



1 New Methodology Shows Short Atmospheric Lifetimes of

Oxidized Sulfur and Nitrogen due to Dry Deposition

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Abstract

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- The atmospheric lifetimes of pollutants determine their impacts on human health, ecosystems
- and climate and yet, pollutant lifetimes due to dry deposition over large regions have not been
- determined from measurements. Here, a new methodology based on aircraft observations is used
- to determine the lifetimes of oxidized sulfur and nitrogen due to dry deposition over $(3-6)x10^3$
- 20 km² of boreal forest in Canada. Dry deposition fluxes decreased exponentially with distance
- 21 resulting in lifetimes of 2.2-26 hours. Fluxes were 2-14 and 1-18 times higher than model
- 22 estimates for oxidized sulfur and nitrogen, respectively, indicating dry deposition velocities
- which were 1.2-5.4 times higher than those computed for models. A Monte-Carlo analysis with
- 24 five commonly used inferential dry deposition algorithms indicates that such model
- 25 underestimates of dry deposition velocity are typical. These findings indicate that deposition to
- 26 vegetation surfaces are likely under-estimated in regional and global chemical transport models
- 27 regardless of the model algorithm used. The model-observation gaps may be reduced if surface
- 28 pH, and quasi-laminar and aerodynamic resistances in algorithms are optimized as shown in the
- 29 Monte-Carlo analysis. Assessing the air quality and climate impacts of atmospheric pollutants
- 30 on regional and global scales requires improved measurement-based understanding of
- 31 atmospheric lifetimes of these pollutants.



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1 Introduction

Deposition represents the terminating process for most air pollutants and the starting point for ecosystem impacts. Understanding deposition is critical in determining the atmospheric lifetimes and spatial scale of atmospheric transport of pollutants, which in turn, dictates their ecosystem (WHO, 2016; Solomon et al., 2007) and climate (Samset et al., 2014) impacts. In particular, atmospheric lifetimes (7) of oxidized sulfur and nitrogen compounds influence their concentrations and column burdens in air, which affect air quality and hence human exposure (WHO, 2016). Furthermore, the lifetime of these species affects their contributions to atmospheric aerosols, with a consequent influence on climate via changes to radiative transfer through scattering and cloud formation (Solomon et al., 2007). In addition, their deposition can exceed critical load thresholds causing aquatic and terrestrial acidification, and eutrophication in the case of nitrogen deposition (Howarth, 2008; Bobbink et al., 2010; Doney, 2010; Vet et al., 2014; Wright et al., 2018). Quantifying τ and deposition thus provides a crucial assessment of these regional and global impacts. Deposition occurs through wet and dry processes. While wet deposition fluxes can be measured directly (Vet et al., 2014), there are few validated methods for dry deposition fluxes (Wesley and Hicks, 2000), and none which estimates deposition over large regions. Dry deposition fluxes (F) may be obtained using micrometeorological measurements for pollutants for which fast response instruments are available. However, these results are only valid for the footprints of the observation sites, typically hundreds of meters (Aubinet e al., 2012), and their extrapolation to larger regions may suffer from representativeness issues. As a result, atmospheric lifetimes τ with respect to dry deposition have not been determined through direct observations. On a regional scale, dry deposition fluxes are typically derived by multiplying





56 network-measured or model-predicted air concentrations with dry deposition velocities (V_d) (Sickles and Shadwick, 2015; Fowler et al., 2009; Meyers et al., 1991), which are derived using 57 resistance-based inferential dry deposition algorithms (Wu et al., 2018), and compared with 58 limited micrometeorological flux measurements (Wesley and Hicks, 2000; Wu et al., 2018; 59 Finkelstein et al., 2000; Matsuda et al., 2006; Makar et al., 2018) for validation. When applied to 60 61 a regional scale, an inferential-algorithm derived V_d may have significant uncertainties (Wesley and Hicks, 2000; Aubinet et al., 2012; Wu et al., 2018; Finkelstein et al., 2000; Matsuda et al., 62 2006; Makar et al., 2018; Brook et al., 1997). For example, inferred V_d for SO₂, despite being 63 64 the most studied and best estimated, may be underestimated by 35% for forest canopies (Finkelstein et al., 2000). Underestimated V_d for SO₂ and nitrogen oxides can contribute to 65 model over-prediction of regional and global SO₂ concentrations (Solomon et al., 2007; Christian 66 et al., 2015; Chin et al., 2000), or under-prediction of global oxidized nitrogen dry deposition 67 fluxes (Paulot et al., 2018; Dentener et al., 2006). 68 69 Here, a new approach is presented to determine τ with respect to dry deposition and F for total oxidized sulfur (TOS, the sulfur mass in SO₂ and particle-SO₄ (pSO₄)) and total reactive 70 71 oxidized nitrogen (TON, the nitrogen mass in NO, NO2, and others designated as NOz) on a spatial scale of (3-6)x10³ km², using aircraft measurements. This approach provides a unique 72 73 methodology to determine τ and F over a large region. Coupled with analyses for chemical 74 reaction rates (for **TOS** compounds), the average V_d for **TOS** and **TON** over the same spatial scale were also determined. The airborne measurements were obtained during an intensive 75 campaign from August to September 2013 in the AOSR (Gordon et al., 2015; Liggio et al., 2016; 76 77 Li et al., 2017; Baray et al., 2018; Liggio et al., 2019) in northern Alberta, Canada. Direct





- 78 comparisons with modelled dry deposition estimates are made to assess their uncertainties and
- 79 the spatial-temporal scales of air pollutant impacts.

2 Methods

2.1 Lagrangian Flight Design

Details of the airborne measurement program have been described elsewhere (Gordon et al., 2015; Liggio et al., 2016; Li et al., 2017; Liggio et al., 2019; Baray et al., 2018). Briefly, an instrumented National Research Council of Canada's Convair-580 research aircraft was flown over the Athabasca oil sands region (AOSR) in Alberta, Canada from August 13 to September 7, 2013. The flights were designed to determine emissions, assess atmospheric transformation processes and gather data for satellite and numerical model validation. Three flights were flown to study transformation and deposition processes by flying a Lagrangian pattern so that the same pollutant air mass was sampled at different time intervals downwind of emission sources for a total of 4-5 hrs. Flights 7 (F7, Aug 19), 19 (F19, Sep 4) and 20 (F20, Sep 5) took place during the afternoon when the boundary layer was well established. The flights were conducted in clear sky conditions so wet deposition processes were insignificant. The aircraft flew tracks perpendicular to the plume at multiple altitudes between 150 to 1400 m agl and multiple intercepts of the plume downwind. Vertical profiles conducted as spirals were flown at the centre of the plume which provided information on the boundary layer height and extent of plume mixing. There were no other anthropogenic sources downwind of the AOSR.

2.2 Aircraft Measurements

A comprehensive suite of detailed gas- and particle-phase measurements were made from the aircraft. Measurements pertaining to the analysis in this paper are discussed below.



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SO₂ and NO₃. Ambient air was drawn in through a 6.35 mm (1/4") diameter PFA sampling line taken from a rear-facing inlet located on the roof towards the rear of the aircraft. The inlet was pressure-controlled to 770 mm Hg using a combination of a MKS pressure controller and a Teflon pump. Ambient air from the pressure-controlled inlet was fed to instrumentation for measuring SO₂ and NO₃. SO₂ was detected via pulsed fluorescence with a Thermo 43iTLE (Thermo Fisher Scientific, Franklin, MA, USA). NO_y (also denoted as Total Oxidized Nitrogen (TON)) was measured by passing ambient air across a heated (325°C) molybdenum converter that reduces reactive nitrogen oxide species to NO. NO was then detected through chemiluminescence with a Thermo 42iTL (Thermo Fisher Scientific). An inlet filter was used for SO₂, but NO₃ includes particulate nitrate (pNO₃), NO, NO₂, HNO₃ and other oxides of nitrogen such as peroxy acetyl nitrate. The conversion efficiency of the heated molybdenum converter and inlet transmission was evaluated with NO2 and HNO3 and found to be near 100% and >90%, respectively. Other NO₃ species are expected to be greater than that of HNO₃. Species like NO₃ radical and N₂O₅ are expected to be low as they photolyze quickly during daytime. Zeros were performed 3-5 times per flight for all instruments by passing ambient air through an in-line Koby King Jr cartridge for ~5 minutes. Multiple calibrations were conducted before, during and after the study using National Institute Standards and Technology reference standards. Data were recorded at a time resolution of 1 second and corrected for a sampling time delay of 1-3 seconds depending on the instrument. Aerosols. Multiple aerosol instruments sub-sampled from a forward facing, shrouded, isokinetic particle inlet (Droplet Measurement Technologies, Boulder, CO, USA). A Time-of-Flight High Resolution Aerosol Mass Spectrometer (AMS) (Aerodyne Research Inc.) was used to measure non-refractory submicron aerosol components including pSO₄, pNO₃, pNH₄, and p-organics.





123 Details of the AMS and its operations have been published elsewhere (DeCarlo et al., 2006). 124 The instrument was operated in mass spectrometry V-mode with a time resolution of 10 seconds. Filtered measurements were taken 4-5 times per flight to determine background signals. 125 Ionization efficiency calibrations using monodisperse ammonium nitrate were performed during 126 the study with an uncertainty of $\pm 9\%$. Data were corrected for a sampling time delay of 10 127 128 seconds by comparing with faster response instruments e.g. a wing-mounted Forward Scattering Spectrometer Probe Model 300 (FSSP-300) and an in-board Ultra High Sensitivity Absorption 129 Spectrometer (UHSAS) (both from Droplet Measurement Technologies). The AMS data were 130 processed using AMS data analysis software (Squirrel, version 1.51H and PIKA, version 1.10H). 131 132 A collection efficiency was applied to the data and determined by comparing the total AMSderived mass with the mass derived from the size distribution measurements from the UHSAS 133 assuming a density based on the chemical composition; the collection efficiency ranged from 0.5 134 135 to 1. 136 Measurements are discussed in terms of total oxidized sulfur (TOS, the sulfur mass in SO₂ and particle-SO₄ (pSO₄)) and total reactive oxidized nitrogen (TON, the nitrogen mass in 137 138 reactive oxidized nitrogen species, often denoted NO_y). Volatile Organic Compounds (VOCs). Selected VOCs were used to estimate the OH 139 140 concentrations used for determining oxidation rates for SO₂. VOCs were measured with a proton 141 transfer reaction time-of-flight mass spectrometer (PTR-ToF-MS, Ionicon Analytik GmbH, Austria) as well as through discrete canister grab samples. The PTR-ToF-MS and its operation, 142 along with the details of the canister sampling and lab analyses during the study were described 143 144 in detail previously (Li et al., 2017). Briefly, the PTR-ToF-MS used chemical ionization with H₃O⁺ as the primary reagent ion. Gases with a proton affinity greater than that of water were 145





protonated in the drift tube. The pressure and temperature of the drift tube region were maintained at a constant 2.15 mbar and 60°C, respectively for an E/N of 141 Td. The protonated gases were detected using a high-resolution time of flight mass spectrometer at a time resolution of 2 seconds. Instrumental backgrounds were performed in flight using a custom-built zero-air generating unit. The unit contained a catalytic converter heated to 350°C with a continuous flow of ambient air at a flow rate of one litre per minute. The data were processed using Tofware software (Tofwerk AG). Calibrations were performed on the ground using gas standard mixtures from Ionicon, Apel-Reimer and Scott-Marrin for 22 compounds. The canister samples were collected in pre-cleaned and passivated 3L stainless steel canisters that were subsequently sent to an analytical laboratory for GC-FID/MS analyses for a suite of 150 hydrocarbon compounds.

Meteorology and aircraft state parameters. Meteorological measurements have been described elsewhere (Gordon et al., 2015). In brief, 3-D wind speed and temperature were measured with a Rosemount 858 probe. Dew point was measured with an Edgetech hygrometer and pressure was measured with a DigiQuartz sensor. Aircraft state parameters including positions and altitudes were measured with GPS and a Honeywell HG1700 unit.

2.3 Mass transfer rates in the atmosphere

Mass transfer rates (T) across flight screens (Figure 1) were determined using an extension of the Top-down Emission Rate Retrieval Algorithm (TERRA) developed for emission rate determination using aircraft measurements (Gordon et al., 2015). Briefly, at each plume interception location, the level flight tracks were stacked to create a virtual screen. Background subtracted pollutant concentrations and horizontal wind speeds normal to the screen were interpolated using kriging. The background for SO_2 was ~ 0 ppb and pSO₄ was $0.2-0.3~\mu g$ m⁻³





which was subtracted from the pSO₄ measurements before mass transfer rates were calculated
(Liggio et al., 2016). Integration of the horizontal fluxes across the plume extent on the screen
yields the transfer rate *T*. Using SO₂ as an example,

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$$T_{SO_2} = \int_{s_1}^{s_2} \int_{z_1}^{z_2} C(s, z) u_n(s, z) ds dz$$
 (1)

- where C(s,z) is the background subtracted concentration at screen coordinates and z, which represent the horizontal and vertical axes of the screen. The $u_n(s,z)$ is the horizontal wind speed normal to the screen at the same coordinates.
- Since the lowest flight altitude was 150 magl, it was necessary to extrapolate the data to the surface as per the procedures described previously (Gordon et al., 2015). Extrapolation to the surface methods were compared and differences were included in the uncertainty estimates. Since the main source of SO₂ is from the elevated facility stacks, the uncertainty for a single screen is estimated at 4% (Gordon et al., 2015). NO_y was also extrapolated linearly to the surface and the mass transfer rates were similarly compared to other extrapolation methods. NO_y sources include the elevated facility stacks and surface sources such as the heavy hauler trucks operating in the surface mines. The uncertainty in the resulting *T* for a single screen is estimated to be larger at 8%, as a larger fraction of the NO_y mass may be below the lowest measurement altitude (Gordon et al., 2015). Sulfur and nitrogen data were also extrapolated linearly to background values from the highest altitude flight tracks upwards to the mixed layer height, which was determined from vertical profiles of pollutant mixing ratios, temperature and dew point (Table 1). Two different approaches, a finite jump model and a gradient flux approach (Stull, 1988; Degrazia et al., 2015), were used to estimate the potential upward loss across the interface between the boundary layer and the free troposphere for sulfur. In both approaches, the





upward S flux was a minor loss at < 45 g/km²/hr, about 3 orders of magnitude lower than the several to many kg/km²/hr horizontal advectional transport that were determined using TERRA.

Changes in T (denoted ΔT) were then calculated as the differences in T between pairs of virtual screens. The uncertainty in ΔT was estimated as 8% for TOS and 26% for TON as supported by emission rate uncertainties determined for box flights (Gordon et al., 2015). The uncertainty analysis for box flights is applicable to ΔT here, as both account for uncertainties with an upwind and a downwind screen. The ΔT uncertainties were propagated through subsequent calculations.

Knowing ΔT , and accounting for the net rates of chemical loss and formation between screens for SO₂ and pSO₄, the deposition rates (and subsequently the deposition flux in tonnes S (or N) km⁻² hr⁻¹, Section 2.4 were determined as follows, using sulfur compounds as an example:

$$\Delta T_{SO_2} = T_{SO_2}(t_2) - T_{SO_2}(t_1) = X_{SO_2} - D_{SO_2}$$
 (2)

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$$\Delta T_{pSO_4} = T_{pSO_4}(t_2) - T_{pSO_4}(t_1) = X_{pSO_4} - D_{pSO_4}$$
 (3)

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$$\Delta T_{TOS} = T_{TOS}(t_2) - T_{TOS}(t_1) = -D_{TOS}$$
 (4)

where X_{SO2} is the rate of chemical reaction loss of sulfur mass in SO₂, X_{pSO4} is the rate of chemical formation of sulfur mass as pSO₄, D_{SO2} and D_{pSO4} are deposition rates of sulfur mass in SO₂ and pSO₄ respectively, and t₁ and t₂ are plume interceptions times at Screen 1 and Screen 2, respectively. Reaction with the OH radical was considered to be the most significant chemical loss of SO₂ and the most significant path for the formation of pSO₄ (further details in SI Section S4. X_{SO2} and X_{pSO4} were determined using estimated OH radical concentrations, which were determined using the methodology described in SI Section S4.





Dry deposition rates, D_{SO2} and D_{pSO4} , and their uncertainties were determined using Eq. (2) and (3). For total oxidized sulfur **TOS** (i.e., sulfur in SO₂ + pSO₄) and total oxidized nitrogen **TON** (i.e., nitrogen in NO_y) the chemistry term is not relevant, and thus, the dry deposition rate D_{TOS} was directly determined from ΔT_{TOS} using equation (4), and respectively for **TON**.

2.4 Dry deposition fluxes and dry deposition velocities

Average dry deposition fluxes (F) for **TOS** and **TON** were obtained by dividing the deposition rates D with the footprint surface area of the plume between two adjacent screens (Figure 1 grey shaded regions), as shown in Equation 5 for the dry deposition flux F_{TOS} of **TOS** (in t S km² hr⁻¹):

$$F_{TOS} = \frac{D_{TOS}}{Area} \tag{5}$$

where the surface area, Area, was identified as the geographic area under the plume extending to the edges of the plume where concentrations fell to background levels (i.e. SO_2 to ~ 0 ppb; $SO_4 \sim 0.2$ ug m⁻³). This approach was similarly used to derive deposition fluxes from an air quality model, Global Environmental Multiscale – Modelling Air-quality and Chemistry (GEM-MaCH) (Moran et al., 2010; also see SI Section S5 for details). The geographic surface area uncertainty is estimated at 5%. Dry deposition fluxes between the sources and the first screen were also estimated using ΔT based on the extrapolated transfer rates back to the source region ('extended' region). The surface area boundaries for these 'extended' regions were determined using latitude and longitude coordinates that were weighted by emissions. This was done by first using the average wind direction from Screen 1 and creating a set of parallel back trajectories (~ 20)



 SO_2).



starting at different parts of Screen 1 back across the source region. For **TON**, the NO_x emission sources along each back trajectory were weighted by their NO_x emissions to obtain an emissions-weighted center location with latitude and longitude coordinates for each back trajectory. The line connecting these emissions-weighted center locations formed the boundary of the extended surface area. The extended surface area was similarly determined for **TOS** based upon the known locations of the major SO₂ point sources. The uncertainty of the 'extended' regions is estimated at 10% based on repeated optimizations of the geographical area. Surface areas are visualized as grey shaded regions between screens in Figure 1 and tabulated in SI Table S1.

Spatially-averaged dry deposition velocities, **V**_d, based on the aircraft measurements were determined over the surface area between screens using average plume concentrations across pairs of screens at about 40 meters above the ground for **TOS** and **TON** (e.g. Equation 6 for

$$V_d = \frac{F_{SO2}}{[SO2]} \tag{6}$$

The largest source of uncertainty in V_d calculated this way was the determination of concentration at 40 meters above the surface as the measurements were extrapolated from the lowest aircraft altitude to the surface and interpolated concentrations were used. The measurement-derived V_d are compared with those from GEM-MACH which uses inferential methods.





2.5 Monte-Carlo simulations of dry deposition velocities using multiple resistance-based parameterizations

Parameterization of dry deposition in inferential algorithms is commonly based on a resistance approach with dry deposition velocity depending on three main resistance terms as below:

$$V_d = \frac{1}{R_d + R_b + R_c} \tag{7}$$

where R_a , R_b and R_c represent the aerodynamic, quasi-laminar sublayer and bulk surface resistances respectively. Although these resistance terms are common among many regional air quality models (Wu et al., 2018), the formulae used (and inputs in to these formulae) to calculate the individual resistance terms differ significantly among the inferential deposition algorithms. To assess the potential for a general underestimation of V_d across different inferential deposition algorithms, and to compare with the aircraft-derived V_d , five different inferential deposition algorithms, including that used in the GEM-MACH model for calculating V_d (Wu et al., 2018) were incorporated into a Monte-Carlo simulation for V_d for SO₂. NO_y was not considered here, as its measurement includes multiple reactive nitrogen oxide species with different individual deposition velocities. We note that many of the inferential algorithms are based on observations of SO₂ and O₃ deposition made at single sites, and the extent to which a chemical is similar to SO₂ or O₃ features into its V_d calculation – the comparison thus has relevance for species aside from SO₂.

The five deposition algorithms considered are denoted ZHANG, NOAH-GEM, C5DRY, WESLEY and GEM-MACH. To perform the simulations, formulae for the first four algorithms





were taken from Wu et al. (2018) and for GEM-MACH taken from Makar et al. (2018). The
stomatal resistance in the ZHANG algorithm was from Zhang et al. (2002). The GEM-MACH
formula (Equation 8.7 in the SI of Makar et al. (2018)) for mesophyll resistance R_{mx} contained a
typo (missing the Leaf Area Index (LAI)) and was corrected for as follows:

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$$R_{mx} = [LAI(H^*/3000 + 100 f_0)]^{-1}$$
 (8)

Prescribed input values were constrained by the range of possible values consistent with the conditions during the aircraft flights and are shown in SI Table S3 with associated references. Calculations for the R_a term were based on unstable and dry conditions as observed during the aircraft flights. The Monte-Carlo simulation generated a distribution of possible V_d values, based on randomly generated values of the input variables to each algorithm and selected from Gaussian distributions with a range of 3 sigma for all input parameters. All simulations were performed with the same input values that were common between the algorithms.

3 Results and Discussion

3.1 Meteorological and Emissions Conditions during the Transformation Flights

During the experiments, the dry deposition rates (D) were quantified under different meteorological conditions and emissions levels of **TOS** and **TON** (E_{TOS} and E_{TON}) for the three flights (see Table 1). These differences played important roles in the observed pollutant concentrations and resulting dry deposition fluxes for F7, F19 and F20. Mixed layer heights (MLH) were derived from aircraft vertical profiles that were conducted in the centre of the plume at each downwind set of transects. The profiles of temperature, dew point temperature, relative humidity and pollutant mixing ratios were inspected for vertical gradients indicating a contiguous layer connected to the surface. The highest MLH was determined for F7 at 2500





300 magl. The combination of a high MLH in F7 with the highest wind speeds resulted in the lowest pollutant concentrations of the three flights. In F19, lower wind speeds and the lowest mixed 301 layer heights led to the highest pollutant levels. F20 had emissions and meteorological 302 conditions that were in between F7 and F19 resulting in pollutant concentrations between those 303 304 of F7 and F19. 305 Emission rates of SO₂ and NO_x (designated as E_{TOS} and E_{TON}) from the main sources in the AOSR were estimated from the aircraft measurements and varied significantly between the 306 307 three flight days. The measurement-based emission rates of E_{TOS} and E_{TON} were taken from the 308 mass transfer rates of T_{SO2} and T_{NOy} (described in Methods) by extrapolating backwards to the source locations in the AOSR using exponential functions (Figure 2, Section 3.2). For TOS, the 309 source location was set at 57.017N, -111.466W, where the main stacks for SO₂ emissions are 310 located. For **TON**, the source locations were determined from geographically weighted 311 312 locations. Emission rates E_{TOS} and E_{TON} for each flight are shown in Table 1. Model-based E_{TOS} and E_{TON} were also obtained from the 2.5 km x 2.5 km gridded 313 314 emissions fields that were specifically developed for model simulations of the large AOSR surface mining facilities (Zhang et al., 2018) i.e. Suncor Millenium, Syncrude Mildred Lake, 315 316 Syncrude Aurora North, Shell Canada Muskeg River Mine & Muskeg River Mine Expansion, 317 CNRL Horizon Project and Imperial Kearl Mine. The emissions fields have been used in GEM-MACH (described in SI Section S5) to carry out a number of model simulations (Zhang et al., 318 2018; Makar et al., 2018) including for the present study. In this work, emissions were summed 319 320 from various sources including offroad, point (Continuous Emissions Monitoring (CEMS)), and 321 point (non-CEMS) for the surface mines to obtain total AOSR hourly emission rates for the

magl whereas F19 had the lowest MLH at 1200 magl (Table 1). In F20, the MLH was 2100



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flight time periods of interest (Table 2). The standard deviations reflect the emissions variations during the simulated flight.

3.2 Mass Transfer Rates

The mass transfer rates T across the virtual flight screens for all three flights are shown for TOS and TON in Figure 1 and plotted in Figure 2. In F20, two distinct TON plumes were observed, allowing separate T calculations for TON. Monotonic decreases in T were observed for both TOS and TON during transport downwind in all flights, clearly showing dry depositional losses. The deposition rate D (Methods, Section 2.3) was used to estimate the cumulative deposition of **TOS** and **TON** as a fraction of E_{TOS} or E_{TON} and is shown in Figure 3 for F7, F19 and F20 for transport distances of up to 107-135 km downwind of the sources. Curves were fitted to the **TOS** and **TON** dry deposition cumulative percentages from which $d_{1/e}$ and τ were determined (SI Table S1). The transport e-folding distance $(d_{I/e})$ was determined where 63.2% of E_{TOS} (or E_{TON}) was dry deposited, i.e., $\sum_{d=0}^{d_{1/e}} D(d) = 0.368 E_{TOS}$. The atmospheric lifetimes (τ) were derived as $\tau = d_{I/e}/u$, where u was the average wind speed across the distance $d_{1/e}$. These estimates were compared with predictions from the regional air quality model GEM-MACH (Makar et al., 2018; Moran et al., 2010; SI Section S5) using facility emission rates (Table 2). For **TOS** during F19, (Figure 3b, e), the observed cumulative deposition at the maximum distance accounted for $74\pm5\%$ vs. the modelled 21% of E_{TOS} , due mostly to SO_2 dry deposition (>92%). Fitting a curve to D and interpolating the cumulative deposition fraction to the 63.2% E_{TOS} loss leads to a $d_{1/e}$ of 71±1 km, versus 500 km for the model prediction. Under the prevailing wind conditions, the observed distance indicates a τ for **TOS** of approximately 2.2 hours, whereas the model prediction indicated 16 hours. Large observation-based values and model prediction differences in lifetime were also evident for the





deposition and vastly overestimated $d_{1/e}$ and τ . The observation-based values for τ are also lower than average lifetimes of 1–2 days for SO₂ and 2–9 days for pSO₄ derived from global models (Chin et al., 2000; Benkovitz et al., 2004; Berglen et al., 2004), which include the effects of wet deposition and chemical conversion for SO₂, thus making their implicit residence times with respect to dry deposition even longer.

For **TON** in F19 (Figure 3h, 1), the observed cumulative deposition accounted for $49\pm11\%$ of E_{TON} at the maximum flight distance, versus 19% predicted by the model. Similar model underestimates for cumulative deposition fractions were found for F7 and F2O.

Extrapolating to the 63.2% cumulative deposition fraction, $d_{1/e}$ was estimated to be 190±7 km for F19 versus a predicted 650 km from the model, implying a τ of approximately 5.6 hours for the measurement-based results and 23 hours for the model prediction. Again, analogous differences

for F7 and F20 were found (SI Table S1). Similar to TOS, the measurement-based $d_{I/e}$ and τ

values for TON were significantly smaller than commonly accepted lifetimes of a few days for

other flights (SI Table S1). Clearly, the model predictions significantly underestimated

3.3 Dry Deposition Fluxes F

nitrogen oxides in the boundary layer (Munger et al., 1998).

Using D, the average dry deposition fluxes, F (in tonnes S or N km² hr⁻¹), were calculated by dividing D by the plume footprint surface areas estimated by extending to the plume edges where the concentrations fell to background levels (Methods, Section 2.4). These footprints are shown as the gray shaded geographic areas in Figure 1, totaling 3500, 5700 and 4200km² for F7, F19, and F20 plumes, respectively; see SI Table S1 for **TON** plume areas). Figure 4a shows F_{TOS} values for all three flights, exhibiting exponential decreases with increasing distance away from the sources and showing e-folding distances for F_{TOS} of 18, 27, and 55 km for F7, F19, and



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Similarly, F_{TON} decreased exponentially with increasing transport distances in all flights (Figure 4c), exhibiting e-folding distances of 18 and 33 km for F7 and F19, and 55 and 189 km for the south and north **TON** plumes during F20, respectively. These e-folding distances were similar to those for F_{TOS} , indicating similar rates of decreases in F_{TON} with transport distances. As expected from the τ and transport e-folding distance $d_{1/e}$ comparisons, the GEM-MACH model F_{TOS} were significantly lower than the measurement-based F_{TOS} results (Figure 4a), with the model F_{TOS} e-folding distances usually large: 133, 797, and 57 km for F7, F19, and F20, respectively, or 7.4, 29.5, and 1.1 times longer than the corresponding measurement results. Part of the differences between model and measurement F_{TOS} could be explained by differences in actual versus model emissions, E_{TOS} (Tables 1 vs 2). To remove the influence of emissions, an emission-normalized flux (= F_{TOS}/E_{TOS} and F_{TON}/E_{TON}) was calculated for both measurement and model (SI Figure S1). Figure 4b shows the ratios of measurement to model normalized emissions for TOS. The model emission-normalized fluxes F_{TOS}/E_{TOS} were lower than the measurement-based values by factors of 2.5-14, 1.8-3.4, and 2.0-3.0 for F7, F19, and F20, respectively, decreasing with increased transport distances. However, they coalesce to a factor of 2 at the furthest distances sampled by the aircraft, indicating that the model F_{TOS} estimates were biased low by similar factors. The decreasing trends suggest that at distances further downwind, model fluxes may exceed measurement-based fluxes, albeit at magnitudes lower than those shown in Figure 4a, which is consistent with earlier study results (Makar et al., 2018). For F_{TON} , the model-predicted values were also lower than the measurement results, especially near the sources (Figure 4c), and showed little variation with transport distances for all flights, in strong contrast to the exponential decays observed from the aircraft. However, the emission-

F20, respectively. More than 90% of the decreases in F_{TOS} were accounted for by F_{SO2} .



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normalized fluxes (= F_{TON}/E_{TON}) for the model approached those from measurements within maximum flying distances for F19 and F20, although still significantly lower for F7 (>10x) (Figure 4d).

3.4 Dry Deposition Velocities V_d

The shorter $d_{I/e}$ and τ , and larger deposition fluxes F near the sources determined from the aircraft measurements compared to predictions by the GEM-MACH model indicate that the model V_d was underestimated. Gas-phase V_d in the model is predicted with a standard inferential "resistance" algorithm (Wesley, 1989; Jarvis, 1976), with resistance to deposition calculated for multiple parameters including aerodynamic, quasi-laminar sublayer and bulk surface resistances (Baldocchi, 1987). To demonstrate the model underestimation in V_d , comparisons between the measurement-based and model V_d were made where an evaluation of V_d for TOS and TON was possible. All F_{SO2} were converted into V_{d-SO2} by dividing F_{SO2} by interpolated SO₂ concentrations at 40 meters above ground, averaging 1.2±0.5, 2.4±0.4, and 3.4±0.6 cm s⁻¹ for F7, F19 and F20, respectively, across the plume footprints (Methods, Section 2.4 and SI Table S2). The corresponding model V_{d-SO2} derived in the same way as the observations was 0.72, 0.63, and 0.58 cm s⁻¹, 1.7-5.4 times lower than observations (SI Section S5; SI Table S2). Interestingly, the median V_d for SO₂ of 4.1 cm s⁻¹ determined using eddy covariance/vertical gradient measurements from a tower in the AOSR is higher than the mass balanced method showing an even larger discrepancy compared to the model (SI Section S3; Figure S4). Similarly, derived V_{d-TON} averaged 2.8±0.8, 1.6±0.5, 4.7±1.4 and 2.2±0.7 cm s⁻¹ F7, F19, F20 south plume, and F20 north plume, respectively (SI Table S2), 1.2-5.2 times higher than the corresponding modelled V_{d-TON} of 1.4, 1.3, 0.92, and 0.90 cm s⁻¹.



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3.5 Monte-Carlo simulations of V_d for SO₂

To further demonstrate observation-model differences, V_d distributions of SO_2 from five common inferential dry deposition algorithms (Wu et al., 2018; Makar et al., 2018) were determined for the conditions encountered during the flights using a Monte-Carlo approach as described in Methods, Section 2.5). Results for the V_d simulations algorithms are shown in Figure 5a. Histograms for all five algorithms have peak V_d values at ~1 cm s⁻¹ or lower. Probability distributions for the individual resistance terms, R_a , R_b , and R_c showed that the dominant resistance driving V_d was the R_c term (SI Figure S2). Also shown in Figure 5a are the measurement-derived V_d for Flights 7, 19 and 20, and that from the Oski-ôtin ground site. The observed V_d values are larger than the V_d values for most of the simulations, with the exception of Flight 7, where the Zhang et al. (2002), NOAH-GEM (Wu et al., 2018) and C5DRY (Wu et al., 2018) algorithms' distributions agree with the observations. All algorithms are biased low relative to the observations for the remaining flights, and the Oski-ôtin ground site. It is noted that the ground-site observations that were derived using a standard flux tower methodology (SI Section S3) at a single site, appeared to be higher than all other V_d ; nevertheless, these observations are closer to the aircraft values than the algorithm estimates. These results indicate that an underestimation of V_d relative to both aircraft and ground based measurements in the AOSR region is not unique to the GEM-MACH model or its dry deposition algorithm; similar results would occur with the other algorithms included in the Monte-Carlo simulations, all of which are used within other regional models. To investigate the possible reasons behind the low model V_d relative to the observations, a series of sensitivity tests using SO_2 were conducted. Differences in model V_d have been shown to be mainly due to differences in the calculated R_c (Wu et al., 2018), and sensitivity tests here



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indicated that R_c is particularly sensitive to the cuticular resistance R_{cut}. Hence, factors causing R_{cut} to change can have significant impact on model V_d . In some of the algorithms, R_{cut} and other resistance terms are dependent on the effective Henry's Law constant K_H* for SO₂. The Monte-Carlo simulations for Figure 5 assumed a surface pH= 6.68 resulting in a K_H^* of 1×10^5 for SO₂. Additional Monte-Carlo simulations were performed for the GEM-MACH dry deposition algorithm by adjusting K_H* assuming different pH with small variations from a pH=6.68 significantly changing R_c , R_{cut} , and V_d (SI Figure S3). In Figure 5b – red dashed line, with a surface pH change from 6.68 to 8, consistent with possible alkaline surfaces in the AOSR (Makar et al., 2018), in the GEM-MACH simulation, the V_d distribution is moved to larger values) with its peak value shifting from 0.6 to 1.4 cm s⁻¹. These results show that model V_d may be highly sensitive to assumed surface pH, at least when using some inferential dry deposition algorithms which are pH-dependent. However, Figure 5b shows that this pH-associated increase in V_d is still insufficient to encompass the range of measurement-derived V_d . Increasing pH to 8 for the GEM-MACH simulation reduces R_{cut}, hence R_c, to values much smaller than R_a and R_b, suggesting that model V_d cannot further increase without reductions in both R_a and R_b . In other words, R_a and R_b were probably overestimated in the current deposition velocity algorithms. By using the Zhang et al. (2002) R_a and the NOAH-GEM (Wu et al., 2018) R_b parameterizations in the GEM-MACH algorithm, a further shift of the GEM-MACH V_d distribution to larger values was found, with the range encompassing most of the observations (Figure 5b, pink dashed line). Clearly, from the Monte-Carlo simulations for $SO_2 V_d$ comparisons, inferential dry deposition algorithms as used in regional and global chemical transport models need to be further validated and improved, especially over large geographic regions. Here, the role of pH was identified for improvement in some algorithms along with possible improvement in aerodynamic





and quasi-laminar sublayer resistance parameters. Yet, for other algorithms and for \mathbf{TON} compounds, the model low-biases in V_d remain to be investigated.

The underestimates suggest that the applications of these algorithms in regional or global models may significantly underestimate model predictions of **TOS** dry depositional loss from the atmosphere. Underestimates in V_d are the result of a combination of uncertainties in the parameterizations of each algorithm. In the case of the algorithm used in GEM-MACH, by adjusting the assumed surface pH from 6.68 to 8 (justifiable given the considerable dust emissions in the region (Zhang et al., 2018)), the model V_d moved closer to the aircraft-derived values (Figure 5b), reducing the model-observation gap by approximately 2/3. In addition, substituting the aerodynamic resistance and quasi-laminar sublayer resistance parameterizations in the GEM-MACH algorithm with that from Zhang et al. (2002) and NOAH-GEM (Wu et al., 2018), respectively, resulted in a further increase in the model V_d distribution that encompasses most of the observations (Figure 5b). Clearly, different algorithms respond differently to changes in the parameterizations, and validation and adjustment to each algorithm needs measurement-based results over large regions such as derived here.

4 Conclusions

The atmospheric transport distances and lifetimes $d_{1/e}$ and τ determined from the aircraft measurements are substantially shorter than the GEM-MACH model predictions, and the dry deposition fluxes and velocities F and V_d near sources are larger compared to the predictions by GEM-MACH and five inferential dry deposition velocity algorithms, respectively. There are important implications for these measurement-model discrepancies. Such discrepancies indicate that regional or global chemical transport models using these algorithms are biased low for local





deposition and high for long-range transport and deposition, and **TOS** and **TON** loss from the atmosphere are significantly under-predicted, resulting in overestimated lifetimes. Moreover, emissions assessed through network measurements or budget analysis of atmospheric **TOS** and **TON** (Sickles and Shadwick, 2015; Paulot et al., 2018; Berglen et al., 2004) may be underestimated due to lower V_d used in these estimates, and may require reassessing the effectiveness of control policies. Shorter τ for **TOS** and **TON** reduces their atmospheric spatial scale and intensity of smog episodes, potentially reducing human exposures (Moran et al., 2010). Importantly, shorter τ for **TOS** and **TON** reduces their contribution to atmospheric aerosols; consequently, the negative direct and indirect radiative forcing from these sulfur and nitrogen aerosols are reduced, reducing their cooling effects on climate (Solomon et al., 2007). These impacts suggest that more measurements to determine τ and F for these pollutants across large geographic scales and different surface types are necessary to better quantify their climate and environmental impacts in support of policy. While in the past such determination was difficult and/or impossible, the present study provides a viable methodology to achieve such a goal.





Table 1. Average observed meteorological conditions and facility emission rates of **TOS** (E_{TOS}) and **TON** (E_{TON}), (determined from extrapolated (to distance=0) transfer rates; Figure 1) for **TOS** and **TON** during the F7, F19 and F20 flights. SP=south plume; NP=north plume.

Flight	Date	Time (UTC)	Mean wind speed (m/s)	Mean wind direction (°)	Mixed layer height (m agl)	ETOS (t/hr)	ETON (t/hr)
7	Aug 19/13	2007- 0108	13.0±1.0	256±11.7	2500±100	3.4	1.2
19	Sep 4/13	1854– 2353	9.5±1.9	218±16	1200±100	18.5	3.9
20	Sep 5/13	1933- 2436	8.9±1.2	281±11	2100±100	5.8	2.2 (SP) 1.2 (NP)

Table 2. Model average meteorological conditions and facility emission rates of **TOS** (E_{TOS}) and **TON** (E_{TON}) during the F7, F19 and F20 flights as described above. SP=south plume; NP=north plume.

Flight	Date	Time (UTC)	mean wind speed (m/s)	mean wind direction (°)	mixed layer height (m agl)	E _{TOS} (t/hr)	ETON (t/hr)
7	Aug 19/13	2007- 0108	12.6±0.3	253±5.0	1670±80	3.8	2.9
19	Sep 4/13	1854– 2353	8.1±1.0	225±4.6	1450±43	4.3	2.4
20	Sep 5/13	1933- 2436	9.1±0.7	275±1.6	1590±42	3.7	1.5 (SP) 0.9 (NP)



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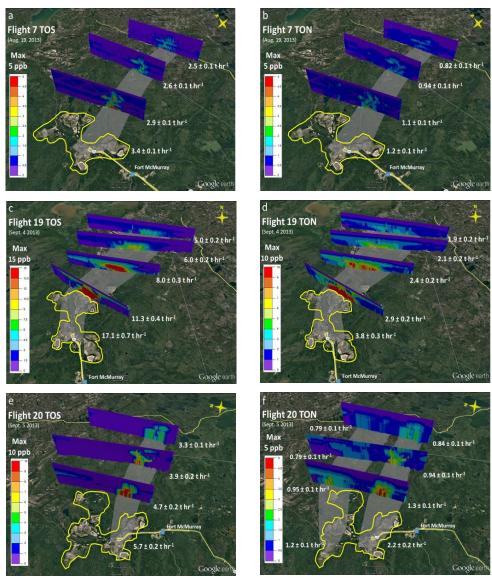


Figure 1. TOS and **TON** plumes downwind of the AOSR during three Lagrangian flights, F7, F19 and F20. The AOSR facilities are enclosed by the yellow outline. The transfer rates *T* in tonnes S or N hr⁻¹ across each screen are shown. The grey shaded surface areas are identified as the geographic footprint under the plumes. Data: Google, Image 2016 Digital Globe © Google Maps.

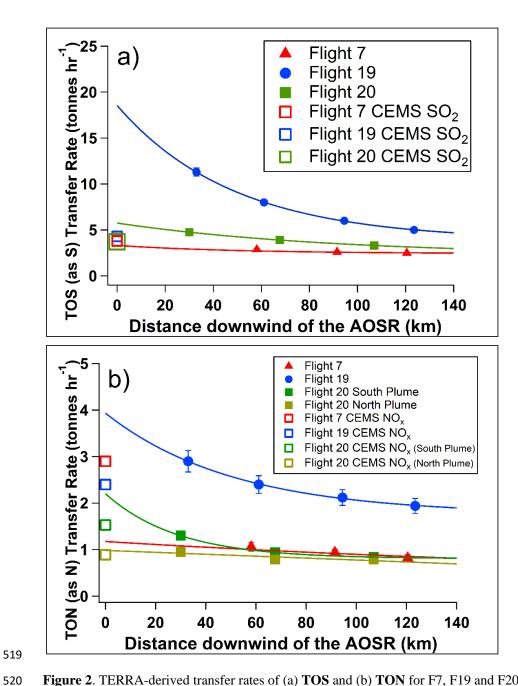


Figure 2. TERRA-derived transfer rates of (a) **TOS** and (b) **TON** for F7, F19 and F20. The vertical bars indicate the propagated uncertainties. The model emission rates E_{TOS} and E_{TON} are shown by the open symbols.



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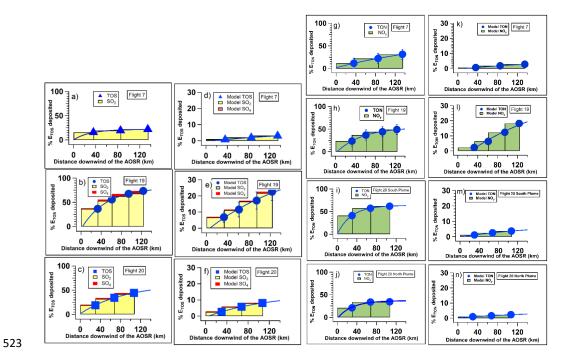


Figure 3. Cumulative dry deposition as a percentage of emissions of E_{TOS} E_{TON} for F7, F19 and F20 measurements and GEM-MACH model predictions. The bars show the dry deposition due to SO₂ and pSO₄. The curves were fitted to the **TOS** and **TON** dry deposition percentages from which $d_{1/e}$ and τ were determined.





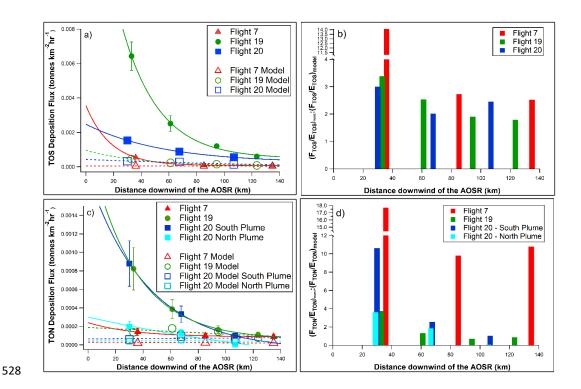


Figure 4. Dry deposition fluxes F_{TOS} and F_{TON} determined from measurements (solid symbols) and GEM-MACH model predictions (open symbols). (a) F_{TOS} , (b) ratios of measurement to model normalized emissions F_{TOS}/E_{TOS} , (c) F_{TON} , and (d) ratios of measurement to model normalized emissions F_{TON}/E_{TON} .

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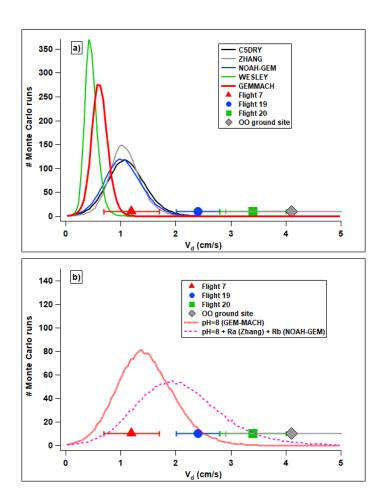


Figure 5. (a) Distributions of V_d for SO₂ from Monte-Carlo simulations using 5 different deposition parameterizations (Wu et al., 2018; Makar et al., 2018) and (b) Monte-Carlo simulations for the GEM-MACH algorithm using a pH=8 and using a pH=8 plus replacing the GEM-MACH algorithm R_a and R_b formulae with that from Zhang et al. (2002) and NOAH-GEM (Wu et al., 2018), respectively. Aircraft-derived V_d for F7, F19 and F20 as well as the median value for the Oski-ôtin ground site (SI Figure S4) are shown in both (a) and (b) for comparison.





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705 706 707 708 709 710	KH, SML, JL, SM, RM, RS, JO, MW all contributed to the collection of aircraft observations in the field. KH, RM and JO made the SO_2 , NO_y and pSO_4 measurements and carried out subsequent QA/QC of data. RM analyzed canister VOCs and provided OH concentration estimates. SM provided OH estimates from MCM modelling as a comparison. AD contributed to the development of TERRA. JL wrote the Monte Carlo code. PM and AA ran the model and provided model analyses. JZ provided emissions data. LZ and RS provided deposition algorithm parameters. KH and SML wrote the paper input from all co-authors.
711	Code availability
712 713 714 715	All the computer code associated with the TERRA algorithm, including for the kriging of pollutant data, a demonstration dataset and associated documentation is freely available upon request. The authors request that future publications which make use of the TERRA algorithm cite this paper, Gordon et al., Liggio et al., or Li et al. as appropriate.
716	Data availability
717 718 719 720	All data used in this publication are freely available on the Canada-Alberta Oil Sands Environmental Monitoring Information Portal: https://www.canada.ca/en/environment-climate-change/services/oil-sands-monitoring/monitoring-air-quality-alberta-oil-sands.html
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