

# Technical note: Effects of Uncertainties and Number of Data points on Line Fitting - a Case Study on New Particle Formation

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10 **Abstract.** Fitting a line on a scatterplot of two measured variables is considered as one of the simplest statistical procedures researchers can do. However, this simplicity is deceptive as the line fitting procedure is actually quite a complex problem. Atmospheric measurement data never comes without some measurement error. Too often, these errors are neglected when researchers are making inferences from their data.

To demonstrate the problem, we simulated datasets with different amounts of data and error, mimicking the dependence of  
15 atmospheric new particle formation rate ( $J_{1.7}$ ) on sulphuric acid concentration ( $H_2SO_4$ ). Both variables have substantial measurement error and thus they are good test variables for our study. We show that ordinary least squares (OLS) regression results in strongly biased slope values compared with six error-in-variables (EIV) regression methods (Deming, Principal component analysis, orthogonal, Bayesian EIV, and two different bivariate regression methods) known to take into account errors in the variables.

## 20 1 Introduction

Atmospheric measurement data never come without some measurement error. Too often, these errors are neglected when researchers are making inferences based on their data. Describing the relationship between two variables typically involves making deductions in some more general context than was directly studied. If the relationship is ill formulated, the inference is not valid either. In some cases, the bias in analysis method is even given a physical meaning.

25 When analysing dependencies of two or more measured variables, regression models are usually applied. A regression model can be linear or nonlinear, depending on the data. Standard regression models assume that the independent variables of the models have been measured without error and the models account only for errors in the dependent variables or responses. In cases where the measurements of the predictors contain error, estimating with standard methods, usually Ordinary Least Squares (OLS), do not tend to the true parameter values, not even asymptotically. In linear models, the coefficients are  
30 underestimated (e.g. Carroll et al., 2006) but in nonlinear models, the bias is likely to be more complicated (e.g. Schennach

2004). Measurement error needs to be taken into account, particularly when errors are large. Thus, we chose such parameters as our test variables in this study. Sulphuric acid ( $H_2SO_4$ ) is known to strongly affect the formation rates ( $J$ ) of aerosol particles (Kirkby et al., 2016; Kuang et al., 2008; Kulmala et al., 2006; Kürten et al., 2016; Metzger et al., 2010; Riccobono et al., 2014; Riipinen et al., 2007; Sihto et al., 2006; Spracklen et al., 2006). The relationship between  $J$  and  $H_2SO_4$  is typically as assumed to be in form  $\log_{10}(J) = \beta \cdot \log_{10}(H_2SO_4) + \alpha$  (Seinfeld and Pandis, 2016). In addition, parameterizations based on the results from these fits have been implemented in global models, e.g. in (Dunne et al., 2016; Metzger et al., 2010; Spracklen et al., 2006), to estimate the effect of new particle formation on global aerosol amounts and characteristics. Theoretically in homogeneous nucleation, the slope of this relationship is related to the number of sulphuric acid molecules in the nucleating critical cluster, based on the first nucleation theorem (Vehkamäki, 2006).

Some published results have shown discrepancies in the expected  $J$  vs  $H_2SO_4$  dependence. Analysing data from Hyytiälä in 2003, Kuang et al. (2008) used an unconstrained least squares method and obtained  $\beta=1.99$  for the slope, whereas Sihto et al. (2006) reported a value of  $\beta=1.16$  using OLS from the same field campaign. They had some differences in pre-treatment of data and used different time windows, but a significant proportion of this inconsistency is very likely due to different methods for making the fit. The problem in the relationship of  $H_2SO_4$  and  $J$  has been acknowledged already in Paasonen et al. (2010) who noted that bivariate fitting method as presented in York et al. (2004) should be applied but could not be used due to the lack of proper error estimates for each quantity. They were not aware of the methods that do not need to know the errors in advance, but instead made use of estimated variances. Here, we present appropriate tools for using that approach.

Multiple attempts have been made to present methods accounting for errors in predictor variables for regression-type analysis, going back to Deming (1943). However, the traditional least squares fitting still holds the position as the de facto line fitting method due to its simplicity and common availability in frequently used software. In atmospheric sciences, Cantrell (2008) drew attention to the method introduced by York (1966) and York et al. (2004) and listed multiple other methodological papers utilizing similar methodology. Pitkänen et al. (2016) raised the awareness of the problem in remote sensing community and this study partly follows their approach and introduces multiple methods to take account the errors in predictors. Cheng and Riu (2006) studied methods with heteroscedastic errors whereas Wu and Yu (2018) approached the problem with measurement errors via weighted regression and applied some techniques also used in our study.

Measurement errors in each variable must be taken into account using approaches called errors-in-variables (EIV) regression. In this study, we compared OLS regression results to six different regression methods (Deming regression, Principal component analysis regression, orthogonal regression, Bayesian EIV regression and two different bivariate regression methods) known to be able to take into account errors in variables and provide (at least asymptotically) unbiased estimates. In this study, we will focus only on linear EIV methods but it is important to acknowledge that there also exist nonlinear methods e.g. ORDPACK introduced in Boggs, Byrd, and Schnabel (1987) and implemented in Python SciPy and R (Boggs et al., 1989; Spiess, 2015). ORDPACK is a somewhat improved version of orthogonal regression, so that arbitrary covariance structures are acceptable and is specifically set up so that a user can specify measurement error variances and covariance point by point.

## 2 Materials and Methods

### 2.1 Data illustrating the phenomenon

Measurement data contains different types of errors. Usually, the errors are divided to two main class: random and systematic error. Systematic errors, commonly referred as bias, in experimental observations usually come from the measuring instruments. They may occur because there is something wrong with the instrument or its data handling system, or because the instrument is not used correctly by the operator. In line fitting, bias cannot be taken account but the random error may have different components, of which two are discussed here: natural error and measurement error. In addition, one should note the existence of equation error, discussed in Carroll and Ruppert (1996), which refers to using an inappropriate form of a fitting equation. Measurement error is more generally understood, it is where measured values do not fully represent the true values of variable being measured. This also contains sampling error, e.g. in the case of  $\text{H}_2\text{SO}_4$  measurement the sampled air in the measurement instrument is not representative sample of outside air (e.g. due to losses of  $\text{H}_2\text{SO}_4$  occurring in the sampling lines). Natural error is that the true connection between the two variables is has stochastic variation by some natural or physical cause e.g. certain amount of  $\text{H}_2\text{SO}_4$  does not cause same number of new particles formed. In the analysis of measurement data, some amount of these errors are known or can be estimated, but some of it will usually remain unknown, which should be kept in mind when interpreting data. Even though the measurement error is taken into account, the regression fit may be biased due to unknown natural error. In this study, we assume that the errors of the different variables are uncorrelated, but in some cases it has to be taken into account, as noted e.g. in Trefall and Nordö (1959) and Mandel (1984). The correlation between the errors of two variables, measured with separate instruments, independent on each other, like formation rate and  $\text{H}_2\text{SO}_4$ , may come e.g. from environmental variables affecting both of them at the same time. Factors affecting formation of sulphuric acid have been studied in various papers, e.g. in Weber et al. (1997) and Mikkonen et al. (2011). New particle formation rates, in turn, have been studied e.g. in Boy et al. (2008) and in Hamed et al. (2011) and similarities between affecting factors can be seen. In addition, factors like room temperature in measurement space and atmospheric pressure may affect to measurement instruments, thus causing additional error.

The data used in this study consist of simulated new particle formation rates at 1.7 nanometre size ( $J_{1.7}$ ) and sulphuric acid ( $\text{H}_2\text{SO}_4$ ) concentrations mimicking observations of pure sulphuric acid in nucleation experiments from the CLOUD chamber in CERN (Kürten et al. 2016; <https://home.cern/about/experiments/cloud>) with corresponding expected values, their variances and covariance structures. The chamber data at CERN are the best characterized and controlled set of new particle formation (NPF) experiments in the history of aerosol science so far. The Proton Synchrotron provides an artificial source of “cosmic rays” that simulates natural conditions of ionization between ground level and the stratosphere. The core is a large (volume 26m<sup>3</sup>) electro-polished stainless steel chamber with temperature control (temperature stability better than 0.1 K) at any tropospheric temperature, precise delivery of selected gases ( $\text{SO}_2$ ,  $\text{O}_3$ ,  $\text{NH}_3$ , various organic compounds) and ultrapure

humidified synthetic air, and very low gas-phase contaminant levels. Existing data include the most suspected candidates for atmospheric NPF, including sulphuric acid – ammonia – water (Kirkby et al., 2011), sulphuric acid – amine (Almeida et al., 2013) and ion induced organic nucleation (Kirkby et al., 2016). The actual nucleation of new particles occurs at slightly smaller size. After formation, they grow by condensation to reach the detection limit (1.7 nm) of the instrument and  $J_{1.7}$  thus refers to the formation rate of particles as the instrument detects them, taking into account the known particle losses due to coagulation and deposition on the chamber walls. These variables were chosen because they are both known to have considerable measurement errors and their relationship is studied frequently using regression-based analyses (Kirkby et al., 2016; Kürten et al., 2016; Riccobono et al., 2014; Tröstl et al., 2016) which makes them good illustrative variables for this study. Additionally, many of the published papers on this topic do not describe how they are taking account the uncertainties in the analysis, which leaves a doubt that they are not treated properly. However, it should be kept in mind that the data could be any set of numbers assumed to have linear relationship but to raise the awareness in the research community we related the simulations to well-known datatype.

## 2.2 Regression methods

We made fits for the linear dependency of logarithms of the two study variables, such that the equation for the fit was given by

$$\mathbf{y} = \boldsymbol{\beta}_0 + \boldsymbol{\beta}_1 \mathbf{x} + \boldsymbol{\varepsilon} \quad (1)$$

where  $y$  represents  $\log_{10}(J_{1.7})$ ,  $x$  is  $\log_{10}(H_2SO_4)$ ,  $\beta$ 's are the coefficients estimated from the data and  $\varepsilon$  is the error term. In order to demonstrate the importance of taking into account the measurement errors in the regression analysis, we tested seven different line-fitting methods. Ordinary Least Squares (OLS), not taking account the uncertainty in  $x$ -variable, and orthogonal regression (ODR, Boggs, Byrd, and Schnabel 1987), Deming regression (DR, Deming, 1943), Principal component analysis (PCA, Hotelling, 1957) regression, Bayesian EIV regression (Kaipio and Somersalo, 2005) and two different bivariate least squares methods by York *et al.*, (2004), and Francq and Govaerts (BLS, 2014), known to be able to take account errors in variables and provide (at least asymptotically) unbiased estimates. The differences between the methods come from the criterion they minimize when calculating the coefficients and how they take account the measurement errors. The minimizing criteria for all methods are given in the supplement S1 but we give here the principles of the methods. OLS minimizes the squared distance of the observation and the fit line either in  $y$  or  $x$  direction, but not both at the same time, whereas ODR minimizes the sum of squared weighted orthogonal distances between each point and the line. DR was originally an improved version of orthogonal regression, taking account the ratio of the error variances  $\lambda_{xy}$  of the variables, (in classical non-weighted ODR  $\lambda_{xy} = 1$ ) and it is the maximum likelihood estimate (MLE) for the model (1) when  $\lambda_{xy}$  is known. Idea of PCA is the same as in ODR but the estimation procedure is somewhat different as can be seen in S1. The bivariate algorithm by York et al 2004 provides a simple set of equations for iterating MLE of slope and intercept with weighted variables, which makes it similar to ODR in this case. However, ODR can consider linear scale uncertainties in logarithmic scale regression, unlike the York (2004) solution. In Bayes EIV, statistical models for the uncertainties in observed quantities are used and probability distributions for

the line slope and intercept are computed according to the Bayes' theorem. In this study, we computed Bayesian maximum a posteriori (MAP) estimates for the slope and intercept values. BLS takes into account errors and heteroscedasticity in both axes and thus is more advanced method than DR (under normality and homoscedasticity, BLS is exactly equivalent to DR). PCA accounts only for the measurement variance, whereas ODR, Bayes EIV and York bivariate regression require known estimates for measurement errors. Thought for Bayes EIV the error can be approximated with a distribution. DR and BLS can be applied with both, errors given by the user and measurement variance based errors. In this study, we applied measurement variance based errors for them. The analysis for OLS and PCA were calculated with R-functions “lm” and “prcomp”, respectively (R Core Team, 2018) DR was calculated with package deming (Therneau, 2018) and BLS with package BivRegBLS (Francq and Berger, 2017) in R. The ODR based estimates were obtained using scipy.odr python package (Jones et al., 2001), while the python package pystan (Stan Development Team, 2018) was used for calculating the Bayesian regression estimates. Finally, the York bivariate estimates were produced with a custom python implementation of the algorithm presented by York et al. (2004).

### 3 Data simulation

In measured data, the variables that are observed are not  $X$  and  $Y$ , but  $(X+e_x)$  and  $(Y+e_y)$ , where  $e_x$  and  $e_y$  are the uncertainty in the measurements, and the true  $X$  and  $Y$  cannot be exactly known. Thus, we used simulated data, where we know the true  $X$  and  $Y$ , to illustrate how the different line fitting methods perform in different situations.

We simulated a dataset mimicking new particle formation rates ( $J_{1.7}$ ) and sulphuric acid concentrations ( $H_2SO_4$ ) reported from CLOUD-chamber measurements in CERN. Both variables are known to have substantial measurement error and thus they are good test variables for our study. Additionally, the relationship of logarithms of these variables is quite often described with linear OLS regression and thus the inference may be flawed.

We generated one thousand random “true”  $H_2SO_4$  concentration values assuming log-normal distribution with median  $2.0 \cdot 10^6$  (*molecules cm<sup>-3</sup>*) and standard deviation  $2.4 \cdot 10^6$  (*molecules cm<sup>-3</sup>*). The corresponding true  $J_{1.7}$  was calculated using model  $\log_{10}(J_{1.7}) = \beta \cdot \log_{10}(H_2SO_4) + \alpha$  with the true slope  $\beta=3.3$  and  $\alpha=-23$ , both are realistic values presented by Kürten *et al.* (2016, Table 2 for the no added ammonia cases). The resulting  $J_{1.7}$  mean was 0.11 and standard deviation was 0.50, similar to  $J_{1.7}$  statistics in Kürten *et al.* (2016).

Simulated observations of the true  $H_2SO_4$  were obtained by adding random errors  $e_x = e_{rel,x} \cdot x + \sigma_{abs,x}$  that have a random absolute component  $e_{abs,x} \sim \text{normal}(0, \sigma_{abs,x})$  and a random component relative to the observation  $x$  itself  $e_{rel,x} \cdot x$ , where  $e_{rel,x} \sim \text{normal}(0, \sigma_{rel,x})$ . Similar definitions apply for the true  $J_{1.7}$ ,  $e_y$ ,  $\sigma_{abs,y}$  and  $\sigma_{abs,y}$ . The standard deviations of the measurement error components were chosen  $\sigma_{abs,x} = 4 \cdot 10^5$ ,  $\sigma_{rel,x} = 0.3$ ,  $\sigma_{abs,y} = 3 \cdot 10^{-3}$ ,  $\sigma_{rel,y} = 0.5$ , which are subjective estimates based on measurement data.

Simulating the observations tends to generate infrequent extreme outlier observations from the infinite tails of the normal distribution. We discarded these outliers with an error larger than three times the combined standard uncertainty of the

observation in order to remove the effect of outliers from the regression analysis. This represents the quality control procedure in data analysis and it also improved the stability of our results between different simulations.

## 4 Results

Differences between the regression methods are illustrated with four different ways. First, by showing line fits on scatterplot of simulated data. Secondly, illustrating how the slopes change when the uncertainty in the measured variables increase, thirdly by showing the sensitivity of the fits on number of observations and finally showing how the fits are affected by adding outliers in the data.

Regression fits with all methods in use are shown in Figure 1. As we know that the “true slope”  $\beta_{true}=3.30$  we can easily see how the methods perform. The worst performing method was OLS, with  $\beta_{ols}=1.55$ , which is roughly half of the  $\beta_{true}$ . The best performing methods with equal accuracy, i.e. within 2% range, were ODR ( $\beta_{ODR}=3.27$ ), Bayes EIV ( $\beta_{BEIV}=3.24$ ) and BLS ( $\beta_{BLS}=3.22$ ), whereas York ( $\beta_{York}=3.15$ ) was within 5% range, but Deming ( $\beta_{DR}=2.95$ ) and PCA ( $\beta_{PCA}=2.92$ ) slightly underestimated the slope.

The sensitivity of the methods was first tested by varying the uncertainty in  $H_2SO_4$  observations. We simulated six datasets with 1000 observations and with varying absolute and relative uncertainties, listed in Table 1, and made fits with each method on all datasets separately. The performance of the methods is shown in Figure 2, with the results corresponding to Figure 1 are marked with black colour. It shows that when the uncertainty is smaller, the bias in OLS fit is smaller but the bias increases significantly as more uncertainty is added to data. Decrease in performance can also be seen with ODR, which is overestimating the slope, and PCA, DR and Bayes EIV, which all underestimate the slope. Bivariate methods, BLS and York, seem to be quite robust with increasing uncertainty, as the slopes are not changing considerably.

The sensitivity of methods to decreasing number of observations was tested by picking 100 random samples from the 1000 simulation dataset with  $n$  of 3, 5, 10, 20, 30, 50, 70, 100, 300 and 500 and making fits for all samples with all methods. The average slopes and their standard errors are shown in Figure 3. It is clear that when the number of observations is 10 or less, the variation in estimated slopes can be considerably high. When  $n \geq 30$  the average slopes stabilized close to their characteristic level (within 5%), except for Bayes EIV and York bivariate, which needed more than 100 observations. The most sensitive methods for small  $n$  are Bayes EIV, ODR and PCA and thus they should not be applied for data with small  $n$ . Though, it should be remembered that number of points needed for a good fit depends on the uncertainties in the data.

The sensitivity for outliers in predictor variable  $H_2SO_4$  was tested with two different scenarios. First, the outliers were let to be randomly either high or low end of the distribution. In the second scenario, outliers were allowed to be only large numbers, which is often the case in  $H_2SO_4$  and aerosol concentration measurements as the smallest numbers are cleaned out from the data when they are smaller than the detection limit of the measurement instrument. Five cases with  $n=1000$  were simulated with increasing number of outliers (0, 5, 10, 20, 100) and 10 repetitions of  $H_2SO_4$  values with different set of outliers. Outliers were defined such that  $x_{obs}-x_{true} > 3 * \text{combined standard uncertainty}$ . The most sensitive methods for outliers in both scenarios

were OLS and Bayes EIV. High number of outliers caused underestimation to PCA and DR, especially in high outlier case, and slight overestimation to BLS in random outlier case. York Bivariate and ODR were not affected in either case and BLS had only small variation between the 10 replicates in the estimated slope. We did not explore how large a number of outliers would be needed to seriously disrupt the fits for the various methods. We felt that it is likely not realistic to have situations with more than 10% outliers.

## 5 Conclusions

Ordinary least squares regression can be used to answer some simple questions on data, such as is  $Y$  related to  $X$ . However, if we are interested in the strength of the relationship and the predictor variable  $X$  contains some error, then error-in-variables methods should be applied. There is no single correct method to make the fit, because the methods measure slightly different things about the data. The choice of method should be based on the properties of data and the specific research question. There are usually two types of error in the data: natural and measurement error, where natural error refers to stochastic variation in the environment. Even if the natural error in the data is not known, taking into account the measurement error improves the fit significantly. In addition, no matter how small the measurement error would be, it should be taken account because taking it into account will never lead to more biased estimator.

As a case study, we simulated a dataset mimicking the dependence of atmospheric new particle formation rate on sulphuric acid concentration. We introduced three major sources of uncertainty when doing inference from scatterplot data: increasing measurement error, number of data points and number of outliers. In Fig 1, we showed that in case of simulations where errors are taken from real measurements of  $J_{1.7}$  and  $H_2SO_4$  four of the methods gave slopes within 5% of the “true” known value: BLS, York bivariate, Bayes EIV and ODR. Estimates from BLS and York bivariate remained stable even when the uncertainty in simulated  $H_2SO_4$  was increased drastically in Fig 2. The main message to learn in Fig 3 is that with small numbers of observations all fit methods are highly uncertain. BLS was the most accurate with smallest sample sizes of 10 and less, ODR stabilized with 20 observations and York bivariate and Bayes EIV needed 100 or more data points to become accurate. After that, they approach the true value asymptotically, while the OLS slope, in contrast, converges towards an incorrect value. With the increasing number of outliers (Figure 4) ODR and York bivariate were the most stable ones, even with 10% of observations classified as outliers in both test cases. BLS remained stable in the case with only high outliers. Bayes EIV was the most sensitive to outliers after OLS.

From this, we can give a recommendation that if the uncertainty in predictor is known, York bivariate, or other method able to use known variances, should be applied. If the errors are not known, and they are estimated from data, BLS and ODR showed out to be the most robust in cases of increasing uncertainty (relative error  $rE > 30\%$  in Fig 2) and with high number of outliers. In our test data, BLS and ODR stayed stable up to  $rE > 80\%$  in Fig. 2 whereas DR and PCA started to be more uncertain when  $rE > 30\%$  and Bayes EIV when  $rE > 50\%$ . If the number of observations is less than 10, and the uncertainties are high, we recommend considering if a regression fit is appropriate at all. However, with our simulation tests BLS showed out to be

the most robust with small numbers of data points. Bayes EIV has significant advantages if the number of observations is high enough and there are not too many outliers, as it is able to estimate the errors in data with distributions.

### Author contribution

- 5 SM prepared the manuscript with contributions from all co-authors. SM, MP and SI performed the formal analysis. MP simulated the data. SM, AA and KL formulated the original idea. SM, MP and AL developed and implemented the methodology. SM, MP, TN and AL were responsible for investigation and validation of data and methods.

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### Competing interests

The authors declare that they have no conflict of interest.

- 15 *Data availability*: Simulated datasets used in the example analysis will be given as supplement upon publication.

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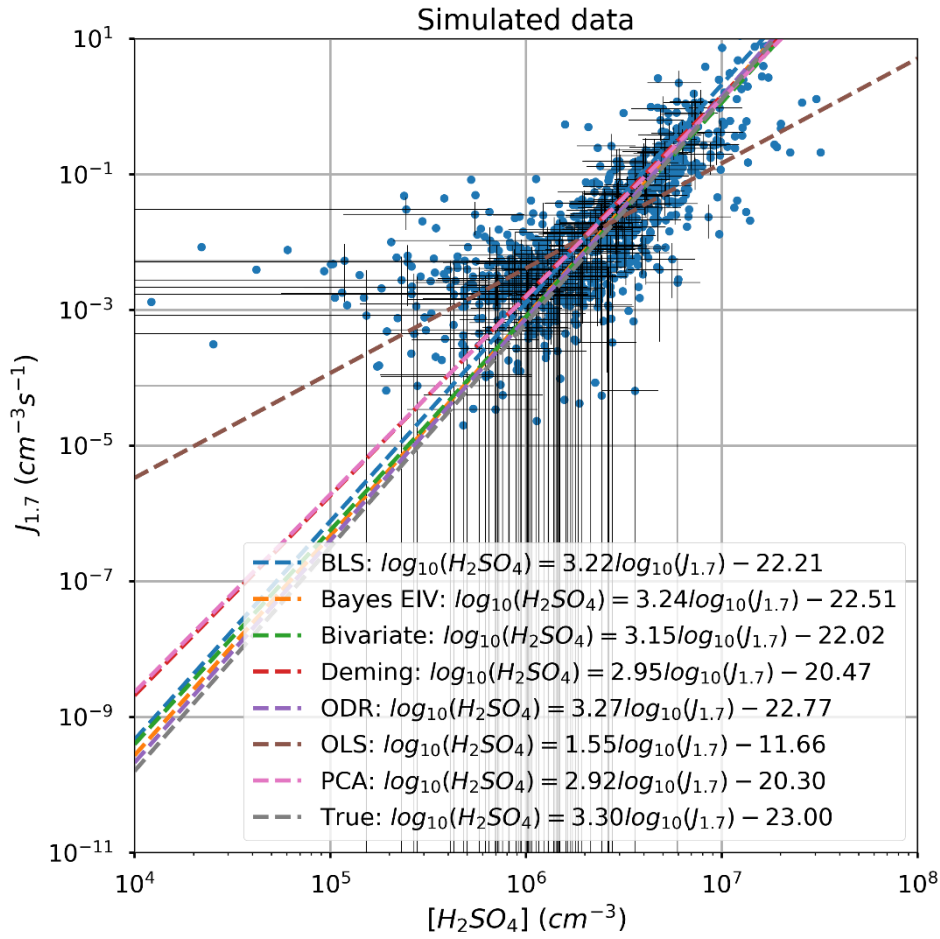


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**Figure 1. Regression lines fitted to the simulated data with all methods in comparison. Whiskers in data points refer to the measurement error used for simulation**

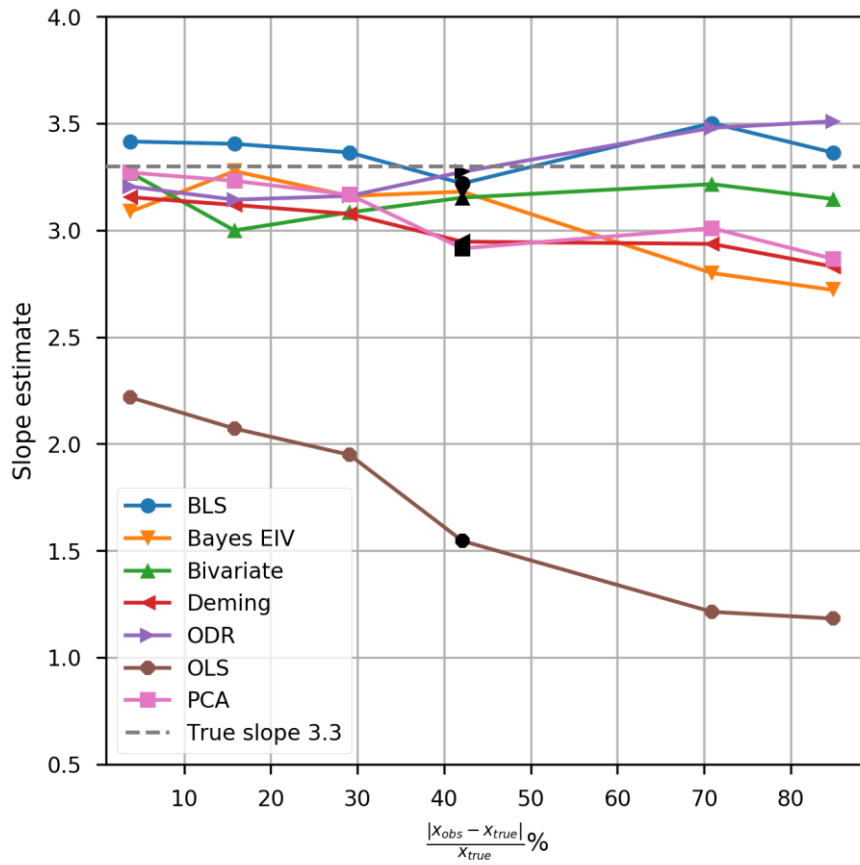


Figure 2. Sensitivity test for increasing uncertainty in simulated data. Black markers show the initial data set described in Section 3. Dashed line indicates the “true slope”.

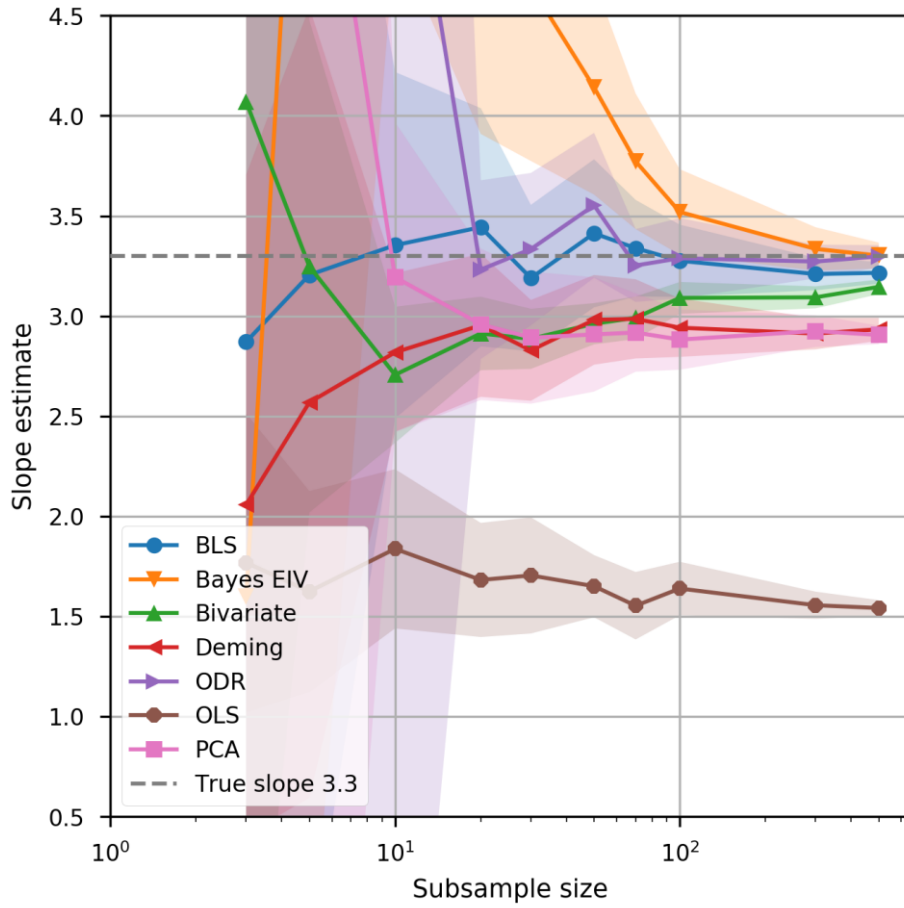


Figure 3. Effect of sample size on the uncertainty of different fits. Lines show the median and shading illustrates one standard deviation range of slope estimates for 40 repeated random samples. Dashed line indicates the “true slope”.

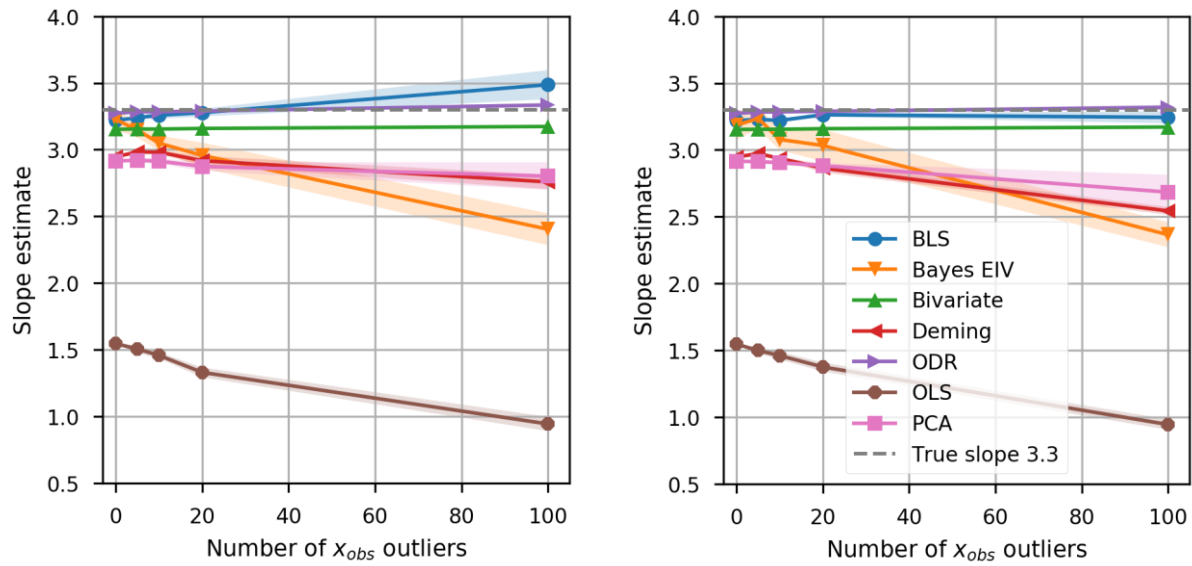


Figure 4. Effect of outliers in the data. Random outliers case on left panel and only high positives on right panel. Lines show the median and shading shows one standard deviation of slope estimates in ten repeated studies. Dashed line indicates the “true slope”.



**Table 1. The uncertainties used in simulation for sensitivity test for increasing uncertainty**

dataset	$\sigma_{\text{abs}}$	$\sigma_{\text{rel}}$	Ratio (= $(\sigma_{\text{rel}} * \overline{x_{\text{OBS}}}) / \sigma_{\text{abs}}$ )
1	$10^3$	0.05	315.0
2	$10^4$	0.18	113.4
3	$7*10^4$	0.3	27.0
4	$4*10^5$	0.3	4.7
5	$6.5*10^5$	0.45	4.4
6	$10^6$	0.55	3.5