- 1 Modelling of street-scale pollutant dispersion by coupled simulation of
- 2 chemical reaction, aerosol dynamics, and CFD
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- 15 ABSTRACT
- 16 In the urban environment, gas and particles impose adverse impacts on pedestrians' health.
- 17 The conventional computational fluid dynamics (CFD) methods that regard pollutant as
- 18 passive scalar cannot reproduce the formation of secondary pollutants and lead to
- 19 uncertain prediction. In this study, SSH-Aerosol, a modular box model that simulates the
- 20 evolution of gas, primary and secondary aerosols, is coupled with the CFD softwares
- 21 OpenFOAM and Code Saturne. The transient dispersion of pollutants emitted from
- traffic in a street canyon is simulated using unsteady Reynolds-averaged Navier-Stokes
- equations (RANS) model. The simulated concentrations of NO₂, PM₁₀ and black carbon
- 24 are compared with field measurements on a street of Greater Paris. The simulated NO₂
- and PM₁₀ concentrations based on the coupled model achieved better agreement with
- 26 measurement data than the conventional CFD simulation. Meanwhile, the black carbon
- 27 concentration is underestimated, probably partly because of the underestimation of non-
- 28 exhaust emissions (tyre and road wear). Aerosol dynamics lead to large increase of
- ammonium nitrate and anthropogenic organic compounds from precursor-gas emitted in
- 30 the street canyon.
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- 32 Keywords
- Pollutant dispersion, Street canyon, Aerosol dynamics, CFD, PM₁₀, Secondary aerosols
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- 35 1. Introduction
- 36 Traffic-related pollutants can impose adverse effects on pedestrians' health in the urban

- 37 environment (Anenberg et al., 2017; Jones et al., 2008). Especially, particulate matter
- 38 (PM) is strongly associated with increased cardiovascular diseases (Du et al., 2016).
- 39 Therefore, investigating the dispersion of PM and the corresponding precursor gas is of
- 40 great significance to evaluate the environmental impact and devise suitable
- 41 countermeasures (Kumar et al., 2008).
- 42 With the development of numerical simulations, computational fluid dynamics (CFD) has
- been widely used for near-field dispersion prediction (Tominaga and Stathopoulos, 2013).
- 44 The pollutant dispersion patterns in complex geometric and non-uniform building
- 45 configurations can be well predicted using CFD simulations (Blocken et al., 2013).
- 46 Pollutant dispersion, deposition and transformation (chemical reactions and aerosol
- dynamics) have primary roles in near-field prediction models. However, most CFD-based
- studies assume that the time scale of transport at the street scale (~ 100 m) is relatively
- shorter than the time scale of deposition and transformation; therefore, they frequently
- regard pollutants as inert matter. Meanwhile, the recirculation flows which commonly
- exist in street canyons lead to low-ventilation zones and may provide sufficient time for
- transformation (Lo and Ngan, 2017; Zhang et al., 2020).
- In addition, when PM is transported as a passive scalar, the distribution of the total
- 54 concentration can be simulated, however, information on the particle size distribution and
- 55 chemical composition is unclear. Understanding the size distribution is important for
- evaluating the health hazards because large particles are deposited in the mouth and upper
- 57 airways, whereas smaller particles deposit deeper in the lungs and can even reach the
- alveolar region of the lungs (Sung et al., 2007). In addition, as particles of different
- 59 chemical compositions are related to different sources and/or precursor gases, gaining
- 60 knowledge of their composition may help devise countermeasures to limit their
- 61 concentrations (Kim, 2019).
- 62 To simulate pollutant concentrations considering both transport and transformation, many
- studies have coupled air-quality models with gas-phase chemistry and aerosol modules
- and achieved chemical transport from a regional scale (~100 km) (Sartelet et al., 2007) to
- a street scale (Lugon et al., 2021b). However, few models can simultaneously represent
- detailed particle dispersion in a complicated urban flow field considering secondary
- aerosol formation.
- 68 For the recent development and application of CFD-chemistry coupling model, Kurppa
- et al., (2019) implemented a sectional aerosol module into large eddy simulation (LES),
- and conducted a particle dispersion simulation on a neighborhood scale. Gao et al., (2022)
- employed the same model to examine the dispersion of cooking-generated aerosols in an
- 72 urban street canyon. In both studies, the effect of particle dynamics on aerosol number

74 not detailed. In addition, the chemical reactions of the precursor gas were not considered. 75 Kim et al., (2019) coupled unsteady Reynolds-averaged Navier-Stokes (RANS) model 76 with gas chemistry and aerosol modules and conducted simulations of PM₁ in a street 77 canyon under summer and winter conditions. The diurnal variations, spatial distribution 78 and chemical composition of pollutants in the street canyon were investigated. However, 79 the size distribution of particles and the secondary organic aerosol (SOA) chemistry were 80 not considered. Therefore, a more comprehensive coupled model is needed to simulate 81 the evolution of gas concentrations, mass and number concentrations of primary and 82 secondary particles at the same time. 83 Vehicles are considered to be the main ammonia (NH₃) source in urban environments 84 (Sun et al., 2017). Reactive nitrogen emissions from many new vehicles are now 85 dominated by NH₃ (Bishop and Stedman, 2015). Since the formation of ammonium 86 nitrate is often limited by HNO₃ rather than NH₃ in urban areas (NH₃-limited), increasing 87 NH₃ may lead to increased ammonium nitrate production and PM concentration in urban 88 streets (Lugon et al., 2021b). However, NH₃ emissions from passenger cars are usually 89 not regulated (Suarez-Bertoa and Astorga, 2018). Therefore, to provide evidence in 90 making policies for NH₃ emission regulation, it is important to investigate the local 91 influence of NH₃ emissions on PM concentrations. 92 Therefore, to achieve a more comprehensive simulation of PM and related precursor gas, 93 this study couple two open-source CFD softwares: OpenFOAM (OpenFOAM user guide) 94 and Code Saturne (Archambeau et al., 2004), with gas-phase chemistry and aerosol 95 module SSH-Aerosol (Sartelet et al., 2020). Both OpenFOAM and Code Saturne own 96 wide users. Therefore, coupling SSH-aerosol with both CFD softwares may satisfy more 97 needs. Simulations of the PM concentrations in a two-dimensional street canyon are 98 conducted. The coupled model is validated by comparison to field measurements. The 99 size distributions and chemical compositions of particles from the models with and 100 without secondary aerosol formation are compared. In addition, cases with large NH₃ 101 emissions are considered and the related PM increase is investigated. 102 The remainder of this paper is organized as follows. The coupling of the aerosol model 103 and CFD is introduced in Section 2. The computational details are presented in Section 3. 104 In Section 4, the simulated pollutant concentrations are compared with field 105 measurements, followed by evaluations of the influence of the grid, coupling method and 106 time step. In Section 5, spatial and temporal variations in the concentrations are analyzed. 107 The chemical compositions and size distributions of the particles between the coupled 108 model and the model that does not consider gas chemistry or aerosol dynamics are

concentration was well reproduced. However, the simulated chemical composition was

compared. In addition, the effect of NH₃ traffic emissions on particle concentrations is discussed. Finally, the conclusions and perspectives are presented in Section 6.

The coupling method between CFD and chemistry modules is similar to the literature

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2. Model description

114 (Gao et al., 2022; Kurppa et al., 2019). OpenFOAM v2012 and Code Saturne 6.2 are 115 used to solve the governing equations of the flow field and transport equations of gas and 116 particle mass fractions. The inflow conditions, pollutants' background concentrations and 117 emission rates are obtained from regional models, and are linearly interpolated into each 118 time step, which will be introduced in Section 3. This simulation method is called 119 transient-condition method (TCM) in this study. However, because time-varying flow 120 fields and concentration fields are expensive to compute in terms of computational time, 121 conducting CFD simulations with fixed boundary conditions and emission rates at 122 specific time points is considered a practical method for evaluating street-level pollutant 123 concentrations (Wu et al., 2021; Zhang et al., 2020). The transport (advection and 124 diffusion) and chemical processes will reach equilibrium, and the simulated 125 concentrations will reach quasi-stable values. These values are often regarded as time-126 averaged concentrations. This method is called the constant-condition method (CCM) in 127 this study, in contrast to TCM. However, the simulation accuracy of CCM has not been 128 validated in simulations that consider both gas chemistry and particle dynamics. 129 Therefore, validation is conducted using boundary conditions and emission rates at 130 specific time points and the simulated concentrations with CCM and TCM are compared 131 in Section 4.2. 132 The unsteady RANS model is used for the transient simulations with both CFD codes. In 133 OpenFOAM, the RNG (Re-Normalisation Group) k-ε model (Yakhot et al., 1992) is 134 deployed for turbulence closure. All transport equations are discretized using the total 135 variation diminishing (TVD) scheme (Harten, 1984; Yee, 1987), which combines the 136 first-order upwind difference scheme and the second-order central difference scheme. The 137 PIMPLE algorithm, a merged PISO (Pressure Implicit with Splitting of Operator)— 138 SIMPLE (Semi-Implicit Method for Pressure-Linked Equations) algorithm in the 139 OpenFOAM toolkit, is used for pressure–velocity coupling. In Code Saturne, turbulence 140 is solved using the k-\varepsilon turbulence model (linear production) (Guimet and Laurence, 2002). 141 The time and space discretizations of velocity, pressure and other scalars in all transport 142 equations are realized through a centred scheme and a fractional step scheme 143 (Archambeau et al., 2004). For both CFD software, the dry deposition schemes for gas 144 and particle are added to the transport equations using volume sink terms based on Zhang

146 provided in Appendix A. 147 SSH-Aerosol (Sartelet et al., 2020) is a modular box model that simulates the evolution 148 of not only gas concentrations but also the mass and number concentrations of primary 149 and secondary particles. In SSH-Aerosol 112 gas species and 40 particle species are 150 considered. The particle compounds are dust, black carbon, inorganics (sodium, sulphate, 151 ammonium, nitrate and chloride), primary organic aerosol (POA) and secondary organic 152 aerosol (SOA). Three main processes involved in aerosol dynamics (coagulation, 153 condensation /evaporation and nucleation) are included. The particle size distribution is 154 modelled using a sectional size distribution. Nucleation is not considered in this study 155 because only the mass and not the number of particles is available for evaluation, and large uncertainties remain on the nucleation parameterizations (Sartelet et al., 2022) 156 157 mostly affecting the number of particles. As nucleation is not considered, the minimum 158 diameter does not need to be as low as 0.001 µm, and it is fixed to 0.01 µm, as in the 159 regional-scale simulations of Sartelet et al. (2018), which provide the background 160 concentrations. Six particle size sections are employed with bound diameters of 0.01, 0.04, 161 0.16, 0.4, 1.0, 2.5 and $10 \mu m$. 162 The coupling between CFD and SSH-aerosol are achieved by using the application 163 program interface (API) of SSH-aerosol. The gas and particle concentrations are 164 initialized in CFD and are transported in the domain for each time step. For each grid 165 volume cell, these transported concentrations, as well as meteorological parameters, such as temperature and humidity, are then sent to SSH-aerosol to advance one time step of 166 167 gaseous chemistry and aerosol dynamics. Once the SSH-aerosol calculation is completed, 168 the concentrations are sent back to the CFD for the next time step. It should be noted that 169 as the SSH-aerosol processes the ensemble-averaged concentration from RANS model, 170 the covariance of turbulent diffusion and chemical reaction may not be fully reproduced.

The influence of different operator splitting algorithms is discussed in Section 4.4.

et al. (2003) and Zhang et al. (2001), respectively. The details of the implementation are

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173 3. Simulation setup

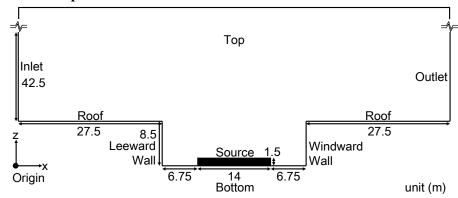


Fig. 1 Simulation domain of street canyon

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The simulation is set up to model a street in Greater Paris (Boulevard Alsace-Lorraine), where field measurements were conducted from April 6 to June 15, 2014. The concentrations of nitrogen dioxide (NO₂), particles with diameters less than $10 \mu m$ (PM₁₀), and black carbon were measured as described in (Kim et al., 2018). Fig. 1 shows the simulation domain. The 2-D street canyon is 27.5 m in width (W) and 8.5 m in height (H). The domain height is 6 H. The street canyon is discretized into uniform grids in xand z- directions. The grid resolutions in the street canyon are 0.5 m in both x-and zdirections, respectively. The largest grid sizes are 4 m (x) \times 2m (z). An analysis of the grid sensitivity is described in Section 4.3. Simulations are conducted from 4:30 a.m. to 5 p.m. on April 30, 2014 at local time (GMT+2). This period is selected because the wind direction is almost perpendicular to the street canyon during that day, allowing for a 2D simulation setting. During the field measurement, there exists several time periods that the wind direction is perpendicular with the street canyon. Meanwhile, some time periods are short (less than 5 hours), and we consider that short period simulation is not representative in simulation accuracy. In addition, we consider that it is critical to have a simulation time long enough to cover both day-time chemistry and night-time chemistry. The first 30 minutes of the simulation corresponds to model spin-up, and the simulation lasts 12 hours. A sensitivity analysis of numerical aspects, such as the splitting method between transport and chemistry and the time step, is described in Section 4.4.

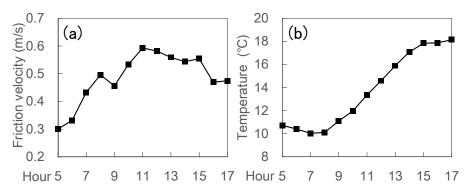


Fig. 2 Time variations of hourly friction velocity and temperature for inflow.

Meteorological conditions (Fig. 2) including time-varying friction velocity and temperature are obtained from the simulation described in Sartelet et al. (2018) using the Weather Research and Forecasting (WRF) model. The grid resolution is 1 km \times 1 km in Paris. The lowest and highest friction velocities occurred approximately at 5 a.m. and 11 a.m., respectively. The lowest and highest temperatures are around 8 a.m. and 5 p.m. For the inflow, the wind direction is perpendicular to the street canyon. The friction velocity u_* is used to prescribe the vertical profiles of the streamwise velocity U, turbulent kinetic energy k and turbulent dissipation rate ε as follows

$$U(z) = \frac{u_*}{\kappa} \ln \left(\frac{z - H}{z_0} \right) \tag{1}$$

$$k(z) = \frac{u_*^2}{\sqrt{C_\mu}} \tag{2}$$

$$\varepsilon(z) = \frac{u_*^3}{\kappa(z - H)} \tag{3}$$

where κ is the von Kármán constant and C_{μ} is the model constant (=0.09) in the k- ϵ model. The roughness length z_0 is set to 1 m for the inlet (Belcher, 2005) and 0.1 m for the wall and bottom (Lo and Ngan, 2015).

In addition, since the domain height is low (51 m) in this study and we focus on the pollutant dispersion behaviors in the street canyon, it is reasonable to consider the atmospheric stability as neutral; therefore the temperature is assumed to be spatially uniform at the inflow. The hourly friction velocities and temperatures are linearly interpolated into each timestep and prescribed at the inflow. It should be noted that the general trends are simulated but the fast fluctuations at the inlet are not reproduced. The same linear interpolation is used for background concentrations and emission rates, which will be described in the following.

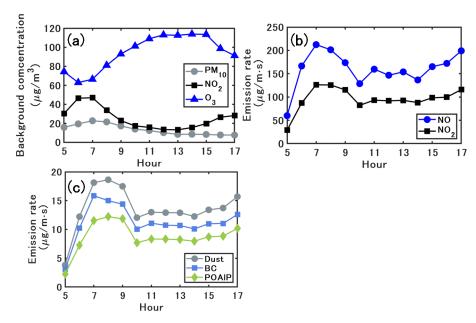


Fig. 3 Time variations of (a) PM₁₀, NO and NO₂ background concentrations, (b) emission rates of NO and NO₂ and (c) emission rates of dust, BC and organics (POAIP).

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Fig. 3(a) shows the time variations of the PM₁₀, NO and NO₂ background concentrations. Fig. 3(b) and (c) show the emission rates for NO, NO₂ and the emitted compounds of PM₁₀. The background concentrations of the gas and particles are obtained from the regional-scale simulations of Sartelet et al. (2018) with the Eulerian model Polair3D of the Polyphemus air quality modelling platform (Mallet et al., 2007), which uses the same chemical representation as in this study. As detailed in Sartelet et al. (2018), the regional background concentrations compare well to measurements of O₃, NO₂, PM₁₀, PM_{2.5}, black carbon and organic aerosols. The hourly background concentrations are linearly interpolated into each timestep and spatial-uniformly prescribed at the inflow and top. The traffic emission source is assumed to be approximately 14 m in width and 1.5 m in height, and it is set in the middle of the bottom of the canyon (Fig. 1). As detailed in Kim et al. (2022), emissions are estimated from the fleet composition and the number of vehicles in the street using COPERT's emission factors (COmputer Program to calculate Emissions from Road Transport, version 2019, EMEP/EEA, 2019). After the speciation of NOx, Volatile Organic Compounds (VOC), PM2.5 and PM10 into model species, emissions are set for 16 gaseous model species and three particle model species: dust and unspecified matter (Dust), black carbon (BC) and primary organic aerosol of low volatility (POAIP). The PM size distribution at emission is assumed to be the same as in the previous studies (Lugon et al., 2021a, 2021b). The exhaust primary PM is assumed to be in the size bin $[0.04 - 0.16 \mu m]$ while non-exhaust primary PM is coarser in the size

244 bin $[0.4 - 10 \mu m]$.

For the boundary conditions of the OpenFOAM, the pressure and the gradients of all other variables are set to zero at the outlet. For the walls, we use the wall functions of ε and turbulent kinematic viscosity ν_t for atmospheric boundary layer modelling in OpenFOAM toolkit (OpenFOAM user guide) based on (Parente et al., 2011). The gradients of turbulent kinetic energy k, concentration, and temperature are set to zero. In Code_Saturne, a two-scales logarithmic friction velocity wall function is used for solving the fluid velocity near wall cell and a three layers wall function is used for computing other transported scalar profiles such as temperature near the wall (Arpaci and Larsen, 1984).

The turbulent Schmidt number Sc_t in the concentration transport equations, which is the ratio of the turbulent diffusivity to the concentration and turbulent kinematic viscosity, is important in turbulent diffusion modeling. The value of Sc_t is considered between 0.2 and 1.3, depending on the flow properties and geometries (Tominaga and Stathopoulos, 2007). For urban environments with a compact layout, a small $Sc_t = 0.4$ is found to show better agreement with wind tunnel experiment data (Di Sabatino et al., 2007). Therefore, a value of 0.4 is adopted in the current study.

4. Model evaluation

4.1. Validation with field measurements and comparison of simulated concentrations with the two CFD software

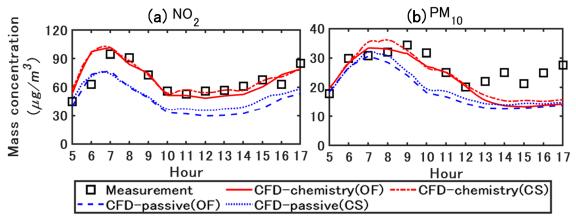


Fig. 4 Measured and simulated NO₂ and PM₁₀ concentrations. The values are spatially averaged in the street canyon ($27.5 \le x \le 55$, $0 \le z \le 8.5$ m). CFD-passive and CFD-chemistry denote the CFD simulation without and with chemistry coupling. OF and CS denote the simulated concentrations based on OpenFOAM and Code_Saturne. All concentrations are represented in local time (GMT+2).

272 Reproducing the flow field is important in this study. Meanwhile, the observation data on 273 wind velocity is not available. Therefore, we conducted a velocity validation for 274 OpenFOAM v2012 using data from a wind tunnel experiment (Blackman et al., 2015). 275 The predicted mean velocity agreed well with the experimental values. The details can be 276 found at Appendix B. 277 Fig. 4 compares the simulated concentrations with those obtained from the field 278 measurements. In the field measurements, the measured concentration was obtained from 279 averaging over two measurement points near the leeward and windward walls in the street 280 canyon. In this section, the simulated results and discussion are based on the spatially-281 averaged values in the street canyon (27.5 $\leq x \leq$ 55, 0 $\leq z \leq$ 8.5 m). CFD-passive and 282 CFD-chemistry denote the CFD simulation without and with chemistry coupling. OF and 283 CS denote simulated concentrations based on OpenFOAM and Code Saturne. The 284 operator splitting order and time step for OF and CS are the A-B-A splitting method with 285 0.5 s and the A-B splitting method with 0.25 s, as detailed in Section 4.4. The simulation 286 time ratio of CFD-chemistry and CFD-passive is about three times in both OpenFOAM 287 and Code Saturne in this study. 288 For NO₂, the peak concentration in the field measurement occurred approximately at 7 289 a.m. owing to the morning traffic. In the CFD-passive simulations, the lack of chemical 290 reactions lead to an underestimation of NO2, while the concentrations simulated with 291 CFD-chemistry agree well with the measurements. For PM₁₀, the concentrations 292 simulated with CFD-chemistry also show better agreement with the measurements than 293 CFD-passive. The primary reason is that CFD-chemistry can reproduce the condensation of inorganic and organic matter from the gas phase to the particle phase, which will be 294 295 further explained in the following sections. The simulation results based on OF and CS 296 show small differences, and detailed comparisons are presented in Fig. 6. 297 Validation metrics (Chang and Hanna, 2004) are used to quantify the overall accuracy of 298 the CFD simulated concentrations based on OF, compared with the measured values 299 (Trini Castelli et al., 2018; Ferrero et al., 2019). The following metrics are used: fractional

$$FB = \frac{\overline{Obs} - \overline{CFD}}{0.5(\overline{Obs} + \overline{CFD})}$$
 (4)

$$MG = \exp(\overline{\ln Obs} - \overline{\ln CFD}) \tag{5}$$

bias (FB), geometric mean bias (MG) and normalized mean square error (NMSE). These

$$NMSE = \frac{\overline{(Obs_t - CFD_t)^2}}{\overline{Obs} \times \overline{CFD}}$$
 (6)

where Obs_i and CFD_i are the measured and CFD simulated concentrations for the

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metrics are defined as follows:

compound/species *i*, respectively. The overbar represents the mean value of the entire dataset. The ideal values are 1 for MG, and 0 for FB and NMSE. Previous research has suggested that |FB| < 0.3, 0.7 < MG < 1.3 and NMSE < 4 are acceptable for simulated concentrations (Hanna et al., 2004).

Table 1 shows the statistical indicators for spatially averaged concentrations of NO₂ and PM₁₀ in the street canyon from 5 a.m. to 5 p.m. For NO₂ and PM₁₀, the mean and 90% percentile concentrations simulated with CFD-chemistry are closer to the measurements than those simulated with CFD-passive. In addition, the FB, MG and NMSE values of CFD-chemistry are closer to the ideal values than those of CFD-passive.

Table 1 Statistical indicators for NO₂ and PM₁₀ in the street canyon from 5 a.m. to 5p.m. The concentrations are simulated with OpenFOAM.

	Concentration (µg/m³)		Validation metrics		
NO ₂	Mean	Percentile 90%	FB	MG	NMSE
Measurement	66.6	91.8	/	/	/
CFD-chemistry	67.3	97.3	-0.01	1.00	1E-4
CFD-passive	45.9	73.7	0.36	1.50	0.14
PM ₁₀	Mean	Percentile 90%	FB	MG	NMSE
Measurement	26.4	32.5	/	/	/
CFD-chemistry	22.3	33.1	0.17	1.23	0.03
CFD-passive	18.8	28.9	0.34	1.45	0.13

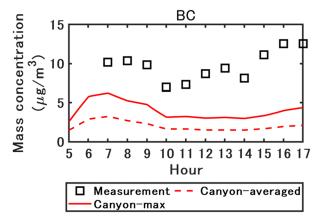


Fig. 5 Measured and simulated black carbon concentrations with OpenFOAM. The canyon-averaged and maximum concentrations in the street canyon are represented by the plain line and the dashed line respectively $(27.5 \le x \le 55, 0 \le z \le 8.5 \text{ m})$.

The black carbon (BC) concentration simulated with OF is compared with the measurements in Fig. 5. Because BC is considered an inert matter, considering chemistry does not influence the mass concentration. Therefore, the concentrations simulated with CFD-passive and CFD-chemistry show little difference; only the concentration simulated with CFD-chemistry is shown here. The BC concentrations are underestimated by a factor of approximately 5. Even the maximum concentrations in the street canyon largely underestimate the measurements. One of the causes of this underestimation may be the underestimation of the non-exhaust tyre emission factors in the COPERT emission factors used here (Lugon et al., 2021a).

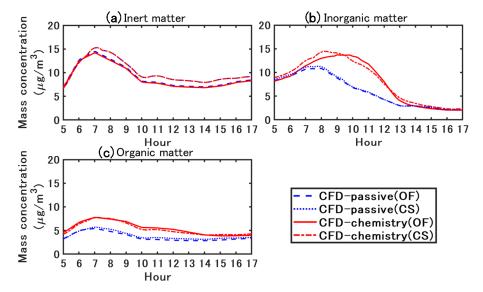


Fig. 6 Simulated particle concentrations with OpenFOAM (OF) and Code_Saturne (CS). CFD-passive and CFD-chemistry denote the CFD simulation without and with chemistry coupling.

The particle concentrations simulated with OF and CS are compared in Fig. 6. The evolutions of the concentrations simulated by OF and CS are similar. Higher PM₁₀ concentrations are simulated by CS around 8 a.m. during the traffic peak and in the afternoon, mostly because of the higher concentrations of emitted inert compounds, such as black carbon and dust. Differences in the turbulence scheme may explain these variations. Meanwhile, the difference between CFD-passive and CFD-chemistry for the inorganic and organic matter is in accordance with OF and CS, showing the robustness of the coupling method between CFD and SSH-aerosol by API. For simplicity, only the simulated concentration based on OF is presented and discussed in the following sections.

4.2. Transient-condition method and constant-condition method

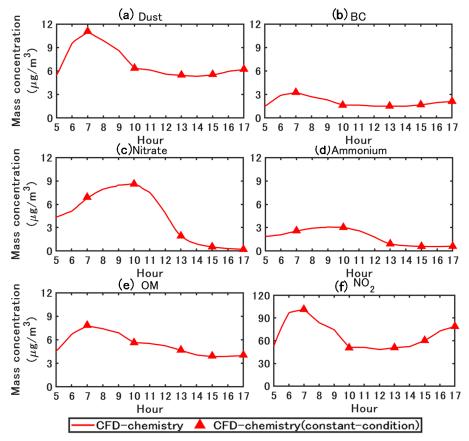


Fig. 7 Simulated PM₁₀ and NO₂ concentrations with the transient-condition and constant-condition methods. The concentrations are spatially averaged in the street canyon.

To validate the simulation accuracy of CCM in simulations that consider both gas chemistry and particle dynamics, simulations are conducted using boundary conditions and emission rates at five time points (7 a.m., 10 a.m., 1 p.m., 3 p.m. and 5 p.m.). Other simulation conditions, including the grid, coupling method, and time step, are the same as the transient-condition simulation.

In Fig. 7, for PM₁₀ and NO₂, the concentrations simulated with CCM (red triangles) are similar to those simulated with TCM. In addition, depending on the background concentration and emission conditions, the simulation time required for CCM to reach dynamic equilibrium is less than 1000 time steps (approximately 500 s). Therefore, CCM can be utilized for parameter studies. The sensitivity analysis of the grid, coupling method and time step in Section 4.3 and 4.4 is based on CCM. However, CCM should be used with caution when the inflow wind speed and direction vary rapidly. The simulated concentrations in Section 5 are based on TCM.

4.3. Grid sensitivity

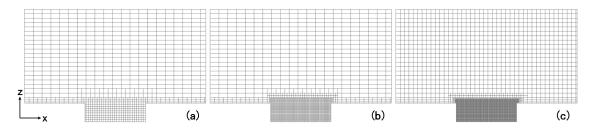


Fig. 8 Different grid resolutions for sensitivity analysis: (a) coarse, (b) basic, (c) fine. The grid resolutions in the street canyon are 1 m, 0.5 m and 0.25 m in both x-and z- directions, respectively. The largest grid sizes are 4 m (x) \times 2m (z) in the coarse and basic grids, and 2 m (x) \times 2m (z) in the fine grid.

Grid sensitivity analysis is conducted based on three different resolutions as shown in Fig. 8. The grid resolutions in the street canyon for coarse, basic and fine grids are 1 m, 0.5 m and 0.25 m in both x-and z- directions, respectively. The largest grid sizes are 4 m (x) \times 2m (z) for the coarse and basic grids, and 2 m (x) \times 2m (z) for the fine grid. The simulations are based on constant-condition method. The A-B-A splitting method, which is introduced in Section 4.4, is used with a time step of 0.5 s. Fig. 9 shows the comparative results for the mass concentration. No significant discrepancy is observed between the different grids for NO₂, inert matter and organic matter. Meanwhile, the simulated inorganic matter based on coarse grids shows slightly smaller concentrations than the other grid resolutions, while the concentrations based on basic and fine grids are close.

Therefore, the basic grid is adopted for simulations in this study.

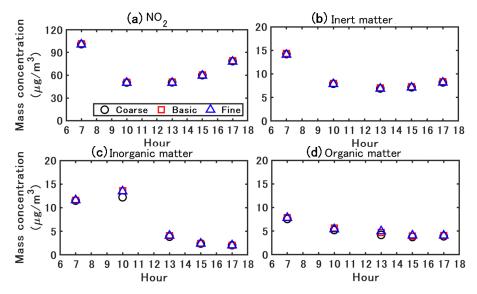


Fig. 9 Simulated NO₂ and particle concentrations with different grid resolutions.

4.4. Coupling method and time step sensitivity

The transport equation for the chemical species includes terms of advection, diffusion, emission and chemical reactions. Ideally, the transport equation should be solved with all the above terms, that is, by coupling all processes. However, the chemical process is integrated with a stiff integrator, whereas advection, diffusion and emission are integrated with a flux scheme. Therefore, operator splitting (Sportisse, 2000) is often employed to solve different terms individually and sequentially over a given time step in chemical transport simulations (Fu and Liang, 2016).

In this study, advection, diffusion and emission are simultaneously solved in CFD, and the chemical reactions including gas chemistry, particle dynamics and size redistribution are solved in SSH-Aerosol. Two operator-splitting orders are considered for coupling: A-B splitting and A-B-A splitting (Sportisse, 2000). For A-B splitting, which can be summarized as CFD(Δt)-Chemistry(Δt), the mass concentrations are first integrated for transport over a time step Δt . The updated concentrations are then integrated for chemistry at the same Δt . On the other side, A-B-A splitting adopts a symmetric sequence of operators, which can be summarized as CFD($\Delta t/2$)-Chemistry(Δt)-CFD($\Delta t/2$). The mass concentrations are first integrated for transport over a half time step, then for chemistry over the full time step and finally for transport again over a half time step.

Table 2 Relative change in the computation time with different operator-splitting order and time steps. The computation time is normalized by ABA-05.

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Case	Operator splitting order	Δt (s)	Change in the computation time	
AB-05	A-B splitting	0.5	0.90	
AB-025	$CFD(\Delta t)$ -Chemistry(Δt)	0.25	1.56	
ABA-1	A. D. A. culitting	1	0.57	
ABA-05	A-B-A splitting CFD($\Delta t/2$)-Chemistry(Δt)-CFD($\Delta t/2$)	0.5	1	
ABA-025	$CFD(\Delta t/2)$ -Chemistry(Δt)-CFD($\Delta t/2$)	0.25	2.44	

A sensitivity analysis is conducted on the operator splitting method and splitting time step. As shown in Table 2, the time step is considered 0.5 s and 0.25 s for the A-B splitting (named AB-05 and AB-025), and 1 s, 0.5 s and 0.25 s for the A-B-A splitting (named ABA-1, ABA-05 and ABA-025). The simulated NO₂ and particle concentrations are presented in Fig. 10. ABA-1 and AB-05 concentrations hardly differ from the figures. Meanwhile, the computational time of ABA-1 is only 63% of that of AB-05. Similarly, the concentrations simulated with ABA-05 and AB-025 are almost the same, and the

computational time of ABA-05 is only 64% of AB-025. Therefore, the A-B-A splitting method can be considered as a cost effective method.



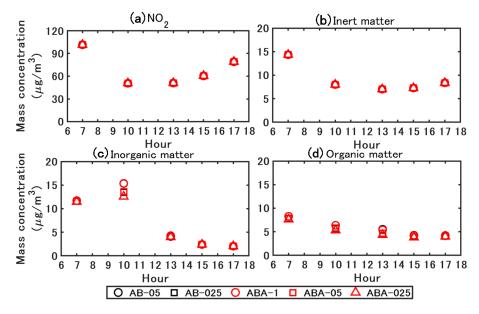


Fig. 10 Simulated NO₂ and particle concentrations with different coupling methods and time steps. ABA denotes the A-B-A splitting method: $CFD(\Delta t/2)$ -Chemistry(Δt)- $CFD(\Delta t/2)$. AB denotes the A-B splitting method: $CFD(\Delta t)$ -Chemistry(Δt). In the legend, the values that follow the capital letter ABA or AB denote the time step Δt (in s) used in the simulation.

The concentrations simulated with the A-B-A splitting method and different time steps show that small time step results in low inorganic and organic matter concentrations. The concentrations simulated with ABA-1 are larger than those of ABA-05, and larger than ABA-025. However, the differences between the concentrations simulated with ABA-05 and ABA-025 are lower than the differences between ABA-1 and ABA-05. For NO₂ and inert particles, no obvious difference is found between the simulations with different splitting methods and splitting time steps. Therefore, the A-B-A splitting method with a time step of 0.5 s is adopted in this study.

5. Results and discussion

5.1. Time-averaged flow field and concentration field

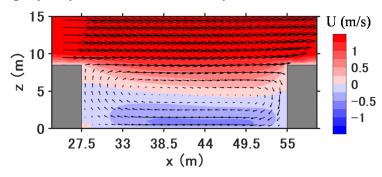


Fig. 11 Time-averaged flow field in the street canyon from 5 a.m. to 5 p.m.

This section shows the results for time-averaged values from 5 a.m. to 5 p.m. Fig. 11 shows the 12-hour time-averaged streamwise velocity and wind direction in the street canyon. At the current aspect ratio (H/W=0.31), a large vortex is observed in the canyon with a small secondary vortex at the corner of the leeward wall. A reverse flow is observed in the lower half of the canyon.

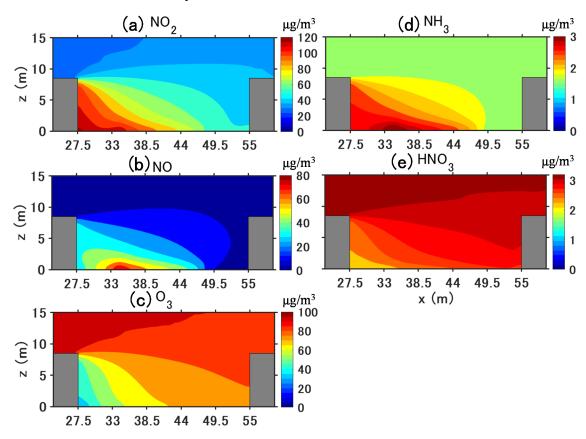


Fig. 12 Time-averaged concentrations (µg/m³) of gaseous pollutants in the street canyon

from 5 a.m. to 5 p.m.

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Fig. 12 shows the time-averaged concentrations of the gaseous pollutants from 5 a.m. to 5 p.m. For gaseous pollutants emitted by traffic, such as NO₂, NO and NH₃, larger concentrations are found in the street, particularly near the leeward wall, compared to the windward wall due to the reverse flow. Simultaneously, gas-phase chemistry and condensation/evaporation between the gas and particle phases also influence the concentration distribution. NO₂ mainly increases due to chemical production from NO emissions and background O₃. Compared to the background NO₂ concentration of 26 μg/m³, the longest retention time at the leeward side corner leads to the street canyon's largest concentration (121 μ g/m³). At pedestrian height (z=1.5 m), NO₂ concentration is 116 μ g/m³ at the leeward wall and 49 μ g/m³ at the windward wall. However, NO and NH₃ generally decrease because of loss by gaseous chemistry and the condensation of ammonium nitrate, respectively; therefore, the largest concentrations are at the leeward corner of the traffic emission source. For secondary gaseous pollutants without traffic emissions such as O₃ and HNO₃, gaseous chemistry and condensation lead to lower concentrations in the street canyon than background concentrations. For O₃, this is due to the titration of O₃ by NO, whose concentration is large near the leeward wall. For HNO₃, this is because of the high concentrations of NH₃, which then condenses with HNO₃ to form ammonium nitrate. In addition, the lowest concentration of O₃ and HNO₃ can be found at the leeward corner which corresponds to the secondary vortex in Fig. 11, indicating that the pollutant residence time is the highest in that corner leading to enhance

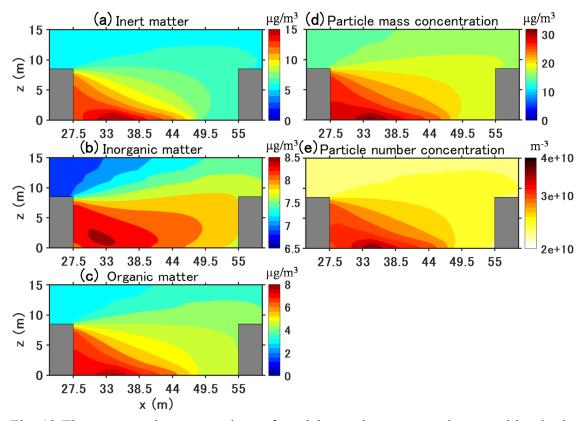


Fig. 13 Time-averaged concentrations of particle number, mass and composition in the street canyon from 5 a.m. to 5 p.m. The unit is $\mu g/m^3$ for mass concentration and m⁻³ for number concentration.

Fig. 13 shows the time-averaged PM₁₀ mass concentration, and the number concentrations and PM composition (inorganic, organic and inert matter) from 5 a.m. to 5 p.m. For inert and organic matter, the highest concentrations are near the leeward corner of the traffic emission source. Because inorganic matter is not emitted, the concentration distribution differs from inert and organic matter. However, as they are produced from gas condensation and strongly influenced by traffic emissions, the highest concentrations are observed in the leeward corner.

At pedestrian height (z=1.5 m), the PM₁₀ mass concentration is approximately 28 μ g/m³ at the leeward wall and 19 μ g/m³ at the windward wall, which is larger than the background concentration of 15 μ g/m³. The number concentration is computed from the mass concentration and therefore has a similar spatial distribution as PM₁₀ mass concentration (nucleation from gas was not taken into account). Traffic emission significantly increases the number concentration. The number concentration is about 2.3×10^{10} m⁻³ in the background, whereas the largest number concentration in the street canyon is about 3.8×10^{10} m⁻³.

5.2. Time-variant characteristics

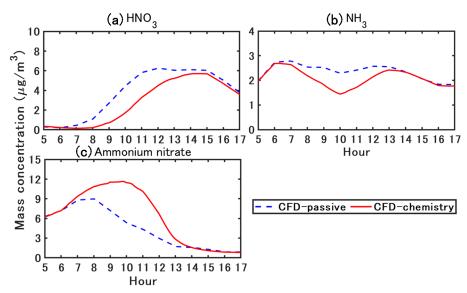


Fig. 14 Simulated time-varying concentrations of ammonium nitrate and precursor gas (HNO₃ and NH₃).

Fig. 14 shows the simulated time-varying concentrations of ammonium nitrate formed by the condensation of HNO₃ and NH₃. Based on the traffic fleet in the current study, NH₃ emission is approximately 1-2% of NOx emissions. Ammonium nitrate and HNO₃ are not emitted and differences between simulations with or without chemistry coupling are due to gas chemical reactions and phase change between the gas and particle. Phase change may be driven by NH₃ emissions, as well as the non-thermodynamic equilibrium of the background concentrations.

In CFD-passive, NH₃ concentration peaks around 7 a.m. as NOx because it is emitted by traffic. The peak in HNO₃ concentration is later in the morning, around 11 am. HNO₃ is formed from the oxidation of NO₂, which is emitted by traffic and is rapidly formed from NO traffic emissions. The formation of HNO₃ is slower than the formation of NO₂, and probably occurs at the regional scale, leading to a delay in the peak of HNO₃ concentration compared to NO₂ concentration. In CFD-chemistry, the temporal variations of HNO₃ concentration show large differences with CFD-passive because HNO₃ condenses with NH₃ to form ammonium nitrate during the daytime. As a result, the HNO₃ concentration peak in CFD-chemistry is later than that in CFD-passive (it is shifted from 11 a.m. to around 2 p.m.). The NH₃ concentration in CFD-passive peaks at 7 a.m. because of traffic emission and is stable from 7 a.m. to 1 p.m. and then decreases from 1 p.m. Meanwhile, the condensation in CFD-chemistry leads to lower concentration than in

CFD-passive during the daytime (between 7 a.m. and 1 p.m.).

For 12-hour time-averaged concentrations, ammonium nitrate increases by 46% in CFD-chemistry compared with that in CFD-passive. Background ammonium nitrate concentration (CFD-passive) peaks around the morning rush (7 to 8 a.m.) and then decreases. Meanwhile, in CFD-chemistry, ammonium nitrate concentration peaks later around 10 a.m., because of the large increase in HNO₃ between the traffic rush and 10 a.m. However, although HNO₃ concentration does not vary much between 11 a.m. and 3 p.m., the ammonium nitrate concentration decreases from 10 a.m. to a very small level (lower than 1 μ g/m³) after 2 p.m. This decrease is probably linked to the temperature increase during the daytime (Fig. 2(b)) and the relative humidity decrease, leading to a decrease in the condensation rate (Stelson and Seinfeld, 1982).

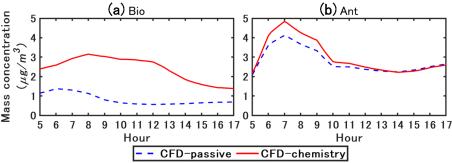


Fig. 15 Simulated time-varying concentration of organic matter. Bio refers to organic matter formed from biogenic precursors. Ant refers to organic matter formed from anthropogenic precursors.

Fig. 15 shows the simulated time-varying concentrations of organic matter. Organic matter is divided into two main categories depending on the origin of the precursors: Bio and Ant refer to the organic matter of biogenic and anthropogenic precursors respectively. In CFD-chemistry, Bio concentration is larger than that in CFD-passive. As biogenic precursors are not emitted in the street, the condensation of Bio is due to background precursor gases. As discussed previously, the concentration of ammonium nitrate is higher in CFD-chemistry than in CFD-passive, providing a larger aqueous mass onto which hydrophilic compounds of the biogenic precursor gases condense. As the condensation of ammonium nitrate decreases in the afternoon as shown in Fig. 14, the condensation of Bio also decreases.

Ant is largely influenced by traffic emissions in the street, particularly by emissions of

Ant is largely influenced by traffic emissions in the street, particularly by emissions of semi-volatile compounds (Sartelet et al., 2018), which soon condenses after emissions. Therefore there is a peak around 7 a.m. owing to the morning rush. In the model, anthropogenic emissions are mostly hydrophobic, therefore the condensation is not

enhanced by the increase in inorganic concentrations. Consequently, the difference between CFD-chemistry and CFD-passive is larger in the morning owing to the large increase in traffic emissions, but small differences are observed in the afternoon.

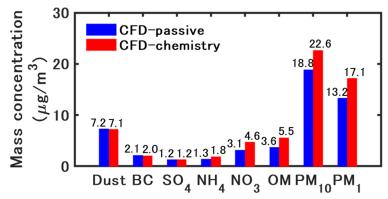


Fig. 16 Time-averaged concentration of PM_{10} , PM_1 and the chemical compounds of PM_{10} from 5 a.m. to 5 p.m.

Fig. 16 shows the time-averaged concentrations of PM_{10} , PM_1 and the chemical compounds of PM_{10} from 5 a.m. to 5 p.m. The time-averaged PM_{10} and PM_1 concentrations increase by approximately $3.8 \,\mu\text{g/m}^3$ in CFD-chemistry compared to CFD-passive, indicating that chemistry mainly influences small particles. Inert matter slightly decreases in CFD-chemistry owing to dry deposition. Condensation increases of 48%, 38% and 53% of nitrate, ammonium and organic matter concentrations in CFD-chemistry compared to CFD-passive.

5.3. Size distribution of particle matter

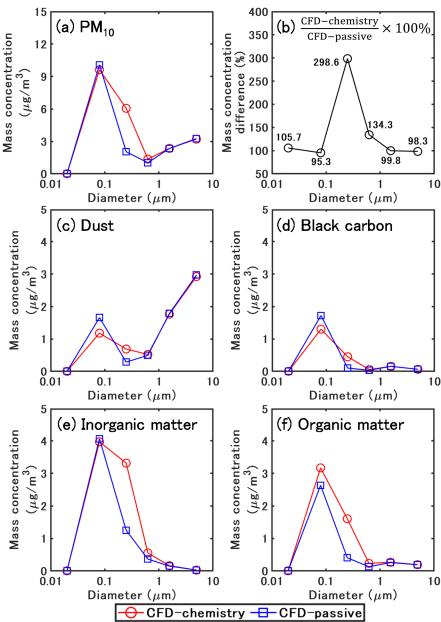


Fig. 17 Time-averaged size distribution of PM_{10} for different chemical species from 5 a.m. to 5 p.m.

Fig. 17 shows the time-averaged size distribution of PM_{10} for the different chemical compounds of particles from 5 a.m. to 5 p.m. The bound diameters are 0.01, 0.04, 0.16, 0.4, 1.0, 2.5 and 10 μ m, and the mean diameters are 0.02, 0.08, 0.25, 0.63, 1.58 and 5.01 μ m.

For the total concentration of PM₁₀ (Fig. 17(a)), the lowest and the largest concentrations are in the first size section (0.01-0.04 μ m) and the second size section (0.04-0.16 μ m)

respectively, for both the CFD-passive and the CFD-chemistry simulations. Generally,

570 the loss and gain of mass concentration in each size section are related to emission, dry

571 deposition, coagulation (small particles coagulate into large particles), and

572 condensation/evaporation (phase exchange between gas and particles).

Fig. 17(b) shows the mass concentration ratio between CFD-passive and CFD-chemistry

for each size section. For particles in the size range of $0.04-0.16 \mu m$, the concentrations

575 are smaller in CFD-chemistry than in CFD-passive, because dry deposition and

576 coagulation both decrease mass concentration for those particles. Furthermore, semi-

577 volatile gases may evaporate from small particles because of the Kelvin effect and

condense onto larger particles. For particles in the size range of 0.16-1.0 µm, the

579 concentrations are much larger in CFD-chemistry than CFD-passive, indicating that

580 coagulation and condensation on the mass-concentration increase are dominant to other

processes, such as deposition. For particles larger than 1 µm, the concentrations of CFD-

passive and CFD-chemistry are similar, because particle dynamics have a low influence

on large particles.

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The size distribution of dust (Fig. 17(c)) shows that most dust mass concentrations are in

particles larger than 1 µm. Meanwhile, most of the mass concentration of BC, inorganic

and organic matter (Fig. 17(d-f)) is in particles smaller than 1 µm. Coagulation is the main

process influencing the size distribution for inert matter (dust and BC). Compared to

588 CFD-passive, the mass concentration of dust and BC in the second size section decrease

by 0.48 and 0.43 μg/m³ in CFD-chemistry. Correspondingly, the mass concentrations of

dust and BC in the third size section increase by 0.41 and 0.35 μ g/m³.

591 For inorganic matter, in the second size section, the concentrations are similar in CFD-

passive and CFD-chemistry: particle dynamics decrease sulphate concentration by 0.32

593 μg/m³ and increase nitrate concentration by 0.17 μg/m³. However, as the results of the

combination effect of coagulation and ammonium nitrate condensation, the

595 concentrations largely increase in the third size section in CFD-chemistry: sulphate,

ammonium and nitrate increase by 0.27, 0.6 and 1.24 μg/m³, respectively.

597 For organic matter, because of condensation of hydrophilic compounds from background

biogenic gases and anthropogenic emissions, CFD-chemistry leads to a small increase in

concentrations (0.53 µg/m³) in the second size section and a large increase in the third

section (1.21 μg/m³) compared to CFD-passive. In detail, Bio concentrations increase by

 $0.89 \,\mu\text{g/m}^3$, and Ant concentrations decrease by $0.36 \,\mu\text{g/m}^3$ in the second size section. In

the third size section, Bio and Ant concentrations increase by 0.67, 0.54 μ g/m³.

5.4. Influence of ammonia traffic emissions

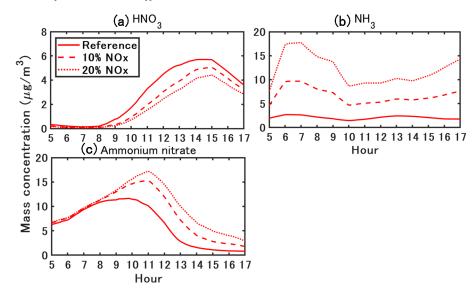


Fig. 18 Sensitivity of ammonium nitrate concentration to NH₃ emission.

Suarez-Bertoa et al. (2017) conducted on-road measurements of NH₃ emissions from two Euro 6b compliant light duty cars (one gasoline and one diesel) under real-world driving conditions, and they found that NH₃ emissions accounted for 11.9% and 0.92% of NOx emissions for gasoline and diesel vehicles. As explained in Section 5.2, NH₃ emission emissions are approximately 1-2% of NOx emissions in the reference case. Two cases are considered to simulate the impact of an increase in the fraction of gasoline cars, and sensitivity simulations are performed with NH₃ emission considered as 10% and 20% of the NOx emissions.

Fig. 18 shows the sensitivity of ammonium nitrate concentration to NH₃ emissions. A larger NH₃ emission delays the peak of ammonium nitrate by approximately one hour. For a 12-hour average, considering NH₃ emissions of 10% and 20% of NOx emissions leads to a large increase in ammonium nitrate (35% and 55%) compared to the reference case, because of the formation of ammonium nitrate by the condensation of HNO₃ and NH₃.

6. Conclusions

Particles in urban environment impose adverse impacts on pedestrians' health. Conventional CFD methods regarding particles as passive scalars cannot reproduce the formation of secondary aerosols and may lead to uncertain simulations. Therefore, to increase the simulation accuracy of particle dispersion, we coupled the CFD software OpenFOAM (OF) and Code_Saturne (CS) with SSH-Aerosol, a modular box model to

- simulate the evolution of primary and secondary aerosols. The main processes involved
- in the aerosol dynamics (coagulation, condensation /evaporation and dry deposition) were
- 631 considered.
- We simulated a 12-hour transient dispersion of pollutants from traffic emissions in a street
- canyon using the unsteady RANS model. The simulation domain was generated to model
- a street-canyon where field measurements are available. The flow field was based on the
- WRF model. The background concentrations of gas and particles were obtained from
- regional-scale simulations with a chemistry-transport model. The particle diameter range
- 637 (0.01 μm to 10 μm) was divided into six size sections. The following conclusions were
- drawn from the results of this study.
- 639 1) The simulated spatially-averaged values in the street canyon were validated from
- field measurement using validation metrics. For both OF and CS, the simulated NO₂
- and PM₁₀ concentrations based on the coupling model (CFD-chemistry) achieved
- better agreement with the measurement data than the conventional CFD simulation
- which considered pollutants as passive scalars (CFD-passive). The differences
- between of the OF and CS results were not obvious and were mainly due to the
- differences in the turbulence scheme. The following conclusions were drawn based
- on the simulated OF concentrations.
- 647 2) For the flow field, a large vortex was observed in the canyon with a small secondary
- vortex at the corner of the leeward wall at the current aspect ratio (H/W=0.31). In
- CFD-chemistry, because of the reverse flow, the 12-hour (from 5 a.m. to 5 p.m.) time-
- averaged NO₂ mass concentration, PM₁₀ mass and number concentrations at
- pedestrian height were much higher near the leeward wall (116 μg/m³, 28 μg/m³,
- $3.2 \times 10^{10} \text{ m}^{-3}$) than the background (26 µg/m³, 15 µg/m³, $2.3 \times 10^{10} \text{ m}^{-3}$).
- 653 3) Secondary aerosol formation largely affected the mass concentration and size
- distribution of particle matter. For 12-hour time-averaged concentrations, ammonium
- nitrate and organic matter increased by 46% and 53% in CFD-chemistry compared
- to CFD-passive because of condensation of HNO₃ and NH₃, background biogenic
- precursor-gases and anthropogenic precursor-gas emissions. Coagulation largely
- influenced the size distribution of small particles by combining particles with a
- diameter of 0.04-0.16 µm into 0.16-0.4 µm. At the same time, CFD-chemistry
- showed a much larger concentration than CFD-passive for the particles in 0.16-1.0
- 661 um, indicating that the effect of condensation on increasing mass concentration was
- dominant compared to other chemical processes.
- 4) Urban areas are NH₃-limited (HNO₃ sufficient) areas, therefore, increasing NH₃ leads
- to a large increase in ammonium nitrate. Vehicles are considered to be the main

- source of NH₃ in urban environments. Increasing the fleet's proportion of recent gasoline vehicles may increase NH₃ emissions. For a 12-hour average, we considered NH₃ emissions of 10% and 20% of NOx emissions led to a large increase in ammonium nitrate (35% and 55%) compared to the reference case which considers NH₃ emission as 1-2% of NOx emissions.
- 670 5) A grid sensitivity analysis showed that the particles' concentrations of inorganic and 671 organic compounds were sensitive to grid resolution, whereas inert particle 672 concentrations were not sensitive to grid resolution. In addition, simulated values 673 based on a grid size of 0.5 m in the street canyon showed small differences with a 674 grid size of 0.25 m, indicating that a spatial resolution of 0.5 m can be enough for 675 reactive particle dispersion at the street level.
- 676 6) Operator splitting is often employed to solve the transport term and chemical reactions over a given time step in chemical transport simulations. Two integration orders were considered: A-B splitting method (CFD(Δt)-Chemistry(Δt)) and A-B-A splitting method (CFD(Δt/2)-Chemistry(Δt)-CFD(Δt/2)). The results showed that the A-B-A splitting method had almost the same concentrations as the A-B splitting method with half the computational time. Further sensitivity analysis on the time step showed that a time step of 0.5 s was enough when using the A-B-A splitting method.

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- 7) Conducting a CFD simulation with constant boundary conditions and emission rates at a specific time point is considered a practical method to achieve time-averaged concentrations for evaluating street-level pollutant concentrations. The validation was conducted using conditions on five time points (7 a.m., 10 a.m., 1 p.m., 3 p.m. and 5 p.m.). The simulated concentration based on the above method exhibited almost the same value as the simulation with transient conditions at the same time points.
- The limitation of this study should be addressed as several reasonable approximations and assumptions were made in the simulation settings.
 - 1) Concerning the simulation domain: since we focused on the coupling of gas chemical reactions and particle dynamics to the CFD codes, we selected a 12-hour period when wind direction was perpendicular to the street. In that case, a 2-D simplification of the simulation domain is reasonable, as shown by Maison et al. (2022). In addition, the 2-D simplification is frequently adopted for studying dispersion of reactive pollutants in a street canyon (Garmory et al., 2009; Wu et al., 2021). However, in more general cases, the pollutant residence time for a 3-D canyon could be shorter compared to the 2-D canyon adopted in this study, and the effects of chemical reaction or aerosol processes could be weaker than this study reported. In addition,

- various wind directions should be considered to better evaluate the performance of the coupled model. Further work will focus on the application of the coupled model to a complex urban environment with changing wind directions.
- 704 2) Concerning the physical model: the simulations were based on RANS-closure, and 705 the SSH-aerosol processed the ensemble-averaged concentration, therefore the 706 covariance of turbulent diffusion and chemical reaction may not be fully reproduced. 707 The simulation based on LES may provide better prediction of second-order 708 quantities. In addition, the radiation on the wall may lead street-level-variations of 709 temperature and could affect the flow field and chemical reaction rates. However, 710 this was not considered here, and the radiation effect on the local temperature was 711 simplified as being the same as in the inflow condition. The inflow temperature was 712 obtained from WRF model where the radiation was considered, and the time variation 713 of temperature was considered to be the same as the background.
 - Future work will be conducted on the influence of environmental factors and emission conditions, aiming to provide knowledge to devise suitable countermeasures to decrease particle concentration in microscale urban environments.

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722 Code/Data availability

- The codes used in this publication are available to the community, and they can be accessed by request to the corresponding author.
- 726 Author contribution
- 727 KS and RO were responsible for conceptualization. CL, YW, CF, KS, YK and ZW
- developed the software. CL and YW conduced the visualization and validation; CL, YW
- and KS performed the formal analysis. KS and RO acquired resources. CL, YW, RO and
- 730 KS were responsible for writing and original draft preparation. CF, YK, HK reviewed and
- edited the manuscript All co-authors contributed to the discussion of the paper.
- 733 Competing interests
- The contact author has declared that neither they nor their co-authors have any
- 735 competing interests.

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907 Appendix A

- The schemes for particle deposition velocity v_d were added to the transport equations
- 909 using volume sink terms based on (Zhang et al., 2001) and can be represented as:

$$v_{d,p} = \begin{cases} v_g + \frac{1}{R_a + R_s}, & \text{Wall surfaces} \\ v_g, & \text{Entire field} \end{cases}$$
(A1)

$$v_g = \frac{\rho d_p^2 g C}{18\eta} \tag{A2}$$

$$R_a = \frac{\ln(z_R/z_0) - \psi_H}{\kappa u_*} \tag{A3}$$

$$R_{s} = \frac{1}{\varepsilon_{0} u_{*} (E_{B} + E_{IM} + E_{IN}) R_{1}}$$
 (A4)

- The deposition velocity for the particles $v_{d,p}$ consists of both gravitational settling and
- 911 surface deposition near the wall surfaces. The gravitational settling velocity v_g was
- 912 considered for the entire field, ρ is the particle density; d_p is the particle diameter; g
- 913 is the acceleration of gravity; C is Cunningham correction factor for small particles; η
- 914 is the viscosity coefficient of air.
- The aerodynamic resistance R_a is calculated from the first-layer-height z_R , roughness
- length z_0 , Von Kármán constant κ , friction velocity u_* and stability function ψ_H . For the
- 917 k— ϵ model, u_* is estimated by $\left(C_{\mu}^{0.5}k\right)^{0.5}$ and $C_{\mu}=0.09$ is a constant of the model.
- The surface resistance R_s is calculated from u_* , the collection efficiency from Brownian
- 919 diffusion E_B , the impaction E_{IM} and the interception E_{IN} . The correction factor
- 920 represents the fraction of particles that stick to the surface R_1 and an empirical
- 921 constant $\varepsilon_0 = 3$.
- The dry deposition schemes for gas were added to the transport equations using volume
- 923 sink terms based on (Wesely, 1989) and (Zhang et al., 2003), which can be represented as:

$$v_{d,g} = \frac{1}{R_a + R_b + R_c} \tag{A5}$$

$$R_b = \frac{2}{\kappa u_*} \left(\frac{Sc}{Pr}\right)^{2/3} \tag{A6}$$

- The deposition velocity for gas $v_{d,q}$ is calculated from the aerodynamic resistance R_a ,
- the quasi-laminar layer resistance R_b and the surface resistance for gas R_c . Sc = v/D
- and Pr = 0.72 are the Schmidt and Prandtl number. v is the kinematic viscosity of air
- and D is the molecular diffusivity of different gases. R_c is calculated based on (Zhang
- 928 et al., 2003).

930 Appendix B

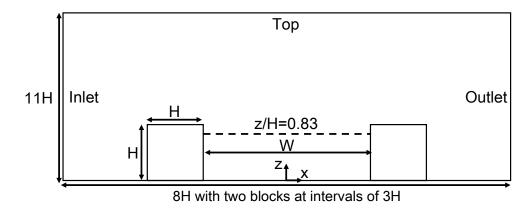


Fig. B1 Simulation domain for velocity validation.

Correctly representing the flow field in the street canyon is important to model accurately the concentrations. Unfortunately, observation data on wind velocity is the street is not available. Therefore, we conducted a velocity validation for OpenFOAM v2012 using data from a wind tunnel experiment (Blackman et al., 2015). The 2-D simulation domain is shown in Fig. B1. The aspect ratio in the experiment (H/W=0.33) is close to this study (H/W=0.31). The building height H is 0.06 m. The grid size is 1/20 H in x- and z-directions in the simulation domain under 3H. The free-stream velocity U_{ref} is 5.9 m/s. The steady-state flow field is simulated with the same turbulence model (RNG k- ϵ model) as in the paper, and cyclic boundary conditions are used for the inlet and outlet. The slip boundary is considered for the top, and non-slip boundary conditions with the same wall functions as in the paper are considered for other walls.

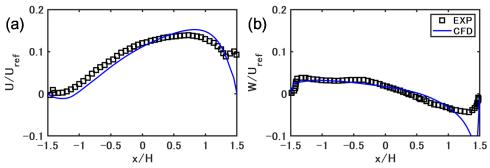


Fig. B2 Streamwise and vertical direction of mean wind velocities at z/H = 0.83.

Fig. B2 compares the simulated streamwise and vertical direction of mean wind velocities with the experimental values at z/H = 0.83. The RNG k- ϵ model reproduce well the velocities, although the velocities very close to the windward wall show differences with

- 951 the experimental values. The above validation shows that if suitable inlet conditions are
- given, the flow field is well reproduced with the turbulence model adopted in this study.