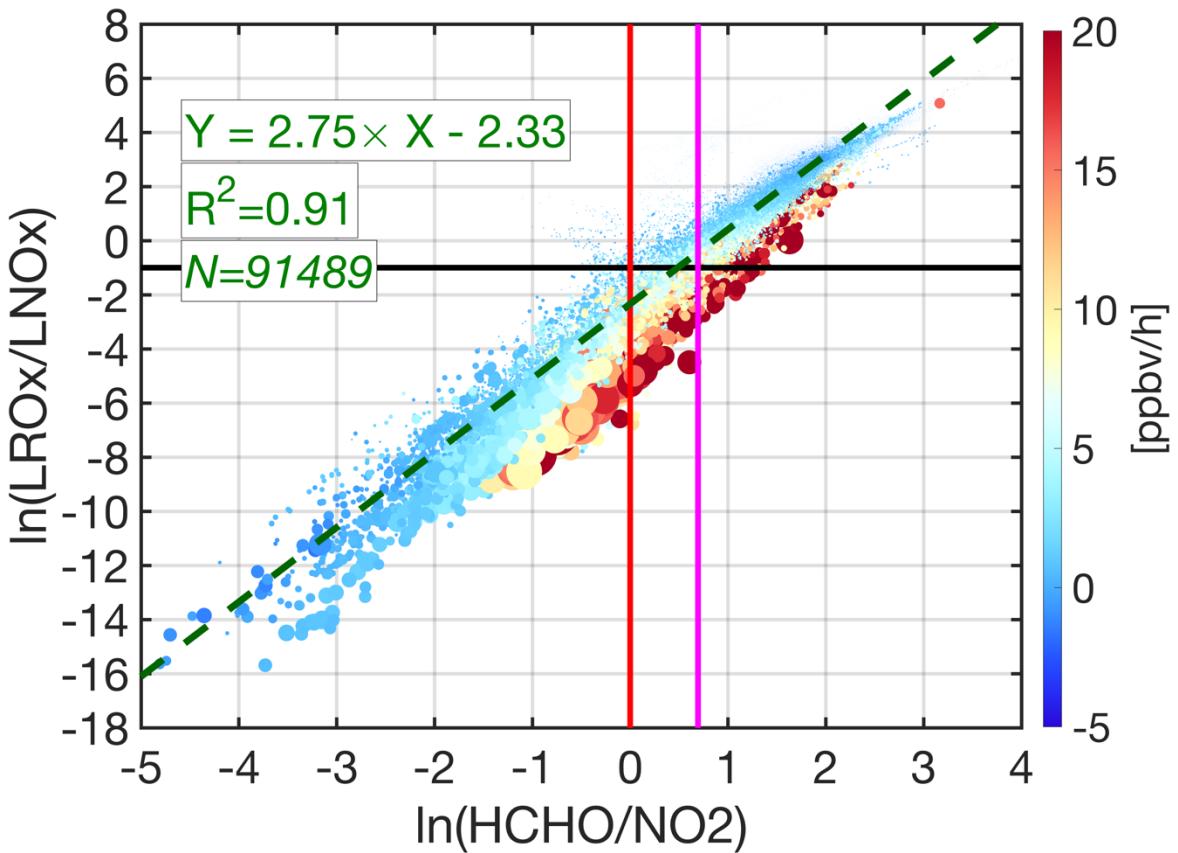
1264 § In the absence of measurements, a default value of 550 ppbv is specified.  
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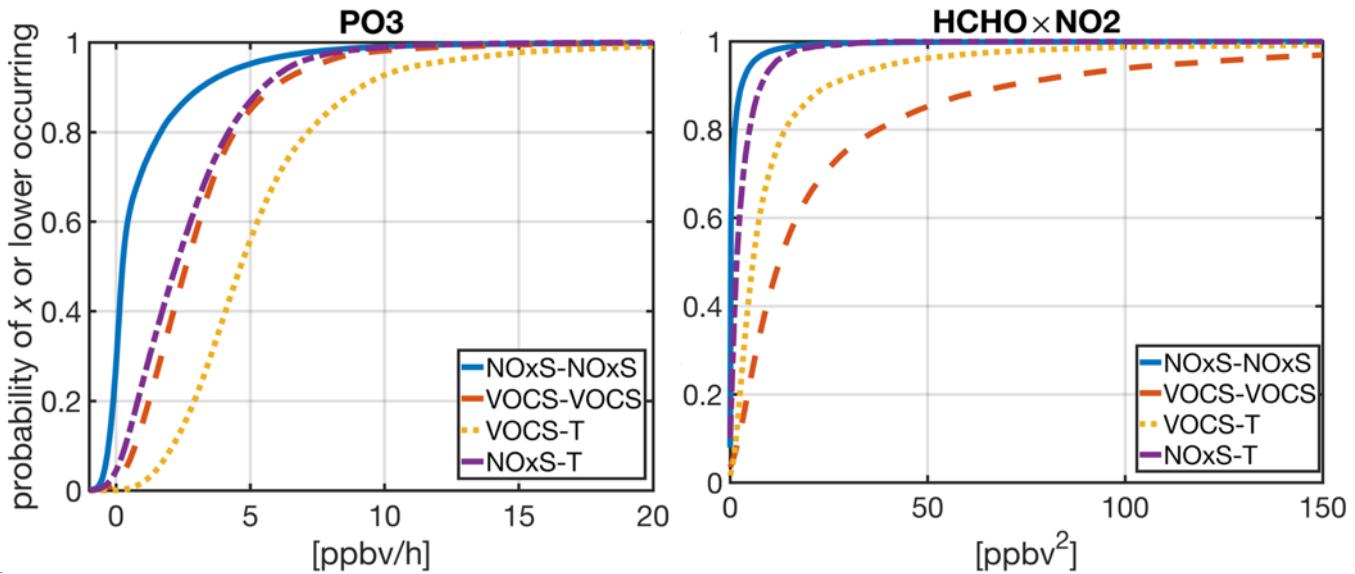
**Figure 1.** The spatial distributions of aircraft measurements collected during NASA's a) DISCOVER-AQ Houston-Texas, b) DISCOVER-AQ Baltimore-Washington, c) DISCOVER-AQ Colorado, and d) KORUS-AQ. The duration of each campaign is based on how long the aircraft was in the air.



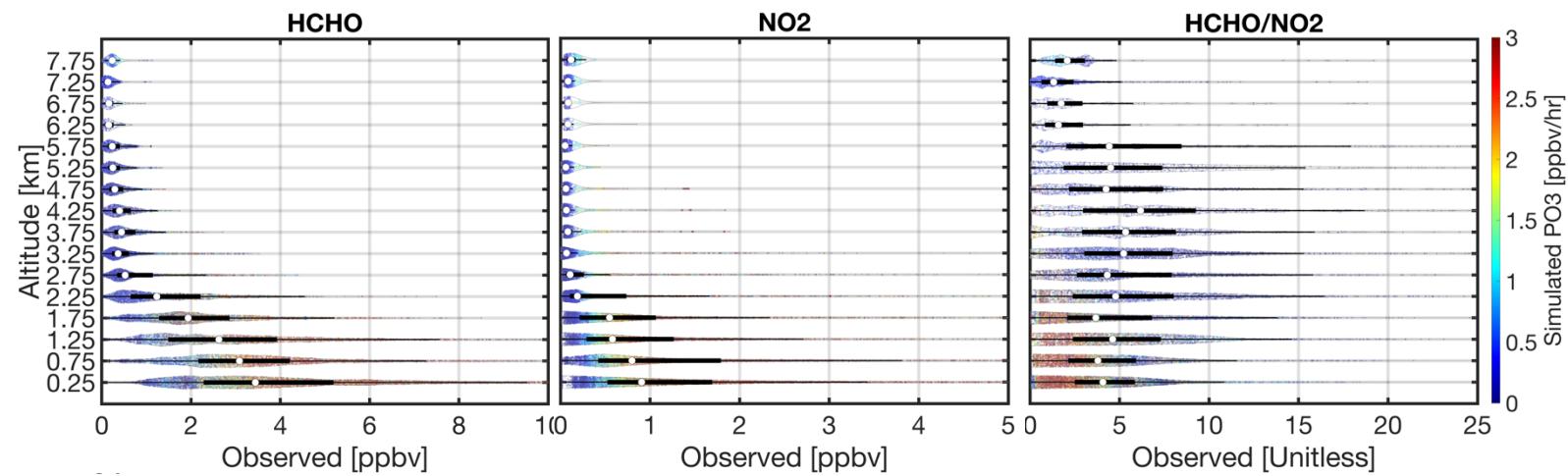
1277 **Figure 2.** The comparisons of the observed concentrations of several critical compounds to those  
1278 simulated by our F0AM box model. Each subplot contains mean bias (MB), mean absolute bias  
1279 (MAB), and root mean square error (RMSE). The least-squares fit to the paired data, along with  
1280 the coefficient of determination ( $R^2$ ) are also individually shown for each compound. Note that we  
1281 do not account for the observations errors in the x-axis. The concentrations of NO and NO<sub>2</sub> are  
1282 log-transformed.



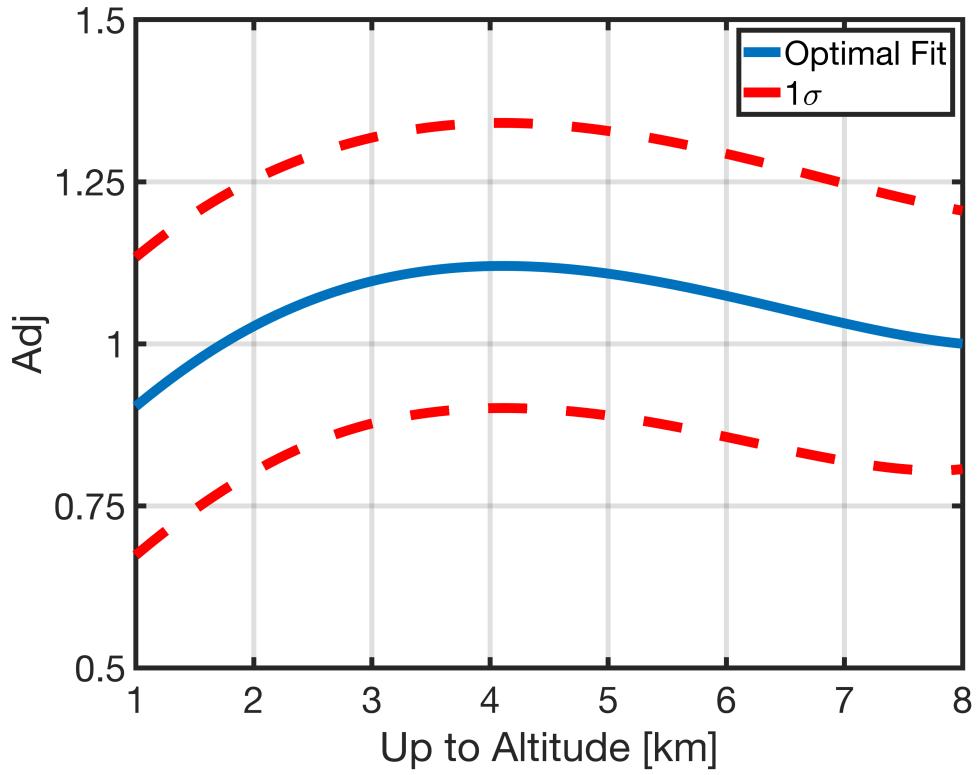
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 1285 **Figure 3.** The scatterplot of natural logarithm-transformed of HCHO/NO<sub>2</sub> versus LROx/LNOx  
 1286 based on the simulated values performed by the F0AM box model. The heat color indicates the  
 1287 calculated ozone production rates (PO<sub>3</sub>). The size of each data point is proportional to  
 1288 HCHO×NO<sub>2</sub>. The black line is the baseline separator of NOx-sensitive (above the line) and VOC-  
 1289 sensitive (below the line) regimes. We overlay HCHO/NO<sub>2</sub>=1 and HCHO/NO<sub>2</sub>=2 as red and  
 1290 purple lines, respectively. The dashed dark green line indicates the least-squares fit to the paired  
 1291 data. The HCHO/NO<sub>2</sub> = 1.8 with a 20% error is the optimal transitioning point based on this result.  
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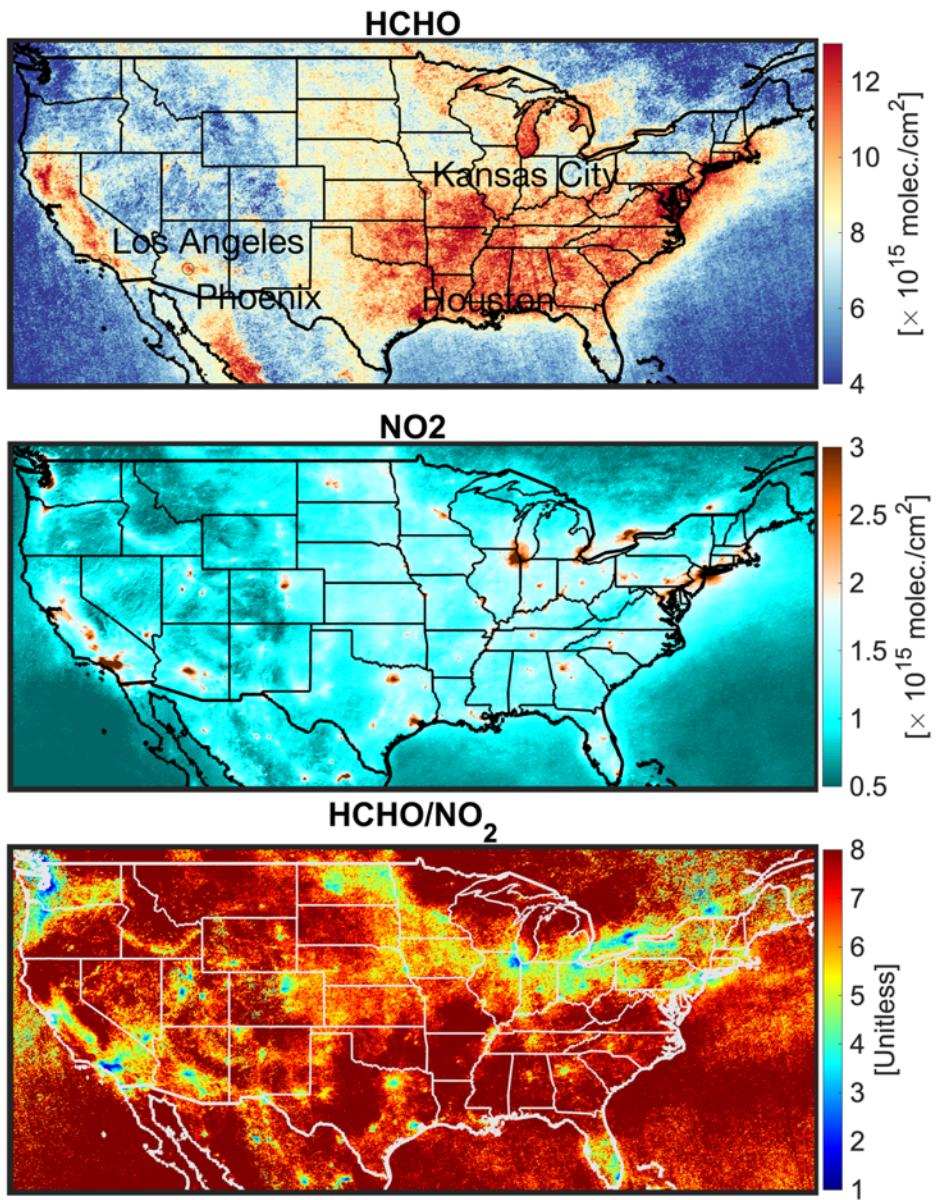
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1294 **Figure 4.** Cumulative distribution functions of  $\text{PO}_3$  and  $\text{HCHO} \times \text{NO}_2$  simulated by the box model  
1295 constrained by NASA's aircraft observations. Four regions are shown: NOx-sensitive — NOx-sensitive,  
1296 NOx-sensitive—transitional, VOC-sensitive—transitional, and VOC-sensitive—VOC-sensitive. The first  
1297 name of the regime is based on the baseline ( $\ln(\text{LROx/LNOx})=-1.0$ ), whereas the second one follows those  
1298 defined in Duncan et al. (2010): VOC-sensitive if  $\text{HCHO}/\text{NO}_2 < 1$ , transitional if  $1 < \text{HCHO}/\text{NO}_2 < 2$ , and  
1299 NO<sub>x</sub>-sensitive if  $\text{HCHO}/\text{NO}_2 > 2$ .  
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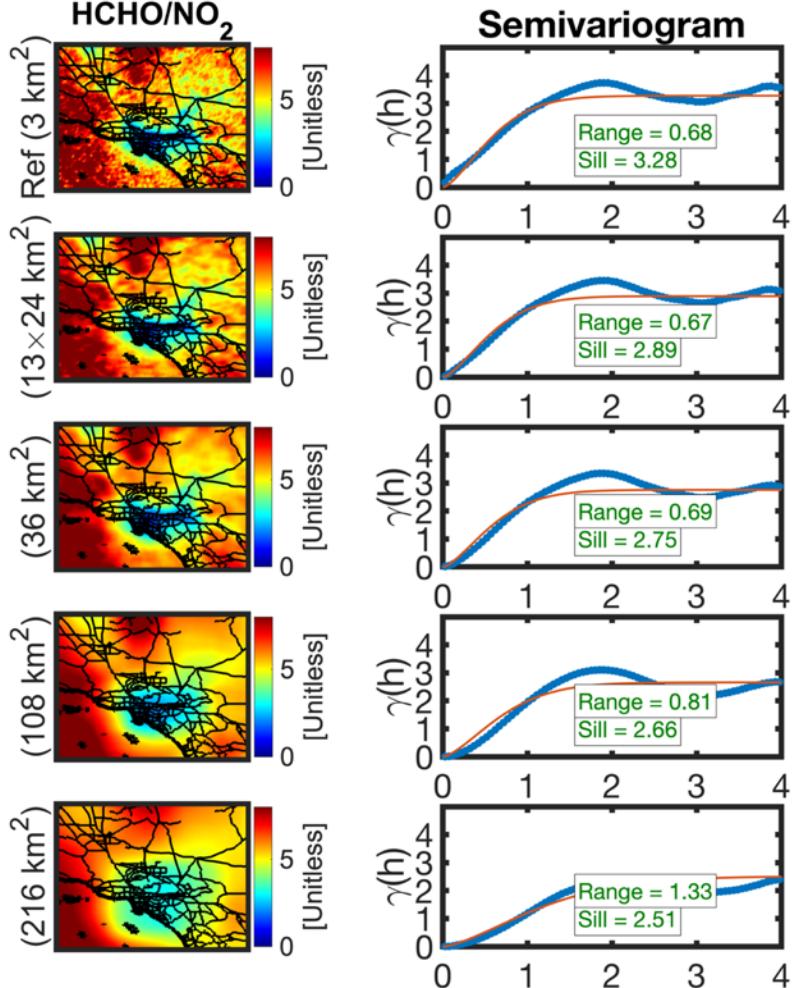
1302 **Figure 5.** The violin plots of the afternoon vertical distribution of HCHO, NO<sub>2</sub>, and HCHO/NO<sub>2</sub>  
1303 observations collected during DISCOVER-AQ Texas, Colorado, Maryland, and KORUS-AQ campaigns.  
1304 The violin plots demonstrate the distribution of data (i.e., a wider width means a higher frequency). White  
1305 dots show the median. A solid black line shows both the 25th and 75th percentiles. The heatmap denotes  
1306 the simulated ozone production rates.  
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 1310 **Figure 6.** The adjustment factor is the ratio of the centroid of the polygon bounding 25<sup>th</sup> and 75<sup>th</sup>  
 1311 percentiles of the observed HCHO/NO<sub>2</sub> columns by NASA's aircraft between the surface to 8 km  
 1312 to the ones between the surface and the desired altitude. This factor can be easily applied to the  
 1313 observed HCHO/NO<sub>2</sub> columns to translate the value to the desired altitude stretching down to the  
 1314 surface (i.e., PBLH). The optimal curve follows a quadratic function formulated in Eq.11.  
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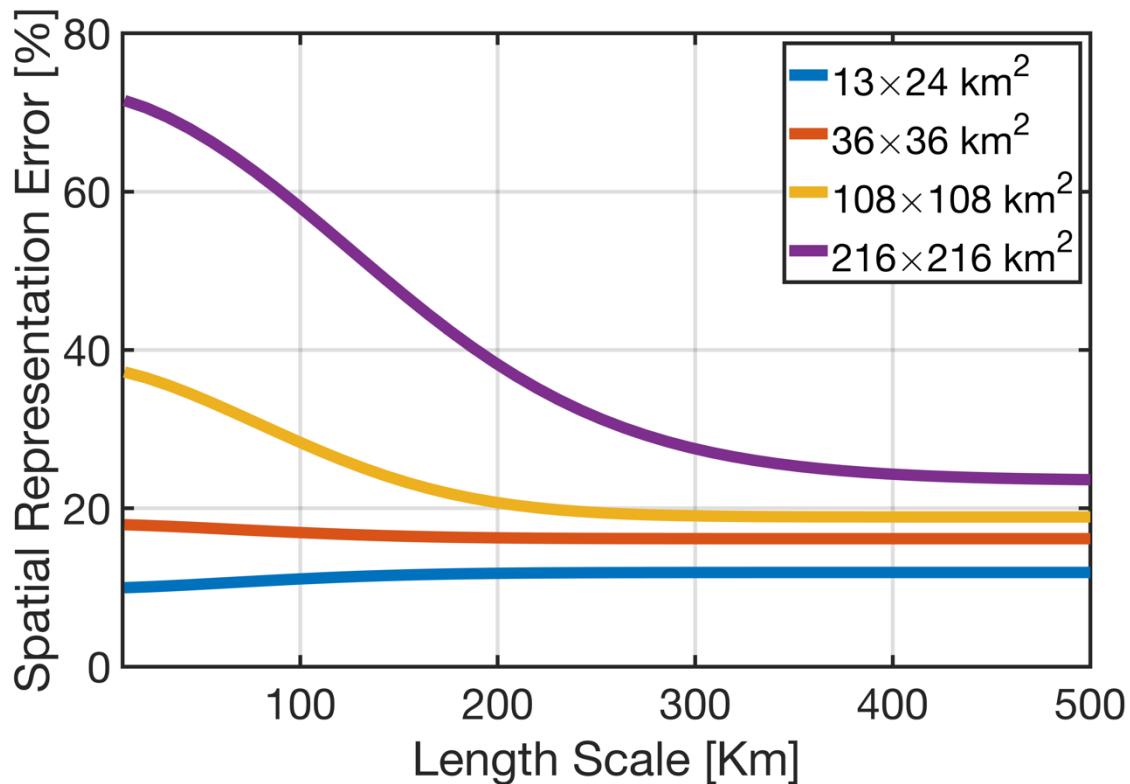


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 1317 **Figure 7.** Oversampled TROPOMI total HCHO columns (top), tropospheric NO<sub>2</sub> columns  
 1318 (middle), and the ratio (bottom) at 3×3 km<sup>2</sup> from June till August 2021 over the US. **The ratio map**  
 1319 **is derived from the averaged maps shown in the top and middle panels.**  
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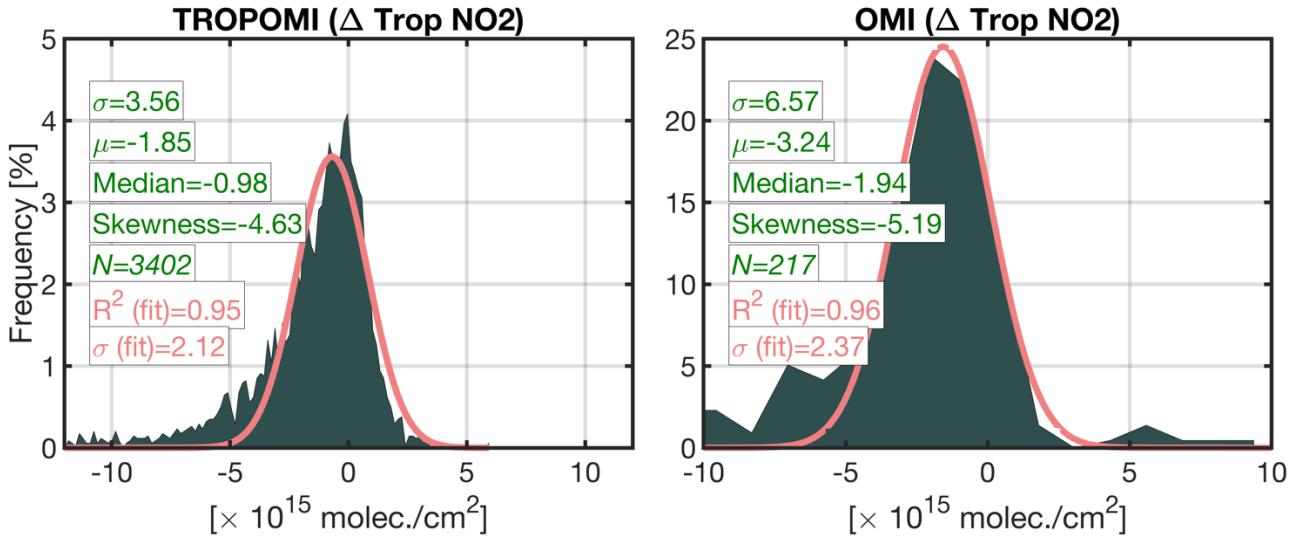


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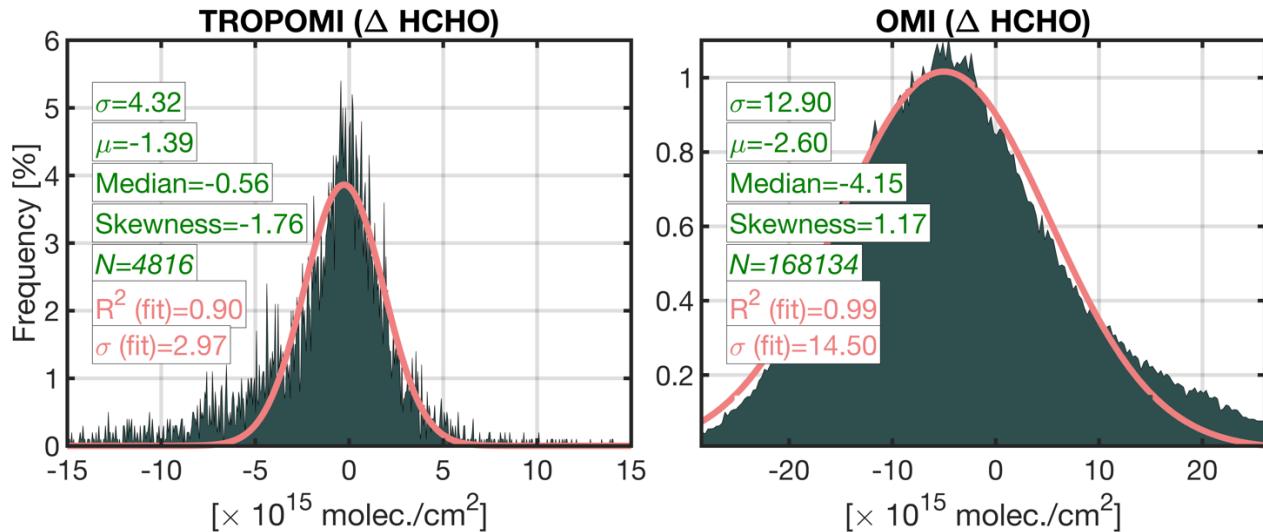
**Figure 8.** The first column represents the spatial map of HCHO/NO<sub>2</sub> ratios over Los Angeles from June till August 2021 at different spatial resolutions. To upscale each map to a coarser footprint, we use an ideal box filter tailored to the target resolution. The second column shows the semivariograms corresponding to the left map along with the fitted curve (red line). The sill and the range are computed based on the fitted curve. The x-axis in the semivariogram is in degrees (1 degree  $\sim 110$  km).



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1330 **Figure 9.** The spatial representation errors quantified based on the proposed method in this study.  
1331 The error explains the spatial loss (or variance) due to the footprint of a hypothetical sensor at  
1332 different length scales. To put this error in perspective, a grid box with  $216 \times 216 \text{ km}^2$  will naturally  
1333 lose 65% of the spatial variance existing in the ratio at the scale of Los Angeles, which is roughly  
1334 50 km wide. All of these numbers are in reference to the TROPOMI  $3 \times 3 \text{ km}^2$ .  
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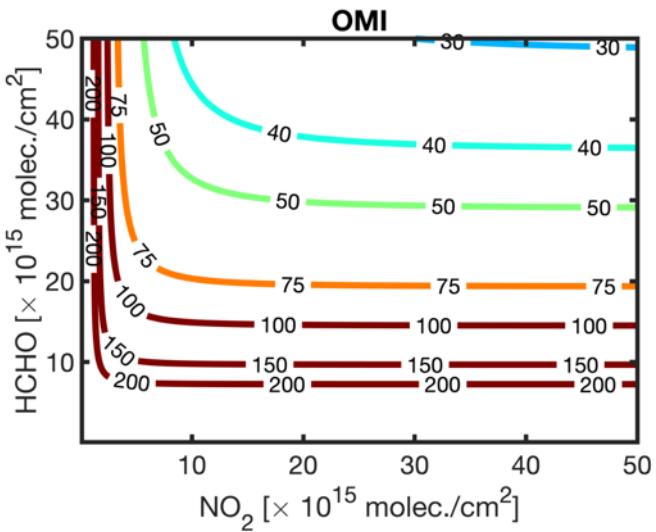
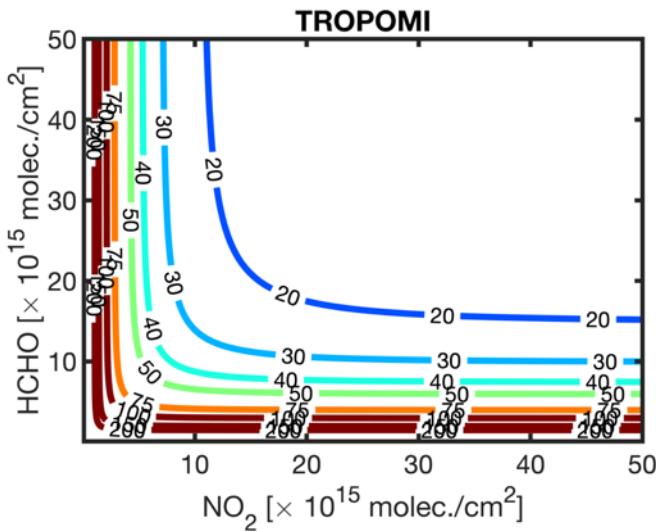


**Figure 10.** The histogram of the differences between TROPOMI and OMI and benchmarks. MAX-DOAS and integrated aircraft spirals are the TROPOMI and the OMI benchmarks, respectively. The data curation and relevant criteria on how they have been paired can be found in Verholest et al. (2021) and Choi et al. (2020). The statistics in green are based on all data, whereas those in pink are based on the fitted Gaussian function.

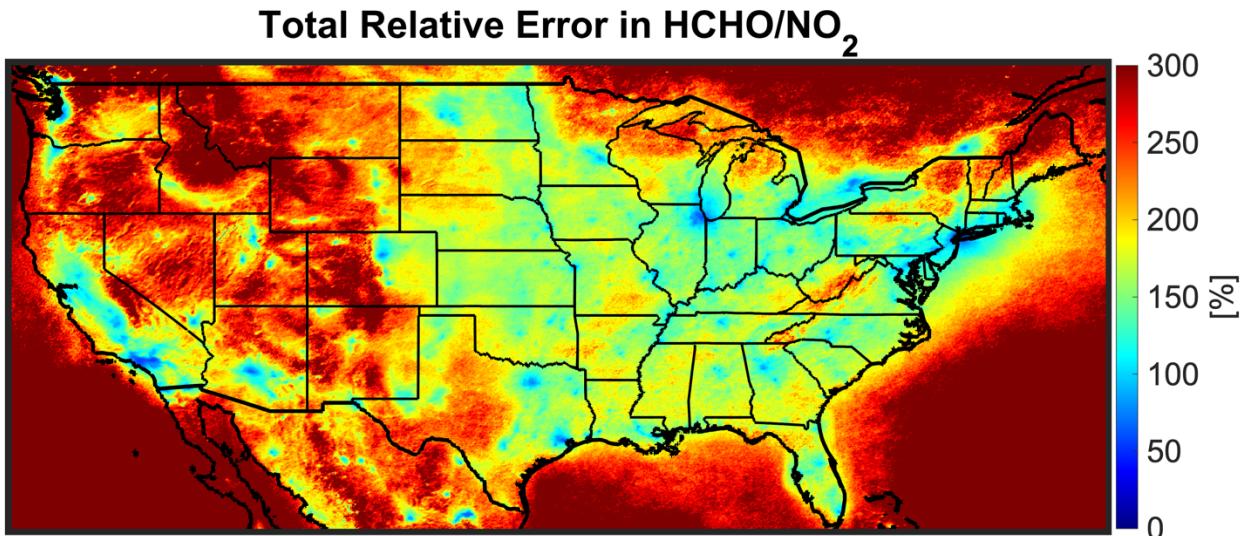


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**Figure 11.** The histogram of the differences between TROPOMI and OMI and benchmarks. FTIR and corrected GEOS-Chem simulations are the TROPOMI and the OMI benchmarks. The data curation and relevant criteria on how they have been paired can be found in Vigouroux et al. (2021) and Zhu et al. (2020). The statistics in green color are based on all data, whereas those in pink are based on the fitted Gaussian function.

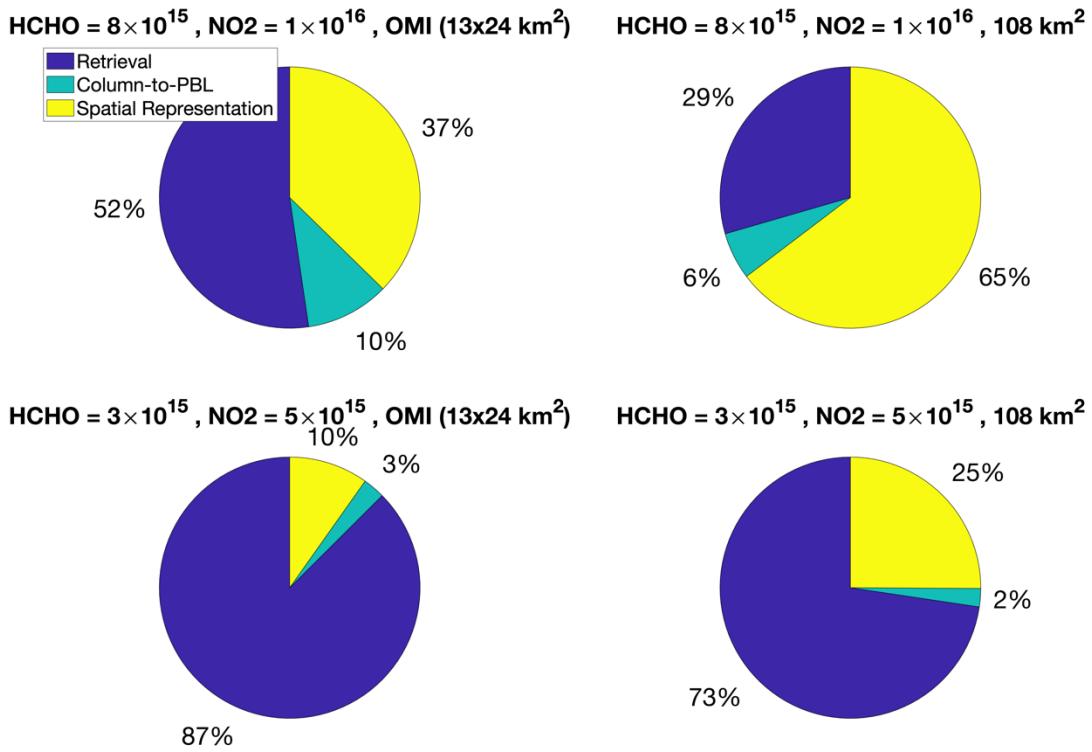


**Figure 12.** The contour plots of the relative errors in TROPOMI (left) and OMI (right) based on dispersions derived from Figures 10 and 11. The errors used for these estimates are based on daily observations.



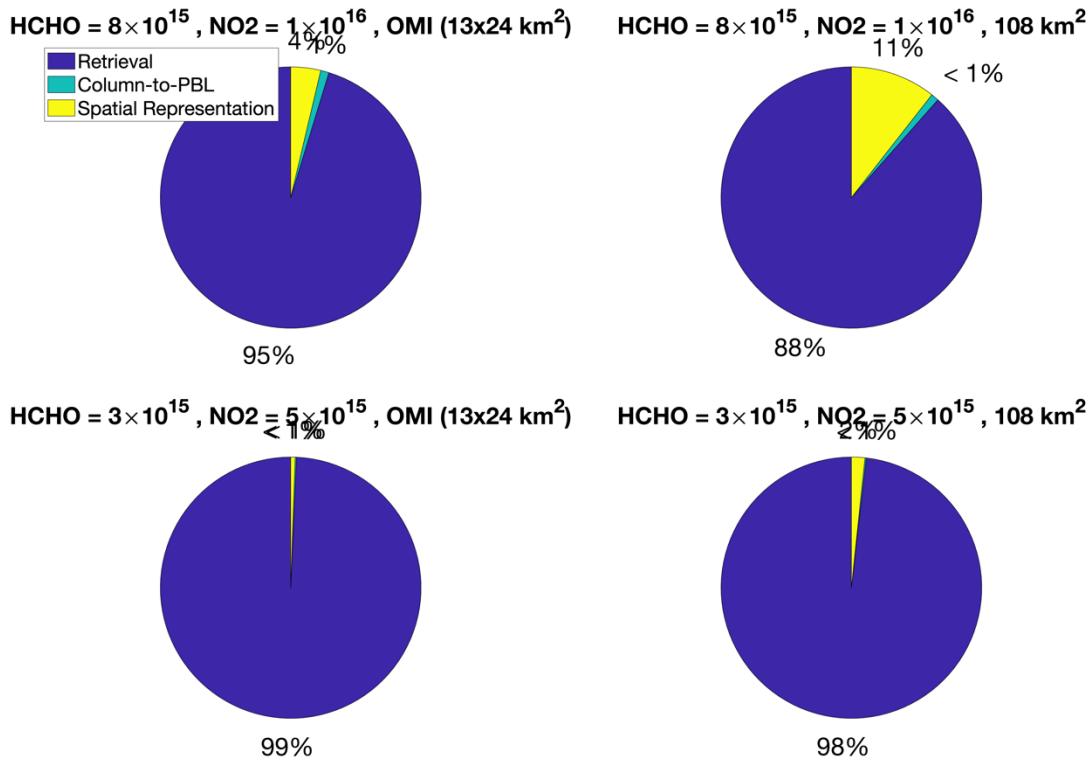
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**Figure 13.** The total relative error for observed TROPOMI HCHO/NO<sub>2</sub> ratios considering the daily TROPOMI retrieval errors ( $\sigma_{NO_2} = 2.11 \times 10^{15}$  molec./cm<sup>2</sup> and  $\sigma_{HCHO} = 2.97 \times 10^{15}$  molec./cm<sup>2</sup>), the spatial representation pertaining to OMI footprint over a city environment (13% loss in the spatial variance), and the column to the PBL translation parameterization (26%) proposed in this study. Please note that the observed FNR is based on mean values from June to August 2021, while the uncertainties used for error calculation are on a daily-basis.



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**Figure 14.** The fractional errors of retrieval (blue), column to PBL translation (green), and spatial representation (yellow) of the total error budget for different concentrations and footprints based on TROPOMI sigma values. The retrieval error used for the error budget is on a daily basis.



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**Figure 15.** Same as Figure 14 but based on OMI sigma values.