

Title: “Arctic Regional Methane Fluxes by Ecotope as Derived Using Eddy Covariance from a Low Flying Aircraft”

by Sayres et al.

General Comments

The main question addressed by the research is the feasibility of regional-scale airborne measurements of the turbulent methane flux. The goal is to provide land-cover resolved methane fluxes that permit placing continuous tower measurements in a regional context. For this purpose a land cover filter based on space-domain decomposition is applied to the airborne methane flux observations, which are subsequently recomposed by target land cover. The authors conclude that airborne eddy covariance presents an affordable way to directly measure and express surface fluxes across inaccessible regions.

The central questions of the research are interesting and important, and have great potential for closing substantial gaps in the presently available hierarchy of environmental observations. While the presented dataset is a treasure trove, the contribution of the paper to the field is incremental at best. This is due to the application of a conceptually flawed analysis tool to the data:

The chosen flux fragment method disregards a fundamental micrometeorological underpinning that permits relaxing what is formally a continuity equation to a single “eddy covariance” term: Atmospheric turbulence needs to be sampled from the high-frequency dissipation range to the first low-frequency spectral gap (e.g., Foken, 2008). As mentioned by the authors, the latter would necessitate the analysis of several kilometres of flight data at once. Nevertheless, the authors revert to the use of 60 meters at a time, thus disembodimenting a few numbers at a time from their theoretical foundation (here: discarding the spatially varying “base state”). Superior space-frequency decomposition techniques are widely available and in use (e.g., Barnhart et al., 2012; Strunin and Hiyama, 2004; Thomas and Foken, 2005; van den Kroonenberg and Bange, 2007). These are not only theoretically sound, but provide better spatial resolution down to meters and do not suffer from the loss of low-frequency contributions.

Next, relating atmospheric fluxes to discrete land cover classes alone neglects intra-class variability (e.g., Beyrich et al., 2006; Ogunjemiyo et al., 2003). This is better expressed with continuous land cover properties such as temperature, vegetation indices etc. (e.g., Glenn et al., 2008; Ogunjemiyo et al., 1997). In addition, FFM results for individual land covers are not comparable across flight days, as day-to-day synoptic variations and different flight times within the diurnal cycle are not taken into account. Moreover, FFM acts as a filter reducing the use of available data by order 50%, i.e. it is wasteful with respect to data use efficiency. As a result of these shortcomings, Figures 4, 7 show that at a 5% significance level the FFM-derived fluxes do not actually differ between land cover classes, i.e. there is more unexplained variation in the error bars than there is explained variation in the land cover means. Also here, techniques

overcoming these systemic deficiencies are available and in use (Jung et al., 2011; Yang et al., 2007)

Hence, to remedy current methodological deficiencies, and to arrive at scientifically more useful and defensible results from this great dataset, I suggest the authors to consider a combination of above methodologies. In fact in their introduction the authors cite Metzger et al. (2013), who demonstrate such combination specifically for the use case of airborne flux measurements.

In consequence, with the current methodology the results only peripherally contribute to the question and do not fundamentally support the conclusions.

The manuscript fits the scope of Atmospheric Chemistry and Physics. The length of the article is appropriate, writing is sufficiently concise and copy-editing is not needed to evaluate scientific merits. While the manuscript is publishable in general I recommend major revisions due to substantial methodological deficiencies.

Specific Comments

Please find specific in-text comments in appendix.

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Arctic Regional Methane Fluxes by Ecotope as Derived Using Eddy Covariance from a Low Flying Aircraft

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Abstract. The Arctic terrestrial and subsea permafrost region contains approximately 30% of the global carbon stock and therefore understanding Arctic methane emissions and how they might change with a changing climate is important for quantifying the global methane budget and understanding its growth in the atmosphere. Here we present measurements from a new in situ flux observation system designed for use on a small, low-flying aircraft that was deployed over the North Slope of Alaska during August of 2013. The system combines a small methane instrument based on Integrated Cavity Output Spectroscopy (ICOS) with an air turbulence probe to calculate methane fluxes based on eddy covariance. We group surface fluxes by land class using a map based on LandSat Thematic Mapper (TM) 30 meter resolution data. We find that wet sedge areas dominate the methane fluxes with a mean flux of $2.1 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ during the first part of August, with methane emissions from the Sagavanirktok river being the second highest at almost $1 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$. During the second half of August, after soil temperatures had cooled by 7°C , methane emissions fell to between 0 and $0.5 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ for all areas measured. We compare the aircraft measurements with an eddy covariance flux tower located in a wet sedge area and show that the two measurements agree quantitatively when the footprints of both overlap. However, fluxes from sedge vary at times by a factor of two or more even within a few kilometers of the tower demonstrating the importance of making regional measurements to map out methane emission spatial heterogeneity. Aircraft measurements of surface flux can play an important role in bridging the gap between ground-based measurements and regional measurements from remote sensing instruments and models.

1 Introduction

Methane is the third most important greenhouse gas after water vapor and carbon dioxide and its concentration in the atmosphere has increased from a pre-industrial value of 0.7 parts per million by volume (ppmv) to its current value of approximately 1.85 ppmv. Methane sources are varied, with major contributors being anthropogenic (including fossil and agricultural) as well as natural. Often multiple sources occur in the same vicinity, for example emissions from gas wells collocated with agricultural fields or pasture for grazing livestock. In the past few years there have been increased efforts to understand how methane emis-



sions, as well as carbon dioxide, might change from the Arctic region in response to warmer temperatures (Yvon-Durocher et al., 2014; Sturtevant et al., 2012; Sturtevant and Oechel, 2013; Walter et al., 2007b, and references therein). For example, temperatures in the Alaskan North Slope have increased 0.6 °C per decade for the last 30 years. Likewise, in that same time period the minimum extent of Arctic sea ice at the end of the summer has decreased from 8 million km² to 5 million km².

5 Late summer sea ice extent until this past century was 10 million ± 1 million km² over the past 1500 years (Kinnard et al., 2011). Global methane concentrations have also varied during this time period, with atmospheric increases slowing down in the 1990s, leveling off in the early part of the 21st century and then increasing again since 2007 with concentrations reaching 1.8 ppmv in 2010 based on several surface based observation networks (Kirschke et al., 2013). It has been postulated that the increase could be from Arctic wetlands (Koven et al., 2011; Walter et al., 2007b). A brief look at the carbon stock in the Arctic
 10 reveals why it has garnered so much attention. The Arctic permafrost region contains between 1330 and 1580 Pg of carbon in the surface layer (0-3 meters depth), Yedoma region and rivers. An additional quantity is contained in deeper deposits and subsea permafrost (Tarnocai et al., 2009). Arctic carbon stock represents about a third of the total global surface carbon pool and increases to 50% when accounting for the deeper soils (Schuur et al., 2015). As the climate continues to warm, this carbon is vulnerable to thaw and decomposition by microbes, potentially leading to large increases in methane and carbon dioxide
 15 emissions. Particularly important are organic carbon stocks in permafrost reduced anaerobically to methane, as the latter has a warming potential more than twenty times larger than carbon dioxide on a 100-year time scale which increases over shorter time periods (Boucher et al., 2009). The release of methane and carbon dioxide from northern wetlands and ocean clathrates in response to a warming Arctic exhibits strong evidence in the paleoclimate record (Zachos et al., 2008; Whiticar and Schaefer, 2007). It is also supported by current observations of methane release from thermokarst lakes formed from melting Arctic
 20 permafrost each spring and summer (Sepulveda-Jauregui et al., 2015; Walter et al., 2007b; Bastviken et al., 2004; Casper et al., 2000), from ebullition from deep sea sediments (Shakhova et al., 2014; Reagan et al., 2011; Damm et al., 2010), and from airborne campaigns (Wofsy, 2011; Chang et al., 2014).

The North Slope of Alaska is covered by several different land classes though dominated by permafrost and the interior is mostly accessible only by airplane or helicopter with the exception of Prudhoe Bay which sits at the end of the Dalton
 25 Highway (Rt. 11) which extends from Fairbanks to Prudhoe Bay. The lack of infrastructure, especially roads, makes continuous ground based measurements difficult except near the major settlements, which in turn makes regional bottom-up estimates of carbon flux uncertain owing to the sparsity of data. At the same time top-down estimates based on inversion modeling rely on some knowledge of flux sources on the ground and lack the spacial resolution to discriminate which sources are dominating the emissions in areas like the North Slope where there are a multitude of broad-scale emitters and point sources. Airborne
 30 measurements, especially from low flying aircraft, have the potential to bridge the scale gap between process level studies on the ground and large scale regional estimates from remote sensing data or inversion modeling of concentration profiles. Flux measurements from low-flying aircraft coordinated with surface measurements allow for the detailed surface flux measurements to be extended to the larger regional scale by mapping the heterogeneity in the fluxes over these larger areas.

Eddy covariance is a direct way to determine the exchange of mass, momentum, and energy between the atmosphere and the
 35 surface. The covariance between turbulent wind and concentration is calculated directly from the individual variances from the



mean and as wind and concentration measurements can be routinely obtained, eddy covariance from the ground or towers is widely represented in the literature as a way of obtaining the flux of a quantity between the surface and atmosphere. Obtaining eddy covariance measurements from a moving aircraft presents some unique challenges including accurately measuring turbulent wind velocity relative to the ground and measuring concentration at high data rate (~ 10 Hz for a slow moving aircraft).

5 Even with these, in order for the flux from the aircraft to be a good proxy for a measurement taken at the surface, it needs to be sampled close to the ground, with the exact distance varying depending on boundary layer height, turbulence, and the footprint size of interest. Even with these difficulties, several groups have successfully measured carbon dioxide and heat flux from low flying aircraft in the Arctic (Zulueta et al., 2011; Oechel et al., 2000, 1998; Gioli et al., 2004), Europe (Bange et al., 2007; Vellinga et al., 2010; Hutjes et al., 2010; Gioli et al., 2006), Asia (Metzger et al., 2013), and continental US (Kirby et al., 2008; 10 LeMone et al., 2003; Avissar et al., 2009).

Here we present in situ methane fluxes taken during the summer of 2013 in the North Slope of Alaska. Using two different methods for calculating flux we show that airborne flux measurements can compare with tower measurements when attention is paid to properly overlapping the footprints of the airplane and the tower. We also derive fluxes from several different land classes and compare with estimates using more traditional ground based techniques.

15 2 Methods

To measure methane emissions over large areas of the North Slope, the Flux Observations of Carbon from an Airborne Laboratory (FOCAL) system was flown during August, 2013 out of Deadhorse Airport, Prudhoe Bay, AK. FOCAL, pictured in Fig. 1 flying near the NOAA Atmospheric Turbulence and Diffusion Division (NOAA/ATDD) flux tower, consisted of three main parts: the aircraft, a Diamond DA-42 from Aurora Flight Sciences, a turbulence probe, the Best Airborne Turbulence 20 (BAT) Probe from NOAA/ATDD, and a fast methane and water instrument from the Anderson Group at Harvard University. Data presented in the results section was obtained during six flights between August 13 and August 28 (Fig. 2 and Table 1). During three of these flights the aircraft made repeated passes near the NOAA/ATDD tower that was set up for comparisons. The other three flights were flown as grid patterns over large regional areas ($50 \times 50 \text{ km}^2$) to better sample the heterogeneity of different land types over a large region. These flights consisted of both profiles from the bottom of the boundary layer (~ 5 -10 25 m) up to ~ 1500 m altitude and long transects (~ 50 km) at low altitudes (< 25 m) that are used to access surface flux using eddy covariance.

2.1 FOCAL instrumentation

The airborne methane flux calculations rely on having fast (10 Hz) measurements of both turbulent wind velocity and dry-air mixing ratio with the two quantities being coordinated in time and space to better than the measurement time, which in this 30 case is 20 milliseconds. NOAA/ATDD developed the BAT probe in the 1990s as a pioneering low-cost solution for mobile atmospheric turbulence measurements (Crawford et al., 1996, 1993; Crawford and Dobosy, 1992). The BAT probe consists of a hemisphere, 15.5-cm in diameter, with nine pressure ports located at selected positions on the probe head. The vertical



and horizontal pairs of ports measure the differential pressure between them to calculate the angle of attack and side slip, respectively. Static pressure is taken as the average of the pressures measured at the four diagonal pressure ports correcting for the attack and sideslip angles. Dynamic pressure is measured as the difference between the pressure measured at the center hole and the static pressure, again correcting for small errors as the angles of attack and sideslip are not truly zero. These pressure

5 measurements are combined with a known model for flow over a hemisphere to determine three dimensional wind direction and speed relative to the probe. In order to get the velocity of the probe relative the ground a GPS/INS system located near the center of gravity (CG) of the aircraft and two GPS antennas, one located on the BAT probe and the other located on top of the main cabin, provide for the movement of the BAT probe relative to the aircraft and the aircraft relative to the Earth's surface (Crawford and Dobosy, 1997, 1992). Fluxes of trace gases are covariances between turbulent winds and fluctuations
 10 in gas concentration. The BAT probe was designed to accurately measure turbulent winds from a moving aircraft and, using accelerometers and GPS/INS, relate those winds to the surface. The BAT probe digitizes samples at 1600 Hz for low-pass filtering and subsampling at 50 Hz to suppress aliasing. The wind measurements are synchronized with the 50 Hz signal from the GPS/INS system. In calculating fluxes, the 10 Hz data from the spectrometers discussed below are interpolated to 50 Hz and synchronized with the data from the BAT probe.

15 The methane instrument draws air from an inlet located 8 cm aft of the BAT probe turbulence measurements. Flow of air through the axis is controlled by a dry scroll pump located in the back of the aircraft. Air from the inlet passes through 1.25 cm diameter tubes into the nose and forward luggage bay sections of the aircraft. The pressure of the air is controlled by a proportional solenoid valve and a pressure control board that uses pressure measured at the detection axis to feed back on the valve orifice position. The actual detection axis is located in the port side forward luggage bay. The methane instrument uses
 20 Integrated Cavity Output Spectroscopy (ICOS) to measure CH_4 , H_2O and N_2O (Witinski et al., 2011). The ICOS instrument uses a high finesse optical cavity composed of two high-reflectivity mirrors ($R = 0.9996$) to trap laser light for a period on the order of $2 \mu\text{s}$ producing effective path lengths 10^3 times the mirror separation. For the fast methane sensor used in this deployment a small ICOS cell (25 cm in length; 5 cm diameter mirrors) was built that combines the sensitivity and stability of ICOS with a small sample volume to attain high flush rates (17 Hz). Using the wavelength region around 1292 cm^{-1} ($7.74 \mu\text{m}$),
 25 measurements of methane achieved a precision of 7 ppbv ($1 - \sigma$, $1 - \sigma$). Due to the high variability of water in the troposphere, water vapor measurements are required with any trace gas measurements in order to quantify dilution effects caused by changes in water vapor content as well as changes to spectroscopic line broadening. Well defined absorption features of water vapor and its isotopologues as well as nitrous oxide are obtained in the same sweep of the laser, therefore the same instrument provides simultaneous measurements of nitrous oxide and water vapor along with methane. This technique provided extremely high
 30 signal to noise observations as well as a robust measurement in flight and has been the basis for several ICOS flight instruments built by this group (Witinski et al., 2011; Sayres et al., 2009; Engel et al., 2006; Paul et al., 2001). Periodic calibration in flight using calibrated gas cylinders were used to track drift over the course of the flight and from flight to flight. There were several other small instruments that augmented FOCAL's capabilities: a radar altimeter, for height above ground which is essential for accurate footprint calculations, and a visible camera, which provided a visual record of the terrain directly under the aircraft
 35 used to check the accuracy of remotely sensed products that are used for primary landscape classification.

Commented [Reviewer1]: •This hemispherical model requires calibration, in the case of very low-level flight in particular to offset dynamic upwash and ground effect which otherwise affect the covariance calculation (e.g., Crawford et al., 1996; Garman et al., 2008). Have these calibrations and corrections been performed, and if so to within which residual error?

•Crawford, T., Dobosy, R., and Dumas, E.: Aircraft wind measurement considering lift-induced upwash, *Boundary Layer Meteorol.*, 80, 79-94, doi:10.1007/BF00119012, 1996.
 •Garman, K. E., Wyss, P., Carlsen, M., Zimmerman, J. R., Stirn, B. H., Carney, T. Q., Santini, R., and Shepson, P. B.: The contribution of variability of lift-induced upwash to the uncertainty in vertical winds determined from an aircraft platform, *Boundary Layer Meteorol.*, 126, 461-476, doi:10.1007/s10546-007-9237-y, 2008.

Commented [Reviewer2]: •Please confirm that you use CH_4 dry mole fraction for the covariance / flux calculation.

•In case your calculation is based on partial density, how do you correct for density variations due to temperature and humidity fluctuations (WPL), as well as variations in pressure-altitude and corresponding changes in temperature and pressure, and thus partial density (Poisson equation)?



Aurora Flight Sciences' version of the DA-42, named the Centaur, is a twin-engine aircraft, and has several characteristics that make it an ideal platform for the work discussed here. Due to the twin engine configuration, the entire center fuselage is available for instrumentation and sampling. The Centaur is electrically and structurally well-adapted for carrying a sophisticated scientific payload, having ample spare power from its two alternators and ideally located hard points for the probe and the spectroscopic equipment. Finally, once fixed costs (e.g. aircraft access, instrument integration and certification) have been accounted for, the operating cost of the Centaur are just \$1500 per day and \$600 per flight hour - a substantial savings compared to many other scientific platforms.

2.2 Turbulence measurements

Eddy covariance is a direct way to determine the exchange of mass, momentum, and energy between the atmosphere and the surface. Since the observed flux is assumed to represent the exchange at the surface, the airplane is flown as low as is safely possible, typically below 30 m (Mahrt, 1998). Flux measurements from fixed surface sites, important complements to the airborne measurements, provide extended temporal coverage at selected locations as well as validation of the airborne flux measurements. The covariance of the dry-air mixing ratio of these gases (Webb et al., 1980; Gu et al., 2012) with the turbulent vertical wind component determines the flux as shown in Eq. (1) where the bar represents the average which defines the base state, ρ_a is the dry air density, w' is the departure of the wind from the base state, and c' is the analogous departure of the methane mixing ratio of dry air.

$$F = \overline{(\rho_a w') c'} \quad (1)$$

Unlike a stationary tower, measuring the turbulent vertical wind component from an airplane requires finding the small (vector) sum of the airspeed and the ground speed, two large, nearly canceling vectors. Since both vectors fluctuate rapidly and independently, many independent measurements must be made with precise synchrony at high accuracy and sample rate. Since turbulent fluctuations can be less than 0.1 m/s, the two large velocities must each be accurate within 0.1 m/s. Four samples define the minimum effectively resolvable turbulent eddy size, about 5 m at 60 m/s.

The Centaur uses a small Inertial Navigation System integrated with a GPS (GPS/INS) to report its ground-speed vector over the surface as well as its roll, pitch, and heading, all at 20 Hz. The low-frequency component of the Centaur's velocity is filtered to 1 Hz and extrapolated to the probe's location to mix with the high-frequency component measured directly at the probe. The airspeed vector (airflow relative to the probe) is determined from the distribution of induced pressure over the BAT probe's hemispherical surface. One static pressure and three differential pressures are taken over nine ports. From these four pressure measurements plus temperature come the five relative-flow parameters: ambient pressure, ambient temperature, and three components of the airflow relative to the probe. The dominant airflow component is along the airplane's longitudinal axis, approximately equal to the airplane's true airspeed.

Commented [Reviewer3]: •At 5 m above ground this is approximately the eddy wavelength contributing most to the turbulent vertical transport.

•Using the power law of spectral decay, for this platform the need for high-frequency spectral correction of the vertical turbulent flux would be minimal only at measurement heights of 50 m above ground and higher.

•As you are focusing on measurements below 25 m above ground, which high-frequency spectral correction did you use, and how large was the correction?



2.3 Methane Flux Measurements

2.3.1 Running Flux Method

The running flux method (RFM) (e.g. LeMone et al., 2003) is commonly used to analyze airborne fluxes. The RFM calculates the mean flux over a contiguous integration length (e.g., 3 km). As opposed to a stationary tower, which averages in time, the aircraft is moving over the landscape, so that fluxes are more appropriately averaged over distance. Here we use the same notation as Crawford et al. (1993)

$$F = \frac{\sum_{k=1}^N (\rho_a w)_k c_k V_k}{\sum_{k=1}^N V_k} \quad (2)$$

where ρ_a , w , and c are defined as in Eq. (1) and V is the airspeed of the aircraft. The sum is over N consecutive samples and the denominator is the spacial averaging length. For the analysis presented here we use a 3 km window that is moved by 1 km increments so that, unlike the normal practice with tower data, there is overlap between adjacent calculated fluxes to provide smoothed interpolation. The RFM quantitatively describes the relation between measured flux and underlying surface features of scales comparable to the averaging length or larger. This method works well as shown by LeMone et al. (2003) who found a 4 km moving average on the US Great Plains to be an appropriate compromise between uncertainty in flux estimation and resolution of landscape-scale heterogeneity. In the Arctic in 2013, the much smaller mixed layer depth gave rise to smaller turbulence scales. Ogive analysis of the frequency distribution showed 3 km to suffice as the integration distance (Berger et al., 2001). However, heterogeneity in the resulting flux estimates was large and repeated flight segments gave variable results likely due to changes in winds and sampling footprints and the scale of the underlying surface features being smaller than the integration length. Nevertheless, there was good agreement between methane fluxes calculated by the RFM using 3 km integration centered near the tower location and fluxes computed directly from the tower measurements (see sec. 3.1). However, given the small scale heterogeneity of surface features on the North Slope using the RFM limits the ability to separate out flux contribution from individual surface types.

2.3.2 Flux Fragment Method

The flux fragment method (FFM) (Kirby et al., 2008) uses a conditional sampling scheme whereby flux is compiled from many τ -second 'fragments' of flux of a quantity, such as methane, along a transect given by

$$f_i = \delta t \sum_{k=1}^n [(\rho_a w)_k c_k V_k]_i \quad (3)$$

$$L_i = \delta t \sum_{k=1}^n [V_k]_i \quad (4)$$

where n is the number of samples per second, δt is the sample interval, and everything else is defined as in Eq. (2) except that instead of summing over a large distance, such as 3 km, the sum is only over a few samples. In the case of the data presented here the fragments are 1 second sums ($\tau = 1$ second) of approximately 60 m length. The fragments, labeled f_i , do not constitute



a Reynolds average individually meaning an individual fragment is **not long enough to average over all the frequencies that are important for eddy transport**. Instead, they provide a meaningful flux estimate only in aggregate. Fragments can be grouped, for example, by surface class, determined from footprint estimation (Fig. 3). The sum over each group divided by the total length of all fragments in the group provides the mean flux from the associated surface class as given by

$$F_S = \frac{\sum_{i \in S} f_i}{L_i} \quad (5)$$

The FFM is most appropriate in a region that is heterogeneous on small scales (100 m to 3 km), but relatively homogeneous on large scales such that many instances of the surface class, or other classification used to group the fragments, are sampled during the flight (See Kirby et al. (2008) for the full description of the method). Initial assessments of the data presented here indicate that the FFM is well suited for application to the North Slope, where Arctic tundra is interspersed with thermokarst

lakes, bogs, fens and bare ground. First, land-cover data is classified using a current land-cover image at 100 m resolution or better (e.g. Landsat). We use this to establish transects at altitudes typically 10 m to 30 m above ground; low as safely possible. These are flown repeatedly and coordinated with eddy-covariance towers for validation and temporal continuity. The base state is then defined, representing in principle the deterministic (non-turbulent) mesoscale component of the flow. Flux fragments are calculated using 1 s sums of squares and cross products of departures from the base state. Finally, **a footprint model is applied** to estimate the level of influence of each surface type on each fragment which allows the fragments to be grouped by type having a predetermined probability of coming from a single surface type (see sec. 3.2 for examples of how FFM is used to interpret these data). We use the parameterization scheme described in Kljun et al. (2004) which uses a backward Lagrangian model (Kljun et al., 2002) for a range of heights, stability measures and other turbulence quantities that are measured from the aircraft. The flux estimate for each land surface type is the sum of the fragments in the associated group divided by their accumulated length. The number of fragments necessary to provide a robust result can be determined by bootstrap resampling (Kirby et al., 2008). For the data presented here 3 km or ~50 fragments suffice.

2.4 Land Surface Classification

The land surface on the North Slope can be divided into different classes based on dominant plant species, topography, soil content, and soil moisture. The North Slope Science Initiative (NSSI) has identified 24 classes based on Landsat Thematic Mapper (TM) 30 meter resolution land cover maps in conjunction with field surveys (Initiative, 2013). These classifications, assigned based on remotely sensed data, are good proxies for properties that have been shown to be primary drivers of methane production and emission such as water table height, soil content, and emission pathways such as sedge roots. The areas flown over by FOCAL were dominated by a mixture of wet sedge, mesic sedge - dwarf shrub, fresh water marsh, tussock tundra, and open water consisting of both lakes and rivers (Fig. 2). Open water is visible from the air and includes lakes of various sizes and origin and rivers but for this analysis excludes coastal waters. By definition in the tussock-tundra land class, shrubs more than 20 cm tall occupy less than 25% of the surface, and tussocks occupy more than 35%. The sites are cold, poorly drained and underlain by mesic to wet, silty to sandy mineral soils with a shallow surface organic layer surrounding the tussocks. Wet sedge sites are defined as those with sedge species accounting for more than 25% of the cover and Sphagnum for less than 25%.

Commented [Reviewer4]: •Correct, this method neglects low-frequency contributions to the vertical turbulent flux.
 •As mentioned above, Ogive analysis typically saturates at 100 - 1000 x measurement height.
 •How did you correct low-frequency loss and how large were the contributions to the flux?

Commented [Reviewer5]: •How was the turbulence statistics for a robust application of the flux footprint model calculated? A 1 s flux fragment has far too large random error to assume upstream isotropy of the wind field.

Commented [Reviewer6]: •This model is 1-D and does not resolve the cross-wind distribution of the influence area – how did you take this into account?
 •An updated 2-D version of this model is available (Kljun et al., 2015). Why was this model not used?
 •Kljun, N., Calanca, P., Rotach, M. W., and Schmid, H. P.: A simple two-dimensional parameterisation for Flux Footprint Prediction (FFP), Geosci. Model Dev., 8, 3695-3713, doi:10.5194/gmd-8-3695-2015, 2015.



Soils range from acidic to non-acidic, are saturated during the summer, and typically have an organic layer over silt or sand. Mesic sedge - dwarf shrub has shrubs less than 25 cm tall covering more than 25% of the area and sedge cover is also more than 25%. Soil surface is generally mesic, but sometimes wet and is calcareous to acidic. The fresh water marshes (FWM) are semi-permanently flooded, but some have seasonal flooding, and the water depth typically exceeds 10 cm. Soils are muck or mineral, and the water can be nutrient-rich.

We use land types, as defined by a remote measurement, as opposed to soil properties such as moisture, organic carbon content, temperature, etc. as the remotely based definition is most appropriate to comparing to larger regional scale models and satellites. It should be noted therefore that land type here is a proxy for general classifications of areas with different soil moisture and other properties which are likely the primary drivers of differences in methane emissions, though certain plants such as sedge have been shown to act as conduits for direct methane release from the soil to the atmosphere through the plants vascular system (Olefeldt et al., 2013).

2.5 Tower Measurements

Starting a few weeks before the flight campaign and throughout the month of August, a small portable flux tower was setup at 70.08545° North latitude, 148.57016° West longitude, just south of Prudhoe Bay off the Dalton Highway. During that time the tower recorded CO₂ flux, CH₄ flux, latent heat flux, sensible heat flux, air temperature, and incoming radiation. Soil temperature probes were also used to record soil temperature at 2-cm, 5-cm, 10-cm, and 20-cm depth at three different locations around the tower. The tower was situated in an area dominated by sedge grass, and the surrounding area's water table was frequently near the surface such that the surroundings were puddled and muddy, especially in late August 2013. On the NSSI map the area is labeled as wet sedge. Since low light and convective conditions are common on the North Slope of Alaska, data collected during still conditions do not provide reliable eddy covariance flux measurements. Consequently data where the standard deviation of the vertical wind speed was less than 0.1 m/s were removed from the final data set.

3 Results and discussion

3.1 Comparison between aircraft and tower fluxes

On three separate flights FOCAL flew along a transect near the flux tower affording the opportunity for direct comparison between methane flux measured by an eddy covariance tower and by eddy covariance from a moving aircraft. It also allowed for comparisons of methane flux from the ecotone of the tower, in this case wet sedge, with methane flux from sedge averaged over the 50 km transect of the aircraft to look at spatial heterogeneity in the flux from this land type. We present these comparisons with varying levels of footprint overlap and show quantitatively how proper overlap affects the agreement between the tower and aircraft data. On August 13, 25, and 27 the aircraft flew multiple transects in a nominally East-West direction near the tower (Fig. 2). Based on the forecast wind direction, the tracks were slightly south of the tower on August 13 and 25 and north of the tower on August 27. Figure 4 shows 30-minute mean methane fluxes as measured by the flux tower from August 12



to August 29. Fluxes at the tower site roughly correlate with soil temperature with the first half of August showing most 30-minute mean methane fluxes ranging from 1 to $2.5 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$, when soil temperatures at a depth of 10 cm were 10–14 °C, and the second half of August showing most 30-minute mean methane fluxes ranging from 0.5 to $1.3 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$, when soil temperatures at a depth of 10 cm were 3–6 °C. The observed temperature dependence is consistent with previous studies (e.g.

5 Yvon-Durocher et al., 2014). Aircraft methane fluxes for comparison with the tower were calculated by finding the closest point along each leg of the flight to the flux tower and taking a 3-km RFM centered at that point. The mean of the RFM fluxes for each flight are plotted over the 30-minute fluxes from the tower in Fig. 4 (orange circles). Also shown are the fluxes associated with four different land types sampled during the flights using the FFM to calculate flux. The 95% confidence intervals, using bootstrapping, for fluxes derived using RFM and FFM are shown in the three insets. Agreement between the aircraft and tower
 10 on August 13 and 25 are within the confidence intervals of the data, though the aircraft measures significantly less methane flux than the tower on August 27. On August 13 the methane flux from wet sedge (red line), as derived using FFM, agrees very well with the magnitude of the flux measured by the tower, which sits on a sedge site. However, on August 25 the flux from sedge is lower than the tower measurements and on August 27 is also lower, though closer to the tower flux than the flux calculated by RFM near the tower.

15 The differences between the flux measured by the tower and aircraft can be explained by looking at the aircraft footprints for the three flights. Figure 5 shows footprints for selected fragments from each day. On both August 13 and 25 the dominant wind direction was from the North, and the parts of the footprint with the highest probability of influence on the flux fragments (maroon points in Fig. 5) are over sedge. On August 27 the aircraft flew North of the tower as the winds were primarily from the East. While the aircraft footprints did overlap the tower footprint, the highest probability of influence for the fragments
 20 (>80%) was from lakes North-West of the tower. Lakes have been shown to be sporadic hot spots of methane ebullition, but at least at the time of flight these lakes showed very low methane emissions. It is clear that even with flight plans that take into account forecast wind direction, careful attention to footprints must be taken when comparing different measurements. Most importantly though, is that when there is reasonable overlap between tower and aircraft footprints, the flux measurements from the aircraft agree with the tower measurements adding another level of validation to the aircraft data.

25 Though the tower site was situated on wet sedge, the agreement between averaging sedge sites along the approximately 50 km transect of the aircraft and just looking at the sedge in proximity to the tower varied considerably throughout the course of the mission. During the period of consistent warmth in the beginning part of August, methane emissions from sedge averaged over the whole domain of the aircraft flight track agreed with the tower measurements (Fig. 4, inset (a)). During the latter half of August, as both the soil and air temperatures cooled, likely due to decreased insolation, the tower consistently measured almost
 30 twice as much emission as the aircraft (Fig. 4, insets (b) and (c)). Using the RFM to calculate 3 km mean fluxes along the flight transect, which is dominated by sedge, the tower location stands out as a hot spot for methane emissions as shown in Fig. 6. Emissions from the tower region are twice as large as those from the rest of the flight track consistent with the tower measuring almost twice as much as sedge. Though not shown, latent heat flux showed a similar pattern to that of methane. While we have soil temperature and moisture measurements only near the tower, it is possible that the tower was in a locally wet or warm
 35 spot leading to larger methane emissions than westward of the tower. This underscores the importance of coordinating local



measurements, such as with a tower, with larger scale measurements from an aircraft that can show the regional heterogeneity of methane fluxes associated with land classes that from remote measurements look the same.

3.2 Regional methane fluxes

During August, 2013 FOCAL measured methane flux from a variety of ecotopes across the North Slope. In order to distinguish the contribution to the total methane flux from individual land types, the data are filtered to only include flux fragments where 85% of the probability density comes from a single land class. Increasing this metric, increases the causal relationship between the calculated flux and a single land class, but reduces the number of footprints available for the analysis thus loosening the confidence interval. Varying this filter between 80% and 95% produces only a small effect on the quantification of flux from each land class. We find that 85% is a good compromise between singling out individual land classes while still retaining a large dataset. For the flight speed of the Centaur at low altitude and wind conditions during the flights, the footprint length for each 60-m fragment varied between 0.5 and 5 km, though the part of the footprint whose probability density of contributing more than 90% of the flux was only between 100 and 800 m. The above filter eliminates about half of the flux fragments from each flight. Of those, we limit the land classes to those where the total number of flux fragments is more than 50 fragments or an equivalent distance of 3 km. The flux fragments are summed and then divided by the total integration length for each land cover type (Fig. 7). Land cover type varies over the North Slope, so different flights sampled different types of terrain (see Table 1 and Fig. 2), with wet sedge being the most dominant and thus sampled on each flight. Other land cover classes such as bare ground, dwarf shrub, and low-tall willow were also observed but not with sufficient frequency to calculate a statistically significant flux. Prevalent near the tower site, which was sampled on August 13, 25, 27, were wet sedge, mesic sedge-dwarf shrub, some lakes, the Sagavanirktok (Sag) river, and fresh water marsh. Soil temperatures in mid-August varied by 1.5 °C with a mean soil temperature of 8 °C at 5 cm depth. By the end of August soil temperatures had dropped to a mean of 3 °C. Sedge showed the strongest correlation with soil temperature, with fluxes falling from $2.1 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ on August 13th to less than $0.5 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ by the end of August. This relationship held true for emissions from the Sag river with emissions falling from $1 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ to near 0. Lakes showed no trend though it should be noted that the number of lakes sampled on August 13 was small as indicated by the large 95% confidence interval. While data on August 13 was sparse for the other land classes sampled, during the latter half of August emissions from fresh water marsh and tussock tundra were similar to those from lakes and sedge.

Airborne measurements made during August, 2013 are consistent with findings from other studies. Olefeldt et al. (2013) reported sites dominated by sedge and wet soils having methane emissions ranging from 0.46 to $1.6 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ with a median value of $0.87 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ across multiple permafrost sites. Other studies at single locations fall into this same range. For example, Harazono et al. (2006) measured methane fluxes from a wet sedge site in Happy Valley, AK during August of 1995 ranging from 0.38 to $1.5 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ and Sturtevant and Oechel (2013) measured wet sedge near Barrow with emissions of $0.39 \pm 0.03 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ with short periods of higher emissions up to $1.1 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$. Emissions from mesic-sedge sites near the Sag river, though south of the areas measured by FOCAL, showed fluxes of 0.35 to $0.58 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ in the first half of August falling to 0.12 to $0.23 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ in the second half of August (Harazono et al., 2006).



Emissions from lakes tend to be more variable than the land classes with measured emissions from individual lakes ranging from 0.25 to $6.3 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ across various thermokarst and other lakes in the North Slope (Walter et al., 2007a; Sepulveda-Jauregui et al., 2015). These fluxes are reported as means over a year, so emission rates during short periods of time may be lower or higher for an individual lake. While FOCAL did not sample the same lakes as in the aforementioned studies, during the flights near the tower multiple passes over the same lakes allow emissions from individual lakes to be measured. On August 13, five lakes were sampled with sufficient frequency to produce a statistically significant flux ranging from 0 to $2.6 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$. On August 25 a single lake was measured with an emissions rate of $0.72 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$. On August 27 four lakes were measured with emissions ranging from 0.09 to $0.18 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$. These data are consistent with the rates measured by the above studies.

4 Conclusions

The FOCAL campaign during the summer of 2013 showed how methane fluxes could be successfully measured over large regions using airborne eddy covariance measurements from a small, low-flying aircraft. Comparing the airborne measurements to those of a tower showed that the data were quantitatively comparable when there was good overlap between the tower footprint and aircraft footprint. However, along the flight track local conditions dominated the flux especially in the transition season from summer to fall in late August. Comparing wet sedge at the tower site with wet sedge west of the tower showed a factor of two difference in methane emissions during the later half of August which underscores the importance of regional measurements as fluxes can have large dependence on spatial heterogeneity even over relatively short distances. During the middle of the summer fluxes from sedge were more homogeneous across the area flown.

Measurements of methane flux over the North Slope of Alaska in August showed a strong correlation with soil temperature consistent with previous studies. Wet sedge showed the highest persistent methane emissions with mean fluxes about $2 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ in the first half of August falling to $0.2 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ in the latter half of August. Emissions from the Sag river showed a similar trend, while other land surface classes were not sampled enough during the first half of August to provide a statistically significant sample. Individual lakes sampled near the tower showed a large range of emissions varying from near 0 to $2.6 \mu\text{g} \cdot \text{m}^{-2} \cdot \text{s}^{-1}$ consistent with the range of lake emissions reported in the literature.

Aircraft measurements of surface flux can play an important role in bridging the gap between ground-based measurements and regional measurements based on inversion modeling or downwind-upwind differences. While airborne campaigns are generally more costly than ground based measurements, using small aircraft these costs can be minimized and for areas that are logistically challenging to access, such as the North Slope, airborne eddy covariance presents the easiest and least expensive way to directly measure surface fluxes regionally with large coverage.



5 Data Availability

All data is publically archived at the NSF ACADIS website (<http://articdata.io>) under citation: David Sayres. 2014. Collaborative Research: Multi-Regional Scale Aircraft Observations of Methane and Carbon Dioxide Isotopic Fluxes in the Arctic. NSF Arctic Data Center. urn:uuid:58bddf69-74fe-4a20-958e-4cd23bb6941f.

Commented [Reviewer7]: •There is no such website.
Where can the data (incl. raw data) be accessed?

- 5 Acknowledgements. This work was supported by NSF Grant 1203583 and data is archived at the ACADIS website. The authors wish to gratefully acknowledge the efforts and exceptional flying of our pilot, Bernard 'Bernie' Charlemagne, without whom these data could not have been collected.



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Figure 1. Picture of the FOCAL system flying near the NOAA/ATDD flux tower in North Slope, AK.

Table 1. Flights used in the analysis along with location, time of day, mean air temperature, and surface land classes.

| Flight Date YYMMDD.# | Location | Start Time UTC-10 | End Time UTC-10 | Temperature ¹ (°C) | Dominant Land Types ² |
|-------------------------|--------------|----------------------|--------------------|-----------------------------------|---|
| 130813.2 | Tower | 08:19 | 10:22 | 16 | Sedge, Mesic Sedge, Lakes, Sag river, FWM |
| 130825.1 | Tower | 17:43 | 19:49 | 5 | Sedge, Mesic Sedge, Lakes, Sag river, FWM |
| 130827.1 | Western Grid | 09:40 | 13:00 | 6 | Sedge, FWM, Lakes, Tussock tundra |
| 130827.2 | Tower | 16:46 | 20:02 | 10 | Sedge, Mesic Sedge, Lakes, Sag river, FWM |
| 130828.3 | Western Grid | 08:39 | 11:39 | 11 | Tussock tundra, Lakes, Lake margins are FWM and Sedge |
| 130828.4 | Eastern Grid | 13:59 | 15:44 | 16 | Sedge, Mesic Sedge, Lakes, River, FWM |

¹ Temperature calculated as mean temperature recorded by instrument during flight time and below 100 m. ² Land classes are given in order of largest percent coverage first.

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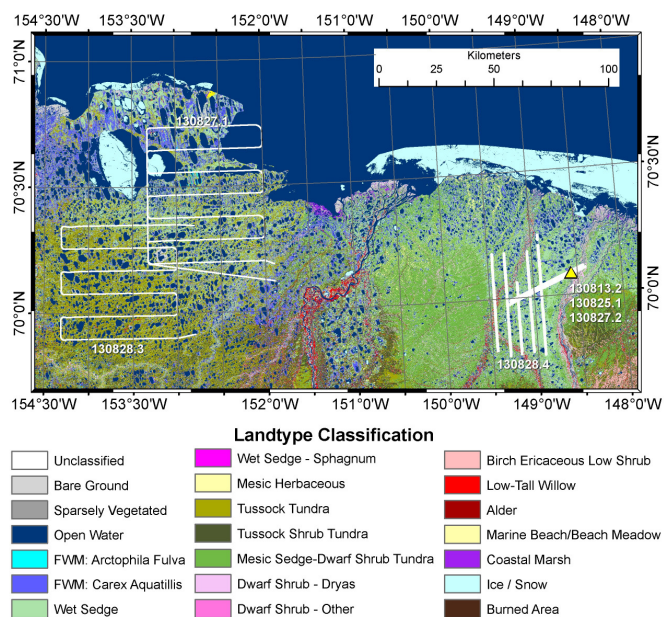


Figure 2. Six flight tracks flown by FOCAL during August, 2013 are shown in white. Dates given in the figure as YYMMDD.#, where # stands for the flight number for that day. Flight tracks shown are only for portions of the flight below 25 m above ground. Flight tracks are displayed over a false color, land cover map produced from LandSat 30 m Thematic mapper data with land types assigned by the NSSI as described in the text. Yellow triangle gives position of the NOAA/ATDD flux tower.

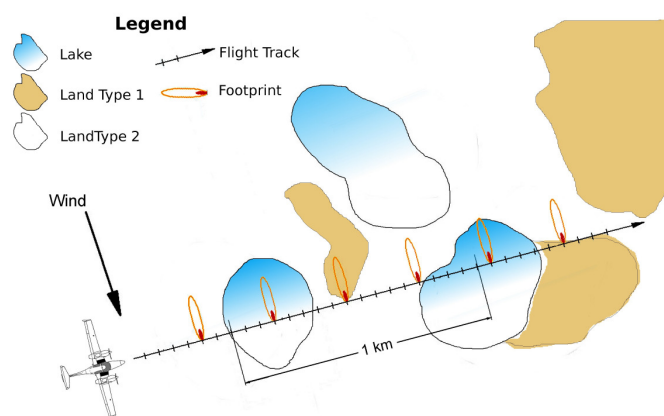


Figure 3. The Flux Fragment Method (FFM) relies on dividing up the covariance measurements into small fragments whose footprints can be attributed to different landscape features or classes. In the figure the landscape has been divided into lakes and two types of land, for example wet sedge and fresh water marsh. Footprints are calculated for each fragment and footprints that lie mostly (>85%) on a single land type are labeled as that land type. All footprints for a single land type can then be summed and divided by the cumulative path length in air.

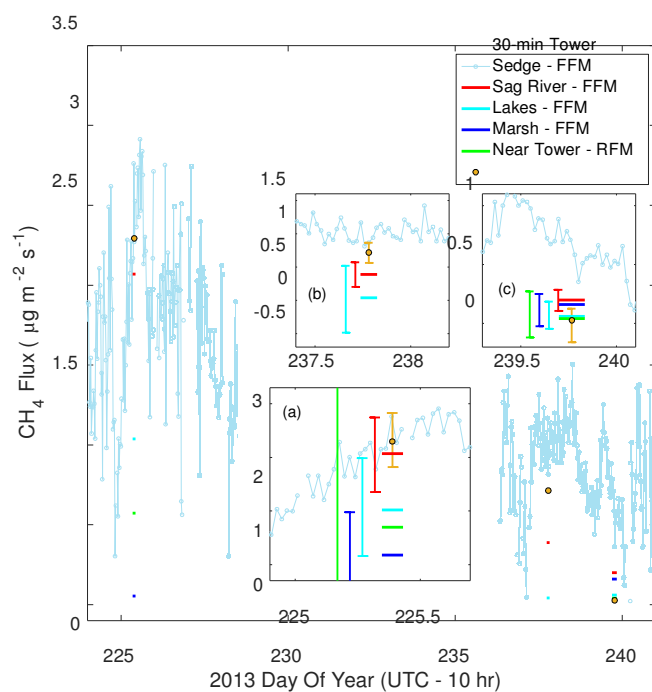


Figure 4. Comparison of methane flux measured by the flux tower with fluxes measured by the FOCAL system. Tower methane fluxes are 30-minute means plotted versus day of year. Three flights (Aug. 13, 25, and 27) made repeated flight transects near the tower. A running mean flux using the nearest 3 km of flight track to the tower for each leg was calculated and the mean of these fluxes is plotted for each day as an orange circle. Fluxes for sedge, marsh, lakes, and the Sag river were calculated using FFM using data from the whole flight and are plotted for each day, color coded according to the legend, with the length of the line along the time axis representing the time over which the data were taken. Insets (a), (b), and (c) show details for each flight day with bars showing the 95% confidence interval based on bootstrap analysis. Bars are offset along the x-axis for clarity.

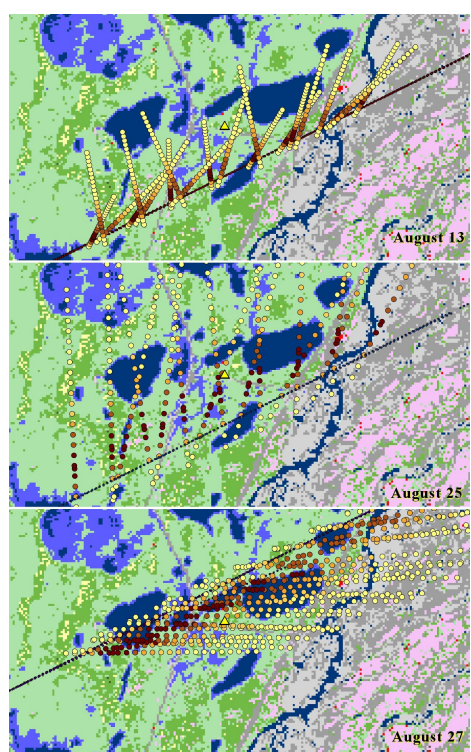


Figure 5. Map of area surrounding the flux tower (yellow triangle) with false color map representing different land classes defined as in Fig. 2. The flight track for each flight is shown as black points, where each point is the start position of a flux fragment. Flux footprints for selected fragments are shown as colored dots with darker and redder dots representing larger probability of contribution to the total flux as described in the text.

Commented [Reviewer8]: •There are more intuitive ways to visualize the footprint influence area. I am wondering why the authors did not use standard contour plots. Also, it is not apparent from the display whether cross-wind dispersion has been taken into consideration – the individual sequences of dots simply extend in the along-wind direction, which is only half the truth.

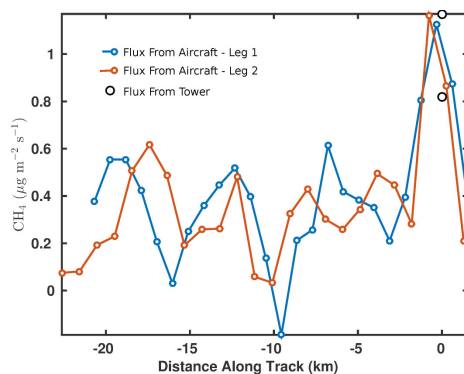


Figure 6. Plot of methane flux derived using RFM versus distance from flux tower for two flight legs on August 25. Positive (negative) distance is East (West) of the tower position. The East to West transect (blue) was flown 30 minutes after the West to East transect (orange). Black circles are the methane flux measured by the tower at the nearest time to when the aircraft passed the tower.

Commented [Reviewer9]: •Nice display of the tower being biased high in terms of spatial representativeness.

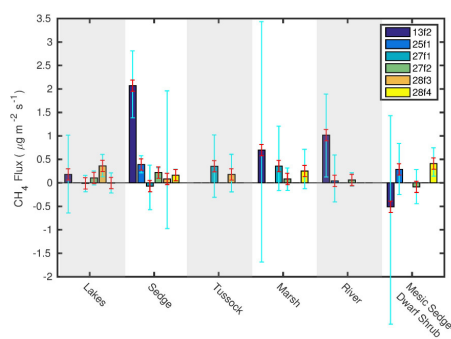


Figure 7. Methane fluxes by land surface class derived using the FFM for each of six flights as given in the legend. Dates of flights are given as day of month in August followed by the flight number for that day. Bars give the instrument uncertainty (red) and the 95% confidence interval as calculated using bootstrapping (blue).