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optimal site locations

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An objective determination of optimal site locations for detecting expected trends in upper-air temperature and total column ozone

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Abstract

In the first study reported on here, requirements on random uncertainty of instantaneous temperature measurements, sampling frequency, season and pressure, required to ensure a minimum random uncertainty of monthly mean temperatures, have been explored. These results then inform analyses conducted in a second study which seeks to identify the optimal location of sites for detecting projected trends in upper-air temperatures in the shortest possible time. The third part of the paper presents a similar analysis for the optimal locations of sites to detect projected trends in total column ozone. Results from the first study show that only for individual measurement random uncertainties > 0.2 K does the measurement random uncertainty start to contribute significantly to the random uncertainty of the monthly mean. Analysis of the effects of the individual measurement random uncertainty and sampling strategy on the ability to detect upper-air temperature trends shows that only when the measurement random uncertainty exceeds 2 K, and measurements are made just once or twice a month, is the quality of the trend determination compromised.

The time to detect a trend in some upper-air climate variable is a function of the unforced variance in the signal, the degree of autocorrelation, and the expected magnitude of the trend. For middle tropospheric and lower stratospheric temperatures, the first two quantities were derived from Microwave Sounding Unit (MSU) and Advanced Microwave Sounding Unit (AMSU) measurements while projected trends were obtained by averaging 21st century trends from simulations made by 11 chemistry–climate models (CCMs). For total column ozone, variance and autocorrelation were derived from the Bodeker Scientific total column ozone database with projected trends obtained from median values from 21 CCM simulations of total column ozone changes over the 21st century. While the optimal sites identified in this analysis for detecting temperature and total column ozone trends in the shortest time possible result from our use of only one of a wide range of objective strategies, these results provide additional incentives for

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initiating measurement programmes at these sites or, if already in operation, to continue to be supported.

1 Introduction

Stratospheric temperatures represent the first order connection between natural and anthropogenically driven changes in radiative forcing and changes in other climate variables at the Earth's surface. There is, therefore, a strong interest in detecting upper-air temperature trends as efficiently and reliably as possible. The vertical structure of temperature trends also provides important information for climate change attribution since increases in atmospheric long-lived greenhouse gas (GHG) concentrations warm the troposphere, but cool the stratosphere. Ozone also acts as a GHG and absorbs UV radiation in the stratosphere such that changes in ozone concentration also change the temperature structure of the atmosphere. Thus, dependable long-term measurements of temperature and ozone are essential for climate change detection and attribution studies.

Historical observations present challenges for estimating trends since measurement uncertainties can be large. A number of papers (e.g. Free et al., 2002; Wang et al., 2012 and references therein) point to the inherent, and partly irreparable, problems that arise from complicated merging of data sets of changing or unknown quality and different measurement approaches. Homogenisation of merged data sets cannot eliminate the respective uncertainty in derived trends.

Although satellite instruments are capable of measuring the vertical distribution of temperature and ozone globally, the resultant measurement series are often deficient for trend detection since: (1) the calibration of satellites, once in orbit, is a challenging task and slight differences in instrumental design, satellite and satellite-operation design, and retrieval algorithms impose severe difficulties on constructing homogeneous time series (Thompson et al., 2012). (2) Individual satellites often measure over periods that are too short to detect trends, and may stop operating unexpectedly, preventing ap-

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appropriate continuity or overlap in observations. (3) The vertical and horizontal resolution of satellite measurements may be too coarse to allow for appropriate interpretation and attribution of observed changes.

Stable ground-based long-term temperature and ozone measurements at selected sites, adhering to stringent measurement standards and traceability protocols (e.g. Immler et al., 2010), facilitate the calibration of individual satellite instruments (e.g. Tobin et al., 2006; Balis et al., 2007; Adams et al., 2013) and support the merging of data sets from different satellites with the goal of creating reliable long-term climate data records (e.g. Tummon et al., 2014 and references therein). Such high-quality temperature and ozone time series can also support bridging any gaps that may emerge in satellite data records. With unexpected termination of satellite operations, as well as the ongoing change in satellite technology, bridging gaps becomes critical to creating a continuous monitoring system for the global atmosphere.

More importantly though, these data sets could allow trend analysis in their own right. If observing sites are strategically placed, they might well sample a sufficiently diverse range of regimes to provide a global picture of trends. Most of the current measurement sites, however, are located close to populated areas for ease of access and for historical reason. With approximately 90% of the global population living in the Northern Hemisphere, measurement sites favour the Northern Hemisphere. As a result, such a distribution of sites is unlikely to be representative of the global climate. An example for this is the distribution of the 15 initial GRUAN (GCOS Reference Upper-Air Network) sites which were predominantly located at Northern Hemisphere mid-latitudes (see map at www.gruan.org). Hence, the need exists to provide an objective approach to determine the optimal location of sites.

To address this need, we describe one objective approach for locating sites for early temperature and ozone trend detection. In Sect. 2, we examine the effects of the individual measurement random uncertainty (hereafter simply referred to as the “measurement uncertainty” to distinguish from systematic biases) and sampling strategy on the robustness of upper-air temperature trend detection. The description and outcomes of

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the site selection process are described in Sect. 3 for temperature and in Sect. 4 for ozone.

2 Sampling and trend detection using temperature profiles

The two key questions addressed in this section are: what individual measurement uncertainty and measurement frequency is needed to achieve a certain uncertainty in monthly mean temperature and what are the effects of the individual measurement uncertainty and sampling strategy on the ability to detect upper-air temperature trends?

The temperature profile data used within this study are 6 hourly data from the Climate Forecast System Reanalysis (CFSR; Saha et al., 2010) produced by the National Centers for Environmental Prediction (NCEP). Seidel and Free (2006), using the re-analysis of the climate of the past half century as a model of temperature variations over the next half century, tested various data collection protocols to develop recommendations for observing system requirements to monitor upper-air (here we define “upper-air” as the free troposphere and above) temperature trends. The analysis of Seidel and Free (2006) focussed on estimating monthly average temperature and its standard deviation (SD), as well as multi-decadal trends in monthly temperatures at specific locations, from the surface to 30 hPa. The analysis presented here repeats, in part, that of Seidel and Free (2006), but extends above 30 hPa (the highest level analysed by Seidel and Free) using NCEP CSFR data to extend the results to 1 hPa and to add to some of their conclusions especially with the goal in mind to provide site location recommendations.

Seidel and Free (2006) also assessed the effects on monthly mean temperatures of increasing the uncertainty of temperature measurements, incomplete sampling of the diurnal cycle, incomplete sampling of the days in the month, imperfect long-term stability of the observations, and changes in observation schedule. They found that observations with an uncertainty of ≤ 0.5 K, made at least twice daily, at least once every two or three days, were sufficient to ensure accurate monthly climate statistics (specif-

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ically, monthly mean temperature and standard variation), i.e. only ~ 5% of monthly statistics will be significantly different from those based on four observations per day.

2.1 Effects of sampling on monthly mean uncertainty

To corroborate the findings of Seidel and Free (2006), and to extend the analysis into the upper stratosphere, a similar approach has been followed here, where for a number of selected locations, the uncertainty on monthly mean temperatures is determined as a function of the uncertainty on each contributing instantaneous measurement, sampling frequency, season, and pressure. For this study, we have used 72 locations in 90° longitude zones and 10° latitude zones and added the 15 initial GRUAN sites, which results in a total of 87 locations as shown in Fig. 1.

The analysis is based on sampling of NCEP CFSR fields, assuming that sampling at the highest possible frequency (6 hourly) produces the “true” monthly mean. Then, by simulating different sampling strategies, with different simulated uncertainties on each measurement, and doing this in a Monte Carlo framework, the SD of the differences between the calculated monthly means and the true monthly means can be determined.

Figure 2 shows the uncertainty on the monthly mean temperature as a function of season and the uncertainty on each individual measurement for 6 hourly sampling throughout the month. There is no contribution to the uncertainty on the monthly mean from sampling because the same 6 hourly sampling is used to derive the “true” monthly mean. Therefore, the uncertainty on the monthly mean is about an order of magnitude smaller than the uncertainty on each instantaneous measurement, which is to be expected when averaging ~ 120 measurements through the month i.e. $1/\sqrt{120} \approx 0.1$. As can be seen clearly in Fig. 1, the seasonal influence is minimal.

Figure 3 shows the uncertainty on the monthly means for the same location and pressure level as in Fig. 2 but now for a range of different sampling strategies, including the 6 hourly sampling already displayed in Fig. 2. Note that this is the uncertainty on the monthly means, neglecting any systematic errors (offsets) as these are less important for trend analysis – so while sampling every 24 h at noon would produce monthly mean

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temperatures very different to what would be achieved when sampling every 24 h at midnight, the SD of the differences between the calculated monthly mean and the true monthly mean (rather than the absolute value) is what is assessed. The uncertainty on the monthly mean now shows a clear seasonal cycle for 12 hourly sampling, or coarser, since the temperatures show a higher degree of variability in the winter months at this location and level. At this pressure level (50 hPa), reductions in measurement uncertainty below 0.2 K have little effect on the uncertainty on the monthly mean because it is the uncertainty resulting from incomplete sampling that dominates. It is only for a measurement uncertainty greater than 0.2 K that the measurement uncertainty begins to make an appreciable contribution to the uncertainty on the monthly mean. This 0.2 K threshold does not only apply to the one location displayed in Fig. 3 but is also valid for the other locations at 50 hPa as well as most other sites at 500 hPa (not shown here). The 0.2 K threshold also supports the GRUAN target of less than 0.2 K uncertainty for instantaneous stratospheric temperature measurements (Immler et al., 2010). The permissible measurement uncertainty varies with pressure and season.

The permissible uncertainty of individual temperature measurements required to avoid increasing the uncertainty on the monthly means by more than 10 % above what would be achieved when sampling with 0.01 K uncertainty is shown in Fig. 4. Results from all the 87 locations selected for this analysis and for all months were averaged to produce this figure, with the individual curves showing the permissible uncertainty for each of the 11 sampling schemes.

When sampling every 12 h, at noon/midnight or at 6 a.m./6 p.m. (solid blue and cyan curves), in the upper stratosphere, measuring with 0.5 K uncertainty is sufficient to avoid affecting the uncertainty of the monthly means by more than 10 %; this reduces to 0.25 K at ~ 20 hPa and to 0.15 K in the free troposphere. If the frequency of sampling decreases, the sampling uncertainty comes to dominate, resulting in less stringent requirements on the uncertainty on each individual measurement. For example, for operational radiosonde sites making twice daily temperature profile measurements, there is something to be gained by reducing the uncertainty on each measurement to 0.2 K

or less since this minimizes the uncertainty on the resultant monthly means, thereby allowing for more robust estimates of upper-air temperature trends. For sites sampling only once per week, or less frequently (blue, green and red dashed curves in Fig. 4), a measurement uncertainty of 0.5 K is sufficient to ensure that there is no additional increase in the random uncertainty of the resultant monthly means. Of course with such infrequent sampling the monthly means will have greater uncertainties than with more frequent sampling.

2.2 Sampling strategies, measurement uncertainty, and trend detection

The effects of individual measurement uncertainty and sampling strategy on the ability to detect upper air temperature trends has also been investigated using the NCEP CFSR reanalyses temperature profiles. Temperature trends were calculated at each of the 37 pressure levels, for each of the 87 locations using a state-of-the-art regression model (Bodeker et al., 1998). Residuals from the regression model fit were then used in a Monte Carlo bootstrap resampling to create 1000 statistically identical time series, each of which was passed through the regression model to create a histogram of trends. Blocks of residuals are selected so as to preserve the autocorrelation structure in the original time series. This method was applied to each of the monthly mean time series, as generated above, based on different assumptions about the uncertainty of each of the individual temperature measurements, and the 12 different sampling strategies (see Fig. 3 and caption of Fig. 4).

Two examples of the effects of (1) uncertainty on individual measurements and (2) sampling strategy on the quantification of temperature trends are displayed in Fig. 5. The graph shows that at this location and pressure, only sampling less frequently than once weekly, and with measurement uncertainty ≥ 2 K is the quality of trend detection significantly degraded. At 50 hPa and 39.95° N, 105.2° W (lower panel of Fig. 5), temperature trends of ~ -0.032 K decade⁻¹ are statistically highly significant in that none of the 1000 Monte Carlo simulations produced positive trends, and are robust against almost all combinations of measurement uncertainty and sampling strategy.

As in the previous example, it is only when the measurement uncertainty exceeds 2 K, and measurements are made only once or twice per month, is the robustness of the trend determination compromised.

3 Site selection for temperature trend detection

In this section, we address the question: which of the existing sites engaged in upper-air temperature measurements are best located to detect expected future trends in upper-air temperatures within the shortest time possible? To do so, we explore and discuss one objective method (without claiming that it is the best or only method) for selecting the optimal locations for detecting projected 21st century temperature trends at approximately 5 and 17.5 km altitude in the shortest time possible.

To provide specific guidance based on the material presented in Sect. 2, we investigated the number of years it would take to detect projected trends in upper-air temperatures for specified sampling regimens (both in terms of frequency and measurement uncertainty). Figure 6 shows expected 21st century trends in upper-air temperatures obtained by averaging trends from REF-B2 simulations made by 11 chemistry–climate models as part of the SPARC CCMVal-2 activity (e.g. Young et al., 2013). REF-B2 is the so-called reference simulation and is a self consistent transient simulation from 1960 to 2100 (Eyring et al., 2010). In this simulation the surface time series of halocarbons are based on the adjusted A1 scenario from WMO (2007). The adjusted A1 halogen scenario includes the earlier phase out of hydrochlorofluorocarbons (HCFCs) that was agreed to by the Parties to the Montreal Protocol in 2007 (Eyring et al., 2010). The long-lived GHG surface concentrations are taken from the SRES (Special Report on Emission Scenarios) GHG scenario A1B (IPCC, 2000).

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The number of years of measurements required to detect a trend at the 95 % confidence level with a probability of 0.9 can be approximated by (Whiteman et al., 2011):

$$n^* = \left[\frac{3.3\sigma_N}{|\omega_0|} \sqrt{\frac{1 + \phi_N}{1 - \phi_N}} \right]^{2/3} \quad (1)$$

where σ_N is the SD of the unforced variability in the time series, i.e. the SD of the residuals after the application of the regression model (described in Sect. 2.2) to remove all known sources of variability, ω_0 is the trend magnitude in K year^{-1} (see Fig. 6), and ϕ_N is the autocorrelation in the residuals (Tiao et al., 1990).

This equation implies that after the calculated number of years, there is a 90 % probability that a trend of the correct sign will have been detected, if we assume that detecting a trend means identifying a trend at the 95 % confidence level. σ_N and ϕ_N values for the 87 analysis locations at the 37 pressure levels were calculated from the NCEP CFSR time series for the 120 different sampling regimens (i.e. 12 sampling strategies for 10 different measurements uncertainties ranging from 0.01–10 K).

When used in Eq. (1) together with the projected 21st century temperature trends shown in Fig. 6, examples of results for two sites are shown in Fig. 7. Calculations were made for 3219 cases (87 locations and 37 pressure levels). Typically, it is only when the uncertainty on each measurement exceeds 2 K, is the ability to detect trends significantly compromised, consistent with the findings presented in Sect. 2.2.

When comparing the results for the two sites displayed in Fig. 7, one in the tropics and one at high latitudes, it is clear that the uncertainty on each temperature measurement, has little impact on the time required to detect the projected trend. Similarly, it is only for sampling regimens of every 4 days, or less frequently, that the sampling frequency affects the number of years required to detect the projected trend (see also Seidel and Free, 2006). The biggest effect on the time required to detect the projected trend stems from the natural variability (the noise) in the time series, the autocorrelation in the data and the magnitude of the expected trend. While for the site at

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25° N the projected trend is expected to be detected within 30 years or less, for the site at 85° N, the projected trend will likely not be detected within 100 years.

To further synthesize the results, three pressure levels, viz. 50, 10, and 1 hPa were selected to investigate which measurement regimens, if any, allow for the detection of a temperature trend within 30 years, assuming an uncertainty on each measurement of 1 K. It is apparent from the analysis (not shown here) that in the upper stratosphere (1 hPa), it is possible to detect temperature trends in the tropics (30° S to 30° N) with almost any measurement programme – even one measurement per month would be sufficient to detect the trend within 30 years. Over the Arctic however, no measurement regimen, no matter how frequently the measurements are made, and even if the measurements are made with very small uncertainty (at 0.01 K), would detect the annual temperature trend within 30 years. In contrast to this, in the Antarctic, most measurement regimens (at 1 K uncertainty) would detect the trend within 30 years. Over the southern mid-latitudes, the trends would be detected at only one location within 30 years, whereas over northern mid-latitudes, trends may be detected at several locations.

At 10 hPa, the situation is similar to the 1 hPa level, with tropical trends being detected more easily than extra-tropical ones, but the robustness now also extends to northern mid-latitudes. The trend detection over the Antarctic is less robust. At 50 hPa, trends may be detectable at up to half of the locations within the tropics, whereas in the extra-tropical regions, no measurement regimen would lead to the detection of the expected temperature trends within 30 years.

This analysis was performed using annually averaged trends and it might well be that trends in some seasons are more likely to be detectable than in the annual mean, either because the trend is steeper in that season, or because the variability in that season is smaller, or both. For the purposes of trend detection, analyses such as those summarized in Fig. 7 should be conducted for any proposed measurement site to define the required random uncertainty on the measurements, the measurement regimen, and the time it is likely to take to detect the expected trend in temperature. Sites should

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then be selected based on the magnitude of the expected trend, the natural variability, and the auto-correlation in the data as detailed in Eq. (1).

To identify such preferable sites where temperature trends could be identified sooner than elsewhere, an analysis based on Microwave Sounding Unit (MSU) and Advanced Microwave Sounding Unit (AMSU) temperature measurements, available from remote sensing systems (Mears and Wentz, 2008), was carried out. Figure 8 shows the results of this analysis for the merged MSU channel 2 and AMSU channel 5 temperatures. These are indicative of the middle troposphere with the weighting function peaking at ~ 5 km altitude. The SD of the residuals from the application of the regression model to monthly mean temperatures (Fig. 8a) and the first order auto-correlation coefficient (Fig. 8b) are two of the quantities needed to calculate the number of years required to detect a prescribed temperature trend as detailed in Eq. (1).

The month-to-month variability in the data minimizes in the tropics and maximizes over high latitudes, particularly over the Canadian Arctic. This would suggest that the tropics would be ideally suited to long-term temperature trend detection in the middle troposphere. However, as shown in Fig. 8b, the auto-correlation in the temperature time series also maximizes in the tropics. When the SD on the monthly means and the calculated first order auto-correlation are used together with a prescribed trend of $0.5 \text{ K decade}^{-1}$ in Eq. (1), the results shown in Fig. 8c are obtained. Large regions of the tropics and sub-tropics have temperature time series that would be amenable to detection of mid-troposphere temperature trends of $0.5 \text{ K decade}^{-1}$ within ~ 10 years. However, as seen in Fig. 6, temperature trends at 5 km are not everywhere $0.5 \text{ K decade}^{-1}$. If we use the expected temperature trends at 5 km from Fig. 6 in Eq. (1) then the results displayed in Fig. 8d are obtained. This is the optimal figure to use for deciding where to locate measurement sites for detecting trends in mid-tropospheric temperatures.

One objective strategy (but certainly not the only strategy) is to select an existing site from the relevant global observation networks closest to the minimum value shown in Fig. 8d. For the purposes of this study, only sites from the GRUAN and GUAN networks were considered for this selection. The site closest to the minimum value was

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tained from 21 CCM simulations of total column ozone changes over the 21st century under the CCMVal2 REF-B2 scenario. Except for one model (CMAM), sea-surface temperatures and sea-ice concentrations are prescribed from coupled ocean model simulations, either from simulations with the ocean coupled to the underlying general circulation model, or from coupled ocean–atmosphere models used in the IPCC 4th assessment report under the same GHG scenario. At each latitude and longitude, the median ozone trend value from the 21 CCM simulations available was extracted and used as the indicative total column ozone trend.

Trends in total column ozone, unlike those in temperature, are not expected to be linear over the coming century over many regions of the globe. It is therefore less relevant to consider the time to detect expected 21st century trends in total column ozone as an indicator of where total column ozone observing sites should be located. For example, if in some region of the globe, such as the tropics, where ozone is expected to increase until the middle of the 21st century and then to decrease thereafter, the time to detect the expected trend until 2100 may be significantly longer than the time to detect the trend until 2050. The approach taken is therefore to first conduct an analysis, similar to that for temperature, but considering expected trends in ozone from 2010 to 2020 and identifying which set of locations would be best suited for detecting those expected trends. The trend period is then extended by one year to consider trends from 2010 to 2021, and a second set of sites is identified. This is repeated until 2010–2050, thereby creating 31 sets of optimal sites for detecting ozone trends. An example of the outcomes of this analysis for the 2010–2050 analysis is shown in Fig. 10a.

Monthly mean total column ozone data obtained from the Bodeker Scientific total column ozone database¹ spanning the period November 1978 to August 2012 were then analysed for their SD and first order auto-correlation, two of the quantities needed to calculate the number of years required to detect a prescribed total column ozone trend. The model used to derive the residuals was similar to that used in Bodeker et al. (2001), which includes terms accounting for the mean annual cycle, the linear

¹<http://www.bodekerscientific.com/data/total-column-ozone>

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trend, the quasi-biennial oscillation (QBO), the El Niño Southern Oscillation (ENSO), the solar cycle, and the El Chichón and Mt. Pinatubo volcanic eruptions. The resultant SD of the monthly means and the first order auto-correlation coefficient are displayed in Fig. 10b and c. Month-to-month variability in the data minimizes in the tropics and maximizes over high latitudes, particularly over Siberia. This would suggest that the tropics would be ideally suited to long-term total column ozone trend detection. However, as shown in Fig. 10c, the auto-correlation in the total column ozone also maximizes in the tropics. When the SD of the regression model residuals and the first order auto-correlation are used together with the projected trends in total column ozone, the results shown in Fig. 10d are obtained.

In analogy to the temperature trends, one objective strategy (but certainly not the only strategy) to use Fig. 10d to determine optimal locations for measurement sites is to select an existing site closest to the minimum value shown in Fig. 10d. In this case only sites from WOUDC, SHADOZ and NDACC networks were considered.

The site closest to the minimum value was found to be the historical WOUDC site at Ushuaia (II). We now look for the next site with the shortest time to detect expected total column ozone trends that is at least 6000 km from Ushuaia. This is found to be Hobart. We then continue to look through the list of existing measurement sites, ordered by the number of years required to detect trends, selecting sites that are at least 6000 km away from sites already selected. The resultant distribution of sites is shown in Fig. 10d and listed in Table 3. Three of the sites in Table 3 are also on the list of the 10 most often selected sites within the 31 sets of optimal sites discussed above and summarized in Table 4. In this analysis, 66 sites were selected in total with 23 of these sites being located in the Southern Hemisphere.

5 Summary

For a number of globally distributed locations around the globe (87 in total, see Fig. 1), the dependence of the uncertainty on monthly mean temperatures on individual mea-

surement uncertainty, sampling frequency, season, and pressure was assessed using NCEP CFSR reanalyses. Our results show that only for individual temperature measurement uncertainties greater than 0.2 K, does the measurement uncertainty start to contribute significantly to the uncertainty on the monthly mean. In practical terms, this means that for operational radiosonde stations which carry out temperature profile measurements twice daily, it is worthwhile to work to reduce the uncertainty on each measurement to ≤ 0.2 K since this minimizes the uncertainty of the resultant monthly means, which should lead to more robust estimates of upper-air temperature trends. However, there is little to be gained by reducing the measurement uncertainty to much less than 0.2 K. This conclusion supports the recommendations made by GRUAN.

With a reduction in sampling frequency, the sampling uncertainty starts to dominate, such that less rigorous criteria regarding the uncertainty requirements for each individual measurement are acceptable. For example, for sites where sampling is only weekly or less frequently, measurement uncertainties of 0.5 K are sufficient to ensure that there is no additional increase in the random uncertainty on the resultant monthly means by more than 10 % above what would be achieved when sampling with 0.01 K uncertainty. This concurs with the findings of Seidel and Free (2006) who found that if the individual measurement uncertainty is at least 0.5 K, monthly means are accurate to within ~ 0.05 K, and SDs are accurate to within 10 %.

Seidel and Free (2006) also found that increasing the uncertainty on temperature measurements has minor effects on the accuracy of the monthly means and SDs and is not an important factor in determining multi-decadal trends. The latter is consistent with our finding that only when the measurement uncertainty exceeds 2 K, and measurements are made just once or twice a month or less frequently, the quality of the trend determination is compromised. We find that for a wide range of uncertainties and sampling frequencies, these aspects of a monitoring programme have little impact on the number of years required to detect the projected trend which depends more on the natural variability and auto-correlation in the time series. As a result, at some locations such as in the tropics, the projected temperature trend is expected to be detected within

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30 years or less, while for locations in the northern high latitudes, the projected trend will likely not be detected even within 100 years.

Given these constraints, we have endeavoured to find an objective selection process for the most suitable measurement sites where temperature trends in the mid-troposphere and lower stratosphere could be identified sooner than elsewhere. Note that this is just one example of an objective site selection strategy and that the resulting maps depend on the criteria used.

A similar technique was applied to find an optimal distribution of measurements sites to detect ozone trends in the shortest time possible. Since trends in total column ozone are not expected to be linear over the coming century over many regions of the globe, it is less pertinent to consider the time to detect expected 21st century trends in total column ozone as an indicator of where total column ozone observing sites should be located. We have therefore investigated different time periods from 2010–2020 up to 2010–2050 to generate 31 sets of optimal sites for ozone trend detection and the 10 measurement sites appearing most often within these 31 sets are listed in Table 4.

Studies such as the one presented here provide a sound scientific basis for decision making with regard to new and existing measurements sites and can help reduce costs and concentrate efforts where they are the most needed and most effective.

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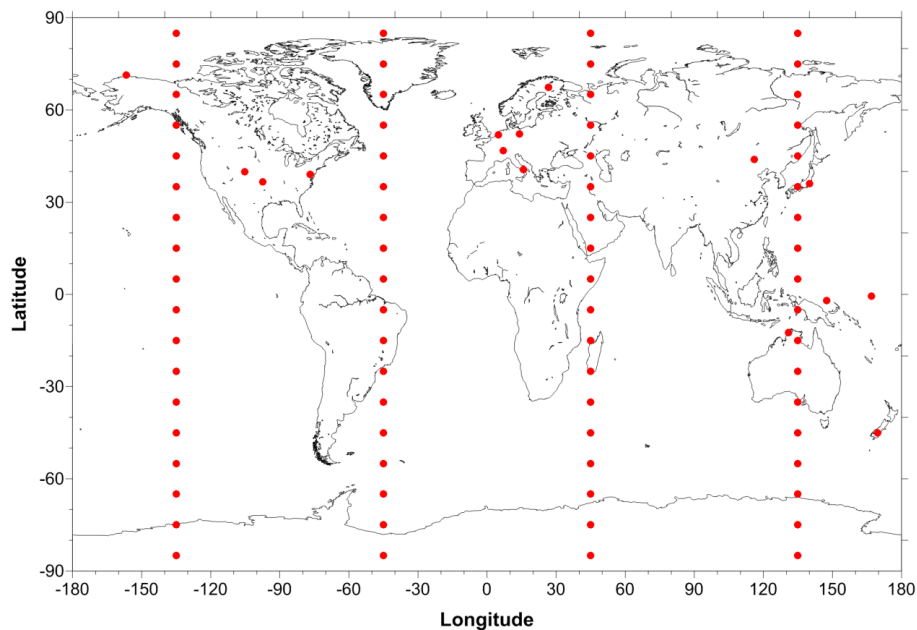


Figure 1. Map of the 87 locations used for the data analysis; 15 of the locations are the initial GRUAN sites and the other 72 of the locations are positioned in 90° longitude zones and 10° latitude zones as shown on the map.

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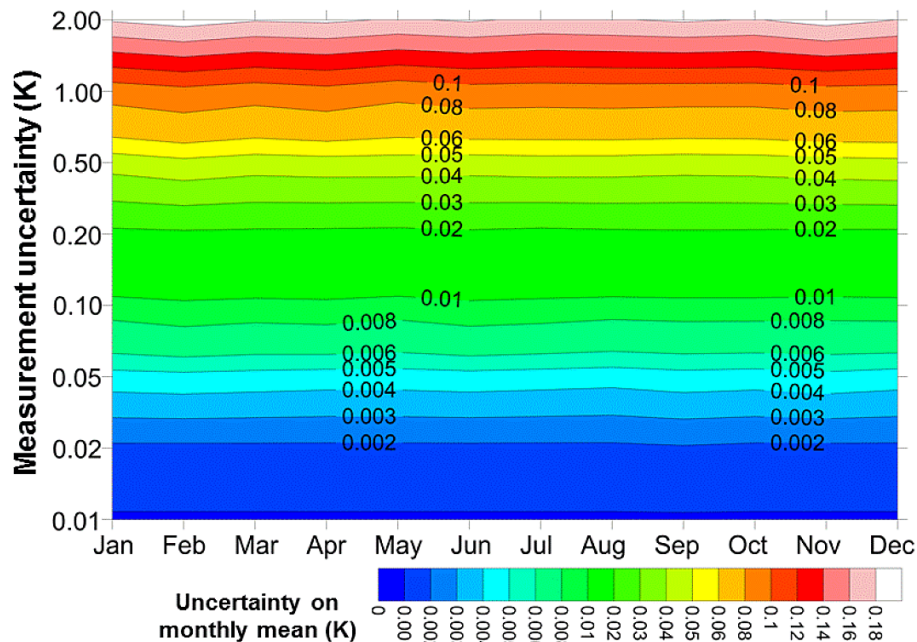


Figure 2. The resultant uncertainty on the monthly means at 50 hPa, 85° N, 135° W (selected randomly as an example), for 6 hourly sampling, as a function of the random uncertainty on each instantaneous measurement.

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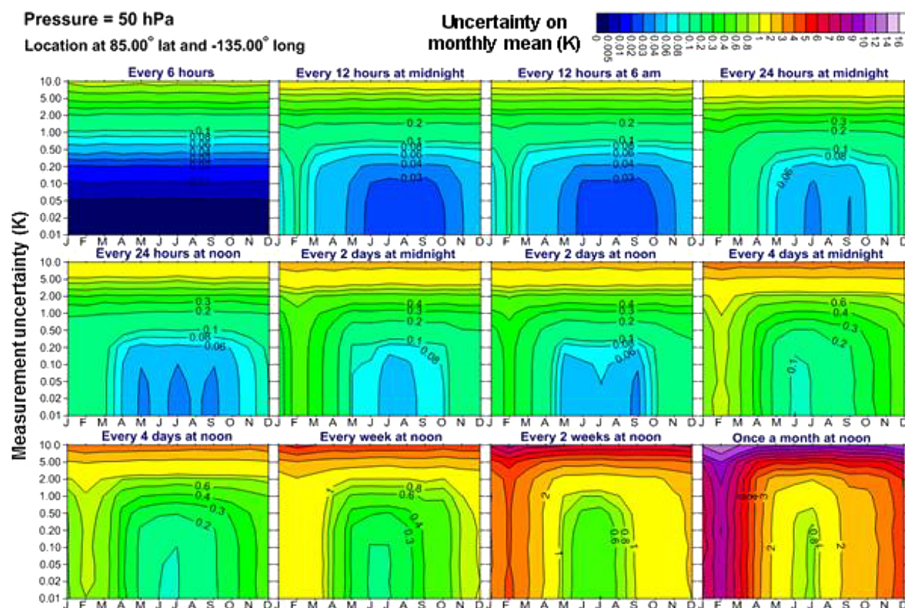


Figure 3. The uncertainty on the monthly means at 50 hPa, 85° N, 135° W, for a range of sampling strategies, as a function of the random uncertainty of each instantaneous measurement.

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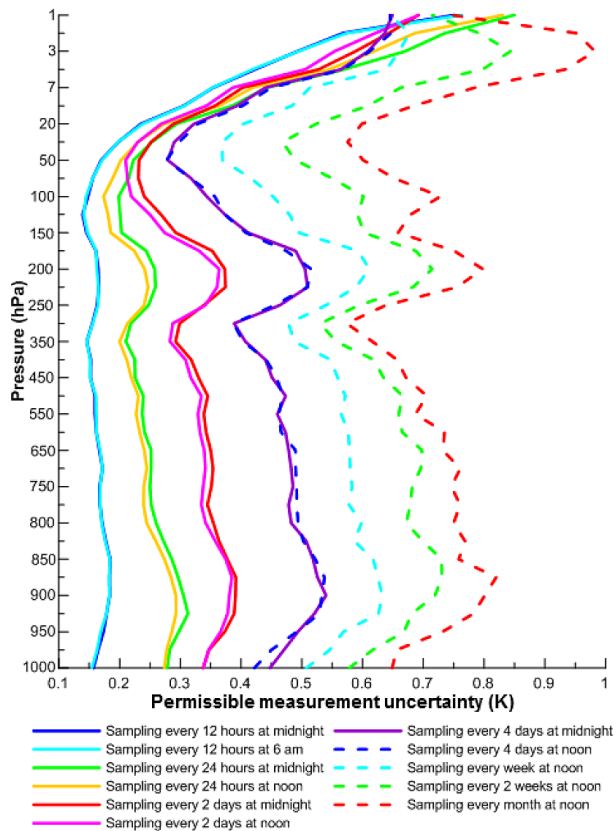


Figure 4. The permissible uncertainty on temperature measurements across a range of sampling strategies required to avoid more than 10% increase in the uncertainty on the monthly means compared to the monthly mean uncertainty that would result from sampling with 0.01 K uncertainty. Results from all 87 locations selected for this analysis and for all months were averaged to produce this figure.

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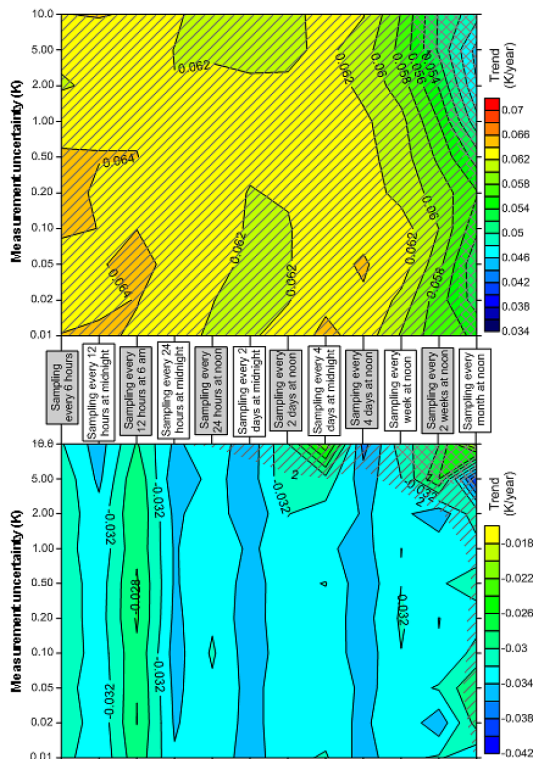


Figure 5. Upper panel: annual mean trends at 1 hPa, 85° N, 135° W, as a function of individual measurement uncertainty used to calculate the monthly means used as input to the regression analysis, and sampling regimen. Regions with single hatching show where trends are statistically significantly different from zero at between 1σ and 2σ . Regions with double hatching show where the trend is not statistically significantly different from zero at 1σ . Lower panel: same analysis as upper panel but for 39.95° N, 105.2° W at 50 hPa.

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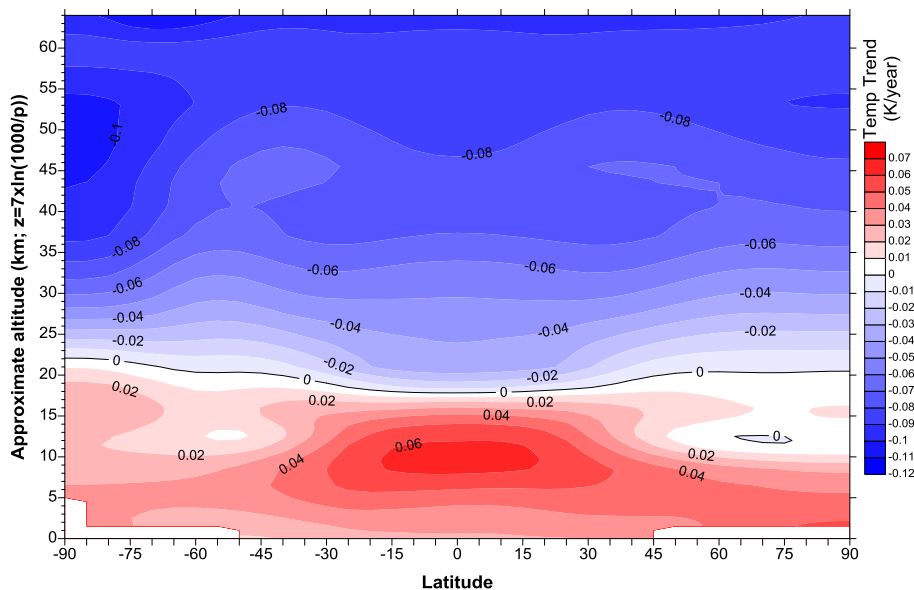


Figure 6. Projected trends in upper-air temperatures for 2000–2099 from 11 chemistry–climate models running the REF-B2 simulation from CCMVal-2.

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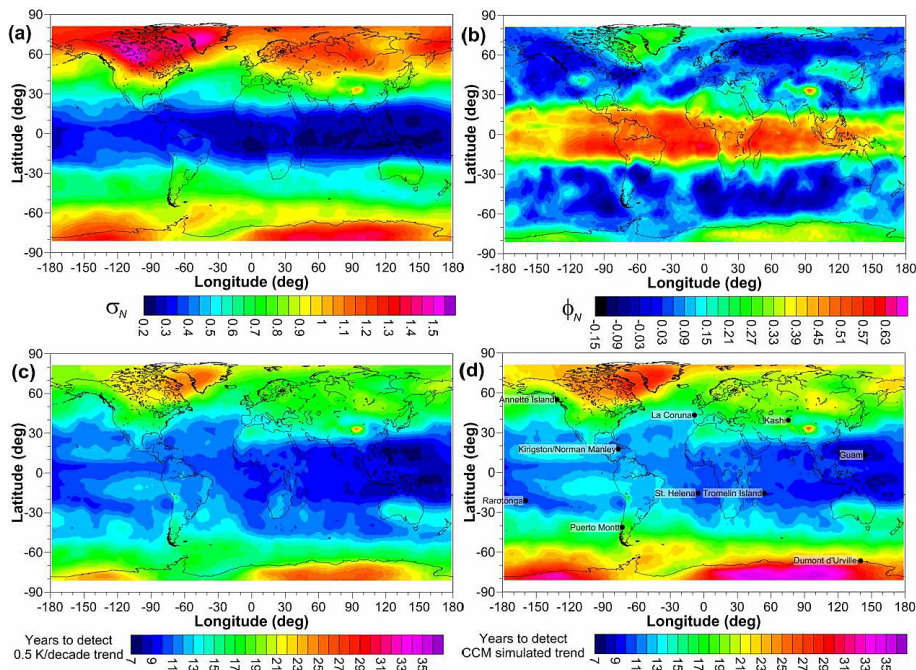


Figure 8. Analyses of merged MSU channel 2 and AMSU channel 5 temperature data – 1978 to 2013. **(a)** SD of regression model residuals, **(b)** the first order auto-correlation coefficient of the residuals **(c)** the number of years required to detect a trend of $0.5 \text{ K decade}^{-1}$, and **(d)** the number of years required to detect the trend at 5 km altitude (close to where the MSU channel 2 and AMSU channel 5 weighting functions peak) as shown in Fig. 6. Only existing GUAN and GRUAN stations have been used as basis to select the optimal sites for early trend detection shown here.

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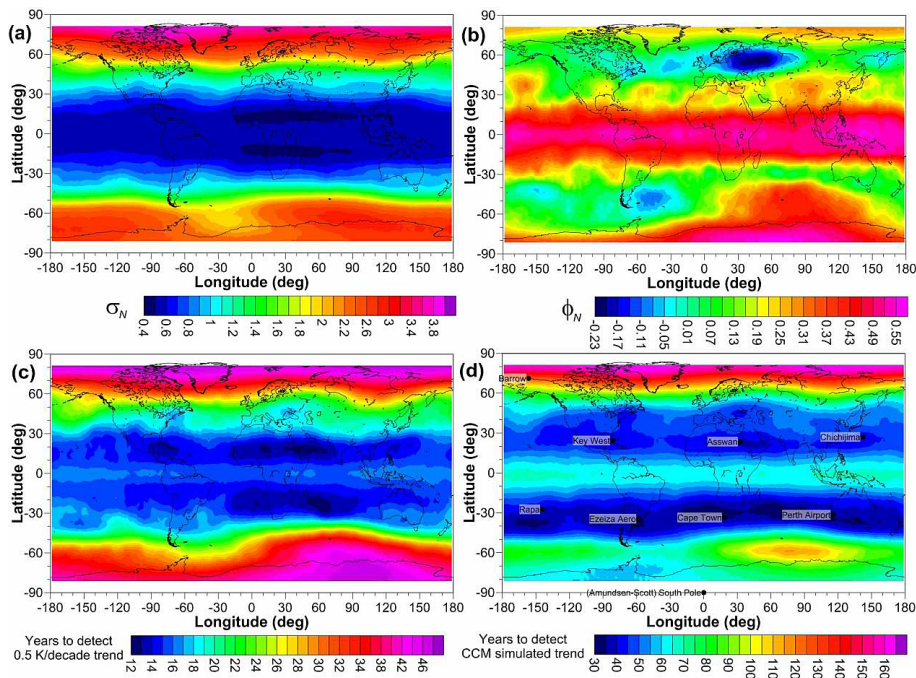


Figure 9. Analyses of merged MSU channel 4 and AMSU channel 9 temperature data – 1978 to 2013. **(a)** SD of regression model residuals, **(b)** the first order auto-correlation coefficient of the residuals, **(c)** the number of years required to detect a trend of $0.5 \text{ K decade}^{-1}$, and **(d)** the number of years required to detect the trend at 17.5 km altitude (close to where the MSU channel 4 and AMSU channel 9 weighting functions peak) as shown in Fig. 6. Only existing GUAN and GRUAN stations have been used as basis to select the optimal sites for early trend detection shown here.



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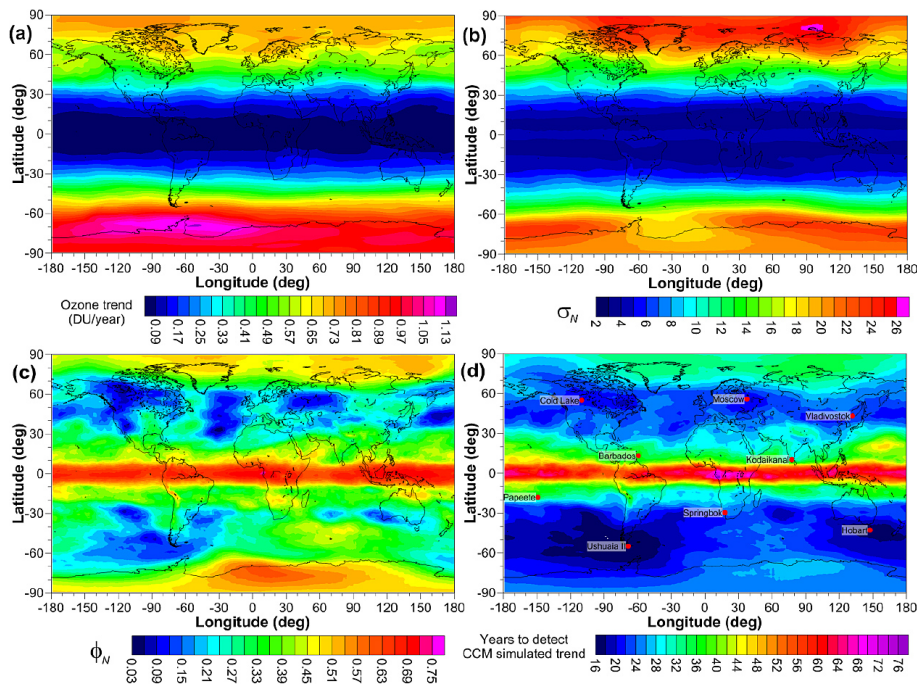


Figure 10. (a) Total column ozone trends in DU/year obtained from median values of trends calculated from 21 CCM projections of ozone over the period 2010 to 2050, (b) the SD in regression model residuals in monthly mean total column ozone calculated from the Bodeker Scientific total column ozone database, (c) the first order auto-correlation coefficient of the residuals, (d) the number of years required to detect the expected total column ozone trends displayed in panel (a). Also shown in panel (d) are selected locations which are at least 6000 km apart but sample regions of short periods to detect expected trends.