

Controls on phase composition and ice water content in a convection permitting model simulation of a tropical mesoscale convective system

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Abstract

Simulations of tropical convection from an operational numerical weather prediction model are evaluated with the focus on the model's ability to simulate the observed high ice water contents associated with the outflow of deep convection, and to investigate the modelled processes that control the phase composition of tropical convective clouds. The 1 km horizontal grid length model that uses a single moment microphysics scheme simulates the intensification and decay of convective strength across the mesoscale convective system. However, deep convection is produced too early, the OLR is underestimated and the areas with reflectivities > 30 dBZ are overestimated due to too much rain above the freezing level, stronger updrafts and larger particle sizes in the model. The inclusion of a heterogeneous rain freezing parameterisation and the use of different ice size distributions show better agreement with the observed reflectivity distributions, however, this simulation still produces a broader profile with many high reflectivity outliers demonstrating the greater occurrence of convective cells in the simulations. Examining the phase composition shows that the amount of liquid and ice in the modelled convective updrafts is controlled by: the size of the ice particles, with larger particles growing more efficiently through riming, producing larger IWC; the efficiency of the warm rain process, with greater cloud water contents being available to support larger ice growth rates, and; exclusion or limitation of graupel growth,

1 with more mass contained in slower falling snow particles resulting in an increase of in-cloud
2 residence times and more efficient removal of LWC. In this simulated case using a 1 km grid
3 length model, horizontal mass divergence in the mixed-phase regions of convective updrafts
4 is most sensitive to the turbulence formulation. Greater mixing of environmental air into
5 cloudy updrafts in the region of -30 to 0 degrees Celsius produces more mass divergence
6 indicative of greater entrainment, which generates a larger stratiform rain area. Above these
7 levels in the purely ice region of the simulated updrafts, the convective updraft buoyancy is
8 controlled by the ice particle sizes, demonstrating the importance of the microphysical
9 processes on the convective dynamics in this simulated case study using a single moment
10 microphysics scheme. The single moment microphysics scheme in the model is unable to
11 simulate the observed reduction of mean mass-weighted ice diameter as the ice water content
12 increases. The inability of the model to represent the observed variability of the ice size
13 distribution would be improved with the use of a double moment microphysics scheme.

14

15 **1 Introduction**

16 Improving the simulation of tropical convective clouds in convection-permitting simulations
17 is an important yet challenging endeavour. Forecasting centres are beginning to use
18 operational numerical weather prediction models with horizontal grid spacing of order 1 km
19 and while these models have been shown to improve the diurnal cycle of convection and the
20 distribution of rain rates (e.g. Clark et al. 2007; Weusthoff et al. 2010), there are numerous
21 deficiencies at these resolutions that impacts the accuracy of the forecasts and the confidence
22 in using these models to help guide parameterisation development for coarser resolution
23 models and develop retrieval algorithms for remotely sensed cloud properties (e.g. Del Genio
24 and Wu 2010; Shige et al. 2009). One salient aspect of forecasting tropical meteorology is the
25 high ice water contents that are responsible for numerous aircraft safety incidents as discussed
26 by Fridlind et al. (2015). These incidents tend to occur in fully glaciated conditions in the
27 vicinity of deep convection where high ice water contents can cause engine power loss (e.g.
28 Lawson et al. 1998; Mason et al. 2006; Strapp et al. 2015). In recognition of this, an
29 international field campaign called the High Ice Water Content (HIWC) study was conducted
30 out of Darwin in the beginning of 2014 and provided a high quality database of ice cloud
31 measurements associated with deep tropical convective systems. These observations are a
32 valuable resource for evaluating convection permitting model simulations and cloud

1 microphysical parameterisations. In this work cloud properties are evaluated from an
2 operational model with the focus on the model's ability to simulate high ice water contents
3 generated from the outflow of deep convection and to understand what modelled processes
4 control the phase composition of the simulated tropical convective clouds.

5 Many previous convection permitting simulations of tropical convection have documented
6 common biases amongst models including excessive reflectivities above the freezing level,
7 lack of stratiform cloud and precipitation, and too much frozen condensate (e.g. Blossey et al.
8 2007; Lang et al. 2011; Fridlind et al. 2012; Varble et al. 2014a,b). Lang et al. (2011)
9 modified a single moment microphysics scheme to reduce the biases in simulated radar
10 reflectivities and ice sizes in convective systems and found better success in a weakly
11 organised continental convective case compared to a stronger oceanic MCS. The reason could
12 be due to dynamical errors in the model that had a greater influence on the microphysical
13 characteristics in the simulations of stronger convection. Varble et al. (2014a) compared cloud
14 resolving and limited area model simulations with the extensive database of observations
15 from the Tropical Warm Pool-International Cloud Experiment. They found excessive vertical
16 velocities even at 100 m horizontal grid spacings, and suggested that the overly intense
17 updrafts are a product of interactions between the convective dynamics and microphysics.
18 These strong updrafts transport condensate and moisture to the upper levels that contributes to
19 the larger amount of frozen condensate seen in simulations, and the reduced detrainment at
20 lower levels could play a role in the lack of generation of significant stratiform cloud and
21 precipitation (Ferrier 1994; Tao et al. 1995; Morrison et al. 2009). In the operational model
22 used in this study the microphysics scheme is a single moment bulk scheme. Model
23 intercomparison studies have shown that double moment microphysics schemes do not
24 necessarily perform better than single moment schemes, and in fact provided that the intercept
25 parameters are not fixed and are able to vary, these more simple schemes can match or even
26 outperform the more complex double moment schemes in their representation of cloud and
27 rainfall properties (e.g. VanWeverberg et al. 2013; Varble et al. 2014b).

28 The aims of this study are twofold: firstly to test different configurations of the dynamics,
29 turbulence and microphysical formulations in the model to determine those that best represent
30 tropical convective cloud systems and to understand the sensitivities in the modelled cloud
31 and dynamical properties to these changes, and; secondly to determine what process control
32 the phase composition and ice water content in the model. As mentioned previously,

1 observations of HIWC (defined here as $> 2 \text{ g m}^{-3}$ at 1 km resolution) typically occur in
2 glaciated conditions. However, as will be shown, the model is unable to replicate this and
3 instead produces mixed-phase clouds under the same temperature regimes. For this reason we
4 examine what processes control the modelled phase composition in order to understand how
5 the model produces HIWC. This understanding will aid in improving the representation of
6 these clouds in the model and produce a better forecasting capability. The following section
7 describes the model and observations used in this work. Section 3 compares the simulations
8 with the available observations including: a time series comparison with the satellite data,
9 comparison of the simulated radar reflectivity characteristics with those from the Darwin
10 radar and an investigation into the controls on phase composition in the model and how the
11 IWC and ice particle sizes compare with the in situ observations. This is followed by a
12 summary of the results in section 4.

13 **2 Description of the model and observations**

14 The Met Office Unified Model (UM) version 8.5 is used to create a series of one-way nested
15 simulations. The global model configuration GA6 (Walters et al. 2015) is the driving model,
16 which uses the Even Newer Dynamics for General atmospheric modelling of the environment
17 (ENDGame) dynamical core (Wood et al. 2014). The global model has a resolution of N512
18 ($\sim 25 \text{ km}$) with 70 vertical levels and is run with a 10 minute time step. The convection
19 scheme is based on Gregory and Rowntree (1990) and uses a vertical velocity dependent
20 convective available potential energy (CAPE) closure. The Prognostic Cloud Prognostic
21 Condensate (PC2) scheme of Wilson et al. (2008) is used with the microphysics scheme
22 described by Wilson and Ballard (1999) but with numerous modifications including
23 prognostic rain and graupel, cloud droplet settling and the Abel and Boutle (2012) rain drop
24 size distribution. The boundary layer scheme used is based on Lock et al. (2000) and the
25 radiative fluxes are determined by the Edwards and Slingo (1996) scheme. The global model
26 is initialised at 00 UTC using the Australian Community Climate and Earth System Simulator
27 (ACCESS; Puri et al. 2013) operational analysis for the case study date of February 18 2014.

28 The first nested simulation within the global model is a 4 km grid length simulation. These
29 simulations are run with a 100 s time step and are forced at the boundaries every 30 minutes.
30 At this resolution the Smith (1990) diagnostic cloud scheme is used where the critical relative
31 humidity is 0.8 above 800 m and increases to 0.96 at the lowest model level. The cloud
32 microphysical parameterisations are the same as the global model except that the generic ice

1 particle size distribution (PSD) scheme of Field et al. (2007) is used. The convection scheme
2 at this resolution has a modified CAPE closure that scales with grid-box area, which allows
3 for more of the convective activity to be modelled explicitly. The other difference from the
4 global model is the diffusion. While there is no horizontal diffusion in the global model, in the
5 4 km model this is modelled by a Smagorinsky (1963) type scheme and the vertical diffusion
6 coefficients are determined using a scheme that blends those from the boundary layer scheme
7 and the Smagorinsky scheme (Boutle et al. 2014). The older dynamics scheme (named New
8 Dynamics; Davies et al. 2005) is used in the control model configuration, as that dynamical
9 core was the one being used in the high resolution operational model forecasts for this version
10 of the model. However, the effects of the dynamics are also tested by using ENDGame in a
11 sensitivity experiment.

12 A suite of 1 km simulations are nested in the 4 km simulation that investigates the effects of
13 the dynamics, turbulence and microphysical parameterisations on the simulations of tropical
14 convective clouds. There are 80 vertical levels and the model is run with a time step of 30 s.
15 The domain is 500 x 500 km² centred on the location of the Darwin radar (12.25 °S, 131.04
16 °E) as shown in Figure 1 and the convection is modelled explicitly. Given that the focus of
17 this work is primarily on the cloud microphysics, a description of the scheme used in the
18 model is provided, with the details of the other parameterisations available in the previously
19 cited references. The microphysics scheme is described by Wilson and Ballard (1999) but
20 with numerous modifications. The single moment scheme carries water in four variables:
21 vapour, liquid, ice and rain, with an additional graupel variable in the 1 and 4 km simulations.
22 The 4 km and control version of the 1 km model use the generic ice particle size distribution
23 of Field et al. (2007), where the aggregates and crystals are represented by a single prognostic
24 aggregate variable. This parameterisation is based on the idea of relating moments of the size
25 distribution to the second moment, which is directly proportional to the ice water content
26 when mass is equal to the square of the particle size. In using this parameterisation there is no
27 need to specify an intercept parameter for the PSD and instead the microphysical transfer
28 rates are derived from the moment estimation parameterisation that is a function of ice water
29 content and temperature. The mass-diameter relationships take the form of a power law

$$30 \quad m(D) = aD^b \quad (1)$$

31 The particle size distributions are generalised gamma functions

$$1 \quad N(D) = N_0 D^\mu e^{-\lambda D} \quad (2)$$

2 where N_0 is the intercept parameter, μ is the shape parameter and λ is the slope parameter.
 3 The coefficients for each hydrometeor species are given in Table 1, where the aggregate and
 4 crystal PSD coefficients are for the simulations that use an explicit PSD and not the generic
 5 ice PSD parameterisation. The explicit ice size distributions have a temperature-dependent
 6 intercept parameter that decreases with warming temperatures, representing larger particles
 7 and the effect of aggregation (Houze et al. 1979), where in Table 1

$$8 \quad f(T) = \exp\left(-\frac{\max(T_c, -45^\circ\text{C})}{8.18^\circ\text{C}}\right) \quad (3)$$

9 following Cox (1988) with T_c the temperature in degrees Celsius. Fall speeds are
 10 parameterised from power laws with the coefficients for crystals and aggregates from
 11 Mitchell (1996), graupel from Ferrier (1994) and rain from Abel and Shipway (2007).

12 Ice can be formed by homogeneous and heterogeneous nucleation processes. At -40°C and
 13 below, homogeneous nucleation instantaneously converts all liquid water (both cloud water
 14 and rain) to ice. Heterogeneous nucleation requires cloud water to be present at temperatures
 15 at or below -10°C . The process is dependent on relative humidity and the mass of the number
 16 of active nuclei produced from the temperature dependent function from Fletcher (1962).
 17 Once ice has been formed it can grow by vapour deposition, riming, collection and
 18 aggregation. The autoconversion of snow to graupel occurs when snow growth is dominated
 19 by riming, with the additional conditions that the snow mass threshold is exceeded and the
 20 temperature is below -4°C . Once graupel has formed it grows by riming and collection. The
 21 ice hydrometeors experience sublimation, evaporation and melting. There are a number of
 22 graupel transfer terms that have not been included in the model as their rates are significantly
 23 smaller than the dominant processes (Wilkinson et al. 2013). The graupel terms not included
 24 are: deposition and sublimation; wet mode growth; collection of ice crystals; and
 25 heterogeneous freezing of rain by ice nuclei.

26 The control model (denoted as nd) in the set of 1km simulations uses the New Dynamics and
 27 the sensitivity to dynamical formulation is investigated by testing the ENDGame dynamical
 28 core in the simulation denoted eg. Modelling the vertical turbulent mixing using the 3D
 29 Smagorinsky scheme rather than the blended scheme used in the control simulation is labelled
 30 3d. The other experiments test aspects of the microphysical parameterisations:

1 nopsd – Rather than use the generic ice PSD as in the control experiment, explicit PSDs are
2 used for ice where the single ice prognostic is diagnostically split as a function of the
3 temperature difference from cloud top into two categories to represent the smaller more
4 numerous ice crystals and larger aggregates (Wilkinson et al. 2013).

5 qcf2 – As for nopsd but the crystals and aggregates are represented as two separate prognostic
6 variables.

7 qcf2hm – As for qcf2 but with the inclusion of an ice splintering parameterisation that
8 increases the deposition rate in the Hallett-Mossop (1974) temperature zone of -3 to -8 °C.
9 This parameterisation represents the increase in the ice particle number concentration due to
10 ice splinter production during riming and is dependent on the supercooled liquid water
11 content, and as such the riming rate, as well as the temperature that allows for increased
12 deposition at temperatures colder than -8 °C due to the vertical transport of ice splinters
13 (Cardwell et al. 2002).

14 qcf2ndrop500 – As for qcf2 but with an increase in the cloud droplet number concentration
15 from 100 cm^{-3} to 500 cm^{-3} .

16 qcf2sr2graupel – As for qcf2 but with the restriction that snow-rain collisions do not produce
17 graupel.

18 qcf2noqgr – As for qcf2 but without the inclusion of graupel.

19 qcf2rainfreeze – As for qcf2 but with the inclusion of a heterogeneous rain freezing
20 parameterisation based on the stochastic parameterisation of Bigg (1953) following Wisner et
21 al. (1972). This process represents the heterogeneous freezing of rain by heterogeneous
22 nucleation by ice nuclei.

23 qcf2raindsd – As for qcf2 but with the Marshall-Palmer (1948) rain drop size distribution.

24 The Darwin C-band polarimetric (CPOL) radar (Keenan et al. 1998) collects a 3D volume of
25 observations out to a range of 150 km. The radar observations have been interpolated onto the
26 model 1 km grid, and the analysis of radar reflectivities is for the area encompassed by the
27 radius $< 150 \text{ km}$ from the radar (see Fig. 1). The precipitation rates derived from the radar
28 reflectivity have uncertainties of 25% at rain rates greater than 10 mm hr^{-1} and 100% for the
29 lowest rain rates (Fridlind et al. 2012). The satellite observations of outgoing longwave
30 radiation (OLR) and ice water path (IWP) were derived from the geostationary satellite
31 MTSAT-1R following Minnis and Smith (1998) and Minnis et al. (2008; 2011). Observations

1 from the French Falcon 20 aircraft include the ice water content (IWC) measurement made
2 with the isokinetic evaporator probe IKP-2 (Davison et al. 2009), and the ice particle size
3 distribution reconstructed from images of individual particles from the 2D-Stereo (Lawson et
4 al. 2006) and precipitation imaging probes (Baumgardner et al. 2001). The particle probes
5 were fitted with anti-shattering tips and the processing of the size observations accounted for
6 any possible remaining ice shattering by consideration of the inter-arrival times and the ratio
7 between the particle surface and lengths (Leroy et al. 2015). Since the IKP-2 measures the
8 total water content, liquid water and water vapour contributions should be subtracted to obtain
9 IWC. Unfortunately, the hot-wire liquid water content (LWC) sensor on the aircraft was
10 unable to measure LWC below about 10% of the IWC in mixed phase conditions, and LWC
11 levels exceeding this value were very rare. Fortunately the Goodrich Ice Detector could be
12 used to detect the presence of liquid water. Two such regions in two very short flight
13 segments for this case, research flight 23, were identified at $-10\text{ }^{\circ}\text{C}$, and these regions have
14 been excluded from the analysis. The minimum detectable IWC of the IKP-2 is determined by
15 the noise level of the water vapour measurements of the IKP-2 and background probes. This
16 resulting noise level of the subtraction of the background humidity from the IKP-2 humidity
17 is a function of temperature: it is about 0.1 g m^{-3} at $-10\text{ }^{\circ}\text{C}$, dropping rapidly to about 0.005 g
18 m^{-3} at $-50\text{ }^{\circ}\text{C}$. Since most data were taken at temperatures colder than about $-25\text{ }^{\circ}\text{C}$, a
19 minimum IWC of 0.05 g m^{-3} was chosen as the threshold to include in our analysis.

20 Two sources of vertical velocity are used from the Falcon 20. Position, orientation and speed
21 of the aircraft are measured by a GPS-coupled Inertial Navigation System. The 3D air motion
22 vector relative to the aircraft is measured by Rosemount 1221 differential pressures transducer
23 connected to a Rosemount 858 flow angle sensor mounted at the tip of the boom, ahead of the
24 aircraft, and by a pitot tube which is part of the standard equipment of the aircraft. Wind in
25 local geographical coordinates is computed as the sum of the air speed vector relative to the
26 aircraft, and the aircraft velocity vector relative to the ground. Both computations use classical
27 formulas in the airborne measurement field described in Bange et al. (2013). The other
28 vertical air velocity measurement used is retrieved from the multi-beam cloud radar
29 observations using the 3D wind retrieval technique described in Protat and Zawadzki (1999),
30 and we use the technique described in Protat and Williams (2011) to separate terminal fall
31 speed and vertical air velocity. Comparisons near flight altitude with the aircraft in-situ
32 vertical velocity measurements show that the vertical velocity retrieval is accurate to within
33 0.3 m s^{-1} . All observations are averaged to the model 1 km grid.

1 **3 Comparison of the simulations with observations**

2 On February 18 2014 the monsoon trough was stalled near the base of the Top End with
3 active conditions continuing about the northern coast. There was a deep moisture layer and
4 low level convergence that produced a mesoscale convective system. At 14:30 UTC, satellite
5 imagery shows the convection around Darwin was somewhat isolated in nature, with a
6 convective cell developing close to the radar (Figure 2). This convection developed into a
7 larger organised oceanic mesoscale convective system by 18 UTC with deep convective cells
8 producing cloud top temperatures of $-80\text{ }^{\circ}\text{C}$. A widespread region of anvil cloud produced
9 from the outflow of deep convection was seen to develop from 18 UTC and persist for over 8
10 hours. The HIWC research flight penetrated convective cores in a region northeast of the
11 radar at 22 – 24 UTC (Fig. 1) with peak ice water content up to 5 g m^{-3} at 1 s resolution.
12 There was almost no supercooled water detected during the flight, even at $-10\text{ }^{\circ}\text{C}$, and graupel
13 was intermittently observed. The absence of supercooled water coupled with the occasional
14 presence of graupel is due to the system being sampled at the mature-decaying stage, where
15 the supercooled water had been consumed in the production of graupel. Most of the time the
16 particle images were of dense ice aggregates at flight level, except within some convective
17 cores where graupel was observed, as also indicated by strong W-band attenuation.

18 Comparison of the modelled outgoing longwave radiation (OLR) with the satellite
19 observations in Figure 2 show that in general, the control simulation represents the lifecycle
20 of the MCS fairly well. The location of the mostly oceanic convective cells look reasonable,
21 however, the modelled MCS is larger and composed of more numerous and deeper convective
22 clouds than what was observed in the pixel level satellite OLR data and seen in the low level
23 radar reflectivity fields shown in Figure 3. The model also produces more convection over the
24 Tiwi Islands than what was observed at 17:30 UTC. As the MCS transitions from a
25 developing-mature system through to a mature-decaying system, the observed reduction of
26 deep convective cells with time is simulated, although the OLR remains significantly
27 underestimated. During the research flight at 23:30 UTC, the modelled MCS shows cloud
28 positioned in a similar location to that observed with respect to the MCS structure, however,
29 the modelled cloud is shifted somewhat to the northeast (Fig. 2h,l).

30 The mean precipitation rates and ice water path (IWP) (Fig. 3) calculated for the radar domain
31 shown in Figure 1, demonstrate that a larger IWP implies a larger surface rainfall rate as seen
32 in previous tropical studies (e.g. Liu and Curry 1999). The radar derived precipitation shows

1 that the simulations overestimate the domain mean rainfall rate during the development stages
2 of the MCS, and produce the peak in precipitation about 2 hours earlier than is observed. The
3 model precipitation maximum occurs when the simulated convection is strongest, as
4 measured by the largest domain mean vertical velocity at 500 hPa and the maximum vertical
5 velocities. The observed domain mean rainfall maximum corresponds to the time when the
6 domain mean cloud top height is highest (not shown), and together with the infrared satellite
7 imagery (Figure 2), suggests that the generation of significant anvil cloud occurs before the
8 domain mean precipitation maximum, rather than when the convection is strongest as is the
9 case in the simulations. Note that the simulated domain mean precipitation rate at both the
10 earlier and later times is outside of the uncertainty range of the radar derived rainfall rate
11 (Fridlind et al. 2012).

12 The underestimate in modelled surface rainfall for the later times when the MCS has matured
13 is not due to an underestimate in the domain mean upper tropospheric cloud cover, as both the
14 model and satellite observations show mostly overcast conditions, but rather the
15 underestimate in condensate reaching below the freezing level (Figure 3f). The observed IWP
16 is only valid for the daytime from about 22:30 UTC or 8 am local time, and while the
17 simulations with the generic PSD parameterisation compare well with the satellite derived
18 value, the comparison of VISST IWP with CloudSat in tropical regions was shown by
19 Waliser et al. (2009) to be underestimated by 25%, likely due to the maximum retrieved
20 optical depth being limited to 128. Together with the CloudSat uncertainties (30% bias and
21 80% root mean square error; Heymsfield et al. 2008), this suggests that the modelled domain
22 mean IWP may be underestimated from 22:30 – 23:30 UTC. Other studies have documented
23 the lack of stratiform rainfall in convective-scale simulations and some attributed the error to
24 excessive evaporation in single-moment microphysics schemes that use a constant intercept
25 parameter in the rain DSD (Morrison et al. 2009). That is not the case in this work and rather
26 the cause is likely due to overly strong convection (Figures 2 and 3d) that detrains too high
27 and does not produce enough condensate in the lower stratiform regions as has been shown by
28 Ferrier (1994), Tao et al. (1995) and Morrison et al. (2009).

29 The greater IWP in the simulations that use the generic ice PSD parameterisation is associated
30 with larger relative humidity in the upper troposphere (Figure 4a). In a study comparing
31 different microphysics schemes, VanWeverberg et al. (2013) found the same result and
32 associated the increased moisture with the sublimation of ice particles due to the scheme with

1 the slowest ice fall speeds producing the greatest condensate and moisture. That is not the
2 case for this current study where the larger IWP and relative humidity is produced by the
3 microphysics configuration that produces larger mean mass-weighted particle sizes (Figure
4 4c) but similar ice fall speeds above about 12 km, with faster below this height. Figure 4b
5 shows the fall speeds for the ice crystals and aggregates/snow particles. All simulations use
6 the same formulation for snow, and even though the generic PSD only represents a single
7 hydrometeor category there are two fall speeds used to enable a representation of both fast
8 and slow sedimenting particles based on size. The method when using the generic PSD is
9 described by Furtardo et al. (2014) where for narrow size distributions and small mean sizes
10 the fall speed used is that shown for the ice crystals in Figure 4b, and for broader size
11 distributions and larger mean sizes the snow fall speed is used (the cross over is around 600
12 μm). Looking at the mean mass-weighted ice diameters in Figures 4c and 4d shows larger
13 sizes for the simulations that use the generic PSD, however, the slower ice crystal fall speed
14 used in these cases produces a similar mean fall speed to the simulations that use two ice
15 prognostics.

16 The higher RH in the simulations using the generic ice PSD could be due to the larger, faster
17 falling particles in the levels below 12 km removing more of the LWC via riming, which
18 would allow for greater supersaturation. More riming would release more latent heat, which
19 along with the larger ice particles being more effectively off-loaded, could lead to the
20 generation of stronger updrafts with less entrainment and higher RH in the upper troposphere.
21 This is illustrated in the convective updraft ($> 1 \text{ m s}^{-1}$) horizontal mass divergence profiles
22 shown in Figure 5a. As discussed by Yuter and Houze (1995), the presence of decelerating
23 updrafts and accelerating downdrafts can be largely explained by entrainment. Entrainment
24 reduces the buoyancy of updrafts, slowing and eventually stopping the air parcel, which is
25 where divergence is expected. In contrast, entrainment into downdrafts enhances evaporative
26 cooling, increasing the downward mass transport and convergence. Note that above 16 km the
27 vertical velocities show oscillatory motions consistent with gravity waves, and therefore,
28 above this height the mass divergence appears to be driven by these waves.

29 Figure 5a shows that horizontal mass divergence in the mixed-phase regions of the convective
30 updrafts is the most sensitive to the turbulence formulation in the model, with the simulation
31 with greater turbulent mixing (3d) showing greater mass divergence, indicative of greater
32 entrainment, in the range of 5 – 8 km. This contrasts with the upper ice-only regions of the

1 convective updrafts that show that the largest control on horizontal mass divergence is the ice
2 sizes. The simulations with smaller sized particles have more mass divergence above 12 km,
3 indicating more entrainment and a larger reduction in the buoyancy in the upper levels of
4 convective updrafts than the simulations with larger sized ice particles. This is confirmed by
5 examining the convective updraft buoyancy properties at 14 km shown in Figure 5b and c.
6 The buoyancy, $\Delta \theta_d$, is calculated from the difference in the density potential temperature
7 (that includes condensate) from the slab mean for the convective updrafts with vertical
8 velocity $> 1 \text{ m s}^{-1}$. Comparing the equivalent potential temperature as a function of $\Delta \theta_d$ at 14
9 km (Fig. 5b) between simulations with larger and smaller ice sizes shows that for the
10 positively buoyant updrafts, the simulation with smaller ice sizes has fewer occurrences of
11 high θ_e . This gives support to the argument derived from the convective updraft horizontal
12 mass divergence that entrainment is larger in the upper ice-only convective updrafts when the
13 ice sizes are smaller, although we do note that some of this difference could be due to
14 differences in freezing. To analyse this in more detail, the histogram of convective updraft
15 buoyancy (Fig. 5c) shows a greater number of occurrences of more positively buoyant clouds
16 at 14 km for the simulations that have larger sized ice particles, supporting the argument that
17 less horizontal mass divergence represents less entrainment with more positively buoyant
18 updrafts that penetrate higher (as confirmed by examining the cloud top height distributions;
19 not shown). Similarly, comparing θ_e as a function of $\Delta \theta_d$ at 6 km between the control
20 simulation and the one that increases turbulent mixing, shows that the case with greater
21 mixing has significantly more occurrences of low θ_e , consistent with greater entrainment.

22 **3.1 Radar reflectivity characteristics**

23 The model hydrometeor fields have been converted into radar reflectivities by assuming
24 Rayleigh scattering, with no consideration of the effects of attenuation or attempt to model the
25 radar bright band. Due to the long wavelength of the CPOL radar (5.3 cm) modelled
26 reflectivity is calculated following Hogan et al. (2006) where the reflectivity is considered
27 proportional to mass squared

$$28 \quad Z = R \int_0^{\infty} M(D)^2 N(D) dD \quad (4)$$

29 where $R = 10^{18} \frac{|K|^2}{0.93} \left(\frac{6}{\pi \rho} \right)^2$, ρ is the particle density and the mass M and particle size

1 distribution $N(D)$ are defined by (1) and (2). For cloud liquid water the reflectivity is
2 calculated from the constant number concentration of 100 cm^{-3} in the simulations with the
3 size distribution $N(D) = PD^2 \exp^{-\lambda D}$, where $P = N/2\lambda^3$ following McBeath et al. (2014).
4 The dielectric factor $|K|^2$ is set to 0.93 for water and 0.174 for ice. The particle densities used
5 in the calculation of R are 1000 kg m^{-3} for rain, 917 kg m^{-3} for aggregates and crystals and
6 500 kg m^{-3} for graupel. For the simulations that use the generic ice PSD parameterisation, the
7 aggregate reflectivity is proportional to the 4th moment of the PSD, which is calculated from
8 the Field et al. (2007) moment estimation parameterisation.

9 **3.1.1 Statistical radar coverage analysis**

10 To examine the temporal evolution of the mesoscale convective system and evaluate the
11 modelled MCS lifecycle and the simulated reflectivities, a statistical coverage product has
12 been produced following May and Lane (2009). The data used to construct the statistical
13 product are reflectivity fields from CPOL and the simulations every 30 minutes for 12 hours
14 from 12 – 24 UTC. At each height the fraction of the total area within the radar domain
15 covered by reflectivity thresholds is calculated, with the thresholds chosen as 10, 20, 30 and
16 40 dBZ.

17 The observed statistical radar coverage product shown in Figure 6 illustrates the development
18 of the MCS. At 12 UTC the radar domain has a low fractional area coverage of up to 0.15 for
19 the 10 dBZ threshold, showing that at 12 UTC there were radar-detectable hydrometeors
20 covering 5 – 15% of the radar sampling area between the lowest detectable altitude of 1.5 km
21 and 8 km. Highest reflectivity echo tops of 11 km are seen in the > 10 dBZ fractional
22 coverage at 17:30 UTC, which coincides with the time that the very cold cloud tops
23 associated with deep convective cells were seen in the satellite imagery (Fig. 2). The
24 maximum coverage of the domain by hydrometeors with reflectivities > 10 dBZ is 85% seen
25 at 21 – 22 UTC, which is when the large anvil cloud shield appears a few hours after the
26 deepest convection occurs. The observed areas of reflectivity > 10 dBZ are fairly uniform
27 with height from 2 – 6 km, demonstrating little variability of the reflectivity echo coverage
28 from the low levels to a couple of kilometres above the freezing level. Fractional areas larger
29 than 0.05 with reflectivities > 20 dBZ are mostly confined to below 6 km, with the maximum
30 fraction of 0.65 occurring at 21 UTC at 4 km. The > 30 dBZ area is not greater than 10% until

1 16 UTC, and is maximum between 20:30 – 22 UTC at 4 km with a value of 0.35. There is no
2 fractional area of the domain > 0.05 that contains observed reflectivities greater than 40 dBZ.

3 While the statistical radar coverage product produced for the control simulation does show a
4 transition to widespread stratiform cloud regions, as shown by the peak < 10 dBZ coverage at
5 21 UTC, and predicts the timing of the deepest clouds generally well (Fig. 6), there are clear
6 deficiencies in the simulated evolution of the MCS. There are much larger high dBZ
7 fractional areas, deeper clouds occur too early in the simulation and there is a strong vertical
8 gradient in the area coverage with height. The less uniform vertical area coverage shows that
9 the simulated clouds have more variability in reflectivity with height compared to the
10 observations. In coarse resolution models a common model error is too little detrainment at
11 the freezing level (e.g. Franklin et al. 2013), however, in this convection permitting
12 simulation the change in hydrometeor area with height is mainly due to too little stratiform
13 cloud and rain area, which explains the reduction in area below the melting level and the
14 convective-stratiform modelled ratio being skewed towards more convection than is observed
15 (discussed in section 3.2.2).

16 A clear difference between the observations and the simulation is the > 20 dBZ reflectivity
17 areas above the freezing level. The observations show some hydrometeors present 1 – 2 km
18 above the freezing level that have reflectivities > 20 dBZ, but no areas that meet the minimum
19 threshold of 5% that have reflectivities > 30 or 40 dBZ. The simulation on the other hand
20 shows large > 20 dBZ fractional areas > 0.6 indicative of larger ice particles in the model than
21 in the observations, which will be explored in detail later. The simulated reflectivity area > 30
22 dBZ above 5 km is due to the presence of both ice and rain, and the > 40 dBZ areas are almost
23 exclusively due to rain. The simulated rain above the freezing level that is not observed
24 suggests that the model has faster updrafts than observed, which loft large rain particles
25 upwards and/or the heterogeneous freezing of rain that is not represented in the model is an
26 important process in tropical convection and/or other errors in the representation of the rain
27 DSD. This result is what motivated the experiment with the addition of a heterogeneous rain
28 freezing parameterisation as observations in oceanic convection have shown that most drops
29 freeze between about -6 and -18 °C (Stith et al. 2002, 2004; Heymsfield et al. 2009).

30 All simulations show the same main errors in the statistical radar coverage as the control case,
31 nd. The simulation that uses a differing turbulent mixing formulation produces the closest
32 representation of the observed fractional areas for the dBZ thresholds of 10 and 20 dBZ in the

1 larger areas below the melting level (Fig. 6i, j). This can likely be attributed to greater
2 horizontal mass divergence between 5 and 8 km at the earlier convective times (Fig. 5),
3 indicative of increased entrainment and mixing of environmental air in this simulation, which
4 acts to increase the amount of IWC (Fig. 3 and 13) and the area of precipitation.

5 **3.1.2 Contoured frequency by altitude diagrams**

6 The CPOL contoured frequency by altitude diagram (CFAD) using the observations from 23
7 – 24 UTC every 30 minutes exhibits a fairly narrow distribution at the heights above the
8 freezing level, with the altitude range of 12 – 13 km having little variability, reflecting the
9 dominance of small ice particles growing primarily by deposition in the uppermost cloud
10 levels (Figure 7a). Below 10 km the distribution shows increasing reflectivity with decreasing
11 height as particles grow rapidly through aggregation, with reflectivities centred on the modal
12 value of 10 dBZ. At altitudes below the melting level the distribution widens and the
13 reflectivities extend from 5 – 35 dBZ with the largest occurrences around 30 dBZ. The lack of
14 a predominant bright band in the observations is likely due to the data being collected from
15 volumetric scans, however, there are slightly higher reflectivities seen at 4 km indicating a
16 bright band.

17 The simulations all show the common errors of: clouds within these reflectivity regions
18 extending too high, reflectivities that are too large between 4 – 6 km, greater reflectivity range
19 below 4 km, and disjointed profiles due to separate hydrometeor categories. The simulations
20 show more of a convective type profile with broader distributions above the freezing level
21 compared to the observations. The more numerous high reflectivity outliers in the simulations
22 indicate a larger number of deep convective cells and/or a smaller proportion of convective –
23 stratiform area.

24 The simulation with the different dynamical core, ENDGame shown in Figure 7c, shows
25 higher clouds and a broader range of reflectivities at 14 – 16 km. This latter result suggests
26 the presence of large particles being lofted into the upper cloud levels by intense convective
27 cores, as can be seen by the 40 dBZ reflectivities at 17 km. The observations do show some
28 sign of this lofting occurring at 11 – 12 km, however, the reflectivities are constrained to be <
29 20 dBZ. This feature can also be seen in the cases that include the ice splintering process, the
30 limited graupel case and the increased droplet number concentration case. The simulations
31 that use the generic ice PSD parameterisation (Fig. 7b and c) overestimate the occurrence of

1 low reflectivities above 10 km and have a modal reflectivity at 6 – 8 km that is too low
2 compared to the observations. Using explicit ice PSDs produces a closer match to the
3 observed reflectivity distribution above 10 km, although the simulated clouds still have
4 greater vertical extent, and the modal value of the reflectivities at 6 – 8 km with the explicit
5 PSDs is approximately 5 dBZ too large. The inclusion of a heterogeneous rain freezing
6 parameterisation reduces the number of occurrences of reflectivities > 20 dBZ between 5 and
7 10 km and reduces the cloud top heights. Both of these results agree better with the
8 observations suggesting that this process may be important in tropical convective cloud
9 systems. However, given the errors in the dynamics and microphysics in the model for this
10 case, further study is required to better understand the effects of this process. Even in the
11 simulation without graupel the reflectivities are overestimated at the melting level (not
12 shown) and this is due to the ice aggregate PSD.

13 Focussing on the 2.5 km reflectivity distribution shown in Figure 8a allows an evaluation of
14 the rain properties from the simulations, in particular the rain DSD. All simulations except for
15 one use the Abel and Boutle (2012) rain DSD, with the remaining simulation testing the
16 sensitivity of rain drop sizes by using the Marshall-Palmer (1948) DSD. The Abel and Boutle
17 rain DSD represents the observed rain reflectivity distribution fairly well, however, the
18 observed peak of 30 dBZ is underestimated and there are too many occurrences in the tails of
19 the distribution. The contribution from the convective updrafts is demonstrated by the largest
20 occurrences in the high reflectivity tail coming from the simulation with the different
21 dynamical core. It is this ENDGame simulation that produces the strongest updrafts (Fig. 11)
22 and is the least representation of the observed rain reflectivity distribution for the reflectivities
23 > 40 dBZ. The simulation using the Marshall-Palmer DSD peaks at too low a reflectivity at
24 around 10 dBZ and produces too many small rain drops with low reflectivities.

25 At 6km the observations again show a bimodal reflectivity distribution, with the largest peak
26 centred on approximately 16 dBZ (Figure 8b). The simulations show a more complicated
27 distribution at this height with multiple modes due to the presence of multiple hydrometeor
28 species. The simulations that use the generic ice PSD parameterisation peak at -1 dBZ. When
29 this parameterisation is not used and the explicit ice size distribution is used the peak is too
30 high at 24 dBZ. When an additional ice prognostic is added this peak is reduced and compares
31 better to the observations at 18 dBZ, however, the tail of the distribution in these cases is too
32 long with too many occurrences at high reflectivities. While the tail of the distribution for the

1 generic ice PSD cases is also too long, compared to the observed reflectivity distribution these
2 cases represent the graupel reflectivities better than the cases that use the explicit PSD even
3 though all cases use the same graupel PSD. The better graupel representation with the generic
4 ice PSD coupled with the significantly larger occurrence of weak reflectivities around 0 dBZ
5 is similar to the result found by Lang et al. (2011). They modified microphysics
6 parameterisations to reduce the occurrence of excessive large reflectivities and found that this
7 resulted in too many low reflectivities due to a shift in the reflectivity distribution, as is this
8 case here when comparing the generic and explicit ice PSD cases.

9 To examine to what extent the generic ice PSD parameterisation is misrepresenting the
10 observed reflectivities or how much the erroneous cloud dynamics are responsible for errors
11 in the modelled reflectivities, the PSD moments derived from the generic PSD
12 parameterisation using the observed IWC and temperature are shown in Figure 9. In
13 calculating the predicted moments the observed mass-diameter relation was
14 used, $m = 4.97 \times 10^{-3} D^{2.05}$, and the observed moments are calculated only for particle sizes $>$
15 $100 \mu\text{m}$ in diameter and for $\text{IWC} > 10^{-3} \text{ g m}^{-3}$ to be consistent with the data used to derive the
16 Field et al. (2007) parameterisation. The 4th moment is equivalent to radar reflectivity when
17 mass is proportional to the square of the particle diameter, and it can be seen in Figure 9a that
18 the slope of the parameterised reflectivity results in an overestimate of the larger reflectivities.
19 The generic ice PSD parameterisation underestimates the zeroth and first moments and has a
20 good representation of the third moment. The underestimate of the number concentration (Fig.
21 9d) is consistent with the overestimation of particle sizes and reflectivities. The observations
22 in this case may be in a different type of cloud environment from the data used to construct
23 the Field parameterisation, as suggested by the observed number concentration being below
24 the lower range shown in Field et al. (2007).

25 **3.1.3 Maximum reflectivity profiles and vertical velocities**

26 In agreement with many previous studies (e.g. Blossey et al. 2007; Varble et al. 2011) the
27 model overestimates the reflectivity above the freezing level as can be seen in the profiles of
28 maximum reflectivity shown in Figure 10, as well as overestimating the rain reflectivities
29 below 5 km. From the set of simulations it can be seen that graupel is not the sole cause of the
30 significantly higher reflectivities as the simulation without graupel also displays this bias. The
31 largest difference between simulated and observed maximum reflectivity during 23 – 24 UTC
32 occurs above 7 km and increases with height for many of the simulations, with the difference

1 between the simulation with the different dynamical core and the observations at 10 km equal
2 to 40 dBZ. The observations show a decrease in the maximum reflectivity with height from
3 approximately 2 km, whereas the simulations tend to show a more constant profile. The
4 observed reduction in height may be due to large raindrops falling out of strong updrafts or
5 due to raindrops falling through weak updrafts and growing due to the accretion of cloud
6 droplets. The likely overestimate in updraft strength in the simulations (shown next) will
7 advect the raindrops upwards allowing these particles to be collected by the existing ice,
8 generating larger ice particles and maximum reflectivities above the freezing level, as well as
9 acting as a source of latent heating to further fuel convective updrafts. The simulation that
10 decreases the maximum reflectivity with height the most is the simulation with differing
11 subgrid turbulent mixing (Figure 10b), which suggests weaker updrafts. The addition of a rain
12 heterogeneous freezing parameterisation follows the different turbulence simulation in
13 reducing the maximum reflectivity from the freezing level up to 8 km, reflecting the reduction
14 in rain and a better representation of the reflectivities.

15 At 17 – 18 UTC, when the greatest amount of deep convection occurs in all of the simulations
16 and the coldest satellite derived cloud top temperatures are observed, the CPOL maximum
17 reflectivity profile has a more constant profile with a slower reduction of reflectivity with
18 height as compared to the later less convective times (Fig. 10). The observed 40 dBZ contour
19 reaches 8 km in agreement with the results of Zipser et al. (2006) who showed that radar
20 echoes of this strength rarely occur above 10 km. The profile of maximum reflectivity from
21 the simulation that uses the new dynamical core shows essentially the same profile at these
22 strong convective times as for the later times when the MCS has matured, unlike the
23 observations and the majority of the simulations, suggesting that there is less variability in
24 maximum updraft when using ENDGame. There is little spread in the maximum reflectivity
25 profile across the simulations at 17 – 18 UTC, with strong updrafts $> 20 \text{ m s}^{-1}$ in all
26 simulations (not shown) that allows large particles to be advected into the upper troposphere.
27 There is a clear difference in the two simulations that limit or exclude graupel, demonstrating
28 that at the time of strongest convection, the vertical advection of graupel is responsible for the
29 largest error in the maximum reflectivities in the upper troposphere.

30 Comparing the control case with the cases that use a different dynamical core and different
31 turbulent mixing parameterisation shows that the reduction in maximum reflectivity with
32 height at 23 – 24 UTC is well correlated with the reduction in maximum vertical velocity

1 shown in Figure 11b. These cases all use the generic ice PSD and the differences are likely
2 due to the different entrainment and water loading that affects the cloud buoyancy and the
3 strength of the updrafts that advect large particles into the upper troposphere. The ENDGame
4 simulation produces significantly larger maximum updrafts and has less accumulated ice
5 water (see Fig. 13). Conversely there is greater accumulated IWC for the simulation with the
6 different turbulent mixing parameterisation compared to the control case, supporting the
7 argument that water loading differences likely contribute to the differences in maximum
8 vertical velocities and maximum reflectivities.

9 Comparing the differences in maximum vertical velocity across the simulations for the times
10 23 – 24 UTC shows that the largest sensitivity tends to come from the choice of dynamics and
11 turbulence. The reduction in updraft strength at these times with the 3D Smagorinsky
12 turbulence scheme is also achieved with the inclusion of a heterogeneous freezing rain
13 parameterisation. Both of these cases tend to have larger ice water contents in strong updrafts
14 (see Fig.12) that will reduce buoyancy through the effect of water loading. While there is
15 different sampling between the aircraft observations and the simulations, the aircraft
16 observations of maximum updraft strength shown in Figure 11 are smaller than the
17 ENDGame simulation by as much as 20 m s^{-1} . In this simulation it seems as though the
18 stronger and deeper updrafts are able to generate enough latent heating that this effect on
19 buoyancy is larger than that of entrainment and water loading as compared to the other cases.
20 The in-cloud mean vertical velocity for this simulation is also larger than the other cases from
21 4 – 8 km, as well as the 99th percentile of upward vertical motion (Figure 11). The shape of
22 the mean updraft velocity is similar for the ENDGame case and the simulation without
23 graupel, both showing greater mean updraft strength from 3 to 7 km. These two simulations
24 produce the largest domain mean rain rate (Fig. 3a) at these times and show that dynamical
25 changes to the cloud system can be achieved through changes to the model's dynamical core
26 and the cloud microphysics.

27 While the maximum updrafts produced by the simulations at these times are within the range
28 of observed maximum tropical updrafts from other field campaigns at Darwin (e.g. $< 25 \text{ m s}^{-1}$
29 in TWP-ICE; Varble et al. 2014a), the maximum updrafts produced throughout the MCS
30 lifecycle are much larger and in excess of 50 m s^{-1} for the ENDGame simulation at 17 – 18
31 UTC. These values are well outside the range of maximum vertical velocities presented for
32 oceanic convection by Heymsfield et al. (2010) and agree with other studies showing

1 excessive tropical vertical velocities simulated by convection permitting models. Hanley et al.
2 (2014) demonstrated that the UM with a grid length of 1.5 km simulated convective cells that
3 were too intense and were initiated too early, as was also shown by Varble et al. (2014a),
4 suggesting that convection is under resolved at grid lengths of order 1 km. Improved initiation
5 time was shown by Hanley et al. (2014) to occur when the grid length was reduced to 500 and
6 200 m. However, the intensity of the convective cells was not necessarily improved, with the
7 results being case-dependent. Varble et al. (2014a) showed that in the tropics the intensity of
8 the updrafts remained overestimated even at the 100 m grid length. Both of these studies
9 suggest that there are missing processes in the model and/or the interactions between
10 convective dynamics and microphysics are incorrectly represented.

11 Most of the simulations show a double peak in vertical velocities with maxima at 3 km and in
12 the upper troposphere at about 13 km. The upper level updraft peak has been observed (e.g.
13 May and Rajopadhyaya 1999) and is argued to be due to the deep column of convectively
14 available potential energy in the tropics, coupled with latent heat released by freezing
15 condensate and the unloading of hydrometeors, both of which increase parcel buoyancy. A
16 bimodal peak has been observed but tends to be correlated with the freezing level rather than
17 a couple of kilometres lower as in the simulations. The apparent lack of observational support
18 for the low level peak is likely due to the inability of many observations to distinguish
19 between non-precipitating cloud and clear air, and dual profiler measurements during TWP-
20 ICE do show some evidence of a low level peak (Collis et al. 2013).

21 **3.2 Phase composition and comparison with in situ observations**

22 Due to the small sample size of observations from the single research flight on 18/02/2014,
23 the observations from 18 of the Darwin HIWC flights have been used to allow for a more
24 robust comparison of the model to the observations (Fig. 12 and 14). The majority of the
25 flight time for these cases was in clouds with temperatures < -10 °C and vertical motions
26 within the range of -2 to 2 m s⁻¹. Therefore, when comparing the model to the aircraft
27 observations, the focus is on this subset of cloud conditions as there are limited observational
28 samples outside of these ranges.

29 In the simulations, the relationship of IWC to vertical velocity changes with the temperature
30 regime, as shown in Figure 12. For the warmest range of 0 to -5 °C the IWC reduces as the
31 strength of the updraft increases from 1 m s⁻¹. For the two intermediate temperature regimes, -

1 5 to -10 and -10 to -20 °C, the IWC is fairly constant with vertical velocities greater than 2 m
2 s⁻¹, with the colder regime consisting of 1 g m⁻³ more ice for a given vertical velocity. For the
3 coldest regime analysed the IWC increases as the vertical velocity increases.

4 For the warmest temperature regime the decline of IWC with updraft speed is offset by the
5 strong increase in LWC, with the fraction of condensate that is supercooled cloud water
6 reaching 0.8 at 15 m s⁻¹ (not shown). In this temperature regime there is no new ice being
7 formed as heterogeneous freezing in the model does not occur until the temperature cools to -
8 10 °C. Any ice in this regime has formed above and has been recirculated into these updrafts,
9 and as the vertical velocity increases the saturation specific humidity increases faster than the
10 supercooled water can be removed by deposition and riming resulting in the large LWC. The
11 circulation of ice from high levels to those below was suggested by Black and Hallett (1999)
12 to be a factor in the observed rapid glaciation of clouds in hurricanes. The no graupel and
13 limited graupel cases do not show the same decline in IWC in the warmest temperature
14 regime. For these cases the fraction of condensate that is supercooled water is lower so there
15 is less competition for the available water vapour, which results in greater depositional ice
16 growth. In these simulations the greater proportion of ice mass with slower fall speeds leads
17 to greater in-cloud residence times producing larger accumulated IWC than the other cases
18 with two ice prognostics (see Fig. 13). This shows that when graupel is included in the
19 simulations and allowed to grow unrestricted, the removal of LWC by ice processes is less
20 efficient in this temperature regime. The other simulation with different behaviour and larger
21 IWC in this warmest regime is the case that includes rain heterogeneous freezing. In this
22 simulation there is an additional source of ice and this results in greater IWC in strong
23 updrafts due to the rain that is advected upwards freezing rather than remaining as liquid
24 water as in the other simulations. The impact of this on the cloud liquid water is to increase
25 the cloud water content in strong updrafts as shown in Figure 12. This is due to the reduction
26 in the riming of cloud water by graupel as compared to the accretion of cloud water by rain.

27 The large IWC in the downdraft regions of the warmer temperature regime is where graupel is
28 expected, which is often located behind and below the convective updrafts (Barnes and Houze
29 2014) where the suggestion is that these larger particles help to generate downdrafts through
30 mass loading (Franklin et al. 2005; Jung et al. 2012). This argument is supported by analysis
31 of the downdraft IWC that shows that the majority of the ice in the downdrafts is graupel. For

1 example in the control simulation, 82% of the ice mass is graupel for the warmest regime
2 downdraft of 5 m s^{-1} .

3 The colder regime of -10 to $-5 \text{ }^\circ\text{C}$ shows IWC invariable to vertical velocity. These colder
4 temperatures will produce a greater difference in saturated vapour pressure and saturated
5 vapour pressure over ice and, therefore, larger depositional growth rates via the Bergeron-
6 Findeisen process than the warmest temperature regime.

7 Compared to the warmer temperature regimes, the temperature regime of -20 to $-10 \text{ }^\circ\text{C}$ shows
8 a small increase in IWC with vertical velocity (Fig. 12c) due to the effects of heterogeneous
9 freezing (that occurs at temperatures $< -10 \text{ }^\circ\text{C}$) on increasing the mass of ice and further
10 increases in the vapour pressure. In agreement with the observations, the simulations increase
11 the IWC from -1 – 2 m s^{-1} , with the mean modelled IWC increasing from 0.5 – 2 g m^{-3} . The
12 observed IWC then drops off but increases again for updrafts $> 13 \text{ m s}^{-1}$. The reduction in
13 observed IWC seems likely to be due to sampling, with few observations in strong updrafts.
14 The spread in IWC across the simulations is typically not statistically significant, particularly
15 for the stronger updrafts, however, the differences can be attributed to the effects that the
16 changes have on producing and removing LWC, with different dynamics, turbulence and
17 microphysics all displaying sensitivities to the amount and distribution of IWC within tropical
18 clouds.

19 Across the temperature regimes the simulations show an increase in cloud LWC with updraft
20 strength (Figure 12e, f), with the LWC reducing as the temperature cools along with the
21 fraction of condensate that is supercooled liquid water. The strongest updrafts are associated
22 with convective cores that will have minimal entrainment and consequently high
23 supersaturations. The simulations that use the generic ice PSD tend to have lower liquid water
24 contents for a given vertical velocity, likely due to the increased accretion and riming growth
25 due to the larger ice particle sizes compared to the explicit PSD (Fig. 4 and 14). Increasing
26 the cloud droplet number concentration in the model only directly impacts the microphysical
27 process of autoconversion between cloud droplets and rain, and reduces the precipitation
28 efficiency. For this case the reduced autoconversion rate does not make a significant
29 difference to the surface rainfall, since the ice processes dominate the rainfall production (see
30 Fig. 3). However, the less efficient transfer of cloud water mass to rain does change the cloud
31 structure with more LWC and a larger amount and fraction of condensate being supercooled
32 water for the temperatures between -10 and $-30 \text{ }^\circ\text{C}$ (Fig.12). As cloud water is the only liquid

1 water source used in the model for deposition growth via the Bergeron-Findeisen mechanism
2 and that can freeze heterogeneously, this implies potentially greater growth rates for ice.

3 The other simulation that produces more cloud water for updrafts $> 5 \text{ m s}^{-1}$ in the coldest
4 temperature regime is the simulation that includes ice splintering or the Hallet-Mossop
5 process (Fig. 12f). Looking at the accumulated ice crystal mass between the simulation that
6 does and does not include an ice splintering parameterisation (Fig.13, qcf2 and qcf2hm),
7 shows that while there tends to be less crystal mass at most heights when the H-M process is
8 included, there are crystals present in updrafts up to 15 m s^{-1} , whereas in the qcf2 case there
9 are no crystals present in updrafts $> 4 \text{ m s}^{-1}$ (not shown). Similarly for the aggregates there is
10 ice spread across a wider range of updrafts when the H-M process is included, particularly for
11 the colder temperatures, resulting in a larger accumulated amount of snow and total ice (Fig.
12 13). The generation of a larger quantity of ice crystal mass in the H-M zone allows for a larger
13 amount to be transported to the upper cloud levels by the convective updrafts where the
14 crystals then grow through deposition, riming and aggregation producing a larger mass of
15 snow.

16 The observed mean mass-weighted ice diameter shown in Figure 14 increases with warmer
17 temperatures and shows a strong dependence on IWC, with the characteristic size decreasing
18 with increasing IWC reflecting the dominance of smaller particles for higher IWC. This
19 contrasts with the lack of dependence of mean ice particle size on IWC that has been observed
20 in earlier flights over Darwin and Cayenne in 2010 – 2012 (Fridlind et al. 2015) but agrees
21 with more recent findings by Leroy et al. (2015). These findings show similar results to those
22 documented by Gayet et al. (2012), with high concentrations of ice crystals occurring in
23 regions of ice water content $> 1 \text{ g m}^{-3}$ sustained for at least 100 s at Darwin (Leroy et al.
24 2015) and $> 0.3 \text{ g m}^{-3}$ in the over shooting convection in the midlatitudes in Western Europe
25 (Gayet et al. 2012). Gayet et al. (2012) proposed that the high concentration of ice crystals
26 that appeared as chain-like aggregates of frozen drops, could be generated by strong updrafts
27 lofting supercooled droplets that freeze homogeneously. However, using updraft parcel model
28 simulations, Ackerman et al. (2015) showed that this process produced a smaller median mass
29 area equivalent diameter than is observed. They proposed a number of other possible
30 microphysical pathways to explain the observations, including the Hallett-Mossop process
31 and a large source of heterogeneous ice nuclei coupled with the shattering of water droplets
32 when they freeze.

1 The modelled mean snow diameter increases with increasing temperature, reflecting the
2 process of aggregation, however, the modelled snow PSD also increases the mean diameter
3 with increasing IWC, with the rate of increase being similar in both the generic ice PSD and
4 the explicit specified gamma size distribution. The mean diameter from the generic ice PSD
5 tends to agree reasonably well with the observed size for $IWC < 0.5 \text{ g m}^{-3}$, however, the sizes
6 are significantly overestimated for $IWC > 0.5 \text{ g m}^{-3}$. Given that the number concentration is
7 dependent on the size of the particles, for a given IWC this implies that the generic ice PSD
8 simulates larger concentrations of larger particles than the observations. This reflects the data
9 that was used to develop the generic ice PSD coming largely from stratiform clouds with
10 smaller IWC and larger ice particles. The explicit gamma PSD shows the opposite behaviour,
11 underestimating the mean ice diameter for $IWC < 0.5 \text{ g m}^{-3}$ and matching the observed size
12 for higher IWC. To more accurately represent the snow sizes in the model for this case
13 requires a double moment microphysics scheme to be able to better capture the observed
14 variability of the PSD, or the use of a wider data set that includes high IWC observations to
15 generate a more applicable generic ice PSD parameterisation for modelling tropical
16 convective cloud systems.

17 **4 Conclusions**

18 A set of 1 km horizontal grid length simulations has been analysed to evaluate the ability of
19 the UM to simulate tropical convective cloud systems and to investigate the impacts of
20 different dynamical, turbulent and microphysical representations on the cloud properties,
21 including the phase composition. The case study is February 18 2014 where active monsoon
22 conditions produced a mesoscale convective system in the Darwin area.

23 Analysing 12 hours of observed and simulated radar reflectivity has shown that the
24 simulations capture the intensification and decay of convective strength associated with the
25 lifecycle of the MCS. However, convection occurs too early in the simulations, the radar
26 detectable cloud tops heights are overestimated, as are the maximum reflectivities and areas
27 above the freezing level with reflectivities greater than 30 dBZ. The observed maximum
28 domain averaged precipitation rate coincides with the generation of significant anvil cloud,
29 whereas the simulations generate the highest mean precipitation rate a few hours too early at
30 the times of deepest convection. Observations of maximum vertical velocity suggest that the
31 new dynamical core simulation overestimates the strength of convection at the mature-
32 decaying stage of the MCS. In this case the stronger updrafts contribute to the excessive

1 reflectivities above the freezing level, but this was apparent in all of the simulations albeit to a
2 lesser degree, suggesting that both the updraft dynamics and the particle sizes are responsible
3 for this error.

4 The simulated reflectivity CFADs show more of a convective type profile compared to the
5 observations, with broader distributions and a greater occurrence of high reflectivity outliers.
6 This suggests a larger number of convective cells in the simulations, as was apparent in the
7 plan views of OLR and 2.5 km radar reflectivity, which has been seen in tropical convective-
8 scale model intercomparison studies (e.g. Varble et al. 2014a). The simulation with the
9 differing turbulence parameterisation showed the best agreement with the observed maximum
10 reflectivity at the later times of 23 – 24 UTC. The change to the 3D Smagorinsky scheme
11 induces greater mixing resulting in a reduction of the maximum vertical velocities and
12 reflectivities during the mature-decaying MCS stages. This same reduction in the vertical
13 velocity and reflectivity up to 8 km was also found with a change to the microphysics
14 formulation with the addition of a rain heterogeneous freezing parameterisation. At 17 – 18
15 UTC at the time of deepest convection, all simulations showed a similar error in maximum
16 reflectivity regardless of dynamics or turbulence formulation due to the larger and less
17 variable maximum updrafts across all of the simulations at these times.

18 The largest sensitivities in the maximum updraft velocities are generally produced by changes
19 to the dynamical and turbulence formulations in the model. However, the spread across the
20 simulations for the mean and percentiles of updraft velocity show the greatest sensitivity
21 coming from changes to the microphysical parameters and processes. Changing the
22 microphysics affects the dynamics by altering the vertical distribution of latent heating. The
23 horizontal mass divergence was shown to be most sensitive to the turbulence parameterisation
24 in the mixed-phase regions of the updrafts, where the greater mixing generated larger mass
25 divergence, indicative of greater entrainment at these heights. The upper ice-only regions of
26 the convective updrafts showed that the control on updraft buoyancy was the size of the ice
27 particles. Simulations with smaller particles have fewer occurrences of positively buoyancy
28 convective updrafts, reflecting the importance of the microphysical processes on the
29 convective dynamics.

30 Analysing the relationship between phase composition and vertical velocity for 4 different
31 temperature regimes showed that the phase composition in the modelled convective updrafts
32 is controlled by:

- 1 1. The size of the ice particles, with larger particles growing more efficiently through
2 riming, producing larger IWC.
- 3 2. The efficiency of the warm rain process, with greater cloud water contents being
4 available to support larger ice growth rates.
- 5 3. Exclusion or limitation of graupel growth, with more mass contained in slower falling
6 snow particles resulting in an increase of in-cloud residence times and more efficient
7 removal of LWC.

8 The evaluation of a tropical mesoscale convective system in this study has documented a
9 number of model shortcomings and developments that improve the model performance:

- 10 1. Excessive areas with high reflectivities improve with reduced ice sizes, inclusion of a
11 heterogeneous freezing rain parameterisation, an additional ice prognostic variable and
12 increased turbulent mixing through the use of the 3D Smagorinsky turbulence scheme.
- 13 2. Too much rain above the freezing level is reduced with the inclusion of a heterogeneous
14 rain freezing parameterisation.
- 15 3. Too little stratiform cloud and rain area is increased with increased turbulent mixing.

16 While the listed model changes do improve aspects of the simulations, none of these produce
17 a simulation that closely matches all of the observations. This study has shown the need to
18 include a better representation of the observed size distribution, which could be achieved
19 through the use of a double moment microphysics scheme. Being able to predict both the
20 number concentration and mass would allow the model to better represent the observed
21 variability of the PSD, which would impact the model's representation of the ice water
22 contents and reflectivities, as well as the convective dynamics through the effects of latent
23 heating and water loading on buoyancy.

24

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15

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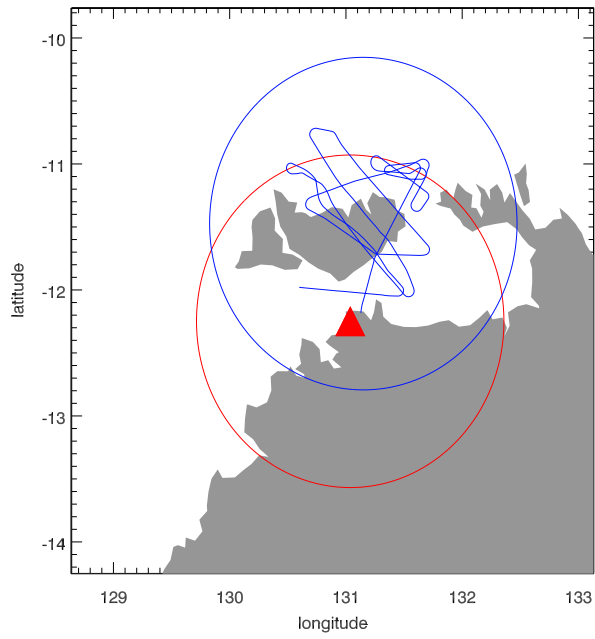
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- 3

1 Table 1. Parameters used to define the mass-diameter relationships (1) and particle size
 2 distributions (2), where $f(T)$ is given by (3).

Parameter	Units	Rain	Aggregates	Crystals	Graupel
a	kg m^{-b}	523.56	2.3×10^{-2}	2.3×10^{-2}	261.8
b		3.0	2.0	2.0	3.0
N_0	m^{-4}	$0.22\lambda^{2.2}$	$2 \times 10^6 f(T)$	$40 \times 10^6 f(T)$	$5 \times 10^{25}\lambda^{-4}$
μ		0	0	0	2.5

3

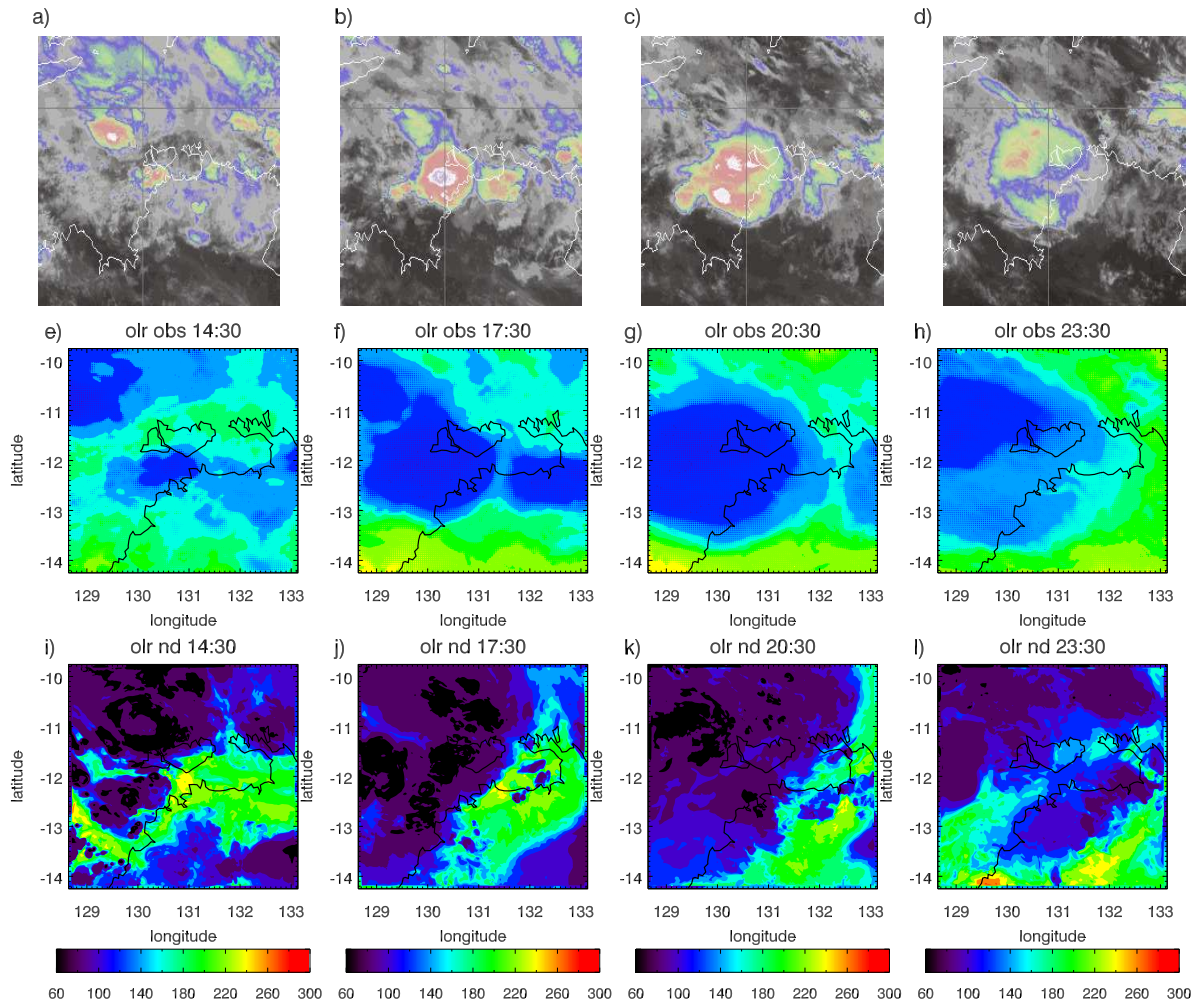
4



1

2 Figure 1. 1 km simulation domain with the radar location denoted by the red triangle and the
3 150 km range of the radar shown by the red circle. The aircraft flight track is shown by the
4 blue line with the domain used in the aircraft comparison given by the blue circle.

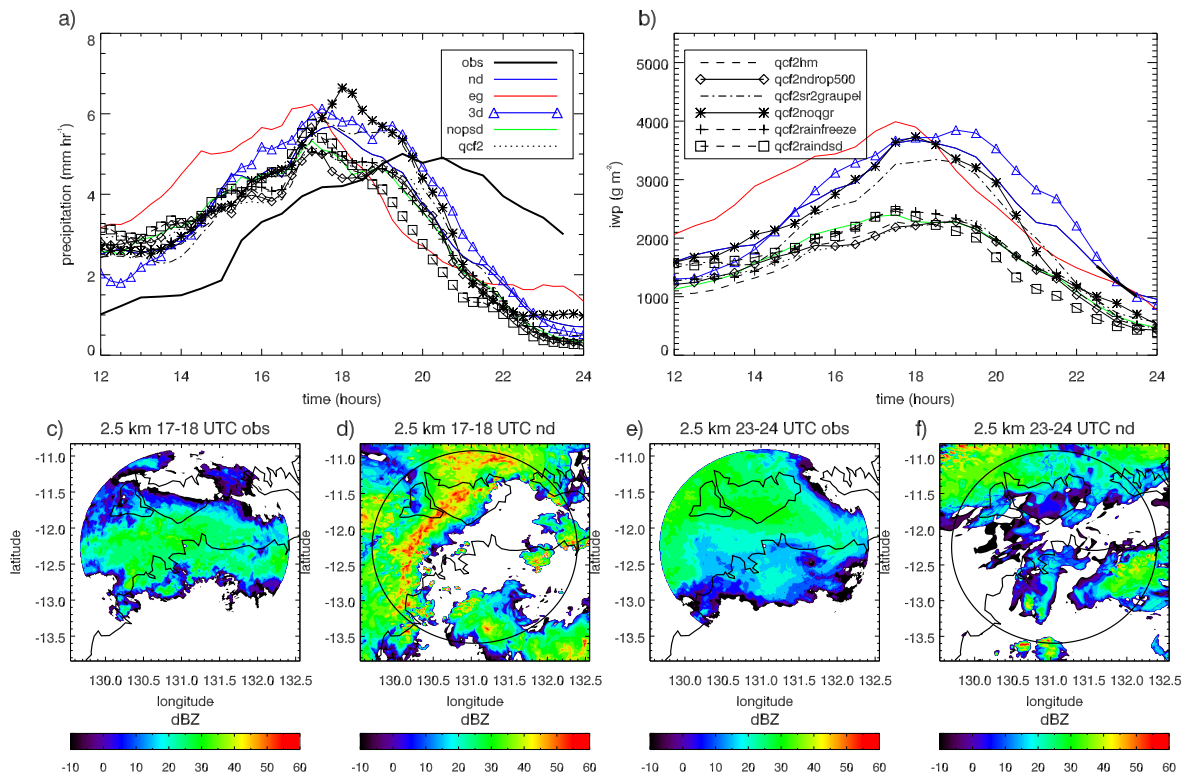
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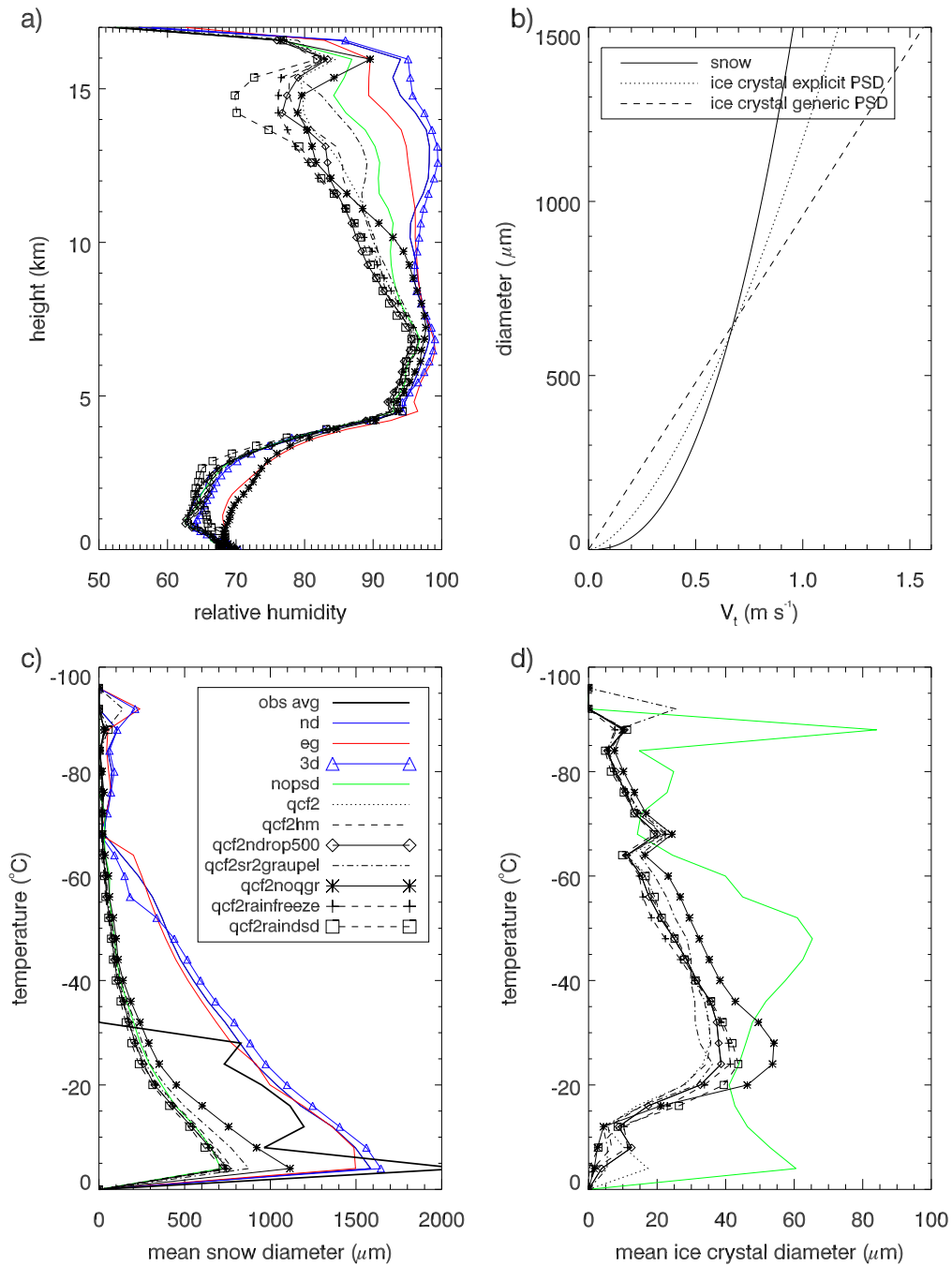
3 Figure 2. Top row: time series of enhanced infrared satellite imagery over the Darwin region
4 on 18/02/2014 a) 14:30, b) 17:30, c) 20:30 and d) 23:30 UTC. Middle row: time series of
5 observed outgoing longwave radiation centred on the Darwin radar, where the pixel level
6 satellite data has been interpolated onto the 1 km model grid. Last row: as above, but for the
7 modelled outgoing longwave radiation from the control experiment labelled nd.

8



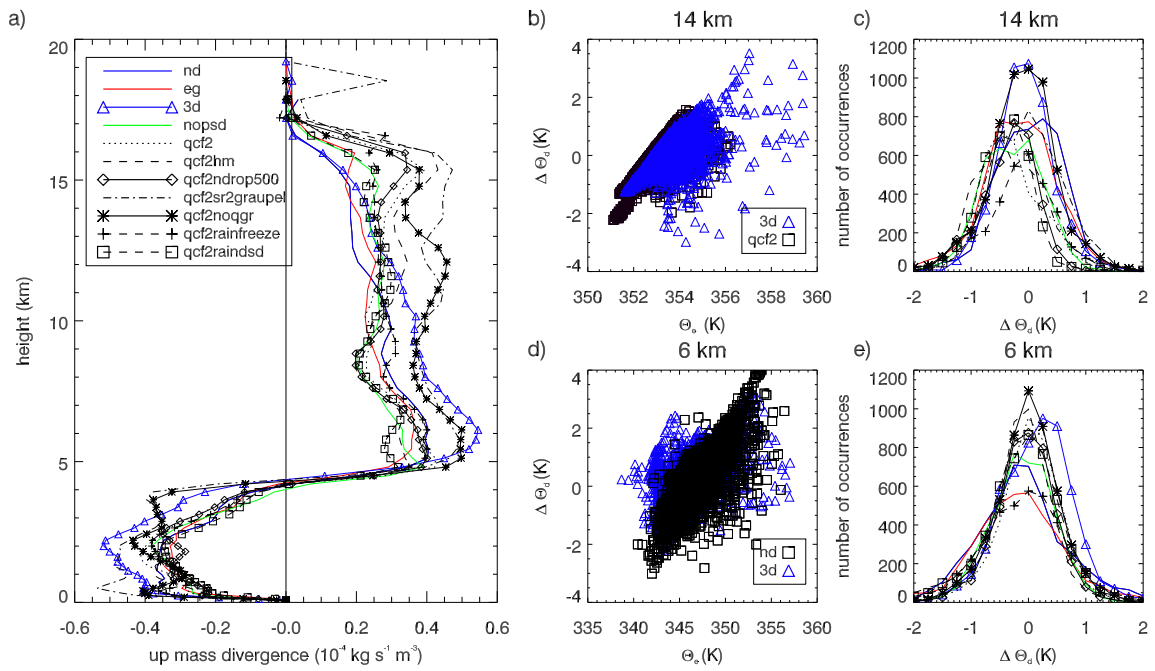
1

2 Figure 3. Time series of domain mean a) precipitation (mm hr⁻¹) and b) ice water path (g m⁻³),
 3 The observations are from the CPOL radar in a) and the satellite retrieval b), note that the
 4 observed IWP is only plotted from 22:30 – 23:30. The time period spans 12 – 24 UTC on
 5 18/02/2014. c) 2.5 km observed radar reflectivity averaged over 17 – 18 UTC, d) as in c)
 6 except for the modelled reflectivity from the control simulation (nd), e) as in c) except for 23
 7 – 24 UTC, d) as in d) except for 23 – 24 UTC.



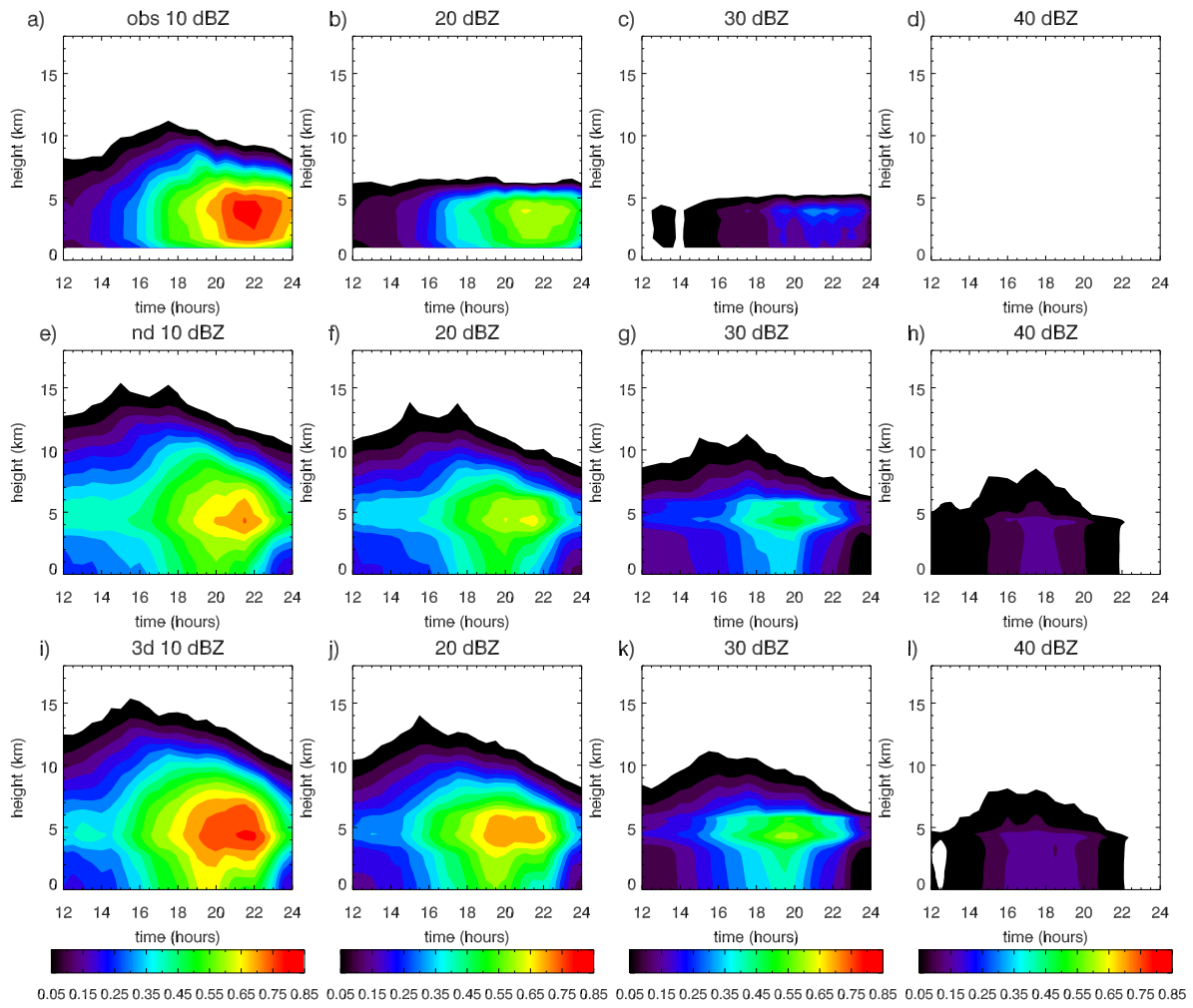
1

2 Figure 4. a) Simulated relative humidity is for the area encompassed by the 150 km radius
 3 centred on the Darwin radar on 18/02/2014 from 23 – 24 UTC. b) Ice fall speeds (m s^{-1}) as a
 4 function of diameter (μm) for the snow category and the ice crystals used in the simulations
 5 with the explicit and generic PSD, see text for details. c) Mean mass-weighted snow diameter
 6 (μm) as a function of temperature ($^{\circ}\text{C}$) where the observations are from the aircraft and have
 7 been averaged to be representative of a 1 km^2 grid cell. d) As for c) except for the mean mass-
 8 weighted ice crystal diameter (μm).

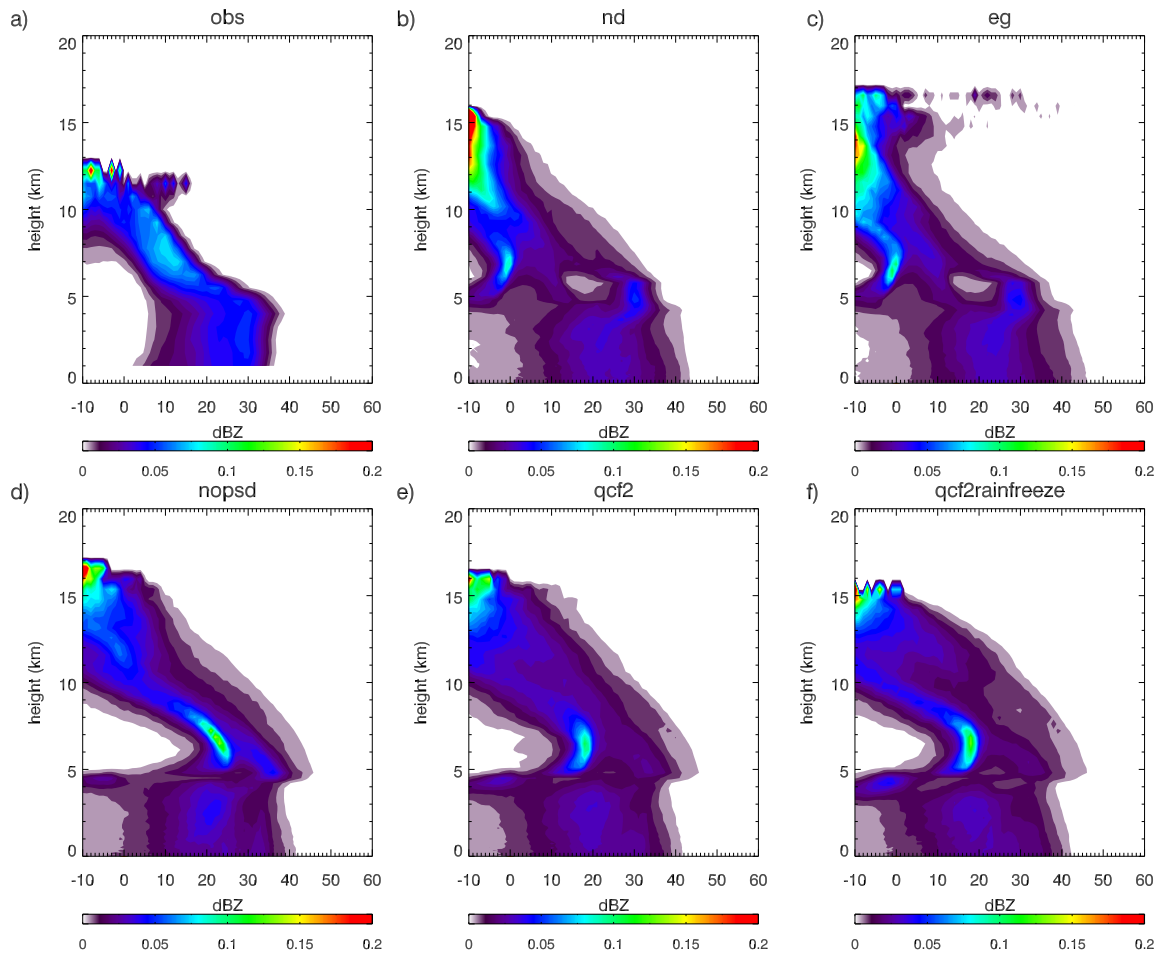


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2 Figure 5. a) Vertical profile of convective updraft (> 1 m s⁻¹) mean horizontal mass
 3 divergence (10⁻⁴ kg s⁻¹ m⁻³) at 18 UTC. b) scatterplot of θ_e against Δθ_d at 14 km for two
 4 simulations that change the turbulent mixing (3d) and add an additional ice prognostic
 5 variable and have smaller ice sizes (qcf2). c) Histogram of Δθ_d at 14 km. d) As in b) except
 6 for 6km and comparing the control (nd) and the 3d simulations, and e) as in c) except for 6
 7 km. See text for details.



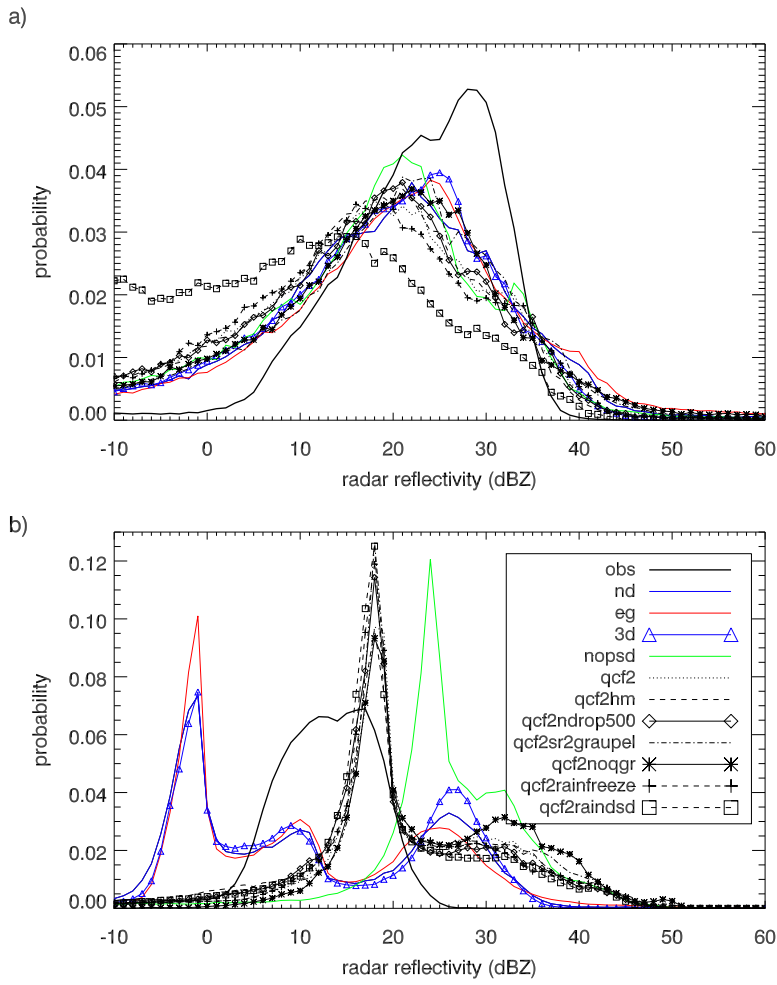
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 2 Figure 6. The observed (top panels), simulated by the control model (middle panels) and
 3 simulated with a change to the turbulent mixing (lower panel) fraction of radar detected area
 4 covered by reflectivities greater than a,e,i) 10, b,f,j) 20, c,g,k) 30 and d,h,l) 40 dBZ for 12 –
 5 24 UTC on 18/02/2014.
 6



1

2 Figure 7. Contoured frequency with altitude diagrams of radar reflectivity for the region
 3 within 150 km of the radar for the times 23 – 24 UTC. a) Observations, b) control simulation,
 4 c) ENDGame dynamical core simulation, c) no use of the generic ice PSD parameterisation,
 5 d) additional ice prognostic and e) inclusion of heterogeneous ice freezing parameterisation.
 6 See text for details on different simulations.

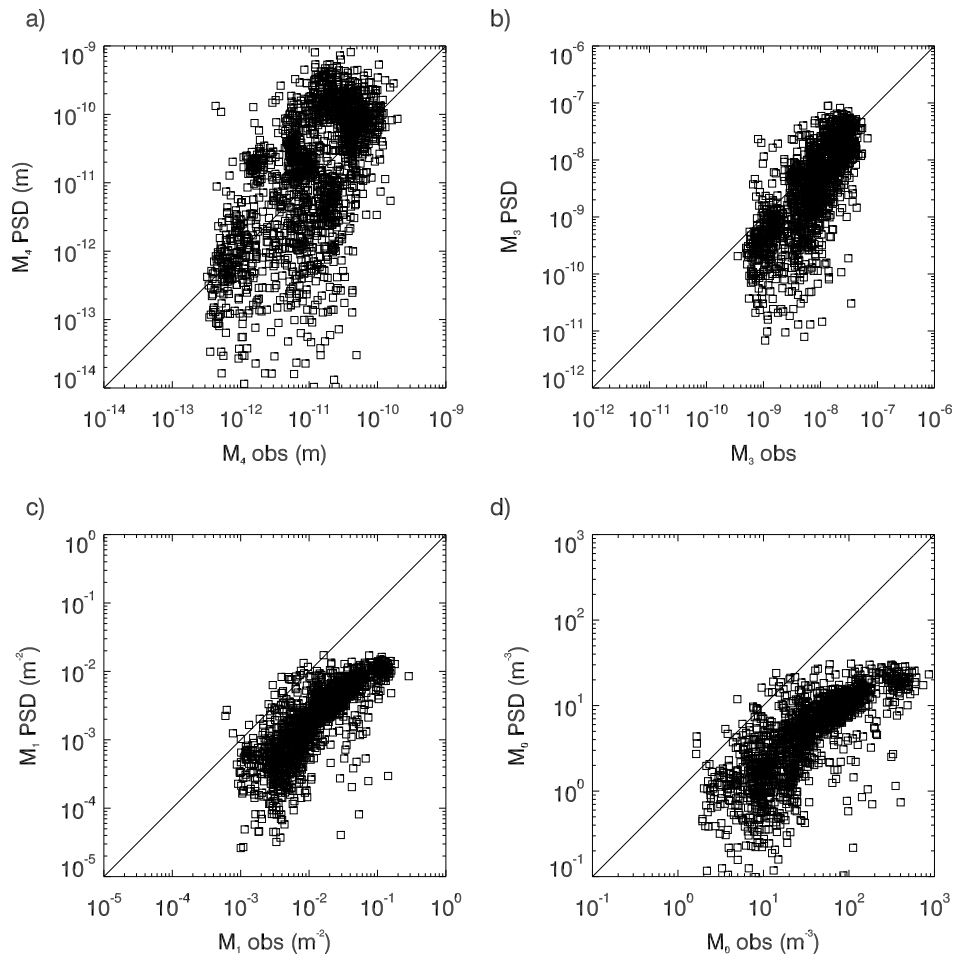
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2 Figure 8. Radar reflectivity probability density functions for two heights, a) 2.5 and b) 6 km.

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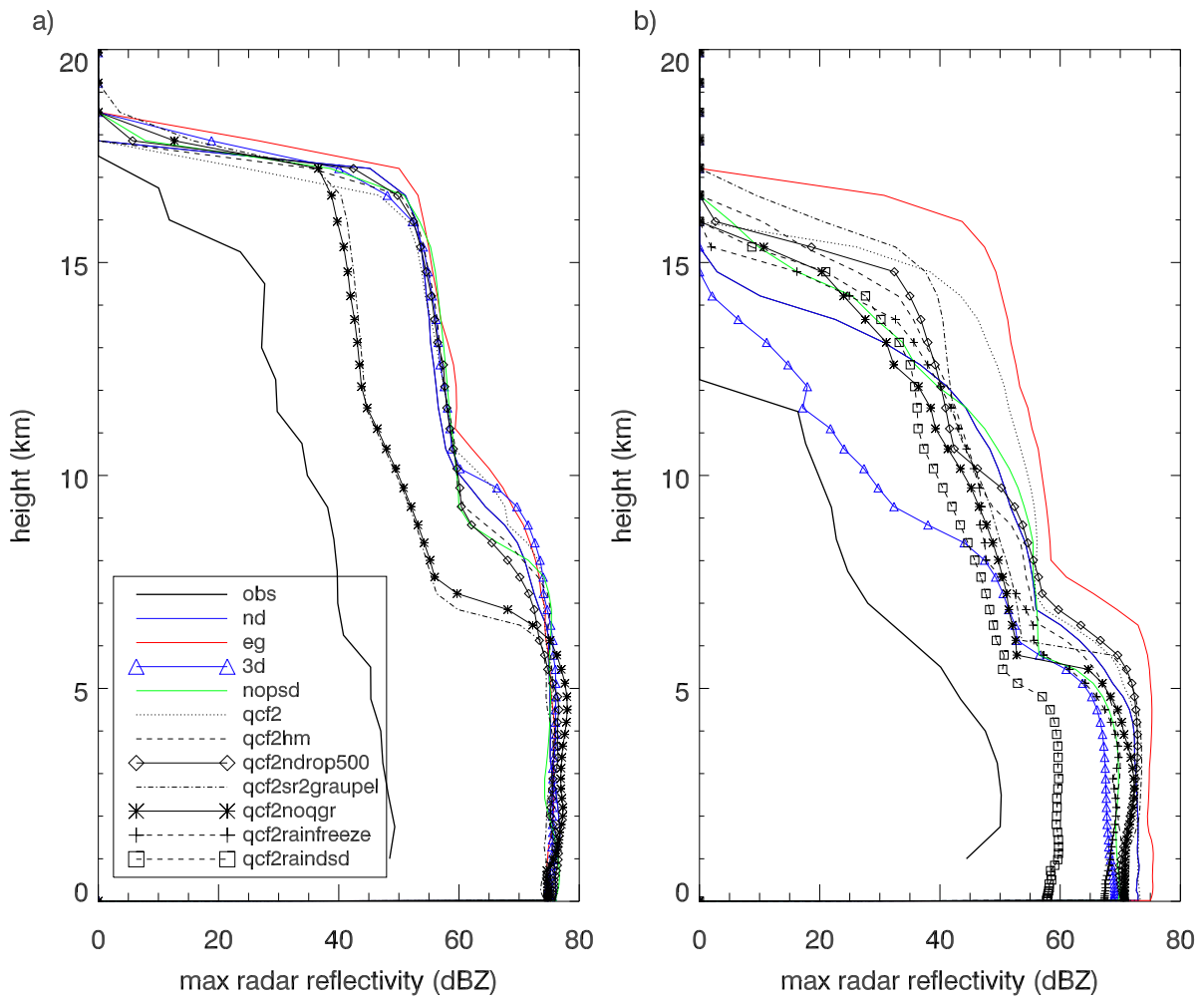


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2 Figure 9. Moments (4th, 3rd; 1st and 0th) of the observed particle size distribution by the aircraft
 3 (for particles with diameters > 100 μm) and predicted using the PSD parameterisation with
 4 the observed ice water content (> 10^{-3} g m^{-3}), temperature and mass-diameter relationship.

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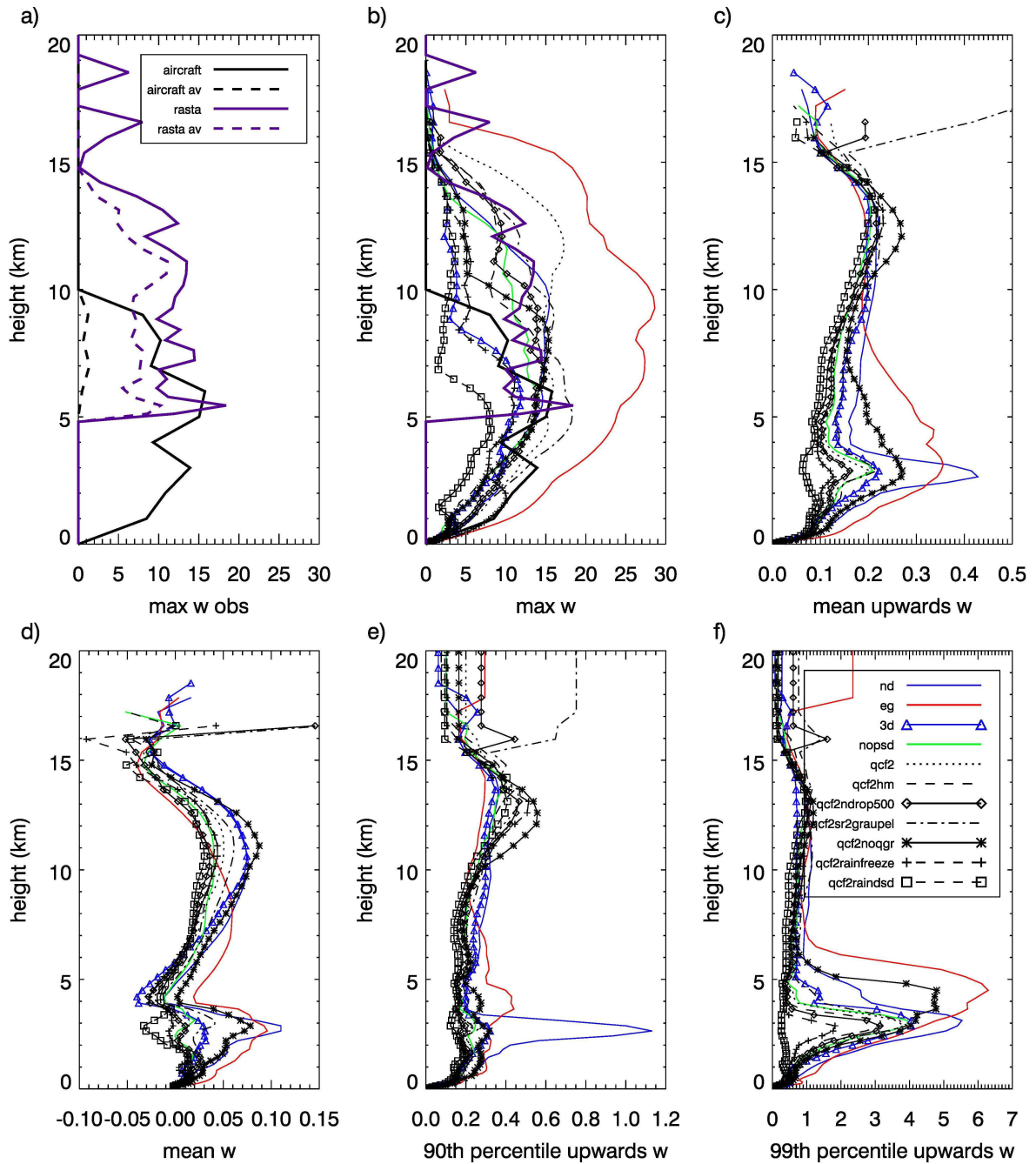


2

3 Figure 10. Profiles of maximum radar reflectivity for the times a) 17 – 18 UTC and b) 23 – 24

4 UTC.

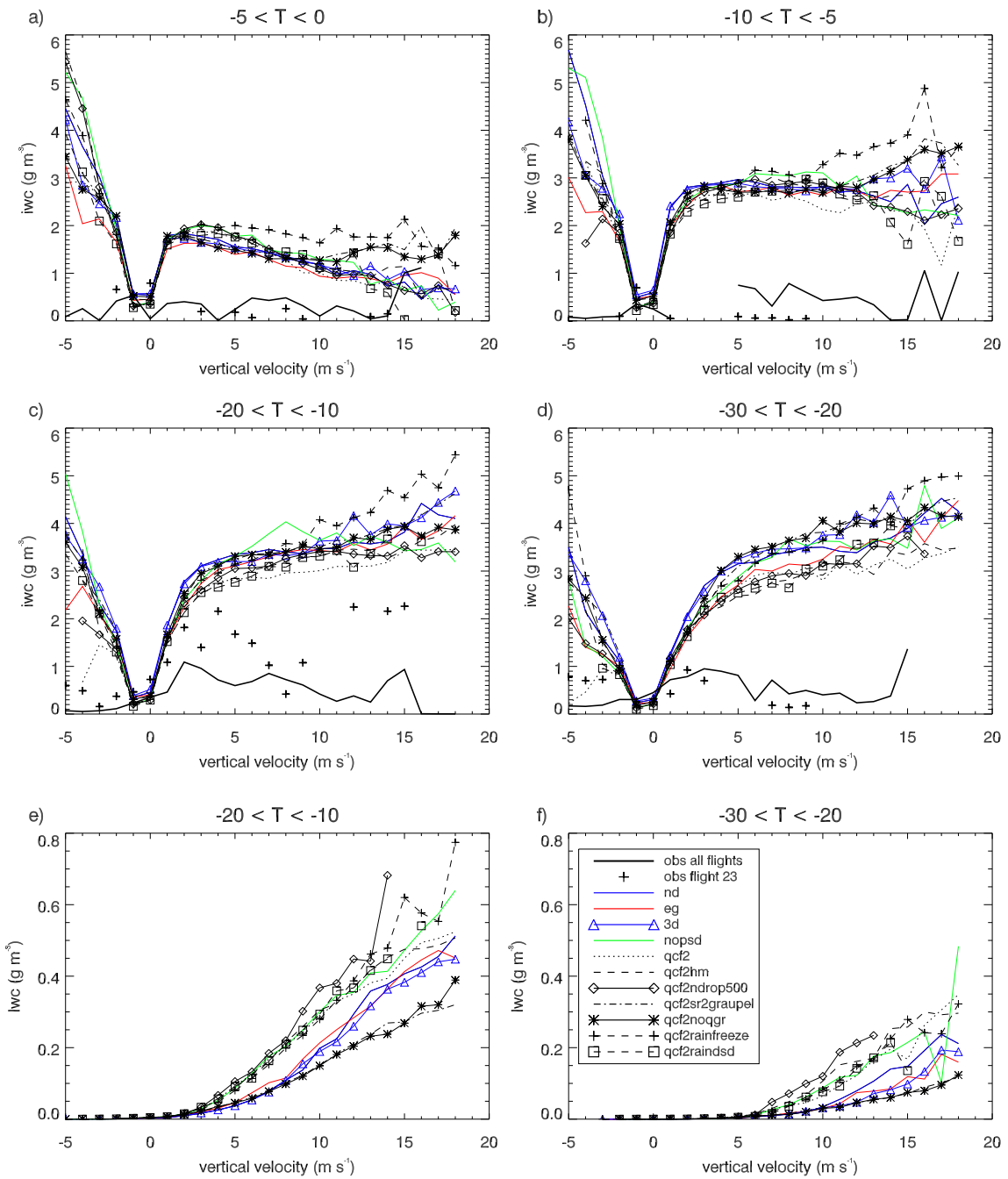
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3 Figure 11. a) Maximum vertical velocity observed by the aircraft and derived from RASTA
 4 (Radar SysTEM Airborne) for the times 23 – 24 UTC. Solid lines are using the highest
 5 resolution observations, dashed lines are using the observations averaged to the 1 km
 6 resolution. Modelled in-cloud vertical velocity statistics (m s^{-1}) over the radar domain for the
 7 times 23 – 24 UTC: b) maximum, c) updraft mean, d) mean, e) updraft 90th percentile, and f)
 8 updraft 99th percentile.

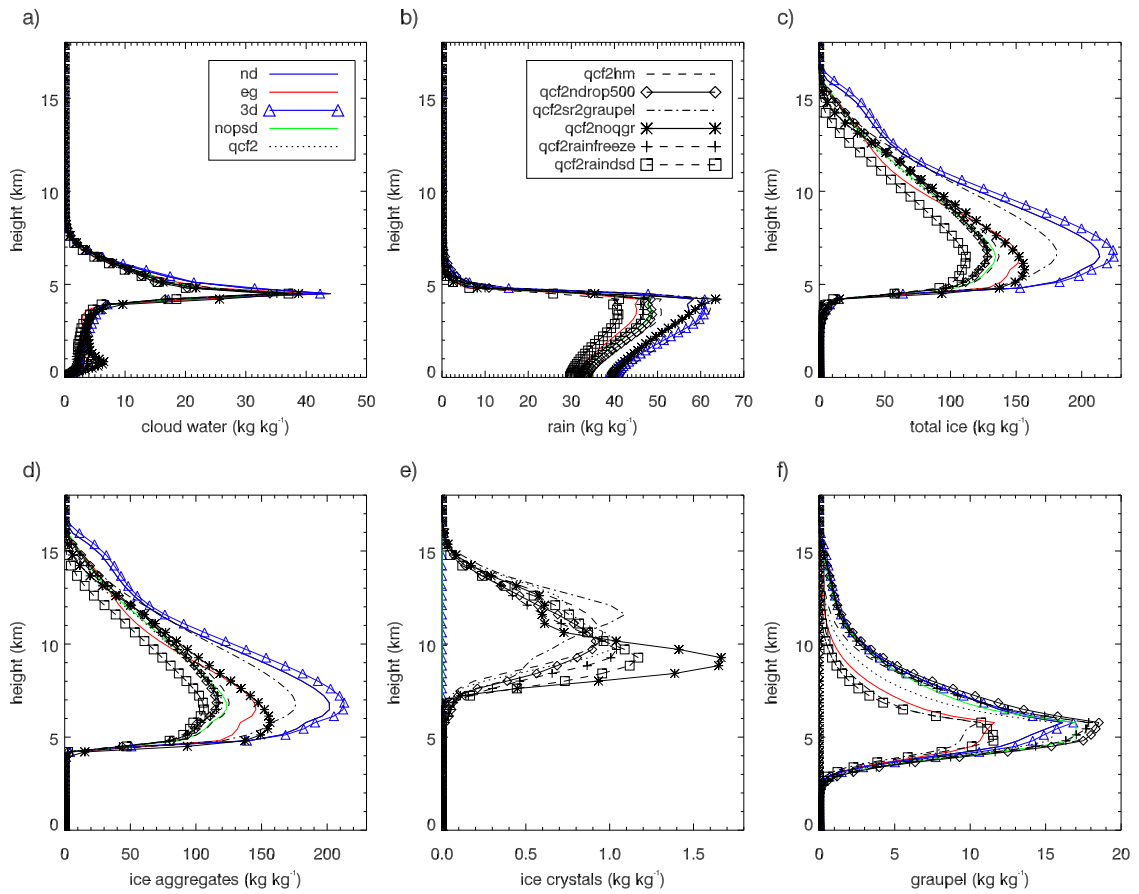
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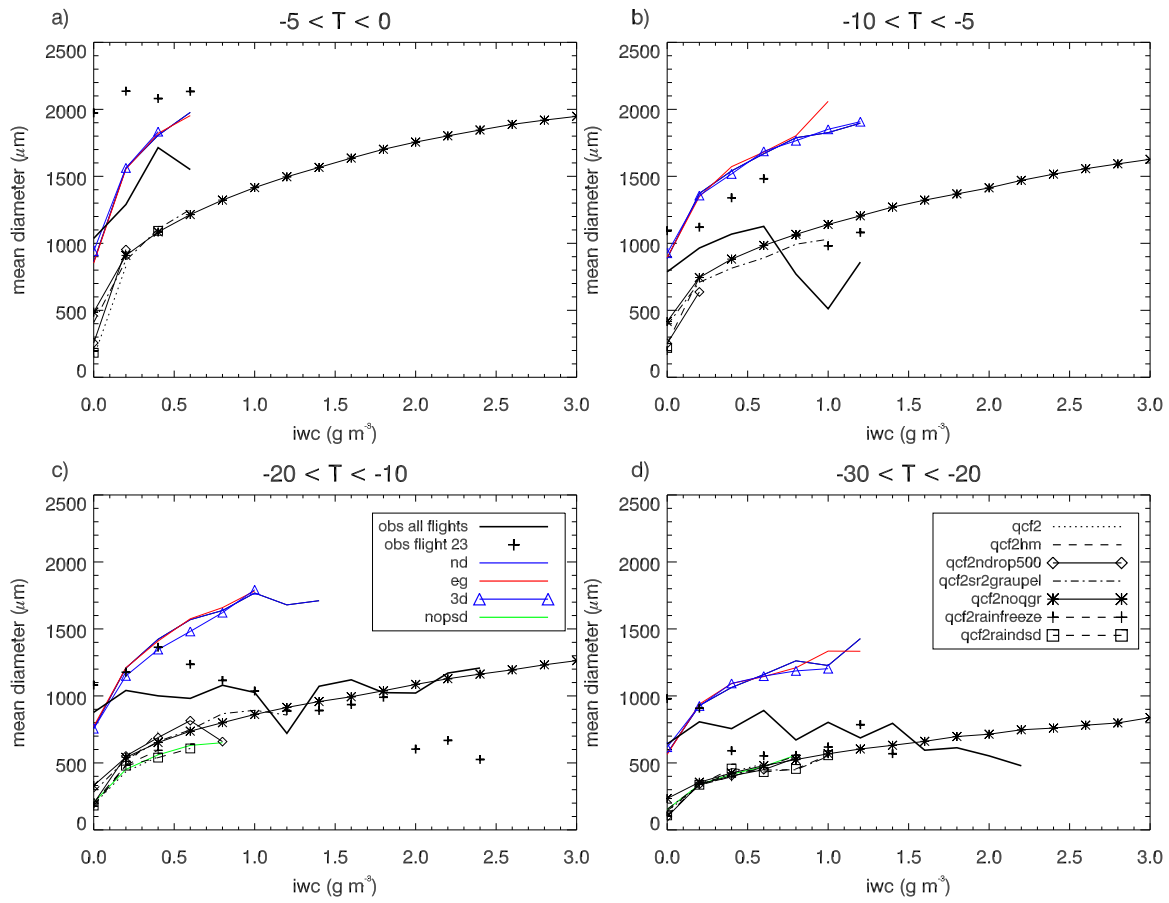
2 Figure 12. Ice water content (g m^{-3}) as a function of vertical velocity (m s^{-1}) for four
 3 temperature regimes: a) $-5 - 0$; b) $-10 - -5$; c) $-20 - -10$, and; d) $-30 - -20$ °C. e) and f) show
 4 liquid water content (g m^{-3}) as a function of vertical velocity for the two coldest regimes: e) -
 5 $20 - -10$, and; f) $-30 - -20$ °C.

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Figure 13. For the aircraft analysis region (150 km radius from the mean aircraft track), the total accumulated water contents (kg kg^{-1}) over the domain from 23 – 24 UTC. a) Cloud liquid water, b) rain water, c) total ice, d) ice aggregates/snow, e) ice crystals and f) graupel.



1

2 Figure 14. Mean mass-weighted ice particle size (μm) as a function of ice water content (g m^{-3}) for four temperature regimes: a) $-5 - 0$, b) $-10 - -5$, c) $-20 - -10$, and; d) $-30 - -20$ $^{\circ}\text{C}$.

3