



## ABSTRACT

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The vertical structure of Arctic low-level clouds and Arctic boundary layer is studied, using observations from ASCOS (Arctic Summer Cloud Ocean Study), in the central Arctic, in late summer 2008. Two general types of cloud structures are examined: the “neutrally-stratified” and “stably-stratified” clouds. Neutrally-stratified are mixed-phase clouds where radiative-cooling near cloud top produces turbulence that generates a cloud-driven mixed layer. When this layer mixes with the surface-generated turbulence, the cloud layer is coupled to the surface, whereas when such an interaction does not occur, it remains decoupled; the latter state is most frequently observed. The decoupled clouds are usually higher compared to the coupled; differences in thickness or cloud water properties between the two cases are however not found. The surface fluxes are also very similar for both states. The decoupled clouds exhibit a bimodal thermodynamic structure, depending on the depth of the sub-cloud mixed layer (SCML): clouds with shallower SCMLs are disconnected from the surface by weak inversions, whereas those that lay over a deeper SCML are associated with stronger inversions at the decoupling height. Neutrally-stratified clouds generally precipitate; the evaporation/sublimation of precipitation often enhances the decoupling state. Finally, stably-stratified clouds are usually lower, geometrically and optically thinner, non-precipitating liquid-water clouds, not containing enough liquid to drive efficient mixing through cloud-top cooling.

## 1 **1. Introduction**

2 Rapid changes in the Arctic climate during the past decades (Serreze et al., 2000;  
3 Overland et al., 2004; ACIA 2005) have led to widespread attention in the global  
4 climate research community. Annual average near-surface temperatures in the Arctic  
5 have increased by over a factor of two compared to the rest of the world (ACIA  
6 2005; Richter-Menge, 2010) and the sea-ice extent has been declining at an  
7 accelerating rate, especially during summer and early fall (Comiso, 2002; Nghiem et  
8 al., 2007; Stroeve et al., 2012). Extreme anomalies in the mid-September ice extent  
9 minima over the last decade (Serreze et al., 2007; Stroeve et al., 2012), including  
10 record minima in 2007 (Maslanik et al., 2007; Lindsay et al., 2009) and 2012  
11 (Simmonds and Rudeva, 2012; Devasthale et al., 2013; Zhang et al., 2013) are  
12 indicative of an increasing “Arctic amplification” (Serreze and Francis, 2006;  
13 Serreze and Berry, 2011) signaling rapid climate change. This amplification has been  
14 attributed to several factors that affect the surface energy budget; one is the surface-  
15 albedo feedback (Perovich et al., 2008; Stroeve et al., 2012) and how changes at the  
16 surface impact the cloud response (Kay and Gettelman, 2009), and vice versa. Other  
17 amplification hypotheses exist, such as the lapse-rate feedback associated with the  
18 vertical structure of warming (Bintanja et al., 2012; Pithan and Mauritsen, 2014), or  
19 how changes in the large-scale northern hemisphere atmospheric circulation  
20 (Graversen et al., 2008; Kapsch et al., 2013) may result in changes in the clouds and  
21 hence the surface energy balance.

22 Global climate models exhibit a large variation in global and regional  
23 sensitivity to imposed large-scale forcing, which has been attributed to differences in  
24 cloud parameterization schemes and cloud feedbacks, especially those of low-level  
25 clouds (Bony and Dufresne, 2005; Webb et al., 2006; Lauer et al., 2010). To  
26 understand the Arctic climate system, a detailed understanding of cloud processes  
27 and their impact on both the surface and atmospheric thermodynamic structure are  
28 required (Curry et al., 1996). In general, solar radiation is reflected by clouds,  
29 leading to a radiative cooling at the surface, whereas longwave radiation is both  
30 absorbed and emitted by clouds. Over the Arctic, where surface albedo and solar  
31 zenith angles are relatively large and clouds are predominantly low, the net effect on  
32 the sea ice surface is a warming (Shupe and Intrieri, 2004; Sedlar et al., 2011),  
33 except possibly for a short period in summer, when the surface albedo is reduced by

1 sea ice melt (Intrieri et al., 2002). The influence of the clouds on the surface energy  
2 budget depends on several parameters, such as the cover, phase, and vertical and  
3 horizontal cloud distribution, etc. (Randall et al., 1998); combining all the factors is  
4 complex and it is no surprise that clouds are very difficult to model.

5 Low-level clouds are very frequent in the Arctic, especially during the summer  
6 when they occur for 80-90% of the time (Curry and Ebert, 1992; Wang and Key,  
7 2005; Tjernström, 2005; Shupe et al., 2011). Clouds below 3 km a.s.l (above surface  
8 level; unless otherwise stated all heights will be given above the surface) over the  
9 Arctic are most frequently mixed-phase, consisting of both droplets and ice crystals  
10 (Shupe, 2011); the liquid is often concentrated in a relatively thin layer near the top  
11 of the cloud, with near-continuous precipitation consisting of frozen drizzle or ice  
12 crystals formed within the liquid layer (Shupe et al., 2008). These clouds have been  
13 observed to persist for long durations – hours to days (Shupe et al., 2011) – and are  
14 believed to have a critical impact on the surface energy balance (Intrieri et al., 2002;  
15 Persson et al., 2002; Shupe and Intrieri, 2004; Sedlar et al., 2011). Both short- and  
16 longwave radiation are very sensitive to cloud phase; longwave opacity (emissivity)  
17 increases asymptotically to unity with cloud liquid water path, while shortwave  
18 reflection to space increases with increasing numbers of smaller, spherical cloud  
19 droplets (e.g., Twomey, 1977; Stephens, 1978). The end result is more longwave  
20 radiation emitted to the surface and less shortwave radiation transmitted to the  
21 surface when liquid droplets are present than for ice-only clouds (Shupe and Intrieri,  
22 2004; Prenni et al., 2007).

23 Mixed-phase clouds are particularly poorly handled by current climate models  
24 (Tjernström et al., 2005; 2008; Karlsson and Svensson, 2010), suggesting that the  
25 processes that support the maintenance of these clouds in the Arctic are not fully  
26 understood. These processes are discussed in Morrison et al. (2012). For example,  
27 turbulence generated by cloud-top cooling and in-cloud upward air motion play a  
28 critical role; the layer with largest liquid concentrations near cloud top emits  
29 longwave radiation to space (Pinto, 1998), which decreases static stability in the  
30 clouds and leads to a buoyant overturning circulation (e.g., Nicholls, 1984). These  
31 cloud-driven turbulent motions promote the growth of both liquid and ice, rather than  
32 just ice growing at the expense of the liquid (Korolev, 2007) as would intuitively be  
33 expected in an ice/liquid mixture. Moreover, mixing from below cloud base may also

1 be ongoing, driven by surface forcing and/or advection in the lower troposphere,  
2 leading to an upward transfer of heat and moisture. The coupling, or lack thereof  
3 (hence referred to as decoupling), between cloud- and surface-generated turbulence  
4 may be critically important for the sustenance of mixed-phase clouds.

5       Because of the strongly stable near-surface conditions that often occur during  
6 Arctic winter to early spring (Kahl, 1992; Curry, 1986), surface fluxes are often  
7 considered to have no significant contribution to the cloud's moisture during these  
8 seasons; this changes from late spring until October when both open ice-free ocean  
9 and melting sea ice expose a vast source of heat and moisture to the relatively cool  
10 and dry lower atmosphere (Pinto and Curry, 1995). Analysis of the vertical  
11 atmospheric structure in late summer from four different expeditions, including the  
12 Arctic Summer Cloud Ocean Study (ASCOS; [www.ascos.se](http://www.ascos.se), also see Tjernström et  
13 al., 2014) revealed a neutrally-stratified layer extending from the surface up to about  
14 300-600 m (Tjernström et al. 2012), which indicates that the surface and the  
15 boundary-layer clouds could potentially be thermodynamically coupled.

16       Shupe et al. (2013) investigated the interactions between the cloud and  
17 boundary layer using one week of observations from ASCOS and found, however,  
18 that for this time period, such coupling took place only 25% of the time; the rest of  
19 the time the cloud layer was decoupled from the surface. In addition, even when  
20 clouds were coupled with the surface, surface fluxes did not seem to drive this  
21 coupling; instead they simply responded to the mixed-layer processes aloft, driven  
22 primarily by in-cloud generated turbulence.

23       The present study is also based on ASCOS data and provides a complementary  
24 view on cloud-surface interactions to that by Shupe et al. (2013); they analyzed three  
25 case studies, each 9 to 12 hours long, to provide a process-level view of what  
26 happens in these clouds; the time evolution and the transitions between coupled and  
27 decoupled states were important aspects of this study. They also provided a statistical  
28 description of some characteristics of the coupling states, although for a limited time  
29 period and based only on single-cloud layer profiles. The present study offers a  
30 complete statistical analysis on cloud-surface coupling and the main purpose here is  
31 to identify properties in the thermodynamic structure that generally characterize the  
32 state of cloud-surface coupling and assess which factors drive these interactions. The  
33 connection between (de)coupling and precipitation structure is also investigated.

1 Moreover, while in Shupe et al. (2013) only clouds that generate turbulence are  
2 examined, here we also identify clouds where the in-cloud mixing is inhibited; an  
3 attempt to explain why the generation of cloud-driven motions is prevented in these  
4 cases is also provided.

5       Apart from considering a different approach of the surface-cloud coupling  
6 issue, the two studies also differ in method. Shupe et al (2013) used profiles of  
7 turbulence dissipation rate, derived from Doppler radar velocities, to determine the  
8 coupling state and the depth of the cloud-driven mixed layer below cloud base. Here  
9 we instead use vertical profiles of equivalent potential temperature,  $\Theta_E = \Theta (1 + L$   
10  $Q_v / C_p T)$ , a conserved quantity during moist adiabatic processes, to identify stability  
11 and stability changes within the cloud and sub-cloud layers. While deriving profiles  
12 of turbulence dissipation rate from the cloud radar requires more ideal conditions  
13 (e.g. active mixing) than observing the thermal structure of the lowest troposphere,  
14 our method allows us to examine profiles from all periods (Tjernström et al., 2012,  
15 2013) of ASCOS, from the whole ice drift as well as the transit periods (to/from the  
16 ice-drift). This allowed us to include substantially more data in our analysis with a  
17 larger variety of meteorological conditions, compared to only the week-long period  
18 characterized by relatively steady conditions and free-atmosphere subsidence.  
19 Moreover, the dissipation rate method does not allow examination of decoupling  
20 below 150 m (near the first radar vertical range gate), whereas profiles of  $\Theta_E$  can  
21 indicate decoupling much closer to the surface.

22       The present study is organized as follows; Section 2 includes a brief  
23 description of ASCOS, the atmospheric conditions and the instrumentation deployed;  
24 included here is also a discussion on the analysis methods. Section 3 describes the  
25 results of this study, first examining the characteristics of surface turbulence and  
26 cloud properties and then examining how the boundary layer responds to these  
27 interactions - or the lack of. A discussion and the conclusions are given in Section 4  
28 and 5, respectively.

## 1 **2. Data and methods**

### 2 **2.1 ASCOS**

3 ASCOS operated under the fourth International Polar Year (IPY 2007-2009) and was  
4 an intensive field experiment observing many aspects of the atmosphere, sea ice and  
5 the upper ocean for 40 days through August and late September 2008, in the North  
6 Atlantic sector of the central Arctic Ocean (~87.2 N). Tjernström et al. (2014)  
7 provides a detailed description of this endeavor, as well as of the instruments and  
8 measurement strategies that were deployed. ASCOS was conducted on the Swedish  
9 ice-breaker *Oden*, which left Longyearbyen on Svalbard on 2 August (Day of Year;  
10 DoY 215) and returned on 9 September (DoY 253). Between 12 August (DoY 225)  
11 and 2 September (DoY 246), *Oden* was moored to and drifted with a 3x6 km ice-  
12 floe, where an ice camp was established. The drift track was approximately from  
13 87°21'N and 01°29'W to 87°09'N and 11°01'W; this period will be referred to as  
14 the “ice drift”. Note that the term “ice drift” is used here for the period when the  
15 icebreaker was moored to and drifted with the ice; however, the whole dataset used  
16 in this study, including the transitions, comes from within the ice pack. Ice cover  
17 conditions were fairly similar throughout ASCOS, although the surface melt ended  
18 and the freeze up started towards the end (Sedlar et al., 2011; Sirevaag et al., 2011)

19 Detailed observations of Arctic clouds are sparse, limited in time and space to  
20 a small number of intensive observational campaigns, including SHEBA (Uttal et al.,  
21 2002) and AOE-2001 (Leck et al., 2004; Tjernström et al., 2004) or the pan-Arctic  
22 observatories discussed in Shupe et al. (2011). One aim of ASCOS was to study the  
23 formation and life-cycle of low-level clouds, with a focus to better understand their  
24 impact on the surface energy budget, especially during the fall transition towards  
25 sea-ice freeze up. ASCOS included arguably the most comprehensive suite of  
26 instruments for observing surface, atmospheric and cloud processes over a remote  
27 sea-ice environment (Tjernström et al., 2014).

28 Large-scale atmospheric conditions during ASCOS are documented in  
29 Tjernström et al. (2012) while detailed descriptions of the meteorological conditions  
30 encountered during ASCOS ice drift are provided by Sedlar et al. (2011) and  
31 Tjernström et al. (2012; 2013); hence only a brief recap will be provided here. Sedlar  
32 et al. (2011) analyzed the surface energy budget during the ice drift and defined four

1 periods with different energy budgets and cloud characteristics. Tjernström et al.  
2 (2012) included surface temperature variability and vertical structure of the lower  
3 troposphere and subsequently divided the first period into two sub-periods, defining  
4 five periods in total. These are the periods adopted here and Fig. 1 illustrates these 5  
5 ice drift periods overlaid on the reflectivity from the vertically pointing cloud radar.  
6 DoYs prior to 226 and after 246 are during the transit towards and away from the ice  
7 drift, respectively.

8         The first (DoY 226-230) and second (DoY 230-234) periods during the ice  
9 drift had the largest positive surface energy residuals, indicating melt was still  
10 ongoing (Sedlar et al., 2011). Surface temperatures were primarily close to the  
11 melting point of fresh water during these periods. Both periods were affected by  
12 synoptic weather systems and deep frontal cloud structures, but the first was  
13 synoptically more active and significantly more variable in temperature than the  
14 second (Fig. 1). This period of synoptic activity ended on the evening of DoY 233.  
15 During the third period (DoY 234-236) a sharp drop in temperature was observed,  
16 down to -6 °C. Quiescent conditions prevailed during these two days and an  
17 intermittent, and occasionally tenuous, low-level stratiform cloud or fog layer  
18 emerged below an upper level, optically thin cirrus layer (Sedlar et al., 2011).

19         On DoY 236, a frontal system produced heavy snow fall during much of the  
20 evening. After that, the following 4<sup>th</sup> period (DoY 236-244) was characterized by  
21 high pressure and large-scale subsidence in the free troposphere, with only weak  
22 frontal passages. Single and multi-layered stratiform clouds below 2 km were  
23 persistent for nearly the entire week (Sedlar et al., 2011), topped by thin liquid cloud  
24 layers with ice crystals growing within, and falling from, these layers. The surface  
25 temperature was somewhat higher, close to the freezing point of ocean water, but  
26 still below fresh-water melting. Sedlar et al. (2011) concluded that this period was  
27 vital to the transition of the surface towards the seasonal freeze up. These relatively  
28 steady conditions continued during the 5<sup>th</sup> period (DoY 244-246), when an area with  
29 partly clear skies and optically thin clouds advected over the ASCOS site, allowing  
30 surface temperatures to plummet below -12 °C and the autumn freeze up to initiate  
31 (Sedlar et al., 2011). Finally, during both transit periods, before and after the ice  
32 drift, numerous synoptic weather systems were encountered; see Tjernström et al.  
33 (2012) for detailed profiles of radar reflectivity and subjective analysis of frontal



1 profiles during each of these periods.

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## 3 **2.2 Instrumentation**

4 A detailed description of all ASCOS instrumentation is provided by Tjernström et al.  
5 (2014). Here, only basic information about the instruments used in this study is  
6 given, while further details can be found in the cited references.

7 Information on the vertical atmospheric structure is derived from radiosondes  
8 and a 60-GHz scanning radiometer. Radiosoundings were released approximately  
9 every 6 hours. Although the limited temporal resolution is a major disadvantage,  
10 radiosondes provide accurate temperature, moisture and wind measurements. The  
11 scanning radiometer (Westwater et al., 1999) provides temperature profiles up to  
12 1200 m with a vertical resolution of around 7 m near the surface, gradually  
13 deteriorating with altitude to about 200 m at 1 km. A 5-min averaging window was  
14 applied to the 1-Hz raw data to improve the signal-to-noise ratio. The scanning  
15 radiometer has been shown to provide accurate measurements, with a low root mean  
16 square error relative to independent radiosondes up to 800 m (P.O.G. Persson,  
17 personal communication, 2013); above this height, the scanning radiometer  
18 temperatures gradually revert to the linear interpolation between the radiosonde  
19 profiles used as the a priori assumption in the retrieval process. Nevertheless, due to  
20 its high temporal resolution, and the fact that many of the cloud and sub-cloud layers  
21 are below 800 m, these profiles provide a valuable coherent data set of temperature  
22 profiles.

23 Cloud boundaries and characteristics are, to a large extent, derived from a  
24 vertically-pointing 35-GHz Doppler Millimeter Cloud Radar (MMCR; Moran et al.,  
25 1998). The vertical resolution is 45 m with a lowest radar gate at 105 m and a time  
26 resolution of 10 s. The measured Doppler spectrum was processed to estimate the  
27 three Doppler radar moments: radar reflectivity (dBZ), mean Doppler velocity ( $\text{m s}^{-1}$ )  
28 and Doppler spectrum width ( $\text{m s}^{-1}$ ) in clouds and precipitation. The reflectivity,  
29 which is nominally proportional to hydrometeor size to the sixth power, is usually  
30 dominated by ice crystals since they are normally larger than liquid droplets. The fall  
31 velocity of the hydrometeors can also be used to assist in distinguishing hydrometeor  
32 phase; cloud droplets have a very small, nearly negligible, fall velocity, whereas ice

1 crystals and drizzle/rain droplets generally fall with larger velocities. As is common  
2 in radar meteorology, a positive Doppler velocity is defined downward. The Doppler  
3 spectrum width can provide indications of multiple cloud phases, i.e., particles in the  
4 same volume with different fall speeds, and/or turbulence within the radar pulse  
5 volume.

6 Under most observed conditions, the MMCR can accurately identify cloud top;  
7 however when precipitation occurs between multi-layer clouds, the MMCR may not  
8 provide information on cloud top height for lower layers. The full Doppler spectra  
9 were used to create spectrographs of vertically-resolved reflected power as a function  
10 of Doppler velocity. These proved useful for distinguishing multiple cloud layers  
11 when other sensors indicated the potential for cloud layering masked by  
12 precipitation; spectrographs are discussed in Section 2.3.

13 MMCR derived cloud boundaries are also complemented with additional  
14 remote sensors. Cloud base is derived using two laser ceilometers with a sampling  
15 interval of 15 s. In general, laser ceilometers become attenuated by large  
16 concentrations of liquid droplets; this instrument is therefore able to penetrate  
17 precipitating layers of ice crystals and drizzle droplets and identify the vertical  
18 locations of up to 3 cloud bases, provided the lower cloud layers are not too optically  
19 thick. Once the return signal is attenuated, it is not possible to detect additional cloud  
20 layers aloft. A comparison of the two time series revealed relatively good agreement  
21 between the two ceilometers.

22 A dual-channel microwave radiometer provides vertically-integrated liquid  
23 water path (LWP) retrievals with an uncertainty of  $25 \text{ g m}^{-2}$  (Westwater et al., 2001);  
24 ice water path (IWP) is estimated using a multi-sensor cloud phase classification and  
25 MMCR reflectivity power-law relationship (Shupe et al., 2005). Cloud condensation  
26 nuclei (CCN) concentration was measured by an *in situ* CCN counter (Roberts and  
27 Nenes, 2005), set at a constant supersaturation of 0.2%, based on typical values used  
28 in other similar expeditions (Bigg and Leck, 2001; Leck et al., 2002). These CCN  
29 measurements were made on the ship via an inlet at 25 m above the surface.

30 Finally, turbulent fluxes are derived using two techniques. Eddy covariance  
31 measurements are available from the ice drift (12 August – 1 September) at heights  
32 between the surface and 30 meters from sensors deployed on masts on the ice. The

1 uncertainty of individual turbulent flux estimates is not easy to determine but is  
2 generally considered to be around 10% (Andreas et al., 2005). Diffusional and rime  
3 icing on the turbulent flux instrumentation poses a more critical problem, and leads to  
4 time periods when turbulent fluxes could not be estimated. To maximize the use of  
5 this data, a single consensus time series was created from all available data, regardless  
6 of height, assuming it was all sampled within the so-called "constant-flux layer"; tests  
7 indicate that this is a reasonable approximation.

8         So-called "bulk turbulent fluxes", based on mean vertical differences, are less  
9 accurate than direct measurements but data from instruments onboard the ship allow  
10 fluxes to be estimated for the whole expedition. Static stability is estimated from the  
11 Marine Atmospheric Emitted Radiance Interferometer (MAERI) instrument onboard  
12 *Oden* to fill missing data periods from the eddy correlation measurements, as well as  
13 to extend the observations of turbulent fluxes to the entire ASCOS expedition. The  
14 MAERI measured air temperature, viewing horizontally out from its position at 21 m  
15 on the port side of the ship, and the surface temperature, viewing down at the surface  
16 from the same position; since the same sensor is used for both, the temperature  
17 difference is not affected by systematic errors. These data were combined with the  
18 observed humidity, assuming a saturated surface with respect to the observed  
19 temperature, and wind speed from the ship's weather station to obtain the turbulent  
20 fluxes using the TOGA COARE bulk flux scheme, modified for Arctic sea-ice  
21 conditions (Persson et al., 2002). However, MAERI temperatures were sometimes  
22 affected by certain physical factors; when the ship was oriented so that the MAERI  
23 sensor viewed open ocean, rather than ice, it sometimes measured a higher  
24 temperature than over the adjacent ice surface, leading to an overestimation of the  
25 heat fluxes. Also, when the wind direction was from *Oden's* starboard side, across  
26 the ship, the MAERI, being located on the port side, may have observed too high air  
27 temperatures due to the heat plume from the ship; then the sensible heat flux is likely  
28 underestimated.

29

### 30 **2.3 Analysis method**

31 The first MMCR range gate in the vertical with a return power below the radar  
32 sensitivity demarcates the cloud top, while the highest observed ceilometer cloud

1 base below cloud top is considered as the base for this layer. Both ceilometers are  
2 used for consensus. Median cloud boundaries were computed from a 2-min window  
3 following each scanning radiometer measurement and a 10-min window following  
4 each radiosonde release. For the analysis of cloud bulk properties (LWP, IWP) and  
5 the radar Doppler moments, the same time windows were used to derive median  
6 values. Considering the persistence of low-level Arctic clouds (Shupe et al., 2011),  
7 the assumption that the median cloud layers are in steady state over the above  
8 applied time-windows is reasonable. Median boundaries are used, instead of the  
9 mean, in order to reduce the effect of outliers (Sedlar et al., 2011), as may  
10 occasionally occur with only slightly less than complete overcast conditions, or when  
11 a second cloud layer emerges within the time window following thermodynamic  
12 profiles.

13 Profiles of  $\Theta_E$  are used to define the cloud-driven turbulent mixed layer;  
14 depending on whether this layer extends down to the surface or not, the cloud is  
15 classified as either “coupled” or “decoupled”, respectively. If a cloud-driven mixed  
16 layer is not observed, then the cloud is classified as “stably-stratified”. Note that  
17 “stably-stratified” clouds are also not connected to the surface; here the word  
18 “decoupled” refers only to cases with a cloud-driven mixed layer. Two sets of data  
19 are used; either using the radiosoundings directly or combining the higher frequency  
20 scanning radiometer temperature profiles with interpolated specific humidity from  
21 the soundings. While the radiosonde equivalent potential temperature data is more  
22 accurate, it has temporal limitations. On the other hand, while the interpolation of  
23 specific humidity is a limitation for the scanning radiometer data, it allows using a  
24 higher temporal resolution and increases the number of profiles included in the  
25 study. The classification of vertical thermodynamic structure of the clouds based on  
26 the scanning radiometer profiles is in good agreement with the results derived from  
27 the radiosonde dataset. Therefore, the majority of the results in this study are based  
28 on the scanning radiometer, while for other information the radiosonde data is used  
29 (e.g., humidity and wind).

30 An algorithm was developed to identify the main temperature inversion in the  
31 layer extending above cloud base until 100 m above cloud top, by applying  
32 thresholds to the  $\Theta_E$  profiles. A quasi-constant  $\Theta_E$  from the inversion base down to  
33 the surface is taken to indicate coupling, whereas a decrease towards the surface

1 below the cloud indicates a local stable layer and hence decoupling. The height at  
2 which the  $\Theta_E$  has decreased by  $0.5^\circ\text{C}$ , compared to the cumulative mean value of the  
3 layer above, is considered to be the decoupling height. This threshold was selected to  
4 optimize between accuracy and reliability, given the vertical variability of the  
5 observed temperature, especially in the soundings, and the results were reasonably  
6 insensitive to small changes in the threshold. The layer between the cloud base and  
7 the decoupling height will be referred as the sub-cloud mixed layer (SCML). Both  
8 coupled and decoupled clouds will be often referred as neutrally-stratified clouds,  
9 referring to the gradient  $\Theta_E$  profile within the cloud layer. If the gradient of  $\Theta_E$  is  
10 positive through the whole cloud layer, it is classified as a stably-stratified or stable  
11 cloud. Moreover, profiles with no inversion near cloud top were reexamined by  
12 estimating the  $\Theta_E$  gradient from cloud top to cloud base. These profiles were found  
13 to have large gradients and so these cases are also considered to be stable clouds. To  
14 illustrate qualitatively the differentiation of the categories using the  $\Theta_E$  profiles,  
15 examples are given in Fig. 2 for coupled (Fig. 2a), decoupled (Fig. 2b) and stable  
16 clouds with a main inversion identified close to the cloud top (Fig. 2c) and with no  
17 main inversion identified (Fig. 2d).

18 Only profiles with a cloud top below 1500 m, a cloud base below 1200 m and a  
19 cloud thickness larger than 135 m (three radar gates) are included in the analysis. It  
20 is not possible to evaluate how these choices affect the results, since these limits are  
21 set by real limitations in the instruments that cannot be freely varied. In addition,  
22 profiles where cloud thickness is greater than 700 m are assumed to be two cloud  
23 layers with precipitation falling from the upper cloud and where the ceilometer fails  
24 to penetrate the lower cloud to detect the upper cloud base; the choice of this  
25 threshold is based on relative results by Shupe et al. (2013), who included only  
26 single cloud layers in their analysis. For some of these cases, it is possible to  
27 estimate the upper cloud base from spectrographs. Two examples are shown in Fig.  
28 3. For these cases, the cloud top detected by the MMCR is the top of the upper cloud,  
29 whereas the existence of a lower dense cloud prevents the ceilometer from  
30 measuring the corresponding upper cloud base height. In the cases in Fig. 3, the  
31 cloud top and base derived directly from the instruments is 960 m and 90 m, and  
32 1095 m and 75 m, respectively, but from the spectrographs we could infer that there  
33 are two cloud layers present and the base of the upper clouds are around 750 m and

1 700 m, respectively. These are identified as the levels where the Doppler velocities  
2 become systematically large and positive, indicating only falling hydrometeors and  
3 an absence of liquid cloud droplets, assuming that the latter are small and have  
4 negligible (near  $0 \text{ m s}^{-1}$ ) fall velocities. Hence the height where significant radar  
5 power crosses the zero velocity line is indicative of the liquid base height.

6 Using radiosonde profiles for the classification, the same cloud thickness  
7 criteria are applied, since they are due to the MMCR, but a less strict cloud top  
8 criterion is applied, including cloud returns up to 3000 m. The less strict cloud-top  
9 criterion for the radiosonde profiles allows more cases to be included and is  
10 consistent with the aim to analyze stratocumulus. It is chosen because of the shorter  
11 time-series that this instrument provides and the need to include as many profiles as  
12 possible in our analysis.

13 Applying the above criteria, 3436 out of the total available 8261 scanning  
14 radiometer profiles are considered, or 42% data coverage. For almost 40% of the  
15 available ASCOS profiles, a proper low cloud top, as defined above, was not  
16 detected by the radar due to the presence of deep precipitating weather systems (see  
17 Fig. 1), whereas around 18% fail to pass the geometrical restrictions. Hence,  
18 considering only the times when deep weather systems were not present, the  
19 algorithms described above captures roughly two thirds of the available data. As a  
20 comparison, 87 out of the 145 (~60%) radiosonde profiles pass the above criteria for  
21 similar reasons.

22 To investigate the liquid and ice water cloud properties that characterize each  
23 cloud state, single cloud-layer profiles had to be selected, since the derived LWP is a  
24 vertically-integrated quantity; the vertical distribution of the liquid is unknown, and  
25 with multiple cloud layers it becomes difficult to partition the liquid among layers.  
26 For this particular purpose, profiles where the ceilometer detected more than one  
27 cloud base or the MMCR detected more than one cloud top were rejected. Out of the  
28 3436 scanning radiometer profiles that are used for the main analysis, slightly less  
29 than half, or 1611, represent single cloud layers and are used for the analysis of cloud  
30 liquid and ice characteristics.

## 1 **3. Results**

### 2 **3.1 Cloud states**

3 Considering results based on the scanning radiometer alone, 40% of the cases are  
4 decoupled while 28% are coupled and 32% are considered stable (Fig. 4, dark blue).  
5 The corresponding results from the radiosonde profiles are 46% decoupled, 23%  
6 coupled and 31% stable. The somewhat higher (lower) fraction of decoupled  
7 (coupled) clouds for the radiosondes may be due to the inclusion of higher cloud  
8 tops; as will be shown later, higher clouds are more likely to be decoupled than  
9 lower ones. Considering the limited number of soundings available, the agreement is  
10 reasonable and supports the use of the scanning radiometer profiles for the analysis.

11 Figure 4 also shows the relative frequency distributions (RFDs) of coupled,  
12 decoupled and stable clouds for each period of ASCOS (see Section 2.1). Many deep  
13 precipitating weather systems advected overhead from the beginning of the  
14 expedition until the end of the 2<sup>nd</sup> ice drift period, and during the transition to the end  
15 of ASCOS (Fig. 1). Hence there were only short and scattered occurrences of low  
16 stratocumulus during these periods, which is why few profiles are included here.

17 From the beginning of ASCOS until the end of the 2<sup>nd</sup> period of the ice drift,  
18 stable and coupled clouds dominate when low-level stratocumulus are intermittently  
19 present; nearly 80% of the profiles satisfying the geometric cloud constraints  
20 described above during DoY 216-230 contain low clouds with tops below 500 m.  
21 The high fraction of stable clouds during this time is likely due to optically and  
22 geometrically thin clouds; this will be investigated below. In the cases where a  
23 cloud-driven mixed layer is observed, the proximity of these clouds to the surface  
24 makes it easier for the cloud-generated motions to interact with surface-generated  
25 turbulence (Shupe et al., 2013), which we speculate is the reason why decoupled  
26 cases are rare during these early periods of ASCOS.

27 During the second period of the ice drift (DoY 230-234), higher clouds with  
28 tops above 800 m in between the deeper precipitating systems are observed, which  
29 are either decoupled or stable; however the latter is still the dominant state. During  
30 the third period of the ice drift (DoY 234-236), the observed cloud states are either  
31 coupled or stable, but now with coupled being the most frequent. This period is

1 dominated either by very low clouds or fog (95% of the profiles have a cloud top  
2 below 400 m).

3 The fourth period of the ice drift (DoY 236-244) provides almost half of the  
4 profiles included in this study. This is the longest period and also the one that was  
5 examined by Shupe et al. (2013) and Sedlar and Shupe (2014) to study the cloud-  
6 surface interactions and vertical velocity characteristics during ASCOS. The  
7 persistent stratiform layer (Fig. 1) is often decoupled but intermittently connects  
8 thermodynamically with the surface. Stable clouds are observed in only ~10% of  
9 these profiles. Taking only the neutrally-stratified profiles into account, 74% are  
10 found to be decoupled and 26% coupled; this is in very good agreement with the  
11 occurrence statistics found in Shupe et al. (2013) and Sedlar and Shupe (2014).

12 During the fifth period (DoY 244-246), neutrally-stratified clouds still  
13 dominate, although a considerable portion (~ 35%) of stable cases are also observed.  
14 At the beginning of this period the stratiform cloud conditions from the previous  
15 period persist, but are gradually decreasing in depth and height, becoming tenuous,  
16 and at some points even dissipating (Fig. 1). Finally, from the transit period away  
17 from the ice drift, few profiles are included because of the occurrence of several deep  
18 precipitating weather systems. Most profiles are derived from DoY 246-248, when a  
19 low stratiform cloud layer is observed, and from a few hours during DoY 249 and  
20 251, when a very low tenuous cloud is apparent in the MMCR reflectivity (Fig. 1).

21 To summarize, the RFD of coupled, decoupled and stable cloud profiles  
22 derived either from the scanning radiometer (Fig. 4) or the radiosonde (not shown)  
23 reveals that neutrally-stratified clouds (coupled plus decoupled) are more frequent  
24 during ASCOS than stable clouds. Yet, in the majority of the neutral cloud cases the  
25 cloud-generated turbulence does not mix with the boundary layer below down to the  
26 surface and the cloud remains decoupled. This is generally in agreement with Sedlar  
27 and Shupe (2014) and Shupe et al. (2013), although the latter suggest an even higher  
28 fraction of the neutrally stratified clouds to be decoupled; as shown above, this  
29 difference is due to the different samples' size, while the use of different method  
30 does not seem to affect the occurrence statistics.

31 The RFDs for cloud boundaries and cloud thickness are shown in Fig. 5. The  
32 distribution of cloud top (Fig. 5a) indicates that clouds with tops above ~900 m are



1 usually decoupled while those with tops below  $\sim 500$  m are coupled or stable. The  
2 frequency distribution for cloud base (Fig. 5b) shows that coupled and stable clouds  
3 have a cloud base below  $\sim 200$  m during more than 50% of their occurrences,  
4 whereas the decoupled cloud base distribution peak is much broader, between 400  
5 and 800 m. In addition, the RFD for cloud thickness (Fig. 5c) indicates that stable  
6 clouds are geometrically thinner than neutrally-stratified clouds, whereas decoupled  
7 clouds are in general no thicker than the coupled clouds.

8 In summary, this analysis shows that stable clouds are geometrically thin and  
9 low, while neutrally-stratified clouds are thicker with a tendency to have bases  
10 higher above the surface. However, decoupled clouds appear higher up in the  
11 atmosphere than coupled clouds; these results provide hints at the mechanism  
12 explaining the different cloud classes. While turbulence is practically always  
13 generated at the surface by mechanical mixing, unless very weak winds prevail,  
14 strong radiative cooling at cloud top normally gives rise to buoyancy-generated  
15 turbulence inside the cloud layer. In cases when the cloud layer is sufficiently close  
16 to the surface, the two layers may interact, leading to a continuously coupled state.  
17 On the other hand, when cloud layers are displaced higher, with cloud tops above  
18 900 m, the in-cloud turbulence generated at the cloud top usually does not penetrate  
19 to the surface-based mixed layer and thus becomes independent of the surface  
20 conditions; the cloud state is decoupled. An exception to this description is a number  
21 of low clouds that are not mixed at all (stable cloud states); these are about half of  
22 the lowest and thinnest clouds, with cloud bases  $< \sim 200$  m and thicknesses  $< \sim 300$   
23 m. This indicates that these thin clouds do not cool sufficiently to space at the top,  
24 probably because they are either too optically thin or the liquid water content is  
25 distributed rather homogeneously across the cloud layer, but also that the surface  
26 generated turbulence is often too weak to mix clouds even when they lie below a few  
27 hundred meters.

28 The relationship between cloud boundaries and the depth of the SCML is  
29 further explored; it is found that the depth of the SCML increases as cloud base and  
30 top heights increase (not shown). Yet, SCML depths are almost indifferent to cloud  
31 thickness and increase only slightly with increasing cloud thickness; however, it must  
32 be recalled that the range of thickness is similar for nearly all low-level cloud mixing

1 states (see Fig. 5c). The above general relationships were also observed by Shupe et  
2 al. (2013), although for a shorter period, hence the results are not shown here.

3

### 4 **3.2 Surface fluxes**

5 The results in the previous section indicate that cloud-induced turbulence determines  
6 coupling state, however, intuitively it would be reasonable to expect larger surface  
7 fluxes to facilitate coupling to the surface. To examine the influence of the turbulent  
8 surfaces fluxes on the cloud coupling state, RFDs of momentum, sensible and latent  
9 heat fluxes for the three cloud coupling states are shown in Fig. 6. Upward fluxes are  
10 positive; momentum flux is represented by the friction velocity which is always  
11 positive. Turbulent heat fluxes are generally very small while the momentum fluxes  
12 can be substantial (Tjernström et al. 2012). A comparison of the two time series  
13 during times when they overlap (not shown) revealed relatively good agreement for  
14 the momentum and sensible heat fluxes, whereas the latent heat fluxes exhibited  
15 larger differences; see Section 2.2 for a discussion.

16 RFDs for momentum flux (Fig. 6a) show no significant difference among the  
17 three cloud states, although the decoupled state has a broader peak over slightly  
18 higher values. This is contrary to expectations; a larger momentum flux means more  
19 mechanical mixing and, if it was important for the cloud state, less likely to be present  
20 in a decoupled state. These distributions indicate that mechanical mixing is indeed not  
21 a leading factor that determines coupling state. The same conclusion holds for the  
22 sensible (Fig 6b) and latent (Fig 6c) heat fluxes, suggesting that surface turbulence is  
23 not responsible for cloud-surface coupling states and that these interactions are thus  
24 mainly driven by the cloud. This is in agreement with the results from Shupe et al.  
25 (2013).

26

### 27 **3.3 Cloud water properties**

28 Cloud water properties are analyzed from single cloud-layer cases only; see Section  
29 2.3. Of these 52% were decoupled, 31% coupled and 17% were stable. The lower  
30 fraction of stable cases suggests that these are often present during occasions of  
31 multiple cloud layers. However, the ratio between the two mixing states compares  
32 favorably to the results from the whole period and those from only soundings.

1           The results in Fig. 7a are shown as box-and-whisker plots, and in Fig. 7b as  
2 histograms. Negative (unphysical) LWP values included in the statistics are due to  
3 the LWP uncertainty of  $\sim 25 \text{ g m}^{-2}$  from the MWR instrument (see Section 2.2).  
4 Figure 7a reveals that the stably-stratified cloud state is statistically different from  
5 neutrally-stratified cloud states, since the LWP median ( $\sim 32 \text{ g m}^{-2}$ ) is  $\sim 50\%$  smaller  
6 than the corresponding values for the latter states ( $64 - 65 \text{ g m}^{-2}$ ); a student t-test  
7 confirmed the significance of this difference at the 95% confidence level. Hence, the  
8 initial hypothesis about the origin of the stable cases is supported; a cloud emits  
9 radiation as a blackbody when LWP is larger than  $\sim 30 - 50 \text{ g m}^{-2}$  (Stephens, 1978).  
10 Cloud LWPs for the stable state are often at or below this blackbody emissivity  
11 range, and it is likely that cloud-top radiative cooling, and hence buoyant mixing, is  
12 reduced. The two neutrally-stratified cloud states exhibit no statistical difference,  
13 suggesting that LWP by itself does not determine coupling state.

14           Histograms of LWP for the three cloud types (Fig. 7b) also indicate that the  
15 stable cloud states in most cases are optically thin; 72% of the stable cloud profiles  
16 have LWP observations below  $50 \text{ g m}^{-2}$ . Note, however, that even for the clouds that  
17 contain enough liquid to be “blackbodies”, the buoyancy-generation of turbulence  
18 depends on the differential cooling in the vertical. Thus, if liquid is homogeneously  
19 distributed across the cloud then, instead of generating turbulence and mixing, the  
20 whole cloud layer will cool. The RFDs for both neutrally-stratified states have peaks  
21 between  $50 - 80 \text{ g m}^{-2}$ ; decoupled clouds have the RFD peak shifted slightly to  
22 higher values compared to the coupled clouds.

23           This result is contrary to that in Shupe et al. (2013), who found that coupled  
24 clouds tend to have more LWP than decoupled; the reason may be the larger sample  
25 in the present study. To investigate how the choice of a certain period of data affects  
26 the statistical results, we calculated the LWP statistics for the 4<sup>th</sup> period of ASCOS  
27 ice drift separately, the same period analyzed by Shupe et al. (2013), and compared  
28 to the remaining periods. Considering only this period, the median LWP for coupled  
29 clouds is  $\sim 77 \text{ g m}^{-2}$  and its 25<sup>th</sup> percentile is  $\sim 58 \text{ g m}^{-2}$ , while for the remaining  
30 periods it is  $\sim 58$  and  $\sim 43 \text{ g m}^{-2}$ , respectively (not shown). This shows that coupled  
31 cases during a persistent and relatively thick stratocumulus deck (Fig. 1) analyzed in  
32 Shupe et al. (2013) contained relatively more liquid than during the other periods,

1 indicating the difference may lie in the differing time samples. This illustrates the  
2 importance of having long time series for this type of analysis.

3 The results for the IWP (Fig. 8) also show that stable clouds differ from the  
4 other two cloud types; stable cloud states have an IWP median around  $\sim 0.5 \text{ g m}^{-2}$ ,  
5 which is 4–6 times smaller than that for the neutrally-stratified cloud states, and  
6 frequently has zero IWP. The medians for the coupled and decoupled states are  
7 around  $\sim 3.2$  and  $\sim 2.7 \text{ g m}^{-2}$ , respectively. The fact that stable cases have an IWP  
8 close to zero indicates that these clouds are often not mixed-phase. Furthermore,  
9 some of these stable clouds are probably cases of fog, consistent with their lower  
10 cloud boundary statistics (see above).

11

### 12 **3.4 CCN concentrations**

13 Cloud formation depends on the presence of CCN; moreover, the concentration of  
14 CCN strongly affects the optical properties of clouds and may impact on the cloud-  
15 induced turbulence. Figure 9 illustrates near-surface CCN concentrations observed  
16 during coupled, decoupled and stable states. The available CCN data corresponds to  
17 the period between DoY 228-252, while during that time there are several short  
18 periods where no data are available at all (e.g., due to pollution contamination by  
19 ship exhaust; see Martin et al., (2011)). As a result, it is possible to match a CCN  
20 concentration to a cloud state for only 25% of the total scanning radiometer profiles.  
21 Also note that CCN is observed near the surface and that the observations may not  
22 necessarily be representative for conditions in the cloud layer.

23 The median CCN concentration (Fig. 9) for stably-stratified clouds is  $\sim 21 \text{ cm}^{-3}$   
24 <sup>3</sup>, whereas for neutrally-stratified cases the medians are twice as large,  $\sim 43 - 44 \text{ cm}^{-3}$   
25 <sup>3</sup>. The low CCN concentrations explain the limited liquid amounts present in stable  
26 clouds, thus providing additional support to the hypothesis that stable clouds are  
27 optically thin; also see Mauritsen et al. (2011) that analyzed the effects of CCN  
28 concentration on the optical properties of Arctic low-level clouds.

### 1 3.5 Vertical structure

2 To investigate the structure and phase of the clouds, RFDs of radar reflectivity as a  
3 function of height are shown in Fig. 10. These results are shown on a scaled vertical  
4 axis, which, by necessity, are slightly different for the three different cloud states;  
5 each layer is scaled independently. For coupled clouds,  $z_n=-1$  represents the  
6 MMCR's first range gate,  $z_n=0$  is the cloud base and  $z_n=1$  the inversion base. Stable  
7 cases are normalized in similar manner, except that  $z_n=1$  is at the cloud top, since a  
8 temperature inversion associated with the cloud top is not always present; note that  
9 reflectivities above the cloud top are present in Fig. 12c, as a stricter definition on  
10 radar reflectivity was used here to identify cloud boundaries, while the full  
11 reflectivity profile was used for the statistics. Decoupled clouds have three layers;  
12 the first range gate is at  $z_n=-2$  while  $z_n=-1$  is the decoupling height,  $z_n=0$  the cloud  
13 base and  $z_n=1$  the inversion base. Heights above  $z_n=1$  (the free troposphere) are also  
14 scaled by the thickness of the layer below, since there is no other obvious scaling.

15 For coupled clouds (Fig. 10a) the range of reflectivity values extends from -40  
16 dBZ to -5 dBZ, with a maximum frequency around -20 dBZ, throughout the whole  
17 cloud, and almost the whole sub-cloud layer although the spread is larger here. A  
18 rapid decrease is only observed close to the surface, where evaporation or  
19 sublimation of precipitation takes place. Above the inversion base, the maximum  
20 RFD remains constant to about  $z_n \approx 1.3$ , suggesting that the top of these clouds  
21 usually extend into the inversion layer (cf. e.g., Sedlar and Tjernström, 2009; Sedlar  
22 et al., 2012).

23 Decoupled clouds (Fig. 10b) have a similar structure to the coupled cases  
24 inside the cloud, but exhibit a larger spread in reflectivity below cloud base. The  
25 reflectivities of the layer between inversion base and cloud base extend from -40 dB  
26 Z to -5 dB Z, whereas the values of the sub-cloud layer show an even larger spread  
27 especially towards the smaller values (down to -65 dBZ). The RFD of the depth of  
28 the SCML (not shown) revealed that it often varies between 200-600 m; thus, larger  
29 variability in the sub-cloud layer reflectivity (Fig. 10b) may be due to different  
30 features or characteristics of the decoupled cloud and/or sub-cloud layers depending  
31 upon SCML depth.

1           The stable cases (Fig. 10c) are generally characterized by lower reflectivity  
2 compared to the coupled cases. In the lower half of the cloud, reflectivity extends  
3 between -50 dBZ and -15 dBZ, with a maximum frequency around -40 to -30 dBZ.  
4 Below cloud base, the decrease in magnitude with decreasing height is more  
5 pronounced than for coupled cases; the reflectivity is reduced by ~10 dBZ already at  
6  $z_n \approx -0.3$ , although the width of the distribution increases, explaining the more  
7 gradual change in the median. In the upper half of the cloud, reflectivity decreases  
8 rapidly with height. The in-cloud reflectivity values are often well below -17 dBZ, a  
9 general upper limit of cloud droplet-only returns (Frisch et al. 1995), supporting the  
10 hypothesis that stable clouds are not associated with appreciable precipitation.

11           In an attempt to investigate how the depth of the decoupled sub-cloud layer  
12 correlates with the vertical structure of precipitation, we use the relationships  
13 between the three radar moments at the decoupling height and the depth of the  
14 SCML (Fig. 11). Figure 11a shows that reflectivity at the decoupling height  
15 decreases gradually as the mixed layer deepens. For depths greater than 500 m, a  
16 distinct peak in the RFD is apparent at very small reflectivities ( $< -50$  dBZ).  
17 Likewise, the RFD of Doppler spectrum width (Fig. 11c) also shows a decrease in  
18 Doppler velocity variance for SCML depths  $> \sim 300$  m. However, the Doppler  
19 velocity distribution (Fig. 11b) at the decoupling height shows a slight tendency to  
20 increase for SCML  $> \sim 400$  m. This result appears to be inconsistent with the other  
21 two radar moment distributions with SCML depth, as decreasing reflectivity and  
22 reduced spectrum width tend to suggest a more homogeneous hydrometeor  
23 distribution of generally smaller sizes. One possible explanation is that decreasing  
24 reflectivity and spectrum width are affected by decreasing concentration of  
25 precipitation, e.g. caused by sublimation of precipitation occurring in the deeper  
26 SCMLs, but it is very difficult to deconvolve from the strong effect of size.  
27 Nevertheless, all radar moments show a bimodality in RFD for the primary SCML  
28 depths observed. To get a clearer distinction of the conditions that drive the  
29 decoupling at different depths, we separate the decoupled clouds in two sub-  
30 categories: those with a SCML depth less than 450 m and those with a SCML deeper  
31 than 500 m; 60% and 30% of the total decoupled profiles respectively; clouds with a  
32 shallower SCML hence occur twice as often as clouds with a deeper SCML.  
33 Considering that increasing cloud boundaries correspond to increasing SCML depths

1 (section 3.1), the first category includes low decoupled clouds, whereas the latter  
2 includes some of the highest clouds observed.

3 In Fig. 12, the reflectivity for decoupled clouds is shown again, but now  
4 divided into the two categories. The decoupled clouds with the shallower SCML  
5 (Fig. 12a) have a very similar structure to the coupled clouds (Fig. 12a). On the other  
6 hand, decoupled clouds with a deeper mixed layer (Fig. 12b) differ substantially  
7 from all the other cases: the maximum occurrence frequency close to the inversion  
8 base is around -20 dBZ, same as for the coupled and decoupled clouds with shallow  
9 SCML, but near cloud base it decreases to -30 dBZ. This is the only case where a  
10 decrease inside the cloud layer is observed, suggesting that these clouds have little  
11 ice, such that the reflectivity profile within the cloud is actually dominated by the  
12 liquid. Furthermore, in the sub-cloud layer, reflectivity distribution is bimodal (Fig.  
13 12b). In some cases it remains constant through cloud and upper sub-cloud layers,  
14 very similar to coupled and decoupled cases with a shallower SCML; this branch in  
15 the RFD however decreases and vanishes closer to the surface. The lack of values  
16 below the decoupling height suggests that these profiles get decoupled around 100  
17 m, the lowest vertical range gate of the MMCR. For the other mode, there is also a  
18 decrease with decreasing height, from values  $< -40$  dBZ below cloud base until the  
19 decoupling height where the reflectivity minimum is reached, approaching -60 dBZ.  
20 This illustrates the large potential impact on hydrometeors by  
21 evaporation/sublimation, when precipitation falls through a relatively deep sub-  
22 saturated layer below the cloud base.

23 Next the thermodynamic structures of the different (now four) cloud states are  
24 analyzed. We did not find any relationship between cloud states and either cloud top,  
25 cloud base or surface temperatures (not shown), so only the gradients of potential  
26 temperature profiles are shown in Fig 13. Note, these are gradients of  $\Theta$  profiles and  
27 not  $\Theta_E$ , on which the separation of coupled, decoupled and stable state was based.  
28 Through the definition of  $\Theta_E$ , an increase in  $\Theta$  across a layer could be compensated  
29 by a decrease in  $Q_v$  leading to a constant  $\Theta_E$ ; hence, a thermodynamically coupled  
30 case as defined using  $\Theta_E$  could appear decoupled when using the  $\Theta$  profile. Fig. 13,  
31 showing the statistics of the  $\Theta$  gradient profiles with respect to normalized height  
32 (same as for radar reflectivity), reveals that this does not occur here.

1           In the coupled cases (Fig. 13a), the  $\Theta$  gradient is slightly larger than zero in the  
2 cloud, consistent with the release of latent heat in the cloud interior, and remains  
3 almost constantly near-zero in the sub-cloud layer until the surface, where it  
4 increases only slightly. In both the decoupled classes, two separate layers below the  
5 cloud base are apparent. For the shallow SCML (Fig. 13b) category, the  $\Theta$  gradient  
6 is near-zero from inversion base until the decoupling height, followed by a weak  
7 second inversion around the decoupling height and slightly stronger stability below.  
8 Near the surface, the  $\Theta$  gradient is near-zero or even slightly negative, suggesting the  
9 existence of a turbulent surface layer.

10           For the decoupled state with a deeper SCML, however, the secondary  
11 inversion is substantially more pronounced (Fig. 13c). Here the layer above the  
12 decoupling height is also substantially less stable compared to the layer below. This  
13 difference in thermal structure explains the separation between decoupled cloud  
14 states with shallower or deeper SCML; it is actually a separation between states that  
15 are “weakly” or “strongly” decoupled. Thus from here and onwards we will  
16 examine four cloud states, using “weakly” and “strongly” decoupled, rather than  
17 “shallow” or “deep”. In most stable cases (Fig. 13d), the near-surface structure is  
18 somewhat more neutrally-stratified than aloft. The stratification is stable throughout  
19 the profile and these clouds are hence also disconnected from the surface.

20           Figures 14 and 15 show normalized profile RFDs of mean Doppler velocity  
21 and spectrum width. The median velocity profile for coupled clouds (Fig. 14a)  
22 increases from the inversion base to close to the surface. In the cloud layer this  
23 behavior is expected as hydrometeor sizes increase through collisions and diffusional  
24 growth in the cloud interior, leading to larger hydrometeors with larger fall speeds.  
25 In the sub-cloud layer, further increases in mean Doppler velocity indicate a  
26 continued growth of the precipitation particles until approaching the surface. For the  
27 weakly decoupled state (Fig. 14b) this increase stops near the decoupling height and  
28 the Doppler velocity becomes constant below that level. For the strongly decoupled  
29 clouds (Fig. 14c) the Doppler velocity increases abruptly slightly below the cloud  
30 base and then becomes quasi-steady through the entire sub-cloud layer, including  
31 above and below the decoupling height. The RFD maximum frequencies for these  
32 cases are distributed around  $0 \text{ m s}^{-1}$  in the upper part of the cloud layer, suggesting  
33 that the returns in this area are from the cloud liquid droplets. Moving downward in



1 the liquid layer the slowly increasing downward velocity is due to the fact that ice  
2 starts to become relatively more abundant and more important for the total  
3 backscatter. The quasi-constant Doppler velocity below the decoupling height is a  
4 similar feature for both decoupled states; the ceased acceleration of hydrometeors at  
5 the decoupling height could be connected with evaporation/sublimation occurring  
6 locally. The stable cloud states (Fig. 14d) exhibit a totally different vertical structure  
7 where Doppler velocity is distributed around zero throughout both cloud and sub-  
8 cloud layer. The median profile is close to zero suggesting no, or very small, mean  
9 vertical motions occur, in the cloud as well as the sub-cloud layer; this means that  
10 clouds in the stable state have negligible precipitation.

11 The Doppler spectrum width (Fig. 15) is generally increasing from inversion  
12 base down to cloud base for all cloud states, except for stable clouds (Fig 15d),  
13 suggesting that with decreasing height, the variability in hydrometeor size also  
14 increases within the cloud layer. Below cloud base, spectrum width decreases  
15 downwards; this decrease is sharper for decoupled clouds and especially those that are  
16 strongly decoupled (Fig. 15c). The rather quick decrease in spectrum width below the  
17 cloud base in the latter cases is probably due to the fact that there is less ice  
18 precipitation in these clouds and/or the deeper SCML allows for increased  
19 sublimation of the smallest ice crystals, leading to a narrower Doppler spectrum.

20 Again, stable clouds (Fig. 15d) exhibit a completely different behavior than the  
21 other cases. The larger spectrum width frequencies are distributed around 0.2 m/s  
22 with an increasing spread towards higher values with decreasing height. These  
23 substantially smaller values in the cloud layer, compared to the neutrally-stratified  
24 clouds, are an additional indication that stable clouds are often not mixed-phase and  
25 do not drive much turbulent mixing, while the slightly higher spread combined with  
26 near zero average velocities indicates that the lower part of the sub-cloud layer is  
27 slightly more turbulent than the cloud layer.

28 Profiles of relative humidity (with respect to ice,  $RH_i$ ), specific moisture ( $Q_v$ )  
29 and wind speed ( $U$ ) (Figs. 16, 17 and 18) are analyzed from radiosoundings. Both  $Q_v$   
30 and  $U$  exhibited a significant scatter in absolute values, reflecting changes in air  
31 mass, so a scaling method was applied: the scaled variables ( $U''$ ,  $Q_v''$ ) are defined by  
32 subtracting the mean values in the layer between the surface and inversion base (or  
33 the cloud top for stable cases) from the actual values.  $RH_i$  is in a sense already a

1 scaled variable by definition and does not require any normalization. The RFDs of  
2 the two scaled variables and  $RH_i$  are normalized with respect to height as previously.

3 The maximum frequency of  $RH_i$  is at or often above saturation in the cloud  
4 interior for all states (Fig. 16). This indicates that these clouds can support the  
5 coexistence of ice and liquid hydrometeors within the same volume, considering  
6 layer mean temperatures are often below freezing. In the coupled and stable states  
7 (Fig. 16 a, d)  $RH_i$  decreases below cloud base until the surface where it is sub-  
8 saturated. This decrease is also observed in the decoupled cases (Fig. 16 b, c) but  
9 only down to the decoupling height; below that level it either remains roughly  
10 constant (Fig. 16b) or increases again (Fig. 16c). The decrease in  $RH_i$  below the  
11 cloud base is the largest in the strongly decoupled cases (Fig. 16c) and a clear  
12 minimum is observed around the decoupling height, below 85%. The generally  
13 decreasing  $RH_i$  profile with decreasing height below cloud agrees with decreasing  
14 profiles of Doppler spectrum widths and reflectivities, indicating sublimation of  
15 falling ice crystals in the sub-cloud layer appears to be an ongoing process for the  
16 majority of the strongly decoupled cloud states.

17 Specific humidity (Fig. 17) is similar in all states, except for the stable cases  
18 (Fig. 17d), increasing with decreasing height from the inversion base until close to  
19 the surface. For decoupled states, the structure below the decoupling height is  
20 slightly different; specific humidity here is often quasi-constant, especially in the  
21 strongly decoupled state where this layer is substantially moister in water vapor than  
22 aloft (Fig. 17c); this moist environment could favor the formation of a lower  
23 secondary cloud layer. Both coupled and decoupled cloud states (Fig. 17 a-c) show  
24 that moisture increases above the temperature inversion near cloud top (e.g., Sedlar  
25 and Tjernström 2009; Sedlar et al. 2012), indicating a potential source of moisture  
26 for these cloud layers, by entrainment. While all neutrally-stratified cases have the  
27 common feature of a general decrease in specific humidity with increasing height,  
28 the stable clouds (Fig. 17d) feature the exact opposite behavior; a general increase  
29 from near the surface to the cloud top. Only the layer close to the surface often  
30 appears slightly more moist; however, the sub-cloud layer is still less moist than the  
31 cloud layer and the air immediately above the cloud.

32 RFDs of wind speed profiles are given in Fig. 18. Wind speed is a highly  
33 variable component of the system; hence the RFDs appear more scattered. The

1 median of coupled (Fig. 18a) and weakly decoupled clouds (Fig. 18b) are quite  
2 similar, with almost constant wind speed inside the cloud and an increase from the  
3 surface to the cloud base; for the coupled state, there is a very weak indication of a  
4 maximum at the cloud base, agreeing with vertical wind speed shear during coupled  
5 surface and cloud cases analyzed by Sedlar and Shupe (2014). In contrast, for the  
6 strongly decoupled state (Fig. 18c), the median increases below cloud base and  
7 reaches a maximum close to the decoupling height, and then decreases towards the  
8 surface. Although this structure consists of many uniquely varying profiles, it  
9 indicates the presence of low-level jets (LLJ) in some of them; the existence of these  
10 LLJs might explain the slightly higher momentum fluxes observed earlier in the  
11 decoupled cases (Fig. 6). The fact that the LLJ core occurs close to the decoupling  
12 height, where an inversion usually exists (see Fig. 13c), has been also observed in  
13 previous studies of nocturnal LLJs (Andreas et al., 2000; Jakobson et al., 2013).  
14 Finally, for the stable cloud state (Fig. 18d), median wind speed is similar to the  
15 coupled state, only the wind speed starts to decrease already from the cloud interior.  
16 However, the bimodal structure of the RFD in the sub-cloud layer indicates the  
17 potential presence of LLJs also here, with an occurrence of about half the time.

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19

#### 20 **4. Discussion**

21

22 Neutrally-stratified clouds are usually mixed-phase, precipitating clouds, more  
23 frequently decoupled from the surface than coupled to it. In general, decoupled clouds  
24 are higher than coupled; the analysis revealed that clouds with tops below 700 m tend  
25 to get coupled to the surface, whereas those whose tops are above 900 m remain  
26 decoupled from it. No differences were observed in geometric thickness or condensed  
27 water properties between the two states.

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Moreover, the surface fluxes are similar for both states, suggesting that the  
observed cloud thermodynamic state is not driven by changes in the magnitude, or  
sign, of the surface fluxes, in support of similar results in Shupe et al. (2013) and  
Sedlar and Shupe (2014). It is more likely that displacements downwards (upwards)  
of the cloud layer is the leading factor that results in coupling (decoupling), which

1 would instead be related more to the synoptic scale weather patterns and advected  
2 thermodynamics (e.g., Sedlar and Shupe, 2014).

3 Decoupled clouds exhibit a differentiation in thermodynamic structure,  
4 depending on the depth of the SCML; those with SCML less than 450 m are  
5 disconnected from the surface by a weak inversion, whereas the clouds with SCML  
6 greater than 500 m are characterized by stronger inversions at the decoupling height.  
7 The “weakly decoupled” cases occur twice as often compared to the “strongly  
8 decoupled”.

9 Apart from the thermodynamic differences between the coupled and the two  
10 decoupled sub-categories, some microphysical differences were also observed. For  
11 the strongly decoupled cases, the radar reflectivity profiles exhibit a decrease inside  
12 the cloud, close to the cloud base and a bimodality in reflectivity distribution in the  
13 sub-cloud layer. One branch of the distribution indicates a large reflectivity decrease  
14 with decreasing height, suggesting that precipitation undergoes  
15 evaporation/sublimation in the sub-cloud layer. In contrast, for coupled and weakly  
16 decoupled cases the reflectivity remains almost constant throughout both cloud and  
17 sub-cloud layer.

18 In addition, in strongly decoupled cases the sub-cloud mixed layer is  
19 significantly drier; coupled and weakly decoupled RHi profiles decrease by only a  
20 few percent in the sub-cloud layer, while in strongly decoupled profiles it reaches a  
21 minimum around 85%. Moreover, RHi reaches its minimum at the decoupling height  
22 and below that it increases again, suggesting that the vertical level at which the cloud  
23 gets disconnected from the surface could be impacted by evaporation/sublimation.  
24 This hypothesis is also supported by the fact that increasing mean Doppler velocity  
25 with decreasing height ceases at the decoupling height in both decoupled sub-  
26 categories, which suggests that the hydrometeors do not grow below that level; on the  
27 contrary, in coupled cases the hydrometeors continue growing through the whole sub-  
28 cloud layer.

29 Harrington et al. (1999) and Stevens et al. (1998), using modeling tools, suggest  
30 that evaporation can promote decoupling, by cooling the sub-cloud layer and  
31 stabilizing the atmosphere. Based on ASCOS observations, it seems unlikely that such  
32 processes can be the primary reason driving the decoupling, since evidence of  
33 sublimation was mainly found for strongly decoupled clouds, about 1/3 of all the total  
34 decoupled profiles. Yet, we speculate that evaporation/sublimation may explain why

1 decoupling is amplified in these cases; for example, a strongly decoupled case may  
2 occur because of the existence of a substantially warmer and moister layer capped by  
3 the lower inversion, which releases upward latent heat flux, that probably helps in  
4 sustaining the mixed layer over a larger depth above the decoupling height, as drier,  
5 colder cloud-driven eddies come into contact with warmer and moisture air near the  
6 decoupling height. On the other hand, the fact that precipitation falls through a deeper  
7 layer might be the main reason why evaporation/sublimation appears more effective  
8 in strongly decoupled cases, compared to the weakly decoupled.

9       To further support our speculations, we theoretically calculated the evaporating  
10 rate that is required for a decoupling to occur. As a case study, we used a strongly-  
11 decoupled profile (DoY 241, 11.31am) where the sub-cloud layer was disconnected  
12 from the surface by a  $\sim 1.5^\circ\text{C}$  strong inversion. Theoretical estimations revealed that  
13 evaporation can cause a cooling of this magnitude within 1-3 hours, if evaporating  
14 rates are  $\sim 0.5\text{-}1.5\text{mm/day}$ , assuming that all precipitation evaporates over a 100 m  
15 deep layer. While precipitation rate is difficult to derive from our dataset, this simple  
16 test shows that our argument that evaporating precipitation may enhance the  
17 decoupling does not require excessive precipitation rates.

18       Other factors may also affect the stratification of the atmosphere, such as  
19 horizontal advection in the sub-cloud layer. Furthermore, the fact that, in the strongly  
20 decoupled cases, the layer capped by the inversion is often substantially moister than  
21 the layer above, with RH reaching saturation, suggests that a secondary cloud layer  
22 may be present; cloud radiative cooling at that level could also be related to the abrupt  
23 change in stability observed in these cases.

24       Stably-stratified clouds differ substantially from the neutrally-stratified clouds;  
25 they are geometrically the thinnest clouds observed and are also very low, usually  
26 with a cloud base  $< \sim 200$  m. The observed water properties indicate that these clouds  
27 are optically thin, with few droplets; 72% of stable profiles have  $\text{LWP} < \sim 50 \text{ g m}^{-2}$ ,  
28 suggesting that stable clouds do not contain enough liquid to drive efficient in-cloud  
29 mixing, whereas the IWP is close to zero, indicating that they are often liquid only,  
30 or at least with very few ice crystals. For the remaining stable cases, that have  
31 sufficient amount of liquid to produce turbulent motions, the main unanswered  
32 question is the distribution of the liquid water in the vertical, e.g. the liquid water  
33 content profile. One possibility is that the liquid may not be concentrated near cloud  
34 top but rather be distributed more homogeneously across the cloud, so that differential

1 cooling within the cloud layer is inhibited, as hypothesized by Sedlar et al. (2012) for  
2 the portion of cloud layers that extend into the temperature inversion. Moreover, the  
3 CCN concentrations are small for the stable clouds, further supporting that the  
4 majority of stable clouds are optically thin; this assumes that the CCN concentrations  
5 observed near the surface are representative of the in-cloud conditions which may  
6 not be the case neither when the entire surface-to-cloud layer is stably-stratified nor  
7 when the clouds are decoupled.

8 The potential temperature gradient profiles in these stable cases show that  
9 surface turbulence usually does not impact the stable clouds and the specific  
10 humidity profiles, with increasing moisture with increasing height, indicate that the  
11 surface does not serve as a moisture source. The observed Doppler velocities are  
12 close to zero suggesting that these clouds are often non-precipitating. The  
13 magnitudes of the Doppler spectrum width are very small, which also supports the  
14 conclusion that stable clouds are usually not mixed-phase and have little turbulence.

15 The question remains why these stable clouds contain only liquid. The low  
16 CCN concentration with the optically thin stable clouds is an indication that the air  
17 mass for these cases has a low aerosol concentration and it is not unreasonable to  
18 expect that this would also mean that IN concentrations are small; Prenni et al.  
19 (2007) showed that the concentration of IN is critical to the formation of ice crystals.  
20 The fact that IWP is low in these cases may thus be related to the aerosol  
21 characteristics. Mauritsen et al. (2011) studied such a case from ASCOS in detail.  
22 They hypothesize that, due to the low CCN concentration, the optically thin cloud  
23 consists of a small number of relatively large droplets eventually so large that they  
24 sediment out of the cloud, hence feeding back on the low CCN concentration. The  
25 presence of large spherical droplets is borne out by the frequent occurrence of so-  
26 called fog-bows - a halo-like optical phenomenon that only occurs with relatively  
27 large (20-50 $\mu$ m) spherical droplets (Lee, 1998).

28 The statistical approach of this study does not allow a study of development over  
29 time; to further investigate the possible evolution of these clouds we performed a few  
30 case studies, based both on cases with very low LWP and slightly higher LWP,  
31  $\sim 15\text{g/m}^2$  and  $\sim 65\text{g/m}^2$ , respectively (not shown). Based on these studies it appears  
32 that when the LWP is very low, the cloud slowly becomes more and more tenuous  
33 and eventually dissipates; the time for this can be anywhere from half a day up to

1 two days; this is consistent with the hypothesis in Mauritsen et al. (2011). In the case  
2 with more liquid water, the cloud becomes thicker over time growing upwards and  
3 eventually the stably-stratified profile gradually changes into a neutrally-stratified  
4 profile and, within hours it gets coupled to the surface as in-cloud turbulence starts.  
5 In this case a moisture inversion is present and it is hypothesized the cloud has a  
6 homogenous distribution of liquid across its layer as described above, which  
7 prevents destabilization of the cloud layer. As it grows up into the moisture  
8 inversion, the water supply from this is assumed to cause additional condensation  
9 and a redistribution of the liquid in the cloud layer, allowing differential cooling to  
10 occur, which eventually leads to the generation of cloud driven turbulence.

11 Hence, two possible paths for the evolution of stable cloud state appear to be  
12 supported: (1) the thinner clouds become more and more tenuous until they dissipate  
13 completely. (2) the somewhat thicker clouds increase in optical thickness or achieve  
14 changes in the vertical distribution of liquid through more liquid condensate; this  
15 allows them to eventually drive turbulent motions which may connect with surface-  
16 generated turbulence, considering that the stable clouds are often in very close  
17 proximity to the surface (~below 200 m) – thus eventually transitioning to a coupled  
18 cloud state.

19

## 20 **5. Conclusions**

21 Arctic low-level clouds and Arctic boundary layer structure have been examined,  
22 using observations from the ASCOS expedition, in late summer 2008. In particular,  
23 this study focuses on the interactions between low-level clouds and the surface.  
24 Profiles of equivalent potential temperature are used to identify neutrally-stratified  
25 clouds that are thermodynamically “coupled” to, or “decoupled” from, the surface  
26 turbulence. Apart from these two cases, where turbulence is generated inside the  
27 cloud, a significant number of stably-stratified cases are also identified, suggesting the  
28 absence of in-cloud mixing for these cases. The vertical structure and properties of  
29 these three types: decoupled, coupled and stable clouds, is investigated. This study  
30 shows that:

1 • Decoupled clouds occur more frequently than coupled. The coupling state is  
2 primarily driven by the cloud, through turbulence generated in the cloud by  
3 radiative cooling and buoyant processes and is determined by the proximity of the  
4 cloud layer to the surface mixed layer. Surface fluxes seem to simply respond to  
5 the cloud processes aloft.

6

7 • Decoupled clouds exhibit a bimodality in thermodynamic structure, associated  
8 with the depth of the sub-cloud mixed layer (SCML); clouds with shallower  
9 SCMLs are weakly decoupled from the surface, whereas higher clouds with  
10 relatively deeper SCMLs are strongly decoupled. The enhancement of the  
11 decoupling for the cases with a deeper SCML is possibly due to  
12 evaporation/sublimation of precipitation occurring within the SCML.

13

14 • Stable clouds differ substantially from all neutrally-stratified states in both  
15 thermodynamic and microphysical structure, as well as in geometry and water  
16 properties. They are geometrically and optically thin clouds, often single-phase  
17 (liquid) with no or negligible precipitation. Some of these cases, based on their  
18 proximity to the surface and tenuous nature, represent fog.

19

20 Further testing of these conclusions and potential links between the in-cloud  
21 dynamics and the cloud and precipitation microphysics, including feedbacks and  
22 forcing of the thermodynamic structure, should be further explored using modeling  
23 tools (e.g., Solomon et al., 2011; Solomon et al., 2014) Also, while this study  
24 illustrates the power of surface based remote sensing techniques, more direct in-situ  
25 profiling of both turbulence and cloud microphysics from the surface and through the  
26 clouds, to determine the nature of the coupling, would be highly advantageous.

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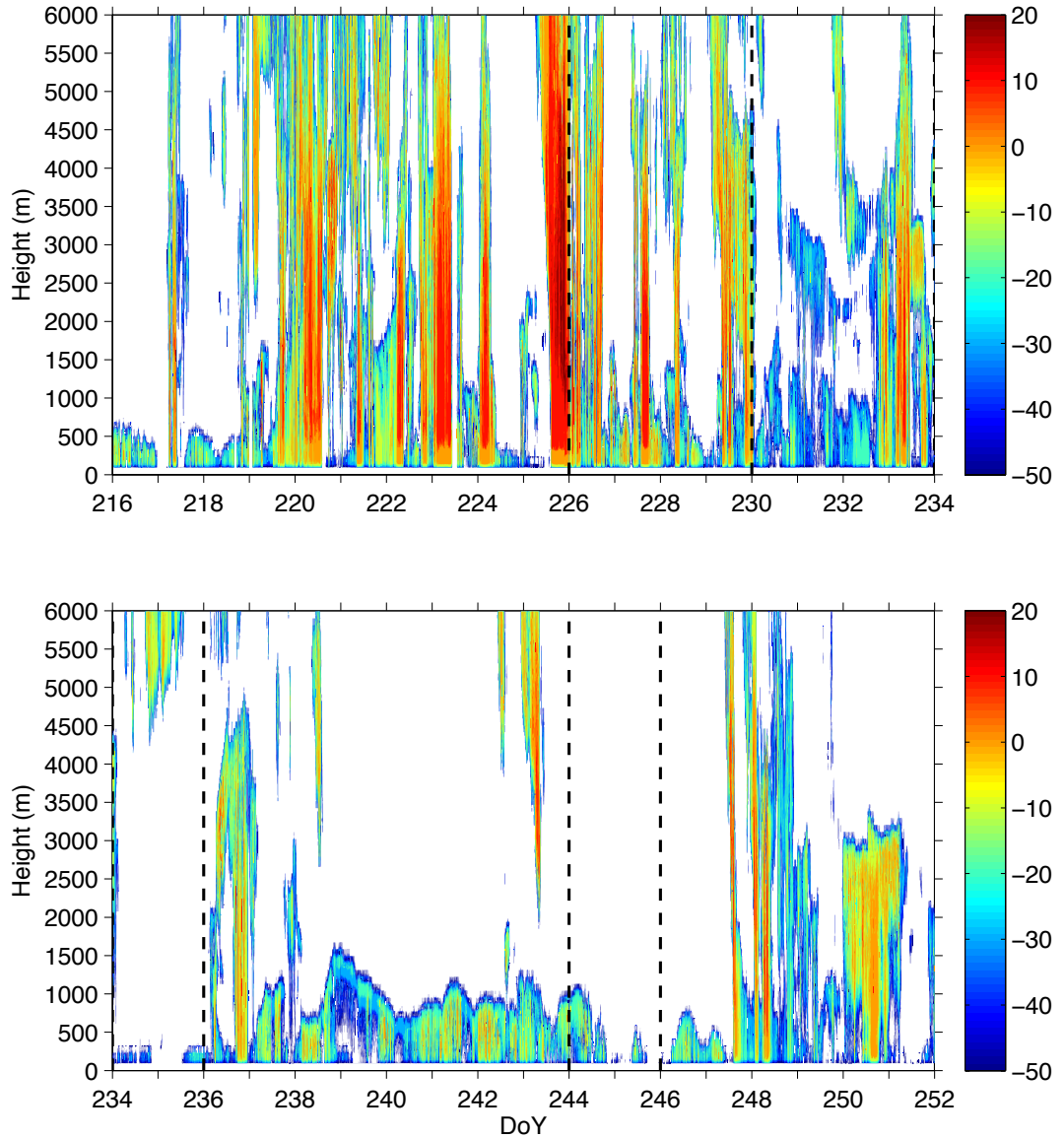
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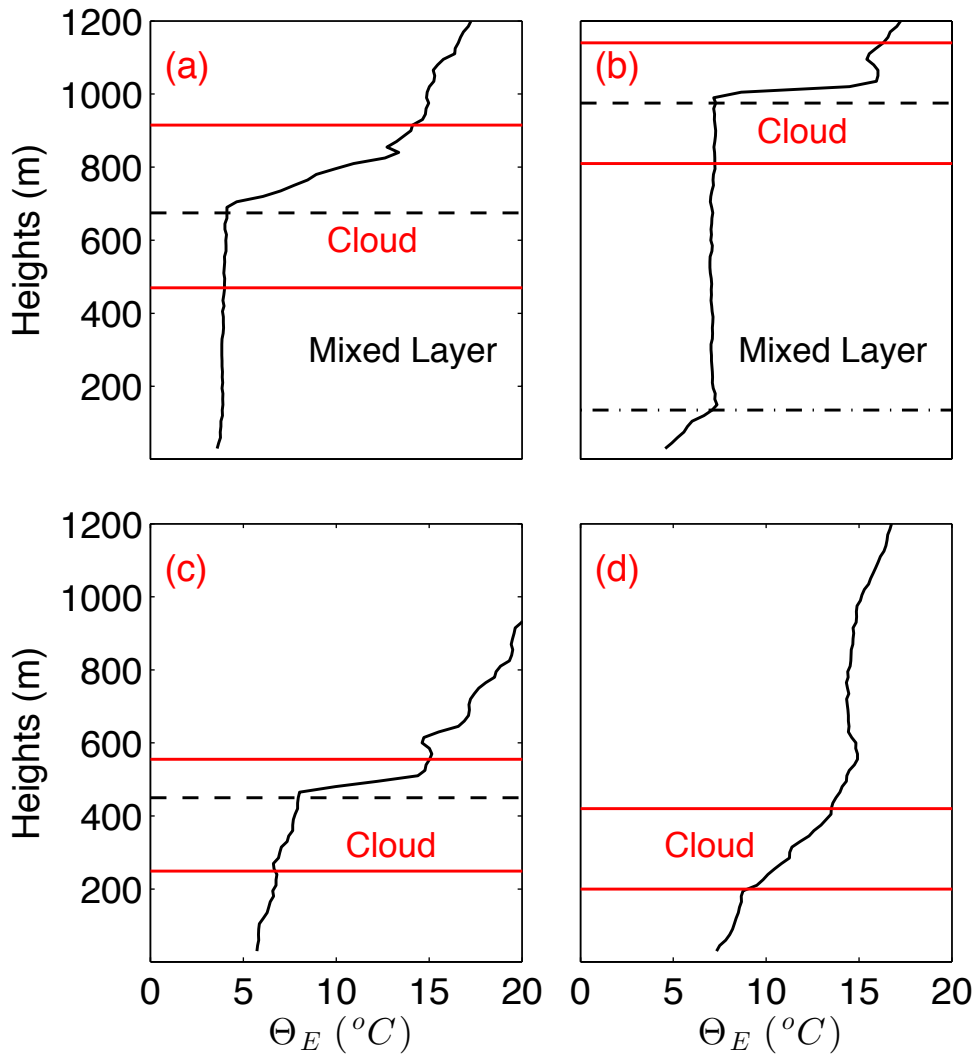
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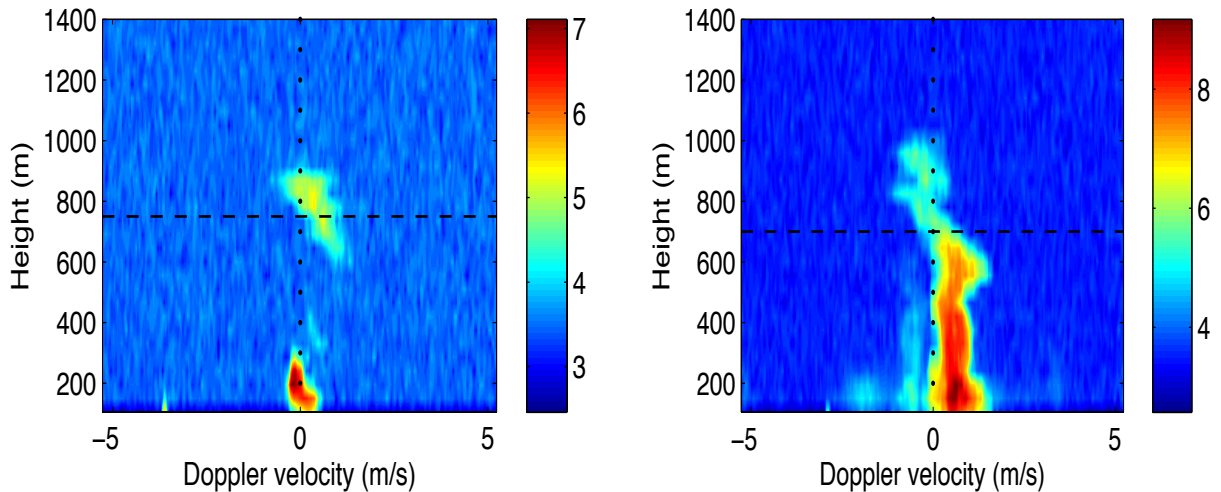




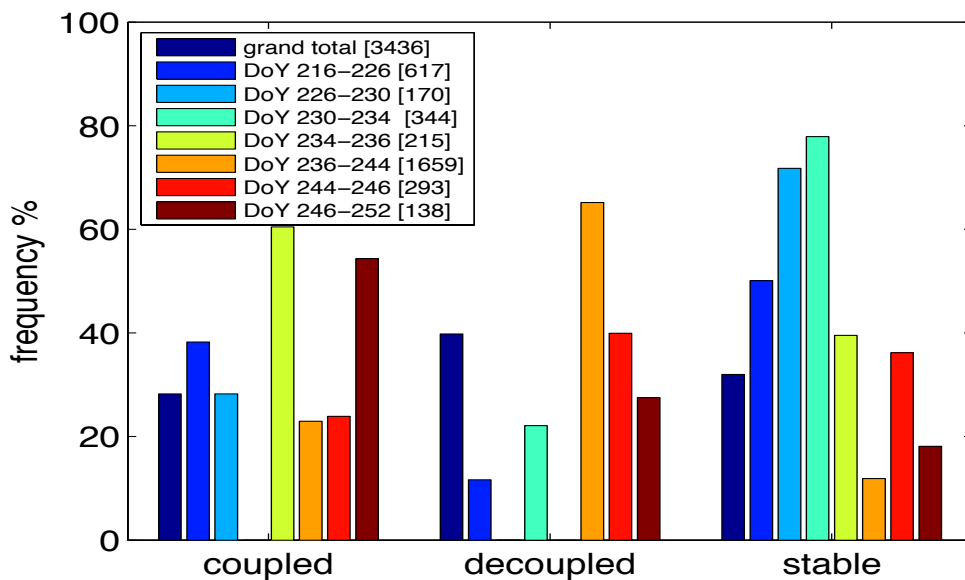
1 Figure 1: Radar reflectivity contour [colors, dBZ] time-series for the ASCOS  
 2 experiment, given in Day of Year (DoY) 2008. The vertical dashed lines differentiate  
 3 the five periods of the ice drift (see section 2.3 for a discussion on period  
 4 characteristics). Periods prior to DoY 226 and after DoY 246 are the transit periods  
 5 (before/after the ice drift). Reflectivity profiles are shown up to 6 km.



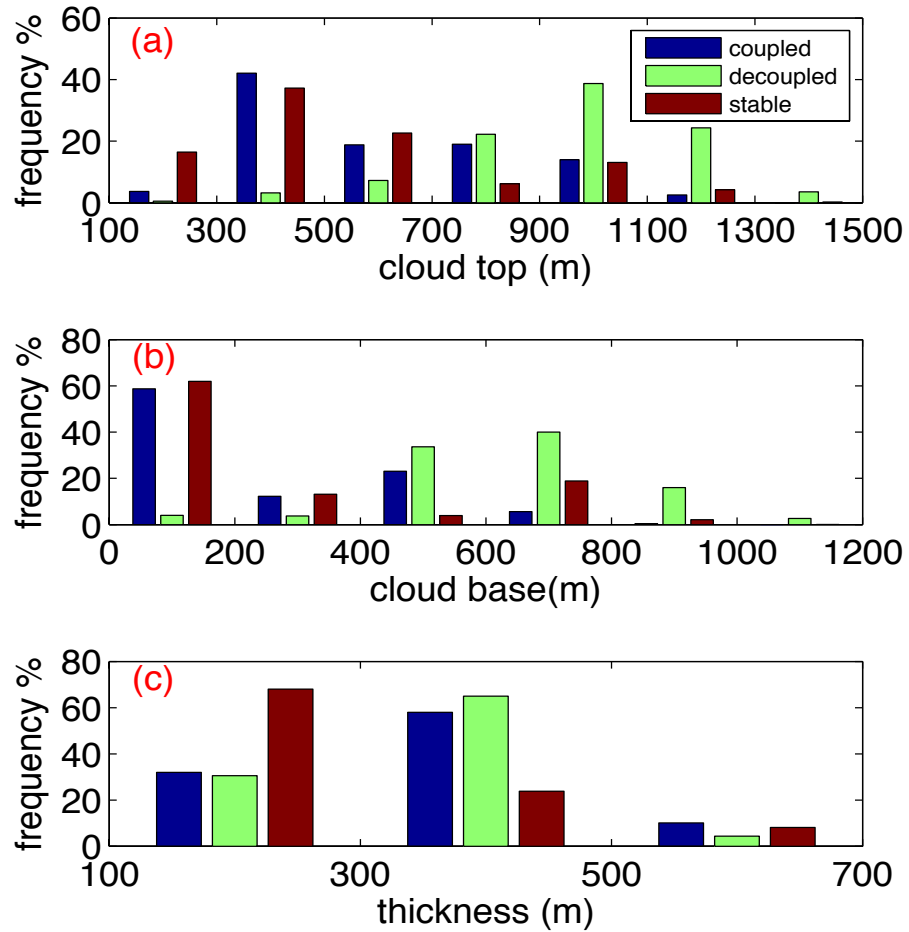
1 Figure 2: Example profiles of scanning radiometer equivalent potential temperature  
 2 ( $\Theta_E$ ) [ $^{\circ}\text{C}$ ] vertical profiles from four ASCOS cases: (a) coupled cloud [DoY 240,  
 3 20:16:47 pm], (b) decoupled cloud [DoY 239, 16:51:47 pm], (c) stable cloud (with  
 4 inversion identified around cloud top) [DoY 217, 16:45:00 pm], (d) stable cloud (no  
 5 inversion around cloud top) [DoY 251, 02:43:13 am]. Red lines indicate the  
 6 respective cloud boundaries observed at profile time. The inversion base height is  
 7 shown as the black dashed line. The black dashed-dotted line indicates the decoupling  
 8 height. The layer between dashed and dashed-dotted, or the surface, is defined as the  
 9 mixed layer.



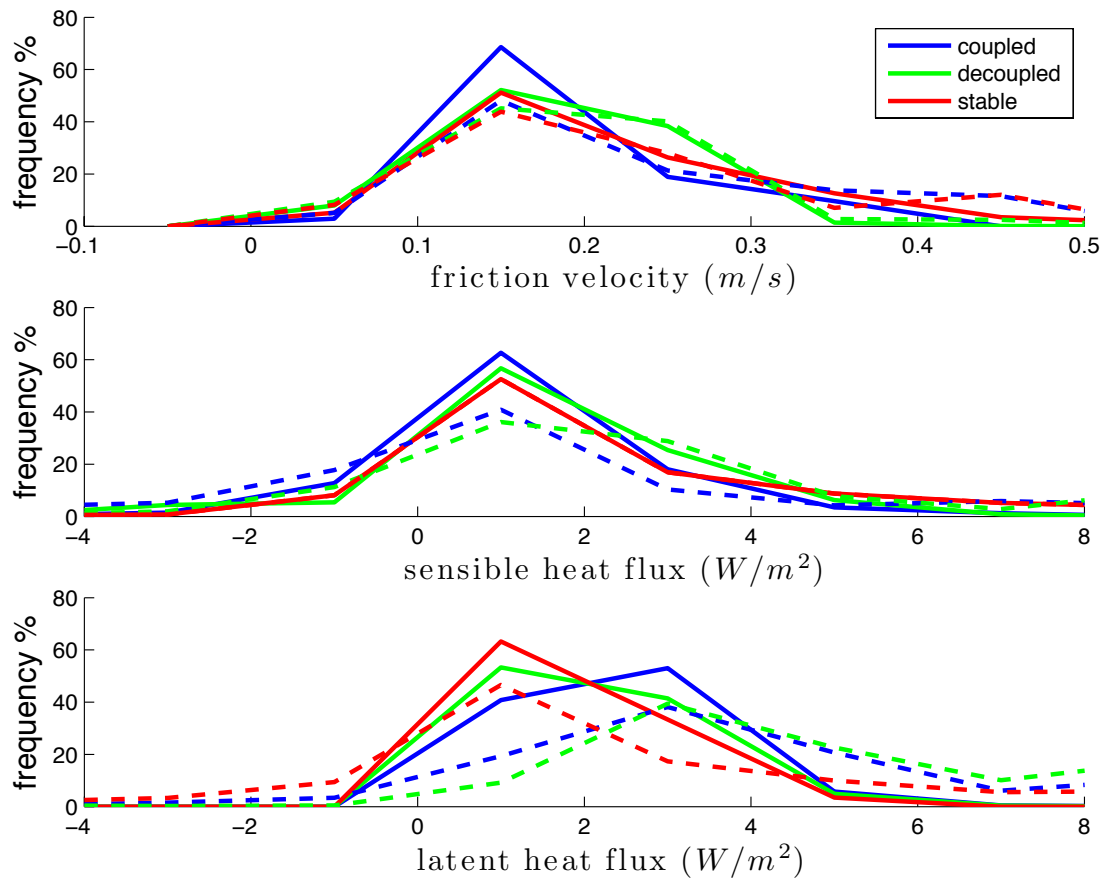
1 Figure 3: Spectrographs for two ASCOS snapshots: (a) DoY 241, 19:11:52 pm: The  
 2 cloud top median height observed by the MMCR is 960 m and the median cloud base  
 3 height observed by the ceilometer is 90 m. We estimate the upper cloud base at 750 m  
 4 from the spectrograph. (b) DoY 237, 10:11:40 am: The cloud top median height is  
 5 1095 m and ceilometer median cloud base height is 140 m. We estimate the real base  
 6 at 700 m. The horizontal black dashed lines indicate the qualitatively derived cloud  
 7 base heights. Colors show the relative frequency distribution (logarithm of reflectivity  
 8 counts) of spectral density of Doppler velocity with height. Positive (negative)  
 9 values represent downward (upward) motion. Zero values are highlighted with dots.



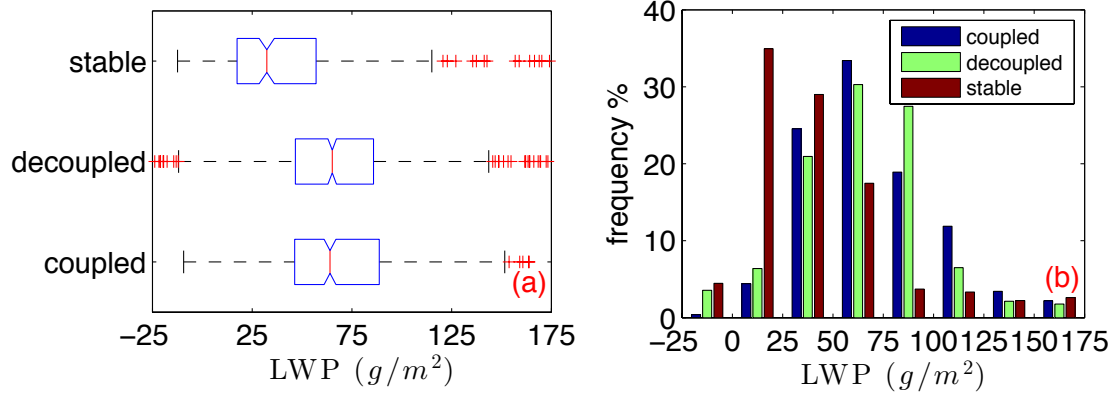
10 Figure 4: Relative frequency distribution (RFD) of cloud state occurrence for each  
 11 period of ASCOS. The number in the brackets indicates the total number of scanning  
 12 radiometer profiles analyzed for each period of ASCOS (see section 2.3 for a  
 13 discussion on period characteristics).



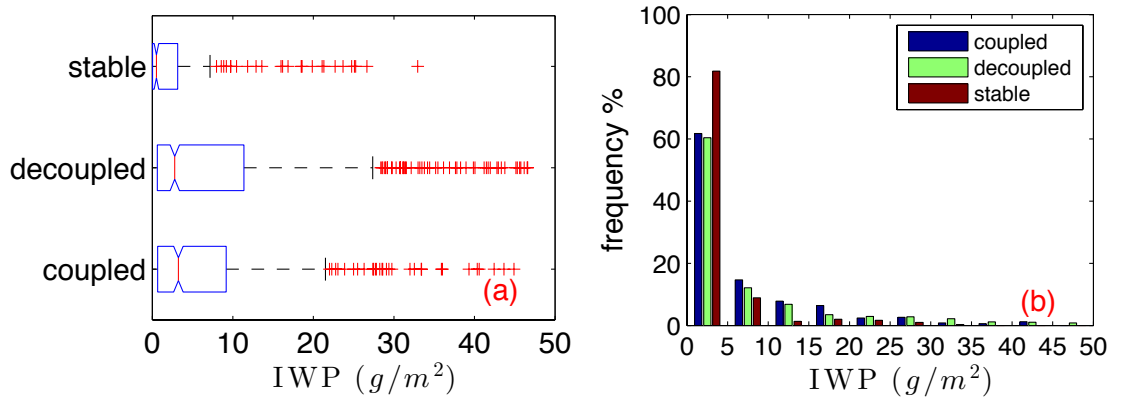
1 Figure 5: RFDs of (a) cloud top height [m], (b) cloud base height [m] and (c) cloud  
 2 thickness [m] for coupled (blue), decoupled (green) and stable (red) cloud states. Bin  
 3 size is 200 m and centered in the interval.



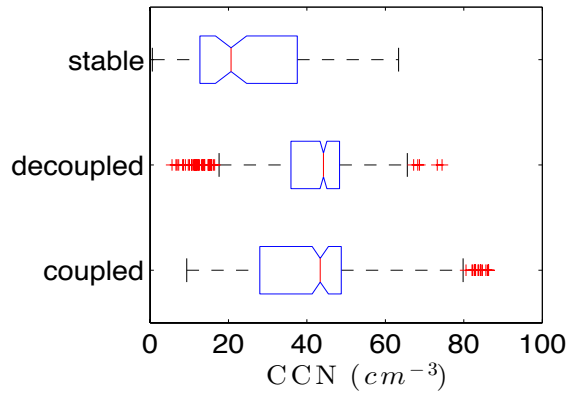
1 Figure 6: RFDs of (a) friction velocity [ $\text{m s}^{-1}$ ] representing momentum flux, (b)  
 2 sensible heat flux [ $\text{W m}^{-2}$ ] and (c) latent heat flux [ $\text{W m}^{-2}$ ] for coupled (blue),  
 3 decoupled (green) and stable (red) clouds. Solid lines represent fluxes estimated from  
 4 sonic anemometers while dotted lines are the bulk fluxes; see Section 2.2 for a  
 5 description on flux calculations.



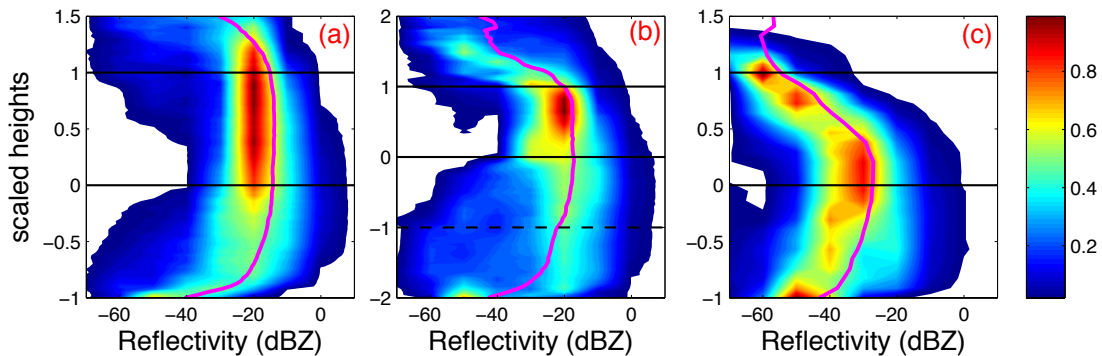
1 Figure 7: (a) Notched box-and-whisker plots and (b) RFDs of LWP [ $\text{g m}^{-2}$ ] for  
 2 coupled, decoupled and stable single cloud layers. In (a), median values are indicated  
 3 by the red solid line, edges of the box mark the lower and upper quartiles, whiskers  
 4 represent the extent of the data that is 1.5 times the difference between the upper and  
 5 lower quartile and crosses are outliers. Notches offer a rough guide to significance of  
 6 difference of medians; the width of the notches is proportional to the interquartile  
 7 range of the sample and inversely proportional to the square root of the size of the  
 8 sample. The bin size in (b) is  $25 \text{ g m}^{-2}$  and centered in the interval. Negative values  
 9 are due to the instrument uncertainty of  $25 \text{ g m}^{-2}$ .



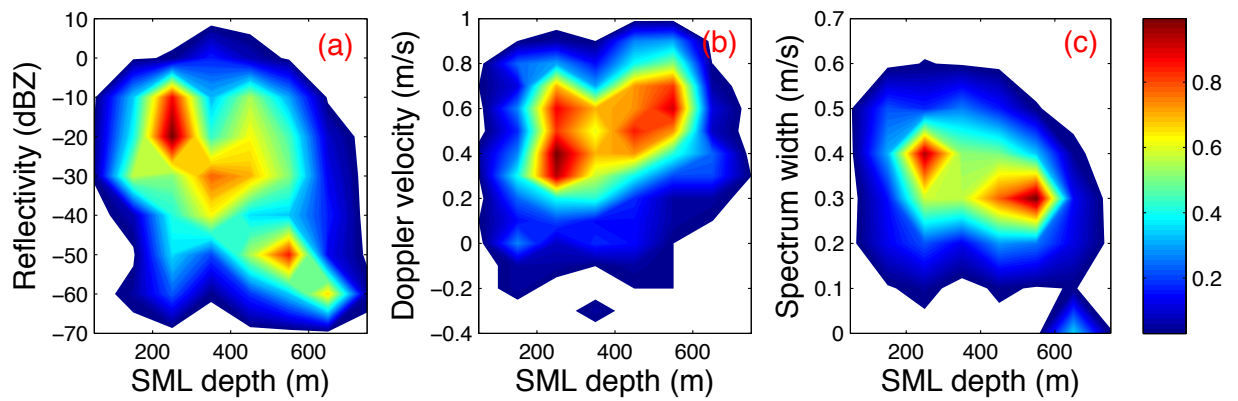
10 Figure 8: Same as in Fig. 9, but for ice water path (IWP) [ $\text{g m}^{-2}$ ] derived from radar  
 11 power-law relationships. The bin size in (b) is  $5 \text{ g m}^{-2}$  and centered in the interval.



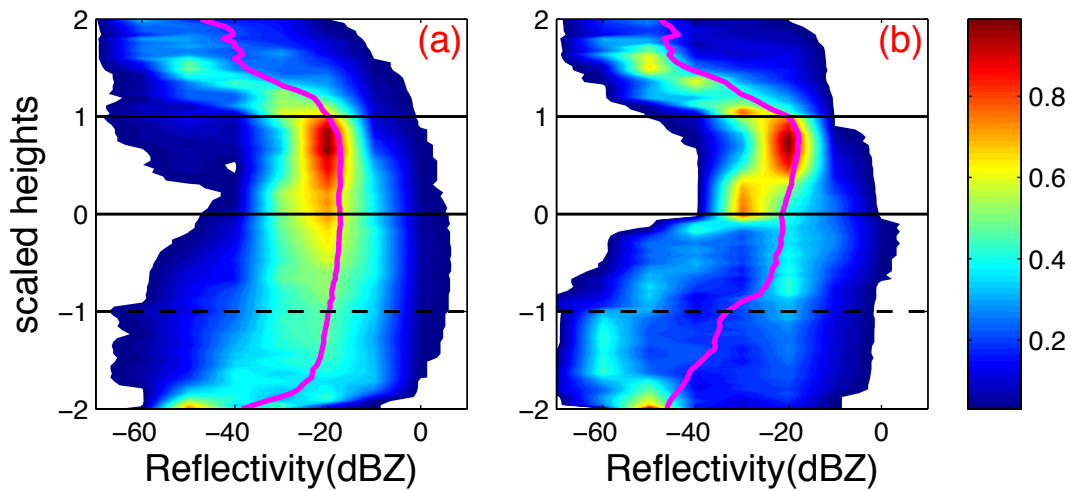
1 Figure 9: Notched box-and-whisker plot of CCN concentrations [ $\text{cm}^{-3}$ ] for coupled,  
 2 decoupled and stable cloud layers. CCN concentrations are measured from ship level  
 3 (see Martin et al., 2011).



4 Figure 10: RFD contour plots of radar reflectivity [dBZ] for (a) coupled, (b)  
 5 decoupled and (c) stable clouds; magenta profiles are the medians. Heights are  
 6 normalized: for (a) coupled clouds,  $z_n=-1$  is the first range gate,  $z_n=0$  is cloud base and  
 7  $z_n=1$  is the main inversion base; for (b) decoupled clouds,  $z_n=-2$  is the first range gate,  
 8  $z_n=-1$  is the decoupling height,  $z_n=0$  is cloud base and  $z_n=1$  is main inversion base; for  
 9 (c) stable clouds,  $z_n=-1$  is the first range gate,  $z_n=0$  is cloud base and  $z_n=1$  is cloud top;  
 10 reflectivity values above cloud top ( $z_n=1$ ) for (c) occur because stricter reflectivity  
 11 thresholds were applied to identify cloud boundaries, while the full reflectivity  
 12 profiles were used to compute the histogram statistics. Frequencies are normalized by  
 13 unity (unity indicates the maximum frequency of all levels).

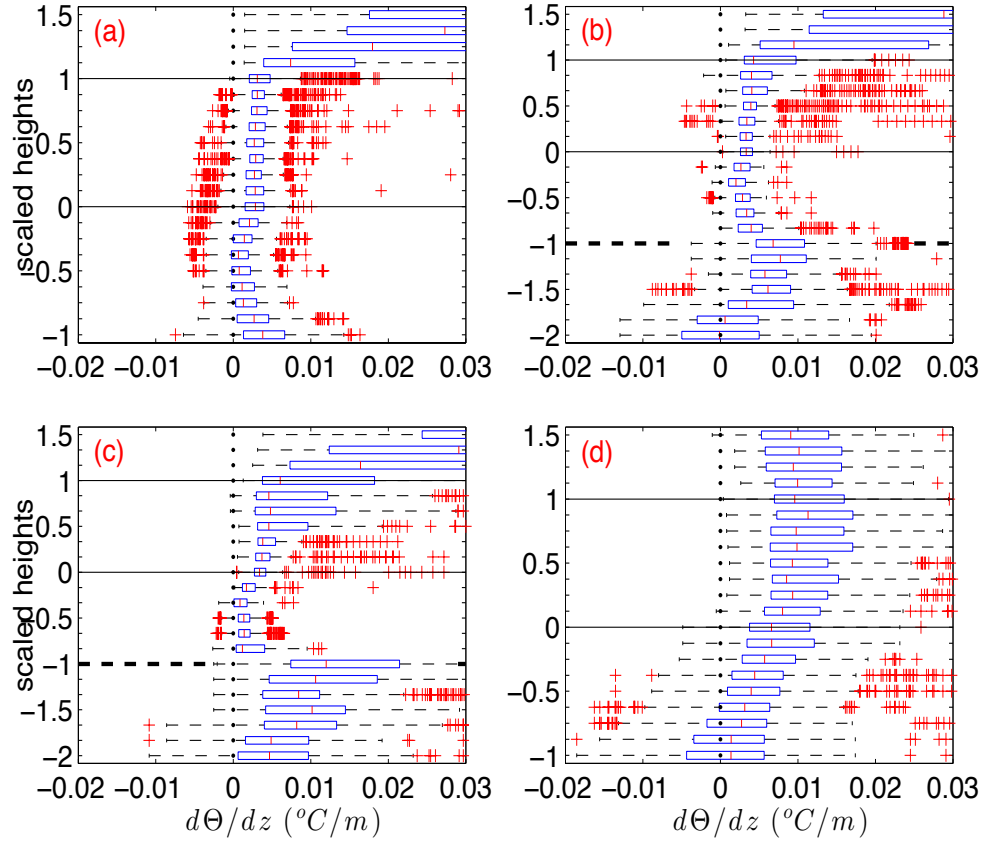


1 Figure 11: 2-D RFD contour plots of (a) radar reflectivity [dBZ], (b) Doppler  
 2 velocity [ $\text{m s}^{-1}$ ] and (c) spectrum width [ $\text{m s}^{-1}$ ] at the decoupling height, in  
 3 relationship to the sub-cloud mixed layer (SML) depth [m]. Frequencies are  
 4 normalized by unity.

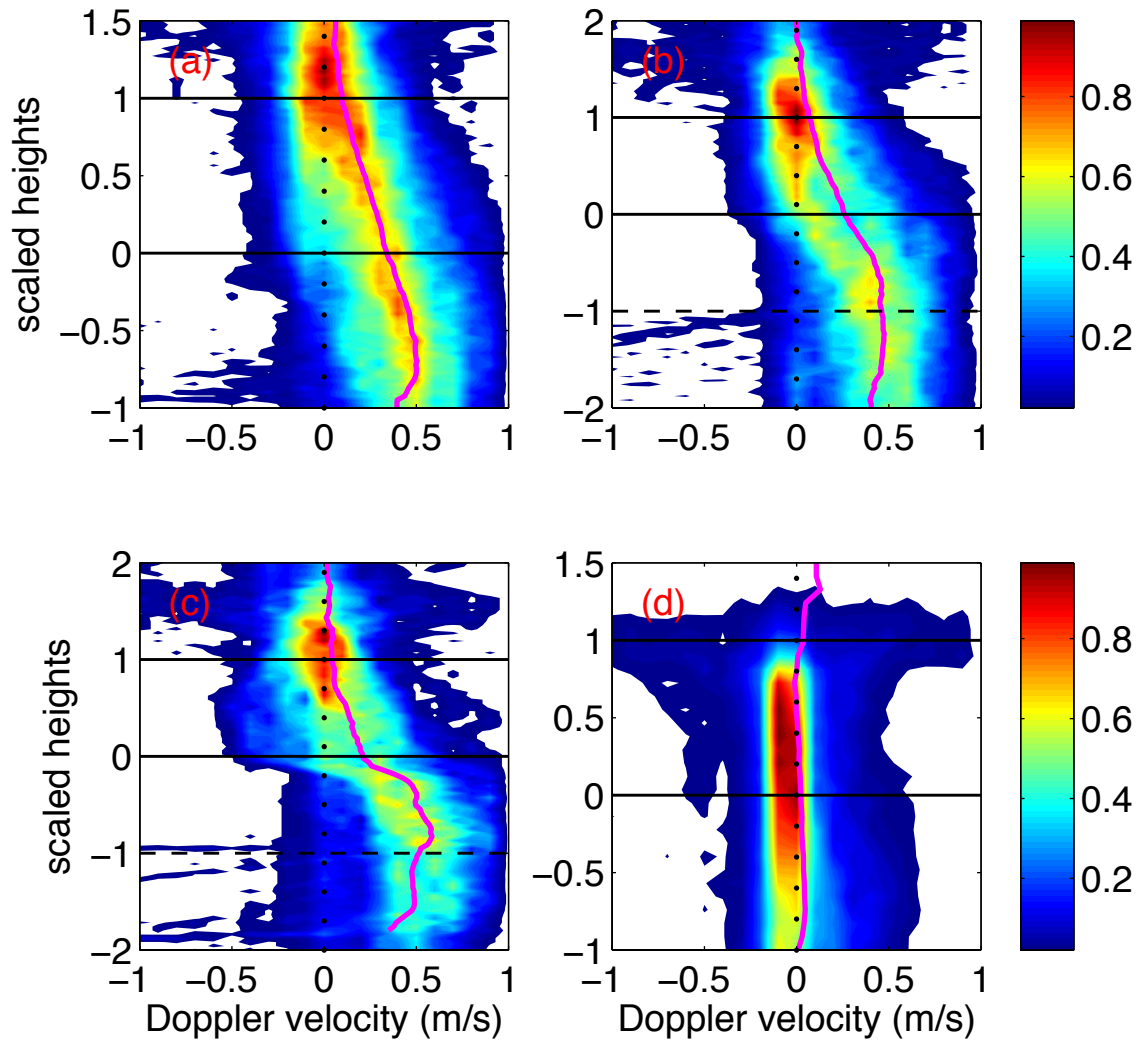


5 Figure 12: Same as Fig. 10 but for (a) clouds decoupled less than 450 m below cloud  
 6 base and (b) clouds decoupled more than 500 m below cloud base.

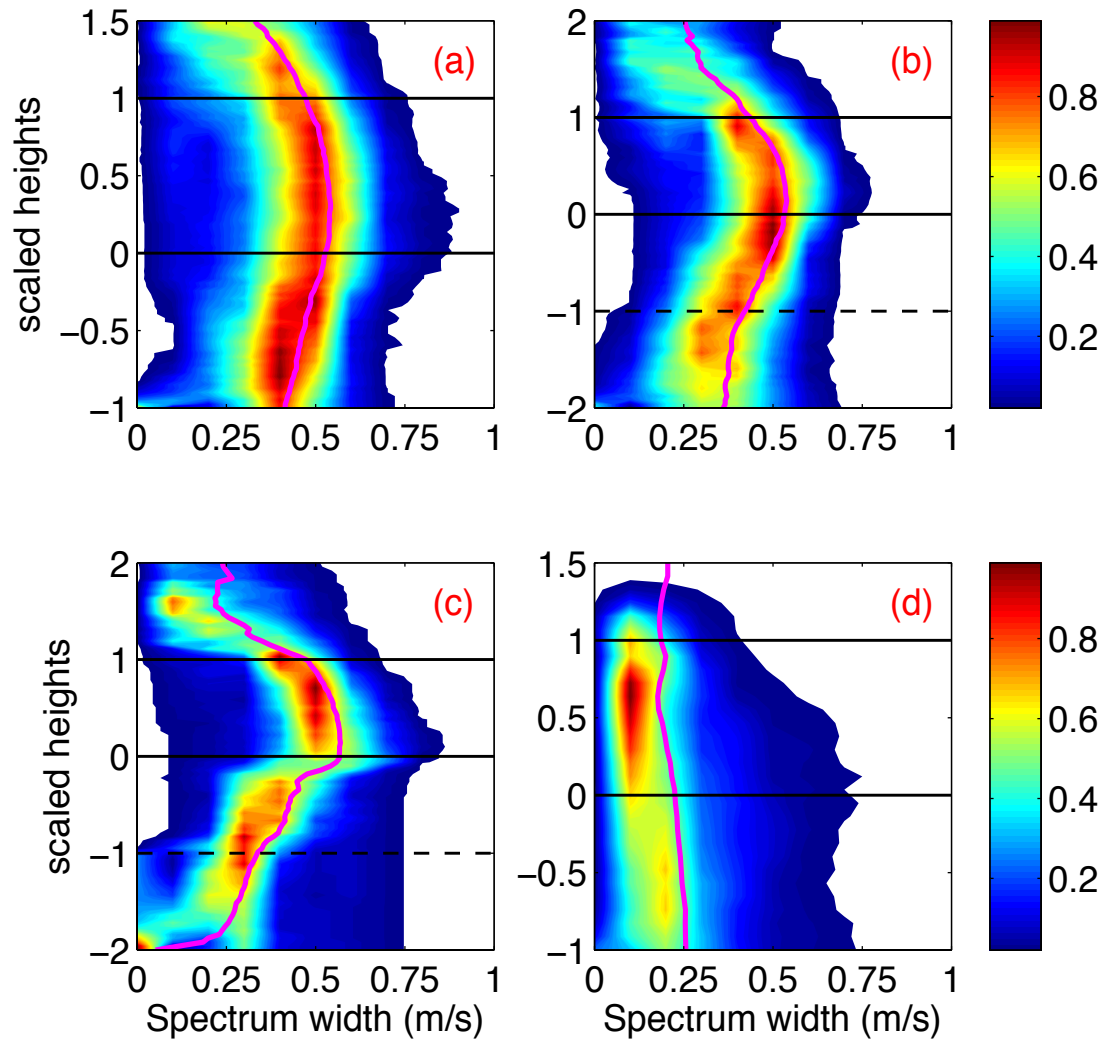




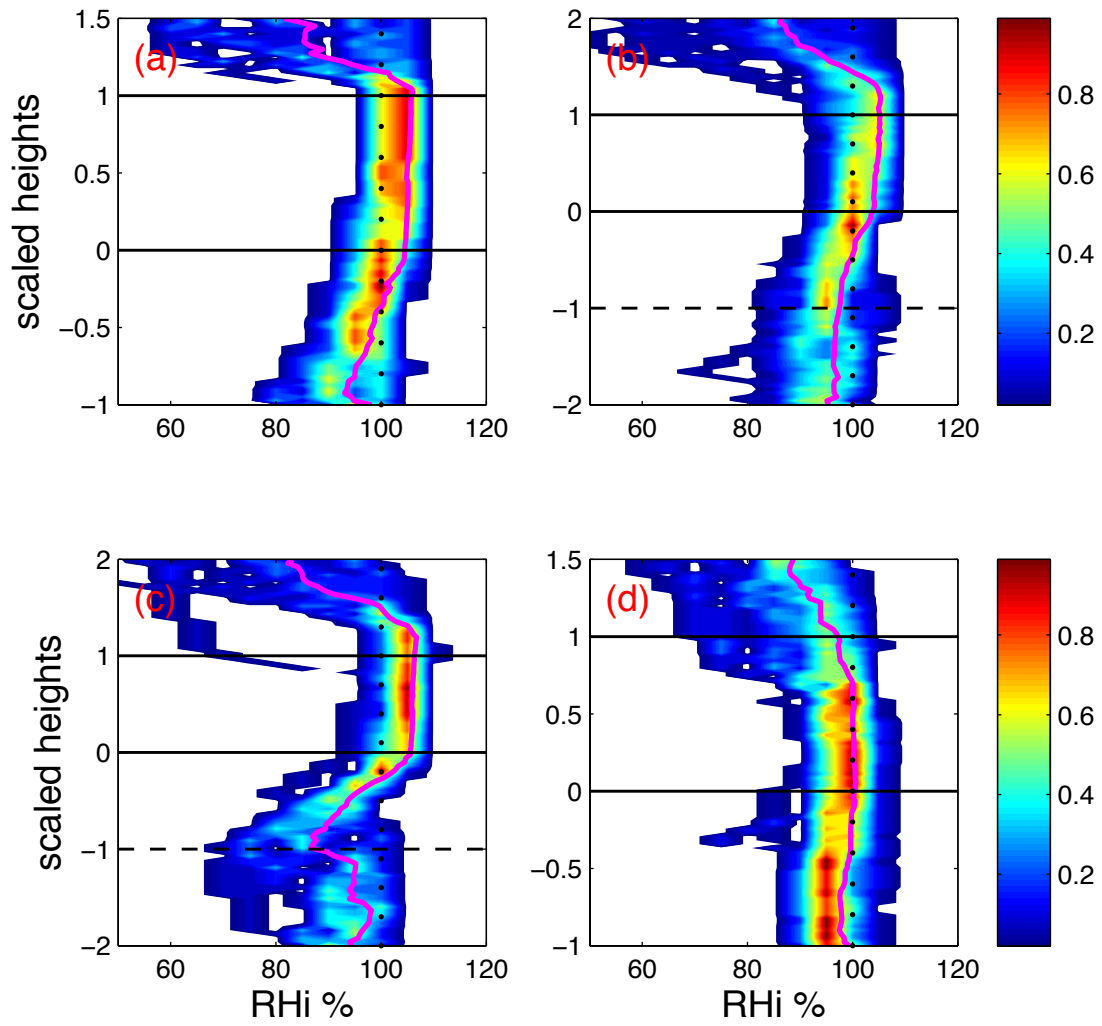
1 Figure 13: Box-and-whisker plots of scanning radiometer potential temperature  
 2 gradient  $d\Theta/dz$  [ $^{\circ}\text{C m}^{-1}$ ] for (a) coupled, (b) weakly decoupled, (c) strongly  
 3 decoupled and (d) stable clouds. The vertical scaling changes with cloud coupling  
 4 state and is same as described in Fig. 10. Zero values are highlighted with dots.



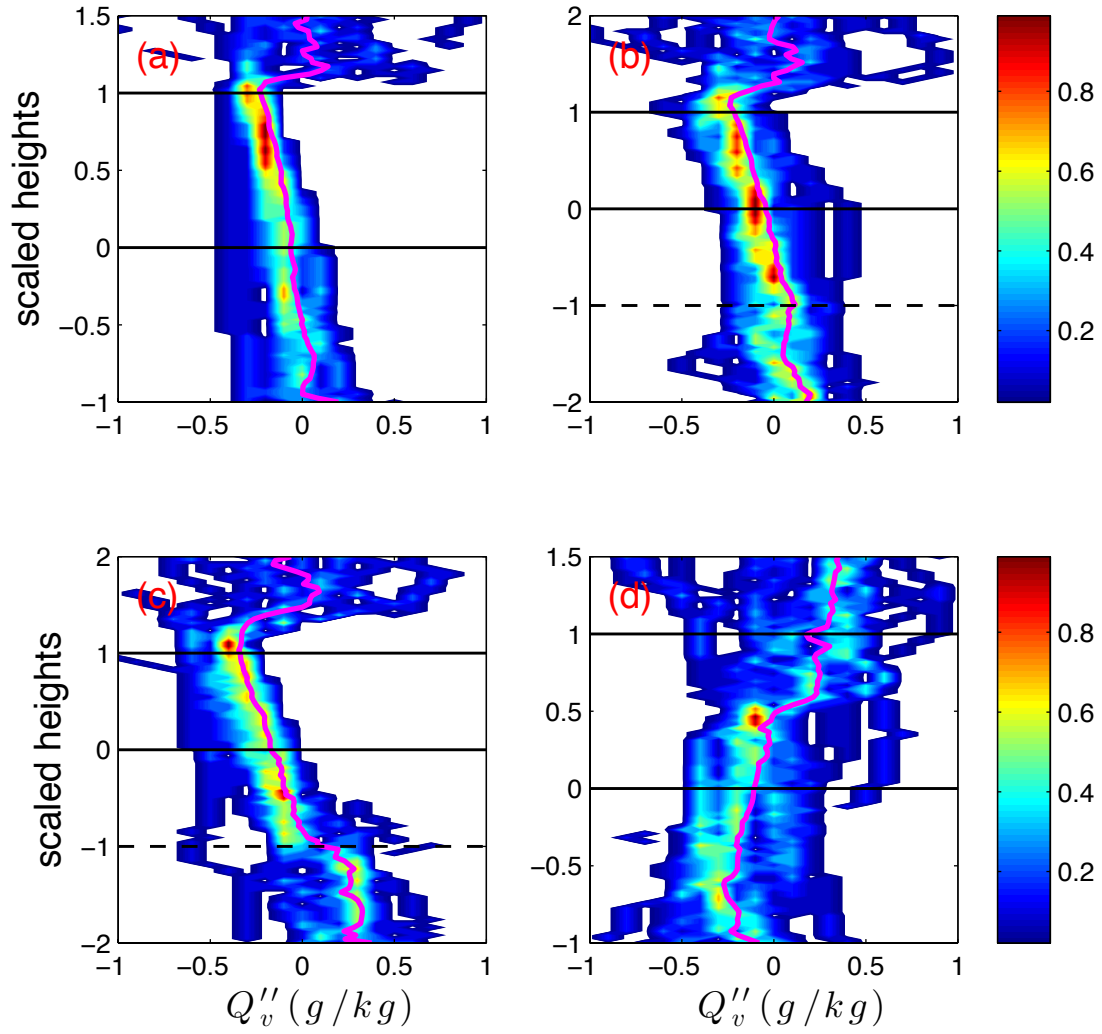
1 Figure 14: RFD contour plots of Doppler velocity [ $\text{m s}^{-1}$ ] for (a) coupled, (b) weakly  
 2 decoupled, (c) strongly decoupled and (d) stable clouds; magenta profiles are the  
 3 medians. The vertical scaling changes with cloud coupling state and is same as  
 4 described in Fig. 10. Zero values are highlighted with dots.



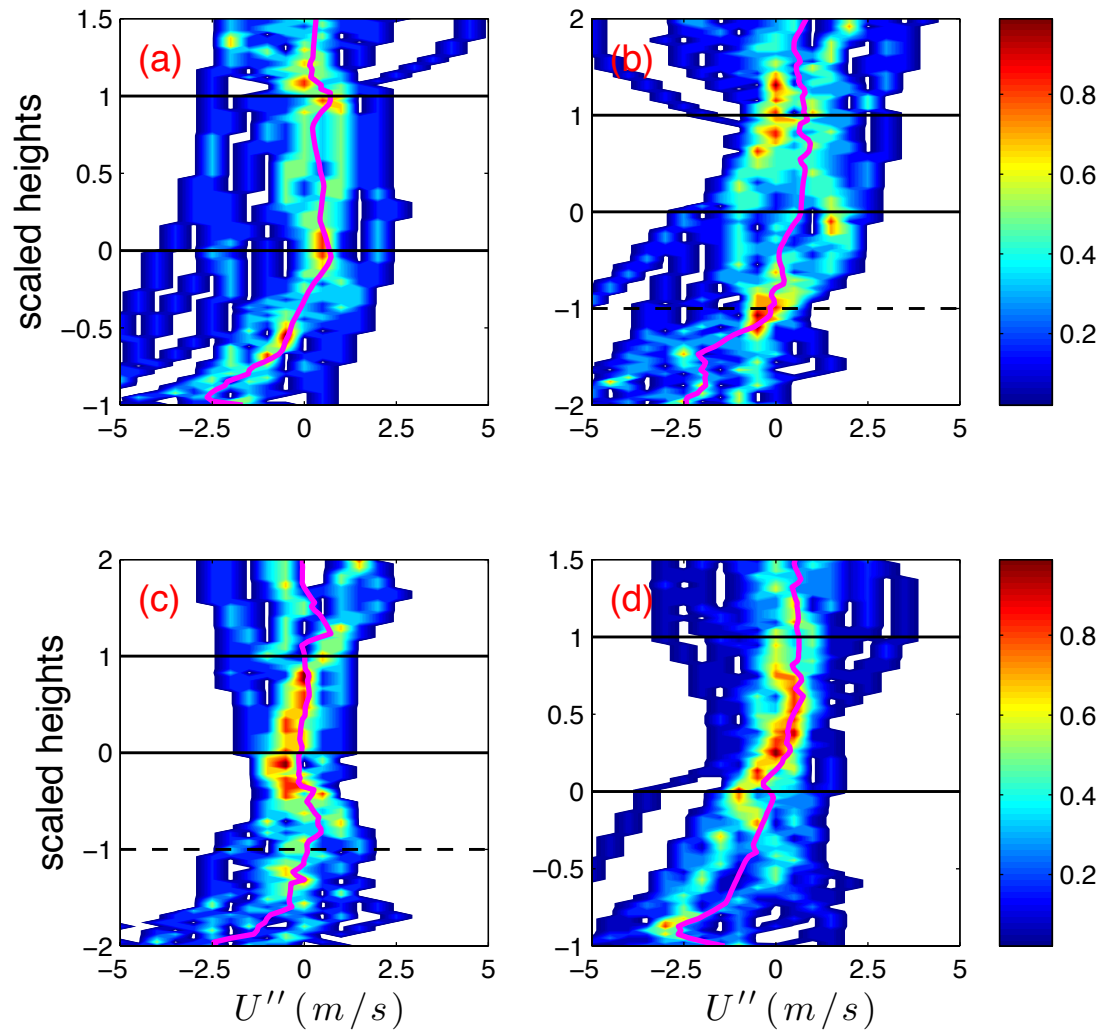
1 Figure 15: Same as Fig. 14, but for spectrum width [ $\text{m s}^{-1}$ ].



1 Figure 16: Same as Fig. 14, but for radiosonde relative humidity [%] with respect to ice  
 2 (RH<sub>i</sub>). 100% values are highlighted with dots.



1 Figure 17: Same as Fig. 14, but for radiosonde scaled specific humidity [ $\text{g kg}^{-1}$ ]. See 2 section 3.5 for details on the scaling method.



1 Figure 18: Same as Fig. 14, but for radiosonde scaled wind speed [ $\text{m s}^{-1}$ ]. See section 2 3.5 for details on the scaling method.