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**Global ozone  
monitoring by  
occultation of stars**

J. L. Bertaux et al.

# Global ozone monitoring by occultation of stars: an overview of GOMOS measurements on ENVISAT

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## Abstract

GOMOS on ENVISAT (launched in February, 2002) is the first space instrument dedicated to the study of the atmosphere of the Earth by the technique of stellar occultations (Global Ozone Monitoring by Occultation of Stars). From a polar orbit, it allows to have a good latitude coverage. Because it is self-calibrated, it is particularly well adapted to the long time trend monitoring of stratospheric species. With 4 spectrometers the wavelength coverage of 248 nm to 942 nm allows to monitor ozone, H<sub>2</sub>O, NO<sub>2</sub>, NO<sub>3</sub>, air, aerosols, and O<sub>2</sub>. Two additional fast photometers (1 kHz sampling rate) allow for the correction of scintillations, as well as the study of the structure of air density irregularities, resulting from gravity waves and turbulence. A high vertical resolution profile of the temperature may also be obtained from the time delay between the red and the blue photometer. Noctilucent clouds (Polar Mesospheric Clouds, PMC), are routinely observed in both polar summers, and global observations of OCLO and sodium are achieved.

The instrument configuration, dictated by the scientific objectives rationale and technical constraints, are described, together with the typical operations along one orbit, and statistics over 5 years of operation. Typical atmospheric transmission spectra are presented, and some retrieval difficulties are discussed, in particular for O<sub>2</sub> and H<sub>2</sub>O.

An overview of a number of scientific results is presented, already published or found in more details as companion papers in the same ACP GOMOS special issue. This paper is particularly intended to provide the incentive for GOMOS data exploitation, available to the whole scientific community in the ESA data archive, and to help the GOMOS data users to better understand the instrument, its capabilities and the quality of its measurements, for an optimized scientific return.

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## 1 Introduction

GOMOS (Global Ozone Monitoring by Occultation of Stars) is the first space instrument specially designed and dedicated to the study of the atmosphere of the Earth by the technique of stellar occultations. It is placed on board the 8.2 tons ENVISAT space platform (ENVironmental SATellite) from European Space Agency (ESA), among nine other Earth Observations instruments. Together with two other instruments (MIPAS, Michelson Interferometer for Passive Atmospheric Sounding, Fischer et al., 2008, and SCIAMACHY, Scanning Imaging Absorption Spectrometer for Atmospheric Chartography, Bovensmann et al., 1999), GOMOS forms a trio of european instruments fully dedicated to the study of atmospheric chemistry. One role of this trio is to collect the corpus of ozone data (and other atmospheric parameters) necessary to answer the following questions:

- what is the time evolution of ozone in the stratosphere (the trend) all over the world?
- what is the effect of CFCs release limitations?
- is the measured ozone trend equal to the trend predicted by our best simulation model predictions?
- if not, is there anything in the data that can indicate where are the shortcomings of our models and how can they be improved for more reliable predictions?

Among the three instruments devoted to atmospheric chemistry, the particular role of GOMOS is to establish the 3-D distribution of ozone in the stratosphere and to monitor its trend as a function of altitude, thanks to the particularly high absolute accuracy offered by the technique of occultation of stars, which is also rather immune to the evolution of calibration parameters.

ENVISAT was launched from French Guiana (Kourou) on 28 February 2002, and placed on a circular orbit 800 km altitude, almost polar ( $98.55^\circ$  inclination), helio-synchronous with descending node at 10:00 a.m. Local Time, and period 100 mn. The first stellar occultation with GOMOS was performed in March 2002, and since then GOMOS has worked almost continuously (with a few gaps that will be discussed later).

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By June 2009, more than 600 000 occultations were collected, to obtain the same number of vertical profiles all over the globe of ozone, NO<sub>2</sub>, NO<sub>3</sub>, H<sub>2</sub>O, air, aerosols, O<sub>2</sub>, temperature and turbulence parameters .

GOMOS was first proposed by a group of european scientists (Bertaux et al., 1988), in response to the Announcement of Opportunity for the Polar Platform issued by ESA for earth observation instrumentation. After peer review, GOMOS was selected together with MIPAS and SCIAMACHY, marking the European will to initiate a major effort in atmospheric research, in the aftermath of the antarctic ozone hole discovery. An industrial Phase A study was conducted by Matra Marconi Space for CNES (Centre National d'Etudes Spatiales) in 1989–1990. Then it was decided at the ESA countries minister conference of Madrid in 1992 that GOMOS would fly on ENVISAT platform as an ESA funded instrument. The GOMOS instrument was developed for ESA by an industrial consortium lead by Astrium Toulouse (now a part of EADS Astrium). ESA formed a Scientific Advisory Group (SAG) composed of scientist of various European countries, to provide advice on the performance requirements of the instrument, and to develop the principles of the data inversion and retrieval algorithms.

GOMOS is the first space instrument specially designed and built to perform atmospheric measurements by stellar occultations: the UVISI instrument (Ultraviolet and Visible Imagers and Spectrometers) on the Midcourse Space Experiment (MSX), which already provided very interesting results with this technique (Yee et al., 2002), was not designed for this purpose, and required that the full 6 tons spacecraft be oriented to the star, while GOMOS has a moving mirror which is oriented successively to the various stars to be occulted, without perturbing the other Earth Observations instruments. The general principle of stellar occultation method is illustrated in Fig. 1, and is described below, with the particular case of GOMOS.

ENVISAT is 3 axis stabilized, nadir pointing, with a yaw steering law to compensate for Earth rotation and push-broom instruments. GOMOS is implemented on the nadir face of ENVISAT, looking backwards (opposite to the velocity vector) allowing to track near the horizon the successive setting down of various stars while the ENVISAT

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platform is moving along its orbit. When the star is high above the horizon (typically  $z > 110$  km), the light spectrum of the star  $S_o(\lambda)$  is recorded by GOMOS, free of any atmospheric absorption. A few seconds later, the light spectrum of the same star seen through the atmosphere (just above the horizon) is again recorded. The spectrum  $S(\lambda, z)$  is modified by the absorption of all atmospheric constituents integrated over the line of sight from ENVISAT to the star, according to the Beer-Lambert law:

$$S(\lambda, z) = S_o(\lambda) \exp(-\sigma_\lambda N(z)) \quad (1)$$

where  $\lambda$  is the wavelength,  $z$  is the minimum altitude of the line of sight above the horizon (tangent height, or tangent altitude),  $N(z)$  ( $\text{mol}/\text{cm}^2$ ) is the integrated quantity of ozone along the line of sight (slant density) and  $\sigma_\lambda$  the absorption cross section of ozone. Here, only ozone absorption is considered for clarity.

From Eq. (1) one derives:

$$N(z) = -\frac{1}{\sigma_\lambda} \text{Log} \frac{S(\lambda, z)}{S_o(\lambda)} \quad (2)$$

During one single occultation, a series of tangential column (slant, or line) densities  $N(z_j)$  are obtained at various altitudes  $z_j$ . This series can be inverted (vertical inversion) to yield the vertical distribution of the local density  $n(z)$  of  $\text{O}_3$  ( $\text{mol cm}^{-3}$ ), assuming that the atmosphere is locally spherically symmetric. This vertical inversion is (in principle) straightforward with the so-called onion-peeling technique. Some care must be taken during the vertical inversion, in order to avoid strong spurious oscillations in the vertical profile  $n(z)$ , as described in Kyrölä et al. (2010).

Besides the extreme simplicity of the retrieval algorithm when compared to other methods, the occultation technique has one enormous advantage readily expressed from the mathematical form of Eq. (2): an absolute estimate of  $N(z)$  is obtained from the ratio of two measurements taken with the same instrument at a few seconds of interval. The method is inherently self-calibrated, and even if the spectral sensitivity of the instrument is changing with time, the ratio will be measured correctly and hence the

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slant density  $N(z)$  (sometimes called also line densities, in short for “density integrated along the Line of Sight LOS”, or slant densities). This protection against long-term drift is of course ideal for the study of trends of ozone and other constituents. The primary measurement of GOMOS is this ratio, which is the spectral transmission of the atmosphere as a function of the tangent height of the line of sight. It is the main data in the Level 2 data product of GOMOS.

In principle, one could use a detector for only one single wavelength  $\lambda$  if ozone were the only absorbing species at this wavelength. This is not the case, in the UV-Visible-NIR region which may be accessed with CCD silicon detectors, as shown on Fig. 2 which displays the cross section of a number of atmospheric constituents. Therefore, in order to properly identify each of the atmospheric absorbers separately, one has to measure in a wide wavelength domain with a sufficient spectral resolution. Equation (1) is modified as follows:

$$S(\lambda, z) = S_o(\lambda) \exp(-\sum \sigma_i(\lambda) N_i(z)) \quad (3)$$

where  $\sigma_i(\lambda)$  and  $N_i$  are respectively the cross section and the line density of each constituent  $i$ . Therefore, before the vertical inversion the first step of the Level 2 processing will be the retrieval of each quantity  $N_i(z)$  for each measured altitude. One needs to measure at least as many different wavelengths as the number of constituents. Since the quantum efficiency of Silicon matches nicely the wavelength domain where ozone is absorbing (a consideration which dictated the choice of these detectors for GOMOS), we decided to cover a large range of the UV-visible part of the spectrum with a continuous coverage and many spectral pixels, and a least square model fit to the measured transmission at each altitude allows to retrieve simultaneously all the  $N_i(z)$  for this altitude: this is the so-called *spectral inversion*, or separation of constituents (Kyrölä et al., 2010). Then, the vertical inversion is performed separately for each constituent. Within the spectral range of GOMOS (Fig. 4, Table 1),  $O_3$ ,  $NO_2$ ,  $NO_3$ ,  $OCIO$ , air,  $O_2$ ,  $H_2O$ , and aerosols may be measured as a function of altitude. Except aerosols (and air Rayleigh extinction), all these chemical species absorbers have a well defined absorption spec-

tral signature, which makes easier its disentangling from the combined spectrum of the atmospheric transmission (Figs. 2 and 12).

Another important feature of stellar occultations is that the altitude of the measurement is entirely defined by the direction of the star and by the position of the spacecraft. ENVISAT position is known with an accuracy better than  $\pm 30$  m, ensuring the same accuracy on the knowledge of  $z$ . The altitude accuracy is important, because an error of 100 m would result in a 2% error in ozone density estimate in the altitude region above the peak of ozone where there is a strong vertical gradient. At variance with other limb emission techniques, the altitude of the measurement does not depend on the attitude of the spacecraft and instrument, therefore protecting from long term drift of the accurate attitude knowledge (1 arcsec is projected at the distance of the limb,  $\sim 3400$  km, as  $\Delta z = 20$  m). The vertical resolution is determined by the time of integration and the vertical velocity of the tangent point, which for GOMOS are 0.5 s. and 3.4 km/s (maximum), resulting in a typical vertical sampling resolution of 1.7 km at most, and less for stars occulted away from the orbital plane. In addition, at lower altitudes where refraction is significant, the vertical velocity is smaller (sampling is higher); but the light path to the star is no longer a straight line, and the exact altitude probed by the ray path depends on the atmospheric air density profile.

The solar occultation technique shares in common with stellar occultations the fact that an absolute quantity is derived from a relative measurement. The Sage-II and POAM instrument have been very successful for Earth's atmosphere research, and much of what we know at present about the ozone trend as a function of altitude comes from the comparison of Sage-II results on a long timescale. The use of stars by GOMOS instead of the sun has some additional favorable features:

- the many wavelengths that are used by GOMOS (instead of 7 or 9 discrete channels for Sage-II and POAM) allows a much safer identification of all absorbers. We note that the more recent version SAGE-III flying since February 2002 (Thomason and Taha, 2003) contains many more spectral channels than its predecessors SAM II, SAGE and SAGE-II, all dedicated to solar occultation probing of the at-

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mosphere.

- the altitude knowledge of the measurement is almost perfect, while for the solar disk extended source, the pointing of the instrument must be known accurately, and preferably the same portion of the sun must always be observed during the occultation ( the disk brightness is not uniform, especially in the UV).
- the solar occultation occurs at dawn or dusk local time, when the photo-chemistry regime of the atmosphere is changing rapidly (even along the LOS), while the LOS to a star pertains generally to a well defined regime (day or night).
- From the sun-synchronous orbit of ENVISAT, only a limited range of latitudes (around high latitudes) are accessible for solar occultations, while stars allow to observe at all latitudes.

There are some drawbacks with the use of stars: they are weak sources, requiring more photon collecting areas. They have different brightness and spectra, which makes the error bar to vary with the magnitude of the star. They are not evenly distributed in the sky, and the sampling of the atmosphere is not as regular as the sampling of emission-looking instruments (like MIPAS and SCIAMACHY, for example). Night side measurements are preferred, because on the day side, the bright limb intensity is competing with the stellar flux. Nevertheless, the inherent advantages of the stellar occultation method are overcoming these drawbacks by a large margin for the study of trends.

During the commissioning phase of the instrument and the data processing software, two unanticipated problems were encountered, which complicated somewhat the data retrieval scheme and the operations of GOMOS. One is related to the CCDs Dark Current (DC) behaviour, which increased significantly under the influence of energetic protons, and moreover showed a variable behaviour (known as Random Telegraphic Signal, RTS). This phenomenon annihilated completely the advantages of the so-called MPP technology fostered by CCD provider EEV company, which in principle should

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have made possible the use of CCDs at room temperature. Counter measures were taken, by setting the CCDs at the lowest possible temperature of + 3 °C allowed by the GOMOS thermal control system, and by collecting at each orbit a measurement of the DC of all pixels, with a deep space observation (no star, in the middle of the night, near equator crossing).

The other problem is related to scintillations of the star, due to small scale vertical temperature fluctuations of the atmosphere, and associated turbulence. The proposing team (Bertaux et al., 1988) anticipated that the shape of the spectrum of the star would be somewhat affected by scintillations because of the chromatic character of refraction, but thought that this effect could be corrected with the signal of two fast photometers (1 kHz sampling) recorded simultaneously. It was discovered from GOMOS data that this is perfectly true when the star setting is observed near the orbital plane (because the line of sight stays in the same vertical plane, the orbital plane, and probes the same atmosphere at all wavelengths), but does not hold any longer with an oblique occultation, revealing the existence of isotropic turbulence (Daladier et al., 2001; Sofieva et al., 2009b). This new effect decreases a bit the ozone retrieval accuracy mainly in the altitude region 20 to 40 km for the brightest stars, and forced us to modify the baseline spectral inversion scheme (defined pre-launch) for NO<sub>2</sub> and NO<sub>3</sub>, in the direction of a modified DOAS (Differential Optical Absorption Spectroscopy) for NO<sub>2</sub> and NO<sub>3</sub> (see Sect. 5.3.3).

In spite of these unexpected difficulties, the excellent quality of the GOMOS results makes us still believe that the stellar occultation technique is the best method to achieve the high accuracy of ozone measurements which is necessary to detect small time variations of ozone. It should be mentioned that not only ozone local densities may be monitored for trends, but also the slant densities  $N(z)$  of ozone (and other constituents) are archived and available for trend studies. Also, the transmission of the atmosphere can be monitored as such; and after all, it is the UV transmission of the stratosphere which has the greatest impact on living matter on Earth.

The GOMOS data is made available by ESA to the whole scientific community. The

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goal of this paper is to provide a rather detailed and comprehensive overview of the GOMOS capabilities and the scientific questions that may be addressed, based on the presentation and discussion of some typical results, obtained after 7 years of operation, and some improvements in the retrieval algorithms. Another goal is to encourage the community to extract interesting results from the GOMOS data, which are freely available through the ESA distribution system.

In Appendix A is presented a brief history of the technique of stellar occultation, with a possible explanation why some strange results were found for ozone during early attempts with astronomical satellites OAO-2 and Copernicus in the middle 70's.

An early estimate of GOMOS ozone trend performance may be found in Bertaux et al. (1991), while the previous most comprehensive description of the GOMOS instrument and its science objectives may be found in the report of the ESA formed Scientific Advisory Group (SAG) for GOMOS, written before launch, and summarizing about 10 years of activity of this group for the preparation of the GOMOS investigation. (Bertaux et al., 2001, SAG Report ESA SP-1244). What is added in the present paper are actual in-flight performances, observations and a brief overview of scientific results.

This paper is one of a series of 12 papers proposed to Atmospheric Chemistry and Physics, to form a GOMOS Special Issue of ACP. Other papers of this special issue are covering various subjects: the retrieval algorithms (Kyröla et al., 2010a), the data characterization and error estimation (Tamminen et al., 2010), the influence of scintillations on GOMOS ozone retrieval (Sofieva et al., 2009), ozone, NO<sub>2</sub> and NO<sub>3</sub> measurements in the stratosphere and mesosphere (Kyröla et al., 2010b), the influence of QBO on tropical ozone, NO<sub>2</sub> and NO<sub>3</sub> as a function of altitude (Hauchecorne et al., 2010), a climatology of the Tertiary Ozone Maximum (Sofieva et al., 2009), Polar Mesospheric Clouds (PMCs, Pérot et al., 2010), aerosols (Vanhellemont et al., 2010), simultaneous measurements of OCIO, NO<sub>2</sub> and O<sub>3</sub> in the Arctic polar vortex (Tétard et al., 2010), a climatology of mesospheric sodium (Fussen et al., 2010), and a comparison of GOMOS ozone retrieval with some ground based measurements (Keckhut et al., 2010).

The rest of the paper is organized as follows. The next section describes how the

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GOMOS science objectives were turned into Instrument requirements. Section 3 contains a description of the instrument, of the operations and coverage, together with a sample of typical observations results: star spectra, transmission spectra, and scintillations. Section 4 describes some problems encountered during the GOMOS mission, while the retrieval algorithms and error estimates are described in Sect. 5. Section 6 presents some validation results of GOMOS products. Section 7 contains an overview of GOMOS results obtained up to now (ozone, NO<sub>2</sub>, NO<sub>3</sub>, OCIO, aerosols, gravity waves and isotropic turbulence, sodium, PMCs), and difficulties associated to O<sub>2</sub> and H<sub>2</sub>O observations. After a short conclusion, calling for a continuation of the GOMOS mission on smaller free flyers, is an Appendix containing a short history of the technique of stellar occultation for probing planetary atmospheres.

## 2 GOMOS science objectives and instrument requirements

### 2.1 Overview

In this section we describe the rationale for the instrument configuration of GOMOS, which is a mixture of scientific reasons and technological constraints considerations. The main objective of long term monitoring of ozone calls for most accurate measurements of ozone, and is the driving factor of the whole specification of GOMOS. The very large variation of the ozone cross section over the UV-visible domain (Fig. 2) offers then a huge dynamic range for the measurement of the slant density of ozone, extending from the tropopause up to the upper mesosphere, at  $z > 100$  km. The strong cross section in the UV, and its reasonable cross-section in the visible (Chappuis bands, quite extended in wavelength) matches very well the sensitivity of silicon CCDs. This defined the spectral range of the main spectrometer A of GOMOS: the shortest wavelength at 248 nm below the maximum cross section of ozone in the UV (255 nm), and the longest wavelength going as far as possible in the visible Chappuis band, still compatible with the design of a single spherical holographic grating. The longest wavelength is there-

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fore at 690 nm. However, since the CCD sensitivity in the UV needs a special treatment which does not favour the sensitivity in the visible, the whole UV-visible domain was split in two parts, impinging on two different CCDs, one having the UV enhancement treatment and covering the domain 248 to 389 nm (CCD A1), the visible CCD covering from 389 nm to 690 nm (CCD A2).

The desired spectral resolution was dictated by two different considerations. On one hand, the Huggins bands at 315–350 nm are highly structured, and the cross section there depends strongly on the temperature (Fig. 3). If the spectral resolution would not permit to resolve these bands, then a minute (and undetected) long term temperature trend would affect the cross-section there, inducing a spurious ozone trend. On the other hand, it was desirable to have a relatively good resolution in order to detect the trend of any other absorber, known or unknown, with a sharp spectral signature somewhere in the ozone band, that could also affect the trend of retrieved ozone. All in all, the sampling of spectrometer A is of 0.312 nm per pixel, and the resolution is 0.8 nm at FWHM.

Within the sensitivity range of silicon CCDs, it was noticed that O<sub>2</sub> and H<sub>2</sub>O have strong absorption bands, and their relevance to the ozone problem justified the inclusion of Spectrometer B, also divided in CCD B1 for O<sub>2</sub> at 760 nm and CCD B2 at 936 nm (see later in this section), with a sampling of 0.047 (0.056) nm and a resolution of 0.13 nm respectively for B1 and B2 (Table 1).

When the stellar light propagates through the atmosphere, it is affected by refraction and by extinction (pure absorption + scattering). It is a usual practice to distinguish these two effects, since refraction will affect mainly the direction of propagation and the global intensity, while extinction will mainly affect the shape of the remaining spectrum (in addition to the intensity). Some authors have classified the occultations as *refractive* or *absorptive* (Smith and Hunten, 1990; Yee et al., 2002). Unfortunately the two effects are present together, because the index of refraction depends on the wavelength, and it was recognized right from the beginning by the GOMOS proposers that scintillations (a refractive effect) would modify the spectrum of the star seen through the atmosphere,

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a detrimental effect to the accuracy of the ozone retrieval. Two fast photometers (1 kHz sampling) are included in GOMOS, which help to correct the effect of scintillations.

Given this instrument set up measuring  $O_3$ ,  $O_2$ , and  $H_2O$ , it was also clear right from the beginning that additional measurements (besides ozone) could be made with GOMOS, some directly relevant to the ozone problem, and some others less directly related: the vertical distribution of  $NO_2$ ,  $NO_3$ , aerosols, air, temperature, and turbulence parameters. The theoretical interest of the various species is discussed below, while actual GOMOS results are briefly overviewed in Sect. 7.

## 2.2 Ozone

A transmission measurement is known to achieve its best accuracy around optical thickness 1. Because of the large dynamic range of the ozone absorbing cross-section extending from the UV to the visible (Fig. 2), it offers the opportunity to probe the whole atmosphere from mesosphere down to the upper troposphere (when there is still enough signal, Fig. 14). Obviously, the mesospheric ozone layer is probed around 250 nm, where the ozone cross-section is at its peak, while at lower altitudes there is no more UV light transmitted, and Chappuis band is used to determine the slant density of ozone. GOMOS is providing routinely hundreds of vertical profiles per day of unprecedented accuracy spread all over the globe, providing data to construct 3-D maps of ozone from the tropopause to the mesosphere.

In Sect. 7 is presented a short overview of what has been done on ozone with GOMOS (including papers of the GOMOS ACPD special issue). Here we discuss in more general terms several lines of research on ozone that may be performed with GOMOS.

*Climatology of ozone:* A study of all the data acquired in 2003 allowed to determine a new climatology of ozone (Kyrölä et al. 2006), superseding the previous Fortuyn and Kelder (1998) climatology, with an average value, and also an estimate of the natural variability of ozone as a function of altitude, season and latitude.

*The understanding of photo-chemistry:* In the upper stratosphere region (say, 35–50 km), ozone is in photochemical equilibrium: the chemical lifetime of  $O_3$  (actually,

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$O_x = O + O_3$ ) is only  $10^4$  s (Brasseur and Solomon, 1984). It is therefore an important region, where the comparison of actually measured ozone density may be compared to the predictions of Chemistry Transport Model (CTM), in order to detect potential deficiencies in the chemistry prescribed in the models. Marchand et al. (2004, 2007) have done such a type of exercise, as summarized in Sect. 7, resulting in a suggestion of a significant revision of the temperature dependence of one constant, of the reaction between ozone and  $NO_2$ .

*The study of time series and trends:* Though models are predicting that it will take several tens of years for ozone to recover pre-CFCs values, it is important to monitor precisely its behavior, as a function of altitude and latitude. An estimate of the GOMOS ozone trend capabilities was made (Bertaux et al., 1991) by analogy with an earlier computation made by Frederick (1984). Frederick addressed the problem of the detection of ozone trend from one single ground station, performing measurements at regular intervals  $\Delta t$ , sufficiently large that two consecutive measurements are completely decorrelated. Annual, semi-annual and quasi-biennial variations are assumed to be regressed.

The actual GOMOS geographical coverage (see next section) is such that, with a particular star covering a circle of constant latitude, the measurement point comes back almost to the same longitude after 3 days (the duration of orbit of 100 mn corresponds to  $14 + 11/35$  orbit per day), which is about the decorrelation time observed for ozone over a particular ground station (2 to 3 days). Therefore, we may consider that all (or most) GOMOS ozone vertical profiles are indeed decorrelated.

Considering the case of 9 latitudes bands of  $20^\circ$  each, Bertaux et al. (1991) found that the smallest ozone trend detectable by GOMOS would be 0.05 % per year, assuming a precision of  $\approx 5\%$ , and a natural variability of 4% at a given altitude (say, between 20 and 40 km). Indeed, the achieved precision is better than 5% on most stars observed, but the natural variability of ozone (at each altitude, season, latitude) was not well documented and this is what can be achieved with GOMOS. Its accurate determination requires that the accuracy on a single measurement be smaller than the natural

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variability. The actual accuracy achieved by GOMOS is discussed in a later section; bright stars are preferred to do this exercise, which yield in principle an accuracy better than 1–2% .

It must be noted however that the above formulation to derive a linear trend assumes that all time variations are periodic and may be regressed. It is possibly not the case in reality, if volcanoes, solar activity or other sporadic factors are playing also a role in the ozone budget. For instance, the influence of Quasi Biennial Oscillation (QBO) on ozone depends on altitude. Hauchecorne et al. (2010) found three different regions with different influences. Also, the period of QBO is not fixed, and regression may be inaccurate. Therefore, the very concept of linear trend must be manipulated with caution. What remains true is that time variations of ozone are monitored with an unprecedented accuracy with GOMOS. In a companion paper of this ACP special issue, Kyrölä et al. (2010) are showing some examples of time series of ozone at various altitudes. Above 20 km in the stratosphere, the median variability is found to be 5.5%, while the median of the retrieval error is 0.6% (to be compared to the assumed above mean values of 4% and 5% respectively, to estimate the accuracy on the trend).

Finally, it can be remarked that a higher precision on slant densities is obtained than on local densities, and all these primary data are also available in Level 2 products for trend studies.

*Ozone as a tracer of dynamics:* Ozone has a long lifetime below 30 km, and geographical variations of ozone density can be used as a tracer of winds in the stratosphere. Therefore, there is an interest to assimilate ozone densities at altitudes lower than 30 km in GCM meteorological models. Of course, Near Real Time products are needed for such a purpose; ESA delivery of GOMOS ozone data within 3 h of collection through the Ground Segment system implemented by ESA. However, it is not yet assimilated routinely in GCM models.

*Day side measurements of ozone.* For a complete description of the ozone field, it was felt necessary to characterize accurately the diurnal variation of ozone. Its amplitude increases from a few percent at 50 km to 80% at 70 km, which reflects mainly

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variations in the diurnal equilibrium between  $O_3$  and  $O$ . Below about 65 km of altitude, almost all the  $O$  is converted rapidly to  $O_3$  after sunset. A study of ozone trend would be incomplete if only night side measurements would be collected, and some efforts were made in the design of GOMOS in order to collect at least a significant number of vertical profiles of ozone also on the day side.

The day side situation is quite challenging for the technique of stellar occultation: the star signal is competing with the limb background radiance of the sun illuminated atmosphere, due to Rayleigh and aerosols scattering. This requirement is a design driver: while the spectrometers need no narrow entrance slit for the star spectrum to be recorded with a high resolution, and could have a large aperture, the rejection of undesired limb radiance calls for a small solid angle of the entrance aperture, which in turn calls for a good tracking accuracy, in order to get the star image at the focus of the telescope (which is also the entrance aperture of the spectrometers) always fully in the aperture. Its width was taken as equivalent to  $195\mu$  radians, or 10 spectrometer pixels. As we shall see, tracking performances of GOMOS are such that many stars can be tracked down to 25 km on the day side.

In addition, the entrance slit aperture is elongated in the vertical direction (perpendicular to the limb), which allows to measure simultaneously the spectrum of the limb radiance above and below the star, in order to subtract it to get the pure star's signal. Three bands of 7 CCDs lines each are therefore devoted to the measurements of the 3 spectra. This is also useful in some night time conditions, in order to subtract some natural atmospheric emissions.

*Mesospheric ozone:* In relation with PMCs, the chemistry of the mesosphere is also addressed, because GOMOS is able to measure the ozone concentration in the mesosphere by absorption at 250 nm, where  $O_3$  cross-section is maximum (Fig. 2). In this altitude range (80–100 km) ozone is produced by reaction of  $O$  with  $O_2$ , atoms of  $O$  coming themselves from the photo-dissociation of  $O_2$  by solar UV in the day side thermosphere. Ozone is destroyed by reactions with hydrogen radicals, i.e.  $H$ ,  $OH$ , and  $HO_2$ . Indeed, the high vertical resolution of GOMOS (Fig. 14) allows to document that

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there is an enormous sink of ozone around 80 km altitude, where the ozone concentration almost vanishes: another type of “ozone hole”, that would deserve a dedicated model study, in conjunction with GOMOS ozone profiles.

The photo-chemical lifetimes of oxygen and hydrogen radicals in the mesosphere are only a few hours (Brasseur and Solomon, 2005), and the ozone concentration should reflect a rapid photo-chemical equilibrium. In spite of this relatively simple situation, there are some significant discrepancy between the (relatively scarce before GOMOS) observations and the prediction of current modeling. The numerous ozone profiles obtained by GOMOS allow documenting further this discrepancy, which would help to improve the modeling. It is clear that, since the situation of ozone balance in the mesosphere is pretended to be simple, if we are not able to reproduce by modeling in this situation, it would cast serious doubts about the modeling of ozone in lower regions of the atmosphere, where the same reactions do occur also when oxygen and hydrogen radicals are present. One powerful diagnostic to validate models is the time variations of mesospheric ozone, and in particular the day-to-night variation, and variations connected to solar activity.

Not expected during the design of GOMOS, was the Tertiary Ozone Maximum (Fig. 28), first reported by Marsh et al. (2001); GOMOS observations of the TOM were reported by Sofieva et al. (2004, 2009), and briefly reviewed in Sect. 7.3.

As a conclusion concerning the ozone objectives of GOMOS, it is clear that not only we must measure as well as possible the ozone 3-D field and its time variations (to check the results of CFCs release limitations), but we must also understand the detailed underlying mechanisms governing the ozone budget, in particular by comparison with chemical models, or by assimilation into Chemistry Transport Models (CTM). In this respect, measurements of a number of other atmospheric parameters that are important for the ozone budget are also included in the design of GOMOS, as seen further below. Needless to say that the measurements carried out simultaneously by MIPAS and SCIAMACHY on ENVISAT are also useful for the understanding of mechanisms controlling ozone. Clearly, the degree of our understanding is directly impacting

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on our capability to predict accurately (through modeling) what will be the future behavior of ozone on the long term (tens of years), and this is our ultimate goal.

### 2.3 Nitrogen gases $\text{NO}_2$ and $\text{NO}_3$

Both gases participate to the  $\text{NO}_x$  family, involved in a catalytic cycle which provides the major loss processes for odd oxygen ( $\text{O}_3$  and  $\text{O}$ ) in the stratosphere (Crutzen, 1971; Brasseur and Solomon, 2005).  $\text{NO}_2$  has an extended absorption band in the visible, with conspicuous peaks at 430–450 nm (Fig. 2), and its stratospheric quantity is enough to be measured in the transmission spectrum of the atmosphere (Fig. 13).  $\text{NO}_3$  is rapidly photo-dissociated and does not exist during the day. It can be observed only during the night, thanks to its strong spectral signatures at 617 and 655 nm. It has no emission in the IR, and GOMOS is providing unique routine observations of  $\text{NO}_3$ . SCIAMACHY has also measured  $\text{NO}_3$  occasionally, by performing moon occultations (Amekdudzi et al., 2009).

Other gases interesting for the ozone budget have also some absorption in the wavelength covered by GOMOS, like OCIO, and BrO. However, in view of the weak stellar signal, and the scarcity of these absorbers, one cannot hope to measure them in one single occultation. There is more hope when piling up many transmission measurements to increase significantly the signal to noise ratio, as was done successfully by Fussen et al. (2006) and Tétard et al. (2010) for OCIO, and summarized in Sect. 7.

### 2.4 Temperature and oxygen

There is an important wavelength domain (310–350 nm, the Huggins bands) where the  $\text{O}_3$  cross-sections are strongly dependent on the atmospheric temperature. Therefore, a long-term variation of absorption in the UV as measured by GOMOS might be due to a temperature variation and wrongly attributed to an ozone density variation. It was felt necessary to include a temperature measurement within GOMOS. This is possible in principle with the A band of  $\text{O}_2$  at 760 nm (Fig. 15). Since  $\text{O}_2$  is a perfectly mixed gas

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and the air is in hydrostatic equilibrium, its scale height  $H$  is directly connected to the atmospheric temperature  $T$ , which vertical profile may be retrieved from integration of the hydrostatic equation:

$$\frac{1}{T} \frac{dT}{dz} + \frac{1}{[O_2]} \frac{d[O_2]}{dz} = -\frac{mg}{kT} = -\frac{1}{H} \quad (4)$$

This measurement of  $O_2$  allows also to relate all measurements of ozone density (and other species) to the air density to yield the mixing ratio  $[O_3]/[air]$ , which is often a quantity used in the models: comparison of GOMOS measurements with models may be easier with mixing ratios than with absolute densities.

The ILAS-I and ILAS-II instruments flown on Japanese missions on ADEOS-1 and ADEOS-2 has been performing similar measurements of  $O_2$  in the A band by solar occultation, with a somewhat similar spectral resolution, but a better signal-to-noise ratio. However, their interpretation suffered from uncertainties on the LOS altitude retrieval, associated to pointing uncertainties on the extended solar disk. The GOMOS  $O_2$  results will be discussed in Sect. 7.

## 2.5 Water vapor $H_2O$

Water vapor is injected in the stratosphere in tropical regions, and is also created by the oxidation of methane in the upper stratosphere. Water vapor plays an important role in the photo-chemistry, and in particular is the major scavenger of ozone (by HOx catalytic reaction cycle) at altitudes larger than 40 km (Brasseur and Solomon, 2005). The strongest absorption band of  $H_2O$  in the silicon CCD domain is in the Near Infra Red (NIR), around 936 nm (Fig. 16). Though this wavelength region is in principle free of other (known) stratospheric gaseous absorber, we have adopted a relatively high resolution for spectrometer B2, because it was already present of spectrometer B1 anyway.

In principle MIPAS, looking the far infra-red emission of water vapor, is more sensitive than GOMOS for water vapor. However, GOMOS may also provide useful  $H_2O$

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measurements for two reasons. In the far IR, an absolute radiometric calibration of the instrument is necessary to retrieve H<sub>2</sub>O from MIPAS, which may be detrimental for minute trend detection. Also, around the Upper Troposphere Lower Stratosphere (UTLS), the region of exchange of water vapor between the troposphere and the stratosphere, the vertical gradient of H<sub>2</sub>O is very large, and then the perfectly well determined altitude range of each GOMOS transmission measurements is a very important asset. In particular, it is hoped that GOMOS could contribute to discriminate between various proposed mechanisms to explain the paucity of H<sub>2</sub>O in the stratosphere: injection only above tropical convective cumulo-nimbus clouds extending at high altitudes, and therefore very cold and trapping H<sub>2</sub>O by condensation, or further dessication in the lower stratosphere by a series of cooling episodes (and condensation and sedimentation) with formation of sub visible clouds, possibly forced by gravity waves. These clouds are indeed observed in GOMOS aerosol data (Sect. 7, and Vanhellemont et al., 2005). The high vertical resolution allows to measure just above thick tropospheric clouds, while emission instruments would be contaminated by the clouds in their FOV.

At mid latitudes, H<sub>2</sub>O may be injected in the stratosphere from lateral motions of air masses along isentropic trajectories.

A very important long term objective is also related to Global warming, which may result into a drastic change (increase or decrease) of water vapor injection in the stratosphere, with a potential impact on ozone, in particular in the upper stratosphere. Balloon borne dew-point hygrometers flown near Boulder, Colorado, show a positive trend (increase) of +0.03 ppmv/year at 25 km over the period 1992–2005, and no variation at 16 km, while HALOE solar occultation instrument on board UARS showed no variation at 25 km and a negative trend of –0.04 ppmv/yr at 16 km. Thus, it is desirable to have other long series of instruments operating now, with some overlap with the previous period 1992–2005, which is exactly what may provide GOMOS on ENVISAT, in the lower stratosphere (LT) and upper troposphere (UT). In fact, due to the extreme sensitivity of H<sub>2</sub>O abundance to atmospheric temperature at the hygropause, GOMOS might be able to detect trends on this temperature based upon a potentially observed

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H<sub>2</sub>O trend. At any rate, since H<sub>2</sub>O and its derivatives HO<sub>x</sub> radicals are scavengers of ozone, the accurate monitoring of H<sub>2</sub>O is also important to understand the future of ozone balance.

## 2.6 Temperature and air density, and ECMWF data

Besides the measurement of O<sub>2</sub> vertical profile and derivation of temperature, there are several other methods which have been thought of to retrieve the vertical profile of temperature from GOMOS data, each of them in a somewhat limited range of altitude:

- the time delay between blue and red scintillations is a totally new method, and allows to determine a High Resolution Temperature profile H RTP (see Sect. 7.14, and Dalaudier et al., 2006).
- the Rayleigh extinction depends on the air density vertical profile, which is retrieved from Spectrometer A (UV-Vis), and then the temperature may be retrieved with the hydrostatic equation, like in the case of O<sub>2</sub>. However, the accuracy actually achieved on air density is not good enough to derive a useful air density and associated temperature.
- as noted previously, the ozone cross section is sensitive to temperature in the Huggins bands wavelength range (310–350 nm) (Fig. 3). GOMOS has enough spectral resolution to make a fit of a temperature-dependent model transmission, which should allow to extract an estimate of the temperature when absorption in this range (310–350 nm) is moderate, which corresponds to the 25-50 km altitude range with typical ozone profiles (Fig. 12).
- the dilution factor depends on the atmospheric profile, and its measure (by averaging scintillations) may be inverted to yield a density and temperature profile. However, absorption and scattering must be known also precisely.

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- the bending angle of refraction is the angle between the apparent direction of the star seen from ENVISAT and the absolute direction in the sky. It may be retrieved from the telemetered angular position of the SFA (Steering Front Assembly) plane mirror, which follows the apparent direction of the star, thanks to the GOMOS active tracking system. One must take into account the actual attitude of ENVISAT as a function of time during the occultation. This is similar to the method used with the imager of MSX/UVISI (Yee et al., 2002). However, some attempts have shown that the accuracy of the SFA angle measurements was too coarse to contribute to temperature profile retrieval.
- On the day side, there is some Rayleigh scattering emission of solar photons by air, that can be also inverted to yield a vertical profile of air, and another temperature profile. One difficulty is that there is a contribution from the nadir brightness to the scattering. It is in principle possible to discriminate the direct solar component from the indirect nadir contribution in the scattered emission in the stratosphere, because of some strong tropospheric absorptions band imprinted on the light coming from the nadir. The  $O_2$  band is not suitable because there is also some emission around 760 nm, and the  $H_2O$  band at 936 nm is possibly the best indicator of the nadir contribution. In fact, even if there is a constant error factor in the determination of the air density because of a wrong estimate of the nadir contribution, it is the vertical gradient which is used in the integration of the hydrostatic equilibrium equation, and inasmuch as the nadir intensity may be regarded as constant during on day side occultation, it should not affect the temperature retrieval.

At the present time (2009), only the H RTP method, using the time delay between the two fast photometers has been developed and validated. It will be implemented in the next version of the operational software, resulting in a GOMOS temperature profile in the Level 2 Product. It was found important to include also in the Level 2 product the air density and temperature profiles derived from the ECMWF (European

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Center Meteorological Weather Forecast) analysis, because it is more accurate than the GOMOS temperature/air density profile in most occasions. It makes also easier to undertake a systematic comparison of GOMOS temperature/density data with ECMWF profiles serving as a reference. The users of Level 2 GOMOS data should be cautious about the possible confusion of the ECMWF data, contained in the Level 2 GOMOS product, and the genuine GOMOS data. It should be noted that the Level 2 processing makes use of the ECMWF field of air density and temperature (analysis), in order to compute an accurate ray tracing of the LOS through the atmosphere with refraction, and also to prescribe the air line density for extinction in the spectral inversion of each transmission spectrum.

Contained in the Level 2 GOMOS product, the O<sub>2</sub> line density and temperature retrieval suffered from earlier wrong cross sections from HITRAN 2000 data base (leading to up to 20% deviation from ECMWF data). Though they were improved in the more recent HITRAN 2004 release we do not felt confident enough yet to use the O<sub>2</sub> measurements for a temperature retrieval in the Level 2 product as discussed in Sect. 7.

## 2.7 Turbulence and scintillations

The vertical transport of chemical species is of fundamental importance for controlling ozone and other trace gases in the stratosphere. In 1-D models, it is most often parameterized by an eddy diffusion coefficient  $K_{zz}$  associated to turbulence. Therefore, the inclusion of fast photometers in the design of GOMOS was not only to correct the spectra from scintillations, but also to study the “climatology” of turbulence, and associated vertical transport. However, it should be recognized that global 3-D Chemistry Transport Models are ignoring such a parameter, and the vertical transport is calculated only by advection, with a vertical velocity resulting from the divergence of the horizontal flux in a cell.

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## 2.8 Aerosols

Stratospheric aerosols are mainly produced by volcanic eruptions, and transformation of SO<sub>2</sub> into sulfuric acid droplets. The content depends therefore on the history of volcanic eruptions. Since these particles may participate to heterogeneous chemistry processes, it is important to monitor their quantity, and to try to determine their composition and size distribution. At the time of ENVISAT launch, the aerosol content at 20 km was possibly at a historical record low, with some increase at the end of 2002 (Thomason and Taha, 2003). This is a situation rather favorable for stellar occultation measurements of other species in the lower stratosphere. It can be noted that both the extinction by the aerosols, and their scattering properties may be obtained with GOMOS, by combining night measurements (extinction) and day side measurements (scattering), for a better retrieval of physical properties of the aerosols. This work is still to be done.

## 2.9 Polar Stratospheric Clouds (PSC)

PSCs are high altitude clouds encountered during very cold conditions in polar regions. They are of several types, according to the nature of the condensate, besides H<sub>2</sub>O. Before launch, we thought that their horizontal optical thickness would be so large that the stellar signal would be lost by the star tracker; in such case the main information would therefore be the altitude at which is observed a very sudden loss of the star signal by the star tracker. It turned out that in many cases, the star may be seen through the PSC, as discussed in Sect. 7, and in Vanhellemont et al. (2005, 2010).

## 2.10 Polar Mesospheric Clouds (PMC)

Noctilucent clouds (NLC) are seen from the ground during twilight. They are the “visible” part of the Polar Mesospheric Clouds (PMC), most of which can be only observed from space. It is a thin layer (~2 km) of small ice particles ( $r < 0.1 \mu\text{m}$ ) at 83–85 km of

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altitude, which vertical optical thickness is  $\tau_v = 10^{-4}$ , and tangential optical thickness around  $\tau_h = 10^{-2}$ . It is connected to the condensation of water vapor during the cold conditions of summer mesosphere.

In emission, they are detected by the spectrometers and the photometers (Fig. 45).  
5 The actual brightness is about the same as Rayleigh scattering at 50 km of altitude and gives a significant signal which can be interpreted in terms of Mie theory and particle size and nature. In absorption, the 1% absorption over 2 km of altitude is difficult to measure.

PMC appear only at high latitudes during summer. This feature is explained easily by  
10 the fact that mesospheric air is ascending during summer conditions at high latitudes; with adiabatic cooling the temperature is at its minimum value (below 150 K, the coldest region of the entire planet). Then water vapor abundance becomes higher than the local saturation vapor pressure, and icy particles condensate around condensation nuclei, which could be either meteoritic dust particles or large water cluster ions.

15 In his review of the subject, Thomas (1991) advocates that the appearance of PMC is a strong evidence of Global Change. The explanation would be that methane has been increasing steadily since 1850 (growing population and associated development of agriculture and livestock), with a growth rate of 1% per year (this growth rate has declined almost to zero in more recent years, possibly in relation with less leakage  
20 from russian gas pipelines). Indeed, oxydation of methane  $\text{CH}_4$  is an important source of  $\text{H}_2\text{O}$  above  $\sim 50$  km, and therefore an increase of  $\text{CH}_4$  at ground level will reflect some years later as an increase of  $\text{H}_2\text{O}$  at mesopause level and a higher probability to encounter frost point temperature conditions. The saturation vapor pressure decreases by a factor of 5 for only a decrease of 4 K for summer mesopause conditions. Therefore,  
25 even a moderate climatic temperature change (as induced for instance by increased  $\text{CO}_2$  cooling at these altitudes) could reflect on a larger PMC cover over the globe. With its capability to detect the presence of PMC at each occultation, GOMOS will allow to establish a good corpus of data over the whole globe. Of particular interest will be to document the North-South asymmetry, and to monitor the evolution of PMC cloud

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cover and the location of its equator boundary. GOMOS detects easily the PMCs in the fast photometer signal, as described in Pérot et al. (2010), and in Sect. 7.11.

## 2.11 Dayside limb emission measurements

On the dayside, the limb radiance (background) due to Rayleigh and aerosols scattering of solar light can also be used to retrieve ozone and other gases, with a technique used by OSIRIS on ODIN (Tukiainen et al., 2008), and SCIAMACHY on ENVISAT (Bovensmann, 1999). The spectrum of the recorded light is influenced by ozone absorption (and also other gases) and may be analyzed in terms of ozone (and other gases) vertical profile. Though the retrieval algorithm is much more complex than the occultation one, it will be useful to compare values of ozone retrieved by the two techniques. Included in GOMOS design is the capability to perform a "dummy" occultation, in which the tracking mirror is no longer piloted by the image of a star in the star tracker, but rather programmed to perform a motion as if there were a star to be occulted, sweeping the whole range of altitudes across the bright limb. In this case, there is no star signal, and only the bright limb emission is present (with some stray light contamination). However, there is one advantage to analyze the limb radiance during a star occultation: the observed altitude is perfectly known, while the altitude accuracy is less when there is no star. New algorithms are presently developed to retrieve ozone and other constituents from GOMOS bright limb measurements, sponsored by ESA and led by FMI.

## 2.12 Moon and planets

Like stars, planets may be used as targets for performing occultations. The advantages are a somewhat larger intensity, and also less scintillation effects, due to the extended source character. The spectral resolution is degraded. If the disc is too large, then it is not possible to track them properly with the GOMOS star tracker as we found out. This is the case for Jupiter and Venus, but for Mars it worked very well. A particularly

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attractive opportunity was the opposition of planet Mars around August 2002, when Mars was at its shortest distance from Earth since space age (and before). Since the absolute calibration of GOMOS is achieved in flight with a high accuracy by comparison with standard stars, the albedo of planets can be measured also from space with a great accuracy over the entire UV-Vis-NIR range of GOMOS spectrometers

Using the moon is also in principle an attractive prospective, because of the high flux expected. However, it cannot be tracked with the star tracker; therefore, GOMOS would have to be operated in the “dummy” mode of occultation, but then refraction will make the moon moving in the FOV. Calculations show that one cannot keep the moon always in the FOV with a fixed inertial direction of the LOS. Moon occultations have not been attempted up to now.

### 3 Instrument description, operations and coverage, typical observation results

#### 3.1 Instrument description

##### 3.1.1 Measurement principle and overall instrument configuration

GOMOS is an instrument designed to measure the atmospheric transmission at the limb in the ultraviolet, visible and near infrared with a good spectral resolution, in order to identify by their spectral signatures atmospheric ozone and other trace gases. It exploits a stellar occultation technique, which measurement principle is described in Fig. 1. The spectral flux of a pre-selected star is measured continuously during the setting of the star behind the earth due to the motion of the spacecraft on its orbit.

When the LOS to the star is fully outside the atmosphere (tangent height  $z$  of the LOS higher than 110 km), the unattenuated star spectrum  $S_o(\lambda)$  (Eq. 1) is measured. Typically the five first spectra are averaged together to give the Reference star spectrum  $S_o(\lambda)$ . Then, during the whole occultation, while the star sets behind the horizon (which last from 30 to 250 s) and the tangent height  $z$  is decreasing, the occulted spectra  $S$

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( $\lambda, z$ ) are measured every 0.5 second with no dead time. These spectra are divided by the reference spectrum of the target star  $S_o(\lambda)$ , allowing for the acquisition of spatially high-resolution atmospheric transmission spectra  $T_m(\lambda, z)$ . Using these measured horizontal transmission spectra  $T_m(\lambda, z)$  and the associated known cross-sections, for each chemical species, the horizontal and vertical density profiles are retrieved, as briefly described in the Introduction and in Sect. 5. Typical reference spectra for the various stars are shown in Fig. 11.

ENVISAT is nadir oriented; a given star has a constant inertial direction, and therefore its direction in the ENVISAT mechanical frame of reference is changing. Therefore, GOMOS needs a pointing system to track the star continuously. It is composed of one single plane mirror, actuated by a Steering Front mechanism and piloted by a Star Acquisition and Tracking system, as shown on Fig. 4. The star light is sent to a Cassegrain mirror telescope, which area is divided in two parts coated differently, one devoted to the UV-Vis part, the other to the near IR. The light is focused to a slit, separated by dichroic plates in various beams, sent to the UV-Vis spectrometers A1 and A2, spectrometers B1 and B2, fast photometers and the SATUs (prime and redundant).

The two fast photometers (1kHz sampling rate) were implemented to correct the measured transmission spectra from the adverse effect of scintillation, and also to determine important atmospheric parameters describing the state of turbulence of the stratosphere.

Given the constraints of the ENVISAT platform, and the scientific specifications defined by the SAG group, the Astrium company, with the help of a number of European companies, designed, developed, calibrated and delivered (under the responsibility of ESA) the GOMOS instrument, with a mass of 166 kg, power consumption of 146 w, and constant data rate of 222 kb/s.

GOMOS is inherently a self-calibrating instrument. This means that long-term drifts in the instrument's radiometric response are compensated since only the ratio of measurements acquired in a relatively short time interval (order of 1 min) are used to compute transmission spectra. In such short intervals, changes in the instrument response

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are negligible. Although GOMOS is specifically optimized for night observations, it performs also measurements during the day (bright limb conditions).

### 3.1.2 Pointing function description

As seen from ENVISAT, stars are setting down in the hemisphere opposite to the velocity vector. Therefore, GOMOS is placed near one end of ENVISAT, to look backwards. A frame of reference is defined with + Z axis towards nadir, and XZ plane maintained in the orbital plane (except for the yaw steering law to compensate for the Earth rotation for imaging instrument). One particular pointing direction is defined by two angles: the azimuth AZ (counted from the orbital plane, 0° looking opposite to the velocity vector), and the elevation EL, counted from the nadir direction. The limb is around 63°, which is 27° below the horizontal plane.

A Steering Front Mirror is used to orientate the LOS towards pre-selected stars. This plane mirror allows for the detection and tracking of a star in a wide angular range (100° in azimuth, from -10° to +90°, and 8° in elevation). The instrument line-of-sight geometry covers both rearward (anti-flight direction) and sideways viewing directions. However, when ENVISAT is near the South Pole, the sun is in the rear hemisphere. A baffle is protecting the entrance of GOMOS, but it occults most of the hemisphere on one side of the orbital plane, limiting the azimuth range on this side to -10°.

The target star is detected by the Star Tracker, a CCD covering a field of view of 0.6° with its focal length of 0.63 m. After detection, the star image is moved to the centre of the CCD and another algorithm performs the tracking with a very high accuracy. The pointing application software realizes the measurement of the position of the star on the CCD with a background removal. It then commands the Steering Mechanism in closed loop to keep the star image at the centre of the CCD during the occultation. Towards the end of an occultation sequence, the star light becomes eventually so attenuated that the instrument can no longer observe and track it. The star is finally lost behind the horizon and the instrument continues by moving its pointing direction (i.e. the mirror) toward the next star according to a pre-defined observation plan. By this way, the

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instrument may acquire up to 40 stars per orbit, yielding typically ~100 000 occultation per year.

To achieve this very high pointing accuracy, an innovative concept has been developed: telescope, focal plane optics and detection units are fixed with respect to the host spacecraft structure; by moving the steering mirror implemented in front of the telescope entrance, the GOMOS line of sight is aligned with the star direction. The GOMOS pointing function actively controls the disturbances induced by the host spacecraft within a low bandwidth (4 Hz). This fine-pointing control loop also corrects for short-term perturbations as induced by the atmospheric refraction and a part of the scintillation effects. Out of the control bandwidth, the LOS stability is guaranteed by the limitation of structural amplification of micro-vibrations through the Steering Front Mechanism on one side, and Telescope and Optical Bench on the other side.

The Steering Front Mechanism (SFM) design is optimized with respect to the mission needs: wide angular range in rallying; high linearity (5%) and low noise ( $<20 \mu\text{Nm}$ ) actuator in acquisition/centering/tracking. These requirements led to a two-stage concept: a two-axis fine stage supported by a one-axis coarse stage (azimuth only).

The micro dynamical behavior of the SFM was characterized on ground by tests performed on a fully representative breadboard. A complete functional validation of the pointing function (acquisition and tracking) has been performed on equipment breadboards with laser simulation. The number of coarse mechanism displacements is qualified for a 7 years lifetime.

Once a given star is acquired by the SATU, the SFM is given a nominal angular velocity corresponding to the predicted motion of the star as seen from ENVISAT (sent from ground by TC). The tracking system then computes only small corrections to this motion. However, at low altitudes when refraction bends the LOS to the star upward (w.r.t. the horizon), the correction becomes more important. With no correction, the star would go away from the CCD nominal reading zone, an effect noted with MSX mission, which was pointed inertial (Yee et al., 2002).

The pointing system is also able to track the star in spite of the additional apparent

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motion due to scintillations, up to a certain extent. In the case of strong scintillations, the tracking may be lost before the obscuration of the star by clouds at the limb.

It is to be noted that because of refraction, the apparent angular velocity of the star is decreasing with decreasing altitude. This is taken care of by the SATU; but an obvious improvement of the GOMOS design would be to pre-program a curve of angular velocity as a function of elevation angle, to compensate for refraction in a typical atmospheric profile.

The final performances in flight are completely in line with the expected. The minimum star already tracked is fainter than magnitude 4 and the total number of stars which can be detected is more than 500. However, measurements were performed routinely on about 150 stars only. The rallying accuracy is better than  $0.03^\circ$ . More than 97% of the target are detected and tracked successfully. The noise in tracking is less than  $1 \mu\text{rad}$  ( $1\sigma$ ) for the faint star in dark limb and  $3 \mu\text{rad}$  in bright limb. The robustness of the pointing chain allows tracking stars sometimes down to 5 km altitude; at other times, clouds or strong scintillations stop the tracking at higher altitudes, as shown in the histogram of Fig. 10.

### 3.1.3 Spectrometers description

The instrument optical design is based on a 30 cm telescope (1.05 m focal length) which simultaneously feeds a medium resolution UV-VIS spectrometer, a high resolution IR spectrometer, two fast photometers and two redundant star trackers (see figure “block diagram”). The splitting of the entrance flux is done by the Optical Beam Dispatcher, placed at the telescope focal plane. Since for stellar spectrometry, there is no need for a slit to limit the spectral resolution, a slit is placed in the OBD only to limit the background and stray light flux. But this implies that the stability of the image on the spectrometer has to be guaranteed by the tracking. Taking into account the very good pointing performance, the spectral stability is better than 0.1 pixel.

All the detection units are implemented on a thermally controlled optical bench. This bench and the telescope are mounted together and fixed on the instrument interface

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via carbon-fiber struts. The spectral dispersion is performed by 2 different gratings. The UVIS grating is an aberration corrected holographic grating. It is used at its first order. The light is then imaged on 2 CCD (UV and VIS), allowing to compensate partially for the grating residual curvature. The IR grating is used in a Littrow configuration in high orders of diffraction (orders 13 and 16). After a dichroic splitting, the light is then imaged on 2 CCD (IR1 and IR2). The unused orders of diffraction are rejected by narrow band-pass filters located before the detectors.

The same type of detectors is used for the 4 spectrometers channels. The CCD (from EEV) is a 27 mm length matrix of 1353×143 pixels. The pixel size is 20×27 μm. They are thinned and back side illuminated in order to improve the efficiency in UV.

They can be used in different modes. In the normal mode (Fig. 6), 3 sets of lines are binned "on chip" to give 3 values per column. This gives 3 spectra. The central one is used to collect all the star target flux. The 2 others (above and below) are used for the dark signal and background correction. Each of these spectra is the integration over 7 lines (this parameter is programmable) equivalent to 0.01°. The total number of spectral elements is 2336, which can be shared by programming between the 4 spectrometers. The baseline configuration is as follows:

spectro A1: pixel 1 to 450 (248.14 to 389.18 nm)  
spectro A2: pixel 451 to 1416 (389.52 to 690.49 nm)  
spectro B1: pixel 1417 to 1836 (755.12 to 774.59 nm)  
spectro B2: pixel 1837 to 2336 (925.97 to 954.42 nm)

Three other modes, for which the integration time can be changed or the individual pixel data can be retrieved, are used for the calibration. The radiometric performances of these CCD in terms of noise and quantum efficiency allow achieving signal to noise ratio in the order of 20 in VIS and 6 in IR for stars of magnitude 3 per pixel. However, an unexpected sensitivity of the CCD dark signal to the protons of the South Atlantic Anomaly leads to a high non-uniformity and instability (RTS effect) of the dark signal

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pattern. This is corrected by a dark signal calibration at each orbit in order to be able to remove it as precisely as possible. The operating temperature of the CCD has also been decreased to  $-4^{\circ}\text{C}$  in order to minimize the impact of the dark signal, but unfortunately this temperature is slowly increasing, because of the evolution of thermal properties of insulating materials.

### 3.1.4 Photometers description

Two fast photometers, operating at 1 kHz, are collecting the star flux in the blue and the red band. Their bandwidth are  $\sim 50\text{ nm}$ . They share the same pupil than the IR spectrometer ( $175\text{ cm}^2$ ). The flux is splitted via a dichroic that provides one spot on each detector. The detectors are CCD matrix of  $14 \times 14$  pixels of  $23\ \mu\text{m}$ . The nominal mode in occultation integrates the flux collected by a programmable area (nominally 14 lines  $\times$  5 columns, corresponding to a FOV of  $0.239 \times 0.671\text{ mrad}$  with a focal length of  $0.48\text{ m}$ ). Another calibration mode allows retrieving the individual pixel data.

The radiometric performance of the CCD in terms of noise and quantum efficiency allow to achieve signal to noise ratio in the order of 6 for stars of magnitude 3 during the 1 ms integration time.

### 3.1.5 Special modes of operations

Some secondary modes of observations and CCD reading may be programmed, mainly for calibration purposes. In the imaging mode, 33 lines of the CCD are read every 6 second. These 33 lines are covering the three useful bands, the Central band in which is usually cumulated the star signal, and the Upper and Lower band which contains the limb brightness (if any). It allows to check that the star spectrum is well placed within the selected bands. A linearity mode allows to measure the same star with various integration time from 0.5 s up to 10 s, in order to determine the non-linearity of the output signal ( a very minor effect). A calibration campaign called CALEX using these two modes is activated every month, and the results are automatically fed in a

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calibration data base, as an input of the pipeline processor. A dummy occultation may be made, in which the instrument is pointed to a particular celestial direction void of star, and the tracking system deactivated. In such a mode, the line of sight crosses the limb. It is used, either to record the DC pattern of all CCDs (night side), or to record the limb brightness vertical distribution on the day side, without any star contamination.

## 3.2 Operations and Earth coverage

Owing to the combination of altitude (mean, 799.8 km), and inclination (98.55°), the precessing orbit is maintained at a constant local time with the descending node being at 10:00 LT  $\pm$  5 min. The latitude of the occultation of a given star varies along the year, but repeats identically each year. On Fig. 7 is represented the occultation latitude as a function of date of year of the 70 brightest stars (up to visual magnitude  $m_v = 2.25$ ) that can be occulted from ENVISAT on the night side. Of course, not all of them may be observed at each orbit. For some stars, the latitude varies slowly, while for others (for example, the brightest star Sirius S001 in the GOMOS numbering convention), there is a large range of sampled latitude over 7 months during which this star can be observed with GOMOS on the night side.

Still, from one orbit to the next, the occultation latitude is not changing much. Therefore, the same star may be observed at each orbit for some weeks. The orbital period of ENVISAT at 100.6 mn is maintained with  $14 + 11/35$  orbits per day; therefore, after 3 days, the occultation point of a given star is almost at the same latitude and longitude, with 43 points uniformly spread in longitude along a circle of constant latitude. As noted earlier, the decorrelation time of ozone at a given point in the stratosphere is of the order of 3 days.

Along the polar orbit of ENVISAT the latitude is changing fast. Once an observed star is fully occulted, GOMOS is rallying towards another star, which will be occulted at a different latitude. The latitude coverage depends on the availability of bright stars, and is not regular. Figure 8 indicates a typical coverage of GOMOS occultations for a period of 3 days, while Fig. 9 indicates the coverage over 7 years of GOMOS night

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time occultations. The pattern repeats itself from one year to the next.

In Fig. 9 a continuous arc represents many occultations of the same star at successive orbits, covering all longitudes and slowly varying in latitude. Essentially, the Earth is rotating fast inside the orbit plane/star system, while the orbit plane rotates by 1° per day w.r.t. the star system.

There are some interruptions in time, which were caused by some malfunctions of the Steering Front Mirror assembly mechanisms, as described later. In particular, after the malfunction of early 2005, the coverage is less dense. The average number of occultations per day decreased from 400 to 250–300 when operations were resumed in 2005.

The observation of a particular sequence of star occultations requires the uploading of a set of star pointing parameters that control the initial pointing direction and the apparent angular velocity (due to the satellite motion) of individual target stars. The observing programme for GOMOS is established on the ground at ESRIN, with the help of Starsel software, which optimizes by picking up the brightest stars available, knowing the occultation time and duration for one star, and the time to rally to another star. Pre-launch was defined a list of 1,000 stars, named for GOMOS purpose from S001 (Sirius) to S1000, ordered by increasing order of magnitude (decreasing order of brightness at 550 nm). Actually, the dimmest star that was useful to provide a decent ozone accuracy is S185, at magnitude  $m_v=3.08$ .

Planets have also a number, along with a series of ~50 dark regions in the sky (DSA, Dark Sky Area), void of stars, which can also be occulted during a dummy occultation, to measure the Dark Charge (at high altitude) and the limb brightness or to characterize stray light contamination.

*Altitude coverage:* Once a star is acquired at an altitude >120 km, it is tracked by the SATU as long as possible by acting on the plane mirror, keeping the image of the star in the center of the slit. It is lost either because of the presence of clouds, or from strong scintillations which move the star vertically and modulates strongly the signal, both ways (brightening and dimming). The star is declared “lost” when the star

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tracker does not find the star during more than 0.1 s (10 samplings). Figure 10 show a histogram of the altitudes at which was lost the star, during all occultations of 2004. The stars can typically be tracked from the top of the atmosphere (120–150 km) down to 5–20 km tangent altitude for night occultations. It seems that when no clouds are present, stars can be followed as low as 5 km altitude (especially bright stars). The presence of clouds in the field-of-view leads to losing the signal. The lowest altitude reached in occultations of bright stars can potentially provide valuable information about cloud top height (Tamminen et al., 2010). Its geographical distribution is informative. For instance, in the South Polar night, measurements are often terminated at 15–18 km, most probably because of frequent occurrence of polar stratospheric clouds. In the tropics, there is a concentration over the continents and east pacific of high altitude clouds (cirrus and convective clouds, Tamminen et al., 2010).

### 3.3 Typical results

#### 3.3.1 Stellar spectra

At each occultation, when the star is acquired and tracked by the SATU (Star Acquisition and Tracking Unit), at high altitude, (usually around 120 km), the five first spectra are averaged together to give the Reference star spectrum  $S_0$ , outside the atmosphere. Figure 11 represents spectra for various stars, illustrating two features of GOMOS. The first feature is that the signal is dimmer when the star magnitude is larger (the magnitude of a star is defined according to its flux at 550 nm). Of course, brighter stars are favored in the selection of stars, but in order to get a good latitude coverage, one has to select quite often dimmer stars (up to magnitude 3), by lack of bright stars at a given latitude. Obviously, the accuracy of ozone (and other species) retrieval depends on the star brightness. The second feature is the fact that hot stars have much more UV flux than cool stars of equal magnitude, allowing ozone retrieval with the Hartley's absorption continuum, peaking at 255 nm (the shortest wavelength of GOMOS is 248 nm). Each spectrum is measured for 0.5 s, and the signal per pixel in electrons gives the in-

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dication of the shot noise, the main source of error bar for the spectral transmission: 1% for a signal of 10 000 electrons. The pixel spectral size (sampling) is given in Table 1.

Note in Fig. 11 the strong Fraunhofer Hydrogen lines in the spectrum of star S005 (GOMOS identification number of the star Vega, the 5th brightest in the sky), allowing a good in-flight wavelength calibration of the spectrometer, and a relative lack of signal around 380 nm, which is an instrumental effect: this is where the spectrum of the star produced by a holographic grating is divided in two parts, reaching two different CCDs (UV and Visible) with some resulting vignetting.

### 3.3.2 Atmospheric transmissions

In Fig. 12 are plotted the spectral transmissions  $T_m$  measured at a number of tangent altitudes  $z$  during one occultation of star Sirius (the brightest in the sky).  $T_m(z)$  is obtained by ratioing  $S_m(z)/S_0$ , where  $S_m(z)$  is the measurement of the spectrum through the atmosphere obtained at altitude  $z$ , during 0.5 s (altitude integration over 1.7 km at most, depending of the distance of the star to the orbital plane). In this particular case, the minimum altitude was lower than 10 km, while for dimmer stars, the tracker may lose the star between 20 and 10 km. From UV to 700 nm, one can recognize on the transmission spectra:

- the strong Hartley's absorption continuum at 250-280 nm, allowing to measure ozone up to 100 km
- the Huggins bands of ozone at 300-340 nm (visible from 29 to 52 km)
- small spectral features around 440 nm due to  $\text{NO}_2$
- the broad absorption Chappuis band of ozone, from 480 to 700 nm, with pronounced spectral features
  - a small feature at 656 nm due to  $\text{NO}_3$
  - a small  $\text{O}_2$  band at 670 nm
  - the Rayleigh extinction of air, giving the slope around 400 nm (visible essentially below 30 km).

There are also some irregularities (conspicuous on the 37 km transmission around

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400 nm), which are due to imperfect corrections of the scintillation effects, as is explained further below.

In Fig. 14 is displayed the vertical profile of ozone,  $\text{NO}_2$  and  $\text{NO}_3$  retrieved from one occultation of star Sirius. For ozone, the retrieval extends from 16 to 106 km (lower stratosphere to mesosphere), with a range of concentration covering six orders of magnitude. This exceptional dynamic range is allowed because of a corresponding large range of absorption cross section over the GOMOS wavelength domain. GOMOS is the first instrument providing systematic  $\text{NO}_3$  profiles. This species exists only at night, being rapidly photo-dissociated by sun light.

On Figs. 15 and 16 are displayed the spectral transmission obtained respectively in the Oxygen  $\text{O}_2$  band (called the A band) around 760 nm, and in the water vapour band around 936 nm. Measured transmission spectra are compared with a simulation of the model transmission  $T_{mod}$ . It is obtained with HITRAN line-by-line calculations at highest possible spectral resolution, then convoluted to the actual resolution of the instrument, considering only these gases. It should be noted the high degree of resemblance between the data and the model, demonstrating the high spectral quality of the data, considering the weakness of the stellar source.

### 3.3.3 Scintillations observed from fast photometers

Scintillations are one aspect of refraction. They are due to small irregularities in the air density vertical profiles (and therefore, temperature). Figure 17 shows an example of scintillation measurements by GOMOS fast photometers. The rms of relative fluctuations of intensity recorded by the photometer rapidly grows with decreasing altitude (roughly proportional to air density) until it saturates at values  $\sim 1$  at altitude of  $\sim 30$  km. The spectrometers have a much lower sampling rate of 2 Hz. However, the photometer signal averaged down to 2 Hz still exhibit fluctuations (not shown here). The amplitude of these fluctuations range from  $\sim 4$  up to  $\sim 20\%$  at altitudes below 30 km. This modulation of the transmittances caused by scintillation significantly exceeds the instrumental noise, especially in case of very bright stars. Therefore, the signals from the two pho-

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tometers are used to correct the deformations of transmission spectra as much as possible before the spectral inversion.

In addition, the photometers data may be exploited to characterize the turbulent state of the atmosphere (Sofieva et al., 2007a, b, 2009a; Gurvich et al., 2007), and derive a vertical profile of the temperature with high resolution, from the measured time delay between the blue peaks and the red peaks, which are produced by the same air temperature irregularity: the blue rays are more refracted than the red rays, and are therefore encountered later by GOMOS during the occultation.

## 4 Problems encountered during the GOMOS mission

During the 8 first years of the GOMOS mission (2002–2009), some difficulties and problems were encountered, which deserved to be described in some details, as well as mitigations schemes. These are: an unexpected increase of the Dark Charge (DC) of the CCD detectors, the scintillations produced by the isotropic component of temperature fluctuations, some malfunctions of the orientation mechanisms, a component of stray light on the day side, and the “cosmic hits “ produced by energetic particles encountered when ENVISAT is in the South Atlantic Anomaly (SAA).

### 4.1 Dark Charge of the CCDs

The CCDs used as detectors in the GOMOS spectrometers were procured from EEV company. They are back side illuminated, ensuring a good quantum efficiency for the whole wavelength range of the spectrometers. They were sold to have a very low Dark Charge (DC), using the MMPP technology, allowing to avoid to have to cool them at  $-40^{\circ}\text{C}$ , as it is usual for CCDs. The thermal concept of the instrument was therefore simplified, and a good thermo-mechanic stability was ensured (specially important to avoid spectral shifts).

Unfortunately, some pixels soon showed a different behavior, which affected all of

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them after 2–3 years in orbit. The DC increased by more than a factor of 10, and also showed variations of mean level much greater than expected from a Poisson statistic, on scale times of tens of minutes. This phenomenon is referred as RTS in the literature (Radio Telegraphic Signal), caused by radiation belt energetic particles changing the structure of the silicium in the pixel. Instead of being uniform along the CCD, the DC presented a highly structured pattern: the DCNU (Dark Charge Non Uniformity).

The situation was mitigated by devoting at each orbit one full dummy occultation, pointing at a Dark sky area, allowing to record the exact pattern of the DCNU. This occultation occurs near the ascending node (crossing the equator), in the depth of the night side to avoid any light contamination. This recorded pattern is then used to correct by subtraction all the occultations of the following orbit.

Nevertheless, the mean DC is increasing as a function of time, as shown in Fig. 18, for a combination of two causes: the increase of temperature of the instrument, because of the degradation of the thermo-optical properties of the insulation layers, and the increase of the RTS. It is possible to disentangle both effects, since the law of DC change with temperature is well known. In Fig. 19 are plotted the histogram of the number of pixels showing a certain dark charge in electrons per 0.5 s, separately for the various years of operation. In 2003, some pixels were still showing low dark charges, while larger and larger values are seen in the following years. It clearly affects the accuracy of the various gases retrieval, mainly for the dimmest stars, which signal is competing with the dark charge, as shown in Keckhut et al. (2010) by comparison with microwave and lidar ground based instruments.

## 4.2 Problems with scintillations

Scintillations are the result of interaction of light waves with air density irregularities (Gurvich and Brekhovskikh, 2001; Dalaudier et al., 2001). It is known that there are two types of air density irregularities in the Earth stratosphere: anisotropic irregularities, which are stretched along the Earth surface (generated by mainly by internal gravity waves), and isotropic irregularities (turbulence), which appear as a result of

gravity wave breaking and due to different instabilities. These irregularities produce scintillations at the observation site.

Before the launch of ENVISAT, the isotropic component was thought to be small in the stratosphere. However, the analysis of the fast photometers, and of the wavelength transmissions measured by the spectrometers showed that it was more important than expected; as a result, the scheme that was designed to correct the spectrometer transmission did not achieved a complete correction.

When a star lies in the orbital plane ( $A_z = 0^\circ$ ), GOMOS will observe *exactly* the same density vertical structure at all wavelengths (but various times); in such a case, the scintillation correction will be perfect, even in the presence of isotropic fluctuation. For a star which is not in the vertical plane (the most current situation), the occultation point will have an oblique trajectory at the limb (Fig. 50). If the fluctuations are purely anisotropic (the vertical structure is conserved horizontally), the scintillation pattern will be exactly the same as if the occultation were in the vertical plane. It was found that this is not the case: there is always an isotropic component to the fluctuations, which result in an imperfect correction of the transmission spectra, becoming worse as the obliquity increases.

The impact on the accuracy of ozone retrieval of such an effect has been studied (Sofieva et al., 2009). The effect is significant between 20 and 40 km, increasing the error on ozone local density from  $<1\%$  up to  $2\%$  for a bright star, and up to  $4\text{--}8\%$  for dim and cool stars of magnitude  $>2.5$ ,  $T < 6000$  K (Tamminen et al., 2010).

### 4.3 Stray light

The internal straylight is the light coming from the region of FOV (Field Of View) limited by the slit, but whose photons generated mainly by the grating as scattered light and it is most manifest as light from the star collected in the background bands (up to  $1.5\%$  of the light collected in the Star Central band in the UV). At present time, no correction of the internal stray light is implemented.

The external stray light is the light which makes its way through the slit, though its

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origin is outside the nominal FOV defined by the slit at the focal plane of the telescope. There are mainly two sources of external stray light. One is the solar light scattered by some ENVISAT hardware into the baffle and optics of GOMOS. The other is coming from the sun-illuminated limb or nadir. It bears a strong tropospheric signature of H<sub>2</sub>O and O<sub>2</sub> absorption. The external stray light of solar origin does not go through the ozone layer and therefore contains some UV even at maximum ozone absorption wavelengths (255 nm). At present time, no correction of the external stray light is implemented, because most of it is the same in the three bands, and is subtracted at the same time as the bright limb contribution (see below). Still, geometrical computations are performed to characterize the illumination conditions of GOMOS, ENVISAT and the tangent point of occultation at the limb at a reference altitude (the nominal value is 50 km). The illumination condition is given in the flag stored in the Level 1b product (PCD ILUM). This index may be also used as a guide for the stray light contamination.

#### 4.4 Cosmic hits

They are generated by high energy particles trapped in the radiation belts, and manifest themselves by a much larger content of electrons in a pixel, or a few adjacent pixels (depending on the angle of the trajectory to the plane of the CCD). They are tracked and flagged by the pipeline software of Level 1b. They are affecting the measurements mainly when ENVISAT is in the South Atlantic Anomaly, or at high latitudes in the auroral zones, as can be seen in Fig. 20. Only the flagged pixels are ignored during the retrieval of constituents, and the occultation as a whole is still valid.

#### 4.5 Orientation mechanism malfunctions

Figure 9 show some interruptions of the data, which all were caused by some malfunction of the Steering Front Mechanism (SFM). In May and July 2003, a malfunction of the "voice coil" commanding the azimuth motion forced ESA to switch GOMOS to a redundant system, Side B. In 2005, a similar problem affected the elevation mechanism,

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which could not track the star completely. It was found through thorough investigation that the problem occurred mainly when a large excursion in azimuth was scheduled between two consecutive stars. Therefore, GOMOS was then operated in a limited range of azimuth, a window of 30° which limits were optimized by one of us (Hauchecorne) in order to still get a good sky coverage. It is obvious from figure 9 that the overall sampling is coarser after this second failure, and GOMOS is still operated in this mode at the time being (December, 2009).

## 5 Retrieval algorithms

### 5.1 Overview

In this section we describe briefly the algorithms used to retrieve from GOMOS raw measurements (Level 0 data) the vertical profiles of atmospheric parameters. A more complete description may be found in Kyrölä et al. (2010a) as a part of this GOMOS ACP special issue.

The species covered by GOMOS are O<sub>3</sub>, NO<sub>2</sub>, NO<sub>3</sub>, H<sub>2</sub>O, O<sub>2</sub>, as well as aerosols and temperature: all these results which constitutes the so called Level 2 GOMOS data products. The Level 2 product contains also the line densities of measured species, and the ECMWF data for air (both local density and temperature, and integrated line density). Measurements cover altitude region 5–150 km. The vertical range of valid data is somewhat variable, in particular with the star type and brightness: for ozone, 10–100 km; for NO<sub>2</sub> and NO<sub>3</sub>, 20–50 km; aerosols, 15–40 km. In special occurrences, NO<sub>2</sub> is seen up to 70 km.

In a very natural way, the data processing of GOMOS includes the extraction of the atmospheric transmission as the intermediate product, defining the output of the processing which conducts from raw measurements (Level 0) to Level 1b (atmospheric transmission). Quite obviously also, the data flow of GOMOS is divided into individual data sets each covering one occultation, since each of them can be analyzed indepen-

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dently from the others. The data processing is somewhat different, according to the illuminations conditions at the tangent point as defined earlier.

The algorithms discussed here are used in the Envisat GOMOS ground segment supported by ESA. The algorithms have been developed in the contract between ESA and the ACRI company in Sophia-Antipolis, France. The scientific institutes, Finnish Meteorological Institute, Service d'Aéronomie (now LATMOS) and Institut d'Aéronomie Spatiale de Belgique, have been the scientific partners of ACRI, to form together the GOMOS Expert Support Laboratory coalition (ESL) in charge of Level 1b the algorithm development. The GOMOS level 1b and Level 2 algorithms have been written down in great detail in the GOMOS Detailed Processing Model-document (GOMOS ESL, 1998).

## 5.2 Level 0 to Level 1b processing overview and Level 1b data products

The data processing to reach Level 1b spectrometers products consists basically of:

- correction of instrumental effects
- separation of stellar light from limb background light and calculation of total transmission
- geolocation of each measurement

The data processing requires a good orbit knowledge, and a good knowledge of instrument characteristics (dark charge, wavelength calibration, wavelength resolution, ...), based on ground calibration and in-flight additional measurements (with special monitoring modes of GOMOS). In addition is needed an atmospheric vertical profile, in order to account for atmospheric refraction of the ray path for a more precise geolocation of the transmission measurement.

The Level 1b data processing is identical for both spectrometers A (UV-Vis) and B (for O<sub>2</sub> 760 and H<sub>2</sub>O 936 nm).

### *Level 1b Data Products*

The Level 1b data products are listed below, with their sampling rate. They are

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grouped occultation by occultation (about ~30 per orbit). Some comments on these data products are listed below, while details on the data processing are given later.

*Reference star spectrum (once per occultation)* : It is obtained by averaging the 10 first spectra obtained above 120 km during the occultation to minimize the noise.

5 *Reference atmospheric profile (2 Hz)*: This density profile is extracted from a meteorological field analysis (ECMWF) combined with a climatological model (MSIS 90). It is used to compute during Level 1b the refraction of the LOS, by full ray-tracing computation. It is also used in Level 2 to fix air density (Rayleigh absorption absorption), and is contained in Level 2 product.

10 *Full transmission spectra and covariance (2 Hz)*: This spectrum is obtained by dividing each spectrum in one occultation by the reference star spectrum. It is said “full” because it is the actually measured transmission, not corrected from refraction effects (dilution, scintillation, chromatic refraction) nor from variable PSF (Point Spread Function). The covariance (here, in fact, the variance of each pixel signal) is computed from analysis of S/N ratio.

15 *Central Background estimate (2 Hz)*: This is the estimated background contribution to the total signal in the central band, which is subtracted to yield the pure stellar signal.

*Photometers data (1 kHz)*: Correction to raw data includes the unfolding of the data (when they suffer from an overflow) and the subtraction of Dark Charge.

20 *SATU data (100 Hz)*: This is the position of the centroid of star image in the SATU CCD (Stellar Tracking Unit), which allows to know where to find each wavelength in the series of pixel.

25 *Wavelength assignment (2 Hz)*: This is the wavelength of the center of each pixel, for the given measurement of transmission (it may change during one occultation owing to imperfect tracking).

*Geolocation (2 Hz)*: This includes both the position of ENVISAT spacecraft and the position of the tangent point of LOS.

*Limb products (2 Hz)*: This product includes the background actually measured with the two external bands of CCD spectrometers, uncorrected and corrected from stray

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light and other factors. This product is found on separate dedicated files.

### 5.3 Level 0 to Level 1b processing details

#### 5.3.1 Geolocation of the LOS

In principle, the tangent altitude of one line of sight is only defined by the position of ENVISAT, and the direction of the star. Several effects must be taken into account. The direction of the stars depends on the date, because of the proper motion of the star and the aberration of light. Also, the LOS is not a straight line, because of atmospheric refraction. A full refraction computation is performed, assuming that the atmosphere is well represented by ECMWF predictions (for Near Real Time processing) or ECMWF analysis (for off-line processing, and re-processing).

#### 5.3.2 Wavelength assignment for spectrometers

In this operation each pixel is assigned a wavelength. It relies on regular calibration observations of stellar features, supplemented for Spectrometer B by the use of the O<sub>2</sub> band atmospheric absorption, very well defined. Since the entrance slit is rather wide, equivalent to ~10 spectral pixels, the mean position of the star during one 0.5 s sample in the horizontal direction translates into a small wavelength shift which is taken into account. The star moves by a few micro radians because of scintillations and imperfections of the tracking. Data form the SATU (Star Acquisition Tracking Unit).

#### 5.3.3 Bad pixels and Cosmic ray processing

A list of bad pixels is regularly updated from GOMOS in-flight calibration process called CALEX, which includes the use of a Uniformity monitoring mode. Only a few pixels, out of 2336, are out of order after 7 years in flight. The CCD detectors are sensitive to high energy particles arriving mainly from the Earth's radiation belts, at high latitude, and in the South Atlantic Anomaly. A cosmic ray produces an additional charge in a single

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pixel or in several pixels if the angle of incidence with respect to the surface of the CCD is small. This phenomenon is seen in all space-flying CCDs. A pseudo- image is built from the succession of all spectra in one single occultation, on which a median filter is applied to detect these cosmic rays. The pixel data is flagged and not used in the further processing. In bright limb condition cosmic ray processing is disabled.

### 5.3.4 Modulation correction

The offset level of the ADC (Analog to Digital Converter) was found to vary by 0.5 to 1.5 ADU (Analog to Digital Unit), according to a very regular pattern. This pattern was determined, and a correction is now systematically applied for spectrometers A1 and A2.

### 5.3.5 Conversion of ADU to measured electrons

Each ADU value is converted in a number of measured electrons, on which the Poisson statistics applies. A linearity correction is applied, which is verified at each CALEX monthly operation, by using a mode in which the same star is observed with various integration times from 0.25 to 10 s. The correction depends on the CCD, but is quite small (less than 1%).

### 5.3.6 Dark charge correction

Even in the absence of light some electrons are generated in a pixel, the so-called Dark Charge, and must be subtracted to get the number of electrons generated by light. As described earlier, the CCDs have aged rapidly on this respect, and have lost their capacity of low DC generation. As a result, the DC has increased constantly with time (Fig. 18); furthermore, it changes from one pixel to the next, and the DCNU pattern (Dark Charge Non-Uniformity) is changing over times scales of tens of minutes. The DCNU pattern is measured at each orbit, while observing a sky dark area, around the ascending node of ENVISAT (in the deep night). These measurements are used

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to correct all other occultations in the same orbit, with a multiplication factor taking into account the CCD temperature dependence of this DC. However, this temperature is digitized by steps of 0.4 °C, rather large to make a very accurate correction. In the future reprocessing, we will use the pixels in the UV range below 280 nm at low altitude, where we know that ozone blocks all the light, to determine the mean value of the DC, and the accurate variation of temperature between the DC calibration near the equator and the current measurement.

### 5.3.7 Correction of the SFA mirror reflectivity

The plane mirror of the SFA (Steering Front Assembly) is oriented in such a way that the line of sight is reflected in a fixed direction, along the telescope axis. The reflectivity of the mirror varies with wavelength and the angle of incidence, which is  $\geq 25^\circ$ . The incidence angle depends on the elevation and azimuth angles, defined in a frame of reference attached to ENVISAT. Since the incidence angle varies by a few degrees during one occultation, it is important to correct for the effect. Otherwise the transmission ratio of two star spectra measured with different incidence angles would be biased. A look-up-table has been built from Sirius observations with various azimuth and incidence angles. The variation of reflectivity is assumed to be a linear function of the angle of incidence, different for each wavelength. This effect was detected in flight, while monitoring the minute variations of star intensities: the influence of azimuth and elevation was obvious.

### 5.3.8 Internal and external straylight correction

At present time, no correction of the internal stray light (leakage of star light in the background bands) is implemented to correct the background bands. However, in full dark limb conditions, there is no subtraction of the background bands from the Central band where the star spectrum is recorded.

In some illumination conditions, there is some external stray light, either directly com-

ing from the sun (and reflected on some part of ENVISAT and scattered to the mirror of GOMOS), or coming from the bright scene illuminated. Each occultation is qualified with an indicator (PCD ILLUM) defining the illumination conditions at the tangent point. One main parameter is the Solar Zenith Angle (SZA) at the tangent point. The data analysis may be slightly different for the various conditions. They are defined as follows:

PCD ILUM = 0: full dark

Not in bright limb nor twilight nor straylight conditions.

PCD ILUM = 1: bright limb

SZA at tangent point  $<97^\circ$  for at least one measurement with altitude at tangent point  $<50$  km.

PCD ILUM = 2 twilight

Not in bright limb and SZA at tangent point  $<110^\circ$  for at least one measurement with altitude at tangent point  $<100$  km.

PCD ILUM = 3 straylight

Not in bright limb and SZA of ENVISAT  $<120^\circ$  for at least one measurement.

PCD ILUM = 4 twilight + straylight

Not in bright limb and both conditions for twilight and for straylight are verified.

The index (PCD ILUM) may be also used as a guide for the stray light contamination.

### 5.3.9 Vignetting correction

The azimuth of the star may go from  $-10^\circ$  to  $+90^\circ$ , where the origin  $0^\circ$  is taken in the orbital plane. For negative azimuth ranging from  $-5$  to  $-10^\circ$ , a part of the telescope area dedicated to feeding Spectrometer B is occulted by the plane mirror. A vignetting correction factor is applied for such cases.

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### 5.3.10 Correction of limb background

In bright limb occultations the background radiation falling on the central band needs to be subtracted from the measured central signal in order to get the star signal alone. This background is estimated by a linear or exponential interpolation (this one is the currently activated in the processing) between the measurements of the background made in the upper (U) and lower (L) bands. The central background estimate is stored in the Level 1b product. The estimates of the upper and lower background are stored in the GOMOS Limb Products, which may be analyzed to retrieve also ozone other gases, as done for SCIAMACHY (Bovensmann et al., 1999) and OSIRIS on ODIN (Tukiainen et al., 2008).

Before the estimates, a flat field correction is applied. The sensitivity of each pixel is retrieved from a PRNU map (Pixel-to-pixel Response Non- Uniformity). The PRNU values of all pixels have been determined in-flight, and for the PRNU band correction, an average is made over the 7 lines of the upper (U), central (C) and lower (L) bands.

The subtraction of the background estimate is not performed in the full dark limb conditions for Spectrometer A because it is negligible and subtracting it would add the noise of the Dark Charge of the two background bands. For spectrometer B (IR), it is not negligible, even during the night. There are indeed an O<sub>2</sub> emission around 760 nm, and OH emissions near 940 nm.

On the day side, the limb brightness is large. It saturates the spectrometers usually at altitudes lower than 26 km so that the background correction is no longer feasible. When any of the upper, central or lower band is saturated, the corresponding column is flagged and not used in the following processings.

### 5.3.11 Star signal and transmission

The stellar signal created by the background subtraction needs to be corrected for flat-fielding in order to get a valid estimate of the star spectrum. The nominal location of the star signal on the CCD, the SATU output data, the photometer engineering data

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and the PRNU full maps are used in flat-fielding. The flat-fielding is most important for the spectrometers B1 and B2 (up to  $\pm 20\%$  for B2, due to an optical interference in the coating of the CCD, and of the order of  $\pm 1$  to  $2\%$  for A1 and A2). The exact position of the star communicated by the SATU is taken into account. In spite of these refinements, we found that the PRNU effect was not corrected perfectly for the B2 spectrometer, dedicated to H<sub>2</sub>O measurements at 936 nm. We suspect that this is because the star light is extremely well focused on the CCD, and that the pixel response is not uniform on one pixel. For the next version of the processing, a new sub-pixel PRNU map will be used, which could be established when the plane mirror made unwanted excursions over the SATU detector (Bertaux et al., 2009).

Once the corrected star signal  $S_{\text{obs}}$  is corrected as described above, the 10 first spectra (obtained above 120 km) are averaged together to form the reference spectrum  $S_{\text{ref}}$ , and the atmospheric transmission  $T_{\text{obs}}$  for each sample is calculated on a fixed reference wavelength grid (one value per spectel) as the ratio:

$$T_{\text{obs}} = S_{\text{obs}}/S_{\text{ref}} \quad (5)$$

This is the actually measured transmission, not corrected from dilution nor scintillations. Therefore, in some extreme cases of scintillations, it may be larger than 1. These corrections are done during Level 2 processing.

### 5.3.12 Error bar on the transmission

All level 1b products are accompanied by error estimates. These estimates are calculated assuming that there is no modelling error and normal Gaussian error statistics. The pixelwise data are assumed to be independent on each other. The error is estimated from Poisson statistics on the number of electrons, the CCD read-out noise, the digitization step (one ADU corresponds to different numbers of electrons for the various CCDs and operating modes), the error on the background subtraction, as described in more details in Kyrölä et al. (2009). All these error estimation formulas have been validated by simulations and by in-flight statistical analysis of measurements.



### 5.3.13 Photometer data processing to reach Level 1b

The photometer data (red and blue channels) are measured with a sampling rate of 1 kHz and each sample corresponds to a time integration of 1 ms. The detectors are CCDs of 16x16 pixels, but only 14 lines are binned together, and five central columns only are read separately to procure a signal in ADU, and added together digitally.

Because of the 12 bits capacity of the on-board adder included in the photometer electronic chain, only the 12 least significant bits are written in the GOMOS packets. In case of overflow, the analysis of the temporal series usually allows to rebuild the original signal by continuity (unfolding algorithm). This algorithm may fail for Sirius (strongest signal) and in case of strong scintillations.

There is also a Dark Charge correction, and the total of ADUs after unfolding is converted in electrons in the processing with the appropriate gain.

A strong sub-pixel response is present in these small CCDs, as was discovered recently.

## 5.4 Level 1b to Level 2 processing

### 5.4.1 Level 2 products and processing overview

Starting from the Level 1b products, the Level 2 processing aims at computing the following Level 2 products for each tangent altitude measurement:

- The local densities (or concentrations in  $\text{cm}^{-3}$ ) of ozone,  $\text{NO}_2$ ,  $\text{NO}_3$ ,  $\text{OCIO}$ ,  $\text{O}_2$ ,  $\text{H}_2\text{O}$  and their error bar
- The line densities (also called slant densities,  $\text{cm}^{-2}$ ) of the same species and their error bar, which are the concentrations integrated along the line of sight.
- The aerosol extinction and its wavelength dependence
- The temperature with a high vertical resolution (available in the next re-processing)

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- The geolocation of these data
- The air density given in the ECMWF/MSISE-90 model, and the corresponding integrated line density along the LOS. This product obviously does not come from GOMOS data, but is recommended to be used when one want to compute a mixing ratio from GOMOS density products.

All these products give one vertical profile for each stellar occultation, with about 30-40 occultations per orbit.

The processing is divided in two sequential steps:

1.the spectral inversion, which gives the line densities for a given transmission measurement

2.the vertical inversion, which provides the local densities from the line densities.

This second step assumes that the distribution of species has a locally spherical symmetry, while the extraction of line densities are independent of such an assumption. In addition, the line density data are noisier than the line densities, because the vertical inversion introduces some oscillations that are smoothed out by a Tikhonov regularization, decreasing somewhat the vertical resolution. Therefore, the time variations and long term trends may be studied, not only on the local densities, but also directly on the line densities.

The spectral inversion is quite different for spectrometer A and B, and they are treated almost fully separated. The reason is that, in the UVIS domain of spectrometer A, the forward modelling of the transmission is rather fast, and is used in a best fit approach with Levenberg-Marquardt scheme; while for O<sub>2</sub> and H<sub>2</sub>O absorption calculations, a line-by-line must be computed with the HITRAN data base, with a prohibitive computing time.

The GOMOS Level 2 data processing assumes that a measured transmission  $T_{\text{obs}}$  (produced by the GOMOS Level 1b processing) can be taken as a product of two transmissions:

$$T_{\text{obs}} = T_{\text{ref}} T_{\text{ext}} \quad (6)$$

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The transmission  $T_{\text{ref}}$  is due to refractive effects and the transmission  $T_{\text{ext}}$  is due to absorption and scattering processes in the atmosphere. The Level 2 processing aims first to estimate the refractive part using the fast photometer data and the geolocation data, and then to remove it from the measured transmission. The remaining transmission  $T_{\text{ext}}$  can then be connected to the atmospheric constituent densities, the retrieval of which is the main mission objective of the GOMOS instrument. This transmission can be written as:

$$T_{\text{ext}} = e^{-\tau} \quad (7)$$

where the optical thickness  $\tau(\lambda)$  is given by an integral along the line of sight  $s$ :

$$\tau(\lambda) = \sum_j \int \sigma_j(\lambda, r(s)) \rho_j(r(s)) ds \quad (8)$$

in which  $\rho_j$  is the density of species  $j$ , with absorption cross section  $\sigma_j(\lambda)$ . The simplifications discussed in Kyrölä et al. (2010a) lead to some inaccuracies of the modelling but they are counteracted by performing iteration loops. After performing spectral and vertical inversion we perform the sequence again and so on. Usually one iteration is enough to converge.

In the forward model to compute the model transmission to be compared to  $T_{\text{ext}}$ , one must take into account the finite measurement time (0.5 s) of GOMOS. During this time the tangent point altitude can change by up to 1.7 km, for occultations in the orbital plane. For occultations outside the orbit plane this movement is smaller leading to a better vertical sampling resolution.

Also, because of the finite spectral resolution of the instrument, we cannot simply use the cross sections as such in the inversion. One solution often chosen is to convolute the cross-sections by the instrumental profile, which is mathematically incorrect. Rather, we convolute the model transmission by the instrumental profile.

## 5.4.2 Refraction corrections

The scintillation and dilution correction process is based on the assumption that the modulation due to refraction may be splitted into two independent terms:

$$T_{\text{ref}} = T_{\text{dil}} T_{\text{sci}} \quad (9)$$

5 where  $T_{\text{dil}}$  represents the dilution component and  $T_{\text{sci}}$  represents the effect of scintillation. The dilution is due to the fact that refraction is bending more and more the star light rays when the impact parameter is decreasing. It depends on the derivative of the refractive index with altitude, and on the distance of the observer to the limb. This is one reason for which the stellar occultation is not very appealing from a geostationary  
10 orbit.

The scintillation is derived from the fast fluctuations of the photometers, assuming that the fluctuations due to extinction by species are negligible at these small vertical scales, which is justified by the geometry of the line of sight, integrating over  $\sim 300$  km. Once  $T_{\text{dil}}$  and  $T_{\text{sci}}$  are determined, the observed transmission  $T_{\text{obs}}$  is divided by  $T_{\text{ref}}$ , to  
15 obtain the transmission due only to the extinction spectrum  $T_{\text{ext}}$ .

Since the refraction depends on the wavelength, one transmission spectrum is probing slightly different altitudes. A correction of chromatic refraction is made, by a linear interpolation between two consecutive acquisitions, and this corrected transmission is then fitted by a forward model of the transmission, depending on all the species that  
20 we want to determine.

## 5.5 Spectral inversion of Spectrometer A (UVIS)

### 5.5.1 Cross sections

As described in more details in Kyrölä et al. (2010), some refinements are introduced to take into account the finite integration time of the instrument, the finite spectral resolution of the imaging system (as well as the combined of effects of these two processes),  
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and the temperature dependent value of the cross section (important for UV absorption of ozone). The cross-sections and their temperature dependence are taken from the GOMOS data base (Figs. 2 and 3).

## 5.5.2 Aerosols

5 Unlike the other trace gases retrieved by the spectral inversion of GOMOS transmission data, the slant path optical thickness  $\tau_a(\lambda)$  of the aerosols and of the stratospheric or mesospheric clouds is not characterized by a well defined extinction cross section that can be measured in the lab. Instead, the spectral dependence of  $\tau_a(\lambda)$  is a product of the inversion, not a data. In the UV-visible range, the extinction of light results from the  
10 Mie scattering by a population of particles whose size distribution is a priori unknown. Important diffractive effects are expected when the wavelength matches the characteristic particle size. However, these effects are smoothed out when integrated over an extended particle size distribution allowing to express  $\tau_a(\lambda)$  by a smooth (polynomial) wavelength dependence as:

$$15 \tau_a(\lambda) = \tau_a^{[0]} + \tau_a^{[1]}(\lambda - \lambda_{\text{ref}}) + \dots + \tau_a^{[p]}(\lambda - \lambda_{\text{ref}})^p \quad (10)$$

and the spectral inversion consists of retrieving the quantities  $\tau_a^{[0]}, \tau_a^{[1]}, \dots, \tau_a^{[p]}$ .

The present stratospheric transparency is very high due to the quasi-unperturbed relaxation of Pinatubo aerosol load since 1991, which makes the measurement of stratospheric aerosols a difficult task. Therefore we restricted the description of the aerosol  
20 slant path optical thickness to a form  $\sigma_0/\lambda$  wavelength dependence in the current operational version of the algorithms, GOPR 6 (also called IPF 5).

During volcanic periods like the aftermath of Mount Pinatubo eruption (Fussen et al., 2001) large stratospheric particle formation has been observed up to radii of 0.5–0.7  $\mu\text{m}$  that induced a broad maximum in the optical wavelength dependence.  
25 The wavelength dependence was modified for the new version GOPR 7, by taking a quadratic form to describe  $\tau_a(\lambda)$ . The arbitrary reference wavelength has been fixed

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at  $\lambda_{\text{ref}} = 500 \text{ nm}$  after an empirical optimization of the covariance matrix elements. Tamminen et al. (2010) have studied the influence on ozone line density retrieval of taking various forms of the aerosols wavelength dependence. There are some significant differences below 20 km.

### 5.5.3 Air density

Before launch we thought that the air density could be retrieved from its Rayleigh extinction. However, because of coupling with aerosol extinction and  $\text{NO}_2$  cross-section, the achieved accuracy was not satisfactory. We decided to fix the neutral density to the value given by ECMWF for altitudes below 1 hPa and to MSISE-90 model above. After all, ECMWF are based on actual measurements made all over the planet, updated every 6 h.

### 5.5.4 $\text{NO}_2$ and $\text{NO}_3$

In the 20–40 km altitude range, chromatic scintillations caused by isotropic turbulence, create perturbations in GOMOS transmission spectra. These lead to unrealistic oscillations in the vertical profiles of line densities of  $\text{NO}_2$  and  $\text{NO}_3$ . The scintillation correction step is unable to remove these scintillations from the transmission data. In order to improve the retrieval, a variant of DOAS (Differential Optical Absorption Spectrum) named GDI (Global DOAS Iterative) is applied for  $\text{NO}_2$  and  $\text{NO}_3$ .

In the GDI a species is artificially separated into two virtual species  $X_S$  and  $X_D$  with their respective cross-sections, one which has a cross-section varying smoothly with wavelength, the other having a rapidly varying cross-section, the sum of the two cross section being equal to the total cross section of  $\text{NO}_2$  (or  $\text{NO}_3$ ).

The spectral inversion is performed in two phases. The first Levenberg-Marquardt fit is applied with  $X_S = 0$  and  $X_D$  as a free parameter together with all other species that we want to retrieve. The fit gives a first value  $X(1)_D$ . The second fit is applied with  $X_S = X(1)_D$ . A second value  $X(2)_D$  is obtained. The process is iterated until the

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maximum number of iterations is performed or until a given convergence criterion is reached.

## 5.6 Spectral inversion of IR spectrometer B (O<sub>2</sub> and H<sub>2</sub>O)

The IR spectrometer measures the densities of two different constituents O<sub>2</sub> and H<sub>2</sub>O in two bands: 756–774 nm (spectro B1) and 926–954 nm (spectro B2) respectively. Due to the physics of the problem, the individual absorption lines are very narrow and saturated, the apparent cross sections change with the integrated densities, and they can no longer be considered as only wavelength dependent. The calculation of the transmission function is computationally very demanding. Therefore, it is difficult to use the same direct inversion method as for the UVIS spectrometer data.

A new algorithm has been developed. The method uses reference transmission spectra  $T_{\text{mod}}(\lambda, N)$  that are calculated for different integrated line densities  $N$  of O<sub>2</sub> and H<sub>2</sub>O. These reference transmissions depend on pressure and temperature. To take into account this dependency, calculations of transmission are performed by using a direct model with a standard atmospheric profile. Several such calculations are done for different atmospheric models (US Standard 76) in order to get the response for 5 different conditions such as tropical, mid-latitude (winter and summer) and subarctic atmospheric profiles. The calculations were made in steps of 1 km altitude from 0 to 100 km, with the highest possible wavelength resolution allowed by the HITRAN data base, and the radiative transfer code LBLRTM. Then, they are convoluted with the spectral function of the instrument and integrated over each spectral wavelength interval (0.046 nm for B1 and 0.056 for B2). They constitute transmission model tables, or LUT (Look Up Tables).

For each measured transmission  $T_{\text{obs}}$  at an altitude  $z$ , and for the climatic table appropriate to latitude and season, a scatter plot of  $T_{\text{obs}}$  as a function of  $T_{\text{mod}}(\lambda, N)$  is made for all pixels of B1 (or B2) separately in log coordinates, for a number of altitudes  $z_i$  (and corresponding  $N_i$ ), around the altitude of measurement. A best-fit linear fit yields a value of the slope  $a_i$ ; in the series of  $a_i$ , two consecutive values are bracketing

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the value 1. A linear interpolation for  $a=1$  is then done in the series  $a_i, N_i$ , yielding the retrieved best-fit line density  $N_{ret}$ .

In order to take into account a possible residual continuous extinction and its possible wavelength dependence, the fitting function of the scatter plot is of the form:

$$\ln(T_{obs}) = a \ln(T_{mod}(\lambda, N)) + b/\lambda + c \quad (11)$$

and the parameters  $b$  and  $c$  are also retrieved in the process. Actually, for the  $O_2$  band at 760 nm, there is a small absorption by ozone in the Wulf bands. Therefore, the observed transmission  $T_{obs}$  is first corrected from the extinction of ozone, as determined from the spectral inversion of spectrometer A. In addition, the Rayleigh extinction by air (fixed with ECMWF and MSISE-90), and the aerosol extinction extrapolated at the wavelength of spectrometers B1 and B2 are also computed for a further correction of  $T_{obs}$ , before the comparison with the tables of  $T_{mod}$ .

The values of  $b$  and  $c$  are not used at present. They may represent a deviation of the wavelength dependence of aerosol extinction far away from the reference wavelength (500 nm). However, one should be cautious, since the dilution and scintillations may change quite severely the level of the continuum, and though the processing does try to correct for it, the value of  $c$  may not represent only the aerosol extinction. At any rate, the value of  $a$  is independent of  $c$ . Due to its nature, this method has been called "comparative method".

## 5.7 Vertical inversion

The GOMOS vertical inversion aims to find a vertical profile that, when integrated along the various lines of sight during one occultation, gives the measured line densities  $N$ . This is the inversion of Abel's integral. The number of layers is given by the number of measurements in the occultation processed. The resulting problem is a readily solvable linear inversion problem. By the triangular nature of the kernel matrix the inversion can be done using the so-called onion peeling method. While in its standard version, the onion peeling technique yields layers with constant density in each layer, for GOMOS

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we approximate the local densities to be linear as a function of altitude between two successive GOMOS measurements.

The fact that line densities are an average over the integration time is dealt with a Taylor expansion. Unphysical oscillations attached to the classical problem of inversion of Abel's integral are smoothed by a special type of Tikhonov regularization (Sofieva et al., 2004). The parameters of such a regularization were selected to provide a constant vertical resolution over some range of altitudes: 20 to 30, 30 to 40, above 40 km. The resolution aimed at is respectively in the 3 regions:

O<sub>3</sub>: 2,2–3,3 km

Aerosols,NO<sub>2</sub>,NO<sub>3</sub>,OCIO: 4,4,4 km

O<sub>2</sub> : 3,3–5,5 km

H<sub>2</sub>O: 2,4,4 km.

Once the vertical inversion is done, the spectral inversion is done once more, in order to take into account the temperature dependence of the cross sections. This loop is necessary because temperature dependent cross sections in the extinction line-of-sight integrals (Beer-Lambert formula) couple the spectral and vertical inversion problems.

## 5.8 Error estimate

The error estimate is based on the propagation of all Level 1b errors, largest contributors of which are dark current and photon noise, through the spectral and vertical inversions. An additional error source in Level 2 is the step where intensity fluctuations from scintillations are removed using photometer data. In the currently available GOMOS data (IPF5, GOPR 6) , this additional error is estimated empirically from large numbers of equatorial measurements with varying azimuth angle. The underlying assumption is that the ozone distribution around the equator is relatively constant and the variability of ozone profiles comes from the scintillations. In the new version GOPR 7.0 of the processing, this is replaced by the use of a full co-variance matrix between spectral pixels: scintillations are perturbing the spectrum, with a strong covariance between

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adjacent pixels. The retrieved quantities are not different from the previous version GOPR 6, but the error bars are somewhat reduced, and are much better estimated.

Figure 22 (from Tamminen et al., 2010) shows the new error estimate on ozone and NO<sub>2</sub>, for various stars (brightness and temperature), and for vertical or oblique occultations (more sensitive to scintillation errors). For ozone, the retrieval error of the night time measurements is typically 1–5% in the stratosphere, and better than 8% up to 100 km, except for cool stars above 40 km. The precision between 20–40 km is around 1–3% and below 20 km it is degrading to 10% at 15 km. With reasonably bright stars NO<sub>2</sub> can be measured at 20–50 km altitude range with 10–20% precision. NO<sub>3</sub> can be measured in the 25–45 km altitude range with a precision of 20–40% with bright and medium brightness stars. The aerosols can be measured up to 30 km with about 5–10% precision. Below 15 km the precision degrades to 30% (Tamminen et al. 2010) have also shown that the increasing CCD dark charge (Fig. 18) degrades the ozone precision from 1.5% to 2.8% (2008) for a dim star (n° 124), while the degradation is weak or negligible for bright stars.

## 5.9 High resolution temperature profile

Besides the scintillation correction, the photometers signals provide a way to study small scale structures in the atmosphere. A high resolution temperature profile can be derived from time delay of the two photometers. This is one of GOMOS Level 2 products for IPF 6. The algorithm is based on the computation of the time delay between the signals of the two photometers. Due to the variation of the index of refraction of air with wavelength, the light beam of an occulted star is more bent in the blue part of the spectrum than in the red part. For a given tangent altitude, the red beam reaches GOMOS before the blue beam (see Fig. 17). The computation of the time delay gives information on the bending angle which is related to the density and temperature profile in the atmosphere. This method allows to derive a high resolution temperature profile with a vertical resolution of 100–200 m, in the altitude range ~20–40 km, where scintillations are most pronounced (see Sect. 7.14).

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## 6 Validation of GOMOS products

In principle, the star occultation method is self-calibrated, and does need to be validated, since an absolute quantity is derived from a relative measurement. The reality is more complex (in a large part due to scintillations), and the comparison with other sources of similar data (validation exercise) allows to make adjustments to the processing, or even to detect errors. One good example is the retrieval of H<sub>2</sub>O, which showed a systematic maximum of ~9 ppmv at 29 km, while other instruments never showed such a behaviour. This bias could be traced back to an unexpected strong sub-pixel PRNU of spectrometer B2 (Bertaux et al., 2009).

The GOMOS data validation activity has been carried out since the summer of 2002. The most useful comparison for ozone was made by Meijer et al. (2004), with balloon-borne ozone sondes, lidars, and microwave instruments, which all give vertical profiles like GOMOS. The results show that in dark limb the GOMOS data agree very well with the other data: between 14 and 64 km altitude their differences show only a small (2.5–7.5%) insignificant negative bias with a standard deviation of 11–16% (19–63 km). This conclusion was demonstrated to be independent of the star temperature and magnitude and the latitudinal region of the GOMOS observation, with the exception of a slightly larger bias in the polar regions at altitudes between 35 and 45 km. GOMOS, MIPAS and SCIAMACHY measurements of O<sub>3</sub> and NO<sub>2</sub> have been compared by Bracher et al. (2005). In the mesosphere and lower thermosphere only satellite data are available for validation purposes. GOMOS ozone results have been compared with MIPAS by Verronen et al. (2005). A general agreement between these two instruments has been found but at that time too few coincident measurements were available for a definitive comparison. Another ozone profiles interesting comparison was made in the tropics with SAOZ long duration balloon measurements in 2003 and 2004 (Borchi and Pommereau, 2007), together with other instruments.

One way to check the internal consistency of the GOMOS data and retrieval scheme is to compare the vertical profile of ozone obtained at the same geographical location,

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but at two different (successive) orbits, and using two different stars (at 2 consecutive orbits, the same star is occulted at the same latitude, but at longitudes differing by about 25°). This was done in Fig. 23, where the tangent points of two consecutive orbits was differing by only 25 km. The two vertical profiles are in excellent agreement, and show also the unique capability of GOMOS to measure mesospheric ozone at night. It should be noted that, while it is assumed, in the vertical inversion, that the ozone distribution is locally spherically symmetric, in reality there are horizontal variations of the local density. As a result, the line density integrated at a given tangent altitude may depend on the angle of the line of sight (with the meridian circle, for example). Calculations have shown that there may be 4% variation in a modelled ozone 3-D field, and this may account for some of the small differences seen in the two profiles of Fig. 23.

## 7 Overview of GOMOS results

### 7.1 Ozone climatology in the stratosphere

Before GOMOS on ENVISAT, the best ozone climatology (based on measurements) was produced by Fortuin and Kelder (1998) (hereafter, F-K), primarily based on ozone sondes up to 30 km, and satellite data above 30 km from SBUV and SBUV-2, using nadir backscattered solar UV, which have an inherently coarse vertical resolution, and stopping at 0.3 hPa (~55 km).

GOMOS was able to provide the first climatology of ozone extending up to 100 km, thus covering the mesospheric ozone layer, and with a good vertical resolution. It was produced from all night-time star occultations recorded during the year 2003 (Kyrölä et al., 2006). The night-time limit was set at a solar zenith angle of 108°, and 43 000 occultations were kept in the analysis, binned by month and latitude zone of 10° (zonal average). The quality was controlled by checking the retrieved ozone profiles for each star individually. The altitude range covered from 10 to 100 km, covering the whole stratosphere and the mesosphere lower thermosphere (MLT) at the same time. For

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the cool stars (with no UV flux), the maximum valid altitude was 35 to 45 km. Mixing ratios were computed with air densities from ECMWF below 50 km, and MSIS-90 model above, included in the GOMOS products, and the yearly mean is represented in Fig. 24.

This 2003 climatology is compared (Fig. 25) to the earlier F-K stratospheric climatology, in the yearly average. In the upper stratosphere above 45 km, GOMOS show more ozone by 5–10% (increasing with altitude), explained by the diurnal cycle of ozone at these altitudes: GOMOS measures at night, while SBUV data are day side. At low altitudes (15–25 km) near the equator, GOMOS finds less ozone than F-K (up to 20% deficit). The GOMOS results are not so reliable below 18 km, but the discrepancy in the region 18–23 km is probably real, with an unclear reason up to now. Finally, there is a conspicuous deficit in both polar regions, very much more prominent in the South. This is the signature of the ozone hole, greater in 2003 than the earlier times of F-K data. However, the time evolution of this relative difference GOMOS versus F-K indicates that the deficit appears already in March, and grows during the South polar night (Kyrölä et al., 2006). Both deficits are probably linked to an increase of NO<sub>2</sub> in the polar winters of 2003, w.r.t. the period around 1985 pertinent to the F-K climatology.

A more recent analysis is providing ozone time series analysis for the period covering the six years period 2003-2008. (Kyrölä et al., 2010b). The average of ozone vertical profiles are displayed on Fig. 26 for the various latitude bins.

The ozone density in the stratosphere has a (well-known) seasonal behavior, with a maximum appearing during winter-spring months. The ozone-column in the range 15–100 km is calculated to be 243.7 Dobson at the equator, 263.7 Dobson in south mid-latitudes and 271 Dobson in North mid-latitudes for the period 2003–2008. Two reasons are acting to have more ozone in the North mid-latitudes than in the South. The main reason is the greater activity of planetary waves in the Northern Hemisphere re-enforcing the Brewer-Dobson circulation. The second reason is the more severe man-made depletion in the Southern Hemisphere (–5.5%) than in the North (–3%), as a result of air masses migrating from polar vortex toward lower latitudes; but this accounts for only 6 Dobson difference between North and South mid-latitudes, out of

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## 7.2 Ozone climatology in the Mesosphere-Lower Thermosphere (MLT)

The night-time occultations of hot stars, which spectra are UV-rich (highest cross section of ozone), allows to measure ozone in the MLT with unprecedented refinement and coverage. In the MLT (Fig. 27) ozone exhibits a bi-annual oscillation (Kyrölä et al., 2010b), with maxima at solstices and minima at equinoxes. This behavior has been explained by Garcia and Solomon (1985), invoking the effect of enhancement of gravity waves breaking at both solstices. They transport more H<sub>2</sub>O from below, a source of H, OH and HO<sub>2</sub> radicals which initiate a catalytic cycle of ozone destruction in this region. It may be noted that at 40° North, the summer maximum lower boundary of the mesospheric ozone layer (at 85–87 km) is lower by 2–3 km than the winter maximum lower boundary. This might be related to the vertical eddy diffusion in this region, which has been shown through modeling to have a strong influence on the detailed vertical distribution of ozone (Smith, 2004).

## 7.3 The tertiary ozone maximum

The vertical profile of ozone mixing ratio presents usually two pronounced maxima (Fig. 28), in the stratosphere around ~25–30 km, and in the mesosphere around ~90 km, corresponding to the two regions of production. A third ozone peak (mixing ratio) was reported first by Marsh et al. (2001), observed at 72 km altitude near the polar night terminator.

In the mesosphere, ozone is destroyed by catalytic reactions involving odd hydrogen (HO<sub>x</sub> = H + OH + HO<sub>2</sub>), as discovered by Bates and Nicolet (1950). As a result, ozone is almost fully absent at an altitude of ~80 km. The tertiary ozone maximum (TOM) is explained by low concentrations of odd-hydrogen and subsequent decrease of destruction rate of O<sub>3</sub>, as modeled by Marsh et al. (2001). The reason is the decrease of H<sub>2</sub>O photolysis by a lack of solar UV radiation at high latitudes in winter. However,

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the predicted peak amplitude is  $\sim 7$  ppmv, while MLS and CRISTA observations were rather showing  $\sim 3$  ppmv. It was suggested that the observed peak was underestimated by the instrumental FOV extent (Marsh et al., 2001).

GOMOS measurements, with their very good vertical resolution, are not affected by this problem (Fig. 28). Sofieva et al. (2004, 2009) have reported the analysis of 4 years of GOMOS data in the night (131 500 occultations), yielding the first spatio-temporal distributions of tertiary ozone maximum (Fig. 29). This experimental TOM distribution was compared with that simulated by the WACCM model (The Whole Atmosphere Community Climate Model) developed under the leadership of NCAR. WACCM is a global model that extends from the ground to  $4.5 \times 10^{-6}$  hPa, approximately 145 km.

We may summarize the findings of Sofieva et al. (2009b) on Tertiary Ozone Maximum as follows:

- the modelling of Hartogh et al. (2004) predicting large ozone values around the pole at upper altitudes (down to 75 km), as a result of strong downward transport of atomic oxygen from the thermosphere, is not confirmed by the GOMOS data.

- the observed tertiary ozone maximum is not clearly isolated from the high latitudes, at variance with the model prediction in Hartogh et al. (2004).

- The overall evolution of the latitudinal distribution of ozone mixing ratio at  $\sim 72$  km (Fig. 29, bottom) is well reproduced by the WACCM model. The only difference is that WACCM predicts slightly larger ozone mixing ratios (up to 5 ppmv) than that observed by GOMOS (not exceeding 4 ppmv, Fig. 28).

- The TOM is sometimes fully destroyed by two types of events: by sudden stratospheric warmings, followed by a strong downward transport of upper mesospheric air rich in NO, another scavenger of ozone (through  $\text{NO}_2$ ), as discussed for example by Hauchecorne et al. (2007) for the January 2004 event, and by energetic particles precipitation such as Solar Proton events (SPE), as discussed in Seppälä et al. (2006) for the January 2005 SPE event.

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## 7.4 Climatology of NO<sub>2</sub> and special events of NO<sub>2</sub> enhancements in the polar night

As a catalytic scavenger of ozone, NO<sub>2</sub> is important to monitor at the same time. The main source of NO<sub>2</sub> is the oxidation of N<sub>2</sub>O by atomic oxygen. Other significant potential sources are the upward transport of NO<sub>2</sub> produced by lightning in the tropical upper troposphere and the downward transport of NO from the thermosphere or the mesosphere in the winter polar vortex.

Partitioning of odd nitrogen family, defined as NO + NO<sub>2</sub> + NO<sub>3</sub> + N<sub>2</sub>O<sub>5</sub>, is controlled in the stratosphere by the fast photochemical equilibrium between NO and NO<sub>2</sub> and the slow photo-dissociation of N<sub>2</sub>O<sub>5</sub> during daytime and the slow conversion of NO<sub>2</sub> into NO<sub>3</sub> and then into N<sub>2</sub>O<sub>5</sub> during nighttime. Owing to these photochemical reactions, the NO<sub>2</sub> concentration is never constant. It is slowly decreasing by night and increasing by day and rapidly increasing at sunset and decreasing at sunrise. It is therefore very important to take into account the local time when comparing measurements made by different instruments. In the case of GOMOS, nighttime observations are made during the ascending path of Envisat and the local time is approximately equal to the local hour of the ascending node, 22:00 LT.

Hauchecorne et al. (2005) have established a first climatology of night time NO<sub>2</sub> from GOMOS occultations, represented in Fig. 30 under the form of mixing ratios monthly maps in latitude-altitude (zonal average).

At mid and low latitudes, a maximum in the vertical profile is observed around 40 km in both hemispheres. The peak value ranges from 14 to 16 ppbv depending on the month and its latitude location varies between 20° S and 20° N with a shift toward the summer/autumn hemisphere, to the south from February to April and to the north from August to November. This value is slightly smaller than the results of Reburn et al. (1996) who found a 17 ppbv peak of night time NO<sub>2</sub> around 3 hPa (~40 km) in ISAMS and LIMS (limb infra red emission) January data at equatorial and south tropical latitudes. At high latitude, lower values are observed in general, except when a

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strong descent of air enriched in  $\text{NO}_x$  ( $\text{NO} + \text{NO}_2$ ) of mesospheric or thermospheric origin occurs inside the winter polar vortex.

It is interesting to note the strong peak of  $\text{NO}_2$  above 38 km, with up to 38 ppbv at 50 km, in the northern high latitude upper stratosphere in November. This peak has been attributed by Seppälä et al. (2004) and Hauchecorne et al. (2006) to the formation of a large amount of  $\text{NO}_x$  during the very intense solar proton event at the end of October 2003. Such  $\text{NO}_2$  enhancement after strong solar proton events have been observed and simulated in the past (Jackman et al., 2000, 2001; Verronen et al., 2002). A very high mixing ratio (up to 36 ppbv at 50 km) is also detected in July at southern high latitude. In this case it is probably due to the strong diabatic descent of mesospheric and thermospheric air with high  $\text{NO}_x$  mixing ratio in the southern winter polar vortex.

Indeed another  $\text{NO}_2$  descent event in 2004 was clearly not associated with particle precipitation, but rather to a dynamical cause (Hauchecorne et al., 2007). A layer of strongly enhanced  $\text{NO}_2$  was detected by GOMOS/ENVISAT starting on January 15, 2004 at 65 km in the North polar stratosphere with mixing ratios up to 1000 ppbv (Fig. 31). The descent of the layer can be followed until March 10 down to 45 km. The simultaneous destruction of  $\text{O}_3$  in the layer is clearly detected. An intense warming was observed in the north polar middle mesosphere at the time of formation of the  $\text{NO}_2$  layer by SABER/TIMED. This warming is an indication of a strong air descent in the polar vortex bringing a large quantity of NO from the lower thermosphere. When such a descent occurs in the polar night, NO cannot be photo-dissociated before reaching an altitude where it is stable and it can be transformed in  $\text{NO}_2$  by reaction with  $\text{O}_3$  (~60–65 km). Large  $\text{NO}_2$  enhancements in the polar winter upper stratosphere/lower mesosphere have been observed in the past. They were attributed to the production of NO by large energetic particle precipitations (solar proton or energetic electron precipitations). These events are relatively rare. In the present 2004 case no significant particle precipitation was reported and we attribute the event to a pure atmospheric dynamical phenomenon, the breaking of atmospheric waves in the upper mesosphere

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inducing a strong descent of thermospheric NO into the polar vortex. If the proposed mechanism appears to be frequent, it will be necessary to reevaluate the contribution of stratosphere-mesosphere-lower thermosphere dynamical coupling in the polar stratospheric ozone budget.

## 5 7.5 The influence of the QBO on tropical stratospheric ozone, NO<sub>2</sub> and NO<sub>3</sub>

In a companion paper of this GOMOS ACP issue, Hauchecorne et al. (2010) have investigated the impact of the Quasi-Biennial Oscillation (QBO) of the equatorial wind on the inter annual variations of ozone, NO<sub>2</sub>. A six years period of GOMOS data from August 2002 to December 2008 recorded between 15° S and 15° N was analyzed, first by establishing a seasonal mean, and then dividing all data by this seasonal mean. It is found that the QBO of the equatorial wind induces variations in the local concentration larger than 10% for O<sub>3</sub> and larger than 25% for NO<sub>2</sub>. The NO<sub>2</sub> and QBO signals are out of phase below 36 km and in phase above 36 km. The correlation between the excess of NO<sub>2</sub> and those of O<sub>3</sub>,  $dO_3/dNO_2$  is displayed in Fig. 32. It has a strong vertical structure. Below 28 km, the correlation is the sign of dynamical control of these species, while above 28 km, there is an anti-correlation, which is due to chemical control, through the catalytic destruction of O<sub>3</sub> by NO<sub>x</sub>. This transition was already observed in the data of SAGE II and explained as described above by comparison with models, by Chipperfield et al. (1994) and Tian et al. (2007). The GOMOS results (Fig. 32) show a new transition at 36 km, previously undetected, for which a new explanation is now proposed (Hauchecorne et al., 2010).

## 7.6 Climatology of NO<sub>3</sub> and temperature retrieval

The measurement of the nitrate radical NO<sub>3</sub> by the GOMOS instrument on board the ENVISAT platform is the first satellite measurement of this species (Fig. 14). NO<sub>3</sub> exists only at night, being photo-dissociated very quickly. Therefore, it is not possible to measure it with solar occultations, and it has no strong infra-red emission.

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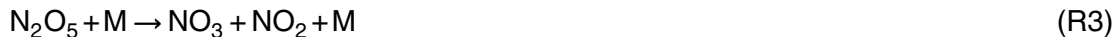
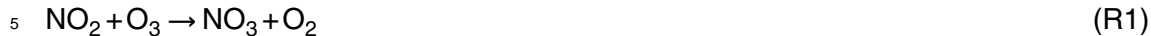
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A climatology of NO<sub>3</sub> has been established for the first time from 2003 night time GOMOS measurements (Hauchecorne et al., 2005), for the same occultations producing NO<sub>2</sub> climatology. The chemistry of NO<sub>3</sub> is rather simple, being associated to O<sub>3</sub>, NO<sub>2</sub> and N<sub>2</sub>O<sub>5</sub>, with the following three reactions:



NO<sub>3</sub> is produced by reaction of NO<sub>2</sub> with O<sub>3</sub> (Reaction R1). This reaction, whose rate constant is strongly temperature dependent, affects the nighttime decay rate of NO<sub>2</sub>. The NO<sub>3</sub> sink in the stratosphere is its reaction with NO<sub>2</sub> (Reaction R2) which produces N<sub>2</sub>O<sub>5</sub>. Finally, the other source of NO<sub>3</sub> is the thermal decomposition of N<sub>2</sub>O<sub>5</sub> (reaction 3). The NO<sub>3</sub> concentrations are close to zero on the day side.

The main features found for NO<sub>3</sub> climatology are as follows. A peak mixing ratio of up to 320 pptv is reached between 41 and 45 km. At low latitude, a semiannual variation is observed in NO<sub>3</sub> peak concentration and stratospheric column with a maximum at equinoxes (Fig. 33). At middle and high latitudes, the variation of NO<sub>3</sub> is annual with a maximum in summer. The peak concentration is linked to the total column 25–50 km, plotted in zonal average (latitude/season) in Fig. 33. The NO<sub>3</sub> mixing ratio in the upper stratosphere is also correlated with temperature through the thermal dependence of Reaction (R1):

NO<sub>2</sub> + O<sub>3</sub> → NO<sub>3</sub> + O<sub>2</sub>, and consequently the maximum NO<sub>3</sub> column follows more or less the latitude of the sub-solar point.

Indeed, from their NO<sub>3</sub> climatology GOMOS data Hauchecorne et al. (2005) have correlated the NO<sub>3</sub> mixing ratio measured by GOMOS to the ECMWF temperature analysis at the point of occultation (Fig. 34). There is a clear dependence of NO<sub>3</sub> on temperature.

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In an interesting exercise, Marchand et al. (2004) have compared some GOMOS  $\text{NO}_3$  densities with those predicted by a chemistry model, in which the GOMOS ozone and  $\text{NO}_2$  densities were assimilated. Restricting the data to the best  $\text{NO}_2$  measurements (less than 30% error, 20–45 km) the plot of measured values versus model prediction may be fitted by a linear regression (Fig. 35), with a slope of  $0.98 \pm 0.04$ . The fact that linear regression slopes are so close to unity indicates that there is no substantial bias in GOMOS  $\text{NO}_3$  data. It also suggests that  $\text{O}_3$ ,  $\text{NO}_2$  and  $\text{NO}_3$  GOMOS measurements are self consistent chemically and that the nighttime  $\text{NO}_3$  chemistry is well understood.

In this exercise, Marchand et al (2004) have assumed that the stratospheric temperature was the one given by ECMWF analysis. However, it is possible to build a reverse approach: the local temperature may be determined from the simultaneous measurements of  $\text{NO}_2$ ,  $\text{NO}_3$  and  $\text{O}_3$  from GOMOS, by using the temperature-dependence of reaction rates in Reaction (R1) and assuming steady state equilibrium.

This was done by Marchand et al. (2007), in an attempt, never demonstrated before, to determine the temperature from chemical measurements. Figure 36 indicates the GOMOS retrieved temperature for a number of occultations of star Antares (Gomos star number 16), as a function of ECMWF temperatures. The GOMOS temperatures are warmer by about  $2^\circ\text{K}$ . When increasing the sample to 4938 occultations of 4 bright stars (for which the temperature is retrieved with a precision better than  $3.5\text{ K}$ ), between  $50^\circ\text{ S}$  and  $50^\circ\text{ N}$ , and 30 to 40 km of altitude, the bias and dispersion are found to be  $2.67^\circ\text{K}$  and  $3.01^\circ\text{ K}$  respectively.

What is the source of the bias? Assuming that ECMWF temperature represents the true temperature (no bias), Marchand et al. (2004) have determined how the rate constants of Reactions (R1) and (R2) should be modified from their current JPL recommended values, which are known for stratospheric temperatures with a 30% error bar. They found that the temperature bias could be eliminated by changing only the activation energy of Reaction (R1): instead of the JPL recommended value  $k_1 = 1.2 \cdot 10^{-13} \exp(-2450/T)$ , they propose a new temperature dependence:

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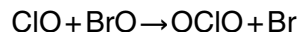
$k_1 = 1.2 \cdot 10^{-13} \exp(-2400/T)$ , which changes  $k_1$  by only 23%, within the uncertainty bar. This work is similar to the one of Renard et al. (2005), with somewhat different results. However, the work of Renard et al. (2005) relied on only a very limited number of balloon observations, while here the statistic sample is much larger.

It illustrates how the stratosphere itself may be used as a gigantic laboratory to determine fundamental reaction rates, provided that simultaneous measurements are performed under a known temperature and pressure environment.

In a similar way, the rate constant of many other reactions of stratospheric pertinence could be adjusted, by comparing GOMOS measurements (or others) to a prediction of a chemistry transport model, in which the GOMOS measurements would be assimilated. A systematic bias between Observed and Forecast would be the sign that something has to be changed in the description of the model, which relies on somewhat uncertain reaction rates.

## 7.7 GOMOS Observations of OCIO

GOMOS has detected the presence of a global OCIO layer in the upper stratosphere that had not been reported before (Fussen et al., 2006). Although OCIO is not directly responsible for the ozone destruction, it plays a fundamental role in the inorganic chlorine ( $\text{Cl}_y$ ) chemistry, responsible for the Cl-based catalytic destruction cycle of ozone, particularly active in the polar regions. It is indeed produced by a reaction involving ClO and BrO, another ozone catalytic scavenger:



and therefore OCIO is a proxy of ozone Cl and Br-based scavengers. The correct modeling of its abundance is a crucial test for our understanding of the stratospheric halogen chemistry. The major sink for OCIO is its rapid photolysis by the solar radiation due to a large absorption cross section well characterized by a strong differential structure in the UV wavelength range. This feature has allowed the measurement of OCIO, a species that is only present at very small concentrations.

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Since the first detection of atmospheric OCIO in Antarctica (Solomon et al., 1987), total column densities were retrieved from ground-based, airborne and satellite measurements. So far, the measurement of the vertical profile of the OCIO number density has been performed in a very limited number of experiments, and only in polar regions, as for example the balloon experiments reported by Pommereau and Piquard (1994), and Renard et al. (1997).

In this context, Fussen et al. (2006) have reported the first global determination of the stratospheric OCIO distribution measured during the year 2003 by the stellar occultation spectrometer GOMOS. The analysis was restricted to about 4500 occultations of the five brightest stars in the range 335–390 nm, where OCIO absorption spectral features can be detected through DOAS method, and distinguished from NO<sub>2</sub> spectral features. Fussen et al. (2006) had to average the transmission spectra in latitude bins of 5° (zonal and time average), in order to identify the small spectral features (below 0.01 differential transmittance). It provided the first latitude-altitude map of OCIO slant path densities, represented in Fig. 37, and compared to the prediction of BASCOE model (Errera and Fonteyn, 2006).

The strong enhancements in both polar nights were known; they are reproduced by the model, with however a much larger extension outside the polar vortex in the data of the north polar region. In addition, the data show the presence of a global OCIO layer in the upper stratosphere that had not been reported before. For more details on the spectral detection of OCLO with GOMOS, the reader is referred to Fussen et al. (2006).

Tétard et al. (2009) made a further study of OCIO GOMOS data, correlated with simultaneous O<sub>3</sub> and NO<sub>2</sub> measurements, and during several winters of the Northern Polar regions. In January 2008, the center of the polar vortex was strongly offset from the pole. As a result, along a constant latitude circle of 72°, strong variations of these species were observed to be correlated (as a function of longitude) in the lower stratosphere. Inside the polar vortex, NO<sub>2</sub> was weak, while OCIO was strong, with a reversed situation outside of the polar vortex. This was a sign of NO<sub>2</sub> trapping on PSC

particles in the vortex (under the form of  $\text{HNO}_3$ , denoxification) and halogen activation, since OCIO is a good qualitative indicator of chlorine activation, and a good quantitative indicator of ClO presence (Sessler et al., 1995).

## 7.8 Water vapor measurements at 936 nm

5 GOMOS is the first instrument measuring water vapor by the technique of stellar occultation. The status of GOMOS  $\text{H}_2\text{O}$  analysis was reported recently by Bertaux et al. (2009). Nine stars are sufficiently bright to provide useful measurements for stratospheric  $\text{H}_2\text{O}$ , with a reasonable latitude/season coverage. Figure 16 shows a comparison of a modeled transmission with one actual measurement. Based on the  $\text{H}_2\text{O}$  results obtained with version GOPR 6 of the software, Montoux (2008) has compared the  $\text{H}_2\text{O}$  GOMOS average measurements with the IR solar occultation HALOE on UARS, and the microwave limb sensor MLS on AURA. In the upper troposphere, GOMOS is thought to be correct, slightly higher than MLS data, while HALOE presents a significant dry bias. In the stratosphere, neither HALOE nor MLS show the bump present in the GOMOS data around 30 km (Fig. 38, left), while all 3 sets of measurements are similar around 40 km, at  $\sim 5$  ppmv (oxidation of methane produces  $\text{H}_2\text{O}$  at this altitude). This exercise of validation (in fact, invalidation in this case) led the GOMOS team to review in detail the  $\text{H}_2\text{O}$  data processing. A problem was identified: the CCD dedicated to 926 nm radiation present a severe pixel-to-pixel non-uniformity of the CCD detector, while the motion of the star image (smaller than one pixel) on the CCD is moving because of refraction/scintillation. The PRNU is about  $\sim 20\%$ , while absorption features are of the order of a few % in the lower stratosphere. This was calibrated on ground, and in principle the Level 1b software takes care of the motion of the star on the particular pixels (at most, two pixels in the vertical direction). However, it was discovered in flight serendipitously that there is also a rather large sub-pixel non uniformity. Some episodes of malfunction of the front steering mechanism occurring in 2008 could be used to reconstruct a much better PRNU including sub-pixel response.

A test with a new Level 1b algorithm taking into account the sub-pixel response was

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performed on a limited set of occultations. Figure 38 compares the H<sub>2</sub>O densities found with the nominal algorithm (left) and the new algorithm (right). The bump at 30 km has completely disappeared, and reasonable values (3 to 6 ppmv) are retrieved in the lower stratosphere.

5 On Fig. 39 are compared the statistical distribution of GOMOS profiles (median, rather than average, to avoid the influence of bad data, and upper and lower quartiles) with HALOE average for similar latitude and season. GOMOS is drier than HALOE above 40 km. However, the absorption features of H<sub>2</sub>O at these altitudes are very weak in the 936 nm band, and the GOMOS values are more uncertain above 40 km.

10 These new results are very encouraging. When GOMOS data will be reprocessed with this new algorithm and sub-pixel PRNU response, it will open the way to a better understanding of the H<sub>2</sub>O trend and possibly of the mechanisms of injection in the stratosphere, two subjects of controversy at this time.

## 7.9 Measurements of O<sub>2</sub>

15 Measurements of O<sub>2</sub> are made in the A band of O<sub>2</sub> around 760 nm (Fig. 15). The basis of the GOMOS retrieval is to compare the transmission spectra to a series of pre-calculated model spectra, computed with the HITRAN data base, and five typical US standard profiles. In the version GOPR 5 of the GOMOS software, we used the 1996 HITRAN data base, while in the version GOPR 6 (the present one) we used a later version, HITRAN 2000. In Fig. 40 are represented the line densities for 6 occultation of Sirius obtained in 2003, retrieved for the two versions of the data base. There is a decrease of the O<sub>2</sub> line density, especially large at the lowest altitude (~-50%) with HITRAN 2000. In fact, when compared to ECMWF data, the GOPR 5 values were much too high. Spectroscopic data for O<sub>2</sub> were wrong in HITRAN 1996.

25 In the Level 2 GOMOS product are now (GOPR 6) registered the retrieved line and local density of O<sub>2</sub>, as well as the line and local densities of air delivered by ECMWF from analysis, for the time and location of the occultation. This gives us the opportunity to compare to a serious reference the GOMOS retrieved quantities. In Fig. 41

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are plotted, for several tens of Sirius occultations of 2003, the ratio  $N(\text{O}_2)/N_{\text{air}}$  of the retrieved line density  $N(\text{O}_2)$  from GOMOS to the line density  $N_{\text{air}}$  contained in ECMWF (obtained by proper integration along the line of sight of the local density). In some sense, it is the mixing ratio of oxygen measured by GOMOS, when averaged along the line of sight. The value of  $\text{O}_2$  mixing ratio in air is in principle 20.946%, while we find much lower values below 15 km, and a large dispersion above 35 km; in the range 15–35 km, the  $1\sigma$  dispersion of GOMOS measurements is about  $\sim 1\%$ , while the bias is +2%. The study of all measurements (15–20 km) on the 9 brightest stars over the year 2003, 2006, and 2008 showed us that the bias was variable with season and latitude, the pattern being somewhat similar from year to year (not shown here). The bias may go up to 6%, and may be also negative. Therefore, it is difficult to invoke again a wrong spectroscopic data base, that would likely give a bias always with the same sign at a constant altitude. This systematic difference with the ECMWF may be explained by three possibilities: i) the ECMWF reference is biased itself; ii) the retrieval algorithm of  $\text{O}_2$  line density (as described in Sect. 5.6) is incorrect; iii) the choice of a small number of pre-calculated model transmissions (5 typical US standard profiles) is insufficient to represent all possible transmission spectra.

In order to test hypothesis iii), a new software was developed at LATMOS. Instead of comparing all occultations to a limited number of typical US standard profiles, the table of modeled transmissions is computed for the very ECMWF profile that corresponds to the time and place of occultation. It is certainly a good approximation of reality, better than using the US standard profiles. However, this procedure is computing-time consuming, and only limited samples could be run up to now. Figure 42 shows an example of compared retrieved mixing ratios of line density profiles (with ECMWF being the reference) with the standard method (GOPR 6) and the new method. Both profiles are normalized to 1 for the mixing ratio 20.946%. The bias of the new method is very similar below 28 km (also checked on 10 other occultations), but much lower above 28 km: this new method may improve the retrieval accuracy above 28 km. Further studies are needed in this field. It is probably useful to perform a systematic compari-

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son with ECMWF line density profiles (with both method, GOPR 6 and new); perhaps, the variations of bias as a function of altitude, latitude, longitude, season, may be then analyzed, to disentangle the respective contributions of the three possible sources of biases mentioned above.

## 5 7.10 Aerosols and Polar Stratospheric Clouds (PSCs)

At the time of ENVISAT launch, the lower stratosphere content was probably at a historical low, making rather challenging the retrieval of aerosols. Nevertheless, Vanhelle-  
mont et al. (2005) established a first GOMOS climatology of aerosols and PSCs, based  
on the analysis of about 50 000 night-time occultations of 2003, which allow to probe  
at lower altitudes and with less noise due to bright-limb background contamination. In  
the fit of transmission spectra, it was decided to describe the aerosol extinction  $\beta_a(\lambda)$   
with one parameter only:

$$\beta_a(\lambda) = N \frac{\sigma_0}{\lambda} \quad (12)$$

with the fixed scaling factor  $\sigma_0 = 3.10^{-7} \text{ cm}^2 \text{ nm}$  and  $N$  (unit:  $\text{cm}^{-3}$ ) the parameter to be  
retrieved.

The climatology grid was composed of monthly bins, with 18 latitude bins with a  
width of 10 degrees, and an altitude grid with 1 km bins from 0 to 60 km. No variations  
along longitude are considered (zonal mean). Finally, the median value in each bin was  
retained for establishing a climatology, and the variability was also studied. In Fig. 43  
is displayed the median value for the whole year 2003 (all monthly bins averaged to-  
gether) of the extinction  $\beta_a(\lambda)$  at 500 nm.

Clearly visible is the umbrella-shaped aerosol layer, having the largest altitude above  
the equator and gradually sloping downwards when moving to the poles. The conspic-  
uous isolated maximum in the tropics at an altitude of 15 to 17 km has been observed  
by other instruments as well and is caused by the presence of high subvisible cirrus  
clouds in the tropics. As shown in Vanhelle-  
mont et al. (2005), this equatorial feature

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has a seasonal motion: along the year, it gradually moves towards the North, and then heads back southwards at the end of the year. This motion is in phase with the seasonal shift of the Intertropical Convergence Zone (ITCZ).

The PSCs revealed themselves in the elevated levels of the aerosol extinction in the Antarctic region, found confined to the polar vortex. On the contrary, no elevated extinction levels are observed in the Arctic region from January to March 2003 (and do not show in the yearly average). This may be explained by the much lower occurrence of PSCs, due to the weaker polar vortex. It should be noted that in this period there were some Sudden Stratospheric Warmings which weaken significantly the polar vortex.

A larger study, covering several years of GOMOS data (2002 to 2008), is presented in a companion paper of the ACP GOMOS Special Issue (Vanhellemont et al., 2010). In this case, based on a later version GOPR 6 of the GOMOS processing software, the wavelength dependence of the aerosol extinction is assumed to be of a quadratic form in  $\lambda - \lambda_{\text{ref}}$ ,  $\lambda_{\text{ref}} = 500 \text{ nm}$  (Sect. 5.5.2). Four types of aerosols could be distinguished (from season, altitude and volcanic history, rather from the spectral signature): PSCs, tropical subvisual cirrus, background aerosol, and volcanic stratospheric aerosols. Their typical vertical profiles are shown in Fig. 44, taken from Vanhellemont et al. (2010). The smoothness of these individual profiles is somewhat exaggerated, as a result of Tikhonov smoothing yielding a 4 km target resolution. The effect of moderate volcanism is clearly seen in GOMOS data (Vanhellemont et al., 2010), and the dispersion of  $\text{H}_2\text{SO}_4$  droplets made from volcanic  $\text{SO}_2$  reaching the stratosphere (18-20 km could be followed, in particular the eruption of the Soufrière Hills volcano (16.7° N, 62.2° W, Montserrat, West Indies), on 20 May 2006.

## 7.11 Noctilucent clouds (Polar Mesospheric clouds, PMCs)

Polar Mesospheric clouds (PMCs) are thin clouds of ice particles condensing around 80–85 km, which can be observed from the ground after sunset, while they are still illuminated by the sun: their first name was accordingly Noctilucent clouds. During a large number of star occultations, GOMOS has seen some extra signal coming from

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PMCs. In Fig. 45 is shown an example of GOMOS photometers observation of a noctilucent cloud (or Polar Mesospheric Cloud), detected as a sharp increase light. In addition to the star signal, and Rayleigh scattering by air molecules, there is some solar light scattered by the icy particles of the clouds.

5 A statistical analysis of PMC occurrence has been established (Pérot et al., 2010) over 4 years of data (bright limb only), from 2002 to 2006. In order to condense, the icy particles need some water vapour and a very cold temperature, conditions found only in the high latitude summer mesosphere. GOMOS data set consists of approximately 10 000 cloud observations all over the eight PMC seasons studied. In  
10 Fig. 46 is presented an example of cloud detection (or non-detection) for the whole year 2004, for all day-side occultations. They are presented under the form of maps in Pérot et al., 2010. It is found that GOMOS photometers allow a very sensitive PMC detection, showing a frequency of occurrence of 100% in polar regions during the middle of the PMC season. According to this first GOMOS climatology of PMCs, they seem to be  
15 more frequent in the Northern Hemisphere than in the Southern Hemisphere. The PMC altitude distribution was also calculated, and the obtained median values are 82.7 km in the North and 83.2 km in the South. It will be interesting to compare with the results of The Aeronomy of Ice in the Mesosphere (AIM) mission, recently launched (2007) by NASA, first satellite mission entirely dedicated to the study of polar mesospheric clouds  
20 (Russell et al., 2009). It would allow to complete the climatology of AIM with years 2003–2006, before the launch of AIM, for a better study of the long term trend. It has been suggested (Thomas and Olivero, 2001) that PMCs could be a potential indicator of global atmospheric changes: the increase of CO<sub>2</sub> will decrease the temperature at these altitudes (by IR radiative cooling), while at the same time there might be an  
25 increase of water vapour injection in the stratosphere. There was indeed a magnificent PMC over Paris on Bastille day (14 July 2009), probably not sufficient to claim for a climatic change indicator!

The GOMOS spectrometers have also seen this PMC emission. The scattering efficiency as a function of wavelength will allow to determine the characteristics (at

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least the size distribution) of these icy particles.

## 7.12 Detection and climatology of the natural sodium layer

A layer of sodium atoms is present in the mesosphere, mainly as a result of ablation of meteoritic material impacting the upper atmosphere. When illuminated by the sun, resonance scattering at 589 nm doublet makes it the source of one of the most conspicuous natural aeronomic emission, particularly for twilight observations (e.g., Bricard and Kastler, 1944), and as such has been studied by a variety of methods (ground based spectrometers, lidars (Mégie and Blamont, 1977), space borne photometers on OGO-6 in 1969, etc.). It has recently attracted a renewed interest, because, besides the scientific questions related to the origin and the vertical distribution of the layer, the mesospheric sodium is of major importance in astronomy where it is used to produce an artificial star on which to guide for adaptive optics, with a lidar illumination.

Although extensive data exist about the mesospheric sodium layer measured from particular sites, very little is known about the geographical distribution (Plane, 2004). GOMOS has demonstrated a new method of study of the sodium layer, and has provided the first global mesospheric sodium climatology measured so far (Fussen et al, 2004). The new method is to detect and measure the tiny absorption of the sodium doublet imprinted on the stellar spectrum during a standard star occultation. Many transmittance spectra have to be binned together, in order to provide a sufficient accuracy. The bins are 1 km altitude,  $10^\circ$  in latitude, and one month time. Figure 47 represent such a transmittance, the median of 1121 occultations in a particular bin. The two components of the Na doublet are well separated, but the line profile ( $\sim 0.5$  nm) is the instrumental one, because the natural lines at mesospheric temperatures ( $\sim 200$  K) are much narrower.

Fitting such a transmittance spectrum, one may retrieve an optical thickness averaged over the sampled wavelength interval and the slant (line) density of Na atoms as a function of altitude (Fig. 48, left). This vertical profile may be fitted by a layer of sodium atoms described by the peak altitude, the peak concentration, and two parameters

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describing the vertical width and some asymmetry w.r.t. the peak altitude.

The first analysis was based on about 100 000 star occultations recorded during the year 2003 (Fussen et al., 2004). It was found later that, in some cases, the absorption lines were saturated, yielding an underestimate of the slant density of Na atoms. Once this effect corrected, Fussen et al. (2010) have extended the GOMOS analysis to the whole period 2003–2009. The main findings are summarized below. For more details, see Fussen et al. (2010).

The peak concentration is variable, in the range  $2\text{--}5 \times 10^3$  atoms  $\text{cm}^{-3}$ . The integrated vertical column is in the range  $1\text{--}7.5 \times 10^9$  atoms  $\text{cm}^{-2}$ . The peak altitude varies in the range 90–93 km, and the vertical extent is typically  $\sim 15$  km. GOMOS data in the latitude bins 30–40° N and 40–50° N were compared to the series of lidar measurements acquired at Fort Collins (latitude 41° N) (She et al., 2000). The results are generally consistent, but not fully identical.

GOMOS average climatology shows a strong enhancement of sodium at both polar winter solstices, with strong minima in between. At tropical latitudes, a semi-annual variation of the total column is present in the data, which evolves progressively at higher latitudes into an annual variation, a time-space distribution pattern unreported so far. The peak altitude demonstrates an annual variation with two peaks at mid latitude, confirming earlier lidar results.

During polar winter, the sodium layer peak altitude is lower, a sign that the layer is influenced by the mesospheric global circulation, ascending at the summer pole and descending at the winter pole around solstices.

It should be noted that, during summer polar solstices, the frequent presence of Polar Mesospheric Clouds (Perot et al., 2010) add a strong signal at the limb, making more delicate the GOMOS retrieval of sodium. Future GOMOS studies will use also the bright limb emission of the Na doublet, in a fashion similar to the ODIN/OSIRIS bright limb observations (Gumbel et al., 2007)

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## 7.13 Scintillations and the study of air density irregularities: internal gravity waves and turbulence

The scintillations of stars observed through the Earth's atmosphere are generated by random irregularities of air density (and, consequently, of refractive index). The two fast photometers of GOMOS (with red and blue filters), allows a statistical study of this field of irregularities with unprecedented refinement, and a global coverage for the first time.

As an example of the variability of observations, we show in Fig. 49 the signals of the red photometer as a function of tangent altitude, recorded during two different occultations. The signal is normalized to 1 at high altitude. Both show increasing fluctuations with decreasing altitude, but the high latitude occultation (62° S, black) displays much stronger fluctuations than the other recorded at 37° S (red). The intensity of fluctuations may be quantified by one main parameter, the variance  $\beta^2$  of relative fluctuations of the measured signal;  $\beta$  is defined as the scintillation index (Sofieva et al., 2007), and displayed at bottom of Fig. 49. At high altitudes, the fluctuations are due to the noise, while at low altitudes, the fluctuations are saturated to unity in both occultations. The curves of  $\beta(z)$  are otherwise very different between 30 and 70 km, opening the prospect to case studies and climatology studies of density irregularities. The various analysis performed from GOMOS scintillation data are briefly overviewed below.

Gurvich et al (2005) have developed a theory of the atmospheric density irregularities, which is fully confirmed by the study of the signal of the two photometers (1 kHz). In this theoretical forward model (going from the field of irregularities to a prediction of scintillations), the field of irregularities is the sum of two independent fields with different characteristics:

- The anisotropic component represents mainly the Internal Gravity Waves (IGW). It is characterized by a spectrum (amplitude vs. size) with a large spectral slope (–3) and a large aspect ratio (horizontal/vertical  $\sim 100$ ).
- The isotropic component is characterized by its Kolmogorov (–5/3 slope) isotropic

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spectrum. These density fluctuations are mainly representative of turbulence, which appear as a result of the breaking of gravity waves (but also from other mechanisms). It leads to effective turbulent mixing of chemicals in the stratosphere and to dissipation of kinetic energy into heat at the final step of this process, two key elements of stratospheric physics and chemistry.

Due to the exponential decrease of air density with altitude, the irregularities at the lowest altitude along the LOS produce the main contribution to the observed scintillations. Figure 50 is a sketch of such a field of irregularities with the two components, and the effect that it will have on the signal of the two fast photometers (FP). Blue rays are more refracted than red rays (the index of refraction is larger), and therefore, from the observer at a given time, the blue ray is probing higher altitudes than the red ray. In the case of a perfectly vertical occultation (in the plane of the orbit), the two signals are probing the same irregularities (for both components), with a time delay between the two photometer signals increasing towards lower altitude. When the occultation is oblique with an angle  $\alpha$  with the local vertical (Fig. 50, bottom), there is also a horizontal separation of the two trajectories of the LOS: the anisotropic component field will be similarly probed by the two photometers, because of the large horizontal extent of the irregularities, while the isotropic component will be completely different. Therefore, the correlation of the two signals will be much smaller for the isotropic component than for the anisotropic component. In Fig. 51 are displayed these photometers signals as a function of altitude in the case of a vertical occultation and for an oblique occultation, for a small slice of altitude of the tangent point (250 m). The correlation between the two signals is much larger for the vertical occultation. Gurvich et al. (2005) have calculated a “coherency” index which quantifies the correlation between the two signals.

The analysis of coherency was performed for 15 stellar occultations, in the range 20–50 km. Below 20 km, the signal is too low, and strong scintillations (multiple paths) may occur. Above  $\sim$ 50 km, the scintillations are generally too small. The analysis allowed the detection of layers with prevailing isotropic component. They are located generally between the altitudes of about 30 and 40 km. The thickness of the layers and their

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altitude distribution depend on observation location.

Overall, the model with the two components, IGW producing anisotropic structures (elongated horizontally) and smaller scale isotropic turbulence is validated by the observations in two colours. Once validated, Sofieva et al. (2007) established algorithms to determine the parameters of IGW and turbulence from the time-frequency spectral analysis of the GOMOS red photometer (preferred because of higher signal, more “focused” in refraction index, and less affected by absorption and scattering). Two retrieved parameters are  $C_W$  and  $C_K$ , the structure characteristic defining the power of (respectively) the anisotropic air density irregularities, and the isotropic irregularities. The two other retrieved parameters are the inner and outer scales of the anisotropic component, found to increase with altitude from  $\sim 5$  m at 25 km to 15–25 m at 45 km (inner scale) and from  $\sim 0.2$ – $0.5$  km at 25 km to 0.5–3 km at 45 km (outer scale). The value of  $C_K$  is found to increase fast from 25 to 35 km, and more slowly above. The isotropic component of temperature fluctuations  $C_T^2$  is related to  $C_K$ :  $C_T^2 = \langle T \rangle C_K$ .

Based on about 8000 night time occultations of the 30 brightest stars in 2003, Gurvich et al (2007) have published the first global and seasonal distribution of the structure characteristic  $C_T^2$  of isotropic turbulence at altitudes 30–50 km. In each season and latitude bin, the median value of  $C_T^2$  (less sensitive to outliers) was kept. Large variations of  $C_T^2$  are observed (Fig. 52): the range of derived values of  $C_T^2$  covers more than two orders of magnitude, from  $3 \times 10^{-5}$  to  $6 \times 10^{-3} \text{ K}^2 \text{ m}^{-2/3}$ . The value of  $C_T^2$  has a clear physical meaning. It is equal to the variance of the temperature difference in two points at a distance of one meter. The largest  $C_T^2$  values are observed above 40–45 km in polar winter in both hemispheres, but they are especially large in the Southern Hemisphere. Based on a simplified spectral analysis, Sofieva et al. (2007) suggested from a dedicated study of GOMOS scintillations that the strong turbulence observed at winter polar stratosphere might be related with breaking IGW in the polar night jet.

At low latitudes, a rather low turbulence is observed, with minimal values of  $C_T^2$  less than  $10^{-4} \text{ K}^2 \text{ m}^{-2/3}$ . Most interesting is the geographical distribution of  $C_T^2$  displayed in

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Fig. 53, in a layer about 3 km thick, centered around  $\sim 42$  km, between 35 N and 35 S. Turbulence intensity is smaller in this zone than in polar regions and, in average, it has a pronounced zonal structure. The plots of Figure 53 show that the average values of  $C_7^2$  follow the sub-solar latitude, as do the main features of the general circulation of the middle atmosphere [Holton, 2004]. Also, almost all of the local enhancements are over continents (except for the one over Western Pacific in June–September). Many of  $C_7^2$  enhancements seen in Fig. 53 correspond well to the typical regions of deep convection, e.g., Africa, South America and Indonesia in December, January–March, regions of Indian and American monsoons and of North African dry convection in June–September.

No systematic increase of  $C_7^2$  over large mountain range such as Himalaya, Andes and Sierra Nevada are seen: turbulence enhancements in tropical regions are not related with orography. Probably mountain waves are too long for transformation into small scale turbulence observed by scintillation at 42 km (Gurvich et al., 2007).

Finally, the whole pattern of  $C_7^2$  suggests (Gurvich et al., 2007) that the observed enhancements in  $C_7^2$  correspond to the last step (before molecular diffusion) of breakdown of temperature irregularities observed by MLS (Jiang et al., 2004) and interpreted as IGW.

More recently, Sofieva et al. (2009) have refined the forward model, and retrieved an additional information on the gravity waves: their potential energy per unit mass  $E_p$  (Joule/kg), which depends on the outer scale of the GW. The new algorithms are implemented at FMI and in the GPOD (Grid Processing-On-Demand) environment at the European Space Agency). In Fig. 54 are shown the latitude/altitude distribution of  $E_p$  zonal mean for two 4 months periods of year 2003: January–March plus December, and June September. The potential energy  $E_p$  increases with altitude. Enhancements in equatorial regions are clearly observed, analogous to those found in global analysis of radio-occultation data and caused large values of GW outer scale at these locations. Enhanced  $E_p$  in the SH winter high latitude stratosphere is observed, but no symmetric enhancement of  $E_p$  at high latitudes in winter is observed in Northern Hemisphere.

Sofieva et al. (2009) suggested that it is probably caused by the fact that occultations at NH winter high latitudes were carried out in January 2003 and in December 2003, when some sudden stratospheric warmings (SSW) lasted a significant part of the observational period. It coincides with previous lidar observations (Whiteway and Carswell, 1994), showing reduced GW activity during SSW.

Future multi-year analysis of GOMOS scintillation measurements will refine the observations and will provide information about spatial and inter-annual variability of GW and turbulence spectra parameters in the stratosphere.

## 7.14 High-resolution density and temperature profiling using bi-chromatic scintillation

As explained above, density irregularities are producing scintillations, which are observed with the two photometers in two colors. The two photometers were implemented in the design of GOMOS for a better correction of the stellar spectra, distorted by refraction. However, it turned out that another use of the two photometers was possible, not anticipated before launch: the retrieval of density and temperature with a high vertical resolution, from the measured time delay between red and blue scintillation peaks corresponding to the same density irregularity. Dalaudier et al. (2006) have developed the so-called HRTP method and algorithms (High Resolution Temperature Profile) to determine the density/temperature profiles between 20 and 30 km, with a vertical resolution of 200 m. In this altitude range, the lower stratosphere is not sufficiently sampled by in-situ measurements while meteorological satellites cannot provide vertical resolution below  $\approx 2$  km. Figure 55 shows a sample of the two photometers signals over 200 m. From the time delay, the bending refraction angle may be determined, which is related to refractivity, therefore density, at the tangent point. Then the inversion method is similar to a classical radio occultation, involving the inversion of an Abel's integral, the hydrostatic equilibrium and the law of perfect gases.

Figure 56 is the result of such an inversion, selected because it was not far from a lidar measurement at Mauna Loa, for comparison purposes. Both lidar and GOMOS

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show similar, and significant departures from the ECMWF profile which is inherently smooth (up to 6 K), while the difference GOMOS HRTP- Lidar does not exceed  $\pm 2$  K above 22 km. We do expect such differences, because the two measurements do not coincide exactly in time and space, while the characteristics of gravity waves are such that ideally the two measurements should be separated by less than 20 km, and less than 2 to 3 h.

While validation with precisely collocated measurements is difficult as shown by Sofieva et al. (2008) (i.e., the balloon borne radiosonde takes  $\sim 1$  h to explore up to 30 km), it is possible to validate HRTP results by comparing the power spectra of temperature fluctuations vs size, as done by Sofieva et al. (2009d). These authors have compared a subset of GOMOS spectra to radiosondes spectra; the requirements on space-time collocation are much less stringent. Overall, the HRTP results were validated, and it was found that the altitude resolution was 150~200 m.

This new HRTP method will be implemented in the GOMOS data processing chain in the next release (GOPR 7 or IPF6), providing a new product of great interest. It should be emphasized that, not only the fluctuations of temperature are recorded with unprecedented vertical resolution from space, but also the absolute value of the temperature is retrieved with a good accuracy, making this product a good candidate for future assimilation in meteorological analysis like ECMWF.

## 8 Conclusions

We have presented the rationale of GOMOS design, the instrument description, some “raw” observations, and an overview of results obtained up to now. A large number of scientific research activities may still be done with the GOMOS data, in the UTLS, the stratosphere and the mesosphere.

The 4 years nominal lifetime of ENVISAT is now exceeded at 7 years. Still, it may be a little bit short for trend studies. The collection of several years of GOMOS measurements, because of their absolute character, will provide a unique benchmark of data,

to be compared to previous measurements sharing also this absolute character, and most over, to future measurements collected by the same method of stellar occultations, for long term monitoring. In this respect we hope that GOMOS is the first of a series of stellar occultations monitoring instruments.

5 The actual size and complexity of GOMOS is in large part due to a number of precautions and redundancies that were included in its design, because of its exploratory character of a new technique. What is learned from this first large-scale investigation of the stellar occultation technique will allow to significantly simplify the design of future instruments, with a smaller mass and complexity. For instance, the use of a dedicated  
10 micro-satellite would be quite adapted to such an investigation. The whole spacecraft might be oriented to each successive star, as is done for SPICAM and SPICAV instruments, respectively around Mars and Venus at present (Bertaux et al., 2006, 2007). It would be recommended to cool the CCD detector to at least  $-40^{\circ}\text{C}$ , in order to make the dark charge negligible, even after radiation damage. Also, a polar orbit is recom-  
15 mended for latitude coverage, but the altitude could be lower, avoiding the problem of radiation contamination in the South Atlantic Anomaly.

## Appendix A

### A short history of the stellar occultation technique

20 The use from space of the stellar occultation technique has been reviewed by Smith and Hunten (1989). It was first discussed in details by Hays and Roble (1968) in a seminal paper, and used to measure terrestrial ozone from the astronomical satellites OAO-2 and Copernicus (OAO-3). Using OAO-2 in 1970 and 1971, Hays and Roble (1973) detected directly for the first time the mesospheric ozone maximum (from  
25 UV absorption of the stellar light) which had been previously inferred from Evans and Llewellyn (1970) from rockets sounding of the  $\text{O}_2(^1\Delta)$  ( $1.27\ \mu\text{m}$ ) and  $\text{O}_2(^1\Delta)$  (760 nm) airglow emission, produced from photo-dissociation of ozone. Later, in 1975 and 1976

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the Orbiting Astronomical Observatory n°3 (OAO-3, soon renamed Copernicus) was also used to measure successfully terrestrial ozone above 45 km from UV absorption in a wavelength region similar to OAO-2 (Riegler et al., 1976, 1977). The problem is that Copernicus retrieved ozone densities in the stratosphere (say, at 50 km) were found to be in a serious discrepancy with model predictions and, more important, with OAO-2 results. Copernicus O<sub>3</sub> densities were 2 to 3 times larger than model predictions, and about 25 times larger than the OAO-2 results. This enormous discrepancy, which is unresolved up to now (Atreya et al., 1981), did not help to promote the validity of stellar occultation technique as a reliable method for ozone measurements, and this is perhaps the reason for which it was not pursued further in the USA, in spite of its inherent merits.

After careful re-reading of the scientific papers, and with the experience accumulated with GOMOS analysis, we may here suggest a new explanation of this discrepancy. Clearly, both OAO-2 and Copernicus results could be reconciled with each other, and with models, by a shift in altitude of the ozone retrieved profiles: about 10 km upwards for OAO-2, and 5 km downwards for Copernicus. Such errors are in principle incompatible with orbital knowledge accuracy, but there is another source of error in the retrieved measurement altitude: the direction of the star in the sky. Indeed, astronomical directions of stars are described in a conventional system with the origin of RA (right ascension) as it was in a given year (so-called J1950 or now, J2000), which rotates with the precession of equinoxes by 360° in 26 000 years, while orbital computations of Earth satellites are most often using the inertial Earth equatorial system *True of date* (with the origin of RA at its position at the time considered). This is because satellite tracking stations are fixed to the Earth, and need to know the coordinates of the spacecraft in a system linked to the Earth. Of course, it is trivial to include the correction of equinox precession in the calculation of the retrieved altitude of occultation measurements, but it has been sometimes overlooked in the past (during the first light of Hubble Space Telescope), or even applied wrongly twice to the calculations (Solstice experiment on UARS and Sorce, private communication, G. Rottman, 2003). An error

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in the position of the star will translate in an error of retrieved altitude which depends on the star position, the orbit altitude, and the particular geometry of occultation. For measurements made in 1975, the precession is maximum w.r.t. J1950 or J2000, and amounts to  $0.36^\circ$ , translating in an altitude error (both ways) of up to 16 km depending on the particular orientation of the occultation geometry.

All these early attempts of stellar occultations suffered from the fact that only one wavelength was monitored during the occultation, letting room for confusion on the exact nature of the absorbing species. One great progress for the occultation technique w.r.t. the description of Hays and Roble was the use of multi-pixel detectors. The advent of CCDs (or other multi-pixels detectors), allowing to measure the whole transmission spectrum at once, increased dramatically the capability of stellar occultation versus the use of filters, or scanning spectrometers. The first multi-pixel occultation (to our knowledge) was inaugurated with the ultraviolet spectrometer UVS placed on board the Voyager 1 and 2 missions: in 1979, an occultation of the star alfa Leonis by the atmosphere of Jupiter was observed from a distance of 14 millions km by Voyager 1 in the full range 110–170 nm allowing to probe the  $H_2$  and methane vertical profiles (Festou et al. 1981). Since then, this technique was fostered at Service d'Aéronomie, in particular for the study of the atmosphere of planet Mars with the Spicam instrument. A first instrument dedicated to multi-wavelength stellar occultations was destroyed with the launch failure of the Russian mission Mars 96 (in November 1996), while a smaller version, SPICAM Light, is now flying on board Mars Express ESA mission (Bertaux et al., 2006), and around Venus (SPICAV) with Venus Express ESA mission (Bertaux et al., 2007).

Before GOMOS and its  $\sim 600\,000$  occultations up to 2009, a big step forward was made with MSX mission, with about 200 occultations recorded around the Earth (Yee et al., 2002). The Cassini mission should also be mentioned, with very successful star occultations by the atmosphere of Titan performed at each encounter with UVIS spectrometer. With its extended atmosphere, Titan is the ideal planet for the technique of stellar occultation, where 6 organic molecules were identified from their UV absorption

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spectral signature (Shemansky et al., 2005).

In the past, a number of stellar occultations have been also performed successfully from a balloon platform, allowing in particular the first observation of NO<sub>3</sub> from a balloon, and the retrieval of its vertical distribution (Naudet et al., 1989; and more recently for NO<sub>2</sub>, Renard et al., 1997). It should be mentioned that stars may be used also from the ground, as in the instrument developed for Antarctic measurements by Roscoe et al. (1997).

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**Table 1.** GOMOS instrument parameters.

Optical Performance Parameters	Channel name	Spectral Range	Spectral sampling per pixel	Spectral resolution
Spectrometer A 2hz	UV(A1)-Vis (A2)	248–690.5 nm	0.31 nm	0.8 nm
Spectrometer B 2hz	IR1 or B1 (O <sub>2</sub> )	755–774.5 nm	0.047 nm	0.13 nm
Spectrometer B 2hz	IR2 or B2 (H <sub>2</sub> O)	926–954 nm	0.056 nm	0.13 nm
Photometer 1 (1 khZ)	Phot 1 (blue)	473–527 nm	Broad band	NA
Photometer 2 (1 khZ)	Phot 2 (red)	646–698 nm	Broad band	NA
Altitude range	Minimum: 5–18 km (night), 25 km (day)	Maximum 250 km		
Vertical Resolution of spectrometers	1–1.7 km (0.5 s sample)			

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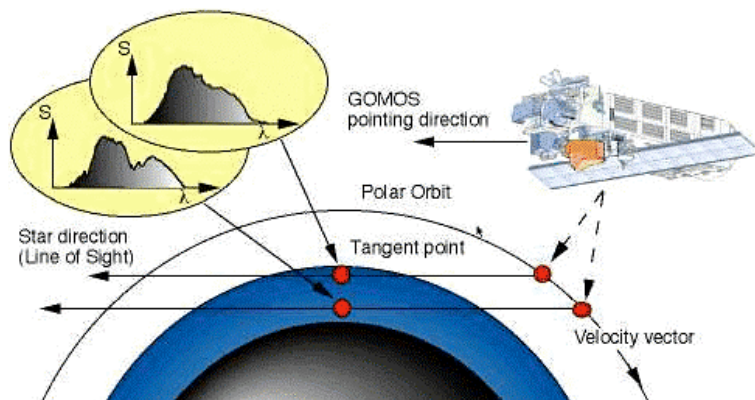
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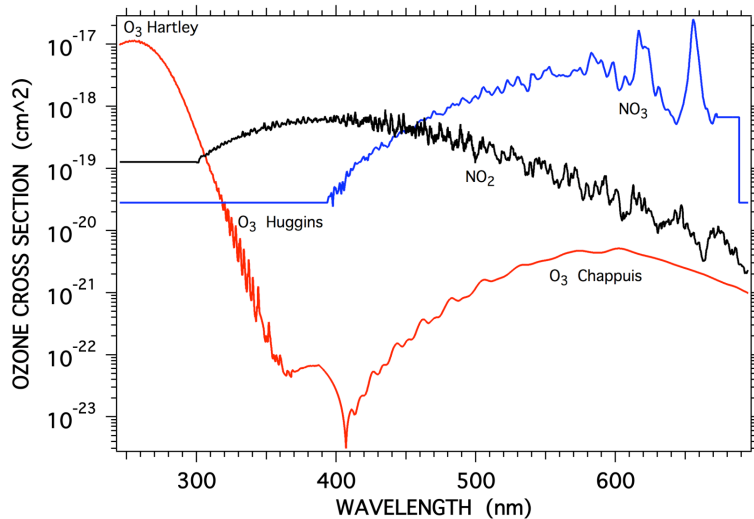


**Fig. 1.** The GOMOS principle of measurement, by occultation of a star. The spectrum of a star is first seen outside of the atmosphere, then through the atmosphere: the ratio of the two spectra is the atmospheric transmission in this spherical geometry, at altitude  $z$ .

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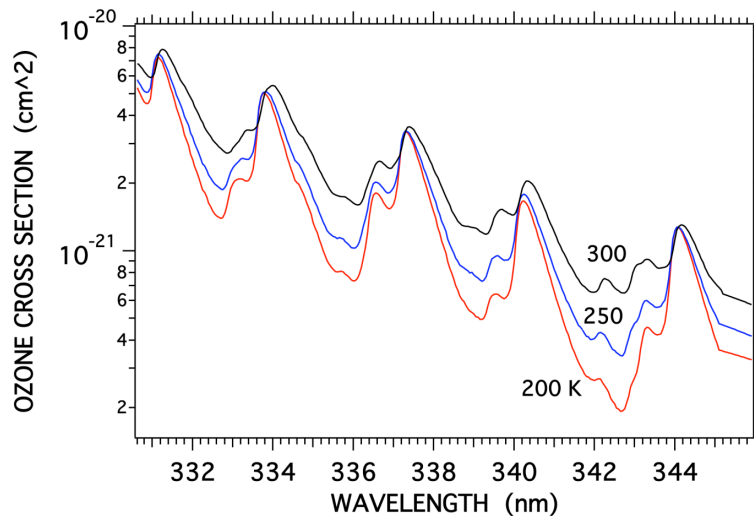


**Fig. 2.** Cross sections of ozone (red), NO<sub>2</sub> (black) and NO<sub>3</sub> (blue) at a temperature of 250 K used in the GOMOS spectral inversion. Cross sections at other temperatures are also used. The Huggins bands are particularly sensitive to temperature.

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**Fig. 3.** Absorption cross-sections of ozone at 200, 250 and 300 K in the Huggins bands. In principle, observations of actual transmission spectra should allow to retrieve a temperature estimate.

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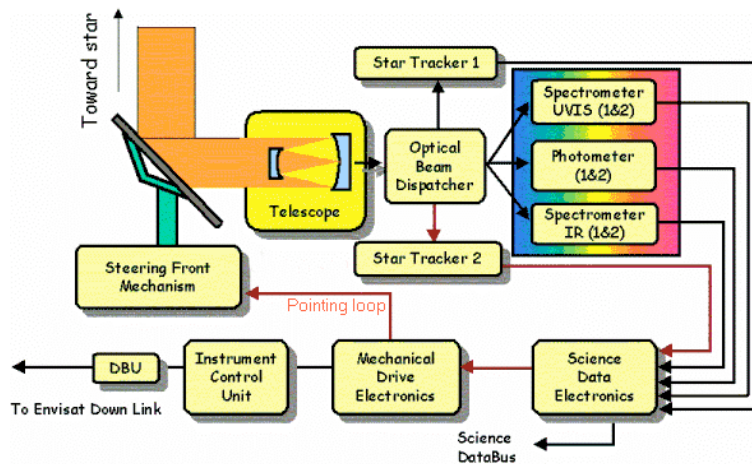


Fig. 4. GOMOS Instrument block diagram.

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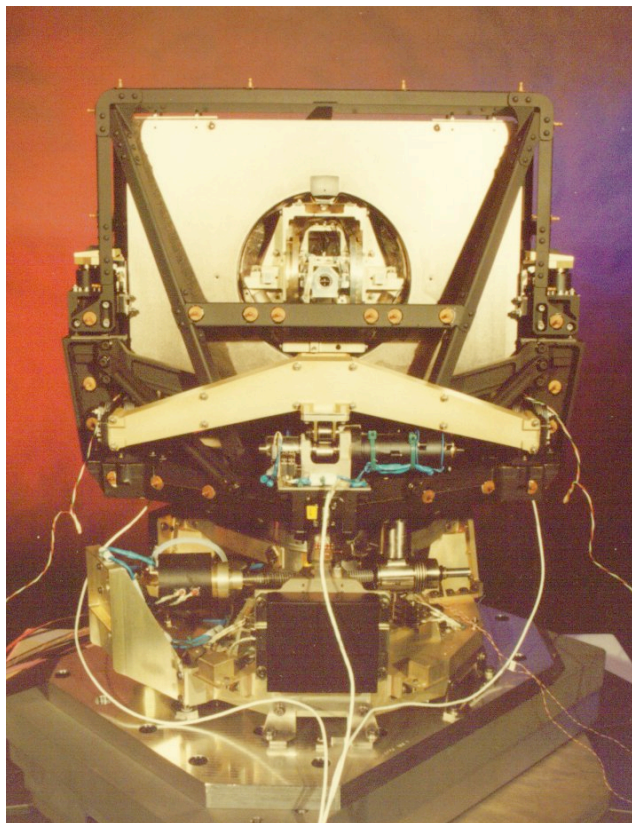
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**Fig. 5.** Steering Front Mechanism rear view. It moves the plane mirror in order to keep the image of the star always in the entrance slit of the spectrometers.

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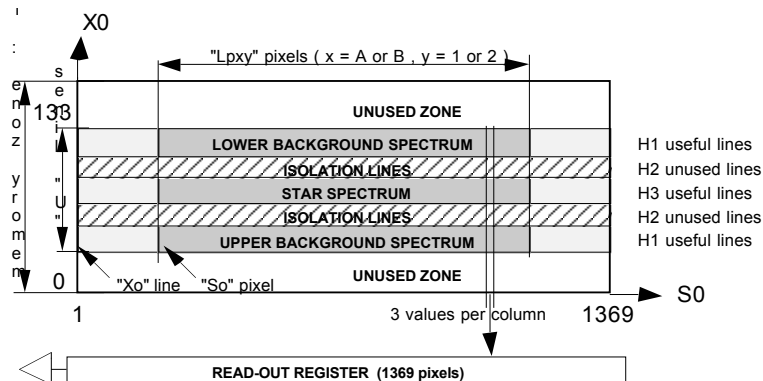
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**Fig. 6.** Spectrometers CCD reading for occultation mode. During the nominal mission of GO-MOS, the interband region was fixed at H1 = 3 CCD lines, and the 3 bands are with H1 = H3 = 7 lines.

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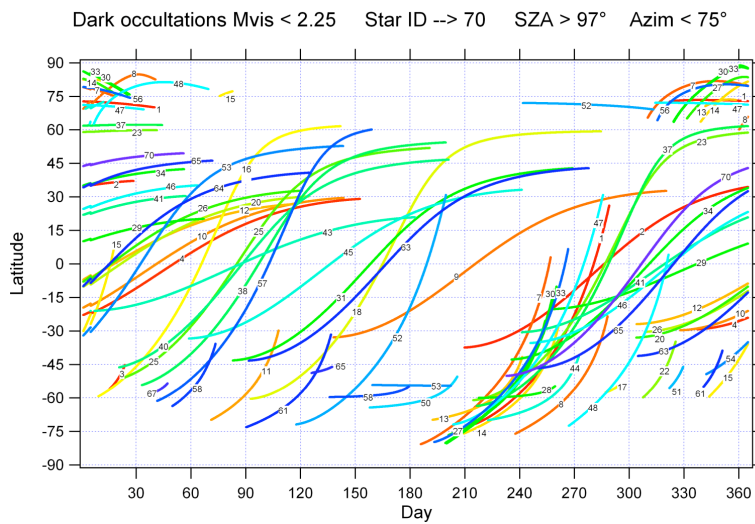
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**Fig. 7.** Each colored curve represents the occultation point latitude as a function of the day of year (DOY) from ENVISAT orbit. The number is the GOMOS identification number, ordered by increasing visual magnitude. Only occultations in dark limb conditions, and with an azimuth angle  $< 75^\circ$  are represented. Scintillations are affecting more the transmission spectra for larger azimuth angles. The pattern repeats identically every year.

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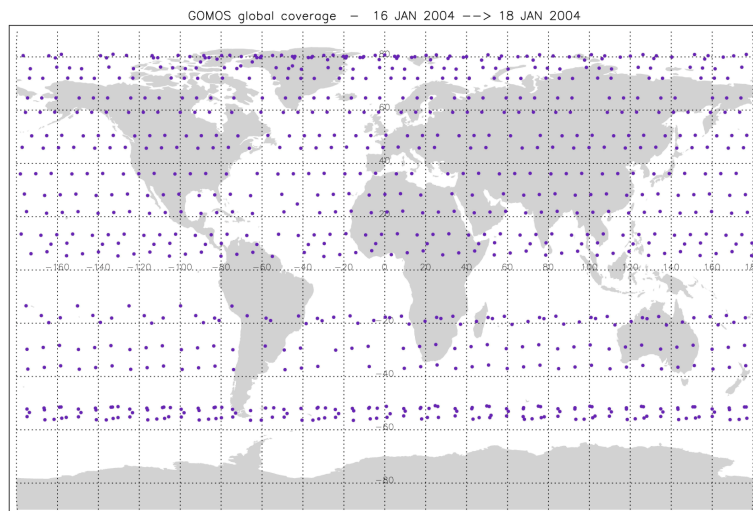
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**Fig. 8.** Each point represent the location of one occultation, performed during a period of 3 days (16–18 January, 2004). The pattern is regular in longitude, but irregular in latitude, since it depends on the availability of stars. Because of the geometry of occultation, one measurement is a horizontal average over a few hundreds km, which adds somewhat to the coverage.

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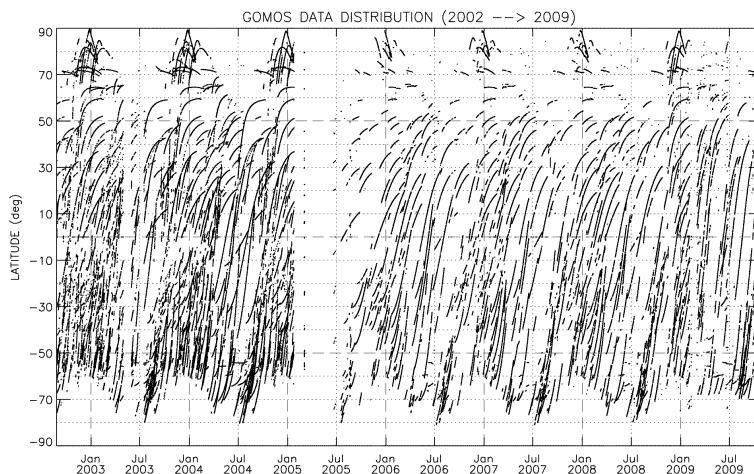
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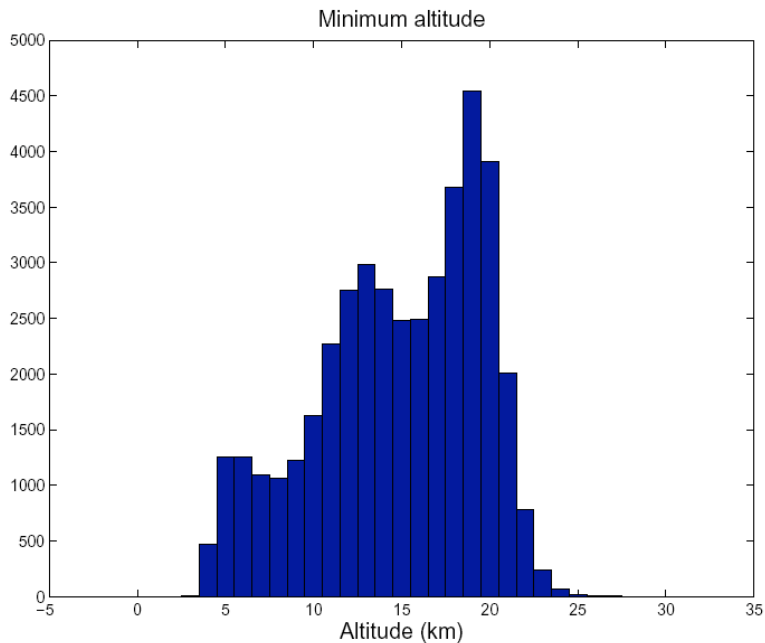


**Fig. 9.** Latitude distribution of all night time occultations performed by GOMOS (2002–2009). One arc represents many successive occultations of the same star, moving in latitude from one orbit to the next. The coverage was somewhat reduced after the 2005 malfunction of the Steering mirror mechanism. Polar latitudes are reached only during winter time.

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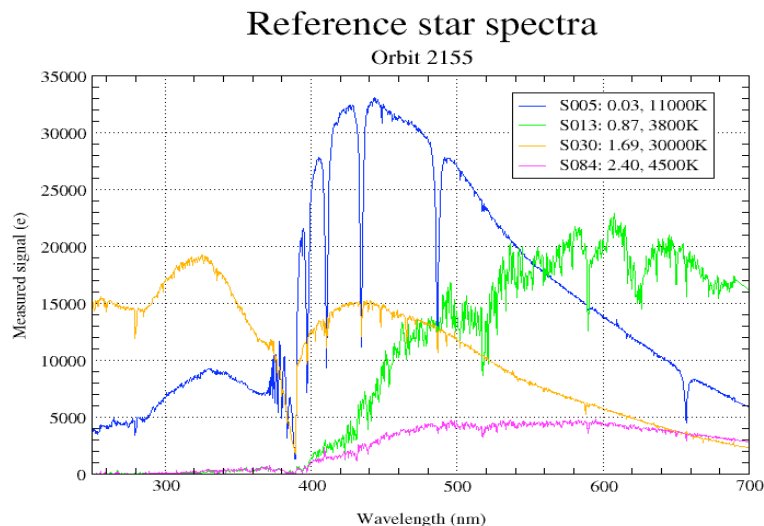


**Fig. 10.** The distribution of the termination altitudes during all occultations 2004, including those in bright limb. In Dark limb average is 15 km.

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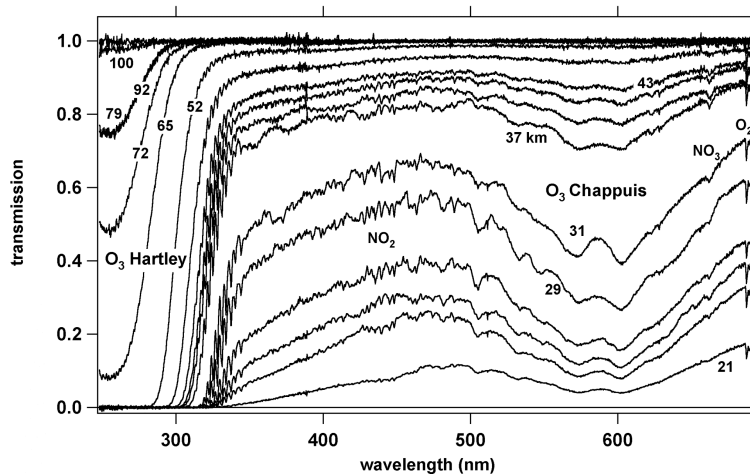


**Fig. 11.** Spectra of different stars observed by GOMOS. Hot stars contain more UV light than cool stars and are more suitable to the measurement of mesospheric ozone. Just below 400 nm, the low signal is due to the separation of the spectrum on two CCDs. The GOMOS ID number of the star is indicated, with its visual magnitude and temperature.

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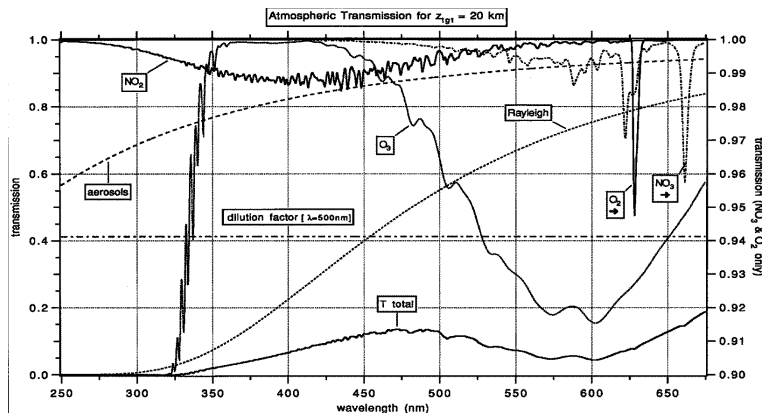
**Fig. 12.** Atmospheric transmission spectra along the line of sight from GOMOS to star Sirius, for different tangent altitudes.

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**Fig. 13.** Forward simulation of the atmospheric transmission. The contribution of various absorbers at a tangent altitude of 20 km are indicated as well as the total transmission. The dilution factor is due to atmospheric refraction, and is about 0.4 at 20 km altitude.

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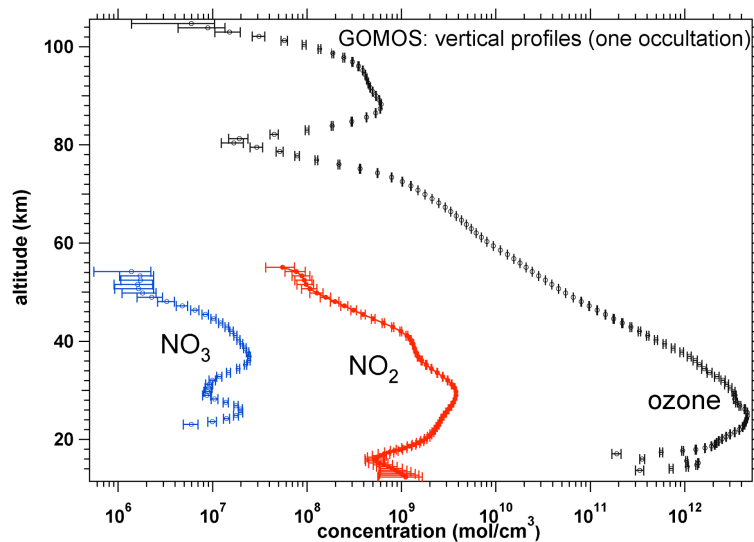
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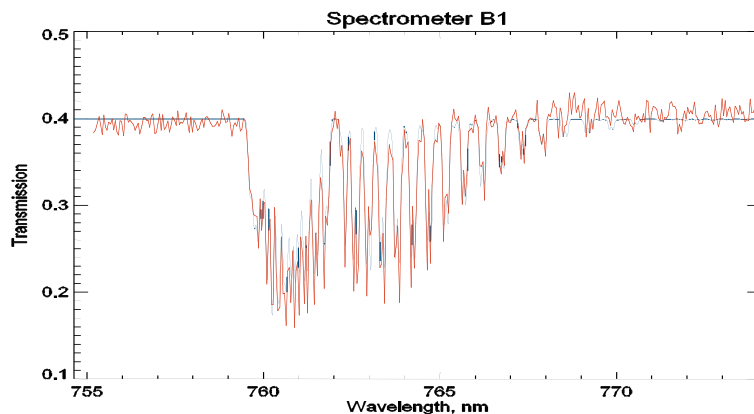


**Fig. 14.** Vertical profiles and their error bars of ozone, NO<sub>2</sub> and NO<sub>3</sub> retrieved from one single occultation of star Sirius.

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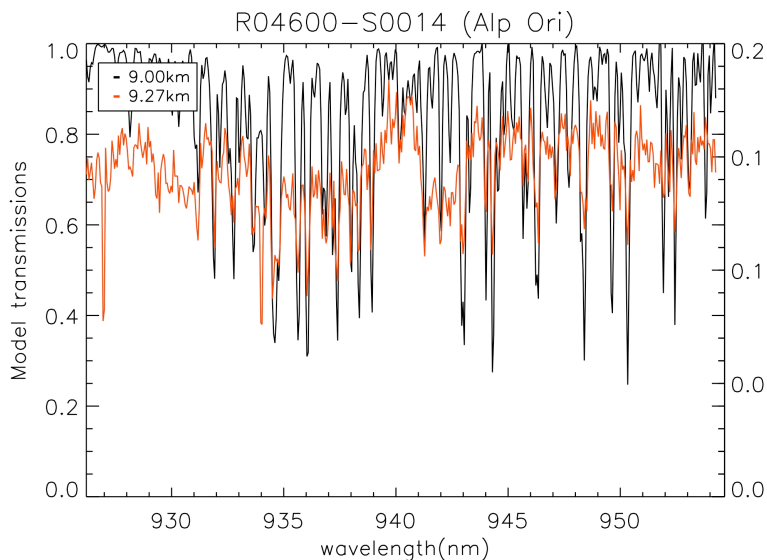


**Fig. 15.** Spectral transmission measured in the O<sub>2</sub> band (called A band around 760 nm), compared with a HITRAN model (adjusted to the baseline). The level of  $T_{\text{mod}}$  was adjusted to the level of the measured transmission, which is well below 1, mainly because of refraction effects.

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**Fig. 16.** GOMOS transmission obtained with the star Alpha Orionis (S0014 is the GOMOS ID number) at a tangent altitude of 9.27 km just below the tropopause (red curve, right scale), and the model transmission at 9 km (black curve, left scale). There are features in the measured spectra that do not come from H<sub>2</sub>O absorption, but rather from an imperfect correction of the severe Pixel-to-pixel-non-Uniformity affecting the CCD of spectrometer B2 in the range 940 nm. This was taken on ENVISAT orbit no. 4600.

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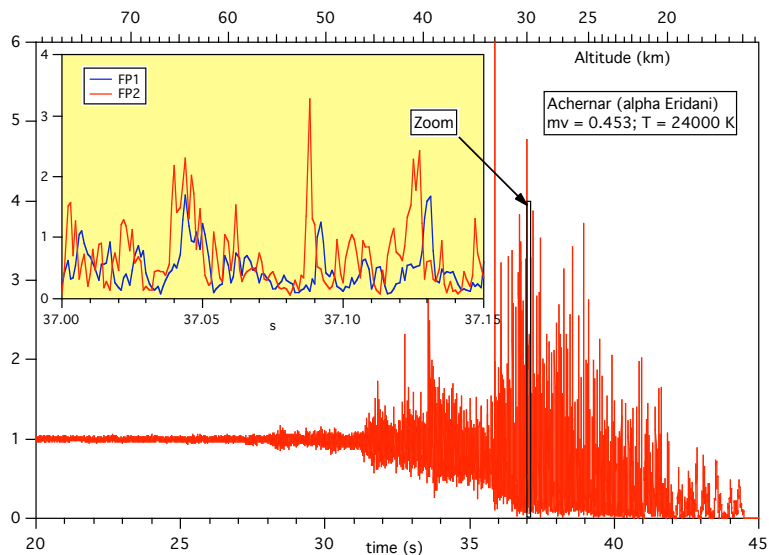
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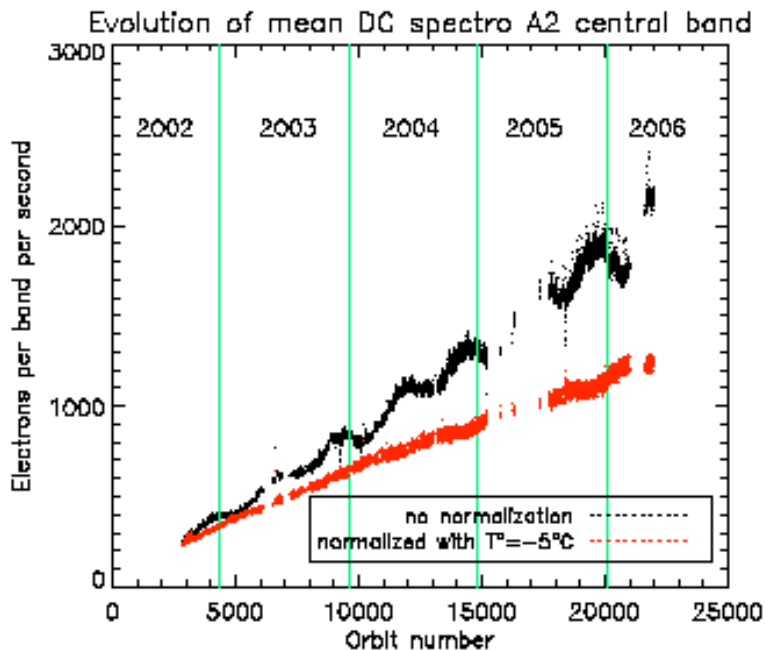


**Fig. 17.** Example of real scintillation recorded at 1 kHz by GOMOS. Tangent altitude is shown on a nonlinear scale at the top of the graph. The zoom shows the signals from “blue” and “red” photometers (see the text for details).

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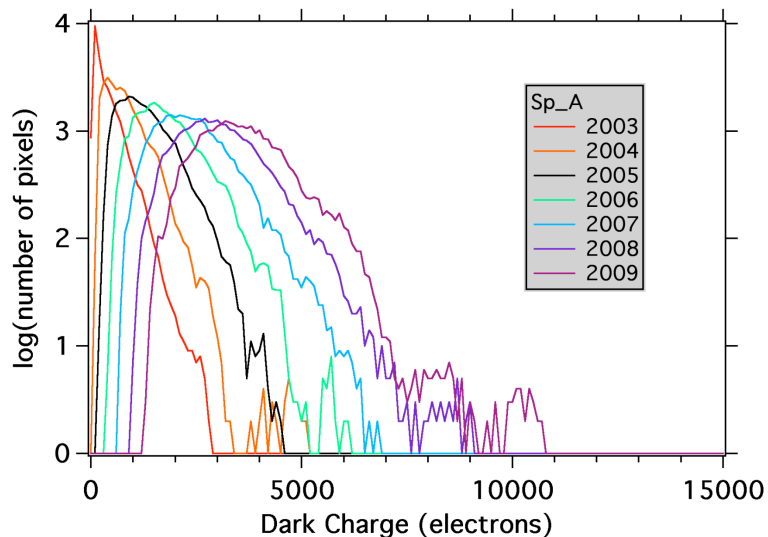


**Fig. 18.** Mean Dark Charge for spectrometer A2. The black curve shows seasonal variations due to the position of the sun and thus to the change of the temperature of the CCD. The red curve has been obtained by normalizing the black curve at a reference temperature of  $-5^{\circ}\text{C}$ . Therefore, the red curve shows that an increase of Dark Charge independent of the temperature still exists, due to radiation damage.

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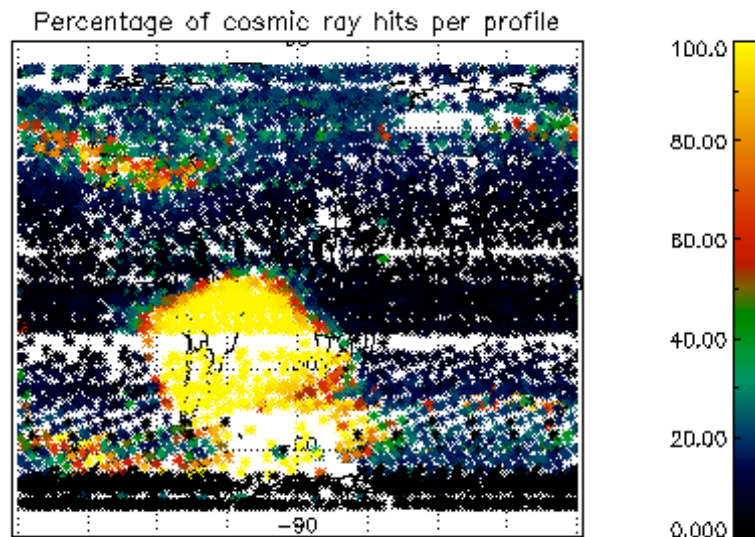


**Fig. 19.** Histogramme of Dark Charge of Spectrometer A CCD detectors. The bins are 100 electrons; the vertical scale is the Log 10 of the number of pixels having the specific dark charge of the bin. They are collected around the 1st of January, during 20 Dark Sky Area observations dedicated to the measurement of Dark Charge. The Dark Charge is increasing from year to year, due to cumulated radiation damage.

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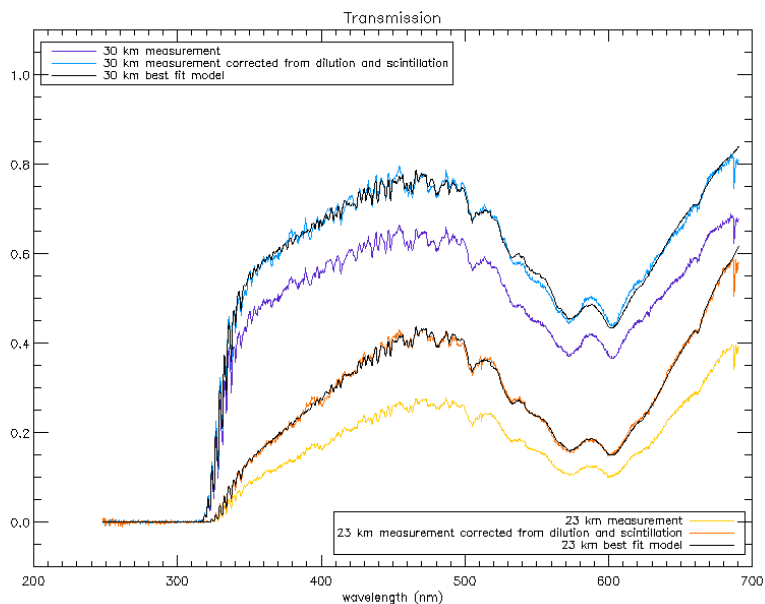
**Fig. 20.** Each point of the world map is the position of ENVISAT at the time of one occultation recorded by GOMOS during the month of November 2004. The color is coding the percentage of 0.5 s samples of CCD spectrometers which have at least one cosmic hit. Both North and South auroral zones are visible, but the region most affected is the South Atlantic Anomaly.

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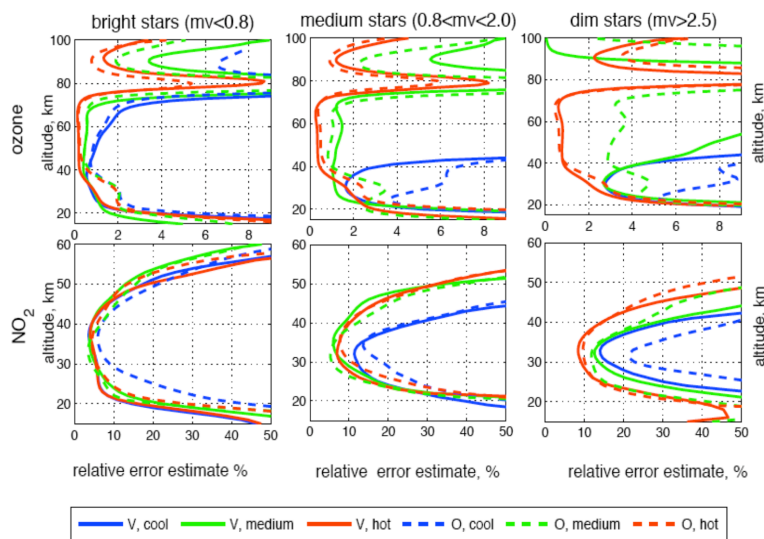


**Fig. 21.** Examples of transmissions measured at 23 and 30 km. The Level 1b measurements are in yellow and violet respectively for 23 and 30 km. In red and blue, after correction of dilution and scintillations. In black, are the best fit models of the transmission.

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**Fig. 22.** GOMOS error estimates of  $O_3$  (top row), and  $NO_2$  (second row) for representative cases: bright star (left column), typical star (middle column) and dim star (right column). The dashed lines correspond to oblique occultations and the solid lines to occultations in orbital plane. Stellar temperature is indicated with the line color: hot stars (red), medium stars (green) and cool stars (blue). These values correspond to the most recent version of data processing (GOPR 7.0) which is the baseline for the reprocessing in 2010 (From Tamminen et al., ACP GOMOS Special Issue, 2010).

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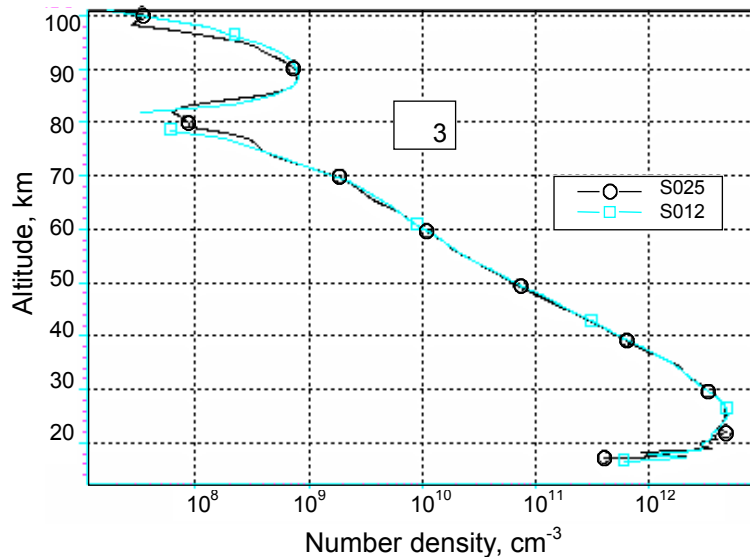
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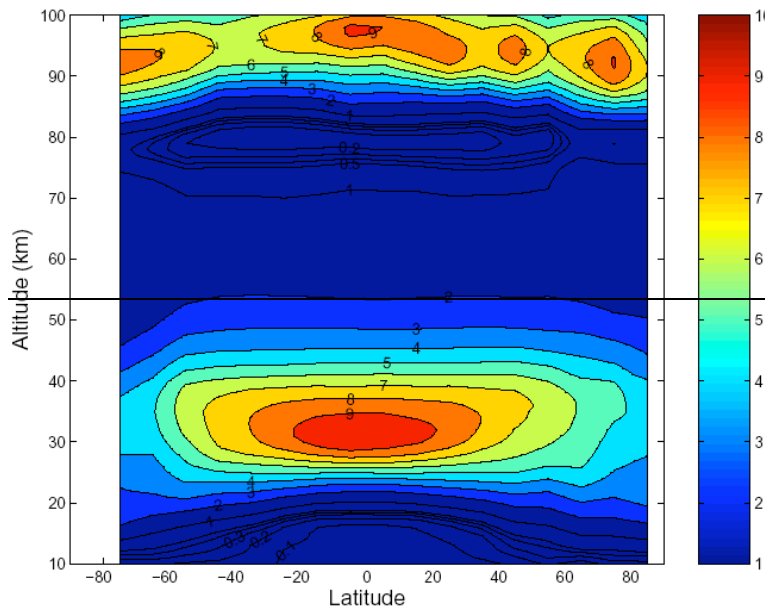


**Fig. 23.** Two vertical profile of ozone obtained at the same geographical location, but at two different (successive) orbits, and using two different stars with the tangent points differing by only 25 km.

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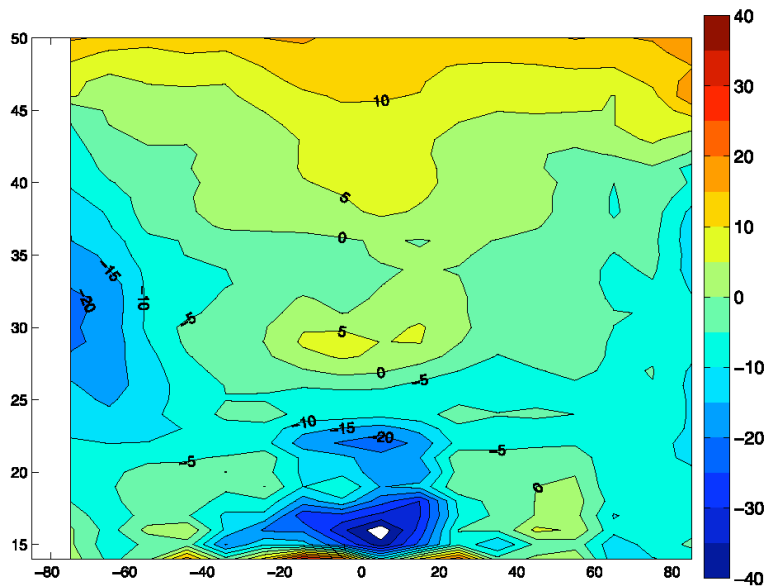


**Fig. 24.** Ozone mixing ratio yearly mean from GOMOS (from Kyrölä et al., 2006).

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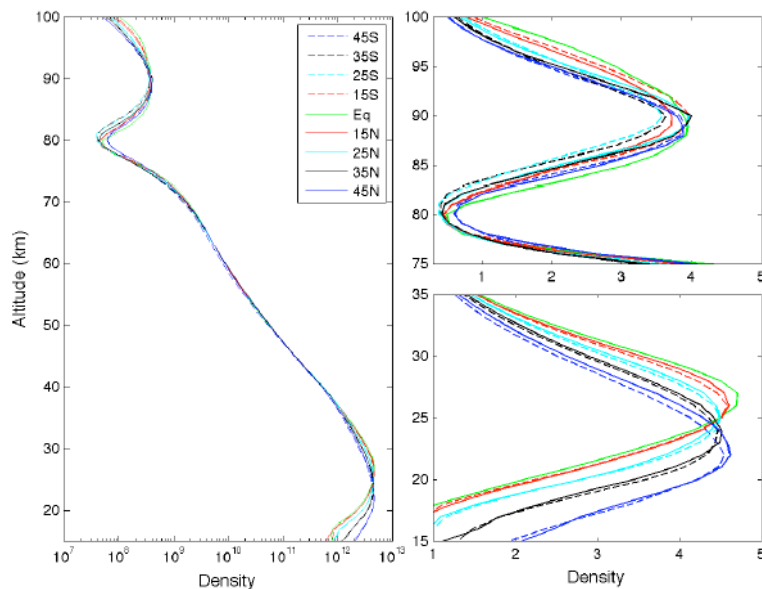


**Fig. 25.** Median of the relative difference (in %) between GOMOS ozone mixing ratio and the F-K climatology in 2003. The contours are separated by 5%. The horizontal axis is latitude in degrees, and the vertical axis is altitude in km (from Kyrölä et al., 2006).

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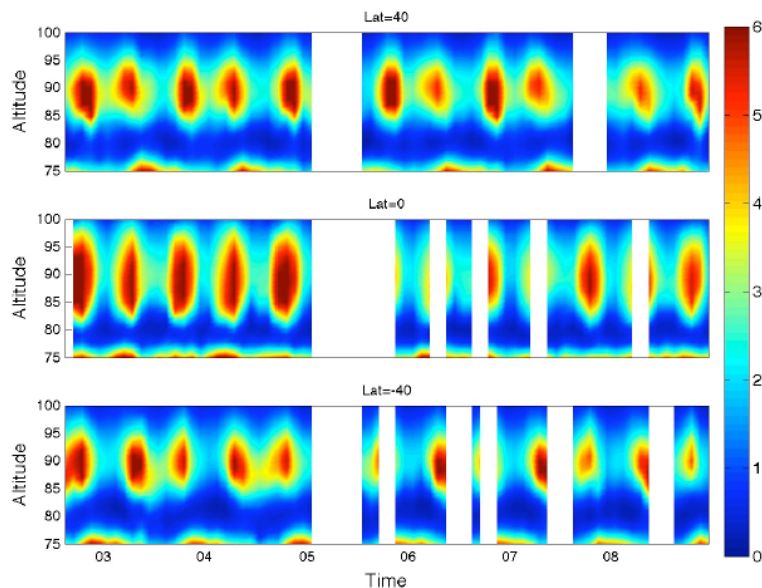


**Fig. 26.** Average vertical profiles of ozone in the period 2003–2008. The left panel shows vertical profiles at different latitudes (unit  $\text{cm}^{-3}$ ). The upper right panel shows the same profiles in the mesosphere (unit  $10^8 \text{ cm}^{-3}$ ) and the lower right panel in the stratosphere (unit  $10^{12} \text{ cm}^{-3}$ ) (from Kyrölä et al., 2010b).

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**Fig. 27.** Ozone number density (scaled by  $10^8 \text{ cm}^{-3}$ ) in the MLT at three latitude belts in 1 August 2002–31 December 2008. Top:  $30^\circ \text{ N}–50^\circ \text{ N}$ , Middle:  $10^\circ \text{ S}–10^\circ \text{ N}$ , Bottom:  $30^\circ \text{ S}–50^\circ \text{ S}$  (from Kyrölä et al., 2010b).

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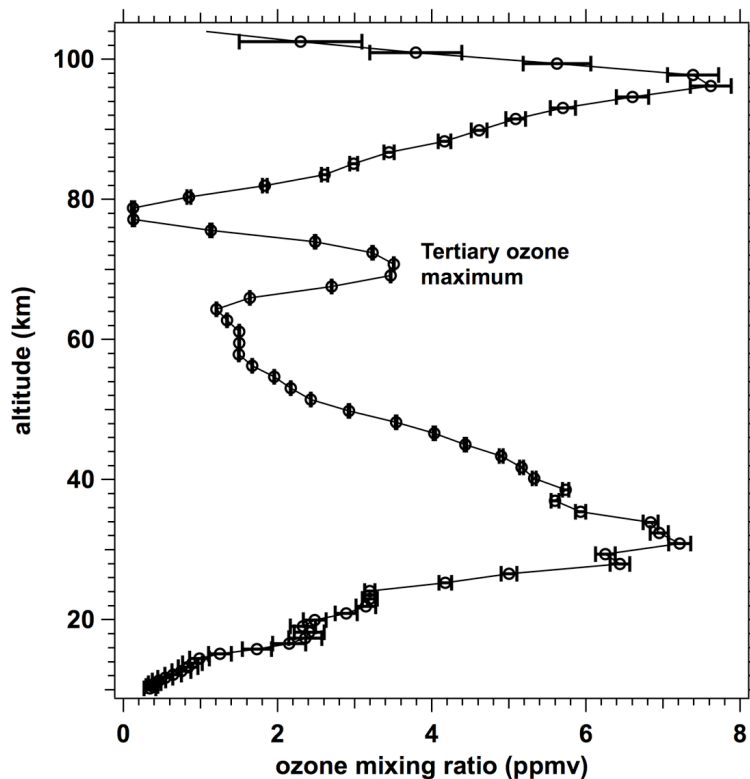
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**Fig. 28.** Vertical profile of ozone mixing ratio measured by GOMOS on star S001 at orbit 4638, at 71° N latitude on 30 January 2003. It displays the Tertiary Ozone Maximum, peaking at 3.6 ppmv on this particular profile. The air density is found in the Level 2 GOMOS product, derived from ECMWF and MSIS 90 model.

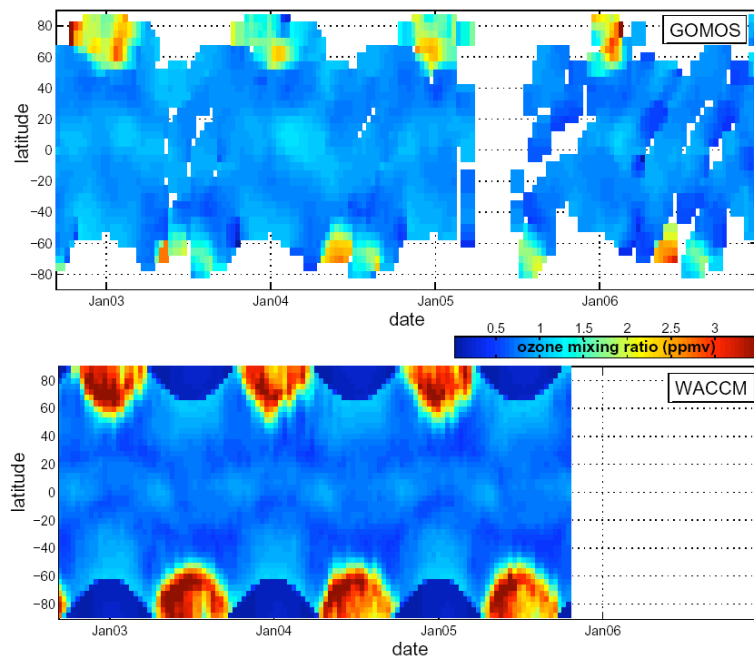
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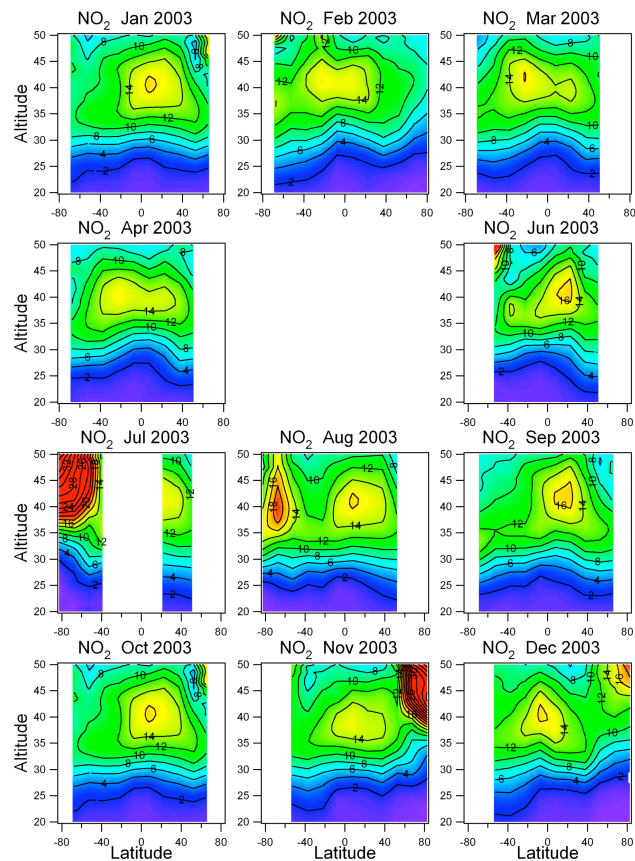


**Fig. 29.** Ozone mixing ratio at 72 km. Top: from GOMOS measurements (zonal mean), bottom: from WACCM simulations (mean over three ensemble simulations for  $0^\circ$  longitude, midnight). Temporal and latitudinal averaging is nearly the same for both experimental and model data (from Sofieva et al., 2009b).

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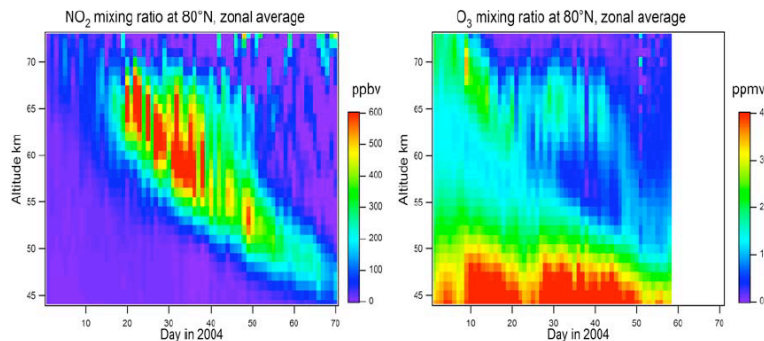


**Fig. 30.** Latitude-altitude maps of  $\text{NO}_2$  mixing ratio in ppbv for each month in 2003. A malfunction of the pointing mechanism occurred in May 2003. There are strong increases of  $\text{NO}_2$  in July 2003 in the south polar region, and in November 2003 in the north polar region, caused by the descent of air carrying  $\text{NO}$  molecules in the polar night (from Hauchecorne et al., 2005a).

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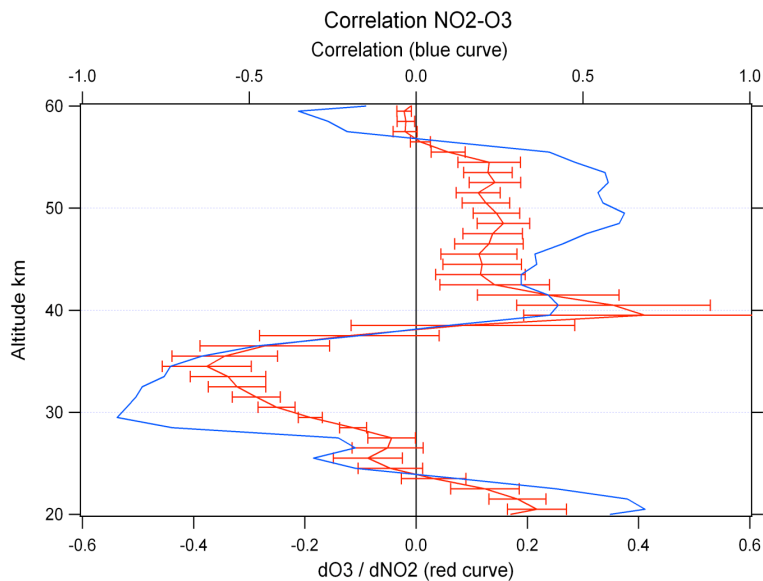


**Fig. 31.** Evolution of zonal averaged mixing ratio of NO<sub>2</sub> (left) and O<sub>3</sub> (right) at 80° N from GOMOS data between 1 January and 10 March 2004 (from Hauchecorne et al., 2007).

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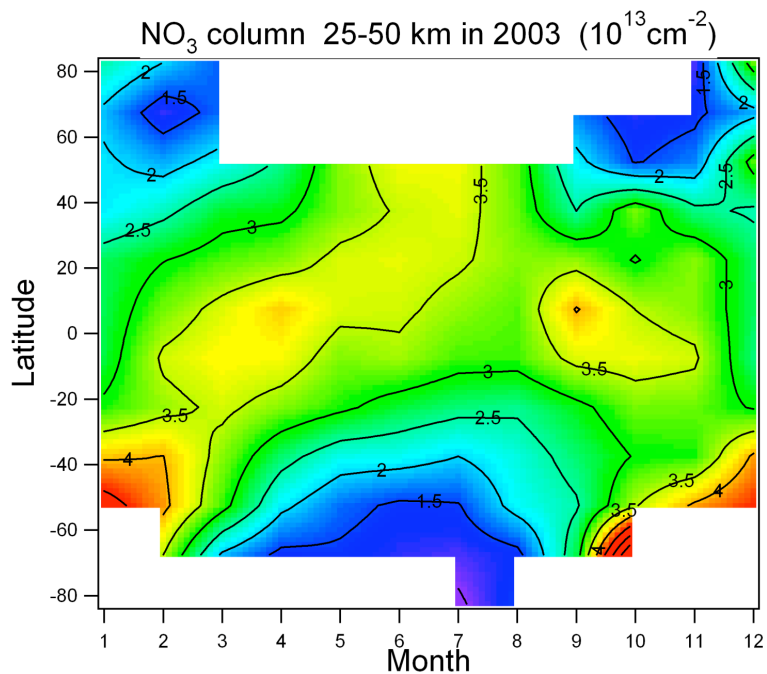
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**Fig. 32.** Correlation between the deviation of NO<sub>2</sub> and O<sub>3</sub> from their mean seasonal value at the same altitude (blue curve) and relative variation of O<sub>3</sub> per unit relative variation of NO<sub>2</sub> (red curve) (from Hauchecorne et al., 2010).

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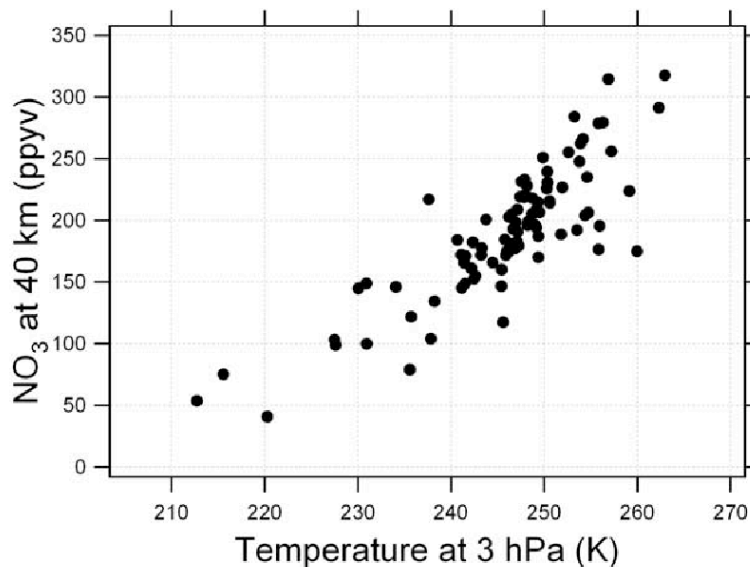


**Fig. 33.** Time-latitude cross section of NO<sub>3</sub> stratospheric column (25–50 km) in  $10^{13} \text{ cm}^{-2}$  in 2003 derived from GOMOS vertical profiles (from Hauchecorne et al., 2005).

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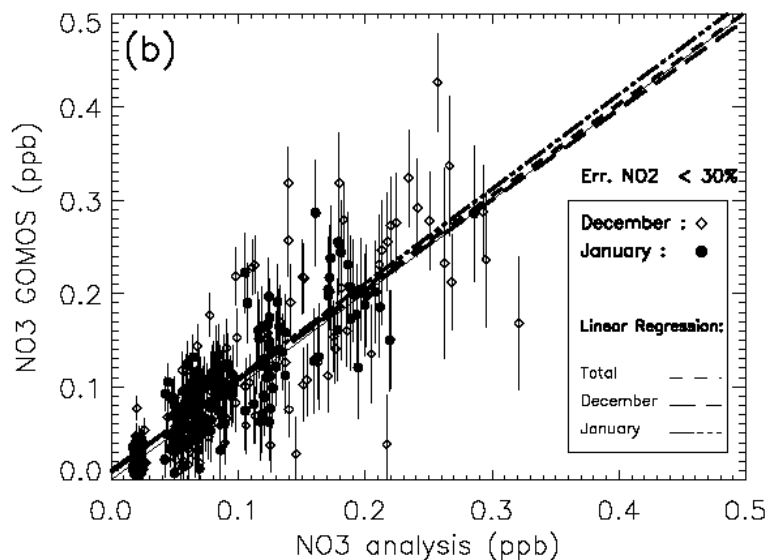


**Fig. 34.** NO<sub>3</sub> mixing ratio at 40 km versus European Centre for Medium-Range Weather Forecasts (ECMWF) temperature at 3 hPa (~40 km), a results of the temperature dependent reaction rate producing NO<sub>3</sub> (from Hauchecorne et al., 2005).

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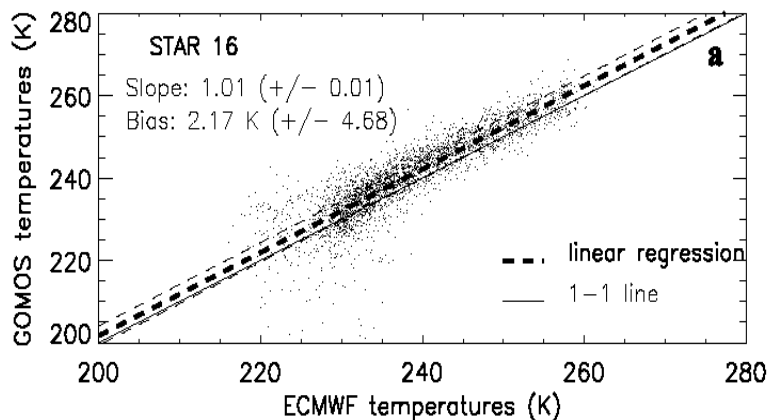


**Fig. 35.** GOMOS NO<sub>3</sub> measurement as a function of analyzed NO<sub>3</sub> for cases when NO<sub>2</sub> error measurements is less than 30%. NO<sub>3</sub> error measurements are indicated with vertical lines. The linear regressions for the different periods are represented with dashed lines. The 1-to-1 line is represented with a thin black line. The two periods of GOMOS O<sub>3</sub> and NO<sub>2</sub> assimilated data are 5 to 6 December 2002, and January 30, with occultations of star star Beta Carinae (GOMOS star S029, visual magnitude 1.67, temperature 10 200 K) in a latitude band band 0–1° N for the first period, and 16–17° N for the second period (from Marchand et al., 2004).

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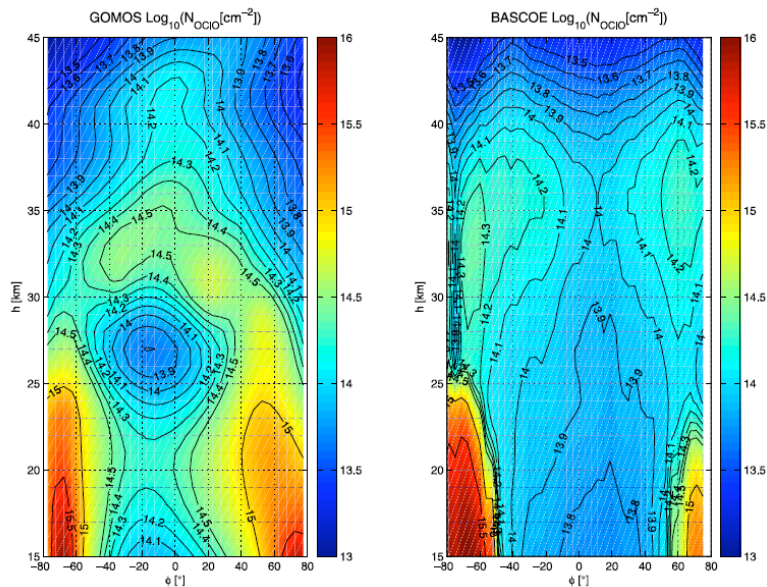
**Fig. 36.** Temperature retrieved from  $\text{NO}_3$  and  $\text{O}_3$  GOMOS data (star number 16, Antares Alpha Scorpio) as a function of the corresponding ECMWF temperatures. The slope is  $1.01 \pm 0.01$ . GOMOS retrieved temperatures are warmer by about  $2^\circ \text{K}$  than ECMWF temperatures. When more stars are included in the study, the bias is found to be  $2.67^\circ \text{K}$  (from Marchand et al., 2007).

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**Fig. 37.** Isocontours (latitude–altitude) of the OClO slant column densities measured by GOMOS and modeled by the BASCOE model at the same geolocation and time for the measurement periods (14 January–9 February 2003) and (20 July–30 December 2003). Both polar regions are probed during polar night (from Fussen et al., 2006).

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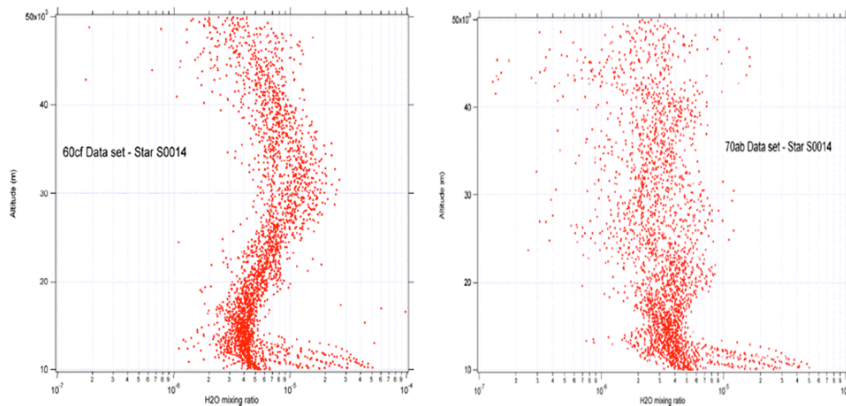
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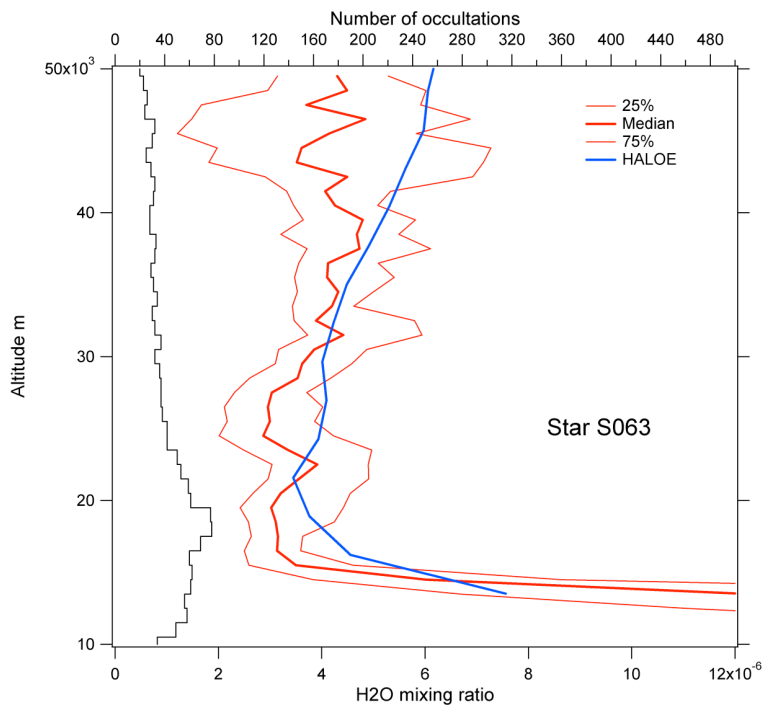


**Fig. 38.** Comparison of the H<sub>2</sub>O mixing ratios found with the official algorithm V 6.0 (left) and the new Level 1b algorithm V7.0 (right). For this series of occultations, the bump at 30 km has completely disappeared (from Bertaux et al., 2009).

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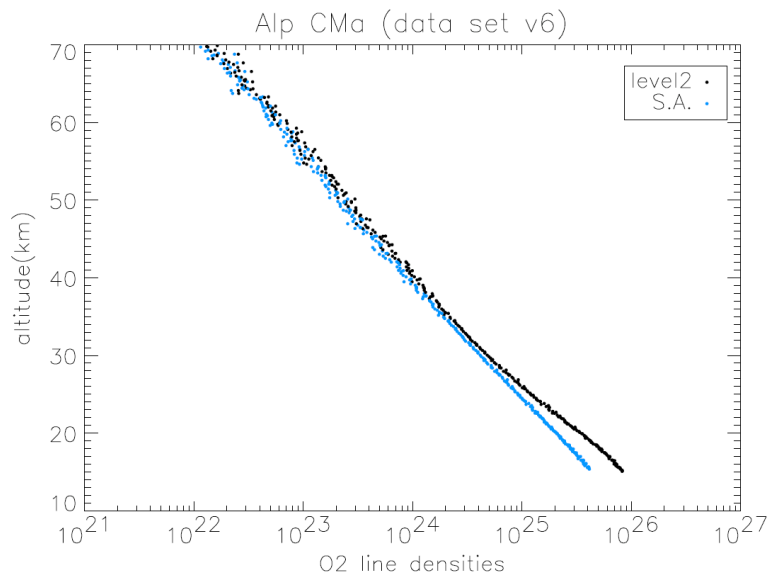


**Fig. 39.** Comparison of H<sub>2</sub>O vertical profiles obtained by HALOE (blue line) and GOMOS (red lines). In black and upper scale: the number of GOMOS measurements in each altitude bin obtained with the occultation of star Gamma Gruis. The thick red line is the median value, and the thin lines are the upper and lower quartile of the distribution in each bin (from Bertaux et al., 2009).

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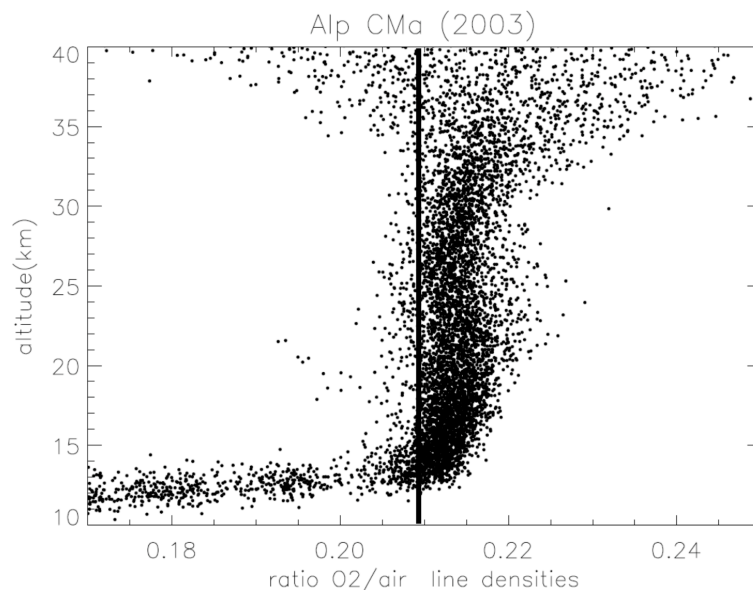


**Fig. 40.** Comparison of oxygen line densities retrieved from GOMOS 760 nm O<sub>2</sub> band transmission measurements for 6 occultations of star Sirius (Alpha Canis Major). Black point: with models computed with HITRAN 1996 data base. Blue points: with HITRAN 2000 data base. There is an increasing difference with decreasing altitude.

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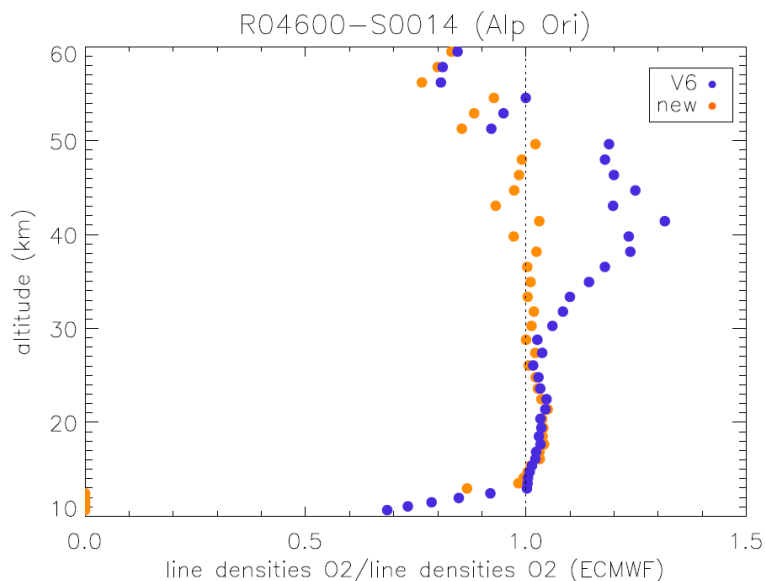


**Fig. 41.** A number of occultations of Sirius are considered during 2003. Each point is the ratio  $N(\text{O}_2) / N_{\text{air}}$  of the retrieved line density  $N(\text{O}_2)$  from GOMOS to the line density  $N_{\text{air}}$  computed from ECMWF. A vertical bar is placed at the value 0.20946, the normal  $\text{O}_2$  mixing ratio. There is an unexplained bias where the measurements are better.

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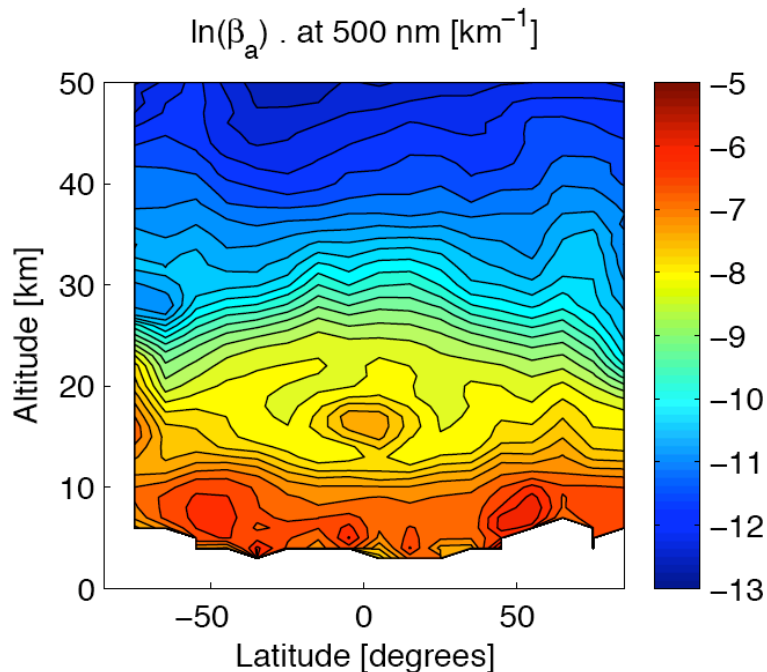


**Fig. 42.** Comparison of the retrieved line densities with the present version GOPR 6 of the algorithm, and a new version, where the modeled transmissions are adapted from ECMWF to the time and location of the occultation. This is one occultation of Alpha Orionis at orbit 4600.

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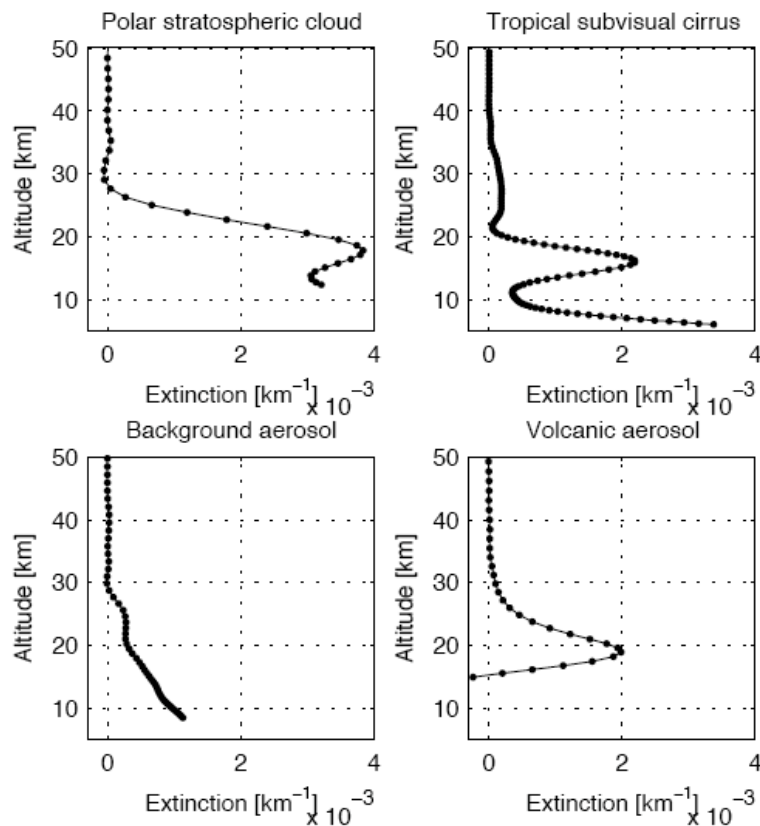


**Fig. 43.** The natural logarithm of the 500 nm aerosol extinction median values for the year 2003 ( $\text{km}^{-1}$ ). The isolated feature at the equator (15–17 km) is due to subvisible equatorial cirrus, while PSCs are mostly seen in the South polar vortex, and barely visible in the North polar vortex (from Vanhellemont et al., 2005)

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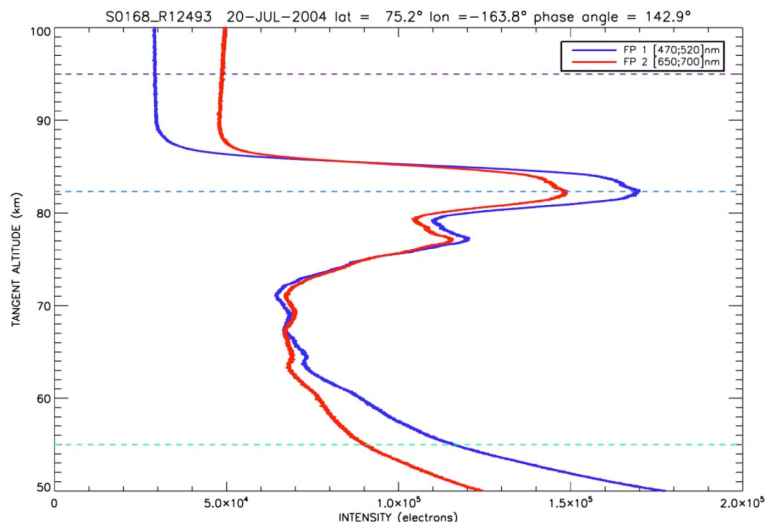
**Fig. 44.** Individual GOMOS particle extinction profiles: a Polar Stratospheric Cloud (30/7/2003, 72,57° S, 2.18° W), a tropical subvisual cirrus cloud (10/7/2002, 0.52° S, 78.69° E), background stratospheric aerosols (12/09/2003, 43.34° S, 137.36° W), volcanic stratospheric aerosols (1/09/2007, 4.52° S, 27.15° E). All plots have the same scale, in order to facilitate comparisons of magnitude (from Vanhellemont et al., 2010).

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**Fig. 45.** Example of GOMOS photometers observation of a noctilucent cloud (or Polar Mesospheric Cloud), detected as an increase of solar light by the particles of the clouds, in addition to the Rayleigh scattering by air molecules around 85 km. The dashed lines indicate, from top, the region with no cloud (signal from the star), the peak intensity of the cloud, and the region below the cloud, where the Rayleigh scattering dominates the bright limb intensity (from Péro et al., 2010).

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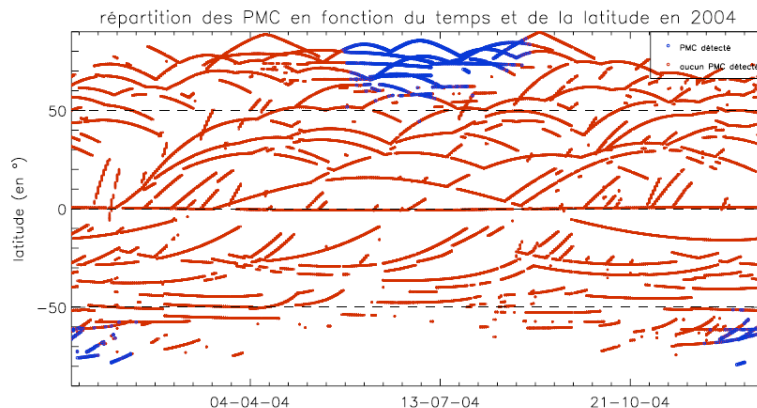
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**Fig. 46.** Latitude-time plot of all day side occultation points during the year 2004. In red are marked the points where no PMC is seen, while in blue are the points with a PMC detected. The seasonal behavior is well marked. The coverage is somewhat poorer in the south, but still PMCs are less frequent in the South than in the North.

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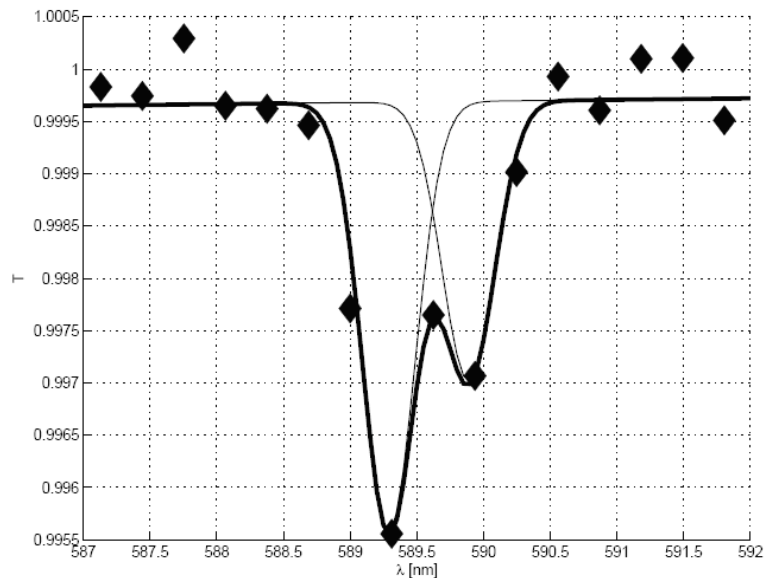
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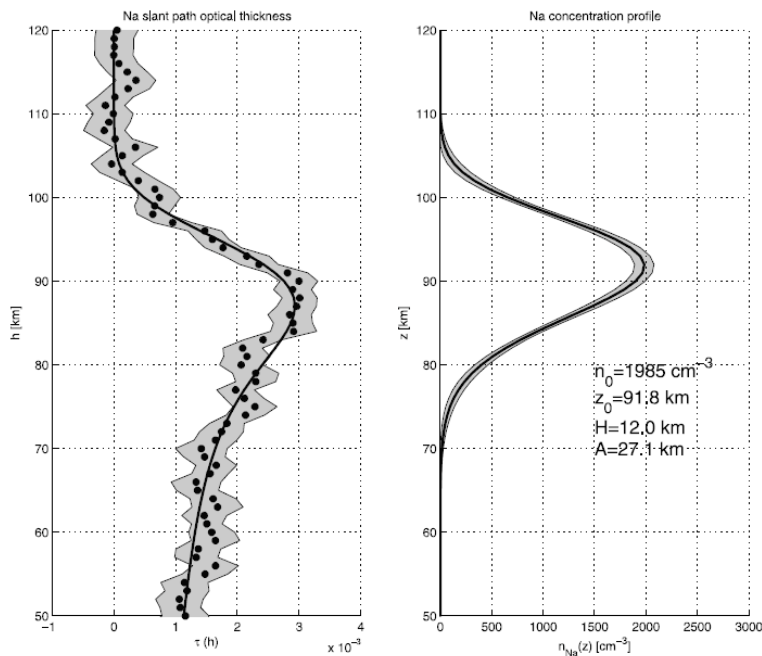


**Fig. 47.** Diamonds: the median transmittance (of 1121 occultations) measured between 70° N and 80° N during January 2003. Thin full lines: individual D2 and D1 absorptions assuming to have the same instrumental line spread function. Thick line: best fit for the total transmittance (with baseline removed) (from Fussen et al., 2010).

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**Fig. 48.** Left panel: Retrieved Na slant path optical thickness (full circles) versus the tangent altitude with associated errors (grey band). The full line is the best fit model. Right panel: corresponding Na concentration profile and optimal parameters. The grey band represents the estimated random error on the transmittance (Fussen et al., 2004).

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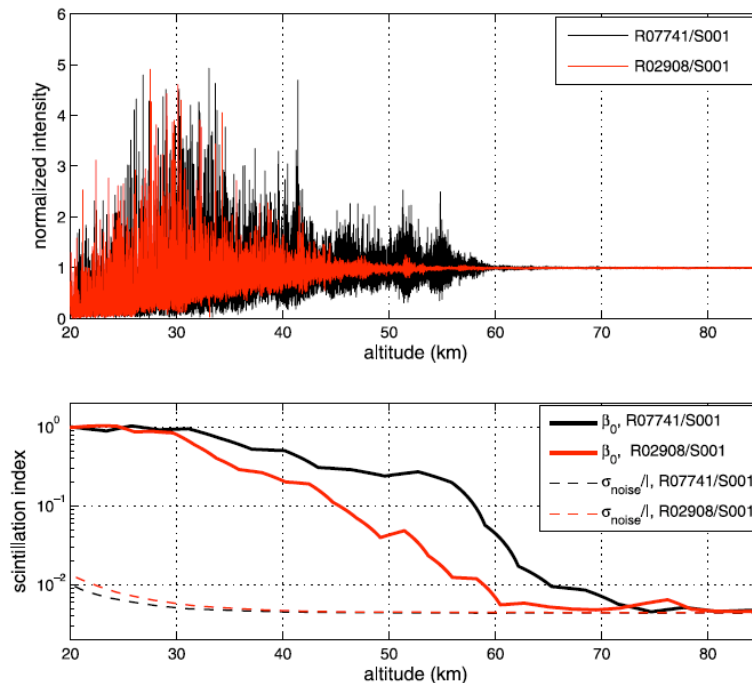
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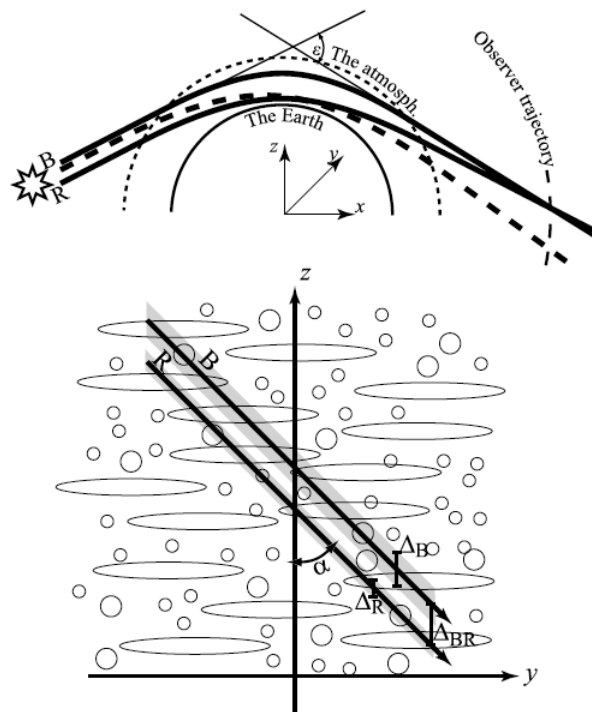


**Fig. 49.** (top) Photometer signals by the GOMOS red photometers in occultations R07741/S001 (62 S, 7 E, 23 August 2003 23:51 UTC) and R02908/S001 (37 S, 106 W, 20 September 2002 07:01 UTC). (bottom) Scintillation index ( $\beta$ ) for these two occultations (from Sofieva et al., 2007).

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**Fig. 50.** Observation scheme of the two-wavelength scintillation. (top) A cut of the atmosphere by the plane containing B (blue) and R (red) rays (thick solid lines), which are received at the same time  $t_0$  by the GOMOS fast photometers FP. The ray curvature and the refraction angle  $\varepsilon$  are largely exaggerated. Thick dashed line denotes a blue ray having the same ray perigee altitude as the red one, but coming to GOMOS FP with a refractive time delay  $dt$ . (bottom) A cut of the atmosphere by the atmospheric screen. Solid lines denote trajectories of the intersection points of the rays with this plane. Shading illustrates chromatic “thickness”  $\Delta R$  and  $\Delta B$  of the rays, due to the filters optical bandwidth. The photometers simultaneously register the rays with the same coordinate  $y$ . Sketched contours illustrate anisotropic and isotropic irregularities of air density (from Gurvich et al., 2005).

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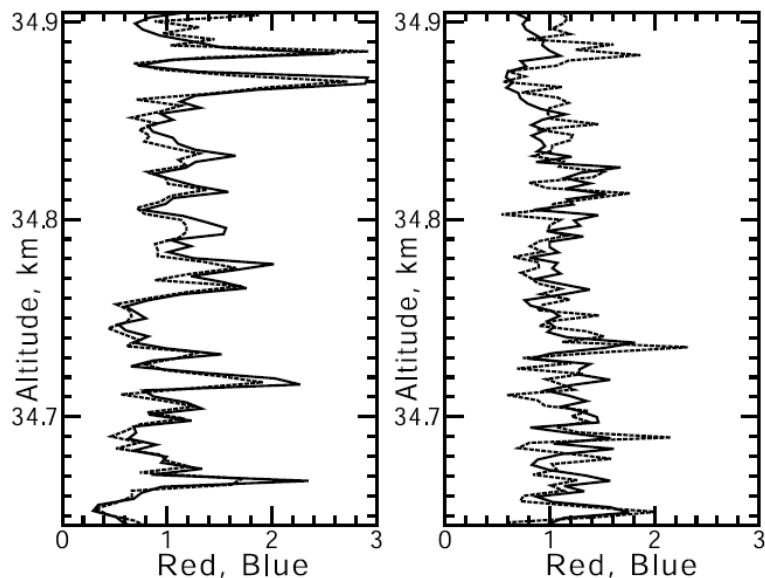
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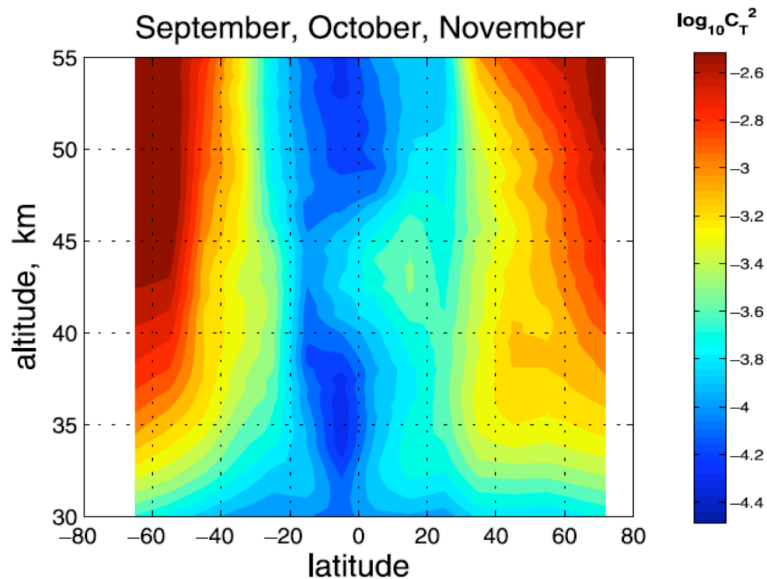


**Fig. 51.** Comparison of two records of two-wavelength scintillations ((left) vertical, (right) oblique at  $46^\circ$ ). Abscissa is red (672 nm, dashed line) and blue (499 nm, solid line) intensities normalized on the corresponding mean. Ordinates are altitude of ray perigee. The correlation is poorer for oblique occultation, because of the effect of isotropic turbulence. (from Gurvich et al., 2005).

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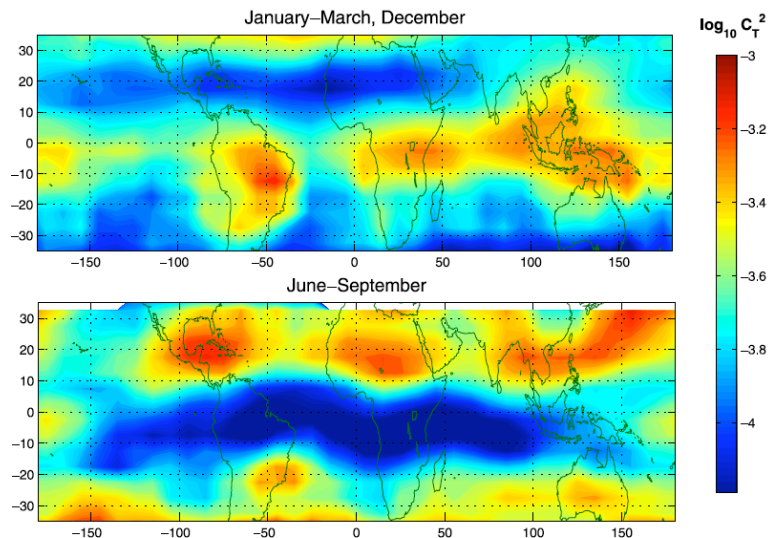
**Fig. 52.** Zonal averaged  $C_T^2$  ( $\text{K}^2\text{m}^{-2/3}$ ) in one season, which covers the end of southern winter pole (September) and the beginning of Northern winter pole (November) logarithmic color scale. It shows the large increase of  $C_T^2$  in both winter poles, connected to the polar night jet. The four seasons are displayed in Gurvich et al. (2007).

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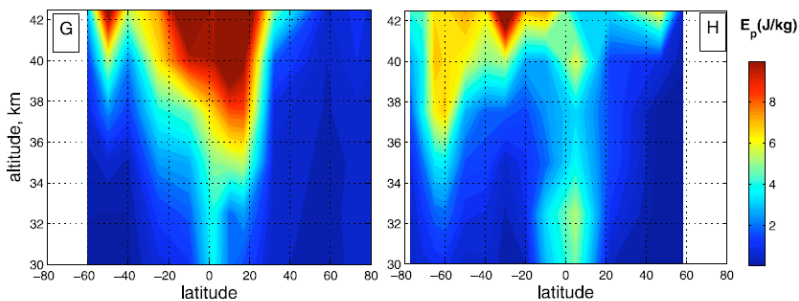


**Fig. 53.**  $C_T^2$  (K<sup>2</sup> m<sup>-2/3</sup>) at 42 km for (top) January–March, December and for (bottom) June–September, logarithmic color scale. The data are averaged in  $5^\circ \times 10^\circ$  latitude-longitude bins and a three-point smoothing is applied to the obtained fields. In order to make these maps more contrasting, the color scale covers one decade only (from Gurvich et al., 2007).

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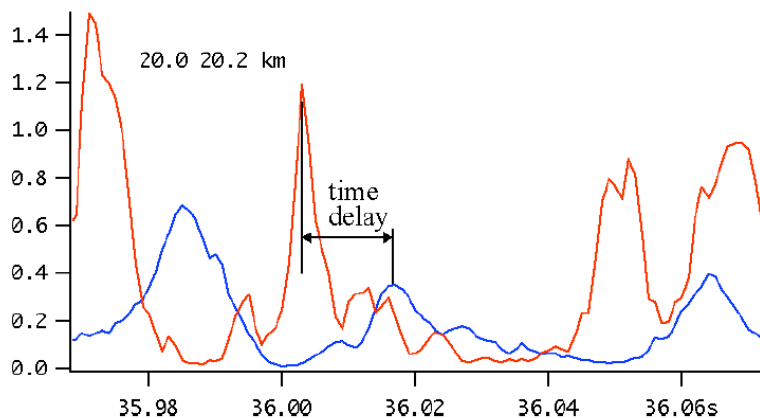


**Fig. 54.** Zonal mean values of the potential energy  $E_p$  (Joule/kg) of gravity waves as determined from GOMOS scintillation measurements during two 4 months periods of year 2003: January–March plus December (left), and June–September (right). See text for discussion (from Sofieva et al., 2009).

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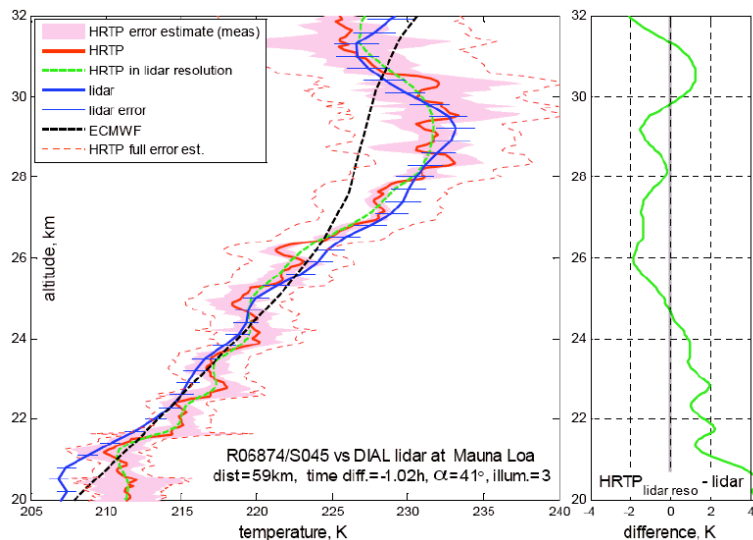


**Fig. 55.** Sample of blue and red photometer records (103 milliseconds only). Tangent altitude is in the range 20.2 to 20.0 km (200 m vertical range). Note the time delay and the additional smoothing of the blue signal due to larger refractivity bandwidth. Absorption of blue light is stronger due to Rayleigh and aerosol scattering (from Dalaudier et al., 2006).

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**Fig. 56.** Sample HRTP temperature profile (in red) obtained from two-color scintillation data. The uncertainty (in pink) distinguishes contribution from random errors (colored area) and total error including initialization bias (dashed). From Dalaudier et al. (2006).

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