Reply to the first reviewer.

General Comment:

The change of land-atmosphere interaction on the Tibetan Plateau has a significant impact on the climate of China and even the whole world. However, due to the high altitude and harsh climate condition, there are few observations and a poor applicability for the empirical models parameterized in other regions. This paper used the measurements with the high temporal resolution to calibrate the parameterization of empirical models for downward longwave radiation, to improve their applicability in the Tibetan Plateau. This paper is expected to provide a useful reference for scientists working on the land surface energy balance over the Tibetan Plateau. To make this paper suitable for publication, please address satisfactorily the specific comments I have appended below.

Reply:

We greatly appreciate the reviewer's opinions on our submission and the manuscript was revised according to these valuable comments and suggestions.

Major Comments:

(1) The biggest flaw in this article is the lack of validation. The author used observation data to optimize the parameterization of the data, but did not use other observation data to conduct effective verification. The dataset used to optimize models were not independent from the dataset to verified models, which seriously affected the credibility of the validation.

Reply:

We partly agree with this comment. The parameterization was established and validated by using 10-fold cross-validation method, which is widely used in the literatures. As suggested in the literature, this method shows the skill of a regression model on unseen data and thereby would be expected to result in a less biased or less optimistic estimate of the model skill than other methods, such as a simple train/test split (James et al., 2013). This means that the parameterizations are, to some extent, validated by this process, although it is not independently assessed.

In order to clearly show the performance of our localized parameterization, we used independent DLR measurements at Lhasa (91.1°E, 29.9°N, 3649 m ASL) during summer in 2012 to verify our model in the revised manuscript according to your suggestion. All clear-sky, cloudy-sky parameterizations including our models were validated and the bias and RMSE are shown in following figure.

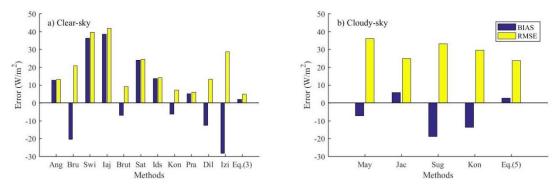


Fig.1 BIAS and RMSE for the LDR parameterizations using (a) the published clearsky model and Eq.(3), and (b) cloudy-sky parameterizations and Eq.(5).

Comparing to the existed parameterizations, the Eq.(3) and Eq.(5) have the smallest BIAS (both less than 2 W·m⁻²) and RMSE (Eq.(3)'s is less than 5 W·m⁻² and Eq.(5)'s is less than 25 W·m⁻²) at Lhasa. This clearly shows that our localized parameterizations produce the best results.

(2) The change of cloud cover during the day is analyzed based on the downward shortwave radiation, but the change of cloud cover at night is not involved. The authors should examine whether there are significant differences in the amount of cloud cover over the Tibetan plateau between day and night. Reply:

According to Sato et al. (2007), there are diurnal cycle of clouds over Tibetan Plateau. However, since we mainly calculate cloud fraction from daytime shortwave radiation measurements, DLR during nighttime is not considered in this research and thereby needs further study in future. We did discussed this issue in the section of discussion.

Sato, T., Miura, H., and Satoh, M.: Spring diurnal cycle of clouds over Tibetan Plateau: Global cloud-resolving simulations and satellite observations, Geophysical Research Letters, 34, 10.1029/2007gl030782, 2007.

(3) The main content of this paper is to adjust the parameters of the empirical model so as to improve its performance in the Tibetan Plateau. However, the process of parameter optimization is not introduced in detail in this paper. We want to guide whether there is some physical significance to the parameters adjustment, or what is the selection criteria for you to finally choose those parameters, and whether those parameters are optimal or not.

Reply:

Selection of variables in the DLR parameterization is generally dependent on physical consideration, for example, air temperature and water vapor dominantly determine clear-sky DLR, however, cloudy DLR is substantially influenced by clouds (cloud cover, its bottom height etc.), so nearly all DLR parameterizations use these variables as dependent variables. This is the basic rationale in the DLR parametrization. It should be noted that the coefficients associated with these variables in the parameterizations vary substantially in different geographical locations that are characterized by different climate. In other words, the values of the parameters, to some extent, are representative of the average atmosphere condition, and therefore locally corrected parameterizations would produce better results and higher time resolution would offer more accurate estimations (Grubler et al., 2012). This is exactly why the DLR parametrizations should be corrected in different places by using local measurements.

The coefficients in the references (Table 2) were originally calibrated and determined in different geographical locations and therefore not be the optimal values for the TP, which is clearly demonstrated by their large systematic and random errors. Thus we take use of 1-minute clear-sky DLR samples to locally calibrate the parameters of these parametrizations. We use 10-fold cross-validation method to determine the parameters. This is a widely used method to estimate the skill of a regression model on unseen data. It is expected to result in a less biased or less optimistic estimate of the model skill than other methods, such as a simple train/test split (James et al., 2013). All the data was randomly dividing into 10 groups of approximately equal size, the coefficients are computed by using 9 groups as the training set, and the remaining 1 group is used as validation. This procedure is repeated 10 times to get the representational value of coefficients (with the lowest test error). Whether those locally corrected parameters are optimal is determined by the validation that demonstrated that our locally corrected parameterizations were the best.

Gubler, S., Gruber, S., and Purves, R. S.: Uncertainties of parameterized surface downward clear-sky shortwave and cloudy-sky longwave radiation, Atmos. Chem. Phys., 12, 5077-5098, 10.5194/acp-12-5077-2012, 2012.

Minor Comments:

Done, thanks.

(1) Table 4 and table 5 should be combined into one table for easy comparison. Reply:

Table 4. Ordir	Table 4. Ordinary and locally fitted cloudy-sky DLR parameterizations		
Reference	DLR _{cld} Parameterization	Ordinary	Locally Fitted
		Parameters	Parameters
		a=0.7855	a=0.85
Maykut(1973)	$(a + b \times CF^c)\sigma T^4$	b=0.000312	b=0.01
		c=2.75	c=3
Jacobs(1978)	$(1 + a \times CF)DLR_{clr}$	a=0.26	a=0.23
$S_{\rm max}$ (1002)	$(1 + \alpha \times CE^{b})$ DID	a=0.0496	a=0.2
Sugita(1993)	$(1 + a \times CF^b) DLR_{clr}$	b=2.45	b=1.3
<i>V</i> 1 (100.4)	$(1 - CF^a)DLR_{clr} + b \times CF^a \sigma T^4$	a=4	a=3.5
Konzelmann(1994)		b=0.95	b=1

(2) Equation 5 is a very interesting highlight of this paper. In previous studies, it was believed that the cloud base height had a very significant impact on the change of downward long-wave radiation, but most empirical models did not consider the cloud base height due to the lack of observation. However, there are limited introduction and verification for the Equation 5. Therefore, I hope the author can add some graphs and tables to introduce this part in detail.

Reply:

Thanks, we revised this paragraph.

A close relationship between CRE and CBH under overcast conditions over the TP is presented in Fig 6. Compared to Viúdez-Mora (2015) results derived at Girona, Spain, a mid-latitude site with low altitude, CRE over the TP is generally lower by $5\sim10 \text{ W}\cdot\text{m}^{-2}$. This is likely because clouds over the TP with the same CBH as that at Girona have relatively lower temperature, thereby producing lower radiative effect on DLR. CRE generally decreases as CBH increases. The result agrees with the expectation since CBH influence on DLR should decrease as CBH increases as a result of increasing water vapor effects on DLR. CRE is about 70 W·m⁻² for clouds < 1 km and decreases to ~40 W·m⁻² for clouds at 3~4 km in TP. The decreasing rate of CRE with CBH is estimated to be -9.8 W·m⁻²·km⁻¹ over the TP that agrees with model simulations (Viúdez-Mora et al., 2015).

Since CBH effect on overcast DLR is apparent, we introduced a modified parameterization to consider CBH effect on DLR under overcast conditions as follows. The calculated DLR_{ovc} (DLR_{ovc}^{cal}) is equal to DLR_{clr} times 1.23 due to CF of 1 in Eq. 5 that is irrelevant to CBH. On the other hand, the measured DLR_{ovc} (DLR_{ovc}^{obs}) is closely related to CHB as shown in Fig. 6, so we calculated the ratio of DLR_{ovc}^{obs} to the corresponding DLR_{ovc}^{cal} that showed a linear relationship to CBH, as shown in Fig.7. A linearly fitted equation was then established between this ratio and CHB. DLR_{ovc} is finally parameterized as follows.

$$DLR_{ovc} = 1.23 \times DLR_{clr} \times (1.07 - 0.046 \times CBH)$$
 (6)

Where CBH has unit of km. The bias and RMSE of Eq. (6) between measurements and calculations are -2.15 W·m⁻² and 19.79 W·m⁻², respectively, which are substantially lower than that of Eq. (5) (10.3 W·m⁻² and 21.4 W·m⁻²) under overcast conditions. This indicates a remarkable improvement in the estimation of DLR under overcast conditions by introducing CBH to the DLR parameterization, therefore, introduce of such instruments as ceilometer to measure CBH is highly significance for studying

cloud's impacts on DLR.

(3) Fig 3 shows that, compared with Zhu's research results, the two are mainly the difference in intercept, which mainly depends on the calibration of initial value and has no great significance for the study of variabilities of DLR. Reply:

We replied to this concerns in our first round review process, which may be overlooked by the new reviewer.

Difference in the calibration is likely one of potential causes for this systematic difference in clear-sky DLR parameterizations, but we tend to consider potential cloud contamination on the clear-sky DLR samples plays a dominant role in this systematic difference. Cloud contamination of clear-sky DLR samples would be expected if we use naked-eye observations of cloud cover every 1-3 hours (just as Zhu's paper). Human observation represents an instantaneous snapshot of the sky dome that is not likely to represent sky conditions within 1-3 hours since clouds show dramatic temporal variability. More importantly, this systematic overestimation ($25 \text{ W} \cdot \text{m}^{-2}$) is much larger than the expected uncertainty of DLR measurements (2.5% or $4 \text{ W} \cdot \text{m}^{-2}$) (Stoffel, 2005). Furthermore, comparison of cloudy DLR parameterizations between this study and Zhu et al. (2017) showed a good agreement.

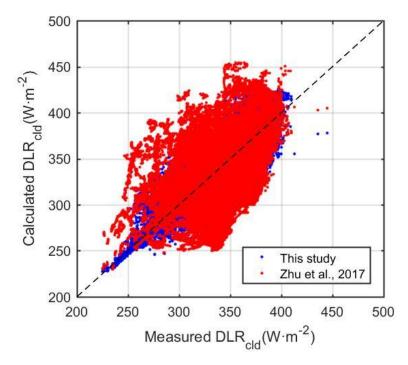


Fig.2 Comparison of our locally corrected cloudy DLR parameterization and that in Zhu et al. (2017) to measured DLR.

Reply to the second reviewer.

1. The manuscript lacks innovation point. Reply:

We respect the reviewer's time and efforts on evaluating our manuscript but we cannot agree with this simple claim without any arguments. We clearly stated our innovation in the last paragraph of section introduction.

This study makes progress in the following aspects as compared to previous studies: 1) clear-sky discrimination and cloud fraction estimation are based on 1-minute DSR and DLR measurements that are objective in nature; 2) misclassification of cloudiness into cloud-free skies would be minimized by adopting strict cloud-screening procedures based on 1-minute DSR, DLR and Lidar measurements; 3) potential effects of CBH on DLR are also investigated. Localized parameterizations of clear-sky and all-sky DLRs are finally achieved, which would be expected to improve DLR estimations over the TP.

2. The calibrated empirical algorithms can not be demonstrated that they also work well at other sites.

Reply: Based on reviewers' comments, we used independent data at Lhasa to validate the parameterizations in the revised manuscript, which clearly shows the best performance of our parameterizations.

3. It is different between the cloud fraction by trained human observers and the radiation-based cloud fraction. They are two different variables.

Reply: We agree with the reviewer's opinion on the difference in cloud fraction derived from human observation and radiation measurements, but frankly speaking, we do not get the key point of this opinion. We argue that human observations seem not suitable for the DLR parameterization under cloudy conditions. The first reason is that the observations are subjective in nature. Second, human observations are made every 1~3 hours that are not enough to capture dramatic variation of sky conditions. Therefore, we use 1-min DSR measurements to deduce sky condition that is then used in the DLR parameterization.

1	A revisit of parametrization of downward longwave radiation in
2	summer over the Tibetan Plateau based on high temporal resolution
3	measurements
4	Mengqi Liu ^{a,c} , Xiangdong Zheng ^d , Jinqiang Zhang ^{a,b,c} and Xiangao Xia ^{a,b,c}
5	^a LAGEO, Institute of Atmospheric Physics, Chinese Academy of Sciences, Beijing,
6	100029, China
7	^b Collaborative Innovation Center on Forecast and Evaluation of Meteorological
8	Disasters, Nanjing University of Information Science & Technology, Nanjing 210044,
9	China
10	^c College of Earth and Planetary Sciences, University of Chinese Academy of Sciences,
11	Beijing, 100049, China
12	^d Chinese Academy of Meteorological Sciences, Chinese Meteorological Bureau,
13	Beijing, 100081, China
14	

Abstract

The Tibetan Plateau (TP) is one of research hot spots in the climate change research 17 due to its unique geographical location and high altitude. Downward longwave 18 19 radiation (DLR), as a key component in the surface energy budget, is of practical implications for radiation budget and climate change. A couple of attempts have been 20 made to parametrize DLR over the TP based on hourly or daily measurements and crude 21 22 clear sky discrimination methods. This study uses 1-minute shortwave and longwave radiation measurements at three stations over TP to parameterize DLR during summer 23 months. Three independent methods are used to discriminate clear sky from clouds 24 based on 1-minute radiation and Lidar measurements. This guarantees strict selection 25 of clear sky samples that is fundamental for the parameterization of clear-sky DLR. 26 Eleven clear-sky and four cloudy DLR parameterizations are examined and locally 27 calibrated. Comparing to previous studies, DLR parameterizations here are shown be 28 characterized by smaller root mean square error (RMSE) and higher coefficient of 29 determination (R^2) . Clear-sky DLR can be estimated from the best parametrization with 30 RMSE of 3.8 W·m⁻² and $R^2 > 0.98$. Systematic overestimation of clear-sky DLR by the 31 locally calibrated parametrization in previous study is found to be approximately 25 W 32 m^{-2} (10%), which is very likely due to potential residual cloud contamination on 33 previous clear-sky DLR parametrization. Cloud-base height under overcast conditions 34 is shown to play an important role in cloudy DLR parameterization, which is considered 35 in the locally calibrated parameterization over the TP for the first time. Further studies 36 on DLR parameterization during nighttime and in seasons except summer are required 37 for our better understanding of DLR's role in climate change based on 1-minute high-38 39 quality DLR measurements.

40

42 1 Introduction

The downward longwave radiation (DLR) at the Earth's surface is the largest 43 component of the surface energy budget, being nearly double the downward shortwave 44 radiation (DSR) (Kiehl and Trenberth, 1997). DLR has shown a remarkable increase 45 during the process of global warming (Stephens et al., 2012). This is closely related to 46 the fact that both a warming and moistening of the atmosphere (especially at the lower 47 atmosphere associated with the water vapor feedback) positively contribute to this 48 49 change. Understanding of complex spatiotemporal variation of DLR and its implication is necessary for improving weather prediction, climate simulation as well as water 50 cycling modeling. Unfortunately, errors in DLR are considered substantially larger than 51 errors in any of the other components of surface energy balance, which is most likely 52 related to the lack of DLR measurements with high quality (Stephens et al., 2012). 53

The 2-sigma uncertainty of DLR measurement by using a well-calibrated and 54 maintained pyrgeometer is estimated to be 2.5% or 4 W·m⁻² (Stoffel, 2005). However, 55 global-wide surface observations are very limited, especially in those remote regions. 56 57 On the other hand, it has been known for almost one century that clear-sky DLR is determined by the bulk emissivity and effective temperature of the overlying 58 atmosphere (Ångström, 1918). Since these two quantities are not easily observed for a 59 vertical column of the atmosphere, clear-sky DLR is widely parameterized as a function 60 of surface air temperature and water vapor density, assuming that the clear sky radiates 61 toward the surface like a grey body at screen-level temperature. Dozens of 62 parameterization formulas of DLR have been developed in which clear-sky effective 63 emissivity (ε_c) is a function of the screen-level temperature (T) and water vapor pressure 64 (e), or simply in the localized coefficients with given functions. Two formulas, i.e., an 65 exponential function (Idso, 1981) and a power law function (Brunt, 1932; Swinbank, 66 1963), have been widely used to depict the relationship of ε_c to T and e. The coefficients 67 of these functions are derived by a regression analysis of collocated measurements of 68 T, e and DLR. Most of these proposed parameterizations are empirical in nature and 69 only specific for definite atmospheric condition. An exception is that Brutsaert (1975) 70 developed a model based on the analytic solution of the Schwarzchild's equation for a 71

72 standard atmospheric lapse rates of T and e. Prata (1996) found that the precipitable water content (w) was much better to represent the effective emissivity of the 73 atmosphere than e, which was loosely based on radiative transfer simulations. Dilley 74 and O'Brien (1998) adopted this scheme but tuned empirically their parameterization 75 using an accurate radiative transfer model. Since DLR is to some extent impacted by 76 water vapor and temperature profile (especially in case of existence of an inversion 77 layer) and diurnal variation of T, a new model with two more coefficients considering 78 79 these effects was developed (Dupont et al., 2008a).

In the presence of clouds, total effective emissivity of the sky is remarkably 80 modulated by clouds. The existing clear-sky parameterization should be modified 81 according to the cloud fraction (CF) and other cloud parameters such as cloud base 82 height (CBH). CF is generally used to represent a fairly simple cloud modification 83 under cloudy conditions. Dozens of equations with cloudiness correction have been 84 developed and evaluated by DLR measurements across the world (Crawford and 85 Duchon, 1999; Niemela et al., 2001). CF can be obtained by trained human observers 86 87 (Iziomon et al., 2003) or derived from DSR (Crawford and Duchon, 1999) and DLR measurements (Durr and Philipona, 2004). High temporal resolution of DSR or DLR 88 measurements (for example, 1-minute) can also provide cloud type information 89 (Duchon and O'Malley, 1999), and thereby allow to consider potential effects of cloud 90 types on DLR (Orsini et al., 2002). 91

With an average altitude exceeding 4 km above the sea level (ASL), the Tibetan 92 93 Plateau (TP) exerts a huge influence on regional and global climate through mechanical and thermal forcing because of its highest and most extensive highland in the world 94 95 (Duan and Wu, 2006). TP, compared to other high altitude regions and the poles, has been relatively more sensitive to climate change. The most rapid warming rate over the 96 TP occurred in the latter half of the 20th century was likely associated with relatively 97 large increase in DLR. Duan and Wu (2006) indicated that increase in low level 98 nocturnal cloud amount and thereby DLR could partly explain the increase in the 99 100 minimum temperature, despite decrease in total cloud amount during the same period. By using observed sensitivity of DLR to change in specific humidity for the Alps, 101

Rangwala et al. (2009) suggested that increase in water vapor appeared to be partly responsible for the large warming over the TP. Since the coefficients of certain empirical parameterizations and their performances showed spatiotemporal variations, establishment of localized DLR parameterizations over the TP is of highly significance. Further studies on DLR, including its spatiotemporal variability, its parameterization as well as its sensitivity to changes in atmospheric variables, would be expected to improve our understanding of climate change over the TP (Wang and Dickinson, 2013).

109 DLR measurements from high quality radiometer with high temporal resolution over the TP are quite scarce. To the best of our knowledge, there are very few 110 publications on DLR and its parameterization over the TP. Wang and Liang (2009) 111 evaluated clear-sky DLR parameterizations of Brunt (1932) and Brutsaert (1975) at 36 112 globally distributed sites, in which DLR data at two TP stations were used. Yang et al. 113 (2012) used hourly DLR data at 6 stations to study major characteristics of DLR and to 114 assess the all-sky parameterization of Crawford and Duchon (1999). Zhu et al. (2017) 115 evaluated 13 clear-sky and 10 all-sky DLR models based on hourly DLR measurements 116 117 at 5 automatic meteorological stations. The Kipp & Zonen CNR1 is composed of CM3 pyranometer and CG3 pyrgeometer that are used to measure DLR and DSR, 118 respectively. The CG3 is the second class radiometer according to the International 119 Organization for Standardization (ISO) classification. The root mean square of hourly 120 DLR is less than 5 Wm⁻² after field recalibration and window heating correction 121 (Michel et al., 2008). Note that human observations of cloud every 3-6 hours or hourly 122 DLR and DSR data are respectively used to determine clear sky and cloud cover in 123 124 these previous studies.

In order to further our understanding of DLR and DSR over the TP, measurements of 1-minute DSR and DLR at 3 stations over the TP using state-of-the-art instruments have been performed in summer months since 2011. These data provide us opportunity to evaluate clear-sky DLR models and quantitatively assess cloud impacts on DLR. This study makes progress in the following aspects as compared to previous studies: 1) clear-sky discrimination and CF estimation are based on 1-minute DSR and DLR measurements that are objective in nature; 2) misclassification of cloudiness into cloud132 free skies would be minimized by adopting strict cloud-screening procedures based on

133 1-minute DSR, DLR and Lidar measurements; 3) potential effects of CBH on DLR are

also investigated. Localized parameterizations of clear-sky and all-sky DLRs are finally

achieved, which would be expected to improve DLR estimations over the TP.

135 136

137 2. Site, Instrument and Data

Measurements of DLR and DSR conducted 1~4 months over the TP at three 138 stations (Table 1), including Nagqu (NQ, 92.04°E, 31.29°N, 4507 m ASL), Nyingchi 139 (NC, 94.2°E, 29.4°N, 2290 m ASL) and Ali (AL, 80°E, 32.5°N, 4287 m ASL) are used 140 for the DLR parameterization. DLR and DSR were respectively measured by CG4 and 141 CM21 radiometers (Kipp & Zonen, Delft, Netherlands). The sampling frequency is 1 142 Hz and the averages of the samples over 1-minute intervals are logged on a Campbell 143 Scientific CR23X datalogger. Simultaneous 1-minute averages of T and e are taken 144 from the automatic meteorological stations. With the aid of its specific material and 145 unique construction, CG4 is designed for the DLR measurement with high reliability 146 147 and accuracy. Window heating due to absorption of solar radiation in the window material, the major error source of DLR measurement, is strongly suppressed by its 148 unique construction conducting away the absorbed heat very effectively. CM21 is a 149 high performance research grade pyranometer. Introduction of individually optimized 150 temperature compensation for CM21 makes it having much a smaller thermal offset 151 than CM3. The installation of the CG4 and CM21 on the Kipp & Zonen CV2 ventilation 152 unit prevents dew deposition on the window of the CG4 and the quartz dome of the 153 CM21. The radiometers are calibrated before and after field measurements to the 154 standards held by the China National Centre for Meteorological Metrology. 155

A Micropulse Lidar (MPL-4B, Sigma Space Corporation, United States) was installed site-by-site with radiometers. The Nd:YLF laser of the MPL produces an output power of 12 μ J at 532 nm. The repletion rate is 2500 Hz. The vertical resolution of the MPL data is 30 m and the integration time of the measurements is 30s. The MPL backscattering profiles are used to identify the cloud boundaries and derive the CBHs (He et al., 2013). The dataset contains about 700 hours of coincident DLR, DSR, Lidar 162 and meteorological measurements.

DLR and DSR were also measured at Lhasa (91.1°E, 29.9°N, 3649 m ASL) during
 summer in 2012 using the same instruments as those in other stations. Lhasa data are
 mainly used for independent validation because of no Lidar data there.

166

167 **3. Methods**

168 **3.1 Clear-sky discrimination**

169 Clear skies should be discriminated from cloudy conditions before performing 170 DLR parametrization, which is achieved by the synthetical analysis of DSR, DLR, and 171 CBH from MPL.

Following the method initiated by Crawford and Duchon (1999), we calculate two quantities reflecting DSR magnitude and variability based on 1-minute observed DSR (DSR_{obs}) and calculated clear-sky DSR (DSR_{cal}) values. DSR_{cal} is calculated by the model C of Iqbal (1983), in which direct and diffuse DSR are parametrized separately. Direct DSR (DSR_{dir}) is calculated as follows.

177

$$DSR_{dir} = S_0 \tau_r \tau_W \tau_o \tau_a \tau_a \tag{1}$$

where τ_r , τ_w , τ_o , τ_a and τ_g are transmittances due to Rayleigh scattering, water 178 vapor absorption, ozone absorption, aerosol extinction and absorption by uniformly 179 mixed gases O₂ and CO₂, respectively. Diffuse radiation is estimated as the sum of 180 Rayleigh and aerosol scattering as well as multiple reflectance. Total ozone column 181 (DU) is provided by Brewer spectrophotometer. w values (cm) are from Vaisala-92 182 radiosonde profiles in AL and Global Position System measurements in NC and NQ, 183 respectively. They are used to create linear regression relationship to collocated ground 184 185 level e (hPa) measurements, which is then used to estimate w from 1-minute measurements of *e*. Ångström wavelength exponent and Ångström turbidity are from 186 CIE-318 sunphotometer observations in NC and AL, while in NQ we adopt the same 187 value as that in AL. Mean single scattering albedo retrieved from CIE-318 observation 188 in Lhasa (91.13, 29.67, 3663m) is 0.90 (Che et al., 2019), which is used in three stations. 189 Surface Albedo is 0.25 and 0.22 in Al and NQ according to in situ measurements (Liang 190 et al., 2012). In NC, it is 0.183 (Zhao et al., 2011). 191

DSR_{cal} values are first scaled to a constant value of 1400 W·m⁻² for each minute of 192 each day. We adopt this value according to Duchon and O'Malley (1998) and Long and 193 Ackerman (2000), which only favors for a clear presentation of the normalized and 194 observed DSR values in the same figure. Afterwards, DSR_{obs} values are scaled by 195 multiplying the same set of scale factors. Finally, the mean and standard deviation of 196 197 the scaled DSR in a 21-minute moving window (±10 minute centered on the time of interest) are used for cloud screening. Selection of the width of 21-minute is empirical 198 199 but a consequence of having a reasonable time span for estimating the mean and variance (Duchon and O'Malley, 1999). Clear-sky DSR should satisfy three 200 requirements: 1) ratio of DSR_{obs} to DSR_{cal} is within 0.95 to 1.05; 2) difference between 201 scaled DSR_{obs} and DSR_{cal} is less than 20 W·m⁻²; and 3) standard deviation (δ) of scaled 202 DSR_{obs} in a 21-minute moving window is less than 20 W·m⁻². 203

Temporal variability of DLR is also used for cloud screening according to Marty and Philipona (2000) and Sutter et al. (2004). Here, δ of scaled DLR (scaled to 500 W·m⁻²) in a 21-minute moving window is used for this purpose. Cloud-free sample is determined if δ is less than 5 W·m⁻².

Since both DSR and DLR experience difficulties in detecting clouds in the portion of the sky far away from the sun (Duchon and O'Malley, 1999) or high-altitude cirrus clouds (Dupont et al., 2008b), coincident MPL backscatter measurements are used to strictly select clear-sky samples. There should be a cloud element somewhere in the sky when MPL identifies cloud, it is thus required that no clouds are detected by MPL in a 21-minute moving window, otherwise it is defined as cloudy.

214 Given the fact that these methods are complementary to each other to some extent (Orsini et al., 2002), we use the following strategy to guarantee a proper selection of 215 clear-sky samples. If DSR, DLR and MPL measurements at the time of interest 216 synchronously satisfy these specified clear-sky conditions, the sample is thought to be 217 taken under unambiguously cloud-free condition; on the contrary, the measurement are 218 made under unambiguously cloudy condition if any method suggests cloudy. Our 219 following clear-sky and cloudy DLR parameterizations are respectively based on 220 measurements under unambiguously cloud-free (8195 minutes) and cloudy conditions 221

222 (69318 minutes).

Fig. 1 shows an example of clear sky discrimination results based on our method. 223 DSR_{obs} presents a smooth temporal variation from sunrise to about 14:00 (LST), being 224 consistent with DSRclr. Similarly, DLR also varies very smoothly during the same 225 period when 21-minute standard deviations of DLR are $< 5 \text{ W} \cdot \text{m}^{-2}$. Both facts suggest 226 sunny and cloudless skies. This inference is supported by MPL that suggests no cloud 227 detected overhead. Contrarily, an abruptly changes of 1-minute DSR_{obs} and DLR are 228 evident during 14:00~17:00 LST and we can see DSR_{obs} occasionally exceeds the 229 expected DSR_{clr}, indicating frequent occurrence of fair weather cumuli clouds. MPL 230 detect a persistent thin cloud layer at 4 km above ground, which agrees with DSR and 231 232 DLR measurements very well.

233

234 **3.2 Cloud fraction estimation**

Given synoptic cloud observations are very limited and temporally sparse, various 235 parameterizations using DSR or DLR data have been developed to estimate CF (e.g., 236 237 Deardorff, 1978; Marty and Philipona, 2000; Durr and Philipona, 2004; Long et al., 2006; Long and Turner, 2008). Because of good agreement between clear-sky DSRobs 238 and DSR_{cal} calculated by the Iqbal C calculations (Iqbal, 1983; Gubler et al., 2012), 239 with mean bias of 1.7 W \cdot m⁻² and root mean square error (RMSE) of 10.7 W \cdot m⁻² (not 240 shown), we use Deardorff (1978)'s method to calculate CF from DSR_{obs} and DSR_{cal}. 241 The method is based on a fairly simple cloud modification to DSR as follows. 242

243

$$CF = 1 - \frac{DSR_{obs}}{DSR_{cal}}$$
(2)

CF (no unit) has values ranging from 0 to 1. To avoid the error caused by abrupt DSR variation, 21-minute mean DSR value rather than its instantaneous measurements are used here.

247

248 **4 Results**

249 4.1 Clear-sky DLR parameterization evaluation and localization

Eleven clear-sky DLR (DLR_{clr}) parameterizations (Table 2) are evaluated based

on 1-minute DLR measurements under unambiguously cloud-free conditions. To 251 compare the performance of these 11 models, RMSE and the coefficient of 252 determination (R^2) are shown by a Taylor diagram in Fig. 2(a). Relatively smaller 253 RMSE (generally < 15 W \cdot m⁻²) and larger R^2 (>0.95) are derived for the Brutsaert (1975); 254 Konzelmann (1994), Dilley and O'Brien (1998) and Prata (1996) models. This is likely 255 because these parameterizations were developed in cool and dry areas, for example, in 256 England (Brutsaert, 1975); in Greenland (Konzelmann, 1994) and dry desert region in 257 Australia (Prata, 1996). The climate in those areas is likely similar to that over the TP 258 to some extent, so those parameterizations are expected to perform well. The higher 259 RMSE (>37 W·m⁻²) and the lower R^2 (~0.7) are derived for Swinbank (1963) and Idso 260 and Jackson (1969) models. This can be partly explained by the fact that only T is used 261 in these two methods. Previous studies suggests substantial uncertainty (RMSE >37.5 262 W·m⁻² and $R^2 < 0.75$) if water vapor effect on DLR_{clr} is not accounted for (Duarte et al., 263 2006). Since w is very low over the TP and thereby DLR is highly sensitive to variation 264 of w in that case, much more attention should be paid to water vapor effect on the 265 266 parameterization of DLR_{clr}.

The coefficients in eleven parameterizations (Table 2) were originally calibrated 267 and determined in different geographical locations; therefore, they may not be the 268 optimal values for the TP. Thus we take use of 1-minute clear-sky DLR samples to 269 locally calibrate the parameters of these parametrizations. We use 10-fold cross-270 validation method to determine the parameters. This is a widely used method to 271 estimate the skill of a regression model on unseen data. It is expected to result in a less 272 biased or less optimistic estimate of the model skill than other methods, such as a simple 273 274 train/test split (James et al., 2013). All the data was randomly dividing into 10 groups of approximately equal size, the coefficients are computed by using 9 groups as training 275 set, and the remaining 1 group is used as validation. This procedure is repeated 10 times 276 to get the representational value of coefficients (with the lowest test error). 277

The coefficient values derived from the non-linear least-squares fitting of the DLR_{clr} parameterizations (Table 2) over the TP are presented in Table 3. For each fitted parameterization, we calculated RMSE and R^2 and the results are shown in Fig. 2b. When using the parameterizations with the locally fitted parameters, the accuracy of the parameterization relative to the published values is obviously improved. Most RMSEs are < 10 W·m⁻² except the parameterization proposed by Swinbank (1963) and Idso and Jackson (1969) that still produce the worst results (with R^2 of 0.71 and RMSE of 15 W·m⁻²) even after the parameters are locally calibrated.

The Dilley and O'Brien (1998)'s parameterization, which is initially developed by 286 considering the adaptation of climatological diversities, is expected to be able to fit the 287 288 measurements in tropical, mid-latitude and Polar Regions. This expectation is verified by its wide deployment in DLR_{clr} estimations in different climate regimes and altitude 289 levels, for example, in the tropical lowland (eastern Pará state, Brazil) and the mild 290 mountain area (Boulder, the United States) (Marthews et al., 2012; Li et al., 2017). 291 292 The present study confirms that Dilley and O'Brien (1998) is the best clear-sky parameterization over the TP. The locally calibrated equation is as follows. 293

$$DLR_{clr} = -2.53 + 158.10 \times \left(\frac{T}{273.16}\right)^6 + 106.40 \times \left(\frac{46.50 \times \frac{e}{T}}{2.50}\right)^{\frac{1}{2}}$$
(3)

295 Where T and e represent air temperature (K) and water vapor pressure (hPa), respectively (T and e have the same meaning and unit in following equations if not 296 specified). The RMSE and R^2 of Eq.(3) are ~3.8 W · m⁻² and > 0.98 respectively, which 297 are substantially lower than those in previous studies over the TP, for example, the 298 RMSE was 9.5 W·m⁻² (Zhu et al., 2017). The Dilley and O'Brien (1998)'s 299 parameterization was suggested to be the most reliable estimates of DLR_{clr} over the TP 300 (Zhu et al., 2017). Note that the parameters here differ quite a lot from their values (Zhu 301 et al., 2017), as shown in Eq. (4). 302

303
$$DLR_{clr} = 30.00 + 157.00 \times \left(\frac{T}{273.16}\right)^6 + 97.93 \times \left(\frac{46.50 \times \frac{e}{T}}{2.50}\right)^{\frac{1}{2}}$$
 (4)

Fig.3 compares instantaneous clear-sky DLR data from measurements against calculations by Eq. (3) of this study and by Eq. (4) from Zhu et al. (2017). The former performs very well as shown by an overwhelmingly large number of data points falling along or overlapping the 1:1 line. By contrast, the latter overestimates DLR by 25 W·m⁻ (10%). This difference is not very likely due to different DLR measurements used to produce Eq. (3) and (4) giving the following considerations. First, this systematic

overestimation is much larger than the expected uncertainty of DLR measurements (2.5% 310 or 4 W·m⁻²) (Stoffel, 2005). More important, comparison of cloudy DLR 311 parameterizations between this study and Zhu et al. (2017) showed good agreement 312 (not shown). Note that only 1-hour CG3 DLR observations are used for clear sky 313 discrimination in Zhu et al. (2017). This method was shown to be very likely 314 contaminated by the thin high cloud (Sutter et al., 2004). This certainly would produce 315 an overestimation of clear sky DLR parameterization since larger DLRs are associated 316 with potential residual clouds relative to real clear-sky DLRs. 317

318

319 4.2 Parameterization of cloudy-sky DLR

Parameterizations of cloudy-sky DLR (DLR_{cld}) are based on estimated DLR_{clr} coupled with the effect of cloudiness or cloud emissivity, which depends primarily on CF as well as other cloud parameters, like CBH and cloud type (Arking, 1990; Viúdez-Mora et al., 2015). Four parameterizations (Table 4), which modifies the bulk emissivity depending on CF, are assessed and locally calibrated in this section.

DLR_{clr} is estimated according to Eq. (3). The fitted values of the coefficients (using 10-Fold Cross-Validation) of the four cloudy parameterizations are presented in Table 4. RMSE and R^2 of original and locally fitted parameterizations over the TP are presented in Fig. 4.

Relative to clear-sky conditions, cloudy parameterizations using the given parameters have higher error RMSE (generally exceeding 35 W·m⁻²) except that developed by Jacobs (1978) (RMSE of 18 W·m⁻²). R^2 was generally smaller than 0.9. RMSE values decrease significantly in Maykut and Church (1973) and Sugita and Brutsaert (1993) as locally calibrated parameters are used. Relative smaller and almost no RMSE improvements are found for the methods developed by Konzelmann (1994) and Jacobs (1978).

Eq. (5) shows the best cloudy-sky parameterization over the TP by combining the clear-sky parameterization of Dilley and O'Brien (1998) with the cloud modulation correction scheme of Jacobs (1978).

339
$$DLR_{cld} = (1 + 0.23 \times CF) \times (59.38 + 113.70 \times \left(\frac{T}{273.16}\right)^6 + 96.96 \times \left(\frac{46.50 \times \frac{e}{T}}{2.50}\right)^{\frac{1}{2}})$$
 (5)

RMSE and R^2 are ~18 W·m⁻² and ~0.89 respectively. RMSE here is close to 15 W·m⁻² obtained in different altitude areas in Swiss (Gubler et al., 2012) and slightly lower than 23 W·m⁻² obtained in mountain area in Germany (Iziomon et al., 2003). Comparing to previous studies over the TP (RMSE of 22 W m⁻² in Zhu et al., 2017), our cloudy model produces better results.

In order to validate the newly developed DLR parameterizations, clear-sky and cloudy-sky DLR parameterizations are validated against DLR measurements at Lhasa. The results are shown in Fig. 5. Compared to the existed parameterizations, the Eq.(3) and Eq.(5) produce the smallest bias (both less than 2 W·m⁻²) and RMSE (Eq.(3)'s is less than 5 W·m⁻² and Eq.(5)'s is less than 25 W·m⁻²). This independently demonstrates the improved DLR parameterizations can be used in other stations over the TP.

351

352 4.3 Effect of CBH on DLR under Overcast Conditions

353 Since clouds behave approximately as a blackbody, the most relevant cloud parameter (besides CF) to DLR under overcast skies (DLR_{ovc}) is CBH (Kato et al, 2011; 354 Viúdez-Mora et al., 2015): firstly, CBH defines the temperature of the lowest cloud 355 boundary, which through the Stefan-Boltzmann law drives the cloud emittance; 356 secondly, DLR emitted by the atmospheric layers above a cloud is totally absorbed by 357 the cloud itself (clouds are thick enough). Radiative transfer model simulation has 358 suggested that CBH under overcast conditions is an important modulator for DLR. The 359 cloud radiation effect (CRE), the difference between DLRobs and DLRclr, decreases with 360 increasing CBH at a rate of 4~12 W·m⁻² that depends on climate profiles (Viúdez-Mora 361 et al., 2015). This indicates that overcast DLR parameterization would be improved if 362 CBH is considered. 363

A close relationship between CRE and CBH under overcast conditions over the TP is presented in Fig 6. Compared to Viúdez-Mora (2015) results derived at Girona, Spain, a mid-latitude site with low altitude, CRE over the TP is generally lower by $5\sim10 \text{ W}\cdot\text{m}^{-2}$. This is likely because clouds over the TP with the same CBH as that at Girona have relatively lower temperature, thereby producing lower radiative effect on DLR. CRE generally decreases as CBH increases. The result agrees with the expectation since CBH influence on DLR should decrease as CBH increases as a result of increasing water vapor effects on DLR. CRE is about 70 W·m⁻² for clouds < 1 km and decreases to ~40 W·m⁻² for clouds at 3~4 km in TP. The decreasing rate of CRE with CBH is estimated to be -9.8 W·m⁻²·km⁻¹ over the TP that agrees with model simulations (Viúdez-Mora et al., 2015).

Since CBH effect on overcast DLR is apparent, we introduced a modified 375 parameterization to consider CBH effect on DLR under overcast conditions as follows. 376 The calculated DLR_{ovc} (DLR^{cal}_{ovc}) is equal to DLR_{clr} times 1.23 due to CF of 1 in Eq. 5 377 that is irrelevant to CBH. On the other hand, the measured DLR_{ovc} (DLR_{ovc}^{obs}) is closely 378 related to CHB as shown in Fig. 6, so we calculated the ratio of DLR^{obs}_{ovc} to the 379 corresponding DLR^{cal}_{ovc} that showed a linear relationship to CBH, as shown in Fig.7. A 380 linearly fitted equation was then established between this ratio and CHB. DLR_{ovc} is 381 finally parameterized as follows. 382

383
$$DLR_{ovc} = 1.23 \times DLR_{clr} \times (1.07 - 0.046 \times CBH)$$
 (6)

Where CBH has unit of km. The bias and RMSE of Eq. (6) between measurements and calculations are $-2.15 \text{ W} \cdot \text{m}^{-2}$ and $19.79 \text{ W} \cdot \text{m}^{-2}$, respectively, which are substantially lower than that of Eq. (5) (10.3 W $\cdot \text{m}^{-2}$ and 21.4 W $\cdot \text{m}^{-2}$) under overcast conditions. This indicates a remarkable improvement in the estimation of DLR under overcast conditions by introducing CBH to the DLR parameterization, therefore, introduce of such instruments as ceilometer to measure CBH is highly significance for studying cloud's impacts on DLR.

391

392 5 Discussion and conclusions

The parameterization of clear-sky DLR requires a well-defined distinction between clear-sky and cloudy-sky situations that commonly depends on human cloud observations 4~6 times each day. Human observation is subjective in nature and its low temporal resolution cannot resolve dramatic high-resolution variation of clouds.

Furthermore, synoptic human cloud observations show the tendency to stronger weight 397 to the horizon that DLR is not highly sensitive (Marty and Philipona, 2004). Clear sky 398 discrimination based on hourly DSR or DLR measurements also tends to be very 399 suspect of residual clouds due to their low temporal resolution. Parameterization of 400 clear-sky DLR based on these two methods is hence very likely biased as a consequence 401 of selection of cloud contaminated clear-sky measurements. This would result in biased 402 estimation of cloud DLR effect since it is the difference between clear-sky and 403 404 measured all-sky DLRs (Dupont et al., 2008b).

Using 1-minute DSR and DLR at 3 stations over the TP, DLR parameterizations are evaluated and localized parameterizations have been developed based on a comprehensive cloud-screening method. We test the fitted parameterizations based on independent DLR measurements at Lhasa. Potential CBH effect on overcast DLR is experimentally determined. Major conclusions are as follows.

Among 11 clear-sky DLR parameterizations tested in this study, two methods using only atmospheric temperature largely deviate from other parameterizations. The best method suitable for TP is the parameterization developed by Dilley and O'Brien (1998). DLR estimation can be improved by localization of these parameterizations. Locally calibrated parameterization can produce clear sky DLR with RMSE of 3.8 W·m⁻².

416 Overcast DLR is highly sensitive to CBH. The parameterization can be 417 substantially improved by consideration of CBH effect. The bias between empirically 418 parameterized calculations and measurements decreases from 10.3 to 1.3 $W \cdot m^{-2}$.

The focus of this study is on daytime DLR parameterization over the TP since DSR 419 is used in the cloud-screening method. Given a significant role of DLR played in the 420 421 surface energy budget during nighttime, it is highly desirable to perform further study on the nighttime DLR parametrization. These results are based on summer DLR 422 measurements, so the conclusions here need to be further tested in other seasons, 423 especially in winter when an increasing tendency of DLR has been observed (Rangwala 424 et al., 2009). Further investigations on these issues are expected to shed new light on 425 how and why DLR has changed over the TP. Our results clearly showed substantial 426

427 CBH effect on overcast DLR, which would be considered in future when ceilometer is428 widely used to measure CBH.

429

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			Tibetan P	lateau		
Site	Altitude	Period	<i>T</i> (°C)	e (hPa)	DLR	Data Points
	(mASL)				(W⋅m ⁻²)	
NQ	4507	2011.7.20-	9.4±8	7.4±5	242.75 ± 40	52980
		2011.8.26				
NC	2290	2014.6.7-	16.8 ± 10	13.4±4	368.25 ± 40	69609
		2014.7.31				
AL	4279	2016.5.27-	7.8±4	4.8±4	253.11 ± 50	86596
		2016.9.22				

Table 1: Description of stations and measurements (magnitude and variability) in the

Table 2. 11 clear-sky DLR parameterizations and their specific conditions

Reference	Clear-Sky Parameterization	Conditions
Angstrom (1915)	$\text{DLR}_{clr} = \{0.83 - 0.18 \times 10^{-0.067e})\}\sigma T^4$	Alt.: 1650~3500 T: 283.15~303.15
		<i>e</i> : 4~1
Brunt (1932)	$\text{DLR}_{clr} = (0.52 + 0.065\sqrt{e})\sigma T^4$	Alt.: 6~3500
		<i>T</i> : 269.15~303.15
		<i>e</i> : 2.5~16
Swinbank (1963)	$DLR_{clr} = 5.31 \times 10^{-13} T^6$	Alt: 2
		<i>T</i> : 281.15~302.15
		<i>e</i> : 8~30
Idso and Jackson	$DLR_{clr} = (1 - 0.261)$	Alt.: 3, 331
(1969)	$\cdot \exp(-0.000777)$	<i>T</i> : 228.15~318.15
	$(273 - T)^2)\sigma T^4$	
Brutsaert (1975)	$(e)^{\frac{1}{7}}$	Alt.: 6~3500
	$\mathrm{DLR}_{clr} = 1.24 \left(\frac{e}{T}\right)^{\frac{1}{7}} \sigma T^4$	<i>T</i> : 269.15~313.15
	-	<i>e</i> : 2.5~-16
Satterlund (1979)	$\mathrm{DLR}_{clr} = 1.08 \left(1 - \exp\left(-e^{\frac{T}{2016}}\right) \right) \sigma T^4$	Alt.: 594
		<i>T</i> : 236.15~309.15
		<i>e</i> : 0~18hPa
Idso (1981)	981) $DLR_{clr} = (0.7 + 5.95 \times 10^{-5} \times e$	Alt.: 331
		<i>T</i> : 258.15~278.15
	$\times \exp\left(\frac{1500}{T}\right) \sigma T^4$	<i>e</i> : 2~6
Konzelmann	/ 1\	Alt.: 340~3230
(1994)	$\mathrm{DLR}_{clr} = \left(0.23 + 0.443 \left(\frac{e}{T}\right)^{\frac{1}{8}}\right) \sigma T^4$	<i>T</i> : 257.15~279.15
		<i>e</i> : 1.5~5.5
Prata (1996)	$DLR_{clr} = (1 - (1 + 46.5\frac{e}{T}) \times exp(-(1.2 + 3 \times 46.5)))$	Not specified
	$(\frac{e}{T})^{0.5})) \sigma T^4$	
Dilley and O'Brien (1998)	$\text{DLR}_{clr} = 59.38 + 113.7 \left(\frac{T}{273.16}\right)^6 +$	Not specified
	$96.96\sqrt{46.5\frac{e}{T}/2.5}$	
Iziomon (2001)	(1 0.42 (11.5e)) = 4	Alt.: 1489
	$\mathrm{DLR}_{clr} = \left(1 - 0.43 \exp\left(-\frac{11.5e}{T}\right)\right) \sigma T^4$	\bar{T} =277.55 \bar{e} =7.4

*Where Alt. is the altitude above sea level, and its unit is (m ASL), e is screen-level water vapor pressure in hPa and T represents surface temperature in K

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Reference	Locally fitted Clear-Sky Parameterization	
Angstrom(1915)	$\text{DLR}_{clr} = \{0.8 - 0.19 \times 10^{-0.068e})\}\sigma T^4$	
Brunt(1932)	$\mathrm{DLR}_{clr} = (0.56 + 0.07\sqrt{e})\sigma T^4$	
Swinbank(1963)	$DLR_{clr} = 4.7 \times 10^{-13} T^6$	
Idso & Jackson(1969)	$\text{DLR}_{clr} = (1 - 0.36 \cdot \exp(-0.00065 \times (273 - T)^2))\sigma T^4$	
Brutsaert(1975)	$\mathrm{DLR}_{clr} = 1.03 \left(\frac{e}{T}\right)^{0.09} \sigma T^4$	
Satterlun (1979)	$\mathrm{DLR}_{clr} = \left(1 - \exp\left(-e^{\frac{T}{2016}}\right)\right)\sigma T^4$	
Idso(1981)	$\text{DLR}_{clr} = \left(0.63 + 7.5 \times 10^{-5} \times e \times \exp\left(\frac{1500}{T}\right)\right) \sigma T^4$	
Konzelmann(1994)	$\mathrm{DLR}_{clr} = \left(0.23 + 0.45 \left(\frac{e}{T}\right)^{0.13}\right) \sigma T^4$	
Prata(1996)	$\text{DLR}_{clr} = (1 - (1 + 46.5\frac{e}{T}) \times \exp(-(1 + 3 \times 46.5\frac{e}{T})^{0.5})) \sigma T^4$	
Dilley and O'Brien(1998)	$\text{DLR}_{clr} = -2.54 + 158.1 \left(\frac{T}{273.16}\right)^6 + 106.4 \sqrt{46.5 \frac{e}{T}/2.5}$	
Iziomon(2001)	$\text{DLR}_{clr} = \left(1 - 0.38 \exp\left(-\frac{14.52e}{T}\right)\right) \sigma T^4$	

Reference	Cloudy-Sky	Cloudy-Sky Parameterization		
Maykut and Church	$\frac{1973}{\text{DLR}_{cld}} = (0.7855 -$	$DLR_{ctd} = (0.7855 + 0.000312 \times CF^{2.75})\sigma T^4$		
Jacobs, 1978	$\frac{\text{DLR}_{cld}}{\text{cld}} = (1 - 1)$	$\frac{\text{DLR}_{cld}}{\text{cld}} = (1 + 0.26 \times \text{CF}) \text{DLR}_{clf}$		
Sugita and Brutsaert	, 1993 DLR _{cld} = (1 + 0.	$DLR_{cld} = (1 + 0.0496 \times CF^{2.45}) DLR_{clr}$		
Konzelmann, 1994	$DLR_{cla} = (1 - CF^4)$) DLR _{ctr} + 0.9	54CF⁴σT⁴	
Table 4. 4 Ord	inary and locally fitted cloudy-sky	y DLR paramet	terizations	
Reference		Ordinary	Locally Fitte	
	DLR _{cld} Parameterization	Parameters	Parameters	
Maykut(1973)		a=0.7855	a=0.85	
	$(a + b \times CF^c)\sigma T^4$	b=0.000312	b=0.01	
		c=2.75	c=3	
Jacobs(1978)	$(1 + a \times CF)DLR_{clr}$	a=0.26	a=0.23	
Sugita(1993)		a=0.0496	a=0.2	
	$(1 + a \times CF^b) DLR_{clr}$	b=2.45	b=1.3	
<i>V</i> and a linear (1004)	(1 OP(1) P (1 OP(1) P)	a=4	a=3.5	
Konzelmann(1994)	$(1 - CF^a)DLR_{clr} + b \times CF^a \sigma T^4$	b=0.95	b=1	

Reference	Locally fitted Cloudy-Sky Parameterization
Maykut and Church, 1973	$DLR_{eta} = (0.85 + 0.01 \times CF^3)\sigma T^4$
Jacobs, 1978	$DLR_{cld} = (1 + 0.23 \times CF)DLR_{clr}$
Sugita and Brutsaert,1993	$\frac{\text{DLR}_{cld}}{\text{CLR}} = (1 + 0.2 \times \text{CF}^{1.3}) \text{DLR}_{clr}$
Konzelmann, 1994	$\overline{\text{DLR}_{eld}} = (1 - CF^{3.5})\overline{\text{DLR}_{elr}} + CF^{3.5}\sigma T$

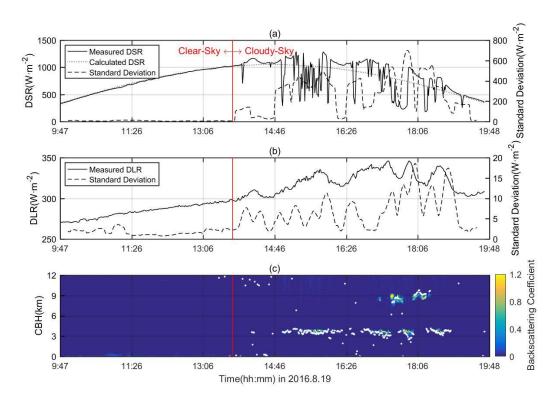
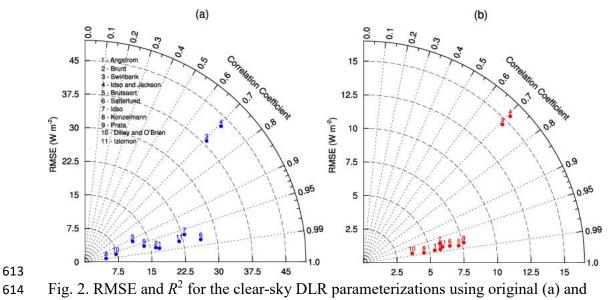


Fig. 1. Time series of data sample on 2016.8.19 transited from clear-sky to cloudy-sky: (a)
measured (black line) and calculated (dotted black line) downward shortwave radiation and its 21min standard deviation (grey line), (b) measured downward longwave radiation and 21-min standard
deviation and (c) MPL backscattering coefficient and the cloud base height.



615 locally calibrated (b) coefficients.

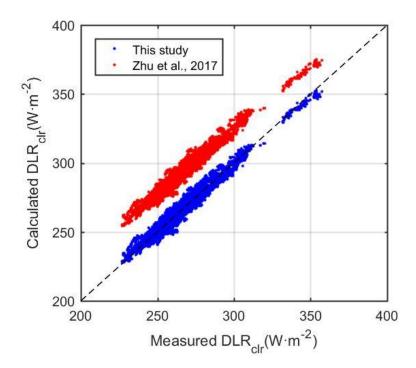




Fig. 3. Scatter plots of measured clear-sky DLR data from as a function of calculations

by the Eq.(3) this study (blue dots) and the Eq.(4) by Zhu et al. (2017) (red dots). Thedash black line is the 1:1 line.

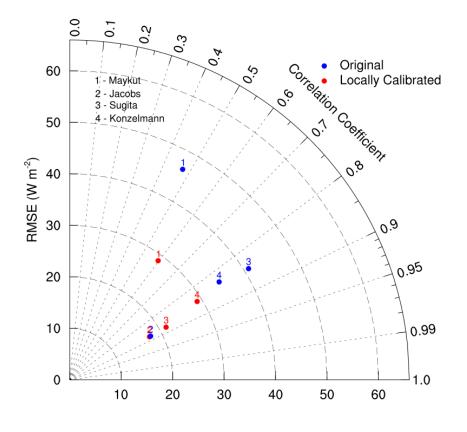


Fig. 4. RMSE and R^2 for the cloudy-sky DLR (DLR_{cld}) parameterizations using the original (blue) and locally calibrated (red) coefficient.

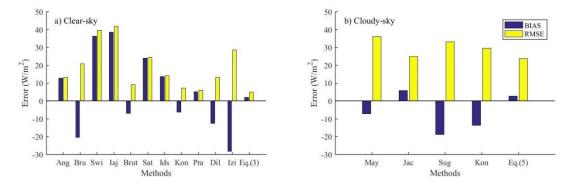


Fig. 5. BIAS and RMSE for the LDR parameterizations using (a) the published clear-sky and Eq.(3), and (b) cloudy-sky parameterizations and Eq.(5).

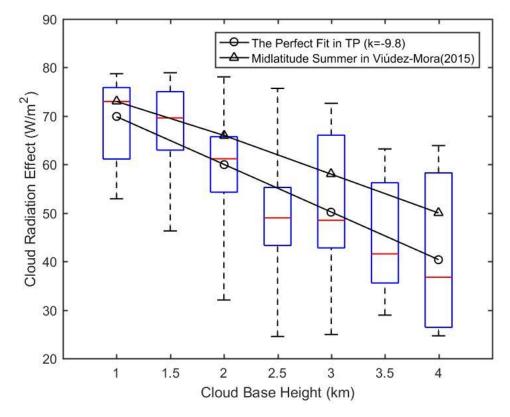


Fig. 6. Distributions of cloud radiative effect against measured cloud base height are
represented by box plot (the blue box indicates the 25th and 75th percentiles, the
whiskers indicate 5th and 95th percentiles, the red middle line is the median). The black
circles line and the black triangles is mean values of cloud radiative effect over TP in
this study and in midlatitude site (Girona, Spain) in Viúdez-Mora(2015) respectively.

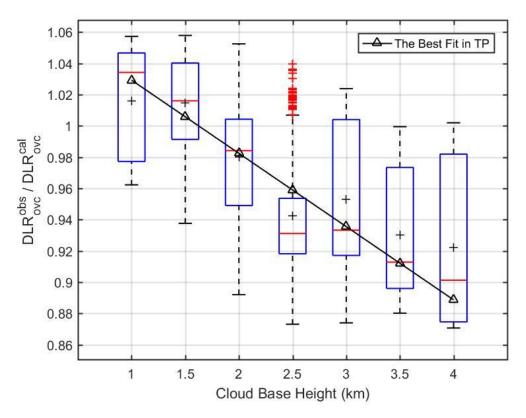


Fig. 7. Distributions of the ratio of observed DLR and calculated DLR by Eq.(5) under
overcast condition against measured cloud base height are represented by box plot (the
blue box indicates the 25th and 75th percentiles, the whiskers indicate 5th and 95th
percentiles, the red middle line is the median, the black plus sign is the mean). The
black triangle line is the fitting line.