

# Improving volcanic ash simulations with the HYSPLIT dispersion model by assimilating MODIS satellite retrievals

Tianfeng Chai, Alice Crawford, Barbara Stunder, Michael J. Pavolonis, Roland Draxler, and Ariel Stein

## Response to Reviewers' comments

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### Responses to the comments of referee #1:

#### General comments:

*The paper "Improving volcanic ash predictions with the HYSPLIT dispersion model by assimilating MODIS satellite retrievals" by Chai et al. discusses the inversion results for the Kasatochi 2008 event [ash] using a combination of the HYSPLIT model, providing the TCMs, and MODIS satellite data. Although inverse modelling studies for volcanic eruptions following similar methodologies are not new, the results for this eruption and the sensitivity studies presented here provide useful information to the reader and therefore supports its publishing in ACPD.*

We thank the referee for thoroughly reading the manuscript and providing valuable comments. Point-by-point responses to the referee's specific comments are given below.

#### Specific comments:

- 1) *Page 2, first paragraph: although not strictly needed, it would be good that it includes additional references on the impacts on the aviation industry as well as references on the residence times of the fine ash fraction.*

The following two papers are added as the references on the impacts of volcanic ash on the aviation industry. In addition, three other papers (Wilson et al., 2011; Horwell and Baxter, 2006; Wilson et al., 2012) are included as the references on the other impacts of volcanic ash.

*Prata, A. J. and Tupper, A.: Aviation hazards from volcanoes: the state of the science, NATURAL HAZARDS, 51, 239–244, doi10.1007/s11069-009-9415-y, 2009.*

*Gordeev, E. I. and Girina, O. A.: Volcanoes and their hazard to aviation, HERALD OF THE RUSSIAN ACADEMY OF SCIENCES, 84, 1–8,*

Rose and Durant(2009) is included as a reference on the residence times of the fine ash.

*Rose, W. I. and Durant, A. J.: Fine ash content of explosive eruptions, J. Volcanol. Geotherm. Res., 186, 32–39, doi10.1016/j.jvolgeores.2009.01.010, 2009.*

- 2) *Page 5, line 13: how was the particle size distribution estimated? It would be good to know the rationale behind the selection of the four bins, their sizes and percentage of distributions. Is that based on measurements? Estimates from another study? Please comment or add reference. This may include a comment on why the largest one considered is 20  $\mu\text{m}$  in relation to the satellite sensitivities and what limitations will this pose when it is the whole fine ash fraction ( $< 63 \mu\text{m}$ ) that may potentially affect aviation.*

The particle size distribution was originally used in the NOAA ARL VAFTAD model based on aircraft samplings of Mount St. Helens and Redoubt Volcano ash clouds. Several grain size distributions were tested by Webley et al.(2009) and were found to cause little effect in ash cloud simulation. The following has been added to the manuscript.

*The same particle size distribution was originally used in the NOAA ARL VAFTAD model (Heffter and Stunder,1993). Webley et al.(2009) evaluated the sensitivity of the grain size distribution on the modeled ash cloud and found that this pre-defined distribution is sufficient for HYSPLIT volcanic ash simulation. MODIS effective particle radii ( $r_{eff}$ ) are retrieved to describe the ash particle size distributions. However,  $r_{eff}$  greater than 15–20 $\mu\text{m}$  are not retrieved since the retrievals cannot be performed reliably when  $r_{eff}$  exceeds 15 $\mu\text{m}$  (Pavolonis et al., 2013).*

*Heffter, J. and Stunder, B.: Volcanic ash forecast transport and dispersion (VAFTAD) model, Weather and Forecasting, 8, 533–541, doi:10.1175/1520-0434(1993)008<0533:VAFTAD>2.0.CO;2, 1993.*

*Webley, P. W., Stunder, B. J. B., and Dean, K. G.: Preliminary sensitivity study of eruption source parameters for operational volcanic ash cloud transport and dispersion models - A case study of the August 1992 eruption of the Crater Peak vent, Mount Spurr, Alaska, J. Volcanol. Geotherm. Res., 186, 108–119, doi:10.1016/j.jvolgeores.2009.02.012, 2009.*

- 3) *Section 2.1 and Section 2.5 line 26: it is clear that the observation uncertainties play a significant role in the inversion. It would be valuable to add more discussion on the uncertainties and errors in the observations in either of the sections (and explain how the estimate of the observational errors are assumed to be  $0.5 \times a_m + 0.3 \text{ g/m}^2$ ) with special emphasis on the cloud top since this parameter is used to define the three options for model to observations adjustment. This is obviously of importance for the*

*second option, where the cloud top is critical and fixes the only model level that will be used in the matching.*

The following has been added in Section 2.5 to provide explanation for the observational error assumption.

*Dubuisson et al. (2014) studied the remote sensing of volcanic ash plumes from SEVIRI, MODIS and IASI instruments. The total uncertainty in MODIS mass loading resulted from errors in the input atmospheric parameters such as ash layer altitude, particle size distribution, and particle composition was estimated to be  $\sim 50\%$ . Their inter-comparison among six satellite configurations shows a standard deviation of  $0.3 \text{ g/m}^2$  for the mean mass loading estimates. In this study, the observational errors are estimated using  $\epsilon_m = 0.50 \times a_m^o + 0.3 \text{ g/m}^2$ .*

*Dubuisson, P., Herbin, H., Minvielle, F., Compiègne, M., Thieuleux, F., Parol, F., and Pelon, J.: Remote sensing of volcanic ash plumes from thermal infrared: a case study analysis from SEVIRI, MODIS and IASI instruments, Atmos Meas Tech., 7, 359–371, doi10.5194/amt-7-359-2014, 2014.*

The following discussion on the cloud top uncertainties is added in the first paragraph in Section 2.3, after the second model-to-observation matching option is introduced.

*However, the retrieved cloud top heights are associated with uncertainties. Pavolonis et al. (2013) showed that the retrieved cloud top height had a low bias of  $0.77 \text{ km}$  relative to lidar. Crawford et al. (2016) compared MODIS cloud top height retrievals with CALIOP vertical profiles of the same event. In general, the MODIS top heights agree well with the top aerosol level indicated by CALIOP profiles but can be off by several kilometers. When CALIOP shows two levels of ash, the MODIS top height falls between them. In addition, the cloud top height retrievals typically lie in the middle of thick ash cloud layers rather than at the top (Pavolonis et al., 2013). To compensate for such uncertainties in ash cloud top height position, the third option is designed to integrate model volcanic ash concentrations over three model layers, i.e. from one layer below to one layer above the cloud top layer.*

*Section 2.3 and 3: the definition of the three options to match the model to observations clearly affects the results. It seems that using the three layers approach, whereby ash above the cloud top is allowed, improves the results. Have the authors considered using option 1 but also allowing that the layer above the cloud top is also considered?*

We tested such an option, among several others (such as integrating over all layers or 5 layers) that are not presented in the manuscript. Based on the tests where only G2 observations were assimilated, the results using this option is not significantly different

from the results using option 1. Although we decided to exclude this option mainly for brevity in presentation, we believe this option is worth further investigation in the future.

- 4) *Section 2.5, line 20. What is the basis for the selection of this a priori emission rate and vertical distribution?*

The constant value and uniform vertical distribution are for simplicity. The small *a priori* emission rate is chosen to avoid unrealistic release rates at time-locations that the observations do not provide any information to modify them. Explanation has been added to text, as shown below.

*For emission points at which the release generates no simulated ash corresponding to any of the assimilated observations, the first guesses remain unchanged. To avoid unrealistic release rates for such emission points, we chose a small constant emission rate of  $10^4$  g/hr ( $\approx 2.8 \times 10^{-3}$  kg/s) at all hours and layers as the first guess.*

- 5) *Section 3: before starting to discuss Figure 3 (line 14) please add (move) lines 24 to 25 so that the user knows what simulations (using GDAS or ECMWF data) the authors are referring to.*

This statement has been moved as suggested.

- 6) *Section 3, line 19: why do the authors finally use the a priori error variances of  $2.8 \times 10^{12}$  kg/s? I see no justification in the text and that would mean that either of the two error variances shown would be usable.*

The statement has been extended (shown below) to include a brief justification for the *a priori* error variances.

*Note that a larger a priori term with smaller a priori error variances in Equation 1 typically helps the minimization procedure in the emission inversion. Since the results using the two a priori errors are similar, the a priori error variances are set as  $\sigma_{ij} \approx 10^{12}$  g/hr ( $\approx 2.8 \times 10^5$  kg/s) in the following tests.*

- 7) *Section 4.2 and following: in line 29 the authors state that Stein et al. (2015b) estimated the uncertainties for the Rank to be of 0.1. However, in all the tables and most of the discussion is based on those numbers, we see the ranks (and all the statistical metrics) to have to significant decimals. How can then we judge the performance of the different MA, M0 and M1 options when often is the second decimal that varies?*

Stein et al. (2015b) estimated the uncertainties of the Rank as 0.08, 0.08, 0.09, 0.08, 0.11, and 0.07 for 6 different tracer releases. The uncertainties of the Rank for the current application could vary but they are not expected to be too different. Thus, two significant decimals are presented and a difference of smaller than 0.1 in Rank may still be significant. While we agree that the performance differences with MA, M0 and M1 options are mostly small, we carefully stated that the M1 option is “slightly better” than the other two options in both Abstract and Summary.

The statement on the uncertainties for the Rank has been clarified (shown below).

*Using HYSPLIT ensembles, Stein et al. (2015b) estimated the uncertainties of the Rank as 0.08, 0.08, 0.09, 0.08, 0.11, and 0.07 for 6 different tracer releases. The uncertainties of the Rank for the current application could vary but they are not expected to be too different.*

- 8) *Could the authors give a better justification of why the zero mass loading pixels correspond to infinite cloud top heights?*

“Infinite cloud top heights” were used to indicate that the modeled mass loadings integrated from surface to the highest level possible should yield zero mass loadings. As it can be ambiguous, the statement in Section 2.3 (2nd sentence of the 2nd paragraph), “This is equivalent to zero mass loading and infinite cloud top height”, is changed to “This is equivalent to zero mass loading for the entire atmospheric column at such a location.”

In addition, the first sentence in Section 4.3, “ash-free regions indicate zero mass loadings and infinite cloud top heights”, is changed to “ash-free regions indicate zero mass loadings for the entire atmospheric columns.”

- 9) *Comparing the simulations with assimilated data (including G2) to G2 observations does not provide real insight since we are comparing assimilated results with the data used in the assimilation procedure. I think it is more useful to base the discussion comparing with G3 onwards if G1 and G2 are assimilated and with G2 onwards if only G1 is assimilated.*

We agree that comparing model results with un-assimilated data will be more useful. In fact, most of the discussion is based on such comparison. For the same reason, no comparison with G1 is listed or discussed. As G2 is not assimilated in some cases, including the comparison with G2 still provides some insight. For instance, in Section 4.2 we found, “If only G2 observations were assimilated, the model performance would be expected to peak

when compared against G2. However, as both G1 and G2 observations are assimilated, this is no longer true.”

### **Technical corrections**

- 1) *Figure 2: please add in the caption that those are the TCMs obtained with the GDAS input data*

It has been added. Now the caption reads “Averaged TCMs using GDAS meteorological data with three different options ...”.