



1 Quantifying errors in surface ozone predictions associated with

- 2 clouds over CONUS: A WRF-Chem modeling study using
- **3 satellite cloud retrievals**
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12 Abstract. Clouds play a key role in radiation and hence O₃ photochemistry by modulating photolysis rates and light-dependent emissions of biogenic volatile organic compounds (BVOCs). It is not well 13 known, however, how much error in O_3 predictions can be directly attributed to that in cloud predictions. 14 This study applies the Weather Research and Forecasting with Chemistry (WRF-Chem) at 12 km 15 horizontal resolution with the Morrison microphysics and Grell 3D cumulus parameterization to 16 quantify uncertainties in summertime surface O_3 predictions associated with the cloudiness over 17 contiguous United States (CONUS). To evaluate the model's own clouds and to restrain the growth of 18 model errors, the model is driven by reanalysis atmospheric data and reinitialized every 2 days. In 19





20 sensitivity simulations, cloud fields used for photochemistry are corrected based on satellite cloud retrievals. The results show that WRF-Chem predicts about 55% of clouds in the right locations and 21 22 generally underpredicts cloud optical depths. These errors in cloud predictions can lead up to 60 ppb 23 overestimation in hourly surface O_3 concentrations on some days. The average difference in summertime surface O₃ concentrations derived from the modeled clouds and satellite clouds ranges 24 from 1 to 6 ppb for the 8-h average O_3 over CONUS. This represents up to ~40% of the total 8-h 25 average O_3 bias under cloudy conditions in the tested model version, and the results are robust with 26 respect to the choice of the microphysics scheme. Surface O₃ concentrations are sensitive to cloud 27 28 errors mainly through the calculation of photolysis rates (for ~80%), and to a lesser extent to lightdependent BVOC emissions. The sensitivity of surface O₃ to satellite-based cloud corrections is about 2 29 30 times larger in VOC-limited than NOx-limited regimes. Our results suggest that the benefits of accurate predictions of cloudiness would be significant in VOC-limited regions which are typical of urban areas. 31

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33 **1. Introduction**

Ozone (O₃) is a secondary pollutant that is formed by chemical reactions involving nitrogen oxides (NO_X = NO + NO₂) and volatile organic compounds (VOCs) in the presence of ultraviolet radiation. Because O₃ is a harmful pollutant and a greenhouse gas, there have been numerous efforts aimed at improving O₃ predictions in air quality models, i.e. through a better characterization of the emissions of O₃ precursors (Brioude et al., 2013), more detailed chemical mechanisms (Carter, 2010; Sarwar et al., 2013), more realistic lateral boundary conditions (e.g., Tang et al., 2009), and improved representation





of meteorological fields with ensemble modeling techniques (Bei et al., 2010; Zhang et al., 2007). A 40 comprehensive review of the current status and challenges of air quality forecasting is given by Zhang 41 42 et al. (2012). A large O_3 bias that still persists in most regional and global models is one of the challenges (Brown-Steiner et al., 2015; Fiore et al., 2009; Im et al., 2015; Lin et al., 2017; Travis et al., 43 2016). The recent multi-model intercomparison study by Im et al. (2015) indicates that over North 44 America models tend to overestimate surface O_3 below 30 ppb by 15–25% and to underestimate O_3 45 levels above 60 ppb by up to \sim 80%. It is not quantitatively understood how much the individual 46 processes contribute to O₃ biases. Among meteorological parameters, clouds can be one of the key 47 48 factors because they greatly modulate the ultraviolet radiation that is critical for O_3 formation. However, they remain one of the largest sources of uncertainties in air quality modeling as Dabberdt et al. (2004) 49 50 pointed out a decade ago. Accurate cloud predictions in numerical weather models are still challenging, 51 and it has not yet been quantified how much errors in cloud prediction impact surface O_3 predictions.

As satellite cloud products have emerged, providing reasonably accurate data with wide coverage and 52 high temporal resolutions in near-real time (e.g., Minnis et al., 2008), they have been employed in 53 various studies to quantify the effects of clouds on actinic fluxes and/or photolysis rates (Mayer et al., 54 55 1998; Ryu et al., 2017; Thiel et al., 2008). Clouds can greatly reduce or enhance actinic flux below, above, and inside clouds, and these effects depend mainly on the cloud optical properties. Ryu et al. 56 (2017) used satellite cloud retrievals of cloud bottom and top heights and cloud optical depth (COD) in 57 a radiative transfer model, and showed that one can obtain fairly good (within $\pm 10\%$) vertical 58 59 distributions of cloudy-sky actinic flux using satellite cloud properties. There are, however, only a 60 limited number of studies that have examined the impact of satellite-constrained clouds and photolysis





rates on O₃ formation. Pour-Biazar et al. (2007) and Tang et al. (2015) used satellite-observed clouds to 61 correct photolysis rates in a three-dimensional chemistry transport model and reported considerable 62 63 improvement in surface O₃ simulations. Pour-Biazar et al. (2007) showed that the difference in O₃ due to the errors in cloud predictions can be up to 60 ppb for a given pollution episode over the south US. 64 Tang et al. (2015) showed that 1-month averages of 8-h surface O_3 can differ by 2–3 ppb between the 65 simulations using satellite-derived clouds and model-predicted clouds over the south US. These studies 66 were performed for rather short time periods (a week or a month) over limited areas, and provide 67 motivation for a more systematic/comprehensive quantification of the importance of cloud errors in O₃ 68 69 predictions in summertime and for various chemical regimes.

70 In the present study, we use satellite-derived COD and cloud boundaries to constrain radiation fields that impact photochemistry, i.e., photolysis rates and light-dependent BVOC emissions, in a three-71 72 dimensional chemistry transport model (WRF-Chem). Our study targets the contiguous United States (CONUS) and numerical simulations are performed for June-September 2013. The WRF-simulated 73 clouds are first evaluated against the Geostationary Operational Environmental Satellite (GOES) data 74 75 (section 3). The vertical profiles of NO₂ photolysis rates are evaluated against in-situ airborne 76 measurements during two field campaigns (section 4). The O₃ biases arising from inaccurate cloud predictions are quantified, and discussed in light of the sensitivity of O₃ chemistry to COD (section 5). 77 Unlike the previously mentioned studies, here we quantify separately the contributions of errors arising 78 79 from changes in photolysis rates altered by clouds vs. those arising from light-dependent BVOC 80 emissions to the O_3 biases. Conclusions and discussion are given in section 6.





81 **2. Methodology**

82 **2.1. Satellite retrievals**

The GOES retrievals were performed using the Satellite ClOud and Radiation Property Retrieval 83 System (SatCORPS), which is an adaptation of the Minnis et al. (2011) algorithms for application to 84 85 imagers on all geostationary weather satellites (Minnis et al. 2008) and on NOAA and MetOp satellites (Minnis et al. 2016). For SatCORPS, the algorithms of Minnis et al. (2011) were altered as described by 86 Minnis et al. (2010) using the low-cloud height estimation method of Sun-Mack et al. (2014) and the 87 88 severely roughened hexagonal column optical model of Yang et al. (2008) for ice cloud COD retrievals. This study uses a subset of the hourly, 8-km SatCORPS cloud retrievals from GOES 13 (GOES-East) 89 and GOES 15 (GOES-West) for the North American domain. The 8-km resolution is achieved by 90 91 analyzing only every other 4-km pixel and line. Each pixel is considered to be either 100% cloudy or 100% clear. Of the variety of cloud properties available, this study only uses cloud bottom height, cloud 92 top height, and COD. Uncertainties in the cloud products are summarized by Ryu et al. (2017). 93

Images from coincident times were unavailable for the two satellites: the GOES 13 and GOES 15 data 94 95 are offset by 15 min. The GOES 13 data taken at UTC + 45 min at every hour were matched with the GOES 15 data at UTC + 00 min. The pixel-level retrievals were re-gridded to a 12-km resolution to 96 match the WRF-Chem domain (see section 2.2) using the Earth System Modeling Framework (ESMF) 97 software and the nearest-neighbor interpolation. Because of the coverage difference between the two 98 satellites, the data of the nearest time from the two satellites (e.g., 1845 UTC from GOES 13 and 1900 99 100 UTC from GOES 15) are merged at 105°W, which is equidistant from the two sub-satellite longitudes. 101 Only daytime hours (09–23 UTC and 00–04 UTC) are used here.





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103 **2.2. WRF-Chem model simulations**

104 The present study employs the WRF-Chem model version 3.6.1. with the updated photolysis scheme. A 105 single domain is used with a horizontal grid size of 12 km (Fig. 1). The meteorological initial and 106 boundary conditions are provided by the NCEP FNL (Final) Operational Global Analysis data with a 107 horizontal resolution of 1°, which are available every 6 hours. The model is initialized at 00 UTC 1 June 2013 and spun-up for the first 10 days in the control simulation (CNTR simulation). The meteorological 108 109 fields are re-initialized every 48 hours at 06 UTC of a given day to avoid the growth of model errors, 110 and the model is run for 54 hours. Here, the first 6 hours are allowed for spin-up and discarded in each 111 run. The model outputs for the period of 12 UTC 11 June 2013 through 12 UTC 1 October 2013 are 112 used for the analysis. As the goal of the study is to use and evaluate the modeled clouds and their impact 113 on O_3 predictions, nudging is not used. This is different from many previous air quality studies that 114 nudged the meteorology and evaluated modeled O₃ with observations. The physics options used are the Morrison two-moment scheme (Morrison et al., 2009) for the microphysics, RRTMG scheme for 115 116 longwave and shortwave radiation (Iacono et al., 2008), MYNN 2.5 level TKE scheme for the boundary 117 layer parameterization (Nakanishi and Niino, 2006), MYNN surface layer scheme, Noah land surface 118 model (Chen and Dudhia, 2001), and Grell 3D ensemble scheme (Grell and Devenyi, 2002) for cumulus 119 parameterization with radiation feedback. The initial and boundary conditions for chemical species are obtained from the Model for OZone And Related chemical Tracers (MOZART) global simulation of 120 121 trace gases and aerosols. For each 2-day simulation, the chemical state of the atmosphere at 06 UTC is 122 obtained from that at 06 UTC of the previous simulation. The MOZART-4 mechanism is used for gas-





phase chemistry as described in Knote et al. (2014), and the Model for Simulating Aerosol Interaction 123 and Chemistry (MOSAIC) aerosol module with 4 bins is used for the aerosol chemistry. Anthropogenic 124 125 gas and aerosol emissions are adopted from the AOMEII project in which the emissions were projected to 2010 from the NEI 2008 inventory (Campbell et al., 2015). Since Travis et al. (2016) reported that 126 NEI NO_X emissions are too high, we reduced NO_X emission by 40% following their analysis. Note that 127 128 the NO_x and PAN from the lateral boundaries are also reduced by 40% in our study. Biomass burning emissions are taken from the Fire Inventory from NCAR (FINN) (Wiedinmyer et al., 2011). Model of 129 Emissions of Gases and Aerosols from Nature (MEGAN) (Guenther et al., 2006) version 2.04 is used 130 131 for BVOC emissions. As done in Travis et al. (2016) to better match isoprene flux observations during the Studies of Emissions and Atmospheric Composition, Clouds and Climate Coupling by Regional 132 Surveys (SEAC⁴RS) field campaign (Toon et al., 2016), we reduced MEGAN isoprene emissions by 15% 133 over the southeast US. The photolysis rate calculations utilize the newly implemented TUV option in 134 135 the WRF-Chem model (Hodzic et al., 2017 in preparation). This new TUV option uses the updated 136 cross section and quantum yield data based on the latest stand-alone TUV model version 5.3, and 137 considers 156 wavelength bins with the resolutions of 1-5 nm. The COD is calculated based on the 138 parameterization given in Chang et al. (1987), which uses cloud liquid water and/or ice water contents and effective droplet radius (assumed to be 10 µm both for liquid and ice droplets). To represent subgrid 139 cloud overlaps, a simple equation of Briegleb (1992) is used, i.e., the effective $COD = COD_0 \times (cloud)$ 140 fraction)^{1.5}, where COD₀ is the cloud optical depth that is calculated following Chang et al. (1987), and 141 142 the cloud fraction is determined based on the relative humidity in a given grid box. According to





Briegleb (1992), applying a power of 1.5 to the cloud fraction is equivalent to the maximum randomoverlap.

In the present study, we performed two sets of simulations that use WRF generated clouds in the CNTR 145 simulation and the GOES clouds in the GOES simulation. The GOES simulations are conducted from 146 147 06 UTC 11 June 2013 through 12 UTC 1 October 2013. The initial chemistry conditions in the GOES simulation are adopted from the outputs of the CNTR simulation at 06 UTC 11 June 2013. The satellite 148 cloud retrievals are used only to correct photolysis rate and photosynthetically active radiation (PAR) 149 calculations (i.e., only within the TUV model in WRF-Chem). That is, the satellite cloud information is 150 not linked to dynamics, microphysics, and atmospheric radiation. The value of COD is linearly 151 distributed through vertical grids from the cloud bottom to the cloud top within the TUV model as done 152 in Ryu et al. (2017). This method is different from the one used in Pour-Biazar et al. (2007) and Tang et 153 154 al. (2015) in which cloud bottom height used in their photolysis rate calculations is estimated from the meteorological model rather than retrieved from the satellite. The use of model estimates can lead to 155 additional uncertainties in the case of misplaced model clouds compared to observations. 156

In the present study, PAR calculated from the TUV model is used for the BVOC emissions in MEGAN for all simulations. This is different from the PAR conventionally used in MEGAN, which is simply converted/scaled from the downward shortwave radiation from the atmospheric radiation scheme. In the CNTR (GOES) simulation, the WRF generated clouds (GOES clouds) are used for the PAR calculation within the TUV model.



162	To examine the impact of changes in BVOC emissions on surface O_3 , another set of sensitivity
163	simulation (EMIS_BVOC simulation) is performed for 10 days (3-12 July 2013), which uses WRF-
164	generated clouds for the PAR calculation and BVOC emissions as in the CNTR simulation but uses the
165	GOES clouds for photolysis rate calculations as in the GOES simulation. The description of the control
166	and sensitivity simulations is summarized in Table 1.

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168 **2.3. Observational data**

169 2.3.1. Aircraft data from field campaigns

We evaluate the model performance using airborne measurements made during two field campaigns in 170 2013, i.e., the NOMADSS (Nitrogen, Oxidants, Mercury and Aerosol Distributions, Sources and Sinks) 171 and the SEAC⁴RS campaigns. The detailed description of the instrument and measurement data is given 172 173 in Ryu et al (2017). The NOMADSS campaign was conducted during 1 June–15 July 2013 mainly over 174 the southeast US. We use 16 flight-day data at 1-min time intervals for the analysis. Data with solar zenith angles larger than 85° are not used. The fire plume data are filtered out by excluding the data 175 showing NO₂ (> 0.1 ppb) or CO (> 120 ppb) aloft at 4–7 km level. Based on the GOES cloud data, 68% 176 of flight data are characterized by clear skies and the remaining data (32%) had clouds in the vertical 177 column where the airplane was located. The SEAC⁴RS campaign also targeted the southeast US 178 179 although the airplane sometimes flew over a larger region including California and Midwestern US. The period used for the analysis is from 6 August through 23 September 2013, which includes 21 flight days. 180 The time intervals are also 1-min and the data with large solar zenith angles (> 85°) and with fire 181



plumes are filtered out. The fraction of data with clouds is 41% for SEAC⁴RS. It is noteworthy that SEAC⁴RS measurements include large and thick clouds in some cases as a few of the campaign goals are to identify the role of deep convection in redistributing pollutants and aerosol-clouds feedbacks, whereas the clouds during NOMADSS were mostly broken clouds.

186 2.3.2. Ground ozone data

The United States Environmental Protection Agency (EPA) hourly O₃ measurements are used for the 187 analysis. To examine the sensitivity of O₃ to COD in different chemical regimes, the VOC- and NO_x-188 189 limited regimes are identified using the ratio of $\Delta O_3 / \Delta NO_v$, following (Sillman and He (2002). They reported that the NO_X-VOC transition occurs when $\Delta O_3/\Delta NO_v = 4-6$. Thus, an EPA site is denoted as a 190 191 VOC-limited (NO_X-limited) regime when the ratio is less than 4 (greater than 6). Among 1,299 EPA 192 sites, 1,062 are used for the analysis: 24% of the sites are in the VOC-limited and 76% in NO_x-limited regimes. The remaining 237 sites are not used in the present study because those sites fall into the 193 transitional zone, i.e., $\Delta O_3 / \Delta NO_v = 4-6$. 194

3. Evaluation of WRF clouds with satellite measurements

The model bias in the cloud spatial coverage is evaluated using a 2×2 contingency table (Table 2), where A and D correspond to hit and correct negative events, respectively, and B and C to false alarm and miss events, respectively. Here, a threshold of 0.3 in hourly COD is used to distinguish between clear and cloudy sky as the lowest detection limit of satellite retrieved COD over land is estimated to 0.25 in Rossow and Schiffer (1999), and the use of 0.3 poses slightly stricter conditions for cloudiness. The agreement index, which is defined as A+D (WRF predicts correctly cloudy or clear skies), is 69.7%





and the probability of detection (POD) for clouds, A/(A+C), is 55.6%. It is found that the fraction of 202 errors in missing clouds (C, 19.8%) is larger than that of predicting wrong clouds (that are not present in 203 204 reality) (B, 10.4%). The WRF underestimates the frequency of cloudy skies as the ratio of (A+B)/(A+C). 0.789, indicates smaller than 1. Figure 1 shows the spatial distribution of each contingency category 205 over CONUS as averaged over the whole study period. In general, the eastern US shows higher cloud 206 207 frequencies than the western US except for the mountain regions and northwestern US. The largest agreement index appears in the central California where the sky condition is mostly clear (Fig. 1d). In 208 209 terms of errors, the missing clouds rate has its highest frequency (20-35%) in the Midwestern and 210 northwestern US, while the highest frequency of false alarm (20–30%) occurs over the southeast US and the southeastern Texas. The sum of category B and C can be found in supplementary (Fig. S1). It 211 212 should be noted that the contingency categories are based on binary results of cloud-free or cloudiness 213 and so they do not provide quantitative comparison of cloud optical properties, e.g., COD. For example, 214 even though the WRF model produces clouds in the right locations (category A), the WRF CODs can 215 differ from those retrieved from satellite data.

Figure 2 evaluates quantitatively COD and vertical extent of clouds between the model and satellite retrievals. The vertical extent of clouds is classified based on the International Satellite Cloud Climatology Project (ISCCP) definition (Rossow and Schiffer, 1999), which are as follows: i) low-level: cloud top height \leq 3 km, ii) mid-level: 3 km < cloud top height \leq 6 km, iii) high-level: cloud bottom height > 6 km, and iv) multi-layered or deep convection: cloud bottom height \leq 6 km and cloud top height > 6 km. Even though multiple cloud layers can be resolved in the WRF model, these kinds of clouds are not resolved in the satellite retrievals used in this study. Thus, for a fair comparison, the





223 multi-layered clouds in the WRF model are not further resolved into cloud layers. Note that the 224 liquid/ice water contents from cumulus clouds (parameterized clouds) are included in the model COD 225 calculations.

The frequency distribution of CODs does not have the same shape in the model and observations. The 226 227 WRF model overpredicts by a factor of 2 very thin clouds with COD < 1, whereas the GOES retrievals show that the most abundant clouds have CODs of 2–5. The majority of optically very thin clouds from 228 the WRF model correspond to high-level cirrus clouds. This is consistent with the result of Cintineo et 229 230 al. (2013), showing that the Morrison microphysics scheme produces too many upper-level clouds by comparing GOES infrared brightness temperature with the WRF model. Note that the optically-thin 231 232 multi-layered clouds very likely contain cirrus clouds because their top height is greater than 6 km. The WRF model produces fewer clouds with COD > 1 than observed, and the discrepancy is most apparent 233 234 for optically very-thick clouds (COD > 50). As a result, the model COD mean and standard deviation 235 are smaller than those for the retrievals, which are 8.3 and 12.7, respectively for the WRF model, and 236 17.8 and 30.8, respectively for the GOES retrievals.

237 **4. Impact of cloud errors on photolysis rates**

Figure 3 compares the cloudy-sky averaged vertical profiles of NO₂ photolysis rates (JNO₂) predicted by WRF-Chem and measured during the NOMADSS (Fig. 3a) and SEAC⁴RS (Fig. 3d) campaigns. The histograms of ratio of JNO₂ simulated to that observed under cloudy conditions are also shown for the CNTR and GOES simulations.



For both campaigns, the simulations with satellite clouds (GOES simulations) generally show better 242 agreement with the observed JNO₂ profiles than the control simulations, especially above the boundary 243 244 layer (above ~ 2 km). The histograms of the ratio model-to-observation JNO₂ also show a better performance generally in the GOES simulation than in the CNTR simulation: the mean of the ratio is 245 closer to 1 in the GOES simulation than in the CNTR simulation for SEAC⁴RS, the standard deviations 246 247 are reduced in the GOES simulation compared to those in the CNTR simulation for both campaigns, the root-mean-square-errors are lowered in the GOES simulation compared to those in the CNTR 248 249 simulation, and the correlation coefficients are closer to 1 in the GOES simulation than in the CNTR 250 simulation. For NOMADSS, the large bias in the highest ratio bin (> 2) is 24% less in the GOES simulation than in the CNTR simulation. The 47% reduction of the large bias (> 2) in the GOES 251 simulation is more substantial for SEAC⁴RS. This is attributed to better representation of the below-252 cloud and inside-cloud conditions (not shown). The larger mean model-to-observation JNO₂ ratio and 253 254 the greater frequency of ratios greater than 1 for NOMADSS are likely due to the overestimation of 255 JNO₂ above clouds as scattered clouds predominate in those measurements. In the TUV calculations, 256 the clouds in a given grid box (e.g., here a 12 km \times 12 km box) are assumed to be infinitely extended in 257 the horizontal direction. However, the sensor can see a broader area (than a $12 \text{ km} \times 12 \text{ km}$ area), and so in the presence of scattered clouds a cloud fraction within sensor view angles can be smaller than 1. 258 259 Therefore, the modeled JNO₂ can be larger in the presence of scattered clouds as compared to the 260 measured JNO₂.





261 **5. Impact of cloud errors on ground level ozone**

262 5.1. An example on 8 July 2013 in Midwestern US

Figure 4 shows an example of how model errors in cloud fields impact O₃ predictions. This example 263 includes thunderstorm systems over the Midwestern US. The CNTR simulation misses clouds or 264 265 underpredicts CODs over metropolitan Chicago and the region south of Lake Michigan. This results in the overprediction of JNO₂ by up to 0.54 min⁻¹ (~90%) compared to that computed using GOES clouds. 266 The resulting changes in O₃ concentration are regional and the O₃ overprediction in the plume 267 268 originating from the Chicago area is up to 62 ppb (~60% of O₃ in the CNTR simulation). As a result of the cloud corrections, O₃ in the GOES simulation agrees better with observations in those regions 269 (compare Fig. 4d with Fig. 4e and Figs. 4g,h,i). The time series of O₃ at the three sites (marked in Fig. 270 271 4f) near Lake Michigan show particularly improved agreement with observations when satellite clouds 272 are used. The large O₃ biases of 20.5 ppb at 11 LST at Chicago, IL, 19.2 ppb at 13 LST at La Porte, IN, 273 and 23.5 ppb at 16 LST at Holland, MI in the CNTR simulation are reduced to 1.7 ppb, 3.2 ppb, and 274 -0.11 ppb in the GOES simulation, respectively. It is also apparent that the bias reduction in O₃ shifts eastward (from Chicago, IL to Holland, MI) as the thunderstorm moves eastward during the day. An 275 important implication of this finding is that errors in cloud predictions can lead to wrong O₃ alerts in 276 277 areas where model does not predict clouds well. For example, the daily maximum $8-h O_3$ concentration is 75.3 ppb at Holland, MI in the CNTR simulation (Fig. 4i) and this value exceeds the O_3 standard (70) 278 279 ppb for 8-h O_3). However, the daily maximum 8-h O_3 concentration at the same location is 63.0 ppb in the GOES simulation and 60.4 ppb in the observation. Therefore, an O₃ action alert would have been 280 281 issued if the CNTR simulation results are used, which results in a false alarm.



In general, the regions exhibiting O_3 differences between the two simulations coincide with the regions where JNO₂ values are different. More importantly, large O_3 differences are found near urban areas (e.g., Chicago, IL; downwind area of Kansas City, MO; Omaha, NE and its downwind area). Even though the difference in COD or JNO₂ is significant in central Indiana, for example, the difference in O_3 in the region is relatively small compared to that near Lake Michigan.

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288 **5.2.8-h average O**₃

The spatial distribution of 8-h average O₃ (10–17 LST average, simply 8-h O₃ hereafter) averaged over 289 the whole study period in the GOES simulation is similar to that in the CNTR simulation, but the O₃ 290 levels are considerably different. Figure 5 shows the maps of 8-h O₃ for the CNTR simulation and the 291 O₃ difference between the CNTR and GOES simulations. In Fig. 5b, the Midwestern, eastern, and 292 293 northwestern US regions show the largest O_3 differences, up to 4.7 ppb, with lower O_3 levels in the 294 GOES simulation. These regions generally belong to the contingency category C (Midwestern and 295 northwestern US) or category A (eastern US). On the other hand, the regions with negative differences, i.e., some places over the south/southeastern US, coincide with the contingency category B. These 296 differences are expected and can be interpreted as follows: when the WRF model misses clouds (clear 297 298 sky in the CNTR simulation, category C) or underestimates COD (as seen in Fig. 2), surface O_3 is overestimated. When the WRF model generates clouds that are not present in reality (clear sky in the 299 300 satellite retrievals, category B), surface O_3 is underestimated. It should be noted that not all regions belonging to category B or C have significant O₃ differences. Interestingly, the regions exhibiting 301 302 significantly large O₃ differences coincide with large urban areas, e.g., Seattle, WA; Los Angeles, CA;





Chicago, IL; Cleveland, OH; Houston, TX; New Orleans, LA; Atlanta, GA; and Miami, FL. The reasons for this result are explored in section 5.4 and 5.5.

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5.3. Relative contribution to O₃ errors from photolysis rates and BVOC emissions

307 It is expected that reduced BVOC emissions (especially isoprene) due to the presence of clouds can also decrease O₃ formation. Figure 6 shows the spatial distributions of relative changes in PAR and isoprene 308 309 emission between the EMIS_BVOC and GOES simulations averaged over a 10-day period. Because the 310 WRF model tends to underestimate COD or is not able to reproduce clouds in Midwestern and western 311 US, PAR and biogenic isoprene emissions are larger in the EMIS BVOC simulation than in the GOES simulation. On the other hand, the model overestimates COD or produces clouds that are not present in 312 reality over the southeast US, so PAR and biogenic isoprene emissions are lower in the EMIS BVOC 313 simulation than in the GOES simulation. The change in PAR (biogenic isoprene emissions) resulting 314 315 from the difference in clouds fields between the WRF model and satellite retrievals is up to $\pm 30-40\%$ 316 $(\pm 25\%)$. The O₃ difference between the EMIS BVOC and GOES simulations (Fig. 6d) is relatively 317 small in comparison to the difference in O_3 between the CNTR and GOES simulations (Fig. 6c) that results from both photolysis rate and BVOC emission changes. In general, the contribution of changes 318 in photolysis rates to changes in O_3 is ~80%, on average, over CONUS and the remaining (~20%) is 319 320 attributed to changes in BVOC emissions. The contribution of BVOC emissions is larger (up to ~40%) 321 in urban areas over the southeast (specifically in Charlotte, NC). The difference in O_3 in Charlotte, NC resulting from changes in BVOC emissions is about 1.5 ppb and that from changes in both photolysis 322





rates and BVOC emissions is about 3.5 ppb. In some regions, such as Midwestern, western
Pennsylvania, and central New York, the effect of BVOC emissions is negligible.

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5.4. Cloud effects on ozone bias in VOC- and NOx -limited regimes

327 In this section, we examine the effects of clouds on O₃ in VOC-limited and NO_X-limited regimes in 328 order to understand the reasons for a stronger O_3 response to cloud corrections in urban areas than in the 329 remote regions. Figure 7 shows how cloud corrections affect O_3 errors in different regimes. Here, 8-h 330 O_3 is used to compute the model O_3 bias (simulation minus observation). Figures 7a and 7b show the 331 probability density functions of the model O₃ bias for the CNTR and GOES simulations, respectively, at all ground sites experiencing considerably thick (COD > 20) clouds. In this example, an EPA site is 332 considered under cloudy sky conditions when hourly COD greater than the chosen threshold (here, 20) 333 334 is present at the site for at least 4 hours within the 8-h time window in a given day. The decrease in the O₃ bias for VOC-limited regime is significant, and the difference in median values between the two 335 336 simulations is 5.4 ppb. The decrease in O_3 bias for NO_x -limited regimes (2.75 ppb) is about 2 times 337 smaller than that for VOC-limited regime. An important result is that the frequency of very large biases (e.g., greater than 20 ppb) is substantially reduced when cloud fields are corrected, especially for the 338 VOC-limited regime. This implies that more accurate cloud predictions ultimately improve the accuracy 339 340 of O₃ alert predictions, especially in polluted urban areas.

Figure 7c shows the change in median values of 8-h O₃ bias for a range of COD thresholds. We find that the O₃ bias increases with increasing cloudiness in the CNTR simulation. As previously mentioned,





the O₃ bias is generally larger for VOC-limited regimes than for NO_x-limited regimes. When the 343 radiation fields are corrected with satellite clouds, the model O_3 bias is considerably reduced (but not 344 345 zero). In addition, the O₃ bias in the GOES simulation does not increase as much as that in the CNTR simulation when cloudiness increases. This implies that there are other sources of O₃ biases in the 346 GOES simulation, which are not likely associated with cloudiness. The other errors sources can be 347 precursor emissions, mixing/transport, and deposition. Fig. 7d compares the median values of $8-h O_3$ 348 bias between the two simulations (CNTR minus GOES), and shows that the difference in 8-h O_3 349 between the two simulations clearly increases as the COD threshold increases and that the effect of 350 351 cloud correction is larger in VOC-limited than in NO_X -limited regimes. The reduced O_3 bias as a result of cloud corrections ranges from 1 to 6 ppb depending on CODs and chemistry regimes. This represents 352 353 up to $\sim 40\%$ of the total O₃ bias under cloudy conditions in the current model version (e.g., 5.4 ppb of 354 13.37 ppb for COD threshold of 20 in VOC-limited regimes).

We examine the O_3 bias over the southeast US where large overpredictions at the surface have been 355 reported (e.g., Travis et al. 2016) in a supplementary section. It is found that a considerable portion of 356 357 O_3 bias is attributable to inaccurate cloud predictions over the southeast US, but the degree of the effects of clouds is smaller than that over CONUS as a whole (Fig. S2). The maximum reduction in O₃ 358 bias due to inaccurate cloud predictions is 4.6 ppb over the southeast US and 5.7 ppb over CONUS. Still, 359 large O_3 biases of ~11 ppb are present over the southeast US (compared to those of 8–9 ppb over 360 361 CONUS) even though the cloud fields are corrected for photochemistry. This result implies that errors 362 resulting from other processes exist and are responsible for the surface O_3 overpredictions over the





southeast US. More in-depth studies that find and quantify errors are therefore required to better predict
the O₃ over the southeast US as well as CONUS.

365

5.5. Ozone formation sensitivity to changes in photolysis rates

367 The difference in O₃ sensitivity to changes in photolysis rates (resulting from the presence of clouds) in 368 different regimes is determined by calculating dln(O₃)/dln(JNO₂) ratios as in Kleinman (1991). Table 3 369 lists those sensitivity coefficients of O₃ to JNO₂ and shows that O₃ is more sensitive to JNO₂ in VOC-370 limited than in NO_x-limited regimes, being 1.69 times larger under cloudy-sky conditions and by 1.65 371 times greater under clear-sky conditions. Similar sensitivities were reported for OH by Berresheim et al. (2003) with the sensitivity of OH to $JO^{1}D$, $dln(OH)/dln(JO^{1}D)$, of 0.8 at high NO₂ levels (~10 ppb) and 372 0.68 at low to moderate NO₂ levels (~1 ppb). The corresponding sensitivities from our study are 1.1 for 373 VOC-limited regimes and 0.66 for NO_X-limited regimes under clear-sky conditions. Similar results are 374 375 also found for the net chemical production of O_3 and OH concentration, revealing stronger responses to changes in cloudiness in VOC-limited regimes than NO_x-limited regimes (Fig. 8). It is interesting to 376 377 note that OH and HO₂ have local maxima at CODs between 2 and 5. As shown in Ryu et al. (2017), the 378 enhancement of actinic flux at the surface due to optically thin clouds (CODs < 5) is considerable for high-level clouds, i.e., cirrus. The local maxima, therefore, likely result from the fact that the GOES 379 380 clouds have the largest portion of cirrus for CODs of 2–5 as seen in Fig. 2b. Figure 8 also shows that the variation (defined by 25 and 75 percentiles) of net chemical production of O₃ with respect to COD is 381 much larger in VOC-limited conditions. This result suggests that predicting O₃ under cloudy conditions 382





is likely more difficult in VOC-limited than in NO_X -limited regimes. It is also noticeable that the HO₂ radical concentration remains relatively high in NO_X -limited regimes even under cloudy conditions as compared to the VOC-limited regimes. Note that the results of WRF-Chem here include the effects of both photolysis rates and BVOC emissions.

387 A simplified box model (BOXMOX, Knote et al. (2015)) simulation using the same chemical mechanism (MOZART-4) as WRF-Chem was performed to better understand O₃ sensitivity to changing 388 389 cloudiness in different chemistry regimes. The emission rates for VOC-limited (NO_x-limited) regime 390 are those of the Chicago urban (rural) area in the WRF-Chem simulation. The initial conditions are taken from the CNTR simulation at 09 LST 7 July 2013 in the Chicago suburban area for both regimes. 391 392 Dry deposition is not considered. Photolysis rates for all species that are photodissociable are varied from clear-sky to cloudy conditions with up to 80% reduction. The 80% reduction roughly corresponds 393 394 to COD of 35 (not shown). The box model is integrated for 12 hours and photolysis rates are kept 395 constant during the simulation (i.e., no diurnal variations). The box model results are found to be consistent with the results from the WRF-Chem simulations: the variations of O₃ and OH with respect 396 397 to decreasing photolysis rates are larger in VOC-limited regime than in NO_X -limited regime (Fig. S3, in supplementary). Figure 9 shows production and loss terms of RO_X (= $OH + HO_2 + RO_2$) radicals with 398 399 variations in photolysis rates for VOC-limited and NO_X-limited regimes. In both regimes, the decreased 400 sunlight due to clouds reduces OH formation by photodissociation of O₃ (primary source of OH). The 401 larger sensitivity of OH radicals to COD in VOC-limited regimes as seen in Fig. 8 is associated with the 402 loss of OH by the radical termination reaction between OH and NO_2 under NO_x -rich conditions, which 403 leads to the large decrease in OH (Fig. 9a). On the other hand, in NO_X-limited regimes, the radical



termination reactions are the radical-radical reactions (Fig. 9b). In this regime, OH mainly reacts with 404 VOCs and propagates through radical cycles by producing HO₂/RO₂ radicals, rather than being 405 406 terminated by the reaction with NO₂. Given that the reaction between NO and HO₂ becomes the largest source of OH budget (secondary source of OH) at an NO_X concentration of ~1 ppb (Ehhalt and Rohrer, 407 408 2000; Eisele et al., 1997), OH can be relatively less sensitive to the changes in radiation. Note that the 409 mean daytime NO_X concentration over CONUS in NO_X-limited regimes is 1.2 ppb and that in VOClimited regimes is 6.7 ppb for this study period. Another attribute is a relatively greater contribution of 410 411 H_2O_2 photodissociation to the production of RO_X in NO_X -limited regimes than that of HNO₃, which is 412 negligible. Unlike the radical terminated in VOC-limited conditions, a non-negligible amount of 413 terminated radicals can be recycled in the NO_X-limited regime.

414

6. Sensitivity of cloud optical depth and O₃ to microphysics scheme

416 It should be emphasized that our study was performed using a specific representation of the cloud 417 microphysics by Morrison et al. (2009). To test the robustness of our results with regard to the 418 representation of clouds, another microphysics scheme, Thompson scheme (Thompson et al., 2008), is 419 employed for a 10-day (3 July–12 July 2013) sensitivity simulation. The COD comparison in Fig. S4 420 shows that with the Thompson scheme the model predicts fewer clouds for all ranges of CODs as compared to GOES retrievals, except for the very thin ones (COD < 1) in which the number of those 421 clouds is still overpredicted as seen in the simulation with Morrison scheme. Compared to the Morrison 422 scheme, the Thompson scheme produces significantly less high-level (cirrus) clouds. This is also 423





424 consistent with the findings of Cintineo et al. (2013). Despite this difference, the shape of the COD425 distribution from the two microphysics schemes are rather similar to each other.

The 8-h O₃ bias with the Thompson scheme is evaluated (Fig. S5), and compared to that of the 426 Morrison scheme for the same period. The baseline simulation with the Thompson scheme (that uses 427 428 model generated clouds) shows that a median bias (14.09 ppb) is a bit smaller than that with the Morrison scheme (16.29 ppb) for that period in VOC-limited regimes. In the sensitivity simulation with 429 the Thompson scheme that uses GOES satellite clouds for photochemistry, the median bias is reduced 430 431 by 6.07 ppb (~43%, Fig. S5a) in VOC-limited regimes and by 1.45 ppb (~14%, Fig. S5c) in NO_Xlimited regimes, which are consistent with the results of our base simulation. The degree of the effects 432 433 of cloud correction in the sensitivity simulations with the Thompson scheme, ranging from 0.5 to 6 ppb, is similar to that found in the simulations with the Morrison scheme. Therefore, the general conclusions 434 435 remain the same: i.e. errors in O_3 predictions resulting from errors in cloud predictions are considerable 436 (up to ~6 ppb on average) and the effects of cloud corrections are larger in VOC-limited regimes than in 437 NO_x-limited regimes.

438

439 **7. Conclusions and discussion**

We performed quantitative analyses with the WRF-Chem model meso-scale (12 km) simulations to determine how much errors in cloud predictions contribute to errors in surface O₃ predictions during summertime over CONUS. Clouds were generated using the Morrison microphysics and Grell 3D





cumulus parameterization schemes. It is found that the WRF-Chem model is able to generate roughly
55% of the clouds in the right locations by comparing to satellite clouds. A quantitative comparison of
COD shows that the WRF-Chem model predicts too many thin cirrus clouds with CODs less than 1, and
also considerably underpredicts the optical depths for a majority of cloud systems.

447 The errors in cloud predictions can lead to large hourly O_3 biases of up to 60 ppb, for example, for specific cases in which the model misses deep convective clouds that are present in reality. On average, 448 449 the errors in 8-h O_3 of 1–6 ppb are found to be attributable to errors in cloud predictions under cloudy 450 sky conditions. We quantify separately the contribution of changes in photolysis rates and emissions of light-dependent BVOCs to cloud-related errors in surface O₃. The contribution of photolysis rates to 451 452 surface O_3 is larger (~80% on average) than that of BVOC emissions. The contribution of BVOC 453 emissions to O_3 can become important (~40%) in the VOC-limited regimes where BVOC emissions are 454 large (i.e., cities of the southeast US).

455 The effects of cloud corrections are more impactful in VOC-limited (or high-NO_X) than in NO_X-limited 456 (or low-NO_X) regimes. The sensitivity of O_3 with respect to COD is about 2 times larger in VOClimited than in NO_x-limited regimes. This finding is consistent with the box modeling results that were 457 458 performed for typical urban (rural) conditions under varying photolysis rates. The production of radicals 459 $(OH, HO_2, and RO_2)$ decreases with decreasing photolysis rates in the presence of clouds. The primary 460 reason for the larger sensitivity of O₃ formation to clouds in VOC-limited regimes is that the loss of OH 461 is much stronger in VOC-limited regimes due to the reaction with NO₂. Thus, OH cannot readily 462 propagate through the radical cycles. In NO_x-limited regimes, the radicals terminated from the radical



463 cycles are mostly HO_2 and RO_2 rather than OH. Thus, OH can remain in the cycles and continue to 464 produce HO_2 and RO_2 by reacting with VOCs before termination. The interconversion of HO_2 to OH is 465 the dominant process in NO_X -limited regimes, and therefore OH and O_3 formations are less sensitive to 466 changes in radiation.

This study suggests that accurate cloud predictions through data assimilation or cloud mask corrections with near-real time satellite cloud data would benefit accurate O_3 predictions and that the benefit is expected to be greater in VOC-limited than in NO_X-limited regimes. Even though considerable reduction in O_3 bias is achieved by correcting cloud-related radiation fields, O_3 is still overpredicted by the WRF-Chem model. The remaining bias likely results from other processes involved in the O_3 lifecycle such as precursor emissions from both anthropogenic and biogenic sources, transport, turbulent mixing, and dry deposition, which quantitative assessment is beyond the scope of this study.

One should keep in mind that the quantitative estimate of the O_3 bias related to the cloud effects on 474 475 radiation as reported in this study could be sensitive to several factors. In particular, this study is based 476 on a particular configuration of the WRF-Chem model with regard to the radiation, microphysics, cumulus, boundary layer parameterization and the chemistry scheme. We have tested the sensitivity of 477 478 our results to the choice of microphysics, and have shown that the 8-h O₃ biases are reduced by up to ~6 ppb with the satellite cloud corrections in the simulations with the Thompson microphysis scheme, 479 480 which is consistent with the results found in our base simulations with the Morrison microphysis scheme. 481



From the perspective of O_3 forecast, it is expected that errors in O_3 predictions are greater when the initial and boundary conditions for WRF-Chem simulations are provided by meteorological forecasts compared to those simulations in which the initial and boundary conditions are provided by meteorological reanalysis because the reanalysis data are an improved estimate of the meteorological state. Understanding the evolution of errors in O_3 forecast associated with errors in cloud forecast and optimizing the use of meteorological forecasts for better O_3 forecast skill are therefore necessary and will be addressed in a future study.

489 Acknowledgments

490 We acknowledge Samuel Hall and Kirk Ullmann for providing actinic flux data that are used for 491 supplementary analysis, Geoff Tyndall and George Grell for helpful discussions. This study is supported from NASA-ROSES grant NNX15AE38G. P. Minnis was supported by the NASA Modeling, 492 493 Analysis, and Prediction Program. The National Center for Atmospheric Research is sponsored by the 494 National Science Foundation. The GOES cloud retrievals are available at https://satcorps.larc.nasa.gov. 495 The EPA data be downloaded ozone can at 496 https://aqsdr1.epa.gov/aqsweb/aqstmp/airdata/download files.html.

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687 Table 1. Description of WRF-Chem simulations.

		Photolysis rates	PAR	Analysis Period
	CNTR	WRF clouds	WRF clouds	06 UTC 11 June-12 UTC 1 October
	GOES	GOES clouds	GOES clouds	06 UTC 11 June-12 UTC 1 October
	EMIS_BVOC	GOES clouds	WRF clouds	06 UTC 3 July-12 UTC 13 July
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- Table 2. Contingency table for WRF simulation and GOES satellite clouds. The number of data for each
- category is normalized by the total number of data.

		GOES Satellite		
		Cloudy	Clear	
	Claudy	A (hit)	B (false alarm)	
WRF	Cloudy	24.8%	10.4%	
simulation	ilation	C (miss)	D (correct negative)	
Clear	19.8%	44.9%		





- Table 3. Sensitivity coefficient of O_3 to JNO₂, i.e., dln(O_3)/dln(JNO₂). The values of dln(O_3)/dln(JNO₂)
- for the period of 09–13 LST are averages over only CONUS EPA stations that have monotonically
- 713 increasing O_3 concentrations with time.

		Cloudy sky (5 < COD < 20)	Clear sky	
	VOC-limited	0.59	1.27	
	NO _X -limited	0.35	0.77	
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Fig. 1. Spatial distribution of each contingency category (see Table 2) between the WRF-generated clouds (CNTR simulation) and SatCORPS GOES retrievals averaged over the whole study period.

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Fig. 2. Histogram of hourly cloud optical depth (COD) during the daytime (16–23 UTC) over CONUS (land only) from the (a) WRF simulation (with the Morrison microphysics) and (b) GOES satellite retrievals. CODs on the *x*-axis represent the mean values of the bins that are 0.3–1, 1–2, 2–5, 5–10, 10– 20, 20–30, 30–40, 40–50, 50–100, and 100–150. For a fair comparison, the multi-layered WRF clouds are not resolved into cloud layers as this layering cannot be resolved by the satellite.







Fig. 3. Model evaluation with 16 NOMADSS flights (top row) and with 21 SEAC⁴RS flights (bottom
row). Note that only cloudy skies are considered. The comparison is performed for the averaged vertical
profiles of JNO₂ for the (a) NOMADSS and (d) SEAC⁴RS. The gray horizontal lines indicate the
standard deviations from the observations. Histogram of ratio of JNO₂ simulated by the model to JNO₂
observed (b) in the CNTR simulation and (c) in the GOES simulation for the NOMADSS. (e and f) are
the same as (b and c), respectively, but for the SEAC⁴RS.

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Fig. 4. Horizontal distributions of cloud optical depth at 13 LST (= 19 UTC) 8 July 2013 (a) in the control simulation and (b) in the GOES simulation. Horizontal distributions of O_3 at 13 LST 8 July 2013 at the lowest model level (shaded) (d) in the control simulation and (e) in the GOES simulation. The circles indicate EPA ozone measurements. (c and f) Difference in JNO₂ and O₃, respectively, between the simulations (i.e., control simulation minus GOES simulation). (g, h, and i) Time series of



- 752 O₃ at the square (Chicago, IL), circle (La Porte, IN), and star (Holland, MI) that are marked in (f),
- respectively.
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Fig. 5. (a) Spatial distribution of 8-h average O_3 at the lowest model level averaged over the whole analysis period in the CNTR simulation. (b) Difference in 8-h average O_3 at the lowest model level between the control and GOES simulations (i.e., CNTR minus GOES).

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Fig. 6. Spatial distributions of (a) PAR change and (b) isoprene emission from biogenic sources between EMIS_BVOC and GOES simulations, (EMIS_BVOC–GOES)/GOES, averaged over the period of 3–12 July 2013. Difference in O₃ (c) between the CNTR and GOES simulations and (d) between EMIS_BVOC and GOES simulations.







Fig. 7. (a) Probability density function of 8-h O_3 bias (model value minus observation value) for VOClimited regime under cloudy sky conditions defined with COD threshold of 20. (b) Same as (a), but for NO_X-limited regime. (c) Median values of 8-h O_3 bias with respect to COD threshold in the CNTR simulation (solid lines with cross marks) and in the GOES simulation (dashed line with triangles) for VOC-limited (purple color) and NO_X-limited regimes (green color). (d) Difference in median values of 8-h O_3 bias between the two simulations with respect to COD threshold (i.e., CNTR minus GOES).







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Fig. 8. (a) Net chemical production of O_3 , (b) OH concentration, and (c) HO_2 concentration with variations of cloud optical depth for VOC-limited regime. The black line indicates the median and cyan shading indicates the 25 and 75 percentiles. Similar variables are shown for the NO_X -limited regimes (d, e, and f).

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Fig. 9. Results of box modeling for production and loss rates of ROx (= $OH + HO_2 + RO_2$) radicals. "Others" in the legend indicates the photolysis of VOCs and reactions between alkenes and O₃. The value of 1 of normalized Jvals on *x*-axis indicates the photolysis rates for clear sky conditions.