Supplement of Toward closure between predicted and observed particle viscosity over a wide range temperature and relative humidity

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20 1 Gordon Taylor Mixing rules

Figure S1 summarizes the glass transition literature data for sucrose and citric acid together with the fitted Gordon-Taylor mixing rule.



Figure S1. State diagram of the sucrose-water system (left) and citric acid water system (right) as a function of the solute weight fraction. Data are from: (Elamin et al., 1995; Jansson et al., 2005; Lienhard et al., 2012; Lu and Zografi, 1997; Maltini and Anese, 1995; Marsh et al., 2018; Murray, 2008; Rothfuss and Petters, 2016, 2017; Saleki-Gerhardt and Zografi, 1994; Summers and Enever, 1980). The blue solid line and shaded area is the estimation from Gordon-Taylor mixing rule (Gordon and Taylor, 1952) (Eq. 3, main text), assuming $k_{GT} = 5.25 \pm 0.5$ (sucrose-water) and $k_{GT} = 3.4 \pm 0.5$ (citric acid water).

2 The variability of kappa with temperature and water activity.

Zobrist et al. (2008) and Lienhard et al. (2012) report parameterizations of water activity as a function of temperature and solute weight fraction for sucrose and citric acid, respectively. For sucrose:

$$a_w(w_s, T) = \frac{1 + a_1 w_s}{1 + a_2 w_s + a_3 w_s^2} + \left(T - T^\Theta\right) \left(a_4 w_s + a_5 w_s^2 + a_6 w_s^3 + a_7 w_s^4\right) \tag{1}$$

where w_s is the solute weight fraction, T is the absolute temperature and $T^{\Theta} = 298.15$ K. For citric acid:

$$a_w(w_s, T) = \frac{1 - w_s}{1 + q w_s + r w_s^2}$$

$$q = a_1 + a_2 T + a_2 T^2$$

$$r = a_4 + a_5 T + a_6 T^2$$
(2)

Table S1. Coefficients to compute water activity for sucrose and citric acid: ^(a)Zobrist et al. (2008) and ^(b)Lienhard et al. (2012).

Compounds	a_1	a_2	a_3	a_4	a_5	a_6	a_7
$sucrose^{(a)}$	-1.00	-1.013	0.1704	0.001688	-0.005151	0.009607	-0.006142
citric acid (b)	-3.16761	0.01939	-4.02725e - 5	6.59108	-0.05294	1.06028e - 4	



Figure S2. The variability of kappa with temperature and water activity for (a) sucrose and (b) citric acid.

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Coefficients of these parameterizations are summarized in Table S1. The phase diagram model in the main text requires input 30 of $\kappa_m(a_w, T)$, which is computed via

$$\kappa = (w_s^{-1} - 1) \left(\frac{1 - a_w}{a_w}\right) \tag{3}$$

which is transcendental due to the dependence of w_s on a_w . For convenience the inversion from $a_w(w_s, T)$ to $\kappa_m(a_w, T)$ is performed numerically. The resulting dependence of κ_m on water activity (or relative humidity) and temperature is visualized in Figure S2. Figure S2 shows that there is a relatively weak composition and temperature dependence of κ_m for sucrose and a strong dependence of κ_m on temperature for citric acid.

3 Cold-Temperature DCIC experiments

The cold temperature DCIC experiments and associated calibrations are described by example of experiment 11_20190521S20 (Sucrose, this experiment is also given in supplement part of 3.2.2 11_20190521S20). The experimental system is described

- 40 in the main text. During a cold-temperature experiment, the freezer is set to some initial temperature. The particle streams are composed of probe particle DMA 1 (polyethylene particles) and test particle DMA 2 (either sucrose or citric acid) are concentrations are ramped up until a coagulation peak is observed. The particles are dried upstream to ensure that the dewpoint temperature of the combined polyethylene/solute mixture is well below the coldest temperature within the entire system. Once the system is at the desired initial condition, the temperature of the conditioner is decreased through an automatic ramp function.
- 45 The upstream drying system can produce variable RH, depending on the temperature of the cold trap, the state of the silica gel drier, and the optional use of a humidifier. Therefore the total moisture content of the particles leaving the coalescence chamber varies with time and can either increase or decrease.



Figure S3. Variation of critical absolute temperatures and frost point temperatures over the duration of the experiment. The dots (T1, T2 and Tfreezer) correspond to the average temperature during an SMPS scan. The solid lines (TdOptica, TfRotronic) are 1 Hz measurements of dew point temperatures of the experiments.

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start (t = 0) until the end of the ramp. Temperature T1 and T2 monitor the temperature inside the coalescence chamber, which is controlled by two thermoelectric coolers (TE-Technology CP-200). The heat rejected by the thermoelectric coolers is dissipated into the freezer, which causes it to warm during the experiment. At the exit of the coalescence chamber the air is split between the SMPS for size distribution measurement and humidity measurements. Humidity is measured by a Rotronic capacitance

Figure S3 shows the time evolution of temperatures and frost point temperatures at various points in the system from ramp

probe, which senses RH and it's internal temperature. From these the frost point is calculated. Air exiting the Rotronic is passed to a frost-point/dew-point sensor (Optica).



Figure S4. Time evolution of the three measurements (top), the lagged correlation coefficient (bottom left), and the regression line (bottom right). Rot. denotes Rotronic.

55 The Rotronic sensor has faster response time but lower accuracy than the frost-point sensor. Lag-correlated linear regression is used calibrate the Rotronic sensor against the frost point sensor. Figure S4 shows the time evolution of the measurement and the frost point temperature obtained from the calibrated Rotronic sensor. The calibrated Rotronic frost point temperature is used together with the average of T1 and T2 to compute the RH inside the coalescence chamber. The time-lag derived between the Optica and Rotronic was 0 s. This shows that there is not processing lag in the dew-point sensor, but the data still show oscillations of the dewpoint sensor which is attributed to the heating/cooling cycle of the chilled mirror.

Figure S5 shows the SMPS mode diameter of the coagulated particles as a function of temperature and RH obtained during the 30 min ramp. The mode diameter is determined by fitting a lognormal size distribution function to the measured distribution. During the ramp temperature decreases and relative humidity increases. If the partial or complete coalescence occurs, the mode diameter decreases. Upon complete coalescence, the mode diameter remains constant. The change in the mode diameter is



Figure S5. Evolution of the measured SMPS mode diameter versus temperature (left) and RH (right) for the 30 min ramp.

65 typically a few nm (Rothfuss et al., 2019). The diameter data are converted to shape factor data as described in Rothfuss and Petters (2016).



Figure S6. Particle shape parameter ξ versus temperature. Blue circles correspond to mode diameters from the SMPS scans as in Figure S4. Black points correspond to bins of $1.84 \pm 0.32^{\circ}C$. The red line corresponds to the logistic fit defined in Eq. (1)).

Figure S6 shows the resulting relationship between particle shape parameter ξ versus temperature. The midpoint of the ξ vs temperature curve where $\xi = 2.5$ (vertical cyan dotted line). The corresponding midpoint temperature is $T_0 = -26.5^{\circ}$ C and $\sigma = 2.15$. The calculated viscosity through the modified Frenkel sintering (Pokluda et al., 1997) is 4.79×10^7 Pa s where the theory uses the ξ , residence time (60 s), monomer diameter of the particles (90 nm), and the surface tension of sucrose (0.08 Jm⁻²), (Table 1, main manuscript). The corresponding RH value (RH = 67.4%) is averaged between the temperatures -27.5° C and -25.5° C for the range of RHOptica. The vertical dark red dotted lines show the temperatures where $\xi = 1.5$ and

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 $\xi = 3.5$. The corresponding RH, T and viscosity values can be found in Table 1 (main manuscript). In Figure S4, the RH and temperature values are corresponding to the conditions where $\xi = 1.5$.

75 4 Summary of Experiments

4.1 Citric Acid Experiments

4.1.1 1_20190508CA15:



Figure S7. Variation of absolute temperatures and frost point temperatures over the duration of the experiment.



Figure S8. Calibration of RH sensors.



Figure S9. Evolution of the measured SMPS mode diameter versus temperature (left) and RH (right) for the ramp.



Figure S10. Particle shape parameter ξ versus temperature



Figure S11. Variation of absolute temperatures and frost point temperatures over the duration of the experiment.

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Figure S12. Calibration of RH sensors.



Figure S13. Evolution of the measured SMPS mode diameter versus temperature (left) and RH (right) for the min ramp.



Figure S14. Particle shape parameter ξ versus temperature



Figure S15. Variation of absolute temperatures and frost point temperatures over the duration of the experiment.



Figure S16. Calibration of RH sensors.



Figure S17. Evolution of the measured SMPS mode diameter versus temperature (left) and RH (right) for the ramp.



Figure S18. Particle shape parameter ξ versus temperature



Figure S19. Variation of absolute temperatures and frost point temperatures over the duration of the experiment.



Figure S20. Calibration of RH sensors.



Figure S21. Evolution of the measured SMPS mode diameter versus temperature (left) and RH (right) for the ramp.



Figure S22. Particle shape parameter ξ versus temperature



Figure S23. Variation of absolute temperatures and frost point temperatures over the duration of the experiment.



Figure S24. Calibration of RH sensors.



Figure S25. Evolution of the measured SMPS mode diameter versus temperature (left) and RH (right) for the ramp.



Figure S26. Particle shape parameter ξ versus temperature



Figure S27. Variation of absolute temperatures and frost point temperatures over the duration of the experiment.



Figure S28. Calibration of RH sensors.



Figure S29. Evolution of the measured SMPS mode diameter versus temperature (left) and RH (right) for the ramp.



Figure S30. Particle shape parameter ξ versus temperature



Figure S31. Variation of absolute temperatures and frost point temperatures over the duration of the experiment.



Figure S32. Calibration of RH sensors.



Figure S33. Evolution of the measured SMPS mode diameter versus temperature (left) and RH (right) for the ramp.



Figure S34. Particle shape parameter ξ versus temperature



Figure S35. Variation of absolute temperatures and frost point temperatures over the duration of the experiment.



Figure S36. Calibration of RH sensors.



Figure S37. Evolution of the measured SMPS mode diameter versus temperature (left) and RH (right) for the ramp.



Figure S38. Particle shape parameter ξ versus temperature



Figure S39. Variation of absolute temperatures and frost point temperatures over the duration of the experiment.



Figure S40. Calibration of RH sensors.



Figure S41. Evolution of the measured SMPS mode diameter versus temperature (left) and RH (right) for the ramp.



Figure S42. Particle shape parameter ξ versus temperature

4.2 Sucrose experiments:

4.2.1 10_20190429S10:



Figure S43. Variation of absolute temperatures and frost point temperatures over the duration of the experiment.



Figure S44. Calibration of RH sensors.



Figure S45. Evolution of the measured SMPS mode diameter versus temperature (left) and RH (right) for the ramp.



Figure S46. Particle shape parameter ξ versus temperature



Figure S47. Variation of absolute temperatures and frost point temperatures over the duration of the experiment.



Figure S48. Calibration of RH sensors.



Figure S49. Evolution of the measured SMPS mode diameter versus temperature (left) and RH (right) for the ramp.



Figure S50. Particle shape parameter ξ versus temperature



Figure S51. Variation of absolute temperatures and frost point temperatures over the duration of the experiment.



Figure S52. Calibration of RH sensors.



Figure S53. Evolution of the measured SMPS mode diameter versus temperature (left) and RH (right) for the ramp.



Figure S54. Particle shape parameter ξ versus temperature

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