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Atmospheric measurement of point source fossil CO₂ emissions

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9

10 Abstract

We use the Kapuni Gas Treatment Plant to examine methodologies for atmospheric monitoring 11 12 of point source fossil fuel CO₂ (CO₂ff) emissions. The Kapuni plant, located in rural New 13 Zealand, removes CO_2 from locally extracted natural gas and vents that CO_2 to the atmosphere, 14 at a rate of ~ 0.1 Tg carbon per year. The plant is located in a rural dairy farming area, with no 15 other significant CO₂ff sources nearby, but large, diurnally varying, biospheric CO₂ fluxes 16 from the surrounding highly productive agricultural grassland. We made flask measurements 17 of CO₂ and ¹⁴CO₂ (from which we derive the CO₂ff component) and in situ measurements of 18 CO₂ downwind of the Kapuni plant, using a Helikite to sample transects across the emission 19 plume from the surface up to 100 m above ground level. We also determined the surface CO₂ff content averaged over several weeks from the ¹⁴C content of grass samples collected from the 20 21 surrounding area. We use the WindTrax plume dispersion model to compare the atmospheric 22 observations with the emissions reported by the Kapuni plant, and to determine how well

atmospheric measurements can constrain the emissions. The model has difficulty accurately
 capturing the fluctuations and short-term variability in the Helikite samples, but does quite well

25 in representing the observed CO₂ff in 15 minute averaged surface flask samples and in ~one

26 week integrated CO₂ff averages from grass samples. In this pilot study, we found that using

27 grass samples, the modeled and observed CO_2 ff emissions averaged over one week agreed to

within 30 %. The results imply that greater verification accuracy may be achieved by
 including more detailed meteorological observations and refining ¹⁴C sampling strategies.

29 30

31 1 Introduction

32 Emissions of fossil fuel carbon dioxide (CO_2 ff) are the main driver of the post-industrial

increase in atmosphere CO_2 mole fraction (IPCC, 2007; Tans et al., 1990). Knowledge of the

34 sources and magnitude of CO₂ff emissions is critical to improving our understanding of Earth's

35 carbon cycle and climate system. Large point sources (electricity generation and large-scale

industry) make up roughly one third of all CO_2 ff emissions (IPCC, 2007). These point sources

37 are the first CO_2 off emissions sector to be regulated under various national and international

38 carbon tax and cap and trade schemes (e.g. Australian Government, 2013; Government of India, 2010) Baint asymptotic and the west likely and ideter for

2010). Point sources are also the most likely candidates for emissions reduction by carboncapture and sequestration (IPCC, 2007).

41

42 The success of regulatory schemes depends on the ability to demonstrate that emissions targets

43 are actually achieved. Regulating emissions without monitoring "is like dieting without

44 weighing oneself" (Nisbet and Weiss, 2010). Currently, point source emissions are determined

45 using "bottom-up" estimates from self-reported inventory data. Emissions estimates are

46 typically obtained from the volume of fossil fuel (coal, oil or natural gas) consumed and carbon

47 content of that fuel (Andres et al., 2012; Gurney et al., 2009). Uncertainties in the calculated 48 emissions arise from uncertainties in the amount of fuel used, which may include transcription 49 errors and errors in collating the data, and from uncertainties in the carbon content of the fuels 50 themselves. In some countries, smokestack CO_2 emissions are directly measured (e.g. CEMS 51 in the US), with a likely uncertainty of 20% (Ackerman and Sundquist, 2008). In upcoming 52 regulatory environments, it is also possible that deliberate falsification of reported emissions 53 will occur. Thus there is a need for independent, objective measurements of these emissions 54 both to improve the accuracy of the reported emissions, and to provide independent monitoring

- as we move into a regulatory environment.
- 56

57 Atmospheric measurements of recently added fossil CO₂ mole fraction can be combined with 58 knowledge of atmospheric transport in a "top-down" approach to infer the CO₂ff emission flux, 59 providing an emission estimate with quantifiable uncertainties, that is independent from the 60 bottom-up approaches. In the top-down approach, two key components are needed: 61 measurements of CO₂ff mole fraction and a model of the atmospheric transport.

62

CO₂ff cannot be directly measured in the atmosphere, since CO₂ff is but one component of the 63 64 total CO₂ mole fraction. The CO₂ background mole fraction is ~400 parts per million (ppm) and increasing by 1-2 ppm yr⁻¹ primarily due to global CO₂ff emissions (IPCC, 2007; Conway 65 66 et al., 2011). Large diurnal and seasonal cycles are superimposed on this, mainly due to the 67 seasonally and diurnally varying exchange with the terrestrial biosphere by photosynthesis and 68 respiration as well as biomass burning (IPCC, 2007). Ocean exchange of carbon, although having a gross flux of similar magnitude, is of lesser importance over the land areas where 69 70 most CO₂ff emissions occur. The CO₂ mole fraction at a given site will also vary with 71 meteorology as different air masses are advected to the location and as vertical mixing varies 72 through time. When the CO₂ff mole fraction added by a point source is large relative to the 73 variability in the CO_2 background, CO_2 measurements alone may be sufficient to determine 74 added CO₂ff mole fraction. However, in many cases, variability in CO₂ background is large 75 relative to the added CO₂ff mole fraction. This is particularly important when there is a strong 76 biospheric carbon flux nearby. Loh et al. (2009) used the WindTrax Lagrangian particle 77 dispersion model to evaluate atmospheric measurements of point source CO₂ and methane 78 emissions at a local scale. They showed that the method could be useful for methane, where 79 the emissions were large relative to the methane background variability, but was more difficult 80 for CO₂, where background variability was a dominant source of uncertainty.

81

82 CO_2 derived from fossil sources is entirely free of the isotope ¹⁴C, which is removed by 83 radioactive decay with a half-life of 5,730 years (Karlen et al., 1968). All other sources of CO_2 84 contain ¹⁴C at levels close to that of the current atmosphere (Randerson et al., 2002; Turnbull et 85 al. 2000). Thus measurements of the radioacerban content of CO_2 ($\Lambda^{14}CO_2$) can be used to

al., 2009). Thus measurements of the radiocarbon content of CO_2 ($\Delta^{14}CO_2$) can be used to quantify the CO₂ff mole fraction (Suess, 1955; Tans et al., 1979). In the current atmosphere, 1 ppm of added CO₂ff decreases $\Delta^{14}CO_2$ by about 2.6‰ (Turnbull et al., 2009).

88

89 Δ^{14} CO₂ can be determined directly from measurements of ¹⁴C in CO₂ extracted from flask

samples of air (e.g. Turnbull et al., 2007; Graven et al., 2007). The 14 C content of CO₂ is also

91 maintained in carbon assimilated by plants so that the average Δ^{14} C of the assimilated CO₂, and

hence the overlying atmosphere at the time of uptake, can be determined from the ¹⁴C content

- 93 of plant materials (e.g. Hsueh et al., 2007; Palstra et al., 2008). CO₂ assimilation rates vary
- 94 with local climatic weather conditions, plant type, and plant growth phase, meaning that a
- 95 complex weighting function may be needed to describe the averaging period (Bozhinova et al.,
- 96 In Press). CO₂ absorption by an alkaline solution (sodium hydroxide, NaOH) is another
- 97 commonly used method to obtain time-integrated average Δ^{14} C in the atmosphere (e.g. Levin et
- 98 al., 2010; Currie et al., 2009; van der Laan et al., 2010).
- 99

100 A number of studies have used correlate tracers to estimate CO₂ff. In this method, a trace gas 101 that is co-emitted with CO₂ff, such as carbon monoxide (CO), is monitored in the atmosphere. 102 If the emission ratio of CO:CO₂ff is known, then CO₂ff can easily be determined (Levin and Karstens, 2007). CO is much more readily measured than Δ^{14} CO₂, so this method can obtain 103 CO₂ff mole fractions at higher spatial and temporal resolution (Vogel et al., 2010; Turnbull et 104 105 al., 2011a). Unfortunately, the emission ratio CO:CO₂ff is imperfectly known, variable by 106 combustion efficiency and method, and large power plants typically emit little or no CO 107 (USEPA, 2012). Other correlate tracers have been considered, including sulphur hexafluoride 108 (Turnbull et al., 2006), perchloroethylene (Miller et al., 2012), and acetylene (LaFranchi et al., 109 2013), but most of these tracers are only indirectly associated with CO₂ff combustion sources, 110 so are likely not appropriate for monitoring of individual point source emissions. Further, the 111 amount of correlate trace gases emitted directly from the point source may vary widely depending on the fuel used, combustion process, and "scrubbing" of pollutant gases before 112 they are emitted into the atmosphere. Hence Δ^{14} CO₂ remains the most robust method for 113 114 quantifying CO₂ff across a range of environments.

115

116 Once the CO_2 ff mole fraction has been determined, the emission flux can be modeled or 117 estimated by using a description of atmospheric transport from the emission source to the 118 measurement location. This has been performed at various scales using techniques ranging 119 from a simple mass balance model for urban scale emissions (Turnbull et al., 2011a), to a 120 Lagrangian particle dispersion model for the regional scale (Turnbull et al., 2011b), to 121 tracer:tracer flux estimates using radon (Levin et al., 2003; Van der Laan et al. 2010). 122 Modeling studies have demonstrated that long-term trends in regional CO₂ff emissions could be determined from a combination of Δ^{14} C observations and regional or global modeling 123 124 (Levin and Rödenbeck, 2007). Monitoring of CO_2 ff from point sources has not previously 125 been attempted, but other species emitted by point sources have been monitored in the 126 atmosphere. Mass balance modeling has been successfully used to monitor ozone from large 127 power plants (Trainer et al., 1995; Ryerson et al., 2001). This method uses aircraft sampling at high temporal resolution across transects downwind of the point source, and a simple 128 129 description of plume dispersion to quantify emissions. It can estimate emissions to within 130 \sim 50% under consistent wind conditions when emissions are large relative to the background 131 mole fraction. More commonly, Lagrangian atmospheric transport modeling is used to both 132 identify emission sources and to quantify those emissions. Point source emissions of numerous 133 pollutant species have been evaluated using this method, including SO₂, NOx and particulates 134 (e.g. Dresser and Huizer, 2011; Ghannam and El-Fadel, 2013). These studies are focused on 135 air quality impacts, and there is little detailed information about the quality of total flux 136 estimates in the models. 137

- 138 Here we examine methodologies for atmospheric monitoring of point source CO₂ff emissions.
- 139 Our experimental site is a small, isolated industrial CO₂ff emission source in rural New
- 140 Zealand. Our focus is on CO₂ff quantification from Δ^{14} CO₂ measurements, examining two
- 141 different sampling methods: snapshot flask sampling in the atmosphere, and time-integrated
- sampling from grass. We use a Lagrangian plume dispersion model run forward in time to
- 143 predict the CO₂ff mole fraction from the known emissions and meteorological data. We then
- 144 compare the predicted and observed CO₂ff mole fractions to examine the different methods.
- 145
- 146 Our goal is to evaluate the methods from both scientific and application perspectives,
- 147 considering:
- Measurement cost and complexity. How easily can the sampling method be deployed at field sites, and how difficult is the measurement?
- What sampling methods are most compatible with the strengths of the current generation of
 atmospheric transport models? Models imperfectly simulate atmospheric transport, and
 emissions detection will be more or less robust depending on how the model is used.
- What are the uncertainties in the estimate of the CO₂ff emission flux, and how could these uncertainties be reduced?
- 155

156 2 Methods

- 157 2.1 Sampling location and point source description
- 158 Our experimental site is the Kapuni Gas Treatment Plant, located in rural New Zealand and run 159 by Vector (figure 1). The Kapuni plant processes natural gas extracted from nearby onshore 160 natural gas wells in the Taranaki Basin. Natural gas from this field contains ~40% CO₂. At 161 the Kapuni plant, the CO_2 is stripped from the natural gas and vented to the atmosphere at a 162 rate of ~0.1 TgC yr⁻¹ (NZMED, 2010). This equates to average emissions of about 3,300 gC s⁻¹ ¹. The emissions are small relative to many industrial facilities and power plants around the 163 world, for example, the world's largest power plant (Taichung, Taiwan) emits ~300,000 gC s⁻¹ 164 165 (Ummel, 2012; Wheeler and Ummel, 2008). We recognize that there will be differences in
- applying the results of our study to larger emission sources.
- 167

168 The Kapuni plant is located in a rural dairy farming area, with no other significant CO₂ff

- sources nearby. The Agri urea plant located 500 m west of the Kapuni plant does emit a small
- amount of CO₂, but this is approximately 1% of the Kapuni plant emissions (NZMED, 2010).
- 171 We avoid sampling close to local roads, and also note that traffic counts are low (one vehicle
- 172 every ~ 10 minutes), so the overall contribution of traffic CO₂ff in our measurements is
- 173 expected to be minimal. There is a small CO₂ff source from residential heating using natural
- 174 gas and from farm vehicle exhaust, but farm and residential power are typically from mains 175 electrical supply with no local CO₂ff emissions. The farmland is highly productive grassland,
- electrical supply with no local CO₂ff emissions. The farmland is highly productive grassland,
 with large, diurnally varying, biospheric CO₂ fluxes. The surrounding terrain is relatively flat,
- with large, diamany varying, biospheric CO_2 fluxes. The suffounding terrain is relatively flat, with elevations within 2 km of the Kapuni plant varying by about 10 m. There are some trees
- 177 with elevations within 2 km of the Kapun plant varying by about 10 m. There are some trees of ~20 m height to the south and west of the plant, and a dip to lower elevation directly to the
- 179 east where a stream flows (figure 1).
- 180
- 181 2.2 Sampling methods
- 182 2.2.1 Kite platform

183 A Helikite, a patented combination kite and helium balloon (Allsopp Helikites Ltd, Hampshire, 184 England) was used to sample air from the surface up to 100 m above ground level, downwind 185 of the Kapuni plant, on October 26, 2012. The Helikite was fitted with a GPS (Garmin 60CSx) 186 to determine location at 1 s time resolution. A tethersonde (Graham Digital Design, Amberley, 187 New Zealand) with an anemometer was used to measure wind speed and direction, temperature, 188 and pressure at 10 s resolution. Transmitted data were received at a ground station providing 189 real-time height and wind data. The anemometer cups tangled with the tether line for short 190 periods during the measurement campaign, identified as zero wind speeds; we exclude these 191 periods from our dataset. 300 m of 4 mm OD polyethylene (Leda Extrusions, New Zealand) 192 tubing was attached to the kite tether close to the tethersonde, bringing air from the kite to our 193 mobile lab. A diaphragm pump (KNF, model # N186.1.2KN.18) was placed halfway along the 194 inlet line on the ground to improve flow rate.

195

196 The inlet line ran to a cavity ring down spectrometer (CRDS, Picarro model G1301) inside a

197 mobile laboratory. The CRDS provided real-time mole fractions for CO_2 in the air arriving 198 from the intake on the Helikite. Individual observations were made at ~ 2 s intervals. The

- 199 measurement precision for CO_2 is better than 0.1 ppm, determined from the spread of repeat
- 200 measurements of an air standard sampled using an experimental setup similar to that used for

201 this experiment. The CO₂ measurements are referenced to the World Meteorological

202 Organization WMO X2007 CO₂ mole fraction scale to within 0.05 ppm, and one-minute 203 averages of transfer gases have also been determined to a standard deviation on replicates of

204 0.05 ppm. Methane (CH₄) was simultaneously measured but is not discussed here since CH₄ 205 sources in the area are complex. The transit time from the inlet to the mobile lab was

206 determined from timed puffs of (high CO₂) human breath, and determined as 173 seconds. The 207 flask filling and CO₂ mole fraction measurements are adjusted for this time delay and matched 208 to the GPS and meteorological measurements, which were operating on the same timestamp.

209

210 Previously evacuated glass flasks (0.8 - 2 L volume) were filled by opening a valve directly 211 upstream of the CRDS unit without reducing sample flow to the CRDS. The air was dried

212 using magnesium perchlorate and then passed through a diaphragm pump to fill the flasks to a

- 213 pressure of 2 bar absolute. Flask fill times varied from 2 to 6 minutes, depending on the flask 214 volume. We determine the CO₂ mole fraction in the flask sample as a weighted average of the
- 215 CO₂ mole fraction measured on the CRDS made during the flask filling time. The weighting
- 216 function for the flask fill was obtained by logging the pressure increase in a flask, as a function
- 217 of time, for the flask sampling pump (KNF, model N814KNE) and scaling the resulting
- 218 function by flask size. The weighting function was then approximated by fitting a polynomial
- 219 to the pressure change through time, which approximates the fill rate well ($r^2=0.99$).
- 220
- 221 2.2.2 Surface flasks

222 Five surface samplers were also deployed on October 26, 2012 at one location upwind of the Kapuni plant and four locations downwind and beneath the Helikite track. For each sampler, 223 224 the air is drawn in through an inlet line (6 mm OD, polyethylene) from an intake 3 m off the

225 ground. A deflated 4 L Tedlar bag is slowly filled at a designated flow rate from a manifold

226 operating at a preset overpressure. In this case, three liters of air was collected over 15 minutes. 227 Each sampler was pre-programmed to purge the sample lines for one minute and then collect a

228 15 minute sample once every 18 minutes. After sampling was complete, a small aliquot was used to determine the CO_2 mole fraction on the CRDS, and then the air sample was transferred into a pre-evacuated glass flask using the flask pump and pressurization method described

- above. A subset of these surface samples were selected for Δ^{14} CO₂ analysis.
- 232

233 2.2.3 Grass samples

When plants photosynthesize CO₂, the ¹⁴C/¹²C ratio of that CO₂ is altered only by isotopic fractionation during photosynthesis (Suess et al., 1955). The ¹⁴C/¹²C fractionation can be quantified from the ¹³C/¹²C fractionation (δ^{13} C), and Δ^{14} C for CO₂ and plant material is normalized to a δ^{13} C of -25‰ (Stuiver and Polach, 1977). Thus the Δ^{14} C of the plant material can be considered identical to the photosynthesized CO₂, integrated over the period of plant growth.

240

A number of studies have shown that plant material records the broad spatial patterns of

242 Δ^{14} CO₂ in the modern atmosphere, using corn leaves (Hsueh et al., 2007; Riley et al., 2008), 243 wine ethanol (Palstra et al., 2008), and rice grains (Shibata et al., 2005). Several of these

studies compared the observations with model predictions, and achieved reasonable agreement at the continental and regional scales, mostly reflecting the spatial pattern of CO₂ff emissions. However, the exact Δ^{14} C measured will depend on the growth period of the plant, variations in photosynthetic uptake during the growth period (e.g. weather conditions) and how the plant allocates the photosynthesized carbon among different parts of the plant (Bozhinova et al., in press). The resulting sample integrates over variable rates of photosynthesis but can generally be viewed as an integrator of the daytime photoperiod Δ^{14} CO₂.

251

252 We collected samples of grass from farmland around the Kapuni plant on August 15, 2012 and 253 October 24, 2012. The grass species was not specifically identified for these samples, but the 254 dominant species in South Taranaki is a ryegrass, Lolium perenne (Roberts and Thomson, 255 1984). The farmland in this region is divided into small paddocks (fenced fields) and each 256 paddock is grazed by the dairy cow herd for one day every 18-25 days. The grass grows ~ 20 257 cm during the regrowth period, and regrazing occurs before any flowering has begun. We 258 sampled grass from paddocks that had been grazed one to two weeks previously, so our 259 samples likely represent an average over one to two weeks. We collected samples of the ~ 20 260 cm regrowth, and radiocarbon measurement was performed on part of an individual grass leaf 261 from each sample. As all growth is in the vegetative phase, allocation of carbon to the leaves is 262 likely consistent across the growth period, but there will be some variability in uptake with 263 weather patterns, which we do not account for. We make the simplifying assumption that the 264 leaf samples represent the daytime average for the one-week period preceding sampling. 265 Sample locations were determined using a handheld GPS, and locations close to obstructions 266 such as hedges and buildings were avoided, as were sites close to roads.

267

268 $2.3^{14}C$ measurement and CO_2 ff determination

CO₂ was cryogenically extracted from the flask samples by slowly flowing the air over a
Russian doll type liquid nitrogen trap (Brenninkmeijer and Röckmann, 1996). In the case of
grass samples, pieces of grass were acid washed (0.5 M HCl at 85°C for 30 minutes) to remove

any adhering material, then rinsed to neutral and freeze dried, prior to sealed tube combustion

with copper oxide and silver wire at 900°C. The resulting CO_2 was cryogenically purified.

 CO_2 from either sample type was then reduced to graphite with hydrogen over an iron catalyst,

- using methods adapted from Turnbull et al. (2007). The ¹⁴C content was measured using
 accelerator mass spectrometry at GNS Science (Baisden et al., 2013).
- 277

Measurement uncertainty in each sample was derived from three sources: counting error of ¹⁴C 278 279 atoms in the sample, counting error in the standards used for calibration, and additional 280 variability amongst those standards. While counting errors in the measurement process are 281 governed by Poisson statistics, we regard the variability in excess of counting errors as being 282 representative of an additional source of uncertainty in the measurement and/or sample 283 preparation. Since these three error sources are assumed independent, they are added in 284 quadrature. All samples in each experimental dataset (two grass sampling experiments, and one 285 flask experiment) were measured in the same AMS measurement wheel. Therefore, we do not 286 include additional uncertainty due to wheel-to-wheel scatter in secondary standards (Turnbull et al., 2007; Graven et al., 2007). The grass samples were measured to 1,000,000 ¹⁴C counts or 287 288 until the graphite target was exhausted, resulting in overall, single sample precision of 1.1 -289 1.5%. Anticipating large CO₂ff contributions in the flask samples, they were counted to 290 650,000 counts or until the graphite target was exhausted. This, combined with poorer AMS 291 stability during the flask sample wheel measurement (as derived from the scatter of the 292 calibration standards), resulted in overall uncertainties of 2.0 - 2.5%. Between 4 and 10 293 secondary standards were also measured in each wheel, and the scatter of these secondary 294 standards within each wheel is, in all cases, consistent with their assigned uncertainties. 295

296 Results are reported as Δ^{14} C, the deviation of the sample ¹⁴C content from that of the absolute 297 radiocarbon standard, and corrected for radioactive decay since time of collection and 298 normalized to a δ^{13} C of -25‰ (Stuiver and Polach, 1977). CO₂ff is determined from the Δ^{14} C 299 of the grass or flask sample, taking advantage of the fact that CO₂ff contains zero ¹⁴C (Δ^{14} C = -300 1000‰), whereas all other CO₂ sources have Δ^{14} C values close to that of the atmosphere. The 301 CO₂ff added relative to a clean air background measurement can be determined using mass 302 balance (Levin et al., 2003).

303

When the CO_2 content of the observed sample is known, as for our flask samples, CO_2 ff is calculated from

306
$$CO_2 ff = \frac{CO_{2obs} (\Delta_{obs} - \Delta_{bg})}{\Delta_{ff} - \Delta_{bg}} - \beta \text{ (eqn 1)}$$

following equation 3 in Turnbull et al. (2009). CO_2obs is the CO_2 mole fraction in the observed sample, and Δ_{obs} and Δ_{bg} are the $\Delta^{14}C$ of the observed sample and background sample, respectively. Δ_{ff} is the $\Delta^{14}C$ of CO_2ff , and is assigned to be -1000‰. Δ_{bg} for the flask samples was determined from surface flasks collected upwind of the Kapuni plant (figure 1) on the same day, at about the same time of day.

312

 β is a small correction term to account for the fact that the Δ¹⁴C of CO₂ from other sources may be slightly different from that of the atmosphere, and may include contributions from

heterotrophic respiration, oceanic CO_2 sources, and nuclear-industry-produced ¹⁴C. Here, we

sis interorophic respiration, oceanic CO_2 sources, and indefear-industry-produced C. There, we set β to zero, and justify this choice for each possible contribution. The background sample was

- 317 collected close to our observational sampling sites in both space and time, so that at our site a
- few tens of kilometers from the ocean, it is likely that ocean CO₂ exchange has altered Δ^{14} C,

but this alteration occurred in both background and observed samples. There is no nuclearindustry activity in New Zealand and only a handful of reactors elsewhere in the Southern

- 321 Hemisphere (Graven and Gruber, 2011), so we assume there is no nuclear industry bias in our
- 322 samples. Of most importance is the effect of heterotrophic respiration occurring throughout
- the landscape. This is expected to have equally impacted both background and observed Δ^{14} C, and hence the heterotrophic respiration correction is implicitly included in the background.
- 325 We tested how important this assumption might be, using the Biome-BGC model v4.2
- 326 (Thornton et al., 2002; Thornton et al., 2005), calibrated to New Zealand pasture (Baisden and
- 327 Keller, 2013). The Biome-BGC model is an ecosystem process model that simulates the
- biological and physical processes controlling cycles of carbon, nitrogen and water of
 vegetation and soil in terrestrial ecosystems. Important inputs include weather conditions at a
- daily time step and site-specific information such as elevation, soil composition and rooting
- depth. The model has a set of 43 ecological parameters that can be customized for a particular
- 332 ecosystem. In previous work, using pasture clipping data from several sites distributed across
- New Zealand, we adjusted selected model parameters to fit modeled pasture growth to the data to obtain a national model of pasture production for both dairy and sheep/beef pasture at a grid
- scale of ~ 5 km (Keller et al., in review). We ran the dairy model for the grid location that includes the Kapuni processing plant to arrive at an estimate for the respiration CO₂ flux and
- its Δ^{14} C at the sampling sites. We assume a boundary layer flushing time of one day at our site, and using the Biome-BGC estimates, β due to the heterotrophic respiration flux could be 0.2-
- 339 0.4 ppm. This is the maximum bias if the heterotrophic respiration flux occurs at the
- 340 observation site but not in the background, an unlikely scenario.
- 341

342 In the case of the grass samples, the CO₂ content of the sampled air is unknown, so

 CO_2 ff was calculated using the slightly different formulation reported as equation 6 in Turnbull et al. (2009), which requires that the CO₂ of the background air (CO₂bg) be known.

345
$$CO_{2ff} = \frac{CO_{2bg} \left(\Delta_{obs} - \Delta_{bg} \right)}{\Delta_{ff} - \Delta_{obs}} - \beta' \text{ (eqn 2)}$$

346

347 The grass Δ_{bg} values were from samples collected ~20 km to the north of the Kapuni plant in 348 similar dairy farmland, on the same day as the observed samples were collected. The 349 background CO₂ mole fraction was estimated as 390 ppm, from measured values at Baring 350 Head, New Zealand at the same time (Currie et al., 2009; dataset extended to 2012). A 4 ppm 351 error in the choice of CO₂ observed (eqn 1) or background (eqn 2) value equates to a 1% error 352 in the determined CO₂ff mole fraction, small relative to the measurement and atmospheric 353 transport uncertainties. β ' is also a bias correction, formulated slightly differently to β , but 354 accounting for the same biases. We also set this value to zero.

355

A further very small bias is induced by the δ^{13} C normalization in the calculation of Δ^{14} C, since the δ^{13} C of CO₂ff is different from that of the atmosphere (Vogel et al., 2013). In our case, this is of minimal importance, since the CO₂ff from Kapuni is -13.8‰ (measured in our laboratory using CO₂ supplied by the Vector Kapuni plant), quite close to that of the atmosphere. This implies an overestimate of CO₂ff of 1 - 2 %, less than 0.1 ppm for most of our measurements.

- 361 We ignore this bias, as δ^{13} C was not measured on these samples, and in fact, the atmospheric
- δ^{13} C value cannot be easily determined from the grass samples since isotopic fractionation

363 occurs during assimilation of CO_2 into the plant. Note that although ¹⁴C fractionation also 364 occurs during assimilation, this is corrected for mathematically in the $\Delta^{14}C$ notation.

365

366 2.4 Atmospheric transport model

367 WindTrax (Thunder Beach Scientific, Nanaimo, Canada) is a Lagrangian stochastic particle 368 dispersion model, designed for modeling short-range atmospheric dispersion (horizontal 369 distances of less than 1 km from source). The physics is described by Flesch et al. (2004) and 370 Wilson and Sawford (1996). We run the model in forward mode, in which CO₂ff emissions 371 are assumed known and gas concentrations or mole fractions at any given location are 372 unknowns to be determined. We set the model to release 10^5 particles from the simulated stack 373 at every time step, enough to reduce model uncertainty to satisfactory levels (the more particles 374 released, the lower the uncertainty in model predictions). Each particle is transported 375 according to the model physics and specified meteorological conditions. Concentration sensors 376 are placed at the observation locations, and the model outputs a prediction of CO_2 ff mole 377 fraction at each sensor for each time step. The wind speed and direction (along with other 378 atmospheric conditions), combined with the prescribed emission rate, determine the predicted 379 CO₂ff mole fraction at that location and time. We then compare the model prediction with the 380 observed mole fractions. Alternatively, the model can be run in backward mode to predict the 381 emissions from the observed CO₂ff mole fractions, but this is computationally more expensive, 382 and forward mode allows us to also investigate the broader patterns of the predicted plume 383 dispersion. The model is stochastic, not deterministic, so the outcome of model runs will vary 384 even with the same initial conditions and parameters. This is a source of model error that is 385 quantified at each time step. The terrain elevation varies by about 10 m across our sampling 386 area, and this is not accounted for in our model simulations.

387 Daily emissions were provided by the Kapuni plant operator, Vector (P. Stephenson, personal 388 communication). We assume constant emissions for each 24-hour period, although Vector 389 estimates that emission rates may vary by up to 3% during that time. Emission rates were 390 3,100 - 3,750 gC s⁻¹ in the two weeks of August 2012 preceding the day when the first grass samples were collected, 2,700 - 3,500 gC s⁻¹ during the two weeks prior to grass sample 391 collection on October 25, 2012, and 3,200 gCs⁻¹ on October 26, 2012 when the flask samples 392 393 were collected. Emissions are from two stacks, both 35 m high, and ~10 m apart. In the model, 394 we assume that the stacks are close enough in space to be modeled as a single point source. We 395 release the emissions from the known stack height of 35 m above ground level. We also tested 396 an alternative scenario where emissions were released from a height of 45 m above ground 397 level, 10 m higher than the actual stack height, to account for buoyant rise of the warm, 398 moving plume (Briggs, 1975). This value was determined using the known emission 399 temperature (80-85 °C) and stack diameter (0.6 m), and a velocity estimated from the CO₂ 400 emission rate. Under the unstable atmospheric conditions during our measurement campaigns, 401 the difference in effective stack height did not make a significant difference in our results.

For the flask samples, we use a model time step of approximately 10 s, commensurate with the wind data collected from the Helikite at 10 s resolution and fed into the model. We note that previous studies have shown that WindTrax performs best over much longer averaging periods (Flesch et el., 2004), on the order of 10 - 30 minutes, and using the model with very short time intervals (i.e. less than 1 min) is problematic, as the relationships built into the model assume atmospheric equilibrium, which might not be the case at such short time scales. Our results should be interpreted with caution, as they might reflect the inability of the model to resolveatmospheric instability and rapid fluctuations at such fine time scales.

410 In the case of the grass samples, 10-minute time steps were used with wind data from the 411 stationary meteorological station installed close to the site (figure 1). Wind information was 412 not available from the local site for the August grass growth period. Instead, we used the 413 meteorological data obtained for the week directly following the grass sampling. We justify 414 this by comparing data from the two weeks at a long-term station ~ 20 km away in Hawera, 415 which provides hourly temperature and pressure data. This long-term station data could not be 416 used as a proxy for wind speed and direction at our Kapuni site because the particular locations 417 and orientations of the two sites relative to Mt Taranaki result in large differences in wind

418 direction between the two sites. However, we found that the weeks preceding and following

419 our August grass sampling had similar wind patterns at Hawera.

420 In the absence of detailed measurements of turbulence and atmospheric stability, a general

421 stability category was specified in WindTrax using the Pasquill-Gifford classes (Pasquill,

422 1961; Gifford, 1961). The Monin-Obukhov length L (a meteorological measurement of

423 stability) was then calculated by the model along with other related variables. As the

424 measurements necessary for a more exact quantification were not made, we assumed 'slightly

425 unstable' conditions for the flask samples, and 'moderately unstable' conditions for the grass

sampling. The meteorological conditions during the grass sampling periods may more

- 427 correctly match neutral to slightly unstable conditions, but we found that under these
- 428 conditions, the model underestimated the observed plume dispersion. This is discussed further 429 in section 4.2.

430 The model output was sampled at the location and corresponding time step(s) for each sample.

431 As the Helikite moved during the flask filling procedure, the modeled sensor was moved both

horizontally and vertically according to the location obtained from the GPS on the kite. For the

433 simulation with the grass samples, the model was sampled at the GPS location and 1.5m above

ground level to avoid surface effects. We found that grouping several model sensors around the

435 GPS location and then averaging their output was more accurate than using just one. In all 436 results reported for the grass samples, we used four sensors placed at the corners of a square

- 436 results reported for the grass samples, we used four sensors placed at the corners of a square 437 30.5 x 30.5 m, with the actual sample location in the center. The model output was averaged
- 437 50.5 x 50.5 m, with the actual sample location in the center. The model output was averaged 438 over all daytime time steps for the week prior to grass sampling to arrive at a final predicted
- 438 over an daytime time steps for the week prior to grass sampling to arrive at a final predicted 439 CO_2 ff mole fraction.

440 **3 Observational Results**

441 3.1 CO₂ measurements

442 During the Helikite sampling period on October 26^{th} , 2013, the measured CO₂ mole fraction 443 varied from 360 ppm at ground level to 592 ppm in samples within the Kapuni emission plume

- 444 (figures 2 and 3). The emission plume moved during the four-hour sampling period, so that
- 445 our Helikite observed the plume at different locations across the north-south transect at

446 different times. The plume also moved in the vertical, and was more dispersed at some times

- than at others.
- 448
- In figure 3, strong photosynthetic drawdown can be seen in the \sim 7 m above the surface, with CO₂ mole fractions as low as 360 ppm, about 30 ppm of drawdown. Above 7 m, the CO₂

- 451 background can be estimated from the lowest CO_2 mole fractions observed (figure 3). This
- 452 background varied from 390 – 395 ppm with height, and also evolved during the four-hour
- 453 measurement time. CO₂ mole fraction in the upwind surface flask samples (collected three
- 454 meters above ground) varied from 386.3 to 387.4 ppm over the 4 hr measurement period.
- 455

456 We determine the CO₂ enhancement over background (Δ CO₂) in each CRDS or flask sample

457 by subtracting the estimated height-dependent CO_2 background value (figure 3) from the 458 observed CO₂ mole fraction. In this method, uncertainty in the background mole fraction 459 propagates directly to uncertainty in the CO₂ enhancement. The CO₂ measurement uncertainty 460 is small relative to the background uncertainty, so the total uncertainty in the enhancement for 461 this dataset is determined from the range of background CO_2 values, and is ± 15 ppm in the 462 lowest 7 m, and ± 2.5 ppm above 7 m. This level of uncertainty is quite significant for most of 463 the measurements, except those where the enhancements are very large. The median CO_2 mole 464 fraction for samples taken above 7 m was 397 ppm, so that the majority of measurements are 465 difficult to distinguish from the CO₂ background of 390 - 395 ppm.

466

3.2 CO_2 and CO_2 ff from ¹⁴C in flasks 467

CO₂ff in the flask samples ranged from 0.6 to 52 ppm, with one-sigma uncertainties of 1.3 ppm 468 (figure 4). Background Δ^{14} C is not changed by CO₂ drawdown, and hence was less variable 469 than background CO₂. Δ_{bg} varied from 39.2 ± 2.6 to 43.9 ± 2.8 ‰, (using Student's t-test, 470 471 these values do not differ significantly, p = 0.39).

472

We compare the ¹⁴C-derived CO₂ff with Δ CO₂ using the ratio Δ CO₂:CO₂ff (R_{CO2:CO2ff}) (figure 473 474 5). If the CO₂ emitted from the Kapuni plant is entirely fossil-derived, then ΔCO_2 should be 475 equal to CO₂ff, and R_{CO2}·CO₂ff equal to one. We find that for the 15 Helikite samples, R_{CO2}·CO₂ff

476 = 1.3 ± 0.4 ppm/ppm, suggesting that there may be a contribution of non-fossil CO₂ in the 477 Kapuni emission plume. However, when we increase the CO_2 background values by 3 ppm (within the range of background variability), we find $R_{CO2:CO2ff} = 1.0 \pm 0.3$ ppm/ppm (blue 478

479 points in figure 5), indicating that the plume CO_2 is entirely fossil derived. The variability in 480 $R_{CO2,CO2ff}$ is therefore likely predominantly due to uncertainties in determining the flask ΔCO_2 481 and background CO₂, and also to uncertainties in CO₂ff which are important in the lower mole 482 fraction samples. The emitted plume appears to be entirely fossil-derived, within the uncertainties of our measurements.

- 483
- 484

485 3.3 CO₂ff from grass samples

The derived CO₂ff in the grass samples for the two sampling dates of August 14th and October 486 24th, 2012 are shown in figure 6. Grass samples were measured to Δ^{14} C precision of 1.1 to 487 488 1.5 %. This equates to 0.6 to 0.7 ppm uncertainty in CO₂ff.

489

490 CO_2 ff mole fraction derived from the grass samples varies from 0.4 to 3.9 ppm in the August

491 samples, and -0.2 to 17.0 ppm in the October samples. A negative CO₂ff value is non-physical,

492 but -0.2 ppm is within one sigma of zero. The highest CO₂ff values were observed in areas

493 that were most consistently downwind of the plant, and locations closer to the plant typically

494 had higher CO₂ff values (figure 6). In August, the wind direction was somewhat variable,

495 dominantly bringing the plume to the east or south of the plant, but sites to the northwest were

496 also occasionally downwind, resulting in small CO₂ff values at all these locations. In October, 497 the winds were consistently from the west, resulting in larger enhancements to the east of the 498 Kapuni plant than in the August samples, and no CO₂ff detected in the sample to the northwest.

499

500 4 Comparison of observation and model CO₂ff

501 4.1 Kite and surface flask samples

502 The model predicts CO₂ff in the Helikite and surface flask samples of 0 to 19.1 ppm. The 503 model results for the kite samples are generally lower than the observed CO_2 ff (figure 7), 504 except for a few samples where observed CO₂ff was quite small. Other work shows that small 505 errors in the simulated wind direction can result in large errors in the modeled CO₂ff mole 506 fraction for individual samples (Dresser and Huizer, 2011). Thus the model may frequently 507 miss the location of the plume over short time periods of a few minutes when the wind 508 direction is fluctuating rapidly. We deliberately sampled in the center of the plume in the area 509 of highest mole fraction, and the likelihood of modeling this specific point accurately is low 510 given the error inherent in these types of models. The assumption that the time-averaging 511 interval represents an equilibrium state of the atmosphere is built into the model. However, 512 these conditions are most likely not met in our simulations. As mentioned earlier, WindTrax is 513 known to perform poorly at time resolutions of less than about 10 minutes (Flesch et al, 2004). 514 Our results reflect the bias in our sampling method as well as the model error associated with 515 non-equilibrium conditions over very short time-averaging periods. The agreement is much 516 better for the surface flasks, likely because of the longer averaging period of 15 minutes (figure 8).

- 517
- 518
- 519 4.2 Grass samples

520 The modeled CO₂ff values for the grass samples are shown in figure 6 and range from 0.4 to 521 4.9 ppm in the August samples and 0.7 to 17.4 ppm in the October samples. The modeled 522 predictions, like the observations, have the highest CO₂ff values in the dominant wind direction, 523 and samples taken closer to the source have higher modeled CO₂ff (figure 8). However, it can be seen that the model significantly underestimates CO₂ff in a number of the October samples 524 525 collected to the southeast of the Kapuni plant. In August, the samples were collected from 526 sites surrounding the Kapuni plant in all directions, and the wind direction was more variable, 527 whereas in the October case, the wind direction was consistently from the west (figure 6). 528 Discrepancies at the edge of the plume in the October samples suggest the model is not

- 529 sufficiently dispersive in the horizontal.
- 530

531 The model simulations assumed moderately unstable atmospheric conditions. We tested the 532 model with neutral and slightly unstable conditions but found that under these conditions, the 533 model was even less dispersive in the horizontal (results not shown). This was most apparent 534 in the October samples, where the slightly unstable model simulation predicted larger CO₂ff in 535 the samples taken directly west of the plant, but very low CO₂ff in the samples taken to the 536 north and south along the same transect shown in figure 1 and figure 6b. We also tested our 537 choice of effective stack height for the emissions (45 m), but found little change in the modeled 538 results, with a significant change in the modeled result for only one of the sampling locations. There was no change overall in the coefficient of determination (r^2) between model and 539 540 observations.

- 541

542 5 Uncertainty in emissions estimated from comparison of observations and model

- 543 We further quantify the comparison between the model and observations for the surface flasks
- and grass samples and evaluate the model-observation mismatch by determining the ratio $CO_2 ff_{model}: CO_2 ff_{obs} (R_{model:obs})$ for each individual grass sample, and then calculate the mean
- $K_{\text{model:obs}}$ $K_{\text{model:$
- 547 model does a very poor job of simulating the Helikite observed CO₂ff, we exclude these
- 548 samples from this analysis.
- 549

Using all 21 measurements, including the four surface flasks collected on October 26th, 2012, 550 eight grass samples from August 2012, and nine grass samples from October 2012, we find 551 552 good overall agreement between the model and observations ($r^2 = 0.8$, figure 8). The mean $R_{\text{model:obs}} = 0.8 \pm 0.5$. That is, on average, the modeled CO₂ff is 20% lower than the observed 553 554 CO₂ff, but with significant scatter among the individual measurements. Using the August and 555 October grass samples alone, we find $R_{model:obs}$ of 0.8 ± 0.6 . Examining just the August dataset 556 (n=8), we find a less biased but more uncertain agreement between observation and model, 557 with mean $R_{model:obs}$ of 1.0 ± 0.7 . The larger scatter on this dataset is mainly because the CO₂ff 558 values are quite small for this dataset. Looking at the October measurements alone, we find a 559 slightly larger underestimate in the model, with $R_{model:obs} = 0.7 \pm 0.3$. In all cases, the model 560 remains within one sigma of a 1:1 match with observations.

561

562 To infer the uncertainty in emissions from our study, we tested the model response across a wide range of emission rates, and found that it is, as expected, linear. Thus, if model transport 563 564 were correct, we would infer from this that the reported emission rate was too low by 30 % in 565 our worst case for the October grass samples. For this experiment, we assume that the reported 566 emissions from the Kapuni plant are correct, and therefore, any differences between the 567 modeled and observed CO₂ff mole fractions must be due to uncertainties in our methods and 568 modeling. Thus we estimate, from our worst case model-observation mismatch that the 569 uncertainty in emissions from our grass sample pilot study is 30 % or better.

570

571 6 Discussion and Recommendations

572 In this pilot study, we found that atmospheric ¹⁴C measurements of ~1 week integrated samples 573 could be used to estimate CO_2 ff emissions from a point source to 30 % or better. This 574 uncertainty estimate is derived from the comparison of our top-down observations with 575 forward modeling, so incorporates all sources of error, including model transport errors, 576 sampling biases and measurement uncertainties. We now consider those various sources of 577 error, the practicalities of field measurements, and outline some improvements that could 578 substantially improve the method and reduce uncertainties in the near future.

579

580 Large CO₂ff mole fractions were observed in the "snapshot" Helikite samples collected over a 581 few minutes, but the WindTrax model was unable to accurately predict the high observed 582 CO₂ff mole fractions. Conversely, the model was quite skillful in predicting the observed 583 CO₂ff mole fractions in the long-term averaged grass samples and in 15 minute averaged 584 surface flasks. The model performed best in capturing the broad spatial pattern of emissions 585 around the Kapuni plant as shown in the August sampling pattern. The model was less skillful 586 at capturing the somewhat finer-scale pattern of the October grass samples, which were 587 predominantly sampled in the same sector. This result is consistent with findings from other 588 studies (e.g. Dresser and Huizer, 2011) that show that small errors in model transport of point

589 source emissions can result in the emission plume being incorrectly located. Averaging the 590 model results over time can reduce the impact of these errors. This conclusion is likely broadly 591 applicable to local scale plume dispersion models such as WindTrax, as well as to regional 592 scale Lagrangian models. The model skill will likely also be improved by more detailed 593 meteorological measurements, including estimates of boundary layer turbulence and 594 to be in the lifety of the second seco

atmospheric stability.

595

596 We found the long-term averaged grass sampling better suited to the model skill than the 597 snapshot Helikite flask samples. Grass sampling is also far cheaper and easier than flask 598 sampling, particularly from an elevated platform such as the Helikite. Flask sampling requires 599 flasks and the equipment to fill them, which may run to many thousands of dollars per 600 sampling system. Elevated platforms such as the Helikite, as well as aircraft and unmanned 601 aerial vehicles can also be expensive, can only operate under specific meteorological 602 conditions and may be subject to air traffic regulations. In contrast, plant sampling can be 603 done simply and quickly using only a few plastic bags and a handheld GPS to record locations. 604 Whereas flask samples may be limited in size by the practicalities of flask volumes and 605 pumping rates, large plant material samples can be collected to facilitate replicate measurements if required. Plant sampling is also less intrusive and less visible to the power 606 607 plant operators and the public, which may be advantageous in some situations. The laboratory 608 ¹⁴C preparation, while slightly different for each sample type, is of similar complexity and cost. 609 However, plant sampling may suffer biases that cannot be easily quantified. The particular 610 environment at our Kapuni site is conducive to the grass sampling method, with rapid grass 611 growth and regular grazing to consistently remove old growth before flowering. Biases in the Δ^{14} C of grass or other plant material due to the details of plant CO₂ assimilation through time 612 613 may make this method challenging in other locations. In future work, we will examine 614 alternative integrated sampling techniques such as NaOH absorption that provide a similar 615 integration period, but allow more control over when CO₂ is collected. This type of sampler 616 would require more complex field sampling than plant material, but could still be relatively easily deployed in the field, allows collection of large amounts of CO₂, and laboratory methods 617 618 are well-established.

619

Uncertainties in observed CO₂ff for the grass samples come from the ¹⁴C measurement 620 uncertainty, uncertainties in the CO₂ assimilation period represented by the grass sample, and 621 from the choice of background. Large gains in ¹⁴C measurement uncertainty are unlikely in the 622 623 near future, but the impact of measurement uncertainties could be reduced by measuring 624 multiple aliquots of each sample, or preferably by collecting and measuring more samples at 625 higher spatial and temporal resolutions to obtain a greater data resolution for the model – 626 observation comparison. As already discussed, uncertainties in the CO₂ assimilation period 627 could be reduced by using an alternative integrated sampling technique such as NaOH 628 absorption. We prepared and measured an individual grass leaf from each sample, but 629 homogenizing and measuring a mixture of several leaves, possibly from several grass plants, 630 might give a more representative sample. There is also potential for bias in observed CO₂ff 631 from the choice of background. We used a single background measurement for each dataset, and any bias in that background will result in a consistent bias in R_{model:obs} calculated for each 632 633 sample. Making several background measurements would reduce background uncertainty and 634 bias.

- 635
- 636 The Kapuni plant emissions are quite small (two orders of magnitude) relative to many fossil
- 637 fuel power plants around the world. Larger point sources will produce larger observed CO₂ff
- mole fractions, and hence relatively smaller measurement uncertainties. However, many large
- 639 power plants will have much higher stack emission heights of 100 to 800 m, and plume
- buoyancy due to hot emissions might raise the effective emission height even further.
- 641 Therefore surface or near-surface measurements might need to be made further downwind to 642 observe the plume. At these larger distances from the source, the plume will be more dispersed
- 642 observe the plume. At these larger distances from the source, the plume will be more dispersed 643 and hence observed CO₂ff mole fractions will be reduced, likely to similar magnitude to those
- 644 we observed at Kapuni. A further modeling consideration is that in this study we used only
- 645 daytime measurements. It is well-known that atmospheric transport models perform best in the
- 646 mid-afternoon when the boundary layer is well-mixed, but have difficulty in accurately
- 647 representing the nocturnal boundary layer. Thus most researchers utilize only daytime
- 648 measurements. This represents an unresolved difficulty in assessing overall emissions for
- 649 power plants, which may have significant diurnal variability in their emission rates.
- 650

We deliberately selected a location with reasonably flat terrain where atmospheric transport is straightforward. More complex terrain will make the transport modeling more difficult and will require additional care in selection of optimal sampling locations and times. Extending this work to sites with multiple emission sources will also complicate interpretation.

655

From this pilot experiment, we believe that it is realistic to substantially reduce the uncertainty in atmospheric determination of point source CO_2 ff emissions in the near future. A goal of 10-20% overall uncertainty appears realistic.

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- 671

672 8 Figure captions

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- Figure 1. Map showing location of Kapuni processing plant and kite sampling locations.
- Figure 2. Measured CO_2 mole fraction across transect from south to north. Large black circles indicate the flask sampling locations.
- Figure 3. Measured CO_2 mole fraction as a function of altitude. Colours indicate the time of day.
- 681
- 682 Figure 4. CO_2 ff calculated from flask samples from the Helikite and surface flasks on October 683 26^{th} , 2013.
- 684
- Figure 5. R_{CO2:CO2ff} in each flask sample. Blue points use the assigned CO₂ background values,
 red points apply a 3 ppm bias to the CO₂ background values in calculating R_{CO2:CO2ff}.
- 687

688 Figure 6. CO₂ff in grass samples collected on August 14th, 2012 (top) and October 24th, 2012

(bottom). The observed CO₂ff derived from Δ^{14} C is shown in yellow, and the modeled CO₂ff

690 prediction is shown in white. Markers indicate the exact sampling location. A wind rose

showing the direction of the wind patterns over the previous one-week period is inset (bars

indicate the direction the wind is traveling to). In the lower panel the point indicated with the

- arrow was measured 500 m to the north-west, off the map.
- 694

Figure 7. Observed CO_2 ff versus modeled CO_2 ff for the kite (red) and surface (grey) flask samples. Error bars are omitted for clarity.

697

698 Figure 8. Comparison of observed and modeled CO₂ff from the August (red) and October

(blue) grass samples, and October 26^{th} surface flasks (grey). The 1:1 line is shown in black.

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Figures



Figure 1. Map showing location of Kapuni processing plant and kite sampling locations.



Figure 2. Measured CO_2 mole fraction across transect from south to north. Large black circles indicate the flask sampling locations.



Figure 3. Measured CO_2 mole fraction as a function of altitude. Colours indicate the time of day.



Figure 4. CO_2 ff calculated from flask samples from the Helikite and surface flasks on October 26th, 2013.



Figure 5. $R_{CO2:CO2ff}$ in each flask sample. Blue points use the assigned CO_2 background values, red points apply a 3 ppm bias to the CO_2 background values in calculating $R_{CO2:CO2ff}$.



Figure 6. CO_2 ff in grass samples collected on August 14th, 2012 (top) and October 24th, 2012 (bottom). The observed CO_2 ff derived from $\Delta^{14}C$ is shown in yellow, and the modeled CO_2 ff prediction is shown in white. Markers indicate the exact sampling location. A wind rose showing the direction of the wind patterns over the previous one week period is inset (bars indicate the direction the wind is traveling to). In the lower panel the point indicated with the arrow was measured 500 m to the north-west, off the map.



Figure 7. Observed CO_2 ff versus modeled CO_2 ff for the kite (red) and surface (grey) flask samples. Error bars are omitted for clarity.



Figure 8. Comparison of observed and modeled CO_2 ff from the August (red) and October (blue) grass samples, and October 26th surface flasks (grey). The 1:1 line is shown in black.