1 Method to calculate the aerosol asymmetry factor based on measurements from

2 the humidified nephelometer system

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11 Abstract

The aerosol asymmetry factor (g) is one of the most important factors for assessing direct aerosol 12 radiative forcing. However, little attention has been paid to the measurements and parameterization of 13 g. In this study, the characteristics of g are studied based on field measurements over the North China 14 Plain by using the Mie scattering theory. The results show that calculated g values for the dry aerosol 15 can vary over a wide range (between 0.54 and 0.67). When ambient relative humidity (RH) reaches 16 90%, g is significantly enhanced by a factor of 1.2 due to aerosol hygroscopic growth. For the first 17 time, a novel method to calculate g based on measurements from the humidified nephelometer system 18 is proposed. This method can constrain the uncertainty of g within 2.56% for dry aerosol populations 19 and 4.02% for ambient aerosols, where the aerosol hygroscopic growth has been taken into account. 20 Sensitivity studies show that aerosol hygroscopicity plays a vital role in the accuracy of predicting g. 21

### 22 **1 Introduction**

In addition to aerosol optical depth and aerosol single-scattering albedo, the aerosol phase function is the most important factor for assessing direct aerosol radiative forcing (DARF) (Andrews et al., 2006;Russell et al., 1997). The Henyey-Greenstein phase function ( $PF_{HG}$ ) is a widely used method to parameterize the phase function (Toublanc, 1996;Boucher, 1998;Pandey and Chakrabarty, 2016) because it uses the aerosol asymmetry factor (g) as the only free parameter. The  $PF_{HG}$  is expressed as

28 
$$PF_{HG}(\theta) = \frac{1-g^2}{(1+g^2 - 2g\cos\theta)^{3/2}}, (1)$$

29 where  $\theta$  is the angle between the incident light direction and the scattered light direction. In this

30 respect, the free parameter g can reflect the angular aerosol scattering energy distribution.

- 31 g is defined as:
- 32

$$g = \frac{1}{2} \int_0^{\pi} \cos \theta P(\theta) \sin(\theta) \, d\theta, \, (2)$$

where  $P(\theta)$  is the normalized scattering phase function. As a result, g can be a computationally 33 efficient parameter to replace the phase function in the study of aerosol radiative transfer properties 34 (Toublanc, 1996; Hansen, 1969; Boucher, 1998). This replacement proves to be useful and has been 35 widely accepted in previous researches (Hansen, 1969; Wiscombe and Grams, 1976; Sagan and Pollack, 36 1967; Andrews et al., 2006) but significant bias may arise in g-related PF<sub>HG</sub> when estimating 37 photo-dissociation rates (Toublanc, 1996) and aerosol radiative forcing effects (Boucher, 1998). Up to 38 now, there have been few studies that have assessed the deviation when replacing the ambient phase 39 40 function with the g-related PF<sub>HG</sub> (Pandey and Chakrabarty, 2016;Boucher, 1998;Wiscombe and Grams, 1976) and there is no study that uses field measurements of aerosol optical properties to estimate the 41 bias. Moreover, variations in g can influence the evolution of the atmospheric vertical structure 42 through its effects on the atmospheric radiative distribution. Kudo et al. (2016) also found that the 43 vertical profile of the asymmetry factor plays an important role in altering vertical variations in the 44 solar heating rate. Marshall et al. (1995) reported that a 10% overestimation of g can systematically 45 reduce aerosol climatic forcing by 12% or more. Andrews et al. (2006) found that a 10% reduction in g 46 would result in a 19% overestimation of atmosphere radiative forcing at the top of atmosphere (TOA). 47 An accurate estimation of g can greatly help improve the assessment of the aerosol radiative effect. 48

There are several methods available to derive the g of aerosol particles under the dry and ambient 49 condition respectively. Horvath et al. (2016) measured the phase function of aerosols, calculated the g 50 of aerosols, and found that the g-related PF<sub>HG</sub> can be used as a good approximation of the measured 51 phase function. Many works used the Mie model (Bohren and Huffman, 2007) to calculate the phase 52 function and proved its reliability (Andrews et al., 2006; Marshall et al., 1995; Shettle and Fenn, 53 1979;Bian et al., 2017). Comprehensive attempts have been made to relate g with the hemispheric 54 backscatter fraction (b). The value of b is the ratio of light scattered into the backward hemisphere 55 compared to total light scattered in all directions (Wiscombe and Grams, 1976;Andrews et al., 56 2006;Horvath et al., 2016), with the definition of 57

58 
$$\mathbf{b} = \frac{\int_{\pi}^{\pi} P(\theta) \cdot \sin\theta \cdot d\theta}{\int_{0}^{\pi} P(\theta) \cdot \sin\theta \cdot d\theta}.$$
 (3)

59 The main advantage of the backscatter ratio is that it can be measured with an integrating 60 nephelometer equipped with a backscatter shutter (Charlson et al., 1974).

The free parameter g varies significantly for different aerosol types and different seasons. In 61 previous study, the g values are studied mainly by using the Mie scattering theory and the measured 62 63 aerosol particle numbers size distribution (PNSD). D'Almeida et al. (1991) suggested that g at a wavelength of 500 nm ranges from 0.64 to 0.83 depending on the aerosol type and season. A mean 64 value of 0.67 at an ambient relative humidity (RH) was also recommended (D'Almeida et al., 1991). 65 Hartley and Hobbs (2001) reported a median g value of 0.7 for aerosols along the east coast of the 66 United States. Formenti et al. (2000) measured Saharan dust aerosol and found that the aerosol g 67 values ranged from 0.72-0.73. Biomass burning aerosols in Brazil had a low g value of 0.54 (Ross et 68 al., 1998). 69

Some works have studied the impacts of aerosol hygroscopic growth on the parameter g (Hartley and Hobbs, 2001;Kuang et al., 2015;Andrews et al., 2006) and found that variations in g with RH can have significant influences on aerosol radiative effects (Kuang et al., 2015;Kuang et al., 2016;Andrews et al., 2006). A parameterization scheme of g, that takes RH and aerosol hygroscopic growth into account, is necessary.

<sup>75</sup> When exposed to the ambient atmosphere, aerosols can grow by taking up water, which causes <sup>76</sup> their corresponding optical properties to change considerably. The  $\kappa$ -Köhler theory (Petters and <sup>77</sup> Kreidenweis, 2007) is widely used to describe the hygroscopic growth of aerosol particles by using a <sup>78</sup> single aerosol hygroscopic growth parameter ( $\kappa$ ) and the  $\kappa$ -Köhler equation, which is shown as

79 
$$\frac{RH}{100} = \frac{gf^3 - 1}{gf^3 - (1 - \kappa)} \cdot \exp\left(\frac{4\sigma_{s/a}M_{water}}{R \cdot T \cdot D_d \cdot gf \cdot \rho_w}\right), (4)$$

80 where  $D_d$  is the dry particle diameter; gf(RH) is the aerosol growth factor, defined as the ratio of the 81 aerosol diameter at a given RH to the dry aerosol diameter  $(D_{RH}/D_d)$ ; T is the temperature;  $\sigma_{s/a}$  is the 82 surface tension of the solution;  $M_{water}$  is the molecular weight of water; R is the universal gas 83 constant and  $\rho_w$  is the density of water. The aerosol hygroscopic growth parameter  $\kappa$  can be further 84 used to investigate the influence of aerosol hygroscopic growth on aerosol optical properties (Tao et al., 85 2014;Kuang et al., 2015;Zhao et al., 2017) and aerosol liquids water contents (Bian et al., 2014).

According to the Mie theory, g is associated with aerosol particle number size distribution, the 86 particle complex refractive index, the aerosol mixing state and ambient RH. At the same time, the 87 aerosol morphology has significant influence on g. Datasets from the humidified nephelometer system 88 can partially account for all of these factors. The humidified nephelometer system consists of two 89 parallel nephelometers, one of which measures dry aerosol scattering properties and the other measures 90 aerosol scattering properties under well-controlled RH conditions. This system can give the light 91 92 scattering enhancement factor (f<sub>RH</sub>), which is defined as  $f_{RH}(\lambda) = \sigma_{sca(\lambda)}/\sigma_{sca(\lambda)}$ , or the ratio of the aerosol scattering coefficient under given RH conditions to that under dry conditions. Each nephelometer can 93 provide a scattering coefficient ( $\sigma_{sca}$ ) and back-scattering coefficient ( $\beta_{sca}$ ) at three wavelengths (450, 94 525 and 635 nm).  $\sigma_{sca}$  can be used to calculate the aerosol scattering Ångstrom index, which reflects the 95 aerosol PNSD to some extent. In general, a larger value for the Ångstrom index always corresponds to 96 a smaller predominant aerosol size. Variations in  $\beta_{sca}$  and  $\sigma_{sca}$  can be used to deduce the aerosol BC 97 98 mixing state (Ma et al., 2012). At the same time, datasets from the humidified nephelometer system can also be used alone to measure the aerosol hygroscopicity and provide an overall hygroscopic 99 100 parameter  $\kappa$  (Kuang et al., 2017). In conclusion, measurements from the humidified nephelometer system might be used for estimating g under the given RH conditions. However, there is no clear 101 relationship between the measured datasets from the humidified nephelometer and g. The non-linear 102 influence of the above listed factors on g makes it difficult to parameterize the g. 103

Random forest machine learning model is a powerful technique that can be used for classification 104 105 and non-linear regression (Huttunen et al., 2016;Breiman, 2001;Hu et al., 2017). This model is a widely used nonparametric machine learning algorithm that has several strengths. First, it involves 106 fewer assumptions regarding the dependence between observations and outcomes when compared with 107 traditional parametric regression models. Second, strict relationships among variables are not needed 108 before implementing the random forest model. Third, this learning model requires much less 109 computing resource than deep learning. Finally, this model has very low risk of over fitting by 110 averaging over an ensemble of decision trees. Thus, the random forest machine learning model is used 111 112 in this work to study the calculation of g based on the datasets of the humidified nephelometer system.

In this study, the Mie scattering theory and field measurements over the North China Plain (NCP) are used to study the characteristics of g. Section 2 describes the related datasets used in this study. Details of the study on the characteristics of g and impacts of aerosol hygroscopic growth on g are shown in section 3.1. A new method, which is based on a random forest machine learning model, is introduced to calculate g in section 3.2. We also discuss the impacts of g variations on the uncertainties of DARF in section 3.3, and the corresponding results are presented in section 4.3. Section 4.1 gives the calculated characteristics of g and section 4.2 proves the feasibility of using the machine learning model to calculate g. At the same time, this method is validated by the ambient aerosol phase function measured with a charge-coupled device - laser aerosol detective system (CCD-LADS). Conclusions are in section 5.

## 123 2. Instruments and datasets

Datasets used in this study come from three field campaigns, which were conducted at three 124 different sites in the NCP. These three field measurements were conducted at Gucheng in Hebei 125 Province (Gucheng, 39°09' N, 115°44' E) from 15 October to 25 November in 2016, the AERONET 126 BEIJING\_PKU station in Beijing (PKU, 39°59' N, 116°18' E) from 21 March to 10 April in 2017, and 127 the Yanqi Campus of the University of Chinese Academy of Sciences (UCAS, 40°24' N, 116°40' E) in 128 the Huairou district, Beijing from 3 January to 27 January in 2016. Details of these locations are 129 shown in Fig. S1. The PKU station is located at the northwest of Beijing, between the 4<sup>th</sup> and 5<sup>th</sup> ring 130 road. It is 11km from the center of the Megacity Beijing, which is adjacent to Hebei Province and the 131 megacity Tianjin. In the above three cities, the industrial manufacturing has led to heavy air pollution. 132 Datasets for this location are representative of urban aerosols in the NCP. Gucheng is located between 133 two megacities (120 km from Beijing and 190 km from Shijiazhuang) of NCP and the pollution 134 conditions of Gucheng can be a good representation of the continental background in the NCP. Details 135 for the Gucheng station can be found at Kuang et al. (2017). The UCAS station is 60 km away from 136 the center of Beijing and is at the edge of the NCP, which makes it suitable for measuring the regional 137 pollution properties of the NCP (Ma et al., 2016). More details of the measurement sites are available 138 in section 1 of the supplementary materials. 139

Table 1 lists the information for the field campaigns and the datasets used in this study. During the campaigns, sampled aerosols that had an aerodynamic diameter of less than 10  $\mu$ m are selected by an impactor (Mesa Labs, Model SSI2.5) at the inlet. These aerosols are then dried to below 30% RH with a Nafion drying tube and then lead to each instrument. Aerosol PNSDs ranging from 3 nm to 10  $\mu$ m are measured by using the scanning mobility particle size spectrometer (SMPS, TSI Inc., model 3936) and an aerodynamic particle sizer (APS, TSI Inc., model 3321) with a temporal resolution of 5 min.

Black carbon (BC) mass concentrations are measured by a multi-angle absorption photometer (MAAP model 5012, Thermo, Inc., Waltham, MA USA) at UCAS and by an Aethalometer 33 (Hansen et al., 1984;Drinovec et al., 2015) at PKU and Gucheng. The aerosol  $\sigma_{sca}$  at wavelengths of 450 nm, 525 nm and 635 nm is measured by an Aurora 3000 nephelometer and the corresponding values are recorded every minute (Müller et al., 2011).

The f<sub>RH</sub> is measured by a self-constructed humidified nephelometer system. In this system, a 151 152 humidifier is used to control the RH of the sample aerosol and  $\sigma_{sca}$  is measured for each of the controlled RH. The sample aerosol is humidified through a Gore-Tex tube, which is surrounded by a 153 circulating water layer in a stainless steel tube. The RH is changed by changing the temperature of the 154 circulating water, which is controlled by the water bath and software. For each cycle, the RH points are 155 set to range from about 50% to about 90% over 45 minutes. For most of the cases, the aerosol PNSDs 156 are consistent over the cycle. These cycles of  $f_{RH}$  values are abandoned when the measured maximum 157 158 and the minimum  $\sigma_{sca}$  value are beyond the range of 1.4 and 0.6 times of the mean measured scattering coefficient of each cycle. The detail information of the humidified nephelometer is described by Kuang 159 160 et al. (2017).

Ambient aerosol phase function with a time resolution of 5 minutes is measured at UCAS by using a CCD-LADS. This system consists of a continuous laser, two charge-coupled device cameras and the corresponding fish eye lenses. The wavelength of the laser is 532nm and a quarter-wave plate was mounted in front of the laser emitter to change the polarization state of the laser from linear to circular. The CCD-LADS can measure the ambient aerosol phase function at a wide angular range of  $10-170^{\circ}$ with a high resolution of  $0.1^{\circ}$ . More details of the measurement system can be found at Bian et al. (2017).

#### 168 **3. Methodology**

## 169 **3.1** Calculating characteristics of g based on the Mie scattering theory $(g_{Mie})$

The Mie model (Bohren and Huffman, 2007) is applied to calculate the characteristics of  $g_{Mie}$ . When running the Mie model, aerosol PNSD, aerosol complex refractive index, BC mixing state and BC mass concentration are essential. Its results include aerosol phase function, and  $g_{Mie}$  can be calculated by the definition shown in formula 2.

Mixing states of the BC come from the measurements of the field measurements. From the work of Ma et al. (2012), the mixing states of BC in the NCP were presented as both core-shell mixed and externally mixed. Ma et al. (2012) provides the ratio of BC mass concentrations under an externally mixed state,  $M_{ext_BC}$ , to total BC mass concentration,  $M_{BC}$ , as follows:

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$$\mathbf{r}_{ext\_BC} = \frac{M_{ext\_BC}}{M_{BC}}.$$
 (5)

The mean value of rext\_BC=0.51 (Ma et al., 2012) is used in this study. The size-resolved 179 distribution of BC mass concentration is the same as that used by Ma et al. (2012). The K-Köhler 180 theory and the Mie scattering model are employed to calculate  $g_{Mie}$  under different RH conditions. 181 When the aerosol grows by taking up water, the BC is treated as a non-hygroscopic and insoluble core. 182 The real time value  $\kappa$ , which is derived from the measurement of  $f_{RH}$ , is used to account for aerosol 183 hygroscopic growth. For each RH value, the growth factor can be calculated based on formula 4. The 184 corresponding ambient aerosol PNSD at a given RH can be determined too by applying the  $\kappa$  and 185 186 formula 4. The refractive index  $(\tilde{m})$ , which accounts for water content in the particle, is derived as a volume mixture between the dry aerosol and water (Wex et al., 2002a): 187

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$$\widetilde{m} = f_{V,dry} \ \widetilde{m}_{aero,dry} + (1 - f_{V,dry}) \ \widetilde{m}_{water}, (6)$$

where  $f_{v,dry}$  is the ratio of the dry aerosol volume to the total aerosol volume under a given RH condition;  $\tilde{m}_{aero,dry}$  is the refractive index for dry ambient aerosols and  $\tilde{m}_{water}$  is the refractive index of water.

The refractive indices of BC, non-light-absorbing aerosols and water, which are used in this study, are 1.8+0.54i (Kuang et al., 2015), 1.53+10<sup>-7</sup>i (Wex et al., 2002b) and 1.33+10<sup>-7</sup>i, respectively. Then, the corresponding g values under the given RH and PNSD can also be calculated. More details on using the Mie model to calculate the aerosol phase function for different RH conditions can be found in Zhao et al. (2017).

# 197 3.2 Calculating g by using the random forest machine learning model $(g_{ML})$

In this study, the random forest machine learning model from the Scikit-Learn machine learning library (Hu et al., 2017;Pedregosa, 2011) was used to calculate g. The random forest model has two parameters: the number of input variables ( $n_{pre}$ ) and the number of trees grown ( $n_{tree}$ ). In this study, the  $n_{pre}$  and  $n_{tree}$  are determined by minimize the relative difference of the  $g_{ML}$  and  $g_{Mie}$ . Details of choosing the values of  $n_{pre}$  and  $n_{tree}$  are shown in section 2 of the supplementary. The  $n_{pre}$  and  $n_{tree}$  are set as eight and thirty-two in this study, respectively. The eight input parameters include the three dry scattering coefficients, three dry backscattering coefficients, RH and  $\kappa$ . 205 The measured datasets are divided into two parts: one as the training data for the random forest model, and the other as the testing data. All training datasets come from field measurements at 206 207 Gucheng station, whereas the datasets from PKU are employed to test the accuracy of the model. With split datasets from different sites, the feasibility of the random forest model in the NCP can be 208 guaranteed. Before calculating  $g_{Mie}$ , we compare the measured  $\sigma_{sca}$  from the dry nephelometer and 209 calculate  $\sigma_{sca}$  from the Mie scattering model. These data, where the relative difference between the 210 211 measured and calculated  $\sigma_{sca}$  is within 30%, are used for the following analyses. With this, the inaccuracy form the measurement of the instruments can be avoided to some extent. More details 212 regarding the used data are shown in section 3 of the supplementary material. 213

To further avoid the uncertainties of the measurements when training the random forest machine 214 learning model, both the required input parameters and the predictors, g values, come from the 215 calculation of the Mie scattering model using the measurement of the aerosol PNSD and BC from the 216 217 field campaign of Gucheng. For each measured PSND and BC, the corresponding  $\sigma_{sca}$  and  $\beta_{sca}$  under dry condition at the wavelength of 450nm, 525nm and 635nm are modeled based on the Mie theory. 218 219 With the concurrently measured  $\kappa$  values from the humidified nephelometer, the g<sub>Mie</sub> values under different RH can be determined too. Then the modeled  $\sigma_{sca}$ ,  $\beta_{sca}$  under dry condition, the  $\kappa$  values and 220 the RH are used as the input data for the model and the corresponding g<sub>Mie</sub> values are used as the 221 prediction data. 222

#### 223 **3.3 Aerosol DARF estimations**

The earth-atmosphere systems can be significantly influenced by aerosols through the scattering and absorption of the energy. In this study, the Santa Barbara DISORT (discrete ordinates radiative transfer) Atmospheric Radiative Transfer (SBDART) model (Ricchiazzi et al., 1998) is employed to estimate the DARF. The characteristics of DARF with the variations in g are studied.

The instantaneous DARF is calculated at the TOA for cloud-free conditions. DARF is defined as the difference between radiative flux at the TOA under present aerosol conditions and aerosol-free conditions:

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$$\text{DARF} = (f_a \downarrow - f_a \uparrow) - (f_m \downarrow - f_m \uparrow), (7)$$

where  $(f_a \downarrow - f_a \uparrow)$  is the downward radiative irradiance flux with given aerosol distributions and  $(f_m \downarrow - f_m \uparrow)$  is the radiative irradiance flux under aerosol free conditions. The DARF at 50km is calculated because almost all of the aerosols are distributed within the height of 50 km in the parameterization scheme (Liu et al., 2009). The wavelengths in the range from 0.25 to 4  $\mu$ m are calculated for irradiance in this study.

237 Input data for the SBDART are listed below. Vertical profiles of the aerosol optical properties, which include the aerosol extinction coefficient ( $\sigma_{ext}$ ), aerosol single scattering albedo (SSA) and g. 238 They all have a vertical resolution of 50 m and come from the results of the Mie scattering and the 239 parameterized aerosol vertical distributions. Methods for parameterization and calculation of the 240 241 aerosol optical profiles can be found in section 4 of supplementary material or refer to Kuang et al. (2016) and Zhao et al. (2017). Atmospheric meteorological parameter profiles come from the results of 242 the intensive radiosonde observations at the Meteorological Bureau of Beijing (39°48' N, 116°28' E) 243 at the local time of 13:30 from July to September in 2008. Kuang et al. (2016) studied these measured 244 profiles and found that the vertical distributions of these parameters, which include profiles for water 245 vapor, pressure and temperature, can be used as a good representation of the meteorological parameter 246 247 profiles in the NCP during the summer. The corresponding measured mean results during field measurement are used in this study and the details of these profiles are shown in section 4 of the 248 249 supplementary material. Surface albedo values are obtained from the Moderate Resolution Imaging Spectroradiometer (MODIS) V005 Climate Modeling Grid (CMG) Albedo Product (MCD43C3). The 250 mean results of the surface albedo of Beijing from July to September in 2008 are used. The remaining 251 input data for the SBDART are set to their default values (Ricchiazzi et al., 1998). 252

253 4 Results and Discussion

# 254 **4.1 Characteristics of g<sub>Mie</sub>**

# 4.1.1 Characteristics of $g_{Mie}$ at different sites

Fig. 1 gives the statistical results for the calculated g properties at Gucheng, PKU and UCAS. The 256 RH at the three sites shows almost the same diurnal variation pattern in Fig. 1 (a) (b) and (c). The RH 257 reaches a peak in the morning at approximately 6:00 am, and then reaches its lowest value at 258 approximately 16:00 in the afternoon. However, the mean values of RH are 77.7%±20.9% at Gucheng, 259 47.8%±20.8% at PKU and 33.49±15.22% at UCAS. The  $g_{Mie}$  values under dry conditions that are 260 261 calculated by the measured PNSD have almost no diurnal patterns. The  $g_{Mie}$  values at PKU 262  $(0.614\pm0.025)$  are slightly lower than those at Gucheng  $(0.601\pm0.021)$  and UCAS  $(0.595\pm0.023)$  as shown in Fig. 1 (d), (e) and (f). The difference in  $g_{Mie}$  values results from different aerosol properties 263 at these sites. From fig. S6, the peak diameter of the mean and median PNSD at Gucheng locates 264

265 around 150nm. However, the peak diameter of the mean and median PNSD at PKU locates at around 100nm. The peak values of the mean and median diameter of the aerosol PNSD at UCAS locates at 266 around 60nm. At the same time, there are large partitions of small particles that are lower than 60nm at 267 PKU and UCAS. However, these particles, which are lower than 100nm, contribute little to the total 268 aerosol scattering. The aerosol PNSD at PKU is more dispersed than that of the Gucheng and UCAS, 269 which corresponds to a larger variation in the g values. From fig. S6 (h), (i) and (j), the size 270 271 distribution of the aerosol scatter coefficient at around 500nm contributes less to the scatter coefficient at PKU than at that of the Gucheng and UCAS. Thus these particles with the diameter larger than 272 500nm contribute more to the aerosol scattering coefficient. As  $g_{Mie}$  increase with the aerosol 273 diameter, the aerosol  $g_{Mie}$  under dry conditions at PKU tends to be larger than that at Gucheng and 274 UCAS. 275

However, ambient  $g_{Mie}$  values have different patterns at different sites, as shown in Fig. 1 (h), (i) 276 and (j). The  $g_{Mie}$  values have an RH-related diurnal pattern at Gucheng, with a mean value of 277 0.668±0.073, but show no diurnal variation at PKU and UCAS, where the mean values of  $g_{Mie}$  are 278 279 0.639±0.049 and 0.618±0.033, respectively. The variations of ambient g<sub>Mie</sub> values are mainly resulted from the variation of the aerosol hygroscopic growth under the ambient condition, which is highly 280 related to the ambient RH. The  $g_{Mie}$  value is significantly influenced by RH when the RH is higher 281 than 80%, which will be detailed in section 4.1.2. Ambient  $g_{Mie}$  values at Gucheng, PKU and 282 UCAS can vary from 0.57 to 0.8, 0.55 to 0.76 and 0.56 to 0.72 respectively, comparable to those of 283 Andrews et al. (2006), which range from 0.59 to 0.72. 284

#### 285 4.1.2 Influence of RH on g

286 To assess the influence of RH on g, the  $g_{Mie}$  values are calculated under different RH conditions for each aerosol PNSD. The statistical results of  $g_{Mie}$  versus RH are shown in Fig. 2. The  $g_{Mie}$  value 287 has a wide variation range between 0.54 and 0.67 with the mean value located at 0.61 under dry 288 conditions. However, the mean  $g_{Mie}$  value can change from 0.65 to 0.8 when the RH reaches 90%. 289 The  $g_{Mie}$  enhancement factor, which is defined as the ratio of  $g_{Mie}$  at a given RH and  $g_{Mie}$  under 290 291 dry conditions, can reach a mean value of 1.2 at an RH of 90%, which means that the  $g_{Mie}$  value under wet conditions is approximately 20% higher than that under the dry conditions. This finding is 292 consistent with that of Hartley and Hobbs (2001), who found that g is highly related to the RH. 293

294 Contrary to RH, the aerosol complex refractive index has little influence on g and the uncertainties 295 for g are less than 0.004 based on the Monte Carlo simulation of the g at different complex refractive 296 index values. More details of discussing the influence of aerosol complex refractive index on g can be 297 referred to insection 6 of the supplementary materials.

#### 298 4.2 Calculating $g_{ML}$ by using the machine learning model

#### 299 **4.2.1** Feasibility of using the random forest model

We establish two independent random forest machine learning models to predict  $g_{ML}$  values under dry conditions and under ambient RH conditions separately.

When the random forest machine learning model are run for g values under dry conditions,  $\sigma_{sca}$ and  $\beta_{sca}$  at three different wavelengths, are used as the input for independent variables. The other two input parameters, RH and  $\kappa$ , are set equal to zero. The predictor g values come from the results of the Mie scattering model. Fig. 3(a) shows the calculated  $g_{Mie}$  values and predicted  $g_{ML}$  values by the random forest machine learning model under dry conditions at the site of PKU. The results show that the  $g_{Mie}$  values and  $g_{ML}$  values have good consistency with an R<sup>2</sup> value of 0.98. There are 95% of the cases that the relative difference between  $g_{Mie}$  and  $g_{ML}$  are within the relative differences of 2.56%.

Fig. 3(b) shows the comparison of the predicted  $g_{ML}$  values under different RH conditions and  $g_{Mie}$  values calculated by the Mie scattering model. The correlation coefficient between  $g_{Mie}$  and  $g_{ML}$ reaches 0.93 and 95% of the relative differences are within 4.02%. The random forest model can be a good method to predict g values under different RH conditions with high accuracy and the uncertainties of predicting g values using the random forest machine learning model is estimated to be 4.02%.

The filled colors of the dots in Fig. 3 represent the concurrently measured  $\sigma_{sca}$ . It is shown that with an increase in  $\sigma_{sca}$ , g values tend to be larger, which is in accordance with the particle scattering properties. When a particle has larger diameters, the  $\sigma_{sca}$  of the particle is higher, and there tends to be a larger partition of forward scattering light.

Wiscombe and Grams (1976) studied the relationship between b and g and gave the expression between them as follows:

321  $g = -7.143889 \cdot b^3 + 7.464439 \cdot b^2 - 3.96356 \cdot b + 0.9893$  (8).

This equation is widely used to calculate g from b (Andrews et al., 2006;Horvath et al., 2016;Kassianov et al., 2007). We use the field measurement results to test its reliability. The

comparison results between calculated g values from the Mie scattering model and parameterized g values from equation 6 are shown in Fig.S9. From fig.S9, we can see that the parameterized g values are prevalently larger than the calculated g values by approximately 10%. When the  $\sigma_{sca}$  is smaller, the deviations become larger. Some other empirical relationships between b and g (Moosmüller and Ogren, 2017) are also tested. These parameterization scheme has almost the same result as Wiscombe and Grams (1976). This result means that the previously established parameterization scheme is not applicable in the NCP

# 331 **4.2.2 Sensitivity of the random forest model**

Sensitivity studies are carried out to assess the influence of each input variable on  $g_{ML}$ . Based on 332 the works of Müller et al. (2011), the uncertainties in total scattering are 4% (450nm), 2% (525nm), 5% 333 (635nm) for experiments with ambient air and laboratory generated white particles. For backscattering, 334 the differences are higher and amount 7% (450nm), 3% (525nm) and 11% (635nm). The uncertainties 335 336 of the measured RH by the RH sensors is 1.7% for RH ranges from 0 to 90% (Kuang et al., 2017) and the uncertainties of the derived  $\kappa$  values is 6% (Kuang et al., 2017). The Monte Carlo simulations are 337 338 conducted to study the sensitivities of the g<sub>ML</sub> to the input parameters in three steps. First, the mean results of the measured dry  $\sigma_{sca}$ , dry  $\beta_{sca}$ , RH and  $\kappa$  values are used to predict the g value. Second, the 339 dry  $\sigma_{sca}$  at 450 nm are randomly changed with a mean value of 0 and standard deviation of 4% and the 340 other input are kept unchanged as the input. The corresponding standard deviation of the predicted g 341 value is used as the sensitivities of the  $g_{ML}$  to the  $\sigma_{sca}$  at 450nm. At last, the sensitivities are carried out 342 343 accordingly for each of the input parameter. The uncertainties of g<sub>ML</sub> values to the input parameters are estimated. The total uncertainties of predicting g RH are derived when all of the input parameters are 344 randomly changed with their corresponding uncertainties. For each test, the Monte Carlo simulations 345 are carried out for 20000 times. 346

Table 2 gives the two time of the standard deviation of the  $g_{ML}$  values corresponding to the uncertainties of the input parameters. Form table 2, it is shown that the uncertainties of measured  $\sigma_{sca}$ has little influence of the  $g_{ML}$  with 0.487%, 0.492% and 0.486% for wavelength of 450nm, 525nm and 635nm respectively. However, the measurement of the three  $\beta_{sca}$  have larger uncertainties and lead to greater influence on predicting  $g_{ML}$  with 0.651%, 0.486% and 0.710%. The uncertainty of the RH has little influence on predicting  $g_{ML}$  with 0.487%. However, the uncertainty of derived  $\kappa$  values (6%) influence the g values most with 1.92%. The total uncertainties of predicting g due to the uncertainties

of the measurment is 1.95%. All in all, the total uncerntaities of predicting the  $g_{ML}$  is estimated to be 4.47% considering the 4.02% uncertainties of the random forest machine learning model from section 4.2.1.

#### 357 4.2.3 Validation of the random forest machine learning model

Datasets of the UCAS campaign are also used to validate the random forest machine learning model. On one hand, the  $g_{ML}$  values are calculated by using the random forest machine learning model with the measurements of the humidified nephelometer. On the other hand, ambient g values are calculated by using the measured phase function from the CCD-LADS  $g_{CCD}$  according to the definition shown in formula 2. Then the g values calculated with the two methods are compared.

Comparison results of these two kinds of g values are shown in fig. 4. Form fig.4, the values of 363  $g_{ML}$  and  $g_{CCD}$  show good consistence. There are 95% of the conditions that the relative differences 364 between the  $g_{ML}$  and  $g_{CCD}$  are in the range of 6.5% which is a little higher than the relative 365 366 difference of the g values (4.02%) between machine learning method and the Mie scattering method. During the period, the  $\sigma_{sca}$  range from 30 to 260 Mm<sup>-1</sup> which lead to cleaner conditions in UCAS than 367 368 in Gucheng and PKU. Correspondingly, most of the  $g_{Mie}$  values are small and locate at the range of 0.54 to 0.62 which are obviously lower than those in other campaigns. At the same time, the 369 surrounding condition at UCAS during the winter is relative dry, which results to small g values. These 370 conditions may partially explain the relatively higher difference between the  $g_{ML}$  and  $g_{CCD}$ . With this 371 validation, we conclude that the random forest machine learning model can give a reasonable g value 372 373 based on the measurements of the humidified nephelometer system.

#### 374 **4.3 Estimating the impacts of g on DARF**

#### 4.3.1 Uncertainties of replacing the calculated phase function with the PF<sub>HG</sub>

When the PF<sub>HG</sub> is used to parameterize the calculated phase function by using the Mie theory 376  $(PF_{Mie})$ , there are some deviations and the influence of these deviations should be estimated. The 377 relative difference between the DARF from the PF<sub>Mie</sub> and from the PF<sub>HG</sub> is used to estimate 378 uncertainties when using the PF<sub>HG</sub>. First, the PF<sub>Mie</sub> profiles are used as inputs to estimate DARFs. The 379 380  $PF_{Mie}$  is then replaced with the g-related  $PF_{HG}$  which is parameterized by  $g_{Mie}$  from the  $PF_{Mie}$ , and the DARFs are calculated again. These relative differences between the DARFs from the above two steps 381 are recorded and compared. The relative differences at different zenith angle conditions are calculated 382 to comprehensively estimate the influence of the PF<sub>HG</sub>. 383

Fig.5 shows the estimated DARFs at different zenith angles. In Fig. 5(a), DARF at the TOA can vary from -2.55 to -4.8 w/m<sup>2</sup>. When the PF<sub>Mie</sub> is replaced by the PF<sub>HG</sub>, the calculated DARF ranges from -2.6 to -5.1 w/m<sup>2</sup>. The relative difference of the DARFs between the two methods ranges from 1.3% to 7.1%, as shown in Fig. 5(b). It is concluded that using the g-related PF<sub>HG</sub> to replace the PF<sub>Mie</sub> to estimate aerosol radiative effects is applicable in the NCP, with a deviation of less than 7%.

#### 389 **4.3.2 Impacts of g variations on DARF estimation**

390 Variations in g can lead to significant changes in the estimated DARF (Kuang et al., 2016; Andrews et al., 2006; Mccomiskey et al., 2008). In this study, the uncertainties of the g values 391 from the input parameter is estimated to be 1.95% and the total variation in running the random forest 392 machine learning model is estimated to be 4.47%. At the same time, the g can varies about 10% for 393 different aerosol PNSD and can be enhanced by 20% with the increment of RH from 30% to 90%. It is 394 very important to know the extent of the variation in DARF corresponding to the uncertainties from g. 395 396 The variation in DARF from the uncertainties of g is calculated by increasing or decreasing g by 1.95%, 4.47%, and 10% to the original g values, and then comparing the corresponding DARFs with 397 398 the original ones. To study the influence of RH on g and DARF, the DARF with the g values calculated from the dry parameterized aerosol population profile, is estimated. 399

Fig. 6 shows the estimated DARFs with different variation in g and the corresponding variations in the estimated DARF. The results show that when g varies by 1.95%, the DARF can vary 4%. However, variations of 4.47% and 10% in g values can lead to variations in the estimated DARF with 9.4% and 21%, respectively.

The estimated DARF using the parameterized aerosol profile, which considers the aerosol hygroscopic growth, is smaller than the DARF using the g profiles from the dry aerosol population. The g values under dry condition are smaller than that of the wet ambient. Thus, there is larger partition of energy that is scattered forward which leads to less outgoing backscattering energy and a larger value of the estimated DARF.

When the DARF are estimated ignoring the impacts of aerosol hygroscopic growth on g, the relative difference can be as high as 20% for all of the zenith angles. Thus, it is necessary to consider the aerosol hygroscopic growth when calculating the g values.

412 5 Conclusions

The characteristics of g in the NCP are studied based on the Mie scattering theory and field 413 measurements from sites of Gucheng and PKU. The results show that  $g_{Mie}$  values are 0.604±0.025 at 414 Gucheng and 0.615±0.021 at PKU. The ambient  $g_{Mie}$  values at Gucheng show obvious diurnal 415 variations due to variations in RH. When the ambient RH reaches 90%, g<sub>Mie</sub> can be enhanced by 20% 416 and the g values from different aerosol population can vary 10%. Comparison of the calculated  $g_{Mie}$ 417 values from the Mie scattering model and the parameterized g values from the Wiscombe and Grams 418 419 (1976) method shows that the parameterized g is overestimated by approximately 10% and that the deviations are become larger when the measured  $\sigma_{sca}$  is below 200 Mm<sup>-1</sup>. 420

The random forest machine learning model and datasets from the humidified nephelometer are 421 employed to calculate  $g_{ML}$  values. The input data of the random forest model contain measured  $\sigma_{sca}$ 422 and  $\beta_{sca}$  at three wavelengths, RH and the hygroscopic parameter  $\kappa$ . Except for RH, all input data came 423 from measurements from the humidified nephelometer system (Kuang et al., 2017). The random forest 424 425 model can significantly improve the accuracy of  $g_{ML}$  prediction. The uncertainties of the predicted  $g_{ML}$  values are constrained within 2.56% under dry conditions and 4.02% under ambient conditions 426 427 and the uncertainties from the measurement of the humidified nephelometer can lead to a variation of 1.95% in g, which is mainly resulted from the inaccuracy of the derived  $\kappa$ . The total uncertainty of g 428 calculation using the random forest machine learning model is 4.47%. This is the first time that 429 machine learning model and datasets from the humidified nephelometer system are combined to study 430 g. At the same time, this method can accounting for the influence of aerosol hygroscopic growth on g. 431 This new method for calculating g is validated by comparing the  $g_{ML}$  values from the random 432

forest machine learning model and the  $g_{CCD}$  values from the measured phase function by using the CCD-LADS. The g values with this two methods show good consistence with 95% of the data within the relative difference of 6.5%.

SBDART model is used to study the impacts of g on DARF. We first studied the relative differences between the estimated DARFs by using the  $PF_{HG}$  and the calculated phase function by using the Mie theory, the measured mean aerosol PNSD and BC mass concentration at the site of Gucheng and PKU. The results show that the relative differences in DARF can be contained within 7.1% when replacing the  $PF_{Mie}$  with g-related  $PF_{HG}$ . The  $PF_{HG}$  can be a feasible parameterization scheme to study DARF in the NCP. The sensitivity study shows that the maximum uncertainties of DARF are 4%, 9.4% and 21%, which correspond to the uncertainties of the g from the instrument measurement, the machine learning model and the variation of aerosol PNSD. However, when the DARF are estimated ignoring the effects of aerosol hygroscopic growth on g, the relative differences of the DARF is as large as 20% for all of the zenith angles. It is necessary to parameterize the g accounting for the effect of aerosol hygroscopic growth.

448 This work can further our understanding of the role of g in the aerosol radiative effects and can449 help reduce uncertainties in estimating DARF.

450

451 *Data availability*. The measurement data involved in this study are available upon request to the 452 authors.

453

454 *Competing interests.* The authors declare that they have no conflict of interest.

455

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Field informa	Datasets and instruments						
Location	Time period	PSND	BC	$\sigma_{sc}$	f <sub>RH</sub>	Phase function	
Gucheng, Hebei (39°09' N, 115°44' E)	15 Oct to 25 Nov, 2016	SMP, APS	AE33	Aurora 3000	Humid ified Nephelometer	None	
PKU, Beijing (39°59' N, 116°18' E)	21 Mar to 10 Apr, 2017	SMPS, APS	AE33	Aurora 3000	Humid ified Nephelometer	None	
UCAS, Beijing (40°24' N, 116°40' E)	3 Jan to 27 Jan, 2016	SMPS, APS	MAAP	Aurora 3000	Humidified Nephelometer	CCD- LADS	

Table 1. Field information, dataset information and instruments that are used in this study. 

Parameter	σ <sub>sca,450</sub>	$\sigma_{sca,525}$	σ <sub>sca,635</sub>	βsca,450	βsca,525	βsca,635	RH	κ	total
Parameter(%) <sup>*1</sup>	4	2	5	7	3	11	6	6	
g(%) <sup>*2</sup>	0.487	0.492	0.486	0.651	0.487	0.710	0.486	1.920	1.950

575 **Table 2.** The sensitivities of g to the input parameters.

\*1. The uncertainties of the measured parameters.

\*2. The uncertainties of g values due to the uncertainties of the measurement parameters.



**Figure 1.** (a)(b)(c) Average diurnal pattern of RH, (d)(e)(f) g values calculated from dry aerosols, and (h)(i)(g) g values from ambient aerosols. The panels (a), (d) and (h) are the results from Gucheng. Panels (b), (e) and (i) are the results from PKU. Panels (c),(f) and (g) are the results of UCAS. The box and whisker plots represent the 5<sup>th</sup>, 25<sup>th</sup>, 75<sup>th</sup> and 95<sup>th</sup> percentiles.



**Figure 2.** Probability distributions of g under different RH conditions. The ticks on the left show g values at different RH values, and the ticks on the right show the g enhancement factor, which is defined as the ratio of g at a given RH to the g value at dry conditions (RH=30%). The solid line (cyan) shows the mean result of g values and the enhancement factor at different RH values.





**Figure 3.** Comparison of calculated g values (g<sub>Mie</sub>) from the Mie model and predicted g values (g<sub>ML</sub>)

from the random forest model under (a) dry conditions and (b) ambient conditions at the site of PKU.

595 Colored dots represent the concurrently measured  $\sigma_{sca}$  corresponding to the time of g.



Figure 4. Comparison of the calculated g values (g<sub>CCD</sub>) from the CCD-LADS measured phase function
and the calculated g values (g<sub>ML</sub>) by using the random forest machine learning model.



599

**Figure 5.** (a) Estimated DARFs at different zenith angles when using the g-related  $PF_{HG}$  (dotted line) and the phase function calculated by using the Mie scattering theory (solid line). (b) The relative

602 difference between the DARFs in (a).

603



**Figure 6.** The variation in DARF when g varies by a range of 1.95% (the filled dark color), 10% (grey color), and 20% (light grey color). Different line styles represent the corresponding mean relative differences in DARF compared to the original value.