

“Inverse modeling of fire emissions constrained by smoke plume transport using HYSPLIT dispersion model and geostationary observations”

General response

Authors express their appreciation to the two reviewers and the editor. Thanks to their productive comments, we were able to improve our manuscript. As the reviewer recommended, we have included additional tests and discussions on the sensitivity. Mistakes were revised, and performance statistics were also updated. We provide below the general responses and the point-by-point responses to the reviewer's comments. Reviewers' comments are shown in italics.

Here are three major points in the revised version of the manuscript.

1. Sensitivity tests for temporal coverage

As both reviewers commented, we agree that the temporal sensitivity section needs a clarification of the goal. Our original intention was to find the most efficient temporal coverage of the inverse system to conduct the assimilation process, which includes both time windows for the assimilation and the use of observational data. On the other hand, the reviewers asked to test the sensitivity by the change of observational data use. We believe that both tests are meaningful, so we included both test results in the manuscript. The former is important in terms of the efficiency of the inverse system because dispersion simulations to construct the TCM is the most time-consuming processes in the inverse system. The latter, selection of observations (used in the assimilation), is also important to investigate the responses of the inverse system.

Indeed, there are three adjustable time windows in the processes and evaluation of fire emission assimilation. As shown in **Figure R1**, the assimilation (or analysis) time window denotes the temporal coverage of fire emission sources and simulated dispersions. The observational data time window (or selection of observations used for constraining in the assimilation) can be set equal to or shorter than the assimilation time window. The evaluation time window (or selection of observations used for evaluation) is also set equal to or shorter than the observational time window. Therefore, we tested combinations of these time windows.

- 1) Assimilation time window (source, dispersion and assimilation process)
- 2) Observation time window (observation)
- 3) Evaluation time window (model and observation)

Model performance statistics were calculated with combinations of temporal coverages of assimilation (shown as “A” in Table R1; 24h-96h), observation (shown as “O”, 24h-96h), and evaluation (shown as “E”, 24h-96h). Results are summarized in Table R1. As discussed in the manuscript, including more analytical period generally improves the performance of the inverse system, but the difference is not critical for more than 48-hour time window.

With fixed analytical period (A:96h), performance statistics are better with shorter observational time window applied. It makes sense because we expect to have a better fit with smaller number of data points during the analysis process although it also has a risk of potential overfitting problem, as the reviewer #2 commented.

The manuscript was revised to include these additional sensitivity tests.

(Line 270) “First, we changed the assimilation time windows from one (24-hours) to four days (96-hours). Since the impact of fire emissions easily translates over multiple days, we tested how temporal coverage affects system results. The ‘one-day’ (aday=0) simulation is run through the inverse model using dispersions and observations for the target day, while the ‘two-day’ simulation uses two days (i.e., 48 hours) of dispersions and observations (aday=-1). For this test, all observations within the

assimilation time windows were selected for the assimilation and the evaluation. The results are shown in **Figure 6a**, while the correlation and error statistics are summarized in the top section of **Table 2** (i.e. [A:24h, O:24h, E:24h], ... , [A:96h, O:96h, E:96h]). With the exception of November 10 and 11, in the early stage of the fire event, both the correlation coefficient (R) and normalized root-mean-square error (NRMSE) were improved by the use of more days (i.e., three or four days) of dispersions and observations for the inverse model. This makes sense, because emissions from multi-day fire events spread out and affect concentrations over proceeding days.

A series of additional simulations were also conducted to test the system's sensitivity to the selection of observations for the assimilation and the evaluation. In these tests, we investigated combinations in assimilation time ("A" in **Table 2**), observational time ("O") and evaluation time windows ("E"). Results are also summarized in **Table 2**. For a fixed assimilation time period (i.e. [A:96h]), using shorter observational time window resulted in a better result. It is reasonable because we expect a better fitting with smaller number of data points. However, it can be easily exposed to overfitting problem if available data for the assimilation is too small."

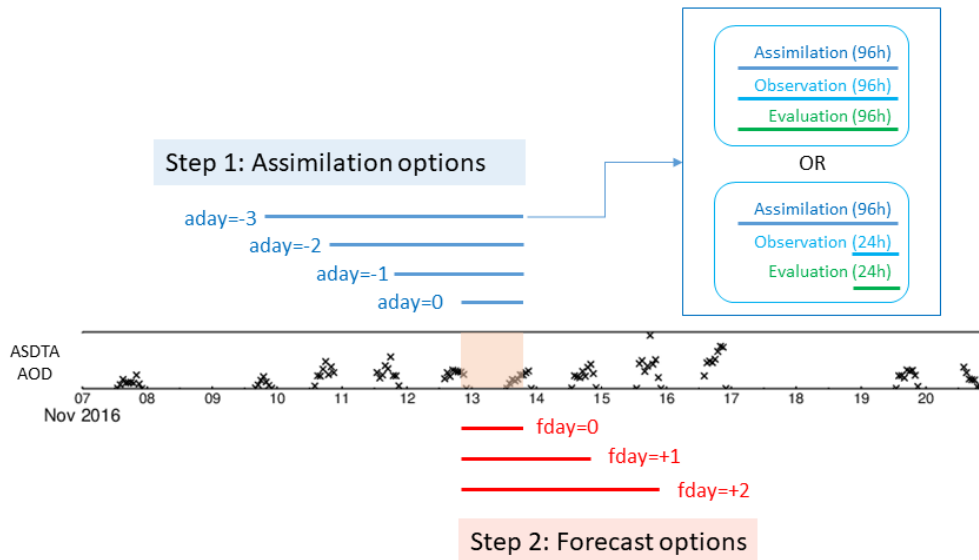


Figure R1 Two steps for smoke forecast with the HEIMS-fire system. Temporal coverage of assimilation days ($aday=0, -1, -2, -3$) and forecast days ($fdays=0, +1, +2$) for operational tests. Assimilation process includes three time windows – assimilation, observation and evaluation time windows.

Table R1 Sensitivity test for temporal coverage. Uses of analysis (A), observation (O), and evaluation (E) time windows (24 hours to 96 hours) were tested, and statistics, NRMSE and R, were compared. The best performance is marked as bold.

NRMSE (%)					R			
Coverage	A: 24h O: 24h E: 24h	A: 48h O: 48h E: 48h	A: 72h O: 72h E: 72h	A: 96h O: 96h E: 96h	A: 24h O: 24h E: 24h	A: 48h O: 48h E: 48h	A: 72h O: 72h E: 72h	A: 96h O: 96h E: 96h
Nov. 10	66.6	63.7	62.7	68.7	0.677	0.654	0.669	0.577
11	75.2	65.9	64.0	63.7	0.410	0.620	0.587	0.593
12	75.1	63.5	61.4	60.6	0.373	0.309	0.562	0.526
13	72.8	65.7	59.9	59.6	0.298	0.476	0.397	0.576
14	75.6	66.3	61.0	56.8	0.285	0.444	0.522	0.469
15	82.7	70.9	62.7	60.2	0.105	0.348	0.465	0.511
16	69.8	72.5	68.2	61.7	0.146	0.150	0.372	0.478
17		69.8	72.5	68.2		0.146	0.150	0.372
Coverage	A: 24h O: 24h E: 24h	A: 48h O: 48h E: 24h	A: 72h O: 72h E: 24h	A: 96h O: 96h E: 24h	A: 24h O: 24h E: 24h	A: 48h O: 48h E: 24h	A: 72h O: 72h E: 24h	A: 96h O: 96h E: 24h
Nov. 10	66.6	49.1	49.0	38.7	0.677	0.713	0.716	0.716
11	75.2	80.6	78.4	78.4	0.410	0.621	0.623	0.623
12	75.1	45.2	56.5	55.8	0.373	0.406	0.425	0.430
13	72.8	58.0	52.9	63.5	0.298	0.534	0.581	0.589
14	75.6	54.6	53.8	53.1	0.285	0.567	0.593	0.609
15	82.7	43.9	42.4	44.6	0.105	0.554	0.589	0.571
16	69.8	34.3	28.4	27.4	0.146	0.464	0.507	0.505
17								
Coverage	A: 96h O: 24h E: 24h	A: 96h O: 48h E: 48h	A: 96h O: 72h E: 72h	A: 96h O: 96h E: 96h	A: 96h O: 24h E: 24h	A: 96h O: 48h E: 48h	A: 96h O: 72h E: 72h	A: 96h O: 96h E: 96h
Nov. 10	53.0	62.1	62.1	68.7	0.746	0.657	0.657	0.577
11	54.7	61.9	63.7	63.7	0.583	0.615	0.593	0.593
12	43.0	54.0	59.1	60.6	0.425	0.481	0.545	0.526
13	40.3	46.4	54.5	59.6	0.664	0.510	0.500	0.576
14	38.3	43.5	50.5	56.8	0.688	0.603	0.499	0.469
15	43.9	50.8	55.3	60.2	0.647	0.572	0.533	0.511
16	33.5	42.2	53.2	61.7 68.2	0.667	0.685	0.581	0.478
17		36.1	53.8			0.624	0.520	0.372
Coverage	A: 96h O: 24h E: 24h	A: 96h O: 48h E: 24h	A: 96h O: 72h E: 24h	A: 96h O: 96h E: 24h	A: 96h O: 24h E: 24h	A: 96h O: 48h E: 24h	A: 96h O: 72h E: 24h	A: 96h O: 96h E: 24h
Nov. 10	53.6	47.1	47.1	38.7	0.746	0.715	0.715	0.716
11	58.1	81.0	78.4	78.4	0.668	0.624	0.623	0.623
12	41.3	48.0	56.7	55.8	0.489	0.432	0.433	0.430
13	39.5	49.8	55.4	63.5	0.691	0.612	0.588	0.589
14	39.5	45.8	51.9	53.1	0.698	0.612	0.612	0.609
15	37.8	43.1	43.1	44.6	0.682	0.552	0.566	0.571
16	33.7	29.6	27.9	27.4	0.614	0.542	0.510	0.505
17								

2. Sensitivity tests for vertical layer selection

For the sensitivity of vertical layer configuration, we added an extra test as the reviewer #2 suggested. With the maximum height fixed at 5,000m, we conducted a sensitivity test by increasing vertical layer resolution from 2 layers to 6 layers. As expected, we have better performance statistics as we increase the number of layers although the change is not dramatic after four layers (**Table R2**).

Indeed, this vertical layer sensitivity is one of the most important topics in the construction of smoke forecast system since it is directly related to the smoke plume rise problem. Therefore, we believe that the topic deserves a separate effort. We are preparing a follow-up study on the plume rise options, based on plume rise parameterization (in HYSPLIT) and inverse modeling technique. For current study, we like to narrow and focus on its own scope. While we demonstrate vertical layer selection sensitivity from its maximum height and vertical layer resolution, detailed analysis on the fire emission plume rise options warrants an additional full research.

Table R2 Sensitivity tests for vertical layers resolution from two to six layers. The best performance is marked as bold.

	Date	2 layers (100, 5000m)	3 layers (100, 2000, 5000m)	4 layers (100, 1000, 2000, 5000m)	5 layers (100, 1000, 1500, 2000, 5000m)	6 layers (100, 500, 1000, 1500, 2000, 5000m)
NRMSE	Nov. 10	72.9	69.2	65.9	63.7	63.7
	11	79.0	71.6	68.1	66.4	65.9
	12	70.7	67.8	65.5	65.0	63.5
	13	68.7	67.6	66.1	65.9	65.7
	14	72.9	70.6	67.2	67.0	66.3
	15	83.3	77.1	72.0	71.0	70.9
	16	78.9	72.0	73.2	72.5	72.5
	17	72.2	70.6	70.2	70.0	69.8
R	Nov. 10	0.577	0.593	0.630	0.654	0.654
	11	0.490	0.558	0.598	0.614	0.620
	12	0.292	0.285	0.303	0.303	0.309
	13	0.449	0.450	0.468	0.470	0.476
	14	0.404	0.419	0.439	0.440	0.444
	15	0.252	0.276	0.338	0.346	0.348
	16	0.112	0.164	0.144	0.149	0.150
	17	0.198	0.139	0.139	0.139	0.146

The manuscript was revised including this information.

(Line 286) “Second, we tested the layers at which fire emissions are initiated in the model. As expected, including more layers results in better statistics, since the transport and dispersion of each smoke plume can vary with the altitude to which their fire emissions are allocated. We tested the model’s uncertainties on layers’ maximum extension and resolution, with varying selections of two to seven layers at 100, 500, 1000, 1500, 2000, 5000, or 10000 meters. To test the maximum extension, starting from two layers (i.e. with emissions released at 100 and 500 meters), we added the next higher layer over six test runs to investigate the effect of maximum extension of smoke plume. **Figure 6b** shows the results, and error statistics are summarized in **Table 3**. Including the 5000m layer, especially, resulted in noticeable changes, implying the potential benefit of including high-level transport for specific days. Since the 5000m layer is above typical planetary boundary layer height, emissions injected at this level experience different physical characteristics. Smoke lofted into the free troposphere is less affected by turbulence and scavenging, and transports easily hundreds or thousands of kilometers downwind because of the higher wind speeds. Addition of the 5000m layer would better represent the potential long-range transport. Smoke plume rise is one of traditionally important questions in smoke modelling, so further research on the topic is warranted. Effects of the layer resolution were also tested. Starting from two layers (i.e. 100m and 5000m), we added intermediate layers up to six layers, and evaluated their performances (**Table S3**). As expected, including more layers resulted in the better statistics, but its improvement was not significant after four layers. “

3. Scope of the study

Here, we like to address the scope of this manuscript again. In this study, we intended to conduct two goals: 1) Suggestion of inverse modeling framework, and 2) improvement of operational smoke forecasts. Our main priority here is to suggest a practical framework to help fire emission estimation. However, for the second goal, we do not claim that our new system is a complete solution and outperforms in all aspects because we know that many uncertainties remained to be resolved until we claim a clearly better forecast system. To improve the forecasting system, we admit that we need more improvement in other components, including the quality of satellite products (to monitor the dispersion of smoke plume), better meteorology and fire activity persistency, as we discussed in the manuscript.

We also provide point-by-point responses to each reviewer.

REVIEWER #2

1. How the experiments with different assimilation time windows are run needs to be made clearer. Is it the case that in all experiments the emissions are initiated at the same locations and times, the only difference being the satellite data assimilation time window? If that is the case, can you clarify why longer time windows results in better agreement with observations for the analysis? I would have thought it would be easier to fit the model to data from one timestep than to fit the model to data from different timesteps. I can not quite understand the explanation given in the paper (e.g. Line 240), which I interpret to mean that this is due to emissions at $(x1,t1)$ affecting the smoke field at $(x2,t2)$. This is true, but I would expect better results for the smoke field at $(x2,t2)$ if there was no observation at $(x1,t1)$ because the emission at $(x1,t1)$ would only be constrained by the observation at $(x2,t2)$ and not $(x1,t1)$ and $(x2,t2)$ simultaneously. You probably also need to clarify which data points are included in the verification statistics (for example, when you assimilate data on day 0, do you calculate verification statistics based on day 0 only or do you also include days -1, 2 etc?).

Thanks for the comment. We agree that the temporal coverage sensitivity section needs improvement. Please, see the general response #1.

2. In performing the forecasts, it is not completely clear whether you are using NWP analysis data to drive the forecasts, or you are using NWP forecast data. If this system is to be used operationally, then clearly NWP forecasts will need to be used, which we expect will result in poorer forecasts than when the NWP analyses are used. I think this needs to be clarified.

Thanks for the comment. This is a fair comment. At this point, we don't have an archive of full length of everyday NAM forecast, so our hindcast has an advantage over operational runs in terms of meteorology. We revised the manuscript to address it.

(Line 316) "Notable differences in the configuration of SFS and HEIMS are plume rise estimation, temporal resolution of fire emissions, fire decaying assumption, and meteorology. While SFS computes plume rise using the Briggs' equation (Arya, 1998; Briggs, 1969), which assumes an air parcel's rise is based only on the buoyance terms, HEIMS determines fire emissions' vertical allocation using an inverse system. At the initial guess, SFS fire emissions are evenly distributed in all layers. Current HEIMS assumes daily emission variation compared to hourly emissions of SFS. Also, SFS assumes 75% of emissions still happen at the same location the next day, the HEIMS uses 50% decay assumption after sensitivity tests, which will be discussed in the next section. For HEIMS simulation, we used $\text{aday}=-1$ (two-day temporal coverage) for the simulations shown. On the other hand, HEIMS would be benefitted with a better meteorology. Although both systems use the NAM12 forecast meteorology, HEIMS hindcast used the first 24 hours portion of everyday forecast cycle, and SFS used 72 hours forecast."

3. Nothing has been said about analysis and forecast errors. Can this system be used to predict errors (uncertainty) or is it purely deterministic? I think some comments on this issue in the paper would be useful.

Thanks for the comment. Uncertainties in the analysis processes include the quality of inputs (i.e. observations, dispersion, and meteorology). Although the system is not purely deterministic, it is difficult to estimate the uncertainties of the results without knowing the meteorological input errors. Performing an ensemble of HYSPLIT predictions using different meteorological inputs can provide some insight in this respect. We added the following text to the conclusion.

(Line 382) "It also should be noted that the uncertainties of the emission estimation and the smoke forecasts thereafter are not quantified in this study. An ensemble of HYSPLIT predictions using different meteorological inputs will be used to estimate the uncertainties of the results in the future."

1. In the abstract you have several acronyms that are only defined later in the text. These must be defined in the abstract or alternatively think about removing them altogether from the abstract. In my view they are not that important for the abstract and can be removed. For example, is it important to know that the model has been developed by NOAA in the abstract?

Revised. We also changed “NOAA’s HYSPLIT” to “HYSPLIT” (not an acronym, See Stein et al., 2015).

2. Line 32: Remove capital letters from words 2-6 in the sentence starting with "Meeting..."

Per convention, the acronym (NAAQS) has been added after “National Ambient Air Quality Standards”.

3. Line 43 (or thereabouts): You need to state that HYSPLIT is a Lagrangian model (and maybe elaborate on what means) as in the next paragraph you start talking about Eulerian models.

Thanks for the comment. We revised the sentence.

(Line 42) “The NOAA’s HYSPLIT (Stein et al., 2015), a Lagrangian model which is designed to track air parcel trajectories, is then used to calculate transport, dispersion, and deposition of the emitted particulate matter. The SFS provides daily smoke forecasts over the continental United States, Alaska, and Hawaii to provide air-quality guidance to the public.”

4. I also notice that you don’t leave spaces between paragraphs, which makes it hard to read at times. Fix this if you can.

We are sorry for the inconvenience, but ACP template formats in such a way.

5. Line 54: You distinguish "top-down" and "bottom-up" approaches to estimating fire emissions. I think it would be useful as well to discuss the advantages and disadvantages of these approaches somewhere in the introduction.

Thanks for the comment. We have added sentences for both approaches.

(Line 73) “Both bottom-up and top-down approaches have their own advantages and limitations. While the bottom-up approach may provide detailed information based on a process- or fuel-specific estimation, it relies on various surveys that require significant time and resources. On the other hand, the top-down approach relies on observations of a few atmospheric variables such as radiation or aerosol optical properties, but it has an advantage from its timely availability and geographical coverage. Both approaches complement each other for better fire emission estimation.”

6. When discussing the methodology it might be worthwhile to explicitly mention that the "inverse system" enables the calculation of fire emissions that produces an "analysis" smoke field covering the observational time window (near past to present) and that these optimal emissions are then used to forecast the future smoke field. I do not think this has been made explicit although it may be obvious to the expert reader.

Thanks for the comment. We have added sentences for two steps (emission inverse and forecast) for the system .

(L207) “This inverse system is designed to estimate fire emissions on the target day by analyzing past and present smoke field, and then utilizes them to forecast the future smoke field.”

7. Another point that I think needs to be made clear in the methodology section is how the experiments with different observational time windows (oday = 0, -1, 2 etc) differ from each other in the model setup. For example, for oday= 0, is it that there are no emissions prior to day 0, or is it that emissions prior to day0 are unconstrained (i.e. they use prior values), or is it that the emissions prior to day0 are in the model but they are constrained by observations on day 0 only. I suspect it is the last scenario, but this needs to be made clear. You could include this information in the paragraph starting at Line 177, which I think needs more clarity. For example, you could indicate that oday = 0 means that emissions from the model start time until day 0 (for example, November 13) are constrained by observations on day 0 only; oday= -1 means that emissions from the model start time until day 0 are constrained by observations on day 0 and day -1 (November 12) etc. As I mentioned, it is not clear that is indeed the experimental setup, but whatever it is, it needs to be made clear. When you calculate the verification statistics for the oday = 0 type experiment, for example, do you include all data (for days 0, -1, -2 etc) or just data for day 0? Please make this clearer.

Thanks for the comment. Please, see the general response #1. We clarified the use of time windows for assimilation, observation and evaluation. Manuscript was also revised accordingly.

8. It would also be useful in the context of Section 3 (or elsewhere like Figure 1 or in the conclusion) to say something about how the two systems (Blue Sky/Initial? and Inverse) really need to complement each other in practice. Apart from providing the all-important first guess (or 'prior') to the inverse system, I would imagine that the Blue Sky system would also be needed to provide the first operational forecast when there are not yet any (or sufficient) observations to assimilate. In addition, in situations where there is extensive cloud cover, I would imagine that there would not be observations of smoke that could be used. This comment is related to Comment #5 above.

Thanks for the comment. This is true. Two systems complement each other. We included its importance at the manuscript.

(Line 263) "This case hints at the importance of both traditional (e.g. Blue Sky emissions) and new inverse system. They complement each other by one providing the latest data assimilation technique while the other providing a prior information and backup stability in a contaminated environment (e.g. excessive cloud cover)."

9. Line 219: The notation associated with this equation needs to be improved. Although I think I understand what you are trying to say, as it stands it is ambiguous. Firstly, it is not clear what "smoke" is supposed to be. I think you are looking at smoke mass loading, or it could be optical depth. Whatever it is, it needs to be made clear. I would use a single-letter symbol to represent the smoke variable. Since "c" is used in the first equation (Lines 148-149) that is what should be used here as well for consistency. Similarly, I would use a single letter to represent the TCM matrix coefficient (T seems like a good choice). Apart from that the equation doesn't look mathematically correct. Summing over the indices i, k, t should produce a scalar, independent of i, k, t but we know that the smoke field (mass load or optical depth) is a function of location, i, and time, t. So something is missing. I think some more work needs to be done here so that the equation makes sense.

Thanks for the comment. We modified equations.

(Line 248) "Using adjusted fire emissions, we can reconstruct the integrated smoke columns as a sum of adjusted emissions, q_{ikt} , applied to each TCM, T_{ikt} :

$$c(n, m) = \sum_{ikt} q_{ikt} \cdot T_{ikt}(n, m)$$

where i , k and t denote spatial, vertical and temporal allocation of emission sources, and m and n denote location and time of receptor (i.e. observation), respectively."

10. Line 226: change "during" to "when".

Corrected.

11. Line 226: Last sentence of paragraph. Some more needs to be said here. Why is there no data on November 17? In addition, you are implying that no satellite data was used in the analysis (presumably because there was none – you must clearly state that if that is the case, and if so, why). And yet in the caption to Figure 5 we are told that a 48-hour observation time window was used. If that is the case, why could not the data for November 16 be used to constrain the analysis? Is it because your algorithm does not perform optimisation if any time steps are missing in the observational time window? You might have mentioned this elsewhere, but how frequent are the satellite observations? Every hour? Every 10 minutes?

Thanks for the comment.

ASDTA AODs are available for every hour, but some data are missing due to operational issues. We don't have control over it. In this simulation, we used 48-hour analysis. As the reviewer commented, we still have some data available to operate the inverse system. Therefore, this case demonstrated the case with limited available data. We revised manuscript to discuss the November 17 case.

(Line 259) “The November 17 output in **Figure 5** shows how the system responds when observations are limited or missing, although it still provides a robust result by honoring the initial guess information. On November 17, no ASDTA AOD was provided from the satellite operation. Under 48-hour configuration (i.e. $\text{aday}=-1$), the inverse system still produced reasonable outputs using limited observations (November 16) and initial guess emissions (November 16 and 17).”

12. Paragraph starting at Line 234: This is related to Comment #7. If you are using emissions initiated at the same time in all experiments in which you vary the length of observational time window, it is surprising, I think, that you get a better fit with a longer observational time window. Intuitively, all things being equal, you would expect to get a better fit with a smaller number of datapoints during the analysis. Of course, for the forecast you would expect better results with more data points during the analysis because you are less exposed to overfitting problems with more data points. It looks like you're talking about the analysis here so can you make it clearer why using data from earlier times (say day -1, -2 etc) makes the analysis better on day 0 for example? I find that a bit unclear. I can see that if you are using data from all days to calculate your forecast verification statistics and not only on the days that data is assimilated, you would get better results by using more data because you are better constraining the smoke over a longer period. If that is the case, please make it clearer which data points are included in the verification statistics.

Thanks for the comment. We strongly agree with the reviewer. In the revised manuscript, we included performance statistics with varying analysis, observation and evaluation time windows. Please, see the general response #1.

13. Paragraph starting at Line 242: When I first read this, it sounded like you are varying the vertical resolution of the sources in these experiments. But it turns out you are just varying the maximum heights of the sources. I think you should consider rewording this so that it is immediately clear what you are doing. In some sense, I think varying the vertical resolution and keeping the maximum height the same would be a more interesting experiment. Rising plumes tend to have a neutral buoyancy level at which most of the mass tends to be detrained from the plume. This is true for volcanic plumes; I don't know if it's true here. So, changing the vertical resolution may have a significant impact on the results.

Thanks for the comment. We modified wording for the vertical layer sensitivity test.

(Line 290) “To test the maximum extension, starting from two layers (i.e. with emissions released at 100 and 500 meters), we added the next higher layer over six test runs to investigate the effect of maximum extension of smoke plume. **Figure 6b** shows the results, and correlation and error statistics are summarized in **Table 3**. Including the 5000m layer,”

We also conducted more sensitivity tests of vertical layers. Please, see the general response #2.

For the detraining level of smoke plume, some wildfire smoke plumes were reported to penetrate the PBL, but generally its upward motion is less dynamic compared to volcanic plumes. We believe the maximum level of smoke plume rise is still important, and added more sensitivity tests.

14. Line 255: You must say something about the outcome of the "third test" here. Would you say coverage does not matter? Or is it better for bigger coverage (Domains 3 and 4)? If the results are inconclusive, say so.

Thanks for the comment. We have added discussion on the spatial coverage test.

(Line 306) “In most days, we have better results when we include fire emission sources at least within domain 2. It makes sense considering the effects of transported fire plumes from Mississippi and Louisiana (**Figure 3**). Maximizing geographical coverage (e.g. domain 4) did not always result in the best performance in our case study. This result, however, should be taken carefully because we do not have strong fire activities outside domain 2 in our study case. Strong long-range transport cases, typically from northwestern US, Canada and Alaska, would have bigger impacts.”

15. Line 271: You need to say something about "p" here even if briefly; for example, "p" is the persistence rate that measures...as explained further in Section xxx.

Thanks for the comment. We have added a description for p.

(Line 331) “The persistency rate, p , assumes the change of future day emissions. Its role will be discussed in the next Section.”

16. Lines 298-307. Given the significant uncertainty in "p", an ensemble modelling approach might be fruitful in the forecast mode. Have you looked at this? If not, it might be something you could look at in the future.

Thanks for the comment. Currently, we are considering a dynamic modeling of decaying rate based on varying weather condition. Extending the idea to ensemble approach would be an excellent idea. We will further pursue the idea. We also included this idea in the manuscript.

(Line 381) “An ensemble of HYSPLIT predictions using different meteorological inputs will be used to estimate the uncertainties of the results in the future.”

17. Line 325: What is "PM"?

PM denotes particulate matter (Line 25).