



1	Improving $PM_{2.5}$ forecast over China by the joint adjustment of
2	initial conditions and source emissions with an ensemble Kalman
3	filter
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7	
8	Abstract. In an attempt to improve the forecasting of atmospheric aerosols, the
9	ensemble square root filter algorithm was extended to simultaneously optimize the
10	chemical initial conditions and emission input. The forecast model, which was
11	expanded by combining the Weather Research and Forecasting with Chemistry
12	(WRF-Chem) model and a forecast model of emission scaling factors, generated both
13	chemical concentration fields and emission scaling factors. The forecast model of
14	emission scaling factors was developed by associating the time smoothing operator
15	with WRF-Chem forecast chemical concentrations. Hourly surface fine particulate
16	matter (PM <sub>2.5</sub> ) observations were assimilated over China from 5 to 16 October 2014.
17	A series of 48-h forecasts were then carried out with the optimized initial conditions
18	and emissions on each day at 0000 UTC and a control experiment was performed
19	without data assimilation. The results showed that the forecasts with the optimized
20	initial conditions and emissions typically outperformed those from the control
21	experiment. In the Yangtze River delta and the Pearl River delta regions, large
22	reduction of the Root Mean Square Errors (RMSEs) was obtained for almost the
23	entire 48-h forecast range attributed to assimilation. Especially, the relative reduction





in RMSE due to assimilation was about 40% at nighttime when WRF-Chem
performed comparatively worse. In the Beijing–Tianjin–Hebei region, relatively
smaller improvements were achieved in the first 24-h forecast.

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### 28 **1. Introduction**

Aerosol prediction by regional air quality model in heavy polluted regions is challenging due to many factors. In addition to the deficiency of chemistries, the uncertainties of primary and precursor emissions and the initial conditions (ICs) also limit the forecast accuracy. Data assimilation (DA), which is used to improve the ICs of aerosols and to optimize data on aerosol emissions, has been shown to be one of the most effective ways to improve the forecasting of aerosol pollution.

From the perspective of reducing the uncertainties in the ICs for aerosols, recent 35 efforts have focused on assimilating aerosol observations using optimal interpolation 36 (Collins et al., 2001; Yu et al., 2003; Adhikary et al., 2008; Tombette et al., 2009; Lee 37 38 et al., 2013) or variational (Kahnert, 2008; Zhang et al., 2008; Benedetti et al., 2009; Pagowski et al., 2010; Liu et al., 2011; Schwartz et al., 2012; Li et al., 2013; Jiang et 39 al., 2013; Saide et al., 2013) DA algorithms. Ensemble-based DA algorithms, such as 40 the ensemble Kalman filter (EnKF) (Pagowski and Grell, 2012) and the hybrid 41 variational-ensemble DA approach (Schwartz et al., 2014) have also been applied to 42 aerosol predictions. All these studies have shown that DA is one of the most effective 43 ways of improving aerosol forecasting through assimilating aerosol observations from 44 multiple sources (e.g. ground-based observations and satellite measurements) to 45 update the chemical ICs. 46

Numerous studies have used DA approaches to estimate or improve source
emissions. The EnKF is one of the most popular DA algorithms used to improve
estimates of aerosols and gas-phase emissions, such as NO<sub>x</sub>, volatile organic
compounds, and SO<sub>2</sub> (van Loon et al., 2000; Heemink and Segers, 2002; Barbu et al.,
2009; Miyazaki et al., 2014). Variational DA algorithms have also been applied to
constrain emissions of air pollution, such as black carbon, organic carbon, dust, NH<sub>3</sub>,





SO<sub>x</sub> and NO<sub>x</sub> (Hakami et al., 2005; Elbern et al., 2007; Henze et al., 2007, 2009; Yumimoto et al., 2007, 2008; Dubovik et al., 2008; Wang et al., 2012; Guerrette and Henze, 2015). These studies have indicated that DA can efficiently reduce the uncertainty in the emission inventories and lead to improvements in the forecasting of air quality (Mijling and van der A, 2012).

The optimization of chemical ICs and pollution emissions can improve aerosol 58 forecasts and therefore further improvements are likely to be achieved by 59 simultaneously optimizing the chemical ICs and emissions. Tang et al. (2011) 60 reported that the simultaneous adjustment of the ICs of O<sub>3</sub>, NO<sub>3</sub> and volatile organic 61 compounds and the emissions of NO<sub>x</sub> and volatile organic compounds produced 62 overall better performance in both the 1-h and 24-h ozone forecasts than the 63 adjustment of pure ICs or emissions. Miyazaki et al. (2012) reported that the 64 simultaneous adjustment of emissions and concentrations is a powerful approach to 65 66 correcting the tropospheric ozone budget and profile analyses.

We developed a system to adjust the chemical ICs and source emissions jointly within an EnKF system coupled to the Weather Research and Forecasting with Chemistry (WRF-Chem) model (Grell et al., 2005). We then applied this system to assimilate hourly surface PM<sub>2.5</sub> measurements over China in early October 2014.

The remainder of the paper is organized as follows. Section 2 describes this DA system in detail. Then the experimental designs are introduced in Section 3. Finally, the surface PM<sub>2.5</sub> observations assimilation results are presented in section 4 before concluding in section 5.

75

### 76 2. Methodology

### 77 2.1 Ensemble square root filter

The ensemble square root filter (EnSRF) algorithm was introduced by Whitaker and Hamill (2002) and its expansion to analyzing aerosol ICs was described by Schwartz et al. (2014). Following the notation of Ide et al. (1997), given an *m*-dimensional background model forecast vector  $\mathbf{x}^{b}$ , a *p*-dimensional observation vector  $\mathbf{y}^{o}$  and an operator **H** that converts the model state to the observation states, we expressed the





- variables as an ensemble mean (denoted by an over-bar) and a deviation from the mean (denoted by a prime). Thus, the ensemble mean  $\bar{\mathbf{x}}^a$  of the analyzed state  $\mathbf{x}^a$
- and the deviations  $\mathbf{x}^{\prime a}$  from the ensemble mean are updated separately by
- 86  $\bar{\mathbf{x}}^{a} = \bar{\mathbf{x}}^{b} + \mathbf{K}(\mathbf{y}^{o} \mathbf{H}\bar{\mathbf{x}}^{b}), (1)$

87 
$$\mathbf{x}^{\prime a} = \mathbf{x}^{\prime b} + \widetilde{\mathbf{K}}(\mathbf{y}^{\prime o} - \mathbf{H}\mathbf{x}^{\prime b}), (2$$

88 where **K** is the traditional Kalman gain matrix and  $\tilde{\mathbf{K}}$  is the gain used to update the

89 deviations from the ensemble mean. These are given by

90 
$$\mathbf{K} = \mathbf{P}^{\mathbf{b}}\mathbf{H}^{\mathrm{T}}(\mathbf{H}\mathbf{P}^{\mathbf{b}}\mathbf{H}^{\mathrm{T}} + \mathbf{R})^{-1} \quad (3)$$
$$\widetilde{\mathbf{K}} = \mathbf{P}^{\mathbf{b}}\mathbf{H}^{\mathrm{T}}\left[\left(\sqrt{\mathbf{H}\mathbf{P}^{\mathbf{b}}\mathbf{H}^{\mathrm{T}} + \mathbf{R}}\right)^{-1}\right]^{\mathrm{T}}\left(\sqrt{\mathbf{H}\mathbf{P}^{\mathbf{b}}\mathbf{H}^{\mathrm{T}} + \mathbf{R}} + \sqrt{\mathbf{R}}\right)^{-1}$$
91 
$$= \left(\mathbf{1} + \sqrt{\mathbf{R}/(\mathbf{H}\mathbf{P}^{\mathbf{b}}\mathbf{H}^{\mathrm{T}} + \mathbf{R})}\right)^{-1}\mathbf{K}, \quad (4)$$

92 where  $\mathbf{P}^{b}$  is the *m* \* *m*-dimensional background error covariance matrix and **R** is 93 the *p* \* *p* -dimensional diagonal observation error covariance matrix. In real 94 applications,  $\mathbf{P}^{b}\mathbf{H}^{T}$  and  $\mathbf{H}\mathbf{P}^{b}\mathbf{H}^{T}$  can be approximated using the background 95 ensemble; namely,

96 
$$\mathbf{P}^{\mathbf{b}}\mathbf{H}^{\mathrm{T}} = \frac{1}{N-1} \sum_{i=1}^{N} \mathbf{x}^{i} (\mathbf{H} \mathbf{x}^{i})^{T}$$
(5)

97 
$$\mathbf{H}\mathbf{P}^{\mathbf{b}}\mathbf{H}^{\mathrm{T}} = \frac{1}{N-1}\sum_{i=1}^{N}\mathbf{H}\mathbf{x}^{\prime \mathbf{b}}(\mathbf{H}\mathbf{x}^{\prime \mathbf{b}})^{T}.$$
 (6)

98 In equations (5) and (6), N is the ensemble size.

Note that for the joint analysis of ICs and emissions, the state vector **x** is the joint vector of the mass concentration **C** and the emission scaling factor  $\lambda$ , i.e.  $\mathbf{x} = [\mathbf{C}, \lambda]^{\mathrm{T}}$ . After each ensemble analysis, the ensemble forecasts were performed with the corresponding models to advance **C** and  $\lambda$  to the next analysis time. The forecast models are described in section 2.2.

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### 105 2.2 Forecast model

A forecasting model, M, was developed to forecast the emission scaling factors and
the aerosol control variables. This model combines the WRF-Chem model and the
forecast model of emission scaling factors.





110 2.2.1 WRF-Chem model

111 Version 3.6.1 of the WRF-Chem model (Grell et al., 2005) was used to forecast the

aerosol and chemical species. WRF-Chem is an online model with the fully coupled

113 chemical and meteorological components.

Most of the WRF-Chem settings were the same as those reported in Liu et al. (2011): the Goddard Chemistry Aerosol Radiation and Transport (GOCART) aerosol scheme coupled with the Regional Atmospheric Chemistry Mechanism for gaseous chemical mechanisms; the WRF single-moment five-class microphysics scheme; the Rapid Radiative Transfer Model longwave and Goddard shortwave radiation schemes; the Yonsei University (YSU) boundary layer scheme; the Noah land surface model; and the Grell-3D cumulus parameterization.

With respect to the emissions, the hourly prior anthropogenic emissions were based on the monthly regional emission inventory in Asia (Zhang et al., 2009) for the year 2006 interpolated to the model grid (40.5 km) for the lowest eight vertical levels. In order to keep objective for the prior anthropogenic emissions, no time variation was added. Thus, the hourly prior anthropogenic emissions were constant. The biogenic (Guenther et al., 1995), dust (Ginoux et al., 2001), dimethylsulfide and sea salt emissions (Chin et al., 2000, 2002) were calculated online.

128

129 2.2.2 Forecast model of scaling factors

As no suitable dynamic model was available to forecast the emission scaling factors, a
persistence forecasting operator served as the forecast model for the scaling factors,
similar to the method used by Peng et al. (2015) for CO<sub>2</sub> emission inversion. Figure
la shows the flowchart for the persistence forecasting operator M<sub>SF</sub>.

If the ensemble members of the updated chemical fields  $C_{i,t-1}^{a}$  and the forecast emissions  $E_{i,t-2}^{f}$  in the previous assimilation cycle are known, then the chemical fields  $C_{i,t}^{f}$  at time *t* can be generated via WRF-Chem (Figure 1b). The ensemble concentration ratios  $\kappa_{i,t}$ , (*i* = 1, ..., *N*) were then calculated using

138 
$$\mathbf{\kappa}_{i,t} = \mathbf{C}_{i,t}^{t} / \mathbf{C}_{t}^{f} (i = 1, ..., N)$$
(7)





- 139 where  $\overline{\mathbf{C}_{t}^{\mathrm{f}}} = \frac{1}{N} \sum_{i=1}^{N} \mathbf{C}_{i,t}^{\mathrm{f}}$  is the ensemble mean of the forecast.  $\mathbf{\kappa}_{i,t}$  are random
- 140 variables with a mean values of 1.
- 141 The ensemble spreads of  $\kappa_{i,t}$ , (i = 1, ..., N) may be small and therefore
- 142 covariance inflation was used to maintain them at a certain level:

143 
$$(\mathbf{\kappa}_{i,t})_{\text{inf}} = \beta \left( \mathbf{\kappa}_{i,t} - \overline{\mathbf{\kappa}_{t}} \right) + \overline{\mathbf{\kappa}_{t}}, (i = 1, ..., N)$$
(8)

144  $\beta = 1.5$  was chosen in this study.  $\overline{\mathbf{\kappa}_t}$  is the ensemble mean of  $\mathbf{\kappa}_{i,t}$ , and is equal to 1.

As the concentrations were closely related to the emissions and there was no suitabledynamic model available to forecast the emission scaling factors, the inflated

147 concentration ratios  $(\mathbf{\kappa}_{i,t})_{inf}$  served as the prior emission scaling factors  $\lambda_{i,t}^{p}$ :

148 
$$\lambda_{i,t}^{p} = (\mathbf{\kappa}_{i,t})_{inf}, (i = 1, ..., N)$$
 (9)

To incorporate the useful information from the previous times, the previous DA cycles' analysis scaling factors,  $\lambda_{i,t-M+1}^{a}$ ,  $\cdots$ ,  $\lambda_{i,t-2}^{a}$ ,  $\lambda_{i,t-1}^{a}$  and the prior scaling factor  $\lambda_{i,t}^{p}$  were used to estimate  $\lambda_{i,t}^{f}$  by the time smooth operator; namely,

152 
$$\lambda_{i,t}^{f} = \frac{1}{M} \left( \sum_{j=t-M+1}^{t-1} \lambda_{i,j}^{a} + \lambda_{i,t}^{p} \right), (i = 1, ..., N, j = t - M + 1, ..., t - 1)$$
 (10)

Here, *M* is the time window of the smooth operator. In this study, a value of M = 4 (hours) was chosen.

# 155 The ensemble members of the emissions were calculated according to

156 
$$\mathbf{E}_{i,t} = \boldsymbol{\lambda}_{i,t} \mathbf{E}_t^{\mathrm{p}}, (i = 1, ..., N), (11)$$

where  $\mathbf{E}_{i,t}$  is the *i*th ensemble member of the emissions for each grid at time t,  $\lambda_{i,t}$ represents the scaling factors and  $\mathbf{E}_t^{\rm p}$  is the prescribed emission, which can be obtained from the emission inventories.

160

## 161 **2.3 Data assimilation system**

- 162 2.3.1 State variables
- 163 The EnSRF algorithm was expanded to optimize the emissions of WRF-Chem.





172

164 For the GOCART aerosol scheme, the aerosol species include unspecified P25 (P25), sulfate (S), hydrophobic and hydrophilic organic carbon (OC1 and OC2, respectively), 165 hydrophobic and hydrophilic black carbon (BC<sub>1</sub> and BC<sub>2</sub>, respectively), dust in five 166 particle size bins (effective radii of 0.5, 1.4, 2.4, 4.5 and 8.0 µm; referred to as D<sub>1</sub>, 167  $D_2$ ,  $D_3$ ,  $D_4$  and  $D_5$ , respectively) and sea salt in four particle size bins (effective 168 radii of 0.3, 1.0, 3.25 and 7.5 µm for dry air; referred to as S1, S2, S3 and S4, 169 respectively). The PM2.5 observation operator was the same as that described by 170 Schwartz et al. (2012) and expressed as 171

 $\mathbf{y}^{f} = \mathbf{\rho}_{d} [\mathbf{P}_{25} + 1.375\mathbf{S} + 1.8(\mathbf{OC}_{1} + \mathbf{OC}_{2}) + \mathbf{BC}_{1} + \mathbf{BC}_{2}$  $+ \mathbf{D}_{1} + 0.286\mathbf{D}_{2} + \mathbf{S}_{1} + 0.942\mathbf{S}_{2}], (12)$ 

where  $\rho_d$  represents the dry air density, which is multiplied by the mixing ratios of aerosol species (in  $\mu g k g^{-1}$ ) to convert the units to  $\mu g m^{-3}$  for consistency with the observations. As reported by Schwartz et al. (2012), the state variables of the analysis of the ICs were the 15 WRF-Chem/GOCART aerosol variables.

177 From the perspective of the optimization of emissions, atmospheric inorganic aerosols are not only from the primary emissions, but also secondary process-178 179 chemical and thermodynamic transformations from the gas-phase precursors. Therefore, not only the primary sources of PM<sub>2.5</sub>, but also the sources of the gas-phase 180 precursors, need to be optimized. In this study, the sources of SO<sub>2</sub>, NO<sub>x</sub> and NH<sub>3</sub> 181  $(\mathbf{E}_{SO2}, \mathbf{E}_{NO} \text{ and } \mathbf{E}_{NH3})$ , which have a large impact on the distribution of PM<sub>2.5</sub>, were 182 also optimized in addition to the primary sources of PM<sub>2.5</sub>. Therefore, the four species 183 of emission scaling factors ( $\lambda_{PM2.5}$ ,  $\lambda_{SO2}$ ,  $\lambda_{NO}$  and  $\lambda_{NH3}$ ) were considered as the 184 185 state variables of the DA system in addition to the mass concentration of 15 aerosol variables. 186

The direct sources of  $PM_{2.5}$  include the unspeciated primary sources of  $PM_{2.5}$   $E_{PM2.5}$ , sulfate  $E_{SO4}$ , nitrate  $E_{NO3}$ , organic compounds  $E_{org}$  and elemental compounds  $E_{BC}$ ; all of them are given in two modes (the nuclei and accumulation modes, represented as i and j in the subscripts respectively) The ratios between the nuclei and accumulation modes were the same as in the suggested emission process for National Emission Inventory in WRF-Chem (Freitas et al., 2011). The formula of





sulfate and nitrate emissions in the model are as below:

194 
$$\mathbf{E}_{PM2.5i}: \mathbf{E}_{PM2.5j} = 1:4, (13)$$

195  $\mathbf{E}_{SO4i}: \mathbf{E}_{SO4j} = 1:4, (14)$ 

196 
$$\mathbf{E}_{\text{NO3i}}: \mathbf{E}_{\text{NO3i}} = 1:4, (15)$$

197  $\mathbf{E}_{SO4i} + \mathbf{E}_{SO4j} = a * (\mathbf{E}_{PM2.5i} + \mathbf{E}_{PM2.5j} - \mathbf{E}_{EC} - \mathbf{E}_{ORG}), (16)$ 

198 
$$\mathbf{E}_{\text{NO3i}} + \mathbf{E}_{\text{NO3j}} = b * (\mathbf{E}_{\text{PM2.5i}} + \mathbf{E}_{\text{PM2.5j}} - \mathbf{E}_{\text{EC}} - \mathbf{E}_{\text{ORG}}), (17)$$

199 where  $\mathbf{E}_{EC}$  represents elemental carbon and  $\mathbf{E}_{ORG}$  organic compounds, and a = 0.074 and b = 0.038 were chosen based on the internal emissions and 200 observational data. In the DA process, the first 6 species of direct sources of 201 emissions ( $\mathbf{E}_{PM2.5i}$ ,  $\mathbf{E}_{PM2.5j}$ ,  $\mathbf{E}_{SO4i}$ ,  $\mathbf{E}_{SO4j}$ ,  $\mathbf{E}_{NO3i}$ , and  $\mathbf{E}_{NO3j}$ ), which may have 202 larger uncertainties in heavy polluted events, were updated according to the variation 203 204 of  $\lambda_{PM2.5}$ .  $E_{PM2.5i}$  and  $E_{PM2.5i}$  were directly updated according to the variation in  $\lambda_{\text{PM2.5}}.$  The emissions  $(E_{\text{SO4i}},~E_{\text{SO4j}},~E_{\text{NO3i}}$  and  $E_{\text{NO3j}})$  were also updated according 205 to the variations in  $\mathbf{E}_{PM2.5i}$  and  $\mathbf{E}_{PM2.5i}$ . 206

207

### 208 2.3.2 Procedure for the DA system

Figure 1 (b) shows the workflow of the DA system. The steps in this workflow are asfollows.

211 (1) The persistence forecasting operator  $M_{SF}$  is applied to forecast the 212 background fields of the emission scaling factors  $\lambda_{PM2.5}^{f}$ ,  $\lambda_{SO2}^{f}$ ,  $\lambda_{NO}^{f}$  and  $\lambda_{NH3}^{f}$ . The 213 forecast chemical fields of P<sub>25</sub>, SO<sub>2</sub>, NO and NH<sub>3</sub> of the previous assimilation cycle 214 are used to create the prior emission scaling factors  $\lambda_{PM2.5}^{p}$ ,  $\lambda_{SO2}^{p}$ ,  $\lambda_{NO}^{p}$  and  $\lambda_{NH3}^{p}$ . 215 The background scaling factors are then generated using equation (10).

216 (2) The ensemble members of the emissions,  $\mathbf{E}_{PM2.5i}^{f}$ ,  $\mathbf{E}_{PM2.5j}^{f}$ ,  $\mathbf{E}_{SO2}^{f}$ ,  $\mathbf{E}_{NO}^{f}$  and 217  $\mathbf{E}_{NH3}^{f}$ , are prepared according to equation (11). The corresponding emissions of  $\mathbf{E}_{SO4i}^{f}$ , 218  $\mathbf{E}_{SO4i}^{f}$ ,  $\mathbf{E}_{NO3i}^{f}$  and  $\mathbf{E}_{NO3i}^{f}$  are obtained based on equations (14–17).

219 (3) Forced by the changed emissions  $(\mathbf{E}_{PM2.5i}, \mathbf{E}_{PM2.5i}, \mathbf{E}_{SO2}, \mathbf{E}_{NO}, \mathbf{E}_{NH3},$ 





220  $\mathbf{E}_{SO4i}$ ,  $\mathbf{E}_{SO4j}$ ,  $\mathbf{E}_{NO3i}$  and  $\mathbf{E}_{NO3j}$  were substituted by  $\mathbf{E}_{PM2.5i}^{f}$ ,  $\mathbf{E}_{PM2.5j}^{f}$ ,  $\mathbf{E}_{SO2}^{f}$ ,  $\mathbf{E}_{NO}^{f}$ , 221  $\mathbf{E}_{NH3}^{f}$ ,  $\mathbf{E}_{SO4i}^{f}$ ,  $\mathbf{E}_{SO4j}^{f}$ ,  $\mathbf{E}_{NO3i}^{f}$  and  $\mathbf{E}_{NO3j}^{f}$ ; the other emissions such as  $\mathbf{E}_{EC}$  and  $\mathbf{E}_{ORG}$ 222 remained unchanged), WRF-Chem is run again to forecast the chemical fields  $\mathbf{\rho}^{f}$ 223 with the updated chemical fields of the previous assimilation cycle as the ICs. The 224 state variables, i.e., 15 aerosol species and four scaling factors, are then prepared. 225 (4) The model-simulated PM<sub>2.5</sub> concentration at the observation space is then

calculated via equation (12).

227 (5) In the assimilation step, the state variables, the concentrations of 14 defined 228 aerosol species and a 15th unspeciated aerosol, and the four species of emission 229 scaling factors  $\lambda_{PM2.5}^{f}$ ,  $\lambda_{SO2}^{f}$ ,  $\lambda_{NO}^{f}$  and  $\lambda_{NH3}^{f}$ , were optimized through EnSRF.

230 (6) After the assimilation step, the optimized emissions ( $\mathbf{E}_{PM2.5i}^{a}$ ,  $\mathbf{E}_{PM2.5j}^{a}$ ,  $\mathbf{E}_{S02}^{a}$ ,

231  $\mathbf{E}_{NO}^{a}$ ,  $\mathbf{E}_{NH3}^{a}$ ,  $\mathbf{E}_{SO4i}^{a}$ ,  $\mathbf{E}_{SO4j}^{a}$ ,  $\mathbf{E}_{NO3i}^{a}$  and  $\mathbf{E}_{NO3j}^{a}$ ) were calculated according to equations

232 (11, 14–17) using the optimized scaling factors ( $\lambda_{PM2.5}^{a}$ ,  $\lambda_{SO2}^{a}$ ,  $\lambda_{NO}^{a}$  and  $\lambda_{NH3}^{a}$ ).

233

### 234 3. PM<sub>2.5</sub> observation data and errors

Hourly averaged surface  $PM_{2.5}$  observations from the Ministry of Environmental Protection of China were assimilated. Figure 2 shows the locations of 77 measurement sites used for the  $PM_{2.5}$  assimilation experiment and forecast verification. The observation sites spanned most of central and eastern China and were primarily located in urban and suburban areas.

240 The observation error covariance matrix **R** in equation (3) includes contributions from measurement and representation errors. Similar to the work of 241 242 Schwartz et al. (2012), who followed Elbern et al. (2007) and Pagowski et al. (2010), the measurement error  $\varepsilon_0$  is defined as  $\varepsilon_0 = 1.5 + 0.0075 * \Pi_0$ , where  $\Pi_0$  denotes 243 the observational values for PM<sub>2.5</sub> ( $\mu g m^{-3}$ ). Thus, higher PM<sub>2.5</sub> values were 244 associated with larger measurement errors. The representativeness error  $\varepsilon_r$  depends 245 on the resolution of the model and the characteristics of the observation locations and 246 is calculated as  $\varepsilon_r = r\varepsilon_0 \sqrt{\Delta x/L}$ , where r is an adjustable parameter (here, r = 0.5), 247





248  $\Delta x$  is the grid spacing (here, 40.5 km), and L is the radius of influence of an observation (here, L was set to 3 km). The total PM<sub>2.5</sub> error ( $\varepsilon_t$ ) is defined as 249  $\varepsilon_{\rm t} = \sqrt{\varepsilon_0^2 + \varepsilon_r^2}$ . The observation errors are assumed to be uncorrelated so that **R** is 250 251 a diagonal matrix.

The PM<sub>2.5</sub> observations were subject to quality control to ensure data reliability 252 before DA.  $PM_{2.5}$  values larger than 800 µg m<sup>-3</sup> are classified as unrealistic and were 253 not assimilated; observations with a first guess departure exceeding 100  $\mu$ g m<sup>-3</sup> are 254 255 also omitted.

256

#### 4. Experimental design 257

Two parallel experiments were performed to evaluate the impact of PM2.5 DA on the 258 analyses and forecasts of aerosols over China: an assimilation experiment and a 259 control experiment. Both experiments used identical WRF-Chem settings and 260 physical parameterizations. The horizontal grid spacing was 40.5 km and there were 261 57 vertical levels with the model top at 10 hPa. 262

263

4.1 Spin-up ensemble forecast with perturbed Initial and boundary conditions 264

The initialization and spin-up procedures were identical to those reported by 265 Schwartz et al. (2014). The ICs and lateral boundary conditions (LBCs) for the 266 meteorological fields were provided by the National Centers for Environmental 267 268 Prediction Global Forecast System (GFS).

The initial meteorological fields were created at 0000 UTC 1 October 2014 by 269 interpolating the GFS analyses onto the model domain. The 50 ensemble members 270 271 were then generated by adding Gaussian random noise with a zero mean and static 272 background error covariances (Torn et al., 2006) to the temperature, water vapor, 273 velocity, geopotential height and dry surface pressure fields. The ICs of each member were zero in the initial aerosol fields, representing clean conditions as described by 274 Liu et al. (2011). 275

276

The LBCs for the meteorological fields were then interpolated from the GFS





analyses from 0000 UTC 1 October 2014 to 0000 UTC 16 October 2014 and
perturbed similarly to the initial fields at 0000 UTC 1 October 2014. The aerosol
LBCs of each member for all experiments represented clean oceanic conditions.

Fifty-member emissions were created by adding standard Gaussian random noise to the anthropogenic emissions, as reported by Schwartz et al. (2014). A 50-member ensemble of four-day WRF-Chem forecasts was then produced using the perturbed ICs at 0000 UTC 1 October 2014, the corresponding perturbed LBCs and the emissions.

285

### 286 4.2 Assimilation experiment

The assimilation experiment was conducted from 0000 UTC 5 October 2014 to 0000 287 UTC 16 October 2014. The assimilation cycle interval was 1 h. The first initial 288 chemical fields were drawn from the WRF-Chem ensemble forecasts valid at 0000 289 290 UTC 5 October 2014, as described in section 4.1. In the subsequent assimilation 291 cycles, the ICs for the chemical variables of each member were drawn from the updated chemical fields of the previous cycle. The aerosol LBCs of each member 292 293 represented clean oceanic conditions. As for the meteorological ensemble fields, the LBCs were prepared in advance as depicted in section 4.1; the ICs of each member of 294 295 the meteorological fields were drawn from the forecast meteorological fields of the 296 previous cycle before re-centering with the GFS analysis because we do not do meteorological analysis: 297

298 
$$\mathbf{\pi}_{i_{\text{new}}} = \mathbf{\pi}_i + (\mathbf{\pi}_{\text{GFS}} - \overline{\mathbf{\pi}}), (18)$$

where  $\pi_i$  is the *i*th member of the forecast meteorological fields of the previous cycle,  $\bar{\pi}$  is the ensemble mean of the forecast meteorological fields of the previous cycle,  $\pi_{GFS}$  is the meteorological field interpolated from the GFS analyses and  $\pi_{i_{new}}$  is the new meteorological field used as the IC in WRF-Chem in the next cycle.

303

304 4.3 Control experiment

305 The control experiment was conducted for the same period as the assimilation





experiment and the simulation cycle period was 1 h, as in the assimilation experiment. The first initial chemical fields were extracted from the ensemble mean valid at 0000 UTC 5 October 2014. In the subsequent simulation process, the ICs for the chemical fields were from the previous cycle's 1-h forecast. The LBCs and ICs for the meteorological fields were updated by interpolating the GFS analyses. The emissions were the prescribed emissions  $\mathbf{E}_t^{\mathbf{p}}$  without any perturbation.

312

### 313 **5. Results**

As the measurement coverage is an important factor that may determine the performance in DA, we primarily focused our attention on the results from three sub-regions with comparatively dense observational coverage (Figure 2): the Beijing– Tianjin–Hebei region (JJJ, 12 stations); the Yangtze River delta (YRD, 24 stations); and the Pearl River delta (PRD, 9 stations).

319

### 320 5.1 Ensemble performance

It is important to assess the ensemble performance for an ensemble-based DA system. 321 In a well-calibrated system, a comparison of the prior ensemble mean 322 root-mean-square error (RMSE) with respect to the observations should equal the 323 prior "total spread" (square root of the sum of ensemble variance and observation 324 error variance) (Houtekamer et al., 2005). Figure 3 shows the time series for the prior 325 326 ensemble mean RMSE and the total spread for PM<sub>2.5</sub> aggregated over all observations in the three sub-regions. It indicates that the magnitudes of both the total spread and 327 the RMSE were influenced by the diurnal cycle and heavy air pollution. Almost all 328 329 the total spreads were smaller than the RMSE, showing an insufficient spread of 330  $PM_{2.5}$  ensemble forecasts, which is especially evident for heavy polluted period with much larger RMSEs. 331

332

333 5.2 Impact on aerosol ICs

334 To evaluate quantitatively the impact of the ensemble assimilation system on the ICs,





335 the mean errors (bias), RMSEs and correlation coefficient (CORR) of the assimilation experiment and the control run were first analyzed. These statistics were calculated 336 against observations over all the analyses from 6 to 16 October 2014. Table 1 shows 337 that the bias magnitudes of the control run were 19.1 and 23.5  $\mu$ g m<sup>-3</sup> for the YRD 338 and the PRD, respectively, suggesting a significant overestimation of the WRF-Chem 339 aerosol mass in these two sub-regions. However, a significant underestimation of the 340 aerosol mass occurred in the JJJ region, where the model bias was  $-16.6 \ \mu g \ m^{-3}$ . The 341 RMSEs of the control run were 76.8, 32.2 and 34.5  $\mu$ g m<sup>-3</sup> for the JJJ, YRD and PRD 342 regions, respectively. After assimilation, the statistics showed an apparent 343 improvement and the magnitude of the bias and the RMSE decreased. Both the 344 maximum bias and the RMSE were obtained in the JJJ region, and were -5.2 and 41.6 345 µg m<sup>-3</sup>, respectively. The CORR increased from 0.79, 0.60, and 0.62 to 0.93, 0.93, 346 and 0.87 for the JJJ, YRD and PRD, respectively. These results indicate that the initial 347 348 PM<sub>2.5</sub> fields can be adjusted efficiently by the EnSRF.

The spatial distribution of the time-averaged differences in PM<sub>2.5</sub> (assimilation 349 minus control) illustrated the impact on the aerosol ICs. Figure 4 shows that the 350 351 average difference in  $PM_{2.5}$  at the lowest model level was negative in the YRD, the PRD and in central China, indicating the reduction of the overestimation of the 352 353 WRF-Chem simulation over these regions with data assimilation. The smallest value of  $-40 \ \mu g \ m^{-3}$  was seen around Guangzhou. Conversely, positive differences were 354 seen in the JJJ region and in northeast China. The largest value (>40  $\mu g m^{-3}$ ) was seen 355 in South Hebei Province. These results indicate that DA greatly improved the ICs. 356

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### 358 5.3 Impact on emissions

To determine the impact of assimilating  $PM_{2.5}$  observations on the chemical emissions, we analyzed the area-averaged time series extracted from the optimized emission scaling factors and the optimized emissions. Figure 5 shows that although the prior emissions had no diurnal variation when the experiments were designed, the optimized  $PM_{2.5}$  scaling factor,  $\lambda_{PM2.5}^{a}$ , showed an obvious variation with time, as did the optimized unspeciated primary sources of  $PM_{2.5}$ ,  $E_{PM2.5}^{a}$ . Moreover, the values of





365  $\lambda^a_{PM2.5}$  were <1 at almost all times in the YRD and PRD, which resulted that the analyzed emission  $\mathbf{E}_{PM2.5}^{a}$  were lower than the prior PM<sub>2.5</sub> emissions  $\mathbf{E}_{PM2.5}^{p}$ . In the 366 YRD, the prior  $\mathbf{E}_{PM2.5}^{p}$  was about 0.127 µg m<sup>-2</sup> s<sup>-1</sup> over all hours. After assimilation, 367 the time-averaged optimized  $E_{PM2.5}^{a}$  decreased to 0.107 µg m<sup>-2</sup> s<sup>-1</sup>, about 15.6% 368 lower than the prior value. In the PRD, the prior  $\mathbf{E}_{PM2.5}^{p}$  was about 0.10 µg m<sup>-2</sup> s<sup>-1</sup>. 369 The time-averaged optimized  $E^a_{PM2.5}$  decreased to 0.066  $\mu g {\cdot} m^{-2}~s^{-1},$  leading to a 370 decrease of 35.0%. However, larger values for the optimized  $E_{PM2.5}^{a}$  were obtained in 371 the JJJ region in three periods, from 1600 UTC 6 October to 0000 UTC 8 October, 372 from 1600 UTC 9 October to 0000 UTC 10 October, and from 1600 UTC 13 October 373 to 0000 UTC 15 October as a result of the increased optimized scaling factor  $\lambda_{PM2.5}^{a}$ . 374 375 This may have been caused by the burning of crop residues during harvesting in this region (Li et al., 2016), which was not taken into account in the prior emissions. 376 377 Although the system is able to detect the emission changes caused by burning events, 378 the time that the system started to show increased scaling factors might be not accurate enough (may shift a few hours later); as the system is optimized based on 379 380 ambient concentrations in which the transport and transformation processes are not directly taken into account. 381

The NO, SO<sub>2</sub> and NH<sub>3</sub> emissions were all adjusted to some extent by our DA approach. The NO emissions increased by 41.3, 43.7 and 20.3% in the JJJ, YRD and PRD regions, respectively. The SO<sub>2</sub> emissions increased by 16.3, 10.0 and 18.3% and the NH<sub>3</sub> emissions increased by 16.7, 7.8 and 7.5% in the JJJ, YRD and PRD regions, respectively.

Figure 6 shows the spatial distribution of the time-averaged scaling factors  $\lambda_{PM2.5}^{a}$  at the lowest model level over all hours from 6 to 16 October 2014. Figure 7 shows the distribution of  $E_{PM2.5}^{p}$  and the time-averaged differences between the ensemble mean of the assimilation and the prior values. These patterns are consistent with those in Figure 5. Negative differences were obtained in most areas of the YRD and PRD, indicating that the PM<sub>2.5</sub> DA primarily decreased the PM<sub>2.5</sub> emissions.





Conversely, positive differences were obtained in South Hebei, North Henan and
Southeast Shanxi provinces, indicating that DA increased the PM<sub>2.5</sub> emissions.

As the economy in China has developed, the spatiotemporal distribution of 395 396 emissions has changed as a result of changes in energy consumption, the structure of the energy market and advances in technology. Therefore although this inventory of 397 emissions may have correctly described anthropogenic emissions in 2006 when it was 398 constructed, it is not representative of the anthropogenic emissions in 2014. 399 Theoretically, the assimilated emissions should reduce the uncertainty in the prior 400 emissions as a result of the application of observations. The diurnal variation in the 401 assimilated emissions verified this statement to some extent. In addition, Liu et al. 402 (2015) reported that PM<sub>2.5</sub> and SO<sub>2</sub> emissions in China decreased from 2006 to 2010, 403 404 whereas  $NO_x$  emissions increased over the same time. Besides, Xia et al. (2016) also reported that NO<sub>x</sub> emissions increased from 2000 to 2011 then decreased slowly from 405 406 2012 to 2014. Our assimilated  $PM_{2.5}$  and  $NO_x$  emissions were in good agreement with 407 this trend, but not the  $SO_2$  emissions. One possible reason for this may be that only surface PM<sub>2.5</sub> observations were applied in this work, which may have less constraint 408 409 on the sources of the secondary aerosol precursors, such as  $SO_2$  emissions. Nevertheless, although we had no direct emission observations to use as a reference, 410 we concluded that the assimilated PM2.5 emissions were a better reflection of the 411 distribution of the spatiotemporal variations in the real discharge than the emissions 412 inventory. More observations are needed to obtain reliable emissions for the sources 413 of the gas-phase precursors. 414

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416 5.4 Verification of aerosol forecasting

For the assimilation experiment, 48-h forecasts were performed at each 0000
UTC from 6 to 16 October 2014 with the hourly forecast output. The ensemble mean
of the analyzed ICs and emissions was used in this longer-range model forecast.

Time series of the hourly  $PM_{2.5}$  extracted from the analysis (AN), the control run (CT) and the hourly output of 48-h forecast (fc24 for the first day forecast and fc48 for the second day forecast) were compared with the observations (OBS) for three 15





423 megacities Beijing, Shanghai and Guangzhou, respectively (Figure 8). As expected, 424 the time series of the analysis were consistent with the observations. The control run 425 showed large deviations from the observations, especially in Shanghai and 426 Guangzhou. Benefit from DA on both the first day and the second day forecasts can 427 be clearly seen.

The RMSE of the surface PM2.5 forecasts as a function of forecast range was 428 then calculated against the observations for the three sub-regions (Figure 9). The 429 RMSEs of the control run were characterized by the diurnal cycle in the YRD and 430 PRD. The largest errors were seen at 2100 UTC in the YRD (about 43  $\mu$ g·m<sup>-3</sup>) and at 431 2200 UTC in the PRD (about 46  $\mu g \cdot m^{-3}$ ), likely indicating significant systematic 432 forecast errors at these times. From 0300 to 0900 UTC, the RMSE values (about 15 433  $\mu g \cdot m^{-3}$ ) were much smaller than at other times in both the YRD and PRD, showing 434 that WRF-Chem performed well during this period. However, in the JJJ region, the 435 RMSEs (about 50  $\mu$ g·m<sup>-3</sup>) were always large as a result of a heavy pollution event. 436 After assimilation, the RMSEs decreased sharply. They remained at about 10  $\mu$ g·m<sup>-3</sup> 437 for all three sub-regions during the whole experimental period, further indicating that 438 439 DA greatly affected the ICs.

The improvements in the surface PM2.5 forecasts by the joint adjustment of the 440 ICs and emissions were dramatic in the YRD and PRD. Large reduction of the 441 RMSEs due to assimilation can be seen for almost the entire 48-h forecast range. 442 From 10- to 23-h and from 34- to 47-h, in particular, the relative reduction in RMSE 443 was about 40%. However, the DA impact was much smaller for 3- to 9-h forecast 444 445 ranges, which are at daytime of the first day forecast. This may be because WRF-Chem performed sufficiently well during this period and therefore the further 446 improvement was more difficult. From the perspective of the DA impact, the 447 differences between the optimized PM2.5 emissions and the prior emissions from 0000 448 to 0700 UTC each day were always smaller than those for other periods. In addition, 449 the improvements were nearly negligible from 27- to 33-h, the daytime of the second 450 day forecast, suggesting that the benefit gained from adjusting the ICs decreased 451 progressively and eventually disappeared with model integration. Nevertheless, 452





attributed greatly to the large adjustment of chemical emissions, substantial
improvements were still achieved from 34- to 47- h. These results revealed that joint
adjustment of the ICs and emissions can improve surface PM<sub>2.5</sub> forecasts up to 48 h in
the YRD and PRD.

The DA system did not perform as well in the JJJ region as in the YRD and RRD 457 and relatively smaller improvements were achieved in the first 24-h forecast. One 458 possible reason for this result may be systematic errors due to chemistry mechanism 459 in WRF-Chem. The sources of the aerosols are so complex that our knowledge of 460 their formation mechanisms is far from clear and large uncertainties still exist in the 461 model simulations. Chemical transport models have a tendency to underestimate PM 462 concentrations, especially during episodes of heavy pollution (Denby et al., 2007) due 463 464 to some missing reactions (Wang et al., 2014; Zhang et al., 2015, Zheng et al., 2015; Chen et al., 2016). As a result, a large bias may be obtained in forecasts of heavy 465 466 pollution given the ICs and emission inventories achieved from the joint assimilation. 467 Another reason may be the sparse coverage of measurements. There were only 12 sites in the JJJ region (Figure 2) and the measurement coverage was much sparser 468 469 than in the YRD or PRD. However, these results are still better than those obtained with the pure adjustment of ICs that lead to improvements in the first 12-h forecasts 470 (Jiang et al., 2013; Schwartz et al., 2014). 471

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### 473 **6. Summary**

The EnSRF algorithm was extended to adjust the chemical ICs and the primary 474 475 and precursor emissions to improve forecasts for surface  $PM_{2.5}$ . This system was applied to assimilate hourly surface PM2.5 measurements from 5 to 16 October 2014 476 over China. To evaluate the effectiveness of DA, 48-h forecasts were performed using 477 the optimized ICs and emissions, together with a control experiment without DA. The 478 results indicated that the forecasts with the optimized ICs and emissions performed 479 much better than the control simulations. Large improvements were achieved for 480 almost all the 48-h forecasts, particularly in the YRD and PRD. However, relatively 481 smaller improvements were achieved in the first 24-h forecast in the JJJ region, which 482 17





- 483 may be attributed to the sparse measurement coverage and the deficiencies in the
- 484 model system for forecasting heavy pollution.
- 485 This study represents the first step in the simultaneous optimization of chemical
- 486 ICs and emissions and only surface  $PM_{2.5}$  measurements were assimilated. In future
- 487 work, gas-phase observations of SO<sub>2</sub>, NO<sub>2</sub> and CO will be used to further improve the
- 488 performance of this DA system.
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### List of Figures and Table 668 669 Figure 1. (a) Framework of $M_{SF}$ and (b) flow chart of the data assimilation system 670 that simultaneously optimizes the chemical initial conditions and emissions. 671 672 Figure 2. Locations of 77 $PM_{2.5}$ observation stations in the model domain. The three 673 colored boxes mark sub-regions with relatively dense coverage for the Beijing-674 Tianjin-Hebei region (JJJ, 12 stations, red), the Yangtze River delta (YRD, 24 675 stations, blue) and the Pearl River delta (PRD, 9 stations, green). 676 677 Figure 3. Time series of prior ensemble mean RMSE and total spread for $PM_{25}$ 678 concentrations aggregated over all observations over the three sub-regions: (a) 679 680 Beijing–Tianjin–Hebei region; (b) Yangtze River delta; and (c) Pearl River delta. 681 Table 1. Comparison of the surface PM<sub>2.5</sub> mass concentrations from the control and 682 assimilation experiments to observations over all analysis times from 6 to 16 October 683 2014. 684 685 Figure 4. PM<sub>2.5</sub> mass differences (assimilation minus control, $\mu g m^{-3}$ ) at the lowest 686 model level averaged over all hours from 6 to 16 October 2014. 687 688 689 Figure 5. Hourly area-averaged time series of emission scaling factors (black) extracted from the ensemble mean of the analyzed $\lambda_{PM2,5}^{a}$ and the corresponding 690 analyzed unspeciated primary $PM_{2.5}$ emissions $E^{a}_{PM2.5}$ (blue) over the three 691 sub-regions: (a) Beijing-Tianjin-Hebei region; (b) Yangtze River delta; and (c) Pearl 692 River delta. 693 694 Figure 6. Spatial distribution of $\lambda_{PM2.5}$ at the lowest model level averaged over all 695 hours from 6 to 16 October 2014. 696 697 Figure 7. Spatial distribution of (a) the prior unspeciated primary sources of PM<sub>2.5</sub> 698 $(\mu g m^{-2} s^{-1})$ and (b) the time-averaged differences between the ensemble mean 699 analyses and the prior values ( $\mu g \cdot m^{-2} s^{-1}$ ) at the lowest model level averaged over all 700 hours from 6 to 16 October 2014. 701 702 Figure 8. Time series of the hourly PM2.5 obtained from observations (circle), analysis 703 (blue line), control run (black line) and hourly output of 48-h forecast in three 704 megacities: (a) Beijing; (b) Shanghai; and (c) Guangzhou. See text in section 5.4. 705 706 Figure 9. RMSE of surface PM<sub>2.5</sub> as a function of forecast range calculated against 707 observations over the three sub-regions: (a) Beijing-Tianjin-Hebei region; (b) 708 709 Yangtze River delta; and (c) Pearl River delta. (d) Normalized RMSE (assimilation divided by control). 710 711





712 (a) (b) Prescribed emissions F<sup>c</sup> Analysis  $\mathbf{x}^{a} = [\mathbf{C}^{a}, \lambda^{a}]^{T}$  $C_{i,t-1}^{a}$  $\mathbf{C}_{i,t}^{\mathrm{f}}$ WRF-Chem  $\mathbf{F}_{i,t-2}^{\mathrm{f}}$ The forecasting model M WRF-Chem M<sub>SF</sub>  $\mathbf{\kappa}_{i,t} = \mathbf{C}_{i,t}^{\mathrm{f}} / \overline{\mathbf{C}_{t}^{\mathrm{f}}}$ Eq. (6) λſ Cf  $\mathbf{F}^{\dagger}$  $(\mathbf{\kappa}_{i,t})_{\text{inf}} = \beta \left( \mathbf{\kappa}_{i,t} - \overline{\mathbf{\kappa}_t} \right) + \overline{\mathbf{\kappa}_t}$ Background  $\mathbf{x}^{b} = [\mathbf{C}^{f}, \boldsymbol{\lambda}^{f}]^{T}$  **H** Hx<sup>b</sup>  $\boldsymbol{\lambda}_{i,t}^{\mathrm{p}} = (\boldsymbol{\kappa}_{i,t})_{\mathrm{inf}}$ EnSRF  $\underbrace{\text{Eq. (6)}}_{\text{Joint analysis vector } \mathbf{x}^{a} = [\mathbf{C}^{a}, \boldsymbol{\lambda}^{a}]^{T}$  $\boldsymbol{\lambda}_{i,t}^{\mathrm{f}} = \frac{1}{M} (\sum_{j=t-M+1}^{t-1} \boldsymbol{\lambda}_{i,j}^{\mathrm{a}} + \boldsymbol{\lambda}_{i,t}^{\mathrm{p}})$ Fa 714

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Figure 1. (a) Framework of  $\mathbf{M}_{SF}$  and (b) flow chart of the data assimilation system 715 that simultaneously optimizes the chemical initial conditions and emissions.

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- Figure 2. Locations of 77  $PM_{2.5}$  observation stations in the model domain. The three
- colored boxes mark sub-regions with relatively dense coverage for the Beijing-
- Tianjin–Hebei region (JJJ, 12 stations, red), the Yangtze River delta (YRD, 24
- stations, blue) and the Pearl River delta (PRD, 9 stations, green).
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725 RMSE and Total Spread( $\mu g \cdot m^{-3}$ ) 150 RMSE Total Spread (a) 100 50 Oct-10 Oct-12 Date Oct Oct-8 Oct-14 -06 Oct-16 RMSE and Total Spread(lug·m<sup>-3</sup>) 00 - 00 00 - 00 00 - 00 00 - 00 00 - 00 RMSE RMSE (c) (b) Total Spread Total Spread Oct-10 Oct-12 Date Oct-8 Oct-14 Oct-16 Oct-8 Oct-10 Date Oct-12 Oct-14 Oct-16 726 Figure 3. Time series of prior ensemble mean RMSE and total spread for PM<sub>2.5</sub> 727 concentrations aggregated over all observations over the three sub-regions: (a) 728 Beijing-Tianjin-Hebei region; (b) Yangtze River delta; and (c) Pearl River delta. 729 730





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Table 1. Comparison of the surface  $PM_{2.5}$  mass concentrations from the control and

assimilation experiments to observations over all analysis times from 6 to 16 October

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	_		2014.	-		
		Mean	Mean			
Region	Experiment	observed	simulated	BIAS	RMSE	CORR
		value	value			
Beijing-	Control		101.1	-16.6	76.8	0.785
Tianjin–	Assimilation	117.7	112.5	5.0	<i>41 C</i>	0.022
Hebei			112.5	-5.2	41.0	0.932
Yangtze	Control		67.0	19.1	32.2	0.603
River	Assimilation	47.9	40.0	1 1	10.5	0.029
delta			49.0	1.1	10.5	0.928
Pearl	Control		87.2	23.5	34.5	0.618
River	Assimilation	63.7		2.4	10.0	0.077
delta			66.1	2.4	12.9	0.866







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739 Figure 4.  $PM_{2.5}$  mass differences (assimilation minus control,  $\mu g m^{-3}$ ) at the lowest

model level averaged over all hours from 6 to 16 October 2014.



















Figure 7. Spatial distribution of (a) the prior unspeciated primary sources of  $PM_{2.5}$ ( $\mu g m^{-2} s^{-1}$ ) and (b) the time-averaged differences between the ensemble mean analyses and the prior values ( $\mu g \cdot m^{-2} s^{-1}$ ) at the lowest model level averaged over all hours from 6 to 16 October 2014.







Figure 8. Time series of the hourly PM<sub>2.5</sub> obtained from observations (circle), analysis
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Yangtze River delta; and (c) Pearl River delta. (d) Normalized RMSE (assimilation divided by control).