

DREAM model

J. Brandt et al.

Modelling transport and deposition of caesium and iodine from the Chernobyl accident using the DREAM model

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Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

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Abstract

A tracer model, DREAM (the Danish Rimpuff and Eulerian Accidental release Model), has been developed for modelling transport, dispersion and deposition (wet and dry) of radioactive material from accidental releases, as the Chernobyl accident. The model is a combination of a Lagrangian model, that includes the near source dispersion, and an Eulerian model describing the long-range transport. The performance of the transport model has previously been tested within the European Tracer Experiment, ETEX, which included transport and dispersion of an inert, non-depositing tracer from a controlled release. The focus of this paper is the model performance with respect to the deposition of ^{137}Cs , ^{134}Cs and ^{131}I from the Chernobyl accident, using different relatively simple and comprehensive parameterizations. The performance, compared to measurements, of different combinations of parameterizations of wet and dry deposition schemes has been evaluated, using different statistical tests.

1. Introduction

On 25 April 1986, 21:23 UTC, the worldwide most serious nuclear accident took place at the Chernobyl nuclear power plant in Ukraine. As a result of two explosions in the power plant a part of the radioactive material was emitted into the atmosphere and transported by the wind to distances thousands of kilometers away from the accident site. At the time of the accident only one simple model developed in France was operational (Piedelievre et al., 1990), and used to describe the development of the plume from the nuclear power plant. Following the Chernobyl accident, many national and international activities have therefore been initiated to develop reliable models that can describe transport and dispersion from a single, but strong source. Such tracer models can be used to estimate the spatial and temporal distribution of the concentrations and depositions of the radioactive material from an accidental release. The output from a tracer model can furthermore be used for warning purposes and to estimate the expo-

DREAM model

J. Brandt et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

5
10
15
20
25

sures and the harmful impacts from the dangerous compounds on humans, animals and vegetation.

The use of different instrumentation and sampling methods in the measurements of the concentrations in the period after Chernobyl made it difficult to perform a sufficiently accurate intercomparison and validation of the models in the ATMES report (Atmospheric Transport Model Evaluation Study) (Klug et al., 1992). After the Chernobyl accident, it became evident that one of the main uncertainties in the model results was due to the uncertainty in the emission data and in the parameterization of the deposition processes. A controlled experiment was desirable where these uncertainties were minimized. Therefore an ATMES-II exercise, called ETEX (the European Tracer EXperiment), was initiated in the autumn of 1994. This experiment included two controlled releases, each with a duration of 12 hours, of harmless and non-depositing tracer gases (perfluorocarbon compounds) from Brittany, France, and 168 measurement stations throughout Europe. The first release took place in October 1994 (ETEX-1) and the second release about three weeks later in November 1994 (ETEX-2) under comparable meteorological conditions. The evaluation of ETEX-1 ended in the spring of 1997 and included comparisons of results obtained from many different models. Many of the models used the same meteorological data (data from the European Center of Medium range Weather Forecast, ECMWF, with $0.5^\circ \times 0.5^\circ$ horizontal resolution) as input to the models. The main conclusions from the ETEX evaluation were that the model uncertainties with respect to concentration levels were within a factor of three and within 3–6 h with respect to the arrival time of a plume to a specific location (Nodop, 1997; Brandt et al., 1998a). This was the achievable limit of accuracy in long-range transport and dispersion modelling – even when the uncertainties connected to the emission rate and the deposition processes were diminished.

Additionally a Nordic intercomparison project, EKO-4 (Emergency Exercises and Information), within the 5th NKS project period (Nordic Nuclear Safety Research in the period 1994–1997) was carried out independent of the European comparison program. The purpose was to perform a “partial functionality test” in which a number of institu-

DREAM model

J. Brandt et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

tions from the Nordic countries participated. The developed model system, which is described here, has been evaluated and validated both within the ATMES-II/ETEX program (Brandt et al., 1997b, 1998b; Mosca et al., 1997) and within the NKS Nordic intercomparison project (Brandt et al., 1995a, b, 1997a).

5 Estimates of the emission from the Chernobyl are still very uncertain. However, models have improved considerably since the time of the Chernobyl accident with respect to the treatment of numerical methods, quality of parameterizations and model resolution, partly due to much faster computers. Furthermore, new high quality deposition measurements have become available in the Chernobyl Atlas (De Cort et al., 1998).
10 These measurements, together with measurements from the Radioactivity Environmental Monitoring (REM) database at Ispra have been used in this paper to evaluate the model performance using different parameterizations of wet- and dry deposition. In Sect. 2 a general description of the DREAM model is given. In Sect. 3, the source term used in the present simulations is described. Section 4 includes an extensive
15 description of the different parameterizations of wet and dry deposition that are tested in this paper. In Sect. 5 some examples of model results are given, and results from the comparisons of the different parameterizations of wet and dry deposition are given.

2. The DREAM model

The tracer model is based on a combination of a Lagrangian meso-scale model (the Risø Mesoscale PUFF model, RIMPUFF) and an Eulerian long-range transport model. The combined three-dimensional tracer model is called the DREAM (the Danish Rim-puff and Eulerian Accidental release Model) (Brandt et al., 1995a, b, 1996a, b, c; 1997a, b, 1998a, b, 1999, 2000; Brandt and Zlatev, 1998 and Brandt, 1998). The coupling of a Lagrangian model with an Eulerian model, for modelling atmospheric
20 transport and dispersion from point sources, has been carried out due to both numerical and physical arguments. Numerical treatment of the advection of air pollutants from a single source is not a simple problem. The traditional Eulerian models have
25

DREAM model

J. Brandt et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

DREAM modelJ. Brandt et al.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

© EGS 2002

problems with sharp gradients from a single strong source. The sharp gradients cause unwanted oscillations, also known as Gibbs phenomena. Lagrangian models have, however, problems with uncertainties in the trajectory calculations on long range, due to exponentially increasing errors. Furthermore, the K-theory, which is usually applied for the description of dispersion in Eulerian models, is unsatisfactory near the source. The basic idea of coupling two models in DREAM is to gain advantage of both types of models. The Lagrangian model is used in the area near the source to calculate the initial transport and dispersion of the release. The Eulerian model is used for long-range transport calculations in the whole model domain that, in the present work, covers all of Europe and parts of Asia and Africa. The numerical performance of the coupled model is described in Brandt et al. (1996a).

The model is applied on a polar stereographic projection with a spatial resolution of 25 km × 25 km in the Eulerian model and 5 km × 5 km in the Lagrangian model. The number of grid points in the two domains are 192 × 192 and 105 × 105, respectively and the model has 16 vertical levels.

In order to obtain a more precise description of the mean meteorological fields, the meteorological meso-scale model MM5V1 (Grell et al., 1995) is used as a meteorological driver for the transport model. Coupling DREAM with a meteorological driver increases the computing time considerably, but improves the quality of the meteorological data significantly (Brandt et al., 1998a). Different parameterizations of vertical dispersion, mixing height and different meteorological input data used in the model is described and their performance with respect to ETEX is tested in Brandt et al. (1998a).

2.1. The Eulerian model

Advective transport, dispersion, emission, wet deposition and radioactive decay are described in the Eulerian modelling framework by the equation:

DREAM model

J. Brandt et al.

$$\begin{aligned}
 \frac{\partial C}{\partial t} = & - \left(u \frac{\partial C}{\partial x} + v \frac{\partial C}{\partial y} + \dot{\sigma} \frac{\partial C}{\partial \sigma} \right) \\
 & + K_x \frac{\partial^2 C}{\partial x^2} + K_y \frac{\partial^2 C}{\partial y^2} + \frac{\partial}{\partial \sigma} \left(K_\sigma \frac{\partial C}{\partial \sigma} \right) \\
 & + E(x, y, \sigma, t) \\
 & - \Lambda C - k_r C
 \end{aligned} \tag{1}$$

where C is the tracer mixing ratio, u , v , $\dot{\sigma}$ are the wind speed components in the x , y , σ directions, respectively. K_x , K_y , K_σ are the dispersion coefficients. The horizontal dispersion in the Eulerian model is set constant ($K_x = K_y = 10000 \text{ m}^2 \text{ s}^{-1}$). $E(x, y, \sigma, t)$ is the emission term, Λ is the scavenging coefficient for wet deposition and k_r is representing the radioactive decay. For ^{131}I the half-life is 8.02070 days, for ^{134}Cs it is 2.0648 years and for ^{137}Cs it is 30.07 years. Radioactive decay of ^{134}Cs and ^{137}Cs is not important for short-term simulations and is therefore excluded in the present work. Dry deposition is represented by the term $-v_d C$, which in practice is applied as a lower boundary condition in the vertical dispersion. The vertical discretization in the model system is in σ -coordinates and defined by the pressure, P , normalized by the surface pressure as $\sigma = (P - P_t)/(P_s - P_t)$, where $P_t = 100 \text{ hPa}$ is the pressure at the top of the model domain and P_s is the surface pressure.

The model has been split into three sub-models (Brandt and Zlatev, 1998) including: (1) three-dimensional advection, horizontal dispersion and emission, (2) vertical dispersion and dry deposition, and (3) wet deposition and radioactive decay. The treatment of the advection and dispersion in the Eulerian model is performed using a finite element algorithm. This algorithm has been tested against several other advection algorithms using the well-known Molenkamp-Crowley rotation test (Brandt et al., 1996a, d). The finite element scheme is a relatively fast scheme. This is important when used operationally. A predictor-corrector algorithm with three correctors has been used for time integration of the first sub-model (Zlatev, 1995). Time integration in the second

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

© EGS 2002

sub-model is solved using the less expensive and more stable θ -method (Christensen, 1997) and the third sub-model is solved directly.

2.2. The Lagrangian model

The Lagrangian model, which has been implemented into the Eulerian model, is a puff model, which simulates a release changing in time by sequentially releasing a series of Gaussian shaped puffs. In the vertical the Gaussian shape has been transformed into σ -coordinates, using the hydrostatic approximation and the ideal gas law. Each puff is advected and dispersed individually along trajectories. The mixing ratio $C_{x,y,\sigma}$ in σ -coordinates at a point (x, y, σ) , is given by the sum of the contributions from the total number of puffs, N , as

$$C_{x,y,\sigma} = \sum_{i=1}^N \frac{M_i g(\sigma_{c_i} + \phi)}{(2\pi)^{3/2} \tilde{\sigma}_{xy_i}^2 \tilde{\sigma}_{\sigma_i} \rho R \bar{T}_v} \times \exp\left(-\frac{1}{2}\left(\left(\frac{x - x_{c_i}}{\tilde{\sigma}_{xy_i}}\right)^2 + \left(\frac{y - y_{c_i}}{\tilde{\sigma}_{xy_i}}\right)^2\right)\right) \times \left(\exp\left(-\frac{1}{2}\left(\frac{\sigma_{c_i} + \phi}{\tilde{\sigma}_{\sigma_i}} \ln\left(\frac{\psi_{c_i}}{\psi}\right)\right)^2\right) + \exp\left(-\frac{1}{2}\left(-\frac{\sigma_{c_i} + \phi}{\tilde{\sigma}_{\sigma_i}} \ln(\psi \psi_{c_i})\right)^2\right) + \exp\left(-\frac{1}{2}\left(\frac{\sigma_{c_i} + \phi}{\tilde{\sigma}_{\sigma_i}} \ln\left(\frac{\psi \psi_{c_i}}{2\psi_{Hmix}}\right)\right)^2\right) \right) \quad (2)$$

where M_i is the mass of the air pollutant in a given puff. $\tilde{\sigma}_{xy_i}$ and $\tilde{\sigma}_{\sigma_i}$ are the standard deviations of the puff i and a measure for the puff size in horizontal and vertical directions respectively. ϕ is given by $\phi = P_t/P^*$, $P^* = P_s - P_t$. The coordinate of the puff's center of mass is given by $(x_{c_i}, y_{c_i}, \sigma_{c_i})$. T_v is the virtual temperature, ρ is the density of air, R is the gas constant for dry air, and g is the acceleration due to gravity. The functions ψ , ψ_{c_i} and ψ_{Hmix} represents the height, the height of the puff center and the

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

mixing height, respectively and are defined as

$$\begin{aligned}\psi &= \frac{\sigma P^* + P_t}{P_s} \\ \psi_{c_i} &= \frac{\sigma_{c_i} P^* + P_t}{P_s} \\ \psi_{H_{mix}} &= \frac{\sigma_{H_{mix}} P^* + P_t}{P_s}\end{aligned}\quad (3)$$

5 where $\sigma_{H_{mix}}$ is the mixing height in σ -coordinates. The first term on the right hand side of Eq. (2) represents the maximum mixing ratio in the center of a puff. The second and third term represents the horizontal and vertical distribution of the concentrations. The last two terms of the vertical distribution are the reflection due to the ground and to the top of the mixed layer H_{mix} . The two terms represent two artificial sources: One below
10 the ground and one above the mixing height. If the vertical standard deviation $\tilde{\sigma}_{\sigma_i}$ is greater than twice the mixing height then further artificial sources are needed. In order to avoid a large number of exponential functions in the expression, total vertical mixing inside the mixed layer is then assumed and Eq. (2) reduces to

$$\begin{aligned}C_{x,y,\sigma} &= \sum_{i=1}^N \frac{M_i g(\sigma_{c_i} + \phi)}{2\pi \tilde{\sigma}_{xy_i}^2 \rho R T_v} \\ &\times \exp\left(-\frac{1}{2}\left(\left(\frac{x-x_{c_i}}{\tilde{\sigma}_{xy_i}}\right)^2 + \left(\frac{y-y_{c_i}}{\tilde{\sigma}_{xy_i}}\right)^2\right)\right) \times \left((\sigma_{c_i} + \phi)(-\ln(\psi_{H_{mix}}))\right)^{-1}\end{aligned}\quad (4)$$

2.3. Numerical treatment of deposition and radioactive decay in the Lagrangian model

The mass loss, ΔM_l , for a puff, l , within the layer z due to dry deposition in the Lagrangian puff model is assumed to be a sum of the mass losses in the horizontal

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

grid-cells, (i, j) , that are covered by the puff, in the lowest model layer

$$\Delta M_l = \sum_{j=1}^J \sum_{i=1}^I M_{l,i,j} \left(1 - e^{-\Delta t \frac{v_{d,i,j}}{z}} \right) \quad (5)$$

where z is the height of the lowest model layer. I and J are the total number of horizontal grid-cells in the lowest model layer, covered by the puff in the x and y directions, respectively. Δt is the time step and v_d is the dry deposition velocity.

The mass loss due to wet deposition and radioactive decay is described in a similar way, but here the summation is performed over all grid-cells in all three dimensions, (i, j, k) , that are covered by the puff

$$\Delta M_l = \sum_{k=1}^K \sum_{j=1}^J \sum_{i=1}^I M_{l,i,j,k} \left(1 - e^{-\Delta t (\lambda_{i,j,k} + k_r)} \right) \quad (6)$$

where K is the number of levels covered by the puff.

The new mass in the individual puff is found by subtracting the total contributions from dry- and wet deposition and radioactive decay. A new mixing ratio field can now be found by inserting the new puff masses in the calculation of the mixing ratios in Eqs. (2) and (4).

3. Source data from the Chernobyl accident

The location of Chernobyl is N 51°17' E 30°15'. The emission data from the Chernobyl accident are not known precisely. The emissions were temporally highly variable. Furthermore, due to the high temperature of the melting core (up to approximately 2000 °C), the material was assumed to reach heights up to 2000 m and even more. Thus, information about the emission rates and emission heights account for a very large uncertainty when simulating the transport and dispersion from the Chernobyl accident.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

DREAM model

J. Brandt et al.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

© EGS 2002

The first estimation of the source term was mainly based on a USSR report to the International Atomic Energy Agency (IAEA) in 1986 (Hass et al., 1990), where the source was estimated on the basis of summation of the material deposited within the countries of the former USSR. These investigations did not take into account the material deposited outside the former USSR and have later been corrected several times from other investigations with more than a factor of two.

The source term used in these simulations (see Table 1) was last revised in November 1995 in an OECD/NEA report (Waight et al., 1995). Still, the uncertainty of the source term has been estimated to at least $\pm 50\%$. The amount of release and temporal variation used in this study is taken from Devell et al. (1995) and similar to the estimates in De Cort et al. (1998). The effective height of the release as a function of time is taken from Hass et al. (1990). The total activity of all the radioactive material released in the accident is estimated to have been around 12×10^{18} Bq. The radionuclide composition of the material released in the accident was very complex and consisted of various isotopes of Xe, I, Cs, Te, Sr, Ba, Zr, Mo, Ru, Ce, Np, Pu and Cm, with radioactive half-lives in the range of hours (e.g. ^{95}Zr) to thousands of years (e.g. ^{239}Pu). The radioactive isotopes of iodine and caesium were of the greatest significance. Iodine with its short radioactive half-life had the greater radiological impact in the short term, and caesium with a half-life of 30 years has the greater radiological impact in the long term.

In the latest revision, the total emission of ^{137}Cs during the release, was estimated to 85×10^{15} Bq, for ^{134}Cs it was estimated to 54×10^{15} Bq and for ^{131}I to 1.76×10^{18} Bq, corresponding to 30%, 30% and 55% of the total core inventory of 280×10^{15} Bq, 180×10^{15} and 3.2×10^{18} Bq, respectively (De Cort et al., 1998). The daily fraction of the total release is largest in the beginning and in the end of the 10 days period of the major release (see Table 1). The initial large release was due to the mechanical fragmentation of the fuel during the initial two explosions. It contained mainly the more volatile radionuclides such as noble gases, iodine and some caesium. The second large release in the end was associated with the high temperatures reached in the

core melt (Waight et al., 1995).

4. Parameterizations of dry- and wet-deposition

The term deposition refers to the transfer of airborne material, both gaseous and particles, to the surface of the earth, including soil, water and vegetation by wet and dry removal processes. Deposition is, however, very difficult to parameterize because deposition of a certain compound depends on boundary layer meteorology, landuse data (different kinds of vegetation, water, soil, etc.), the characteristics of the compound (as e.g. whether it is in gaseous or in particulate form, or both) and on the three-dimensional cloud physics (precipitation rates). Deposition is also a strongly time varying function with an annual variation due to the dependence on vegetation type (with or without leaves, etc.) as well as a diurnal variation due to meteorological conditions and vegetational variation (diurnal variation of stomata). Furthermore there is a stochastic variation due to precipitation.

The deposition process of the three species, ^{131}I , ^{134}Cs and ^{137}Cs , which are treated here in connection with the Chernobyl accident, is not fully understood. The caesium isotopes, ^{134}Cs and ^{137}Cs , are in their particulate form, when released from a nuclear power plant, but the particle size distribution from e.g. the Chernobyl accident is a very uncertain factor (ranging from $0.01\ \mu\text{m}$ to more than $50\ \mu\text{m}$, (Valkama and Pöllänen, 1996; Valkama et al., 1995). ^{131}I is released in its gaseous form, but tends to attach to other particles as e.g. sulphur (Maryon et al., 1991). The effective dry deposition velocity for ^{131}I therefore tends to decrease with time. The typical time scale for this depletion from gaseous to particulate form is, however, large (about 47 days, Maryon et al., 1991) compared to the length of the model simulation (12 days in this study), so this effect is not taken into account here. Because of these uncertainties, both comprehensive and simple parameterizations of wet- and dry deposition are tested in this study.

Typical values of dry deposition velocities used in different publications for simula-

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

tions of the Chernobyl accident show quite large differences. Some typical values, which have been used in different publications, for dry deposition velocities for ^{131}I and ^{137}Cs are shown in Table 2. The values vary with more than one order of magnitude.

The change in the air mixing ratio due to dry deposition is calculated using the flux F from the air to the surface and is applied as a lower boundary condition for the vertical dispersion in the Eulerian model and is proportional to the mixing ratio C

$$F = v_d C \quad (7)$$

The deposition velocity is usually given in z -coordinates. In σ -coordinates v_d is rewritten to (assuming hydrostatic approximation)

$$v_d(\sigma) = \frac{\partial \sigma}{\partial z} v_d(z) = \left(\frac{\rho g}{P_*} \right) v_d(z) \quad (8)$$

The wet deposition of material is based on the equation

$$\frac{dC}{dt} = -\Lambda C \quad (9)$$

where Λ is the scavenging coefficient,

In the following sections, a description of the different parameterizations of dry and wet deposition, used in the model and tested against measurements using different statistics (Sect. 6) are given. The first two dry deposition schemes are based on the resistance method for both gaseous compounds and particles (in the tables referred to as “resistance, gas” and “resistance, particle”). The third is based on a simple parameterization of dry deposition based on the friction velocity and Monin-Obukhov length (referred to as “simple”). These schemes are compared to the very simple case of a constant deposition velocity of 0.2 cm s^{-1} (referred to as “constant”). For wet deposition, two different schemes are tested; one based on precipitation rates, and one based on relative humidity.

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[◀](#)
[▶](#)
[◀](#)
[▶](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Print Version](#)
[Interactive Discussion](#)

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4.1. Dry deposition of gaseous compounds based on the resistance method

Dry deposition is usually parameterized by an analogy to electrical or heat flow through a series of resistances. The transfer of material from the atmosphere to the surface is assumed to take place through three resistances: the aerodynamic resistance (in some contexts also called the atmospheric resistance), r_a , the quasi-laminar layer resistance (or the deposition layer resistance), r_b , and the canopy resistance (also called the transfer resistance or the vegetation layer resistance or the surface layer resistance), r_c .

The dry deposition velocity, v_d , is for gaseous compounds given at the reference height z , as a function of the resistances (see e.g. Seinfeld, 1986)

$$v_d = \frac{1}{r_a + r_b + r_c} \quad (10)$$

The aerodynamic resistance represents the efficiency of turbulent transport of the material to the laminar surface layer. Parameterization of the aerodynamic resistance r_a is given by (see e.g. Hanna, 1991, or Maryon et al., 1996)

$$r_a = \frac{1}{k u_*} \left(\ln \left(\frac{z}{z_0} \right) - \Phi_h \left(\frac{z}{L} \right) \right) \quad (11)$$

where Φ_h is a stability correction function, given by (Voldner et al., 1986)

$$\Phi_h = -5 \frac{z}{L}, \quad \frac{z}{L} > 0 \text{ (stable)}$$

$$\Phi_h = \exp \left[0.598 + 0.390 \ln \left(-\frac{z}{L} \right) - 0.090 \left(\ln \left(-\frac{z}{L} \right) \right)^2 \right], \quad \frac{z}{L} < 0 \text{ (unstable)} \quad (12)$$

The quasi-laminar resistance r_b is used to specify the resistance to transport across the thin quasi-laminar layer over the surface layer. For gaseous compounds, it is parameterized by (see e.g. Hanna, 1991, or Maryon et al., 1996)

$$r_b = \frac{2}{0.72^{2/3} k u_*} S_C^{2/3} \quad (13)$$

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

Sc is the Schmidt number

$$Sc = \frac{\nu}{D} \quad (14)$$

where ν is the kinematic viscosity of air, ($\nu = \mu/\rho \approx 1.5 \times 10^{-5} \text{ m}^2 \text{ s}^{-1}$) and D is the molecular (Brownian) diffusivity of the pollutant given as a function of the particle or molecular diameter D_p (Seinfeld, 1986; Landau and Lifshitz, 1987).

$$D = \frac{k_B T C u}{6\pi\mu D_p} \quad (15)$$

where k_B is the Boltzmann constant ($k_B = 1.38 \times 10^{-23} \text{ J K}^{-1}$), T is the temperature and μ is the dynamic viscosity coefficient ($\sim 1.8 \times 10^{-5} \text{ kg m}^{-1} \text{ s}^{-1}$). The diameter of iodine molecules in gaseous form is set to $2.8 \times 10^{-10} \text{ m}$ (Forsythe, 1956). Cu is the Cunningham correction for small particles or molecules (less than $1 \mu\text{m}$) and is given by (Seinfeld, 1986)

$$Cu = 1 + \frac{\lambda}{D_p} \left(2.514 + 0.80 \exp\left(-\frac{0.55D_p}{\lambda}\right) \right) \quad (16)$$

where $\lambda = 6.53 \times 10^{-8} \text{ m}$ is the mean free path of air molecules at standard temperature (293.15 K) and standard pressure (1013.25 hPa).

The surface resistance, r_c , characterizes the resistance to capture the species by the surface itself. It depends on the specific pollutant and on the different landuse categories. It is the most difficult parameter to estimate. It is appropriate to apply a value for each landuse category. Some preliminary experiments were carried out, where it has been assumed that the magnitude of r_c for iodine is similar to sulphur dioxide for the different landuse categories (see e.g., Sheih et al., 1979; Voldner et al., 1986). Little research has, however, been carried out in this field for the radioactive compound, iodine, and given the lack of experimental data and the uncertainties in determining the surface resistance for this species a fixed value of r_c has been used. Verver and De Leeuw (1992) recommends $r_c \approx 500 \text{ s/m}$ for ^{131}I .

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

4.2. Dry deposition of particulate compounds based on the resistance method

Particulate matter (as e.g. ^{134}Cs and ^{137}Cs) does not interact with vegetation in the same way as gaseous compounds. The canopy resistance is not taken into account because once penetrating the quasi-laminar layer the particles are usually assumed to stick to the surface. The deposition velocity for particles can be expressed as (see e.g. Hanna et al., 1991; Seinfeld, 1986)

$$v_d = \frac{1}{r_a + r_b + r_a r_b v_g} + v_g \quad (17)$$

where v_g is the gravitational settling velocity of the particles given by Stokes equation (Hanna et al., 1991)

$$v_g = \frac{D_p^2 g(\rho_p - \rho) C u}{18\nu} \quad (18)$$

where ρ is the density of air and ρ_p is the particle density (1.88g/cm^3 for caesium, Weast and Astle, 1980). The distribution of the particle diameters of the radioactive species, which are treated here, is an unknown factor. D_p is therefore set constant and different scenarios have been performed with different particle diameters in the range from $0.1\ \mu\text{m}$ to $10\ \mu\text{m}$. In the calculations included here, $D_p = 1\ \mu\text{m}$ has been chosen as a representative particle diameter.

For particles r_b is parameterized in terms of the Schmidt number and the Stokes number, St

$$r_b = \frac{1}{u_* (Sc^{-2/3} + 10^{-3}/St)} \quad (19)$$

where the Stokes number, or impact parameter, a measure of the probability of particle collisions, is given by

$$St = \frac{v_g u_*^2}{g\nu} \quad (20)$$

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

© EGS 2002

4.3. A simple parameterization of dry deposition

The dry deposition velocity can be parameterized in a simple way based on two important boundary layer parameters: the friction velocity u^* and the Monin-Obukhov length, L . The following expression is obtained from Seland et al. (1995)

$$v_d = \frac{u^*}{a}, \quad L > 0$$

$$v_d = \frac{u^*}{a} \left(1 + \left(\frac{300}{-L} \right)^{2/3} \right), \quad L < 0 \quad (21)$$

where $a = 500$ for low vegetation and $a = 100$ for forest. This parameterization is denoted “simple” in the comparison studies in Sect. 5.

4.4. Wet deposition based on precipitation rates

The washout of air pollutants by precipitation is basically dependent on the precipitation rate (in three dimensions) and type of precipitation. The scavenging coefficient is in this scheme defined as (Maryon et al., 1996)

$$\Lambda = Ar^B \quad (22)$$

where r is the precipitation rate (in mm/hour) and A and B are constants, which are dependent on the type of precipitation. Values for A and B (given in Table 3) are determined for convective and non-convective (dynamic) precipitation and depend on whether the temperature is above or below freezing point. Information on whether the precipitation is convective or non-convective is included in the model results from the MM5V1 model.

The coefficients given in Table 3, are of the same order of magnitude as those used in e.g. ApSimon et al. (1988), where $A = 10^{-4}$ and $B = 0.8$ are recommended.

4.5. Wet deposition based on the relative humidity

In some cases, when information about the precipitation rate is not available or uncertain, a more simple parameterization for Λ can be used. This simple scheme is based on the relative humidity, RH (Pudykiewicz, 1989), where the scavenging coefficients are calculated from

$$\Lambda = 0, \quad RH < RH_t$$
$$\Lambda = 3.5 \times 10^{-5} \left(\frac{RH - RH_t}{RH_s - RH_t} \right), \quad RH \geq RH_t \quad (23)$$

$RH_t (= 80\%)$ is the threshold value of the relative humidity where condensation is assumed to occur, $RH_s (= 100\%)$ is the saturation value. The relative humidity, is found from

$$RH \equiv \frac{w}{w_s} \quad (24)$$

where the mixing ratio, w , is calculated from the specific humidity Q

$$w = \frac{Q}{1 - Q} \quad (25)$$

w_s is the saturation mixing ratio calculated from (Wallace and Hobbs, 1977)

$$w_s = 0.622 \frac{e_s}{p - e_s} \quad (26)$$

where p is the pressure and e_s is the saturated partial pressure of water vapour, which is calculated as an approximated function of temperature, T (Seinfeld, 1986)

$$e_s = p_0 \exp \left(13.3185a - 1.9760a^2 - 0.6445a^3 - 0.1299a^4 \right) \quad (27)$$

where p_0 is the standard pressure (101 325 Pa) and a is given by

$$a = 1 - \frac{T_0}{T} \quad (28)$$

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

where $T_0 = 273.15$ K. Eq. (27) is valid to $\pm 0.1\%$ in the temperature range from 50°C to 140°C (Seinfeld, 1986).

5. Model results and comparisons to measurements

The model system has been run with a combination of the different parameterizations for dry and wet deposition described in the previous section. The model results have been validated against measurements. Some examples of model results for Chernobyl are given in Sect. 5.1. Comparisons of the model results obtained using the different parameterizations and using different statistics, are described in Sect. 5.2.

5.1. Model simulations of the Chernobyl accident

Model simulations of the Chernobyl accident are different from model simulations of the two ETEX releases in 1994. The main reason for this is that Chernobyl is a real accident. This means that several issues are connected with greater uncertainties in the case of the Chernobyl accident than is the case of the ETEX releases. This includes uncertainties in the estimation of the source term, uncertainties in the dry- and wet deposition, and greater inhomogeneity in the measurements available after the accident. Greater uncertainties can therefore be expected in the model results from the Chernobyl case compared to the ETEX cases (Brandt et al., 1998a).

Measurements of surface concentrations and total depositions from three radioactive species, ^{137}Cs , ^{134}Cs , and ^{131}I were available after the accident. Therefore model simulations and validation against measurements of the concentrations and depositions of these three species have been performed here. The treatment of the two caesium isotopes are similar in the model. The iodine isotope is treated differently from the caesium isotopes, partly because it has a much shorter radioactive half-life, and partly because it was released in gaseous form, where the caesium isotopes were released as particles. This influences the treatment of dry deposition in the model. Deposition

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

of the radioactive material is an important factor when simulating accidental releases from nuclear power plants. Especially wet deposition can be a major removal process and a large source for radioactive contamination of areas. The different parameterizations of dry- and wet deposition have therefore been compared and tested against measurements of total accumulated deposition for all three species.

The parameterizations of mixing height and dispersion have been chosen from the results of the experiments performed for the ETEX releases (Brandt et al., 1998a). In all the simulations of the Chernobyl accident, that are included here, the mixing height is parameterized based on a bulk Richardson/Zilitinkevich-Mironov scheme, and dispersion in both the Lagrangian model and the Eulerian model is parameterized based on Monin-Obukhov similarity theory, see Brandt et al. (1998a). The meteorological data used in this study for the Chernobyl episode are analyzed data obtained from ECMWF with a $1.5^\circ \times 1.5^\circ$ horizontal resolution. The experiments with ETEX, demonstrated that using the MM5V1 as a meteorological driver improve the results in general compared to the case where the analyzed data are used. Therefore data obtained from running MM5V1, using ECMWF ($1.5^\circ \times 1.5^\circ$) data as input to MM5V1, have been used as meteorological input data to DREAM in the simulations presented here.

An example of the development of the surface concentrations of ^{137}Cs from the Chernobyl accident, calculated by using DREAM, is illustrated in Fig. 1. The figure show the situation with 2 days interval, starting at 27 April 12:00 UTC and ending at 7 May 12:00 UTC. The initial transport of the radioactive species was towards northwest to Sweden and Finland. It is seen in the upper left plot in Fig. 1 that the surface concentrations were close to zero near the accident site in the initial phase. This is due to the source term used in the model. The effective release heights from the Chernobyl accident have been estimated to have different values during the accident (see Sect. 3). The major part of the initial emissions from Chernobyl has been estimated to take place at relatively high altitudes. After a few days the major parts of the emissions took place at lower altitudes. In the following days the concentrations were transported over most of Europe with major exposures in southern, eastern and central Europe.

DREAM model

J. Brandt et al.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[I◀](#)[▶I](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

DREAM modelJ. Brandt et al.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

© EGS 2002

A three dimensional illustration of the 0.15 Bq m^{-3} iso-surface on the third day after the accident on 28 April 12:00 UTC, is shown in Fig. 2. The figure shows the situation seen from the south. The surface concentrations are plotted on the iso-surface. The blue areas on the iso-surface indicate the parts of the plume, which do not have direct contact with the ground. A great part of the wet deposition came from these parts of the plume, which can be seen when comparing the surface concentrations (Fig. 1) with the total depositions (Fig. 7). This is especially true for Finland. It is also seen in the figures, that some parts of the plume are transported by the vertical wind to higher altitudes where the wind direction is opposite the direction at lower levels. This results in transport of the plume in opposite directions at different altitudes, both towards northwest at lower altitudes and towards southeast at higher altitudes.

Some examples of comparisons with measurements are illustrated as scatter plots in Fig. 3. The locations of the measurement stations where measurements of deposition were carried out are given in Fig. 4. The measurements have been obtained from the REM-database at the Environment Institute, Joint Research Center, Ispra, Italy. The figure shows scatter plots of the total dosages, the arrival time, the duration, and the total depositions for the specie ^{137}Cs . Taking into account the uncertainties in the source term, the inhomogeneities in the measurements and the uncertainties in the depositions, the model gives quite good results for the Chernobyl case. There is a relatively large bias in the dosages, which can be explained from biases in the source term or uncertainties in the effective release heights. This bias could easily be adjusted by changing the emission rates, but this correction in the emissions has not been performed, due to the other uncertainties, especially in the wet deposition. However, the correlation coefficient for the dosages is highly significant. The model is able to predict the arrival times to the measurement stations quite accurately with a correlation coefficient of 0.87. The model is also able to reproduce the durations (meaning the time between the arrival time and the time where the plume leaves a specific location) within a factor of two, which is comparable to the ETEX cases (Brandt et al., 1998a). The comparisons of model calculations of the total depositions with

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

© EGS 2002

measurements show that the model is able to estimate the general level of the total deposition and with a significant correlation coefficient.

Below each figure (in Fig. 3), some global statistics are shown. Some of these are used for the comparison of the model results, obtained by using the different parameterizations (see next subsection). The statistics include the number of points, N , the mean values, the standard deviations, the correlation coefficient with a test statistic, the figure of merit, FM , the bias with the 95% confidence interval, the fractional bias, FB , the fractional standard deviation, FSD and the normalized mean square error, $NMSE$, with the 95% confidence interval. A detailed description of the various statistical parameters is given in Spiegel (1992) and Mosca et al. (1997) and also used in Brandt (1998) and Brandt et al. (1998a). A test for significance has been performed for the correlation coefficient by the test parameter $t_c = r(N - 2)^{1/2}(1 - r^2)^{-1/2}$ where r is the correlation coefficient and N is the number of data (Spiegel, 1992). The test hypothesis is that the model results and measurements are linearly independent which means that the correlation coefficient is zero. If the hypothesis can be rejected at a given significance level, the correlation coefficient is assumed to be significant at that level. Critical values for the test parameter for $N = 100$ are 1.66, 2.63 and 3.39 corresponding to significance levels of 0.1 (10%), 0.01 (1%) and 0.001 (0.1%), respectively (Spiegel, 1992).

5.2. Comparisons of different parameterizations of dry- and wet deposition

Accurate parameterizations of dry- and wet deposition are important for reliable model results in the Chernobyl case. In this section the parameterizations of dry- and wet depositions for the three species ^{137}Cs , ^{134}Cs , and ^{131}I are compared. Figures 5 and 6 show examples of the accumulated dry- and wet depositions for ^{137}Cs , using the different parameterizations. Some examples of the accumulated total depositions are given in Fig. 7. All figures illustrate the situation at the end of the simulation period, at 7 May 12:00 UTC.

In Fig. 5 the accumulated dry deposition of ^{137}Cs is shown, using the three different

DREAM model

J. Brandt et al.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

© EGS 2002

parameterizations: the parameterization based on the simple dry deposition algorithm, the parameterization based on the resistance method for particles, and dry deposition based on a constant deposition velocity. As shown in Table 2 there are large differences in the magnitude of the deposition velocities of the radioactive species ^{137}Cs and ^{131}I , which has been recommended and used in different models. Therefore the same constant value for the dry deposition velocity of 0.2 cm s^{-1} has been chosen and applied here for all three species. The three parameterizations of dry deposition give in general the same patterns but with some differences in the general levels and the levels over waters and forests. The constant value of 0.2 cm s^{-1} seems to give larger deposition for caesium compared to the simple dry deposition method and especially the resistance method.

The accumulated wet deposition, using the parameterizations based on relative humidities and precipitation rates, and examples of the total accumulated deposition are shown in Figs. 6 and 7, respectively. The examples of total accumulated depositions are given as the sum of the dry deposition based on the simple dry deposition method and the wet deposition based on the two different schemes, respectively. It is clearly seen in the figure, that wet deposition accounts for the major part of the total deposition. Some differences are seen in the general patterns between the two parameterizations of wet deposition, especially over the Baltic sea, the North sea, the Alpine regions, and in the south-eastern Europe, as e.g. Rumania, Bulgaria and Greece.

Comparisons of combinations of the three different parameterizations of dry deposition and the two different parameterizations of wet deposition are given in Tables 4–7. In Tables 4–6 the six different combinations have been compared to measurements using the REM database of the total deposition for the three species, ^{137}Cs , ^{134}Cs , and ^{131}I and statistics have been calculated. The statistics in the tables are the same as the statistics used in the scatter plots.

In order to evaluate the different model results, obtained by using different combinations of the dry and wet deposition schemes and to estimate the best performing combination, a ranking of the different model simulations has been carried out. For

DREAM model

J. Brandt et al.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

© EGS 2002

each model run, the correlation coefficient, the bias with 95% confidence interval, the *NMSE* with 95% confidence interval, the *FB*, the *FSD* and the *FM* have been calculated for the total deposition. The 95% confidence intervals for the bias and the *NMSE* are considered as separate statistics, because it is possible to obtain values for the bias or the *NMSE*, which indicates very good performance, but with confidence intervals, which indicate bad performance. The opposite is also possible. For each statistical parameter a local ranking has been performed, meaning that the best performing value has been given the value 1, the second best performing value has been given the value 2, etc. Each statistical index has been given the same weight. After the local ranking of each index, a global rank is calculated as the sum of the local rank. In this way, the result with the smallest global rank indicates the best performing model in terms of model results compared to measurements. The lowest value of the global rank (indicating the best performing parameterization), that can be obtained in this case is 8, and the highest value (indicating the worst performing parameterization) is 48.

The same major conclusion is obtained from the global ranking for the three different radioactive isotopes. The best performance, compared to measurements, is obtained by the total deposition combined of the simple dry deposition method and the wet deposition based on relative humidities. Large differences are seen in the results obtained by using the two different parameterizations of wet deposition. The parameterization based on relative humidities is, in all cases, performing better than the parameterization based on precipitation rates, with respect to the global ranks. This indicates that the precipitation rates are relatively uncertain in the meteorological model. Relatively small differences are, however, seen in the statistical tests between the three different parameterizations of dry deposition. This is due to the fact that the major part of the total deposition consists of wet deposition.

The European Commission, Environment Institute, Joint Research Center, Ispra, Italy, has in 1998 produced an atlas based on measurements, with the title: “Atlas of caesium deposition on Europe after the Chernobyl accident”. In this atlas, estimates of the total depositions for 31 countries influenced by the Chernobyl accident are given.

DREAM model

J. Brandt et al.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

© EGS 2002

The results are based on a large number of surface samples taken all over Europe and maps have been produced together with the estimates of deposition on each of the 31 countries. The model was setup to provide corresponding results for each of these countries, and the model results have been compared to the estimates given in the atlas. The results from the comparison are given in Table 7. The table is similar to the Tables 4–6, however, only caesium is included in this comparison. The best performance is (as the case where the REM database is used) obtained by the total deposition combined of the simple dry deposition method and the wet deposition based on relative humidities. Highly significant and relatively larger correlation coefficients (from 0.76–0.86) are seen when testing the model results based on country values compared to the case where individual measurement stations are used (the REM database). This should be expected, since a whole country is much more representative for the model result when comparing with measurements than individual measurement stations. Furthermore, one of the results in the atlas is an estimate of the measured total deposition for all countries giving a total measured deposition of 77 PBq. Using the combination of the different dry and wet deposition parameterizations, modelled values between 75.8 PBq and 99.18 PBq are obtained (see Table 7). All the results obtained when the wet deposition parameterization based on relative humidities is used gives a total deposition for all countries very close to the measured value.

6. Conclusions

A tracer model based on a combination of a near-range Lagrangian model and a long-range Eulerian model has been developed and validated against measurements of ^{137}Cs , ^{134}Cs , and ^{131}I in connection with the Chernobyl accident. Different parameterizations of dry and wet deposition in the model have been tested and compared. The conclusions are based on comparisons with measurements both from the REM database and from the Chernobyl atlas.

DREAM model

J. Brandt et al.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

© EGS 2002

Simulations of the Chernobyl accident show that comprehensive tracer models are powerful tools for estimating the concentrations and depositions after a nuclear power plant accident. The validation of the DREAM model against measurements of ^{137}Cs , ^{134}Cs , and ^{131}I demonstrates that the model is able to simulate the development of the concentrations and the accumulated total depositions with quite good results and with a high level of detail when compared to the maps in the Chernobyl atlas (not shown here). The accuracy of the simulations of the dosages compared to measurements is within a factor of two to three in the worst cases, which is the same accuracy as in the case of ETEX-1 (Brandt et al., 1998a). This is very good, taking into account the uncertainties in the source term, the deposition processes and the inhomogeneities in the measurements. The comparisons of model simulations with measurements of the arrival times and the durations illustrate, that the model is able to simulate these variables with an accuracy within a factor of less than two. The model simulations of the total depositions show that the model is able to reproduce the general levels of the deposition when the results are compared to measurements.

Comparisons of the different parameterizations of dry and wet deposition showed that the combination of the relatively simple dry deposition scheme and the wet deposition scheme based on relative humidities gave the best performance. This was seen for all three species (^{137}Cs , ^{134}Cs , and ^{131}I) and for both databases (the REM database from Ispra and the country-based estimations of ^{137}Cs deposition from the Chernobyl Atlas). This emphasizes the validity of the results.

More work can be done with the parameterization and validation of wet deposition, especially with respect to the parameterization based on precipitation rates, as e.g. to assimilate measurements of precipitation in the calculations, in order to diminish the uncertainties from the estimation of precipitation.

The model will in the future be incorporated as a part of the NERI's air pollution forecast system, THOR (Brandt et al., 2001a, b and c). The THOR system includes operational air pollution forecasts at different scales – from European scale down to urban street scale and of different species, e.g. ozone, sulphur, nitrogen-oxides, VOC's,

etc. Examples of a forecast with the THOR system can be seen at the web page given below.

Further information

Some visualizations and animations from the DREAM model and the THOR system can be found in the following web pages:

<http://www.dmu.dk/AtmosphericEnvironment/WEPTTEL/DREAM>

<http://www.dmu.dk/AtmosphericEnvironment/thor>.

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DREAM model

J. Brandt et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

DREAM model

J. Brandt et al.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

© EGS 2002

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DREAM model

J. Brandt et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

DREAM model

J. Brandt et al.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

© EGS 2002

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DREAM modelJ. Brandt et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

© EGS 2002

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DREAM model

J. Brandt et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

Table 1. Release rates in Bq/day and relative distribution of material released in different heights of ^{137}Cs , ^{134}Cs and ^{131}I in the period of the release, according to Hass et al. (1990), Devell et al. (1995), Waight et al. (1995) and De Cort et al. (1998). Figures in parentheses are the daily release fraction of the total release

Approximate height [m]	Species	25–26 April (23.8%)	27 April (7.9%)	28 April (6.9%)	29 April (4.8%)	30 April (4%)
225	^{137}Cs	–	–	2.9×10^{15}	2.0×10^{15}	1.7×10^{15}
	^{134}Cs	–	–	1.9×10^{15}	1.3×10^{15}	1.1×10^{15}
	^{131}I	–	–	6.1×10^{16}	4.2×10^{16}	3.5×10^{16}
425	^{137}Cs	–	6.7×10^{14}	2.9×10^{15}	2.0×10^{15}	1.7×10^{15}
	^{134}Cs	–	4.3×10^{14}	1.9×10^{15}	1.3×10^{15}	1.1×10^{15}
	^{131}I	–	1.4×10^{16}	6.1×10^{16}	4.2×10^{16}	3.5×10^{16}
715	^{137}Cs	–	3.4×10^{15}	–	–	–
	^{134}Cs	–	2.1×10^{15}	–	–	–
	^{131}I	–	7.0×10^{16}	–	–	–
1090	^{137}Cs	1.0×10^{16}	2.7×10^{15}	–	–	–
	^{134}Cs	6.4×10^{15}	1.7×10^{15}	–	–	–
	^{131}I	2.1×10^{17}	5.6×10^{16}	–	–	–
1575	^{137}Cs	8.1×10^{15}	–	–	–	–
	^{134}Cs	5.1×10^{15}	–	–	–	–
	^{131}I	1.7×10^{17}	–	–	–	–
2225	^{137}Cs	2.0×10^{15}	–	–	–	–
	^{134}Cs	1.3×10^{15}	–	–	–	–
	^{131}I	4.2×10^{16}	–	–	–	–

DREAM model

J. Brandt et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

© EGS 2002

Table 1. Continued.....

Approximate height [m]	Species	1 May (4%)	2 May (7.9%)	3 May (10%)	4 May (14.3%)	5 May (16.4%)
225	^{137}Cs	1.7×10^{15}	3.4×10^{15}	4.3×10^{15}	6.1×10^{15}	7.0×10^{15}
	^{134}Cs	1.1×10^{15}	2.1×10^{15}	2.7×10^{15}	3.9×10^{15}	4.4×10^{15}
	^{131}I	3.5×10^{16}	7.0×10^{16}	8.8×10^{16}	1.3×10^{17}	1.4×10^{17}
425	^{137}Cs	1.7×10^{15}	3.4×10^{15}	4.3×10^{15}	6.1×10^{15}	7.0×10^{15}
	^{134}Cs	1.1×10^{15}	2.1×10^{15}	2.7×10^{15}	3.9×10^{15}	4.4×10^{15}
	^{131}I	3.5×10^{16}	7.0×10^{16}	8.8×10^{16}	1.3×10^{17}	1.4×10^{17}

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[I◀](#)[▶I](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

DREAM model

J. Brandt et al.

Table 2. Different typical values for dry deposition velocities of ^{131}I and ^{137}Cs from different publications

Source	Dry deposition velocities	
	^{131}I [cm/s]	^{137}Cs [cm/s]
Hanna (1991)	0.3	0.1
Maryon et al. (1991)	0.5	0.05
Klug et al. (1992)	0.15–2.0	0.1–0.5
Slinn et al. (1978)	–	0.31 (water 0.9)
Sehmel (1980)	0.1–2.0	0.04–0.5 (water 0.09)

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[I◀](#)[▶I](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

© EGS 2002

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[I◀](#)[▶I](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

© EGS 2002

Table 3. Constants A and B used to calculate the scavenging coefficients, based on precipitation rates (Maryon et al., 1996)

	Rain [s^{-1}]		Snow [s^{-1}]	
	Convective	Dynamic	Convective	Dynamic
Washout below cloud base	$A = 8.4 \times 10^{-5}$ $B = 0.79$		$A = 8.0 \times 10^{-5}$ $B = 0.305$	
Rainout between cloud base and top	$A = 3.36 \times 10^{-4}$ $B = 0.79$	$A = 8.4 \times 10^{-5}$ $B = 0.79$	$A = 3.36 \times 10^{-4}$ $B = 0.79$	$A = 8.0 \times 10^{-5}$ $B = 0.305$

DREAM model

J. Brandt et al.

Table 4. Comparisons of total deposition of ^{137}Cs for the Chernobyl episode based on different combinations of the wet- and dry deposition schemes. Statistics are calculated from comparisons with measurements from the REM database. Values in bold are the most significant of the 6 combinations

Statistics $N = 67$ Dry deposition:	Wet deposition based on relative humidity (RH)			Wet deposition based on precipitation rates		
	Resistance, particle	Simple	Constant (0.2 cm/s)	Resistance, particle	Simple	Constant (0.2 cm/s)
Correlation t_c	0.47 4.32	0.47 4.35	0.47 4.35	0.51 4.73	0.50 4.68	0.49 4.59
Bias ci(95%)	-1.168 0.790	-1.168 0.789	-1.205 0.785	-1.798 0.748	-1.810 0.750	-1.828 0.753
NMSE ci(95%)	3.660 1.251	3.654 1.230	3.755 1.279	7.423 6.146	7.609 6.421	7.907 6.890
FB FSD	-0.612 -0.625	-0.612 -0.616	-0.638 0.661	-1.129 -1.199	-1.141 -1.208	-1.158 -1.221
FM	31.0%	31.1%	31.2%	25.3%	25.0%	24.5%
Global ranks	23	16	24	26	34	42

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

I◀

▶I

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

DREAM model

J. Brandt et al.

Table 5. Comparisons of total deposition of ^{134}Cs for the Chernobyl episode based on different combinations of the wet- and dry deposition schemes. Statistics are calculated from comparisons with measurements from the REM database. Values in bold are the most significant of the 6 combinations

Statistics $N = 58$ Dry deposition:	Wet deposition based on relative humidity (RH)			Wet deposition based on precipitation rates		
	Resistance, particle	Simple	Constant (0.2 cm/s)	Resistance, particle	Simple	Constant (0.2 cm/s)
Correlation t_c	0.45 3.77	0.46 3.83	0.46 3.83	0.57 5.13	0.56 5.08	0.55 4.97
Bias ci(95%)	-0.355 0.485	-0.357 0.483	-0.386 0.478	-0.785 0.410	-0.793 0.411	-0.807 0.414
NMSE ci(95%)	3.174 1.096	3.164 1.119	3.223 1.123	5.213 4.708	5.351 4.978	5.610 5.401
FB FSD	-0.329 -0.268	-0.330 -0.259	-0.362 -0.315	-0.906 -0.860	-0.919 -0.870	-0.943 -0.889
FM	31.3	31.6	31.9	30.6%	30.4%	29.9%
Global ranks	22	19	24	26	34	42

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

I◀

▶I

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

DREAM model

J. Brandt et al.

Table 6. Comparisons of total deposition of ^{131}I for the Chernobyl episode based on different combinations of the wet- and dry deposition schemes. Statistics are calculated from comparisons with measurements from the REM database. Values in bold are the most significant of the 6 combinations

Statistics $N = 25$	Wet deposition based on relative humidity (RH)			Wet deposition based on precipitation rates		
	Dry deposition: Resistance, particle	Simple	Constant (0.2 cm/s)	Resistance, particle	Simple	Constant (0.2 cm/s)
Correlation t_c	0.55 3.14	0.60 3.60	0.57 3.34	0.31 1.59	0.33 1.69	0.31 1.54
Bias ci(95%)	-2.231 4.205	-1.317 4.054	-1.807 4.218	-6.034 3.822	-5.938 3.790	-5.987 3.850
NMSE ci(95%)	2.392 9.853	1.788 2.847	2.126 4.148	7.625 33.284	7.125 29.072	7.497 31.603
FB FSD	-0.321 0.336	-0.178 0.370	-0.252 0.389	-1.196 -1.346	-1.166 -1.332	-1.181 -1.294
FM	35.3%	44.8%	41.1%	19.3%	20.7%	19.4%
Global ranks	24	12	21	43	30	38

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

I◀

▶I

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

DREAM model

J. Brandt et al.

Table 7. Comparisons of total deposition of ^{137}Cs for the Chernobyl episode based on different combinations of the wet- and dry deposition schemes. Statistics are calculated from comparisons with measurements from the Chernobyl atlas (country based). Values in bold are the most significant of the 6 combinations. Total measured deposition is 77 PBq (De Cort et al., 1998)

Statistics $N = 31$	Wet deposition based on relative humidity (RH)			Wet deposition based on precipitation rates		
	Resistance, particle	Simple	Constant (0.2 cm/s)	Resistance, particle	Simple	Constant (0.2 cm/s)
Correlation t_c	0.84 8.22	0.85 8.68	0.86 8.95	0.79 7.01	0.77 6.44	0.76 6.39
Bias ci(95%)	-0.178 0.919	-0.024 0.865	-0.183 0.832	0.563 1.292	0.589 1.392	0.516 1.389
NMSE ci(95%)	1.737 7.966	1.416 8.093	1.429 8.250	2.503 2.946	2.875 2.993	2.930 3.026
FB FSD	-0.091 -0.005	-0.012 -0.086	-0.094 -0.215	0.242 0.535	0.252 0.579	0.224 0.567
FM	54.9%	58.5%	60.2%	49.2%	46.9%	47.0%
Global ranks	19	16	20	33	40	38
Total deposition	76.7 PBq	80.4 PBq	75.8 PBq	99.13 PBq	99.18 PBq	97.07 PBq

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

I◀

▶I

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

© EGS 2002

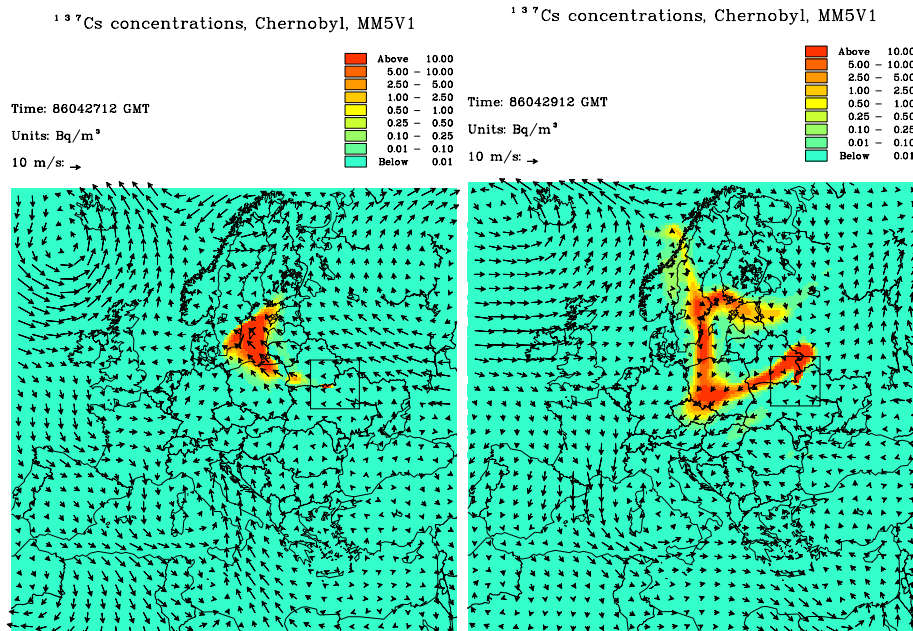


Fig. 1. Model simulation of the development of the surface concentrations of ^{137}Cs from the Chernobyl accident. The figures show the situation with 2 days interval, starting at 27 April 12:00 UTC (the day after start of release) and ending 12 days after start of release. Dry deposition is based on the simple dry deposition scheme and wet deposition is parameterized based on relative humidity.

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[◀](#)
[▶](#)
[◀](#)
[▶](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Print Version](#)
[Interactive Discussion](#)

© EGS 2002

DREAM model

J. Brandt et al.

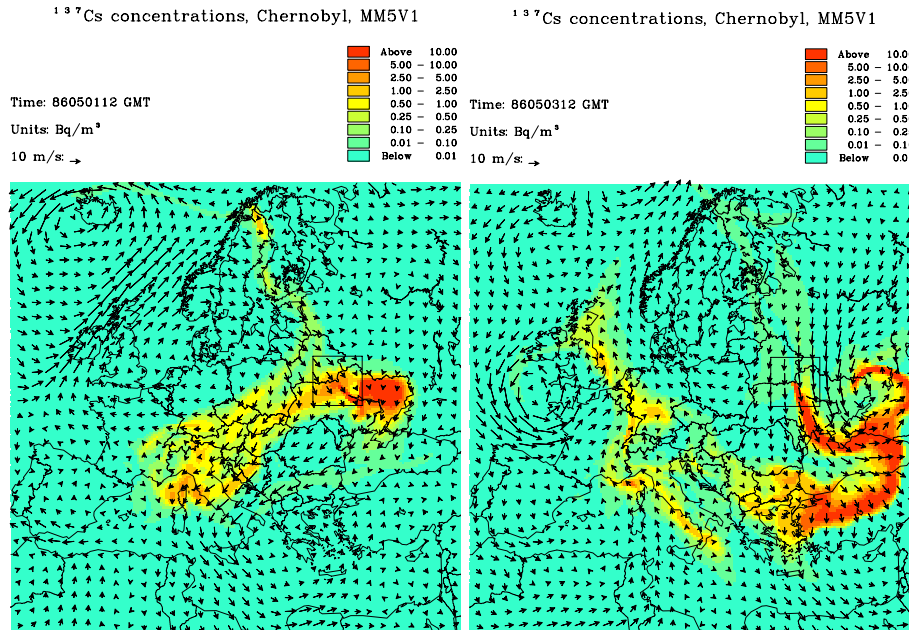


Fig. 1. Continued.....

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

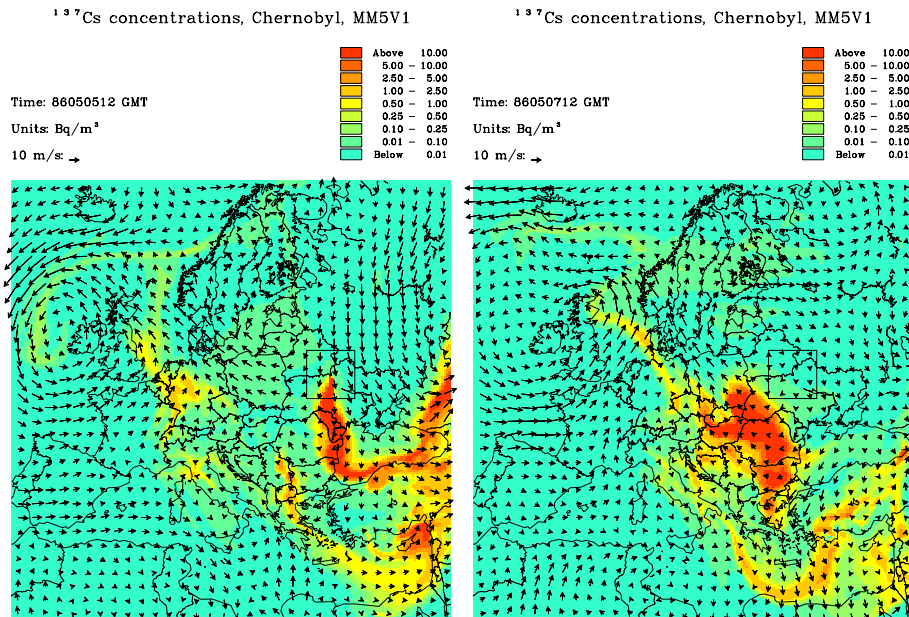


Fig. 1. Continued.....

Title Page	
Abstract	Introduction
Conclusions	References
Tables	Figures
◀	▶
◀	▶
Back	Close
Full Screen / Esc	
Print Version	
Interactive Discussion	

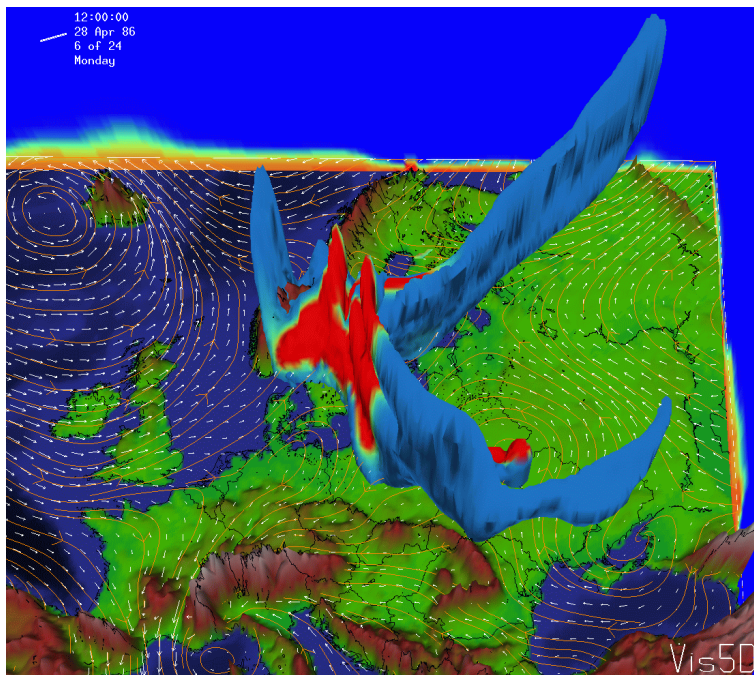


Fig. 2. A three-dimensional illustration of the 0.15 Bq m^{-3} iso-surface of ^{137}Cs from the Chernobyl accident, on the third day after the accident, 28 April 12:00 UTC. Parameterizations are the same as in Fig. 1. The surface concentrations are plotted on the iso-surface and are the same as given in Fig. 1 (red indicate high surface concentrations and blue indicate low surface concentrations). The blue color on the plume therefore indicates parts of the plume, which does not have contact with the ground. The bulk Richardson number is given as vertical slices at the boundaries. The blue color at the boundaries indicate the domain where the bulk Richardson number exceeds the critical value of 0.25, and is therefore an indicator of the height of the planetary boundary layer.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion

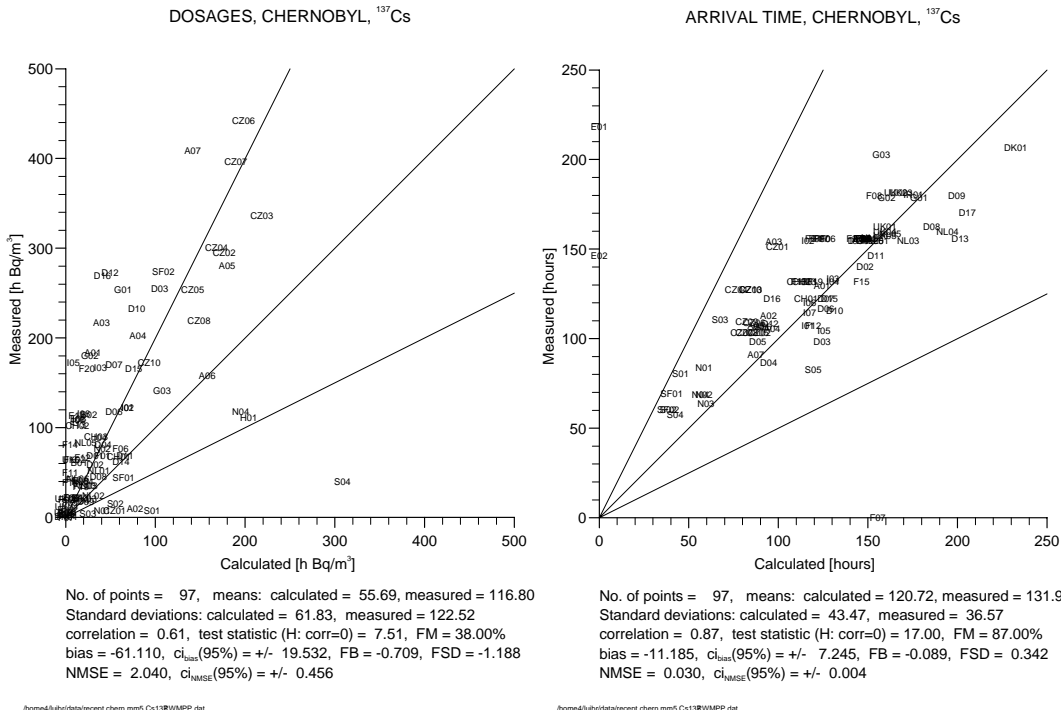


Fig. 3. A comparison of model calculations of ¹³⁷Cs with measurements for Chernobyl at 97 measurement stations (67 stations for deposition). Parameterizations are the same as in Fig. 1. Left: dosages (integrated concentrations for every hour over the whole period). Right: arrival times - meaning the time where the plume arrives to the different measurement stations. Figure 3 continues.....

Title Page

Abstract Introduction

Conclusions References

Tables Figures

◀ ▶

◀ ▶

Back Close

Full Screen / Esc

Print Version

Interactive Discussion

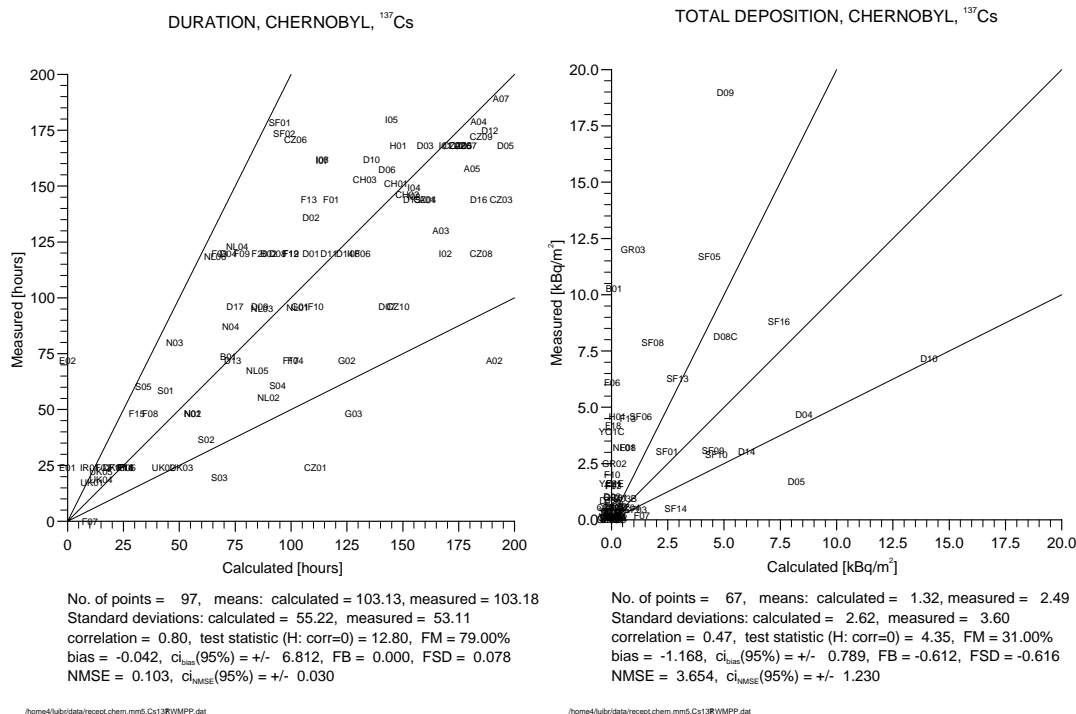


Fig. 3. Continued..... Left: duration (the time between the time of arrival of the plume and the time where the plume leaves the location of the measurement stations). Right: total deposition at 67 stations.

Title Page

Abstract Introduction

Conclusions References

Tables Figures

◀ ▶

◀ ▶

Back Close

Full Screen / Esc

Print Version

Interactive Discussion

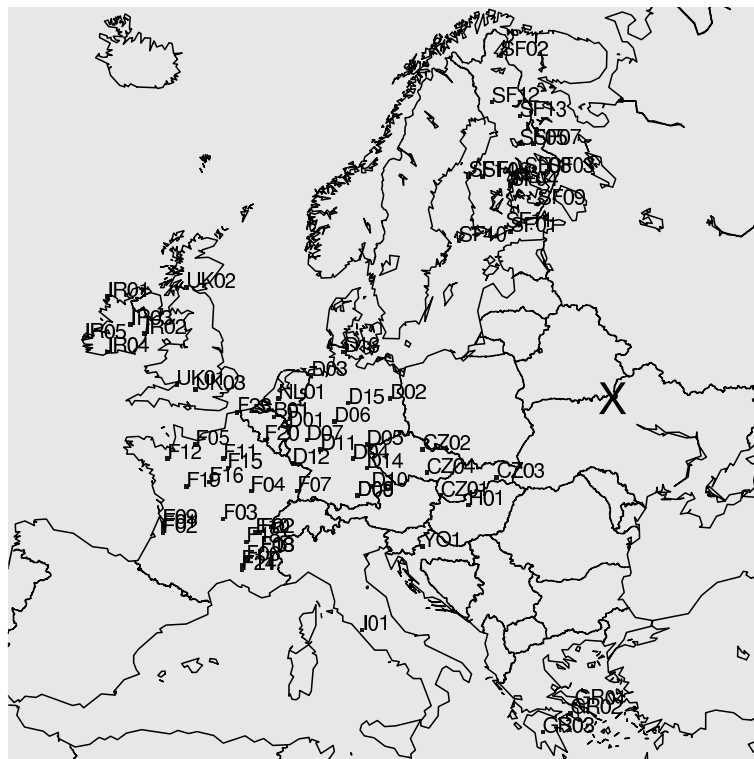


Fig. 4. Location of the measurement stations, where measurements of the total depositions are available in connection with the Chernobyl accident (from the REM database). “X” denotes the location of the release site.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Print Version](#)[Interactive Discussion](#)

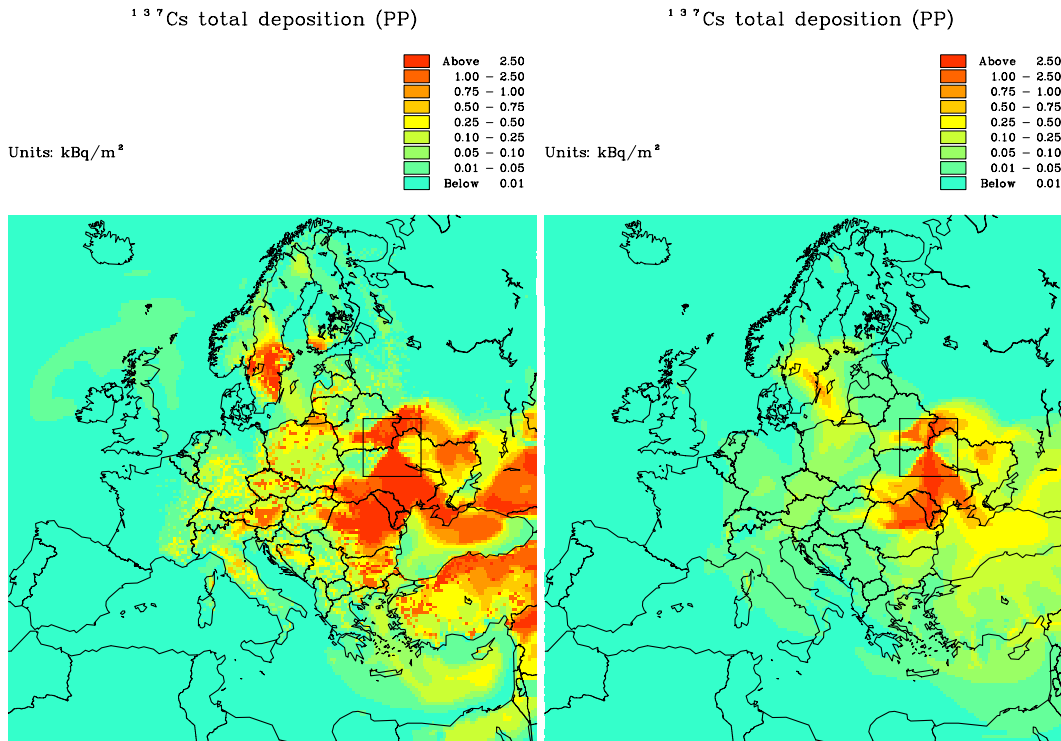


Fig. 5. Accumulated dry deposition of ^{137}Cs from the Chernobyl accident, at the end of the simulation period (7 May 12:00 UTC), calculated using three different schemes. Left: simple dry deposition method. Right: parameterization based on the resistance method for particles. Figure 5 continues....

Title Page	
Abstract	Introduction
Conclusions	References
Tables	Figures
◀	▶
◀	▶
Back	Close
Full Screen / Esc	
Print Version	
Interactive Discussion	

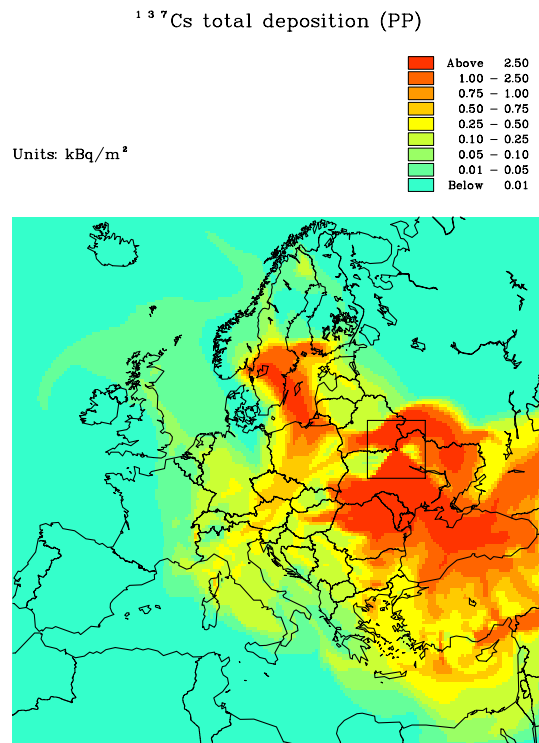


Fig. 5. Continued..... constant deposition velocity (0.2 cm s^{-1}).

Title Page	
Abstract	Introduction
Conclusions	References
Tables	Figures
◀	▶
◀	▶
Back	Close
Full Screen / Esc	
Print Version	
Interactive Discussion	

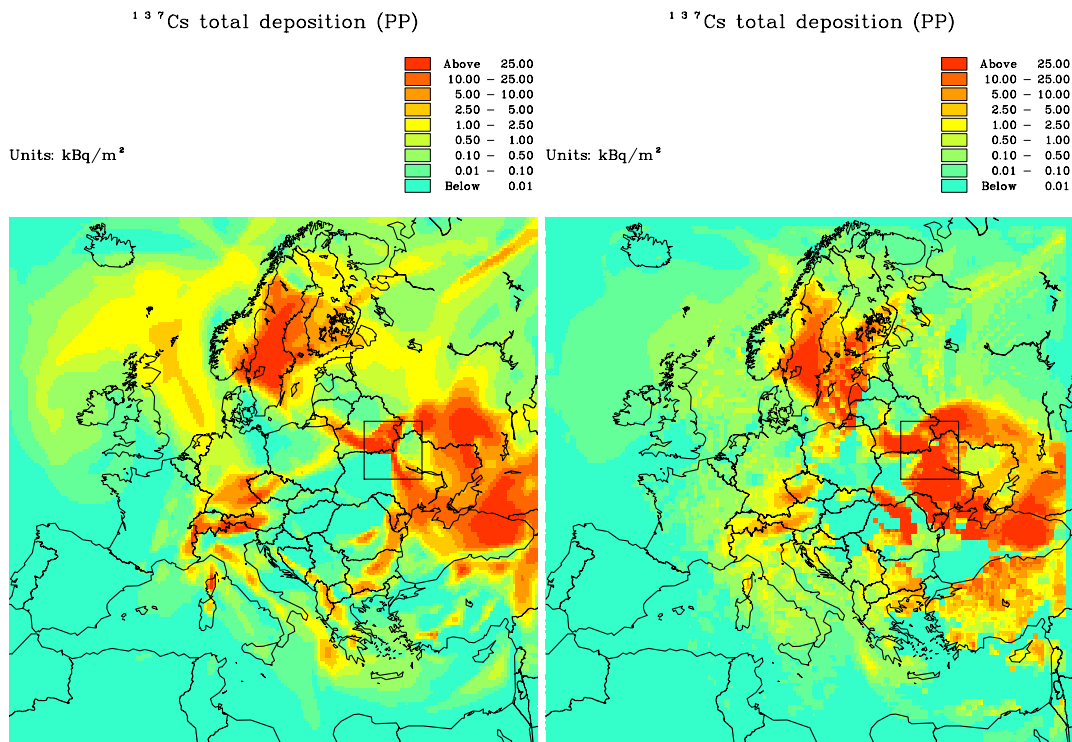


Fig. 6. Accumulated wet deposition of ^{137}Cs , calculated using two different schemes from the Chernobyl accident, at the end of the simulation period (7 May 12:00 UTC). Left: accumulated wet deposition based on relative humidity. Right: accumulated wet deposition based on precipitation rates.

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[◀](#)
[▶](#)
[◀](#)
[▶](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Print Version](#)
[Interactive Discussion](#)

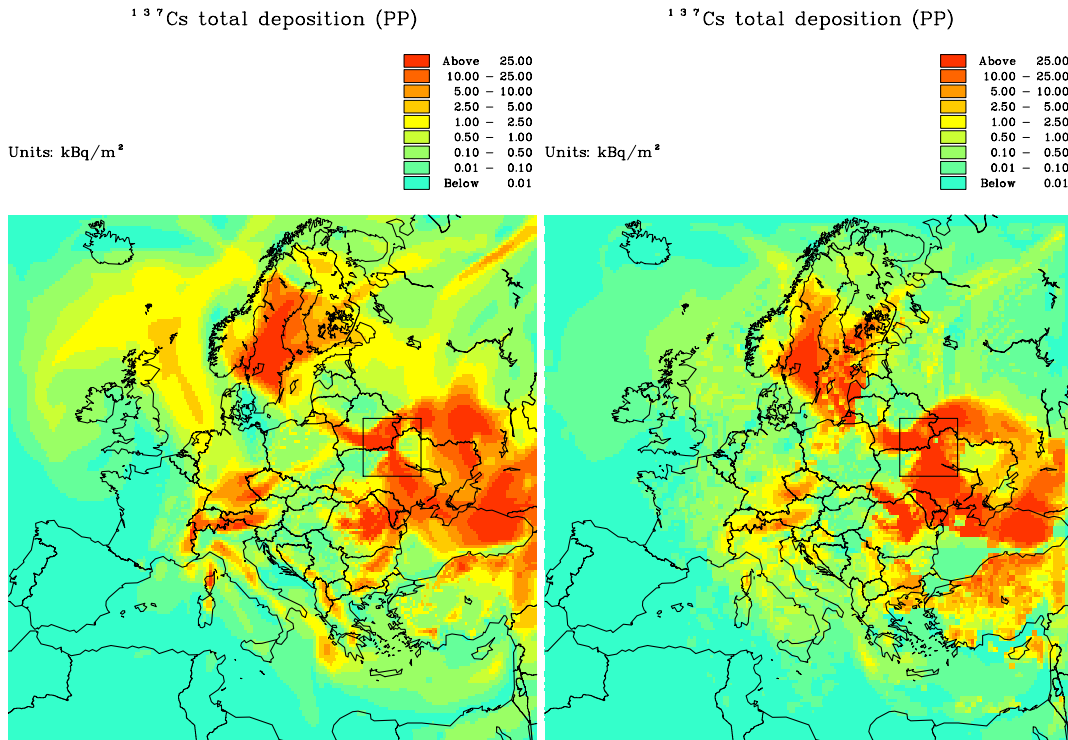


Fig. 7. Examples of the accumulated total deposition of ^{137}Cs from the Chernobyl accident at the end of the simulation period (7 May 12:00 UTC). Left: accumulated total deposition based on relative humidity for wet deposition and the simple method for dry deposition. Right: accumulated total deposition based on precipitation rates for wet deposition and the simple method for dry deposition.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Print Version

Interactive Discussion