1 Long-term trend analysis and climatology of tropical cirrus

2 clouds using 16 years of lidar dataset over Southern India

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9 Abstract

10 16-year (1998 – 2013) climatology of cirrus clouds and their macrophysical (base height, top 11 height and geometrical thickness) and optical properties (cloud optical thickness) observed using a ground-based lidar over Gadanki (13.5°N, 79.2°E), India, is presented. The 12 13 climatology obtained from the ground-based lidar is compared with the climatology obtained 14 from seven and a half years (June 2006 - December 2013) of Cloud-Aerosol LIdar with 15 Orthogonal Polarization (CALIOP) observations. A very good agreement is found between 16 the two climatologies in spite of their opposite viewing geometries and the differences in sampling frequencies. Nearly 50-55% of cirrus clouds were found to possess geometrical 17 18 thickness less than 2 km. Ground-based lidar is found to detect more number of sub-visible 19 clouds than CALIOP which has implications for global warming studies as sub-visible cirrus 20 clouds have significant positive radiative forcing. Cirrus clouds with mid-cloud temperatures 21 between -50°C to -70°C have a mean geometrical thickness greater than 2 km in contrast to 22 the earlier reported value of 1.7 km. Trend analyses reveal a statistically significant increase 23 in the altitude of sub-visible cirrus clouds which is consistent with the recent climate model 24 simulations. The mid-cloud altitude of sub-visible cirrus clouds is found to be increasing at 25 the rate of 41±21 m/year. Statistically significant decrease in optical thickness of sub-visible 26 and thick cirrus clouds is observed. Also, the fraction of sub-visible cirrus cloud is found to have increased by 9% in the last sixteen years (1998 to 2013) at the cost of fraction of thin 27 28 cirrus clouds which is decreased by 7%. This has implications to the temperature and water 29 vapour budget in the tropical tropopause layer.

32 1 Introduction

33 Cirrus clouds are ubiquitous, high altitude, thin and wispy cold clouds predominantly 34 consisting of non-spherical ice crystals. They exhibit a very high degree of spatio-temporal 35 variability in their macrophysical, microphysical and optical properties (Liou, 1986; Lynch et 36 al., 2001). These clouds affect the earth's radiation budget through two competing radiative 37 effects viz., albedo effect (by reflecting back the incoming shortwave solar radiation) and 38 green-house effect (by trapping the outgoing long wave terrestrial radiation) (Liou, 2005). 39 The former effect causes cooling while the later causes warming. The magnitude of these 40 radiative effects are strong functions of optical and macrophysical (cloud coverage, altitude, 41 thickness) properties. The optical properties are in turn strong function of microphysical 42 (amount, size, shape and orientation of ice-crystals) properties (Liou, 1986; Liou, 2005). 43 Overall, cirrus clouds are found to have net positive radiative forcing (Chen et al., 2000; 44 Hartmann et al., 1992) at the top of the atmosphere (TOA) and thus they warm the climate 45 system. However, these estimates are based on the International Satellite Cloud Climatology 46 Project (ISCCP) cloud data obtained from passive satellites that do not consider the overlap 47 effect of multi-layered clouds. This overlap effect is the largest source of uncertainty in 48 estimating the long-wave radiative fluxes (Stephens et al., 2004) and cannot be neglected in 49 tropics where the occurrence of multi-layered cirrus clouds is the highest (Nazaryan et al., 50 2008). This difficulty can be overcome only by using ground and space-based lidars that 51 provide vertical distribution of clouds with opposite viewing geometry.

52 For decades, the representation of cirrus clouds and their processes in the climate models is 53 found to be challenging, partly owing to the lack of fundamental details of cloud microphysical processes and partly due to the inability to resolve small scale processes in a 54 55 General Circulation Model (GCM) grid box (Boucher et al., 2013 and references therein). For 56 instance, still the cloud feedback from thin cirrus cloud (which causes net warming) amount 57 is unknown which results in a substantial uncertainty in the climate model predictions. 58 Essentially, this demands highly stable, accurate, precise and long-term observations from 59 ground and space-based lidars to understand the processes and validate the models.

60 Cirrus clouds that cover about 50% of the globe with highest fraction over the tropics 61 (Stubenrauch et al., 2010, 2013) have strong potential to impact the regional (especially the 62 tropics) and global climate. It is well known that water vapour, low temperature and ice 63 nuclei (for heterogeneous freezing) are the main ingredients needed for the formation of 64 cirrus clouds. Recent research shows that the stratospheric water vapour which mainly comes 65 from the tropical tropopause layer (TTL) has been increasing (Rosenlof et al., 2001; Solomon 66 et al., 2010) and this increase is closely associated with the changes in the tropopause 67 temperature (Randel and Jensen, 2013). In addition to this, aerosols in the TTL, some of 68 which serve as ice-nuclei are increasing (Kulkarni et al., 2008; Vernier et al., 2015) especially 69 during the monsoon season over south-east Asia. Latitudinal changes in the distribution of 70 water vapour, temperature and aerosols will affect the distribution of TTL cirrus clouds 71 (Massie et al., 2013) and ultimately affect the Earth's radiation balance. Thus, it is essential 72 to quantify the properties of TTL cirrus clouds and their dependence on geographic locations, 73 temperature (altitude) and aerosol composition which necessitate long-term observations 74 (Randel and Jensen, 2013).

75 Several modelling studies have suggested that warming climate will affect cirrus cloud 76 properties such as altitude and thickness (Boucher et al., 2013 and references within; Chepfer 77 et al., 2014). Long-term observations of vertically resolved properties of cirrus clouds can 78 help in early detection of climate change or validate climate models.

79 Despite the continuous efforts made to minimize the uncertainties in cirrus cloud properties at 80 regional and global scales through ground-based, space-based and in-situ observations, 81 regional climatologies of tropical cirrus clouds on the decadal time scale are very few. All 82 these facts strongly encourage us to build a detailed cirrus cloud climatology based on 16 83 years (1998-2013) of ground-based lidar data and seven and a half years (Jun. 2006 - Dec. 84 2013) of Cloud-Aerosol Lidar with Orthogonal Polarization (CALIOP) aboard Cloud-85 Aerosol Lidar and Infrared Pathfinder Satellite Observations (CALIPSO) data over Gadanki (13.5°N, 79.2°E) a tropical location in South Asia. Note that CALIOP has a narrow swath and 86 87 repeat-cycle of the order of 16 days in tropics. It is essential to understand whether such low 88 temporal resolution data captures major cloud variability. Further, there are few advantages 89 and disadvantages of both ground-based and space-borne lidars. While the ground-based 90 (space-borne) lidars have excellent vertical and temporal (spatial) resolution for obtaining 91 cirrus properties, they suffer from poor spatial (temporal) resolution. Further, no information 92 on cirrus clouds can be obtained using ground-based lidar during cloudy conditions while 93 space-borne lidars do not have such restrictions as they are being viewed from the top. Thus, 94 both ground-based and space-borne lidars supplement each other. However, as the two lidars have different viewing geometry and sampling frequency, it is important to investigatewhether these factors affect long-term climatology.

97 In this paper, we report analysis of the 16-year climatology of macrophysical (base height, 98 top height and geometrical thickness) and optical properties (cloud optical thickness) of cirrus 99 clouds observed using ground-based lidar at Gadanki. We compare this climatology with that 100 obtained from CALIOP observations (during 2006-2013). The dependence of cirrus cloud 101 geometrical and optical thickness on mid-cloud temperature is also investigated. In addition 102 to this, we also investigate the long-term trends in the properties of sub-visible, thin and thick 103 cirrus clouds using both lidars.

104 2 Instruments and data used

105 2.1 NARL lidar

106 For this study, we have used sixteen years (1998-2013) of data from a ground-based lidar 107 situated at the National Atmospheric Research Laboratory (NARL), Gadanki (13.5° N, 79.2° 108 E). To the best of our knowledge, this is the longest duration of a ground-based lidar data set 109 ever used for obtaining cirrus cloud climatology over a tropical station. The detailed site 110 description and system specifications of the lidar (hereafter called NARL lidar) are reported 111 in our earlier study (Pandit et al., 2014). A brief description of the NARL lidar is presented here. The NARL lidar is a monostatic biaxial system which transmits Nd: YAG laser pulses 112 113 of wavelength 532 nm at a rate of 20 Hz (50 Hz since 2007). Each pulse has a pulse energy of 114 550 mJ (600 mJ since 2007) and a pulse duration of 7 ns. The backscattered photons are 115 collected by a Schmidt-Cassegrain telescope attached with two identical orthogonally aligned photomultiplier tubes (PMTs). Photon counts are accumulated in 300 m resolution bins and 116 117 integrated for four minutes. Lidar data were collected only during the nights that are free 118 from low-level clouds and rain. This limits the observation time during the cloudy nights especially during the summer monsoon season (June-September) when the sky is mostly 119 120 covered with thick low-level clouds. Lidar profiles were rigorously quality checked based on 121 signal to noise ratio before using them in cirrus cloud statistics. A total of 41,280 profiles 122 qualified for building the cirrus cloud climatology.

123 2.2 CALIPSO cloud products

124 CALIPSO is an integral part of the afternoon-train (called A-train) constellation of satellites
125 dedicated to the synergistic observation of aerosols and clouds over the entire globe. Since its

126 launch on 28 April 2006, CALIPSO has been consistently providing high quality vertical 127 distribution of aerosol and cloud properties at unprecedented resolution and accuracy (Young 128 and Vaughan, 2009). This has significantly improved our understanding of aerosols and 129 clouds globally. In order to compare the properties of cirrus clouds obtained from NARL 130 lidar, we have used level-2, 5-km cloud layer and cloud profile (Version 3.01, 3.02 and 3.03) 131 data products obtained from CALIOP aboard CALIPSO. Here, the attribute 5-km implies 5 132 km horizontal resolution along the satellite track at ground level. CALIOP is a near-nadir viewing space-based, dual-wavelength, dual-polarization, three channel elastic backscatter 133 134 lidar that transmits linearly polarized laser pulses having an average pulse energy of 110 mJ 135 both at first (1064 nm) and second harmonic (532 nm) wavelengths of Nd: YAG laser 136 (Winker, 2003; Hunt et al., 2009; Winker et al., 2009). The specifications of both NARL lidar and CALIOP are compared in Table 1. The backscattered signal is received by a 1 m 137 138 diameter telescope with parallel and perpendicularly-polarized channels at 532 nm wavelengths and one parallel channel at 1064 nm. 139

140 It is well known that the properties of cirrus clouds exhibit significant spatial and temporal 141 variations (Liou, 1986). In order to obtain the best spatio-temporal concurrent observations 142 with respect to NARL lidar observations, CALIOP overpasses within 50 km radius from 143 Gadanki are considered for the period from June 2006 to December 2013. Both day and 144 night-time data are used for obtaining cirrus cloud climatology near Gadanki. The nearest night-time CALIOP overpass takes place at around 20:33 UTC (02:03 local time) which is 145 146 about 11 km away from Gadanki whereas the nearest day time CALIOP overpass takes place 147 at around 08:21UTC (13:51 local time) which is about 34 km away from Gadanki. The 148 proximity of CALIOP night-time overpasses to Gadanki provides us a unique opportunity to 149 study the properties of cirrus clouds simultaneously using ground-based and space-borne lidars over a tropical station with opposite viewing geometry. Two such nocturnal 150 151 observations of cirrus clouds over Gadanki obtained using NARL lidar and CALIOP on 19-152 20 November 2008 and 03-04 December 2013 are depicted in Figure 1, detailed properties of 153 them are presented in the next section. The red circle in the CALIOP vertical feature mask 154 (VFM) in Figure 1 (c) and (h) shows the clouds present in the proximity of Gadanki. Because 155 of the 16 days repeat cycle of CALIOP, at most four overpasses can be obtained in each 156 month, with two day-time and two night-time overpasses. During the period from June 2006 157 to December 2013, a total number of 146 (151) data files are collected during the day (night) 158 in the region selected around Gadanki which contained a total number of 2906 (3022)

profiles, out of which 1820 (1876) profiles were day (night) time profiles (Table S1 in thesupporting material).

161 2.3 NCEP FNL air temperature data

162 For the estimation of extinction coefficient and hence the optical thickness of cirrus cloud 163 layers, pressure and temperature (p-T) profiles over Gadanki during the lidar observation 164 time are required. Since, daily p-T profiles are available only at 12:00 GMT (17:30 local time) over Gadanki from the daily radiosonde launches since 2006, we used six hourly air 165 166 temperature (at 26 pressure levels) from NCEP FNL 1° x 1° data interpolated from the period 167 of 1999-2013 to have near-simultaneous temperature observations over Gadanki during the 168 lidar observation time. For the year 1998 when no NCEP FNL data are available, monthly 169 mean temperature profiles were used for the estimation of the molecular backscattering 170 coefficient. These data were obtained from the website http://rda.ucar.edu/datasets/ds083.2/. 171 Same temperature profiles are used for finding the relation between the cirrus cloud properties and temperature. 172

173 **3 Methodology**

174 **3.1** Cirrus cloud detection and percentage occurrence

175 Cirrus clouds observed using NARL lidar data are detected by using Wavelet Covariance 176 Transform (WCT) method as described in Pandit et al. (2014). Briefly, the cloud detection 177 algorithm uses Haar wavelet with dilation 3 and altitude dependent threshold. The threshold varying with altitude has benefit of low noise in near range and less false detection at far 178 179 range. Further to avoid false detection, if raw photon counts at cloud layer are not greater 180 than mean background plus three times the standard deviation then those profiles are 181 excluded. Cloud base and top heights of five different layers can be obtained very accurately 182 using this method. The lowest physical thickness that NARL lidar could detect is 600m. To 183 distinguish cirrus cloud layer from other clouds, we used a temperature threshold. Only those 184 cloud layers with a base temperature below -20 °C (which corresponds to a base height above 185 8 km) are considered as cirrus cloud layer in this study. Cloud layer boundaries in the 186 attenuated backscattered signal acquired by CALIOP are detected by a Selective, Iterative 187 Boundary Location (SIBYL) algorithm described in Vaughan et al. (2009). This algorithm finds the aerosol and cloud layers (called features) and detects their boundaries. We have 188 189 used same temperature criterion as for NARL lidar to identify cirrus clouds in CALIOP data.

To know the effects of cirrus clouds on regional climate, it is very essential to know how frequent these clouds occur over a given region (especially over the tropical regions) during different months and seasons in a year. For this, the percentage occurrence (PO) of cirrus clouds at each altitude bin for both NARL lidar and CALIOP cloud layer data sets are calculated by taking the ratio of number of profiles with cirrus clouds at that bin to total number of profiles (Pandit et al., 2014).

3.2 Macrophysical and thermodynamical properties of cirrus clouds

197 Macrophysical properties of cirrus clouds viz., cirrus base, top, mid-cloud altitude, 198 geometrical thickness and its distance from the tropopause are obtained from both lidar data-199 sets. Mid-cloud altitude of each cloud layer is taken as mid-point between the base and top 200 altitude for that layer. Base and top altitudes of cloud layers are provided directly in CALIOP 201 5-km cloud layer data files. The geometrical thickness of cirrus clouds is obtained by 202 subtracting the cirrus base altitude from cirrus top altitude. Distance from the tropopause of 203 each cirrus cloud layer in case of NARL lidar is obtained by subtracting the cirrus mid-cloud 204 altitude from the tropopause height provided in the FNL data which uses lapse-rate 205 tropopause definition of WMO. We have used temperature profiles and tropopause height 206 present in CALIOP cloud data products which are originally derived from GEOS-5 data 207 product provided by the Global Modelling and Assimilation Office (GMAO).

208 **3.3 Optical properties of cirrus clouds**

209 Kaestner's lidar inversion method (Kaestner, 1986) has been used for the retrieval of the 210 extinction coefficient (α). The extinction profile integrated between cloud base and the top is 211 used to obtain optical thickness of cirrus cloud layers. Molecular backscattering coefficient at 212 532 nm wavelength is calculated using the pressure and temperature data obtained from 213 NCEP FNL data. Lidar ratio for cirrus clouds is assumed to be constant with altitude and 214 season with a value of 25 sr following CALIOP extinction retrieval algorithm (Young et al., 215 2013; Young and Vaughan, 2009). The effect of multiple scattering which is a function of 216 laser penetration depth, cloud range (or height), receiver field of view (FoV), size and shapes 217 of ice-crystals (Eloranta, 1998) cannot be neglected in the measurement of cirrus cloud properties using a lidar with a receiver FoV of 1 mrad. Several studies (Chen et al., 2002; 218 219 Chepfer et al., 1999; Hogan, 2006; Sassen and Cho, 1992; Sassen and Comstock, 2001) have 220 suggested different values of multiple scattering correction factor (η) ranging from 0.1 – 0.9

221 based on different crystal habits and optical properties of cirrus clouds. In this study, the effect of multiple-scattering is taken care by assuming $\eta = 0.75$ following Sassen and Cho 222 223 (1992) and Sassen and Comstock (2001). Sassen and Cho (1992) used telescope with field of 224 view 3 mrad which is comparable to our telescope. Sassen and Comstock (2001) used three 225 different values of η depending on cloud type which are 0.6 to 0.7 for thick clouds, 0.8 for 226 thin clouds and 0.9 for sub-visible cirrus cloud. We have used single value 0.75 for all the 227 cloud types instead. In case of CALIOP, $\eta = 0.6$ is being used in retrieval algorithm of the 228 extinction coefficient (Young et al., 2013; Young and Vaughan, 2009). The reference altitude 229 used in the retrieval of extinction coefficient is 25 km for NARL lidar.

230 Optical thickness (τ_{cloud}) of cirrus cloud layer is derived using the expression

$$231 \quad \tau_{cloud} = \int_{Z_b}^{Z_c} \alpha(z) dz \quad . \tag{1}$$

Where, α (z) is the extinction coefficient of a cirrus cloud layer with z_b and z_t as a base and top altitudes, respectively.

234 For the retrieval of particulate extinction coefficient profiles obtained from the attenuated 235 backscattered data acquired by CALIOP, the fully automated retrieval algorithms called 236 Hybrid Extinction Retrieval Algorithms (HERA) are being used (Young and Vaughan, 2009). 237 Once the features (aerosol and cloud layers) are identified by Scene Classification Algorithm 238 (SCA), their lidar ratio is estimated using the transmission method (Young, 1995). When 239 transmission method fails, initial lidar ratio is assigned based on the feature type, for example 240 lidar ratio of 25 sr is chosen for cirrus clouds. HERA is then invoked to compute the 241 extinction coefficient profiles using the profile solver (Young and Vaughan, 2009), which is 242 then integrated to obtain cloud optical depth. We use the variable named feature optical depth 243 from the CALIOP level-2 data product which provides optical depths for ten cloud layers. 244 Only those features for which Cloud-Aerosol Discrimination (CAD) score lies between 80 and 100 and are located below -20 °C are considered as cirrus cloud layers. Features with 245 246 negative values of optical depth are excluded from the statistics of cirrus optical properties. 247 Figure 1 (e) and 1 (j) illustrate two cases where extinction profile of cirrus cloud layer observed on two different nights (20th November 2008 and 4th December 2013) over Gadanki 248 249 using NARL lidar is compared with the concurrent extinction profiles obtained from 250 CALIOP cloud profile data. For comparison with the NARL lidar, we averaged three 251 proximate CALIOP profiles shown by blue asterisks in Figure 1(d) and 1(i). For both nights,

252 the base and top altitudes of cirrus cloud layer from NARL lidar and CALIOP show a very good agreement. Also, the cloud layer structure on 20th November 2008 in both lidars show 253 good similarity. However, the structure of cirrus cloud layer on 4th December 2013 and the 254 255 magnitude of extinction coefficient in both cases are different which may be due to the spatial 256 inhomogeneity of the cloud structure. This can be seen clearly from the CALIOP vertical 257 feature mask (VFM) for the two nights as shown in Figure 1(c) and 1(h). The various 258 macrophysical and optical properties of cirrus cloud layer observed on these two nights are 259 listed in Table 2. Overall the extinction coefficients and the cloud optical depths observed using NARL lidar are lower than CALIOP. However, the difference is not same on two 260 nights with 4th December 2013 night having larger differences. 261

262 4 Results and discussion

263 **4.1 Occurrence of cirrus clouds over Gadanki: Climatology**

264 The climatological altitude distribution of PO of cirrus clouds for the entire 16 years (1998-265 2013) irrespective of sampling time is shown with a dashed black line in Figure 2(a). The PO 266 peaks at 14.5 km with a value of 25%. Altitude distribution of PO based on CALIOP data has 267 relatively broader peak with structures. The altitude of peak PO based on CALIOP data is in 268 good agreement with NARL lidar; however, magnitude of peak PO differ significantly with 269 CALIOP having higher values. To investigate whether the difference in time range (16 years 270 vs. 7.5 years) or time of observation (entire night vs. fixed overpass) is responsible for 271 differences in PO based on NARL lidar and PO based on CALIOP, a subset of entire NARL 272 lidar data-set for the period 2006-2013 is made. This data subset contains lidar data acquired 273 only during the half an hour time window centred at 02:03 hours (mean local time for 274 CALIOP night-time overpass near Gadanki). The PO of cirrus clouds based on sub-set NARL 275 lidar data is shown with a triple-dotted dashed magenta line in Figure 2(a). The altitude 276 distribution of PO based on subset data has a slightly better agreement with the altitude of 277 peak PO values based on CALIOP. However, the difference in magnitude between the two PO distributions is still large. This can be attributed to the limited NARL lidar observation 278 279 time during the cloudy nights especially during the monsoon season. For the sake of 280 completeness, the PO distribution for the day-time CALIOP observations (shown by red single dotted-dashed line) is also compared with the other three PO distributions. CALIOP 281 282 night-time PO distribution is slightly larger than that during day-time at all the altitudes. This 283 difference in PO is consistent with the results reported by Sassen et al. (2009) and Thorsen et 284 al. (2013). This has been attributed to two reasons: one due to the day-night difference in the 285 background noise level present in the backscattered signal from the CALIOP measurement 286 and secondly, due to the day-night differences in cirrus cloud occurrence in tropics. The day-287 time background noise level present in the backscattered signal from the CALIOP 288 measurement is larger than that during the night-time which prevents the detection of very 289 thin cirrus cloud layers during the day. In addition to this, when the formation of cirrus clouds 290 is associated with the development of deep-convective clouds which is quite common in 291 tropics, then the frequency of occurrence of cirrus clouds during night and day will be 292 different (Liu and Zipser, 2008; Sassen et al., 2009). Using Micro-pulse lidar observations 293 over a tropical station Nauru Island (0.52° S, 166.92° E), Comstock et al. (2002, Figure 5 (c)) 294 also found higher occurrence of cirrus clouds during evening and night hours than that during 295 noon hours. It is not possible to exactly pin-point which mechanism will be dominant for day 296 and night PO difference at Gadanki with the limited dataset which we have used in this study.

297 4.2 Monthly and seasonal variation in PO of cirrus clouds

298 The altitude distribution of monthly mean PO of cirrus clouds near Gadanki obtained from 299 the 16 years of NARL lidar data and seven and half years of CALIOP night-time data are 300 shown in Figure 3(a) and 3(b), respectively. Both exhibit enhanced PO in the altitude range 301 of 9-17 km during May-September owing to the increased convective activities in and around 302 Gadanki. During this period, geometrically and optically thick cirrus clouds occur frequently 303 near Gadanki region (Sunil Kumar et al., 2003; Martins et al., 2011; Pandit et al., 2014). The 304 occurrence of multi-layered clouds is also high during this time (not shown here). All these factors are responsible for the spread of the PO distribution of clouds during these months. 305 306 Here, we have not filtered NARL lidar data for 2 AM half-an-hour time window as very few 307 profiles (less than 50) are available in that window during June-August. The altitude of high 308 PO obtained from both lidars is found above 14 km (Figure 3 (a & b)) during the months of 309 May-September. The monthly mean base and top altitudes of cirrus clouds (represented by 310 filled red squares and filled pink circles superimposed on the colour contours) obtained from 311 both lidars are consistent with each other (See Figure 3 (a) and 3 (b)). We also observe a 312 significant fraction of cirrus clouds occurring near and some-times above the tropopause 313 (shown by brown inverted triangles) during May-September months. This result is in good 314 agreement with the observations of Pan and Munchak (2011, Figure 7).

315 The seasonal variation in the altitude distribution of PO of cirrus clouds obtained from three 316 (NARL lidar, CALIOP day and night) data sets is illustrated in Figure 2 (b)-(e). Number of 317 cloudy and total profiles for each season used for calculating PO for both the datasets is 318 provided in Table S1 in the supporting material. During the winter season (Figure 2 (b)), the 319 PO distribution above 15 km from NARL lidar data shows higher values than that of 320 CALIOP data. The climatological PO (1998-2013) distribution from NARL lidar during the 321 pre-monsoon season shows very good qualitative and quantitative match with the CALIOP 322 night-time PO distribution (Figure 2 (c)). During the monsoon season (Figure 2 (d)), the 323 number of lidar observations is the lowest. However, the climatological PO from NARL lidar 324 for monsoon season matches well with the CALIOP PO distributions. Overall, we see a very 325 good consistency between the two lidar systems in observing the seasonal occurrence of 326 cirrus clouds in-spite of opposite viewing geometry.

4.3 Macrophysical and thermodynamic properties of cirrus clouds

The histograms for the macrophysical properties (cirrus base, top and mid-cloud altitude, 328 329 distance from tropopause, and geometrical thickness) and the thermodynamical property 330 (mid-cloud temperature) of cirrus clouds are shown in Figure 4 and their statistical details are 331 listed in Table 3. The frequency distributions of cirrus base height from both lidars show a 332 good agreement (Figure 4 (a)). The distribution is spread out between 8 and 18 km such that 333 it is difficult to pinpoint the most probable cirrus base altitude. Careful observation and 334 comparison of cirrus base distribution with that reported in Nazaryan et al. (2008, Figure 6 in 335 20° S - 20° N latitude bands) show that the most probable base altitude lies between 12 and 14 km. Both, NARL lidar and CALIOP histograms show a nearly one to one correspondence 336 337 with each other in case of cloud top altitude (Figure 4 (b)) and mid-cloud altitude (Figure 4 338 (c)). The most probable top-altitude of cirrus clouds observed over Gadanki lies in the 339 altitude range of 15-17 km, which is very close to the tropopause. This is in good agreement 340 with values reported by Comstock et al. (2002) over a tropical island (Nauru Island), who 341 found it to be around 16 km. However, it is little higher than values reported by Seifert et al. 342 (2007) who found it to be in the range 13-15 km over Maldives (another tropical island). 343 Both CALIOP and NARL data in Figure 4 (d) show that cirrus cloud observed over Gadanki 344 lie very close to the tropopause. About 9% of them are found above the tropopause. CALIOP 345 observations show less number of cases of cirrus clouds above the tropopause. Pan and 346 Munchak, (2011) have shown that fixed sampling time of CALIOP can result in

underestimation of cirrus clouds above the tropopause. Most of the time, the mid-cloud temperature is less than -65 °C and found to be as low as -85 °C (Figure 4 (e)). NARL lidar and CALIOP night-time data in Figure 4 (f) show that nearly 50-55% of cirrus clouds observed over Gadanki have a thickness less than 2 km. Though, we observed significant day-night differences in the occurrence of cirrus clouds, the day and night distribution of macrophysical and thermodynamic properties of cirrus clouds do not differ much.

The geometrical thickness of cirrus clouds depends on the formation mechanism, cloud 353 354 altitude and cloud-temperature. Figure 5 (a)-(c) show the dependence of geometrical thickness on the base altitude of the cloud (z_b) . For this, we divided all the cirrus cloud layers 355 356 into three groups based on their occurrence in the different altitude regions. These altitude regions are 8 km $< z_b < 12$ km, 12 km $< z_b < 15$ km and $z_b > 15$ km. Clouds of thickness less 357 358 than 2 km occur predominantly in altitude range above 15 km. Our results agree well with the 359 results obtained using ground-based lidars at other tropical stations viz. Nauru Island 360 (Comstock et al., 2002) and Maldives (Seifert et al., 2007). However, NARL lidar is found to 361 have a larger number of thin clouds in the altitude range above 15 km than CALIOP during night time. Again the comparison of NARL lidar and CALIOP day-time for clouds above 15 362 363 km is good, although caution is advised by Thorsen et al. (2013) while interpreting the day-364 time cirrus cloud observation using CALIOP which are biased towards the smaller 365 geometrical thicknesses. Optical properties of these clouds are discussed in the next subsection. 366

367 4.4 Optical properties of cirrus clouds

368 The distributions of optical thickness of cirrus clouds observed over Gadanki using NARL 369 lidar and CALIOP data sets are shown in Figure 6 (a). The optical thickness of cirrus cloud 370 layers is binned into intervals of 0.1. We see a high fraction of cirrus clouds with optical 371 thickness less than 0.1 in all the three data sets. To further investigate the distribution of 372 optical thickness we divide each data set of cirrus clouds into different categories. Based on 373 the magnitude of optical thickness, Sassen and Cho (1992) classified cirrus clouds into three 374 categories viz. sub-visible cirrus clouds whose optical thickness, $\tau_{cloud} < 0.03$; thin cirrus 375 clouds with $0.03 < \tau_{cloud} < 0.3$ and thick cirrus clouds with $\tau_{cloud} > 0.3$. When this classification 376 was applied to NARL lidar data set, we find that sub-visible, thin and thick cirrus clouds occurred nearly 52% (56% during 2006-2013), 36% (36% during 2006-2013) and 11% (8% 377 378 during 2006-2013) of the total observation time, respectively. Sunil Kumar et al., (2003) have

379 also reported the similar high occurrence of sub-visible cirrus using six years of data over 380 Gadanki. In contrast, nearly equal occurrence of the three cloud categories i.e. 35% sub-381 visible, 32% thin and 33% thick cirrus clouds is observed in CALIOP data, possibly due to 382 inability of CALIOP to detect sub-visible cirrus clouds. It is worth to mention that the aircraft 383 studies made during Tropical Composition, Clouds, and Climate Coupling (TC4) experiment 384 which revealed that more than 50% of sub-visible cirrus cloud with thicknesses less than 0.01 385 are unaccounted in the current CALIOP level 2 cloud products (Davis et al., 2010). Martins et 386 al. (2011) also have reported the underestimation of sub-visible cirrus clouds fraction in 387 CALIOP level 2 cloud data products. Frequency distributions for the individual categories are 388 shown in Figure 6 (b)-(d). CALIOP (day) data set shows very few cases of sub-visible cirrus 389 clouds with optical depth less than 0.007 [Figure 6 (b)] whereas night-time observations from 390 NARL lidar and CALIOP show high occurrence of cirrus clouds with optical thickness less 391 than 0.007. This can be explained by the low sensitivity of CALIOP to the day-time cirrus 392 clouds due to the higher background noise than that during night-time. Overall, the 393 distributions of optical thicknesses of cirrus clouds show good agreement between NARL 394 lidar and CALIOP data sets. These distributions are also in good agreement with the findings 395 of Comstock et al. (2002). Figure 6 (d) reveals that NARL lidar sampled smaller number of 396 thick cirrus clouds with $\tau_{cloud} > 1.5$ as compared to CALIOP. This is possibly due to the lack 397 of NARL lidar observations on cloudy nights and lidar's inability to penetrate the opaque 398 clouds.

399 The optical thickness of cirrus clouds depends on the formation mechanism, cloud-altitude, 400 cloud-temperature, amount, size, shape and orientation of ice-crystals. To investigate the 401 dependence of cirrus optical properties on altitude, we categorized cirrus cloud optical 402 thickness obtained from each data set into three different classes based on their base altitude 403 in the same way we did for the geometrical thickness in section 4.3 (Figure 5). Each data set 404 confirms the high occurrence of sub-visible cirrus clouds occurring above 15 km (Figure 5 405 (d)-(f)). In addition to this, we find that the fraction of sub-visible cirrus clouds detected by 406 NARL lidar is higher than that detected by CALIOP.

The distribution of each cirrus cloud type as a function of the mid-cloud altitude is depicted in Figure 7. We observe that the distribution of sub-visible cirrus clouds from each of the data sets is skewed towards the tropopause (between 16 and 17 km). Most of the sub-visible cirrus clouds (Figure 7 (b)) have their mid-cloud altitude in between 14-17 km with maxima at around 16 km. The distribution of thin cirrus clouds is also similar to the sub-visible cirrus 412 clouds in case of CALIOP data-set but the NARL lidar has a peak in the frequency
413 distribution at lower altitude (14 km) (Figure 7 (c)). Thick cirrus clouds as shown in Figure 7
414 (d) occur most of the time in the altitude range of 12-14 km which may be of convective
415 origin.

416 Distribution of geometrical thickness with a bin size of 0.5 km for each cirrus cloud type and 417 for each data set is shown in Figure 8. Most of the sub-visible cirrus clouds are less than 2 km 418 thick (Figure 8 (b)). CALIOP day-time data shows the high fraction of sub-visible cirrus 419 clouds in the 0-0.5 km bin. The distribution of geometrical thickness for thin clouds obtained 420 from NARL lidar slightly differs from that of CALIOP as shown in Figure 8 (c). In case of 421 the NARL lidar, the peak of the frequency distribution is at about 2.5 km thickness, whereas 422 in case of CALIOP the peak of the frequency distribution is at less than 2 km. The 423 geometrical thickness of the majority of thin cirrus clouds is less than 3 km. The flat 424 distribution of geometrical thickness for thick cirrus clouds shown in Figure 8 (d) indicates 425 the diversity in the thickness of cirrus clouds. Night-time distributions from both lidars agree 426 well for thick clouds. However, the bias of CALIOP day-time observations towards smaller 427 geometrical thicknesses can be seen clearly from Figure 8 (d). This can be explained by the 428 presence of high solar background noise in the CALIOP day-time observations (Thorsen et 429 al., 2013). The detection of true boundaries of cirrus clouds becomes cumbersome in the 430 presence of high background noise especially when there are thick clouds below the cirrus clouds. The 60 m vertical resolution of CALIOP could also be one of the reasons behind the 431 432 high frequency of clouds in the initial bins (smaller values) of geometrical thickness.

433 **4.5 Temperature dependence of cirrus properties**

434 In the previous section it is shown that the geometrical thickness of cirrus clouds has altitude 435 dependence. We also found that most of the cirrus clouds occurring above 15 km have a 436 geometrical thickness less than 2 km while clouds below 15 km showed the broader 437 distribution (Figure 5 (a)-(c)). We investigate the dependence of geometrical and optical 438 properties of cirrus clouds on temperature in this section. Note that the mid-cloud temperature 439 used in case of NARL lidar dataset is NCEP FNL data whereas in case of CALIOP dataset it 440 is GMAO temperature profile data. Figure 9 (a) shows the dependence of geometrical 441 thickness of cirrus clouds on the mid-cloud temperature. The geometrical thickness increases 442 from 1 km to 3.5 km as mid-cloud temperature increases from -90 to -60 °C. For the further 443 increase in temperature from -60 to -20 °C, the geometrical thickness decreases to less than 1

444 km. A very nice agreement is observed between CALIOP night-time and NARL lidar data. 445 The geometrical thickness of cirrus clouds exhibits large variation of about 1-5 km in the 446 mid-cloud temperature range of -50 °C to -70 °C with a mean geometrical thickness greater 447 than 2 km. This is in contrast to Sunilkumar and Parameswaran, (2005) who found it to be 448 about 1.7 km over Gadanki. This could be possibly due to the use of temperature profiles 449 based on MST Radar by Sunilkumar and Parameswaran, (2005), which are not as accurate as 450 NCEP FNL data and have lower values compared to CIRA Model temperature profile 451 (Parameswaran et al., 2000). However, difference in temperature profile alone is not 452 sufficient to explain the difference in cloud thickness. Also, the other factors like length of 453 dataset and differences in cloud detection algorithms may have contributed to the observed 454 difference noticed in the two studies. The dependence of geometrical thickness on mid-cloud temperature obtained from CALIOP night-time data is compared with that obtained from 455 456 CALIOP day-time data and is shown in Figure 9 (b). In the temperature range of -45 °C to -457 60 °C, the day-time dependence appears to be weaker than the night-time dependence. This 458 could be due to underestimation of geometrical thickness of clouds during day-time by 459 CALIOP as discussed in previous section.

460 It is important to know the temperature ranges at which optically different cloud types exist. 461 Figure 10 shows the distribution of mid-cloud temperature for each cirrus types. Both, night-462 time data sets show that the majority of sub-visible cirrus clouds occur at temperatures lower than -65 °C (Figure 10 (b)). In the temperature range of -60 °C to -80 °C, most of the thin 463 464 cirrus clouds occur (Figure 10 (c)). The distributions of sub-visible and thin cirrus clouds are 465 skewed towards very low temperature. While most of the thick cirrus clouds occur in the 466 temperature range of -40 °C to -70 °C. The type of cirrus clouds is found to be dependent on 467 different temperature regimes. This is may be mainly due to the differences in the cloudformation mechanisms for example sub-visible cirrus are formed due to in-situ generation 468 469 near tropopause height whereas thick cirrus are generally formed by convective outflow at 470 relatively lower heights except during deep/overshooting convections. However, CALIOP 471 day-time data set shows rather a flat temperature dependence for all the categories.

472 **4.6 Long-term trends**

In our earlier study (Pandit et al., 2014), we reported 8.4% increase in percentage occurrence of cirrus clouds at 16 km altitude and 0.41 and 0.56 km increase in cloud base and top heights respectively over Gadanki in 16 years. Albeit, the percentage increase of 8.4% was not

476 statistically significant. These findings strengthen the hypothesis that warming climate will 477 cause an upward shift of cirrus cloud (Boucher et al., 2013; Hartmann and Larson, 2002). 478 Assuming a simple linear temporal relation, the rate of upward shift of the base altitude is 479 found to be about 26 m/year while that of the top altitude is found to be about 35 m/year. 480 Chepfer et al. (2014) have predicted an upward shift in the cirrus cloud altitude in tropics at a typical rate of 20 m/year using multiple climate models. Using six years of CALIOP 481 482 observations, Zhou et al. (2014) have also showed an increase in the amount and altitude of cirrus clouds in response to the surface warming. Since the trends presented in Pandit et al. 483 484 (2014) were not separated for cloud types (i.e. sub-visible, thin and thick cirrus clouds) and 485 were presented only for three properties (viz. cloud-base-altitude, cloud-top-altitude and 486 percentage occurrence), therefore, here we investigate long-term trends in mid-cloud altitude, 487 mid-cloud temperature, geometrical thickness and optical thickness of each of these cirrus 488 cloud type using both lidars. Figure 11 shows the trends in above mentioned properties of 489 sub-visible cirrus clouds. Trends in these properties for all the three cloud types are provided 490 in Table S2 in supporting material. In the last sixteen years, the monthly mean mid-cloud 491 altitude of sub-visible cirrus clouds is found to be increasing at the rate of 41 ± 21 m/year. The 492 trend is found to be statistically significant (p values 0.05 using Student t-test). CALIOP 493 observations also show an increasing trend in the mid-altitude but found statistically 494 insignificant. As expected from mid-cloud-altitude trend, both lidars show that the mid-cloud 495 temperature is decreasing, which is found to be statistically insignificant. The geometrical 496 thickness however, does not show a statistically significant trend in any of the lidar 497 observations over Gadanki. This is in contrast to mid-latitude station OHP, France where 498 Hoareau et al. (2013) have found statistically significant increase in geometrical thickness but 499 an insignificant trend in cloud-mid-altitude. The optical thickness of sub-visible cirrus clouds obtained from both lidars is found to be decreasing. The trend $-9.4 \times 10^{-5} \pm 5.5 \times 10^{-5}$ per year in 500 the optical thickness of sub-visible cirrus clouds obtained from NARL Lidar is statistically 501 502 significant (p value 0.09) while CALIOP trend is statistically insignificant. All the properties 503 found to have statistically insignificant trends for thin and thick cirrus clouds except for one. 504 Thick cirrus cloud shows statistically significant decreasing trend (p value 0.01) of -1.5×10^{-1} $^{2}\pm 5.3 \times 10^{-3}$ per year in cloud optical thickness (Figure S1 in supporting material). In the latest 505 506 IPCC report (Boucher et al., 2013), a systematic shift from thick high clouds to thin cirrus 507 clouds or vice-versa is suggested as possible mechanism for cloud-climate feedback, 508 however, at the time of the writing IPCC report, evidence for such systematic shift was not 509 available. In this context, we have investigated trends in the fraction of three cloud types. The

510 fraction of sub-visible cloud type is found to have statistically significant (p value 0.1) 511 increase of 9.4% over 16 years. The increase is at the cost of decrease in thin cirrus cloud 512 fraction which is decreased by 7.6%. It is worth to quote the future projections of the Coupled 513 Model Inter-Comparison Project Phase 5 (CMIP5) which are presented from 2006-2099 514 under the Representative Concentration Pathway (RCP) 8.5 scenarios. The projection shows 515 warming trend at 100 hPa over wide region of 60°N-45°S by the end of twenty-first century 516 (Kishore et al., 2015). The projected increase in temperature of ~3.27K at the end of the 517 twenty-first century at 100 hPa is partly attributed to the increase of sub-visible cirrus clouds 518 near the tropopause region. These may also have significant implications for cross-tropopause 519 water vapour transport and related global climate variability.

520

521 5 Summary and conclusions

522 Using the 16 years of lidar observations from a tropical rural site, climatology of cirrus cloud 523 properties is developed and long-term trends are analysed. The ground-based climatology is 524 also compared with the seven and a half year climatology of cirrus clouds observed using 525 CALIOP. Both datasets exhibit good agreement with each other. Some of the salient features 526 of cirrus clouds emerged from this climatology are summarized below:

- 527 1. Cirrus clouds over Gadanki occur more frequently during night-time than during day
 528 time except during September to November when the reverse is true.
- 529
 2. During the months of May to September, a significant percentage of cirrus clouds are
 530 found to occur near the climatological tropopause, while a 9% of them are found
 531 above the tropopause.
- 532 3. About 50-55 % of the cirrus clouds observed over Gadanki have a geometrical
 533 thickness less than 2 km.
- 4. Cirrus clouds that occurred with mid-cloud temperature between -50°C to -70°C have
 a mean geometrical thickness greater than 2 km in contrast to the value 1.7 km
 reported by Sunilkumar and Parameswaran, (2005). Most of the sub-visible and thin
 cirrus clouds occurred with a mid-cloud temperature of less than -60 °C.
- 5. Analyses of long-term trends show the following: (a) Among the three types only the sub-visible cirrus clouds show an increase in their altitude of occurrence. (b) Optical thickness of sub-visible and thick cirrus clouds shows a statistically significant

- decreasing trend. (c) A 9.4% increase in sub-visible cirrus cloud fraction and 7.6%
 decrease in thin cirrus cloud fraction are found from 1998 to 2013.
- 543
 6. The climatology of the NARL lidar and the CALIOP data shows that the NARL lidar
 544 detects more number of sub-visible cirrus clouds (56% of the total observations)
 545 compared to CALIOP (35% of the total observations) for the overlapping period. This
 546 has implication in global warming studies as sub-visible cirrus clouds have significant
 547 positive radiative forcing and their underestimation will lead to underestimation of the
 548 role of cirrus clouds in global warming.
- 549

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Characteristics	NARL lidar	CALIOP
Operating Wavelength(s)	532 nm	532 nm, 1064 nm
Average pulse energy	550 mJ (1998 – 2006) 600 mJ (2007 – 2013)	110 mJ
Pulse width	7 ns	20 ns
Pulse repetition rate	20 Hz (1998 – 2006) 50 Hz (2007 – 2013)	20.16 Hz
Telescope diameter	35.5 cm	100 cm
Receiver field of view	1 mrad	130 µrad
Detectors	Photomultiplier Tube (PMT)	PMT for 532 nm Avalanche photodiode for 1064 nm
Polarization	Co and cross-polarized*	Co and cross-polarized for 532 nm Co-polarized for 1064 nm
Vertical resolution	300 m	30 m for altitude range -0.5 to 8.2 km 60 m for altitude range 8.2 to 20.2 km
Horizontal resolution	Stationed	0.333 km for altitude range -0.5to 8.2 km along the track1 km for altitude range 8.2 to20.2 km along the track

718 Table 1. Specifications of NARL-lidar and CALIOP

*only co-polarized data of 532 nm channel are used.

Date	19-20 November 2008		03-04 December 2013	
Characteristics	NARL lidar	CALIOP	NARL lidar	CALIOP
Local Time	02:07:38	02:07:48	Average of 02:02 and 02:06	02:05:00
Cloud base altitude (km)	14.91	14.94	11.62	11.53
Mid-cloud altitude (km)	15.81	15.90	12.67	12.55
Cloud top altitude (km)	16.71	16.86	13.72	13.56
Geometrical thickness (km)	1.80	1.92	2.10	2.03
Tropopause height (km)	16.41	16.66	16.44	16.51
Distance from tropopause (km)	-0.60	-0.76	-3.77	-3.96
Average layer extinction coefficient (1/km)	0.03	0.05	0.53	0.88
Cloud Optical Depth	0.06	0.09	0.11	0.18

Table 2. Macrophysical and optical properties of cirrus cloud layer detected using NARLlidar and CALIOP on 19-20 November 2008 and 3-4 December 2013.

723 Table 3. Mean, median and standard deviation of macrophysical and thermodynamical

724 properties of cirrus clouds obtained from NARL Lidar and CALIOP over Gadanki. Values in

725	the parentheses	represent	the	median
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Cirrus Properties	NARL Lidar	CALIOP (night)	CALIOP (day)
Base altitude (km)	$13.0 \pm 2.2 \; (13.1)$	12.5 ± 2.2 (12.6)	12.8 ± 2.0 (12.7)
Top altitude (km)	$15.3\pm 2.0\ (15.5)$	14.9 ± 2.1 (15.3)	$14.5 \pm 2.0 \ (14.9)$
Mid-cloud altitude (km)	$14.1 \pm 2.0 \ (14.3)$	$13.7 \pm 2.0 \ (13.9)$	13.6 ± 1.9 (13.8)
Geometrical thickness (km)	2.3 ± 1.3 (1.8)	2.4 ± 1.7 (1.8)	1.7 ± 1.2 (1.3)
Mid-cloud temperature (°C)	-65.0 ± 11.9 (-67.6)	-61.0 ± 14.7 (-63.6)	-60.5± 14.4 (-63.2)
Distance from tropopause (km)	-2.6 ± 2.1 (-2.4)	-2.8 ± 2.0 (-2.7)	-2.8 ± 1.9 (-2.5)

726 Figures



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728 Figure 1. (a) Night-time evolution of cirrus clouds as a function of altitude observed on 19-729 20 November 2008 using NARL Lidar. Colour scale represents the logarithm of the 730 normalized photon counts. Cirrus base and top altitudes are shown with blue and brown lines, 731 respectively. Black dashed vertical line shows the CALIPSO overpass time near Gadanki. (b) 732 Overpass trajectory of CALIPSO (shown by dashed blue line) near Gadanki (shown by filled 733 red circle). (c) Colours show the vertical feature mask (VFM) along the CALIPSO track as a 734 function of altitude on 20 November 2008. The red circle shows the clouds sampled near 735 Gadanki. (d) Overpass trajectory of CALIPSO (dashed blue line) at around 02:07 LT on 20 736 November 2008 near Gadanki (red plus symbol). Blue asterisks correspond to the proximate 737 CALIOP profiles used for averaging, (e) Averaged extinction coefficient profiles obtained 738 from NARL Lidar (dashed red line) and CALIOP (solid blue line). (f) to (j) are same as (a) to 739 (e) respectively but for the observations on 03-04 December 2013.



Figure 2. (a) Climatological altitude distribution of PO of cirrus clouds obtained from
NARL Lidar data for the period 1998-2013 (dashed black line), NARL Lidar data during half
an hour time window centred at 02:03 LT for the period 2006-2013 (triple dotted dashed
magenta line), CALIOP day-time (single dotted dashed red line) and CALIOP night-time
(solid blue line) data sets for the period 2006-2013. (b) Same as (a) but for winter (DJF), (c)
pre-monsoon (MAM), (d) monsoon (JJA), and (e) post-monsoon (SON) seasons.



750 Figure 3. Filled contours show the climatological monthly mean variation of PO of cirrus

clouds as a function of altitude over Gadanki (a) during 1998–2013 using NARL Lidar, (b)
during 2006-2013 using CALIOP (night-time) data. Monthly mean tropopause height, cloud

base height and cloud top height are shown by dashed brown lines with inverted triangles, red

154 line with squares and pink line with filled circles, respectively.

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760 Figure 4. Histograms showing the frequency distribution of macrophysical properties of cirrus clouds viz. (a) Base altitude, (b) Top altitude, (c) Mid-cloud altitude, (d) Distance from 761 762 the tropopause, (e) Mid-cloud temperature, (f) Geometrical thickness obtained from NARL Lidar (1998-2013) data (dashed black line), CALIOP day-time (single dotted red line) and 763 764 CALIOP night-time (solid blue line) data sets. Bin size for (a)-(d) and (f) is 0.5 km while bin 765 size for (e) is 5 °C. Tropopause altitude in case of NARL Lidar data is derived from 1° X 1° 766 FNL temperature profile data near Gadanki grid whereas in case of CALIOP data tropopause 767 altitude is derived from GMAO temperature profile data.

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771Figure 5. Histograms showing the frequency distribution of geometrical thickness [(a) to (c)]772and optical thickness [(d) to (f)] of cirrus cloud layers with base height (z_b) in the ranges of7738km < z_b < 12 km (dashed red line), 12km < z_b < 15 km (solid blue line) and z_b > 15 km774(dotted black line) obtained from NARL Lidar data [(a) and (d)] for the period 1998-2013,775CALIOP night-time data [(b) and (e)] and CALIOP day-time [(c) and (f)] data sets for the776period 2006-2013. Bin size for each histogram of geometrical thickness is 0.5 km while for777optical thickness it is 0.01.





Figure 6. Histograms showing the frequency distribution of optical thickness of (a) all cirrus cloud layers (bin-size = 0.1), (b) sub-visible cirrus ($\tau < 0.03$, bin-size = 0.0025), (c) thin cirrus ($0.03 < \tau < 0.3$, bin-size = 0.025) and (d) thick cirrus cloud layers ($\tau > 0.3$, bin-size = 0.1) obtained from NARL Lidar (dotted black line), CALIOP day-time (dashed red line) and CALIOP night-time (solid blue line) data sets. Percentage mentioned in each panel is in the same order as legend in (a).





Figure 7. Histograms showing the frequency distribution of mid-cloud altitude in bins of 0.5 791 km for (a) all cirrus cloud layers, (b) sub-visible cirrus ($\tau < 0.03$), (c) thin cirrus ($0.03 < \tau <$ 792 0.3) and (d) thick cirrus cloud layers ($\tau > 0.3$) obtained from NARL Lidar (dotted black line), 793 CALIOP day-time (dashed red line) and CALIOP night-time (solid blue line) data sets.



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Figure 8. Histograms showing the frequency distribution of geometrical thickness in bins of 796 0.5 km for (a) all cirrus cloud layers, (b) sub-visible cirrus ($\tau < 0.03$), (c) thin cirrus ($0.03 < \tau$ 797 < 0.3) and (d) thick cirrus cloud layers ($\tau > 0.3$) obtained from NARL Lidar (dotted black 798 line), CALIOP day-time (dashed red line) and CALIOP night-time (solid blue line) data sets.



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Figure 9. Dependence of geometrical thickness of cirrus cloud layers on mid-cloud temperature obtained from (a) NARL Lidar (open red circles) and CALIOP night-time (filled blue circles) data, (b) CALIOP day -time (open red circles) and CALIOP night-time (filled blue circles) data. Circles show the average value while the error bars show the standard deviation.



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Figure 10. Histograms showing the frequency distribution of mid-cloud temperature in bins of 0.5°C for (a) all cirrus cloud layers, (b) sub-visible cirrus ($\tau < 0.03$), (c) thin cirrus (0.03 < $\tau < 0.3$) and (d) thick cirrus cloud layers ($\tau > 0.3$) obtained from NARL Lidar (dotted black line), CALIOP day-time (dashed red line) and CALIOP night-time (solid blue line) data sets.



Figure 11. Time series of monthly mean (a) mid-cloud altitude, (b) mid-cloud temperature, (c) geometrical thickness and (d) optical thickness of sub-visible cirrus clouds obtained using NARL Lidar (shown by open red circles) and CALIOP night time data (shown by blue filled circle). The dashed black line shows the linear fit to the NARL Lidar data points while the solid blue line shows the same for CALIOP data points. Slopes are expressed in unit per year.