



Multi-source SO₂ emission retrievals and consistency of satellite and surface measurements with reported emissions

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Abstract. Reported sulfur dioxide (SO₂) emissions from US and Canadian sources have declined dramatically since the 1990s as a result of emission control measures. Observations from the Ozone Monitoring Instrument (OMI) on NASA's Aura satellite and ground-based in situ measurements are examined to verify whether the observed changes from SO₂ abundance measurements are quantitatively consistent with the reported changes in emissions. To make this connection, a new method to link SO₂ emissions and satellite SO₂ measurements was developed. The method is based on fitting satellite SO₂ vertical column densities (VCDs) to a set of functions of OMI pixel coordinates and wind speeds, where each function represents a statistical model of a plume from a single point source. The concept is first demonstrated using sources in North America and then applied to Europe. The correlation coefficient between OMI-measured VCDs (with a local bias removed) and SO₂ VCDs derived here using reported emissions for 1° by 1° gridded data is 0.91 and the best-fit line has a slope near unity, confirming a very good agreement between observed SO₂ VCDs and reported emissions. Having demonstrated their consistency, seasonal and annual mean SO₂ VCD distributions are calculated, based on reported point-source emissions for the period 1980–2015, as would have been seen by OMI. This consistency is further substantiated as the emission-derived VCDs also show a high correlation with annual mean SO₂ surface concentrations at 50 regional monitoring stations.

1 Introduction

Sulfur dioxide (SO₂) is a designated criteria air pollutant that enters the atmosphere through anthropogenic (e.g., combustion of sulfur-containing fuels, oil refining processes, metal ore smelting operations) and natural processes (e.g., volcanic eruptions and degassing). Over the past 3 decades both the US and Canada have taken measures to reduce atmospheric emissions of SO₂ in order to combat acidification of the ecosystem (e.g., acid rain) and fine particulate matter. As a result, between 1990 and 2012, reported emissions of SO₂ declined by 78 % in the United States and 58 % in Canada (IJC, 2014). In this study, we examined how well the changes in the reported emissions agree with the SO₂ changes in North America observed by satellite and surface instruments.

Ground-based networks such as the US Clean Air Status and Trends Network (CASTNet) and Canadian Air and Precipitation Monitoring Network (CAPMoN) are specifically designed to monitor long-term trends of gaseous pollutants in rural areas away from major pollution emission sources (Baumgardner et al., 1999; Park et al., 2004; Schwede et al., 2011). Their measurements show that over the eastern US, reductions in regional SO₂ emissions have led to significant reductions in monitored SO₂ concentrations (Sickles II and Shadwick, 2015; Xing et al., 2013).

Satellites provide global measurements of SO₂ vertical column densities (VCDs): the total number of molecules or total mass per unit area (Krotkov et al., 2008; Li et al., 2013; Theys et al., 2015). They have been previously used to study the evolution of SO₂ VCDs over large regions

such as Europe (Krotkov et al., 2016), China (Jiang et al., 2012; Koukouli et al., 2016; Li et al., 2010; Witte et al., 2009), India (Lu et al., 2013), and the US (Fioletov et al., 2011). Satellite instruments can detect anthropogenic SO₂ signals from large individual point sources such as copper and nickel smelters, power plants, oil and gas refineries, and other sources (Bauduin et al., 2014, 2016; Carn et al., 2004, 2007; Fioletov et al., 2013; de Foy et al., 2009; Lee et al., 2009; McLinden et al., 2012, 2014; Nowlan et al., 2011; Thomas et al., 2005). An 11-year-long record of satellite SO₂ data over different regions of the globe, including the eastern US and southeastern Canada, was examined recently (Krotkov et al., 2016). The analysis shows a substantial (up to 80 %) decline in the observed VCD values over that region.

These satellite measurements can also be used as an independent source to verify reported changes in emissions. Methods for emission estimates from satellite measurements have been recently reviewed by Streets et al. (2013). One such method that does not require the use of atmospheric chemistry models has been commonly used in recent years. By first merging observations from the Ozone Monitoring Instrument (OMI) with wind information, the downwind decay of several pollutants can be analyzed, and in so doing estimates of the total SO₂ (or NO₂) mass (α) near the source and its lifetime or, more accurately, decay time (τ) can be derived (Fioletov et al., 2011, 2015; de Foy et al., 2015; Lu et al., 2013, 2015; Wang et al., 2015). The emission strength (E) can be obtained using the expression $E = \alpha/\tau$ if we assume a steady state for these quantities. The mass can be derived directly from satellite measurements, while the lifetime can be either prescribed using known emissions (Fioletov et al., 2013) or estimated from the measurements based on the rate of decay of VCD with distance downwind (Beirle et al., 2014; Carn et al., 2013; de Foy et al., 2015). Model-based comparisons of different methods to estimate E and τ demonstrate that such methods can produce accurate estimates of τ (de Foy et al., 2014). In our previous study (Fioletov et al., 2015), values of α and τ for anthropogenic point sources were derived from OMI measurements by fitting a 3-D function of the geographic coordinates and wind speed.

These methods, however, are applicable to individual point sources. When this condition is not met, as is the case for multiple sources, either the sources can be combined together if they are close (Fioletov et al., 2015) or the fitting domain is split and the sources are fit separately (Wang et al., 2015). Both approaches have their limitations. In this study, we derive a general relationship between emissions and VCDs that can be used for the estimation of emissions from multiple sources. Moreover, the approach can be used in reverse: that is, VCDs can be estimated directly from reported emission data, thus making it possible to study the link between VCDs and surface concentrations even for the period before satellite measurements became available. This study is focused on the eastern US and southeastern Canada, where the majority of large North American SO₂ emission sources (mainly

coal-burning power plants) are located, where the changes in both reported emissions and measured VCDs are particularly large, and where emissions are measured directly at the stack for most sources. In this region, there is also a network with long-term records of uniform SO₂ surface concentration measurements. All of this makes it possible to study consistency between the measurements of emissions, VCDs, and surface concentrations. Once the link between these measurements is verified, it is possible to estimate one measured quantity from another. As an illustration, we demonstrate how European SO₂ emissions can be estimated from OMI VCD data.

2 Data sets

2.1 Satellite SO₂ VCD data

OMI, a Dutch–Finnish UV–visible wide field-of-view nadir-viewing spectrometer flying on NASA’s Aura spacecraft (Schoeberl et al., 2006), provides daily global coverage at high spatial resolution (Levelt et al., 2006). OMI has the highest spatial resolution and is the most sensitive to SO₂ sources among the satellite instruments of its class (Fioletov et al., 2013). Operational OMI planetary boundary layer SO₂ data produced with the principal component analysis (PCA) algorithm (Li et al., 2013) for the period 2005–2015 were used in this study. Retrieved SO₂ VCD values are given in Dobson units (DU; 1 DU = 2.69×10^{26} molec km^{−2}).

OMI SO₂ VCD data are retrieved for 60 cross-track positions (or rows). In order to use only data with the highest spatial resolution, we excluded data from the first 10 and last 10 cross-track positions from the analysis to limit the across-track pixel width from 24 km to about 40 km, while the along-track pixel length was about 15 km (de Graaf et al., 2016). In other words, a single OMI measurement represents an SO₂ VCD value averaged over a 350–500 km² area.

Measurements with snow on the ground were excluded from the analysis as the OMI PCA algorithm presently does not account for the effects of snow albedo. Only clear-sky data, defined as having a cloud radiance fraction (across each pixel) less than 20 %, and only measurements taken at solar zenith angles less than 70° were used. Beginning in 2007, up to half of all rows were affected by field-of-view blockage and stray light (the so-called “row anomaly”) and those affected pixels were also excluded. Additional information on the OMI PCA SO₂ product can be found in other publications (Krotkov et al., 2016; McLinden et al., 2015).

SO₂ VCD data from the Ozone Mapping Profiler Suite (OMPS) Nadir Mapper on board the Suomi National Polar-orbiting Partnership (or Suomi NPP) satellite operated by NASA/NOAA and launched in October 2011 were also used in the study to verify a potential bias in some OMI data (see the Supplement, Sect. S1). OMPS data were processed with the same PCA algorithm as OMI data (Li et al., 2013; Zhang

et al., 2017). OMPS has a lower spatial resolution than OMI, 50 km by 50 km but better signal-to-noise characteristics.

To eliminate cases of transient volcanic SO₂, periods when SO₂ values observed over the eastern US were affected by volcanic emissions; we determined and excluded such cases from the analysis. The range of analyzed SO₂ VCD values was limited to a maximum of 3 DU. Since the average SO₂ value over the largest SO₂ source in the US is about 1 DU and the standard deviation of individual measurements is 0.5 DU, such a limit corresponds to the 4 standard deviations level even over the largest sources. Of the SO₂ values over the eastern US and southern Canada considered here, the years 2008 and 2009 are particularly problematic due to the eruptions of Kasatochi (Aleutian Islands, Alaska, August 2008, 52° N) and Sarychev (Kuril Islands, Eastern Russia, June 2009, 48° N). High volcanic SO₂ values were also observed on several days in 2011. In addition to the filtering based on SO₂ values, five time intervals were explicitly removed from the analysis to avoid misinterpretation of volcanic SO₂ as anthropogenic pollution. The intervals are 7–23 July 2008, 8 August–8 September 2008, 23 March–10 April 2009, 16 June–5 July 2009, and 22 May–9 June 2011. To remove volcanic SO₂ in the case of Europe, the analyzed data were divided into 5° by 5° cells, and for each cell the days with the 90th percentile above a 5 DU limit were excluded from the analysis. Only about 1.5 % of all data were removed by this screening.

2.2 Wind data

As in several previous studies (Fioletov et al., 2015; McLinden et al., 2016), wind-speed and direction data for each satellite pixel were required for the analysis methods applied. European Centre for Medium-Range Weather Forecasts (ECMWF) reanalysis data (Dee et al., 2011; <http://apps.ecmwf.int/datasets/>) were merged with OMI measurements. Wind profiles are available every 6 h on a 0.75° horizontal grid and are interpolated in time and space to the location of each OMI pixel centre. *U* and *V* (west–east and south–north, respectively) wind-speed components were first averaged in the vertical between 0 and 1 km where the majority of the SO₂ mass resides. The wind components were then interpolated spatially and temporally to the location and overpass time of each OMI pixel.

Note that to reconstruct annual mean VCD maps based on annual emissions (Sect. 3.4), it is not necessary to have the actual year-specific meteorological information, as annual mean wind characteristics do not vary much from year to year (see Sect. S6), and so for convenience we simply used wind data from 2005 for all years prior to 2005.

2.3 SO₂ emission inventories

Monthly or annual emissions from individual US point sources available from the US Environmental Protection Agency (EPA) National Emissions Inventory (<https://www.epa.gov/air-emissions-inventories>) for the period 1980–2015 were examined in this study. US EPA national emission inventories are available from 1980, although at that time they contained just annual values and were updated only every 5 years. Regular annual emission data for consecutive years first became available in 1995 and US emission data with higher temporal resolution (monthly, daily, and hourly) are only available after 2004. Note that the inventory data for these sources after the early 1990s were based on direct stack measurements by Continuous Emissions Monitoring Systems as mandated by Title IV of the 1990 US Clean Air Act Amendments (Public Law 101-549; e.g., <https://www.epa.gov/clean-air-act-overview>). The Canadian SO₂ annual point-source emission data were obtained from the National Pollutant Release Inventory (NPRI), <http://open.canada.ca/data/en/dataset/>). Canadian annual point-source emission data sets are available back to 2002 and we used the 2002 emission data for the 1980–2001 period. For Canadian sites, only annual emissions are available and seasonal values were calculated by dividing annual emissions by 4. This study is based on point-source emissions only, but point sources have contributed a large majority (> 90 % in the early 2000s and > 70 % in the recent years) of North American SO₂ emissions.

Information about point-source emissions from the European Union (EU) countries from the European Pollutant Release and Transfer Register (E-PRTR) for 2004–2014 is available from <http://www.eea.europa.eu/data-and-maps/data/lcp-1> and was used for the analysis for Europe. For non-EU European countries, spatially distributed 2005–2014 TNO-MACC-III emission data for air pollutants from the MACC project were used (Kuenen et al., 2014; Monitoring Atmospheric Composition and Climate; see <http://www.gmes-atmosphere.eu/>) prepared by TNO. When E-PRTR data are not available, proxy data are used by TNO, such as for power plants from the World Electric Power Plants Database (WEPP; see <http://www.platts.com/products/world-electric-power-plants-database>). WEPP provides no emission data, only listing unit characteristics, so emissions are allocated to individual plant units based on the reported thermal capacity, configuration and generic interpretations of reported fuel type(s), and installed emission control technologies. Site-specific parameters not provided by WEPP, such as exact fuel sulfur content, achieved pollutant removal efficiencies, and load fluctuations, are not taken into account when emissions are allocated. Therefore, the MACC-III point-source emission data should be regarded as estimates that may differ considerably from the actual emissions.

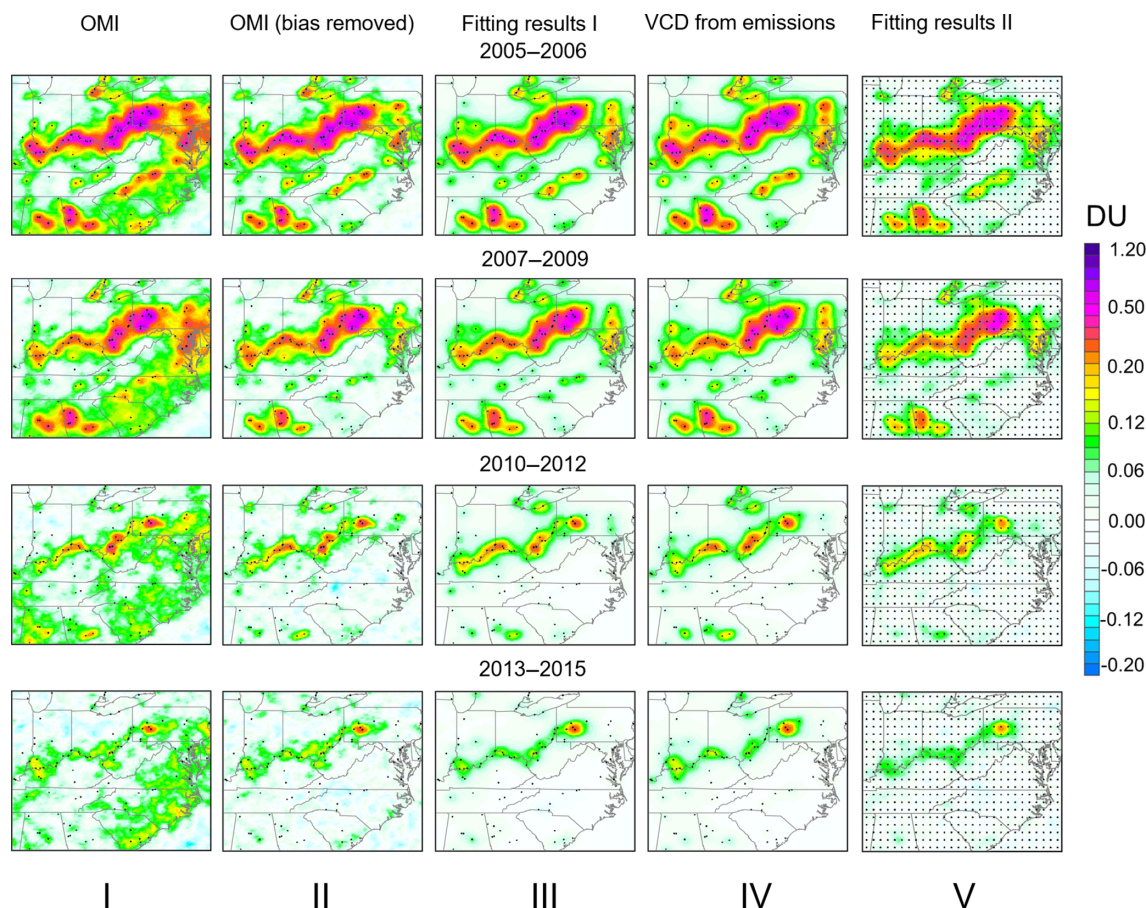


Figure 1. Annual mean OMI SO₂ VCDs from PCA algorithm (column I), mean OMI SO₂ VCDs with a large-scale bias removed (column II), results of the fitting of OMI data by the set of functions that represent VCDs near emission sources using estimated emissions (see text) (column III), and SO₂ VCDs calculated using the same set of functions but using reported emission values (column IV). Point sources that emitted 20 kt yr⁻¹ at least once in the period 2005–2015 were included in the fit (they are shown as the black dots). Results of the fitting of OMI data by the set of functions that represent “sources” as 0.5° by 0.5° grid cells (shown as the black dots) using estimated emissions (see text) are shown in column V. The maps are smoothed by the pixel averaging technique with a 30 km radius (Fioletov et al., 2011). Averages for four multi-year periods – 2005–2006, 2007–2009, 2010–2012, and 2013–2015 – over the area 32.5 to 43° N and 75 to 89° W are shown.

2.4 SO₂ surface concentration data

In situ SO₂ ground-level measurements from the US Clean Air Status and Trend Network (CASTNet; Baumgardner et al., 1999; Park et al., 2004; Schwede et al., 2011), operated by the US EPA (<http://www.epa.gov/castnet>), and the Canadian Air and Precipitation Monitoring Network (CAPMoN: <http://www.ec.gc.ca/rs-mn/default.asp?lang=En&n=752CE271-1>; Schwede et al., 2011), operated by Environment and Climate Change Canada (ECCC), were used in this study. Both networks were established to assess regional trends in pollutant concentrations, atmospheric deposition, and ecological effects due to changes in air pollutant emissions. CASTNet started operations in 1987 and CAPMoN started in the late 1970s. Both networks employ filter packs to measure SO₂, although CASTNet uses a 1-week sampling period vs. a 1-day sampling period for CAP-

MoN. It is important to note that the monitoring sites belonging to these networks are located in relatively remote areas, so that direct impacts of local pollution sources on the measurements are minimal. Annual mean SO₂ values in µg m⁻³ were used in this study.

3 Linking satellite SO₂ VCDs and SO₂ emissions

The method for linking OMI SO₂ VCDs to SO₂ emissions is based on a fit of OMI VCDs to an empirical plume model developed to describe the SO₂ spatial distribution (as seen by OMI) near emission point sources (Fioletov et al., 2015), but unlike the previous studies it is not limited to a single point source. The plume model assumes that the SO₂ concentrations emitted from a point source decline exponentially with time and that they are affected by turbulent diffusion that can be described by a 2-D Gaussian function. The overall

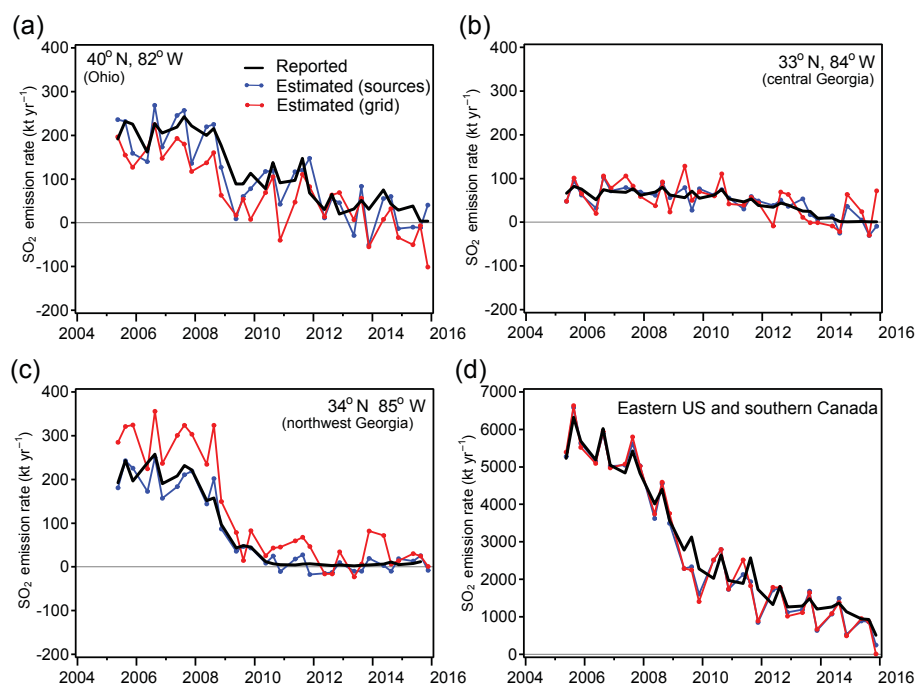


Figure 2. (a–c) Examples of reported and estimated seasonal emissions (in kt yr^{-1}) for three 1° by 1° grid cells as labelled on the plots. (d) Reported and estimated seasonal point-source emission rates for the entire eastern US and southeastern Canada (the region shown in Fig. 1) for spring, summer, and autumn. Estimated emissions are shown for the statistical model based on the actual source location (blue lines) and on a 0.5° by 0.5° regular grid (red lines). Note that the seasonal emission values are scaled to give annual emission rates. Winter data are not shown due to high uncertainties of OMI measurements.

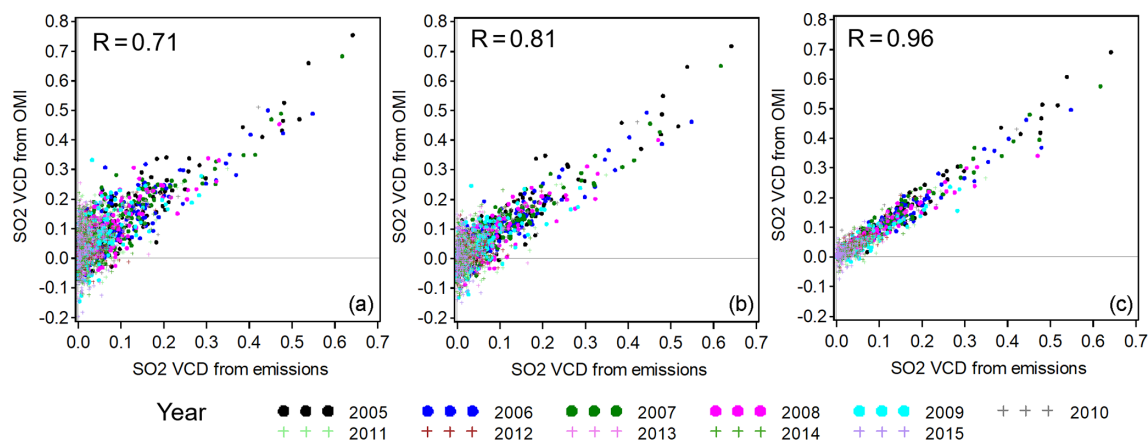


Figure 3. The scatter plots between the reconstructed from emission-based VCDs and the three OMI-based data sets shown in Fig. 1: (a) mean OMI SO₂ VCDs, (b) mean OMI SO₂ VCDs with a large-scale bias removed, and (c) results of the fitting of OMI data by the set of functions that represent VCDs near emission sources using estimated emissions (the first term of Eq. A2). Each symbol on the plot represents the annual mean SO₂ VCD value averaged over one 1° by 1° grid cell and all cells within the domain area shown in Fig. 1 are included in the plot. Different colours represent different years. The correlation coefficients between the two data sets on each plot are also shown.

behaviour can be described as a combination of exponential and Gaussian random variables, also known as an exponentially modified Gaussian function (see the Appendix for details). Each satellite measurement (or pixel) is fit by a sum of plumes from all point sources. The distribution of SO₂ emanating from each source is described by the plume model

based on a known plume function $\Omega(\theta, \varphi, \omega, s, \theta_i, \varphi_i)$ dependent on the satellite pixel coordinates (θ, φ) , pixel wind direction and speed (ω, s) , and source coordinates (θ_i, φ_i) scaled by an unknown parameter (α_i) representing the total SO₂ mass from the source i . These unknown parameters are then estimated from the best fit of the OMI measurements.

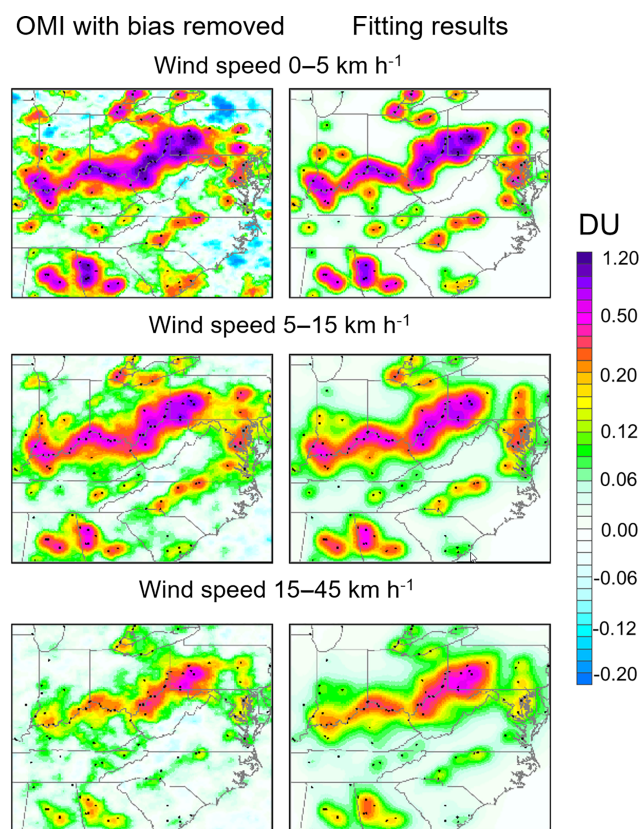


Figure 4. Left: mean OMI SO₂ VCDs grouped by wind speed with a large-scale bias removed. Right: results of the fitting of OMI data by the set of functions that represent VCDs near emission sources using estimated emissions. While the fitting was done using all data, the results of the fitting are grouped by wind speed. Averages for 2005–2007 binned by the wind speed (0–5, 5–15, and 15–45 km h^{−1}) are shown. Sources that emitted 20 kt yr^{−1} at least once in 2005–2015 were included in the fit (they are shown as black dots).

The emission rate for source i is $E = \alpha_i / \tau$, where τ is a prescribed SO₂ decay time. In other words, the method finds the emission rates that produce the best agreement with the observed OMI SO₂ VCD values. The detailed formulas and prescribed seasonal decay times are given in the Appendix.

Thus, the fitting procedure allows for the isolation of the emission-related “signal” in the data from known sources and can be used to check existing point-source emission inventories. If all sources are included in the fit, it can be expected that the difference between the OMI data and the fit is within the noise level and the estimated emission rates E should agree with the reported emissions. We used OMI observations and emission data for the eastern US and southeastern Canada to confirm this expectation. Sources that are not included in the fit would appear as “hotspots” on the maps of the difference between OMI VCDs that could be used for source detection. Furthermore, emissions from such sources could then be derived by adding their coordinates to the

source list in the fitting procedure. The suggested method can thus be used as a source of independent emission estimates in regions where emission values have large uncertainties.

The method requires information about the point-source locations. We used source location data available from the US and Canadian emission inventories mentioned in Sect. 2.3. As discussed by Fioletov et al. (2015), sources that emit 30 kt yr^{−1} or more can be detected by OMI. Since multiple smaller sources located in a close proximity can also be seen as a hotspot in OMI data, we lowered the minimum limit and included all SO₂ point sources that reported emissions of 20 kt yr^{−1} or more at least once in the period 2005–2015. It should be noted that while the method does not improve the level of source detectability, it gives more accurate emission estimates for clusters of small sources where the point-source algorithm is not really applicable.

Earlier versions of the OMI SO₂ data product have some large-scale biases (Fioletov et al., 2011) that were largely removed in the present PCA version. However, we found that even the PCA version has some local biases that may interfere with the regression fit. The local bias can be accounted for by introducing functions that change slowly (compared to signal from emission sources) with latitude and longitude. We used Legendre polynomials of latitude and longitude and their products that are orthogonal over the analyzed domain, as discussed in the Appendix.

The OMI data with and without the bias and the fitting results for four multi-year intervals are shown in the columns I and II of Fig. 1. The additional plots of the bias itself and the residuals are available from the Supplement, Figs. S1–S4. Figure 1 is based on the annual estimates averaged over 2- and 3-year periods. Figure 1 confirms that there was a large decline in SO₂ VCD over the eastern US and southeastern Canada in the period 2005–2015 (Krotkov et al., 2016). In contrast, the bias estimated from the fitting procedure appears to be fairly constant over time (Fig. S1), which suggests that it may be an artifact from the retrieval. The lack of this feature in OMPS observations further suggests it is a bias in OMI PCA data as discussed in the Supplement (Sect. S1 and Fig. S2).

It should be mentioned that the use of an empirical plume model is appropriate when atmospheric advection/diffusion can be considered to be the dominant process and meteorological conditions can be assumed to be quasi-steady. This is a reasonable assumption for short time periods and transport distances and when chemical transformation and surface removal of SO₂ can be well represented as simple first-order loss. The consistent mid-day overpass time for OMI means that the vast majority of the satellite measurements will be associated with a well-developed quasi-steady planetary boundary layer. A 3-D atmospheric chemistry model, in contrast, would be more appropriate for longer time periods and transport distances and for emissions occurring at all times of day, but that is not the case for this analysis.

4 Analysis

4.1 SO₂ emission estimates from OMI data

The functions $\Omega(\theta, \varphi, \omega, s, \theta_i, \varphi_i)$ decline very rapidly with distance from the source located at θ_i, φ_i . For an isolated point source (θ_i, φ_i) where other sources are located 100 km away or more, $\Omega(\theta, \varphi, \omega, s, \theta_i, \varphi_i)$ is not correlated with any other $\Omega(\theta, \varphi, \omega, s, \theta_j, \varphi_j)$, where $i \neq j$, and the regression model (1) or (2) can be simply split into two parts: a model for point-source emission estimates for source i and a model for all other point sources. Then the estimate of α_i is independent from estimates for all other sources. If, however, there is another source j located at (θ_j, φ_j) that is closer to source i than ~ 100 km, then the functions $\Omega(\theta, \varphi, \omega, s, \theta_i, \varphi_i)$ and $\Omega(\theta, \varphi, \omega, s, \theta_j, \varphi_j)$ become correlated, as do their estimates of α_i and α_j . As the two Ω functions depend on the wind, the correlation coefficients also depend on the wind distribution and the locations of the sources relative to the prevailing wind direction and to each other, but the separation distance is the dominant factor. Typical absolute values for the correlation coefficients are about 0.2, 0.6, and 0.8 for distances between sources of 100, 50, and 25 km, respectively. A high correlation means that, in practice, emission estimates for sources located in close proximity have large uncertainties as we may have difficulty separating signals from the individual sources. However, if sources i and j are located in close proximity to each other but far from all other sources, then their combined emissions can still be estimated accurately. Thus, such sources can be grouped into clusters, where the member sources are located in close proximity (20–40 km) but the clusters themselves are well separated and total emissions from each cluster can be estimated from satellite data.

Another way of grouping sources into clusters is to establish a grid over the analysis region and then sum up estimated emissions (E_i) from all sources within each grid cell. Of course, this does not prevent situations in which two sources are in close proximity but are located in adjacent grid cells. Such cases would lead to larger uncertainties in the cell values, but they are uncommon. Figure 2a–c show examples of such estimated total emissions for three 1° by 1° cells. Seasonal emission estimates scaled to annual values were used for this plot and winter data are not shown in this plot due to much higher uncertainties of OMI data. The estimated emissions agree reasonably well with the emissions calculated by summing up reported SO₂ emissions from the point sources in each cell. The standard deviation of the difference between the emission estimates for all 1° by 1° cells within the domain area shown in Fig. 1 and reported SO₂ emissions for the same cells are 112, 39, 28, and 41 kt yr^{−1} for winter, spring, summer, and autumn, respectively. The standard deviations of the difference are 25 and 37 kt yr^{−1} for annual emissions without and with winter data (not shown), respectively. Finally, total point-source emissions for the entire region can be estimated by summing over all individual point sources.

Such a plot is shown in Fig. 2d. The estimated SO₂ emissions in Fig. 2d follow the trend in the reported emissions well, and the correlation coefficient between the two data sets is 0.98. The agreement is particularly good in summer. Large discrepancies are observed only in autumn months after 2007, when relatively high measurement noise combined with the reduction of data due to the row anomaly. In addition, the 2008 and 2009 satellite data were affected by SO₂ emitted from volcanic eruptions (McLinden et al., 2015). More information on the autumn data is available from Sects. S2 and S3.

This grid-based approach can be potentially used for area sources or when the locations of sources are not well known. For illustration, we used VCD measurements over the same area but assumed that it is an area source with no individual point sources. If we set a regular grid and assume that each grid point is a “source”, we can estimate emissions from such “sources” as described above. VCD can then be calculated using these estimated emissions. Such reconstruction for a 0.5° by 0.5° grid is also shown in Fig. 1 (column V) and demonstrates a good agreement with the measured VCD values. Note that the grid spacing should not be too large or else the areal emissions will be underestimated. Likewise, if it is too fine adjacent grid cells will be highly correlated and may result in artificial structure. As Fig. 1 (column IV) shows, the fitting results based on emissions are very close to the OMI fitted data (column II). We used the OMI data with local bias removed because, with this approach, any instrumental local bias will be interpreted as an area source, resulting in overestimation of emissions.

Emissions estimated by this gridded method are also shown in Fig. 2. Their uncertainties are higher than for the case of known source locations but are still reasonable. The standard deviation of the difference between the emission estimates for all 1° by 1° cells within the domain area shown in Fig. 1 and reported SO₂ emissions for the same cells are 54, 37, and 56 kt yr^{−1} for spring, summer, and autumn, respectively. High measurement errors and data gaps prevent estimation of the emissions for winter.

The uncertainties of satellite-based emission estimates have been discussed in our previous studies (Fioletov et al., 2015, 2016). They can be as high as 50 %, but the two largest contributors to this uncertainty, the air mass factor (AMF; determined by the assumed vertical profile, surface reflectivity, and viewing geometry) and the prescribed lifetime, are related to site-specific conditions and can be considered primarily as systematic. They introduce a scaling factor in estimated emissions that affects absolute values but not relative year-to-year changes in emissions. Moreover, the constant, effective AMF embedded in the OMI SO₂ product is based on measurements taken in the eastern US, and the lifetime estimates used here are based on data from the US power plants as well, so these errors are minimal for this region. To further support this claim, AMF values were recalculated for all SO₂ observations used in Fioletov et al. (2016) and its impact on these sources was found to minimal, typically less than 5 %.

4.2 SO₂ VCDs estimated from reported emissions

The equation that links emissions and VCDs (A1) can also be used for forward calculations: if coefficients α_i are known, then SO₂ VCDs can be calculated for any location for given wind conditions and these daily VCDs can be averaged to give annual or seasonal means for the analyzed area. Since $\alpha_i = E_i \cdot \tau$, and τ is prescribed in our calculations, the available emission inventories that contain E_i can be used to calculate α_i . In this case, there is no need to do any fitting or to use any OMI measurements to calculate VCDs. In practice, we can simply use the reported emission data and available OMI pixel locations merged with the wind information and calculate VCDs for each OMI pixel based on its centre coordinates. OMI provides daily near-global coverage, and of course no pixel screening is required for such forward calculations, so it would be essentially a reconstruction of daily VCD maps with spatial resolution of about 15 by 35 km (approximately the average size of the OMI pixel used in this study) assuming a constant emission rate.

Figure 1 (column IV) also shows the result of such annual reconstructions averaged over 2- to 3-year periods. Annual point-source emissions from the EPA and NPRI inventories were used as inputs. The agreement of the reconstructed VCDs with OMI data (with the bias removed) is very good, and the agreement with the OMI data fitting results is truly remarkable. To characterize the overall agreement with the OMI data, fitting results, and reconstructed emission-based VCDs, a 1° by 1° grid was established and various statistical characteristics were calculated for the gridded data. The standard deviation of the residuals ε for this grid is 0.025 DU, i.e., about 20 times less than the uncertainty of individual OMI measurements. The standard deviation of the difference between the OMI-fitted and the reconstructed emission-based VCDs is 0.016 DU.

Figure 3 shows the scatter plots between the annual VCDs reconstructed from emissions and the three OMI-based data sets shown in Fig. 1 for all years. The correlation between the VCDs reconstructed from emissions with the actual OMI data is 0.75, but it rises to 0.91 after the local bias is removed and to 0.97 after the emission-related signal is extracted from the OMI data by the fitting procedure (the first term of Eq. A4). Moreover, values of the latter correlation coefficient are above 0.88 for all seasonal averages (excluding winter) and they are substantially higher than the correlation coefficients with the actual seasonal OMI data. This result could be used to extract an emission-related SO₂ signal from the OMI data when the signal is weak compared to the noise level but the source locations are known. Additional information is available from Sect. S2, including a figure of the difference between the fitted VCDs and the reconstructed VCDs as well as seasonal and annual statistics.

Figure 1 shows the fitting results in geographical coordinates; i.e., the first term of Eq. (A4) from the Appendix was calculated for each OMI pixel without any stratification by

the wind speed and direction. However, the fitting itself is done in a four-dimensional space where the wind speed and direction are the other two coordinates. To illustrate the fitting results for different wind speeds, Fig. 4 shows the original mean OMI SO₂ values (with the bias removed) and the fitting results when the data are binned by the wind speed. Note that the fitting parameter estimate was done using data for all wind speeds and the binning applies only to the fitting outputs. In other words, the first term of Eq. (A4) from the Appendix was calculated using only OMI pixels where the wind speed was within the selected range. The calculations were done for three wind-speed bins for the 2005–2007 period when the SO₂ emissions were the highest and the measurements were not affected by the “row anomaly”. The wind-speed modal value is about 10 km h^{−1}, and the first bin represent calm conditions, the second bin contains measurements taken within ± 5 km h^{−1} from the modal value, and the last bin corresponds to relatively high wind speeds. As Fig. 4 demonstrates the fitting results are able to capture the changes in SO₂ distribution at different wind-speed bins. When the wind speed is low, SO₂ values are high over the sources, while the plume spreads out over a larger area when the wind speed is high. The figure also shows that SO₂ VCD values measured over the sources, or integrated over a small area around the source, are not good proxies for the emissions because they depend on the wind speed.

4.3 Applications for other regions

Direct SO₂ emission measurements are not available for many regions of the globe. The described method can be used to verify or even estimate SO₂ emissions for other regions. To test this method further, we applied it to the European region using E-PRTR and TNO-MACC emission inventory data (see Sect. 2.3). Figure 5 is similar to Fig. 1, but for a part of Europe where the majority of the SO₂ sources are located. Sources that emitted more than 10 kt in any year between 2005 and 2014 are shown on the map as black dots. The limit was lowered to 10 kt yr^{−1} from the 20 kt yr^{−1} value used for North America since clusters of small sources are common in Europe. When the coordinates of the sources were included in the fitting procedure there appeared to be some large-scale local biases particularly over Spain and the Balkan region.

Figure 5 also shows a good general agreement between the OMI data and VCDs estimated from emissions. Both show a substantial SO₂ VCD decline over most regions, with SO₂ values the highest at the beginning of the analyzed period (Spain, Romania, Bulgaria, Greece). No major changes are observed by OMI for power plants in Serbia and in Bosnia and Herzegovina, and they are now producing the highest SO₂ VCD values over the domain shown. As their emissions are not in the E-PRTR database, TNO-MACC emission inventory data were used instead.

The method produces estimates for individual sources that can be further grouped in different ways. Estimated and

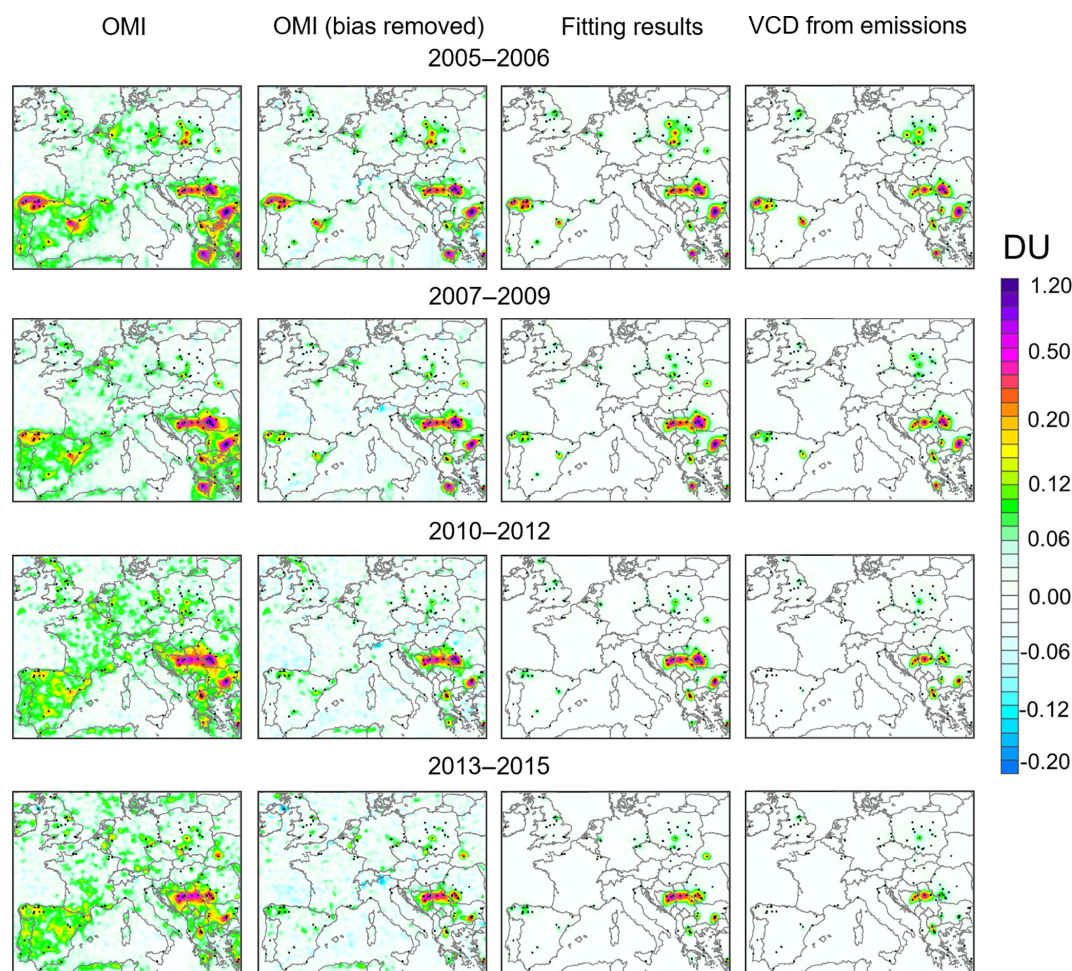


Figure 5. The same as Fig. 1, columns I–IV, but for the part of Europe where the majority of SO₂ point sources are located. Point sources that emitted 10 kt yr⁻¹ at least once in the period 2005–2014 were included in the fit (they are shown as the black dots). High SO₂ values related to the Mt. Etna volcano in Sicily are excluded from the OMI plots. The area 35.6 to 56.6° N and 10° W to 28.4° E is shown.

reported annual emissions for the period 2005–2014 were grouped by nation for nine countries with large SO₂ emissions, as shown in Fig. 6. There is good agreement qualitatively between the reported and estimated emissions. Some differences in absolute values are expected due to possible multiplicative biases in OMI-based estimates (from the air mass factor and potential errors in τ). In some cases, however, a possible deficiency in the reported emissions cannot be ruled out. For example, OMI-based values for Romania show nearly constant emissions up to 2012 and then a 50 % drop, whereas the reported emissions suggest a steady decline between 2005 and 2013. The uncertainty level of the OMI-based emissions is illustrated in Fig. 6 by the panel for Hungary: the total emissions from three sources there are below the sensitivity of OMI-based estimates. Figure 6 also shows OMI-based and inventory emissions for Serbia and for Bosnia and Herzegovina. Their inventory emission data are available as estimates based on reported thermal capacity, configuration, and generic interpretations of reported fuel

type and may not be accurate. OMI-based estimates provide an independent source for their verification. For example, the inventory estimates for the copper smelter at Bor, Serbia, are about 4.5 kt yr⁻¹, i.e., well below the OMI sensitivity level. However, OMI sees this source clearly and the OMI-based mean emission estimate for 2005–2016 is about 70 kt yr⁻¹, a value in line with high SO₂ levels observed there (Serbula et al., 2014). See also Fig. S7.

Another clear benefit of the satellite-based method of emission estimates is that such estimates are available with almost no delay. At the time of this study (February 2017), we were able to estimate OMI-based emission for the period including 2016, while the E-PRTR inventory only reached until 2014.

4.4 Reconstruction of the past VCD distribution

If detailed emission data are available, it is also possible to calculate emission-based VCD maps using Eq. (A3) for years

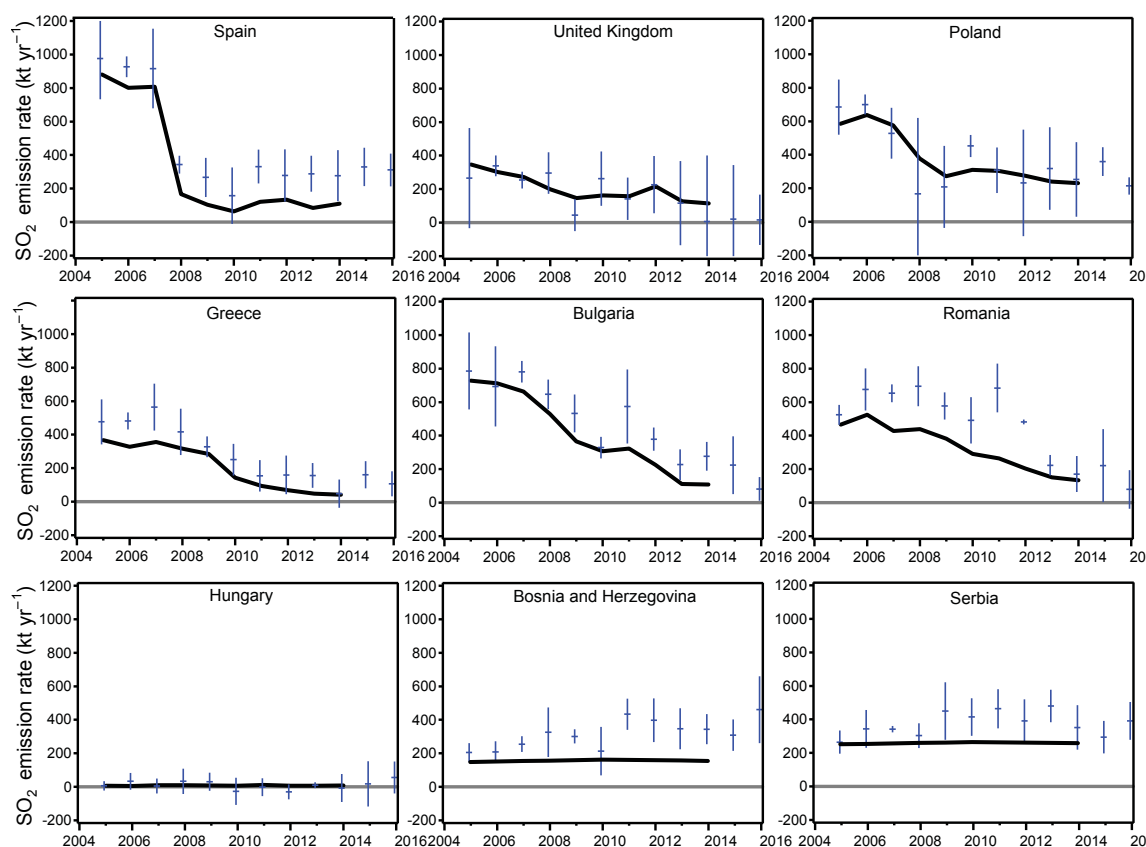


Figure 6. OMI-based (blue bars) and reported/estimated (black lines) emissions for different European countries. E-PRTR reported emissions were used for all countries except Serbia and Bosnia and Herzegovina, where TNO-MACC estimates (Kuenen et al., 2014) were used (see Supplement). The error bars represent 2 standard errors of the annual mean calculated by averaging three seasonal (spring, summer, autumn) OMI-based emission estimates.

before the launch of OMI. Figure 7 shows the annual mean VCD maps over the eastern US and southeastern Canada reconstructed from the emission inventories available since 1980. All point sources (shown by black dots) that emitted more than 1 kt of SO₂ in at least 1 year during the 1980–2015 period were included in the calculations for a total about 380 sources. Note that we slightly expanded the domain area in all directions to include sources that emitted large SO₂ amounts prior to the OMI launch. There are two major periods of dramatic changes in SO₂ VCD values: first, in the early 1990s, corresponding to the implementation of the US Acid Rain Program (ARP), established under Title IV of the 1990 Clean Air Act (CAA) Amendments (IJC, 2014). Then beginning in 2009–2010 there are further large reductions attributable to the installation of additional flue-gas desulfurization units (or “scrubbers”) at many US power plants to meet stricter emission limits introduced by the Clean Air Interstate Rule. The overall decline of total SO₂ point-source emissions from the domain area shown in Fig. 5 between 1980 and 2015 is 86 %.

4.5 SO₂ surface concentrations and VCDs

Multi-year mean surface SO₂ concentrations at stations belonging to the CASTNet and CAPMoN networks (see Sect. 2.4) were compared to the estimated VCD values. Maps of multi-year mean surface SO₂ concentrations at stations belonging to the CASTNet and CAPMoN networks are shown in Fig. 8. The colour scheme of Fig. 8 was chosen to be comparable to that used in Fig. 1. The main features of the VCD and surface concentration distributions are very similar. Both sets of maps portray a strong decline from the 1980s to 2010s with the highest values observed along the Ohio River, where many coal-fired power plants are located. However, the spatial gradients in the VCD distribution appear to be sharper than in the surface concentration distribution and elevated surface concentrations are spread out over larger areas. For example, SO₂ VCDs over Virginia were much lower compared to West Virginia, while SO₂ surface concentrations were similar.

There are 50 network sites within the domain area shown in Fig. 7 that have 15 or more years of observations in the period 1980–2015. A scatter plot of annual mean SO₂ surface

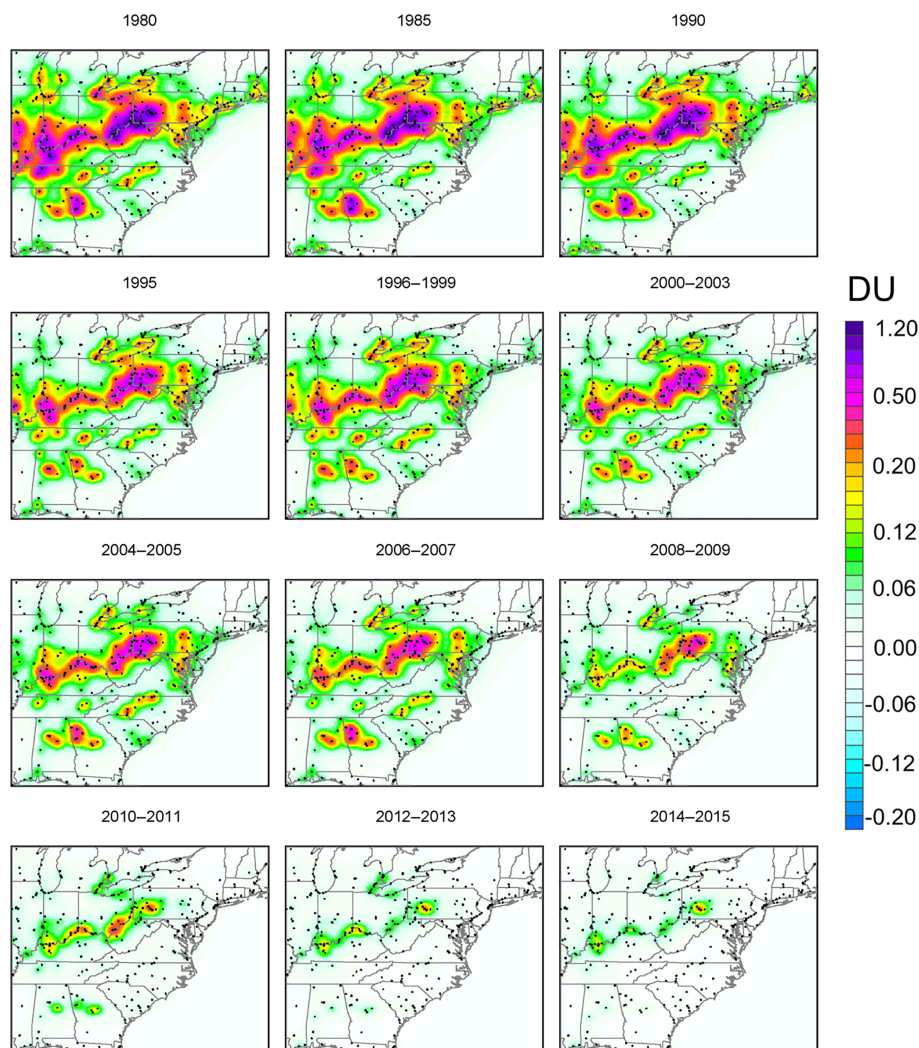


Figure 7. Annual mean SO₂ VCD calculated using the plume model applied to the reported emission data. Annual emission data from ~ 380 SO₂ sources (black dots) that emitted 1 kt yr^{-1} at least once in 2005–2015 were included in the calculations. The area 30 to 48° N and 70 to 90° W is shown.

concentration at all of these sites versus emission-based SO₂ VCD values is shown in Fig. 9a for all available years. While there is a clear correlation between the two quantities that reflects similar spatial distributions and temporal trends, the correlation coefficient is not very high (0.83). However, correlation coefficients calculated separately for individual measurement sites are higher, ranging between 0.87 and 0.99. This is illustrated in Fig. 9b, where a subset of the scatter plot from Fig. 9a for eight sites is shown using different colours for each site.

Figure 9b also shows that the slopes of the regression lines vary from site to site. If we calculate the slope of the individual regression line for each site (it is essentially the surface-concentration-to-VCD ratio) and then multiply the emission-based VCDs by that ratio, then we obtain a very good correlation as illustrated by Fig. 9c ($R = 0.986$ for the eight

sites shown in Fig. 9b and $R = 0.983$ for all data points). The regression-line y intercepts have also been analyzed. A positive intercept means that the surface concentration could be non-zero even in the absence of any regional point-source emissions. The estimated intercepts are within $\pm 1.5 \mu\text{g m}^{-3}$ for all sites except one where the intercepts is $3.5 \mu\text{g m}^{-3}$. The exception is the CASTNet Horton Station site, located in Virginia 18 km east of the Glen Lyn power plant, whose emissions were about 10 in 2008 and 6.5 kt yr^{-1} in 2011. However, its emission information was largely missing for the period 2009–2015 and this affected our VCD calculations.

The surface-concentration-to-VCD ratio ultimately depends on the shape of the SO₂ vertical profile. The shape could be affected by boundary layer height, site elevation, and perhaps some local conditions. There are, however, some common features in the ratio distribution. As shown

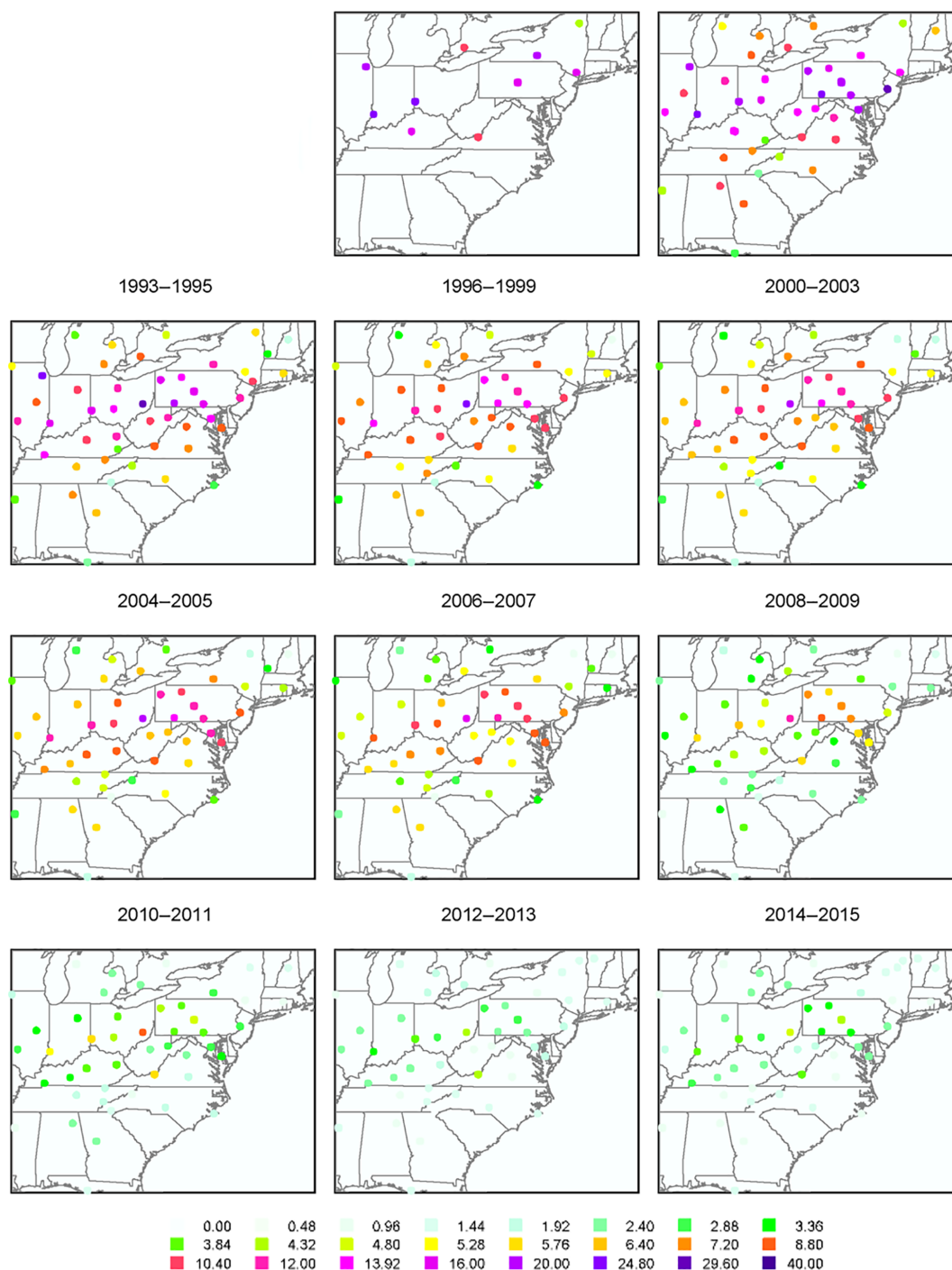


Figure 8. Annual mean surface SO₂ concentrations in $\mu\text{g m}^{-3}$ for different periods calculated using data from the CASTNet and CAPMoN surface monitoring networks. The area 30 to 48° N and 70 to 90° W is shown.

in Fig. 9d, the ratio is low in areas of high emission-based VCDs and low in areas where emission-based VCDs are low. Of course, it is not the mean VCD value itself that affects the ratio but proximity to emission sources. Figure 9d is based on VCDs derived from emissions, but the same analysis for OMI-measured VCD demonstrates similar results (Sect. S5).

It may be possible to reconstruct surface concentration distribution from VCDs and additional information such as the planetary boundary layer height (Knepp et al., 2015), but such estimates are outside of the scope of this study.

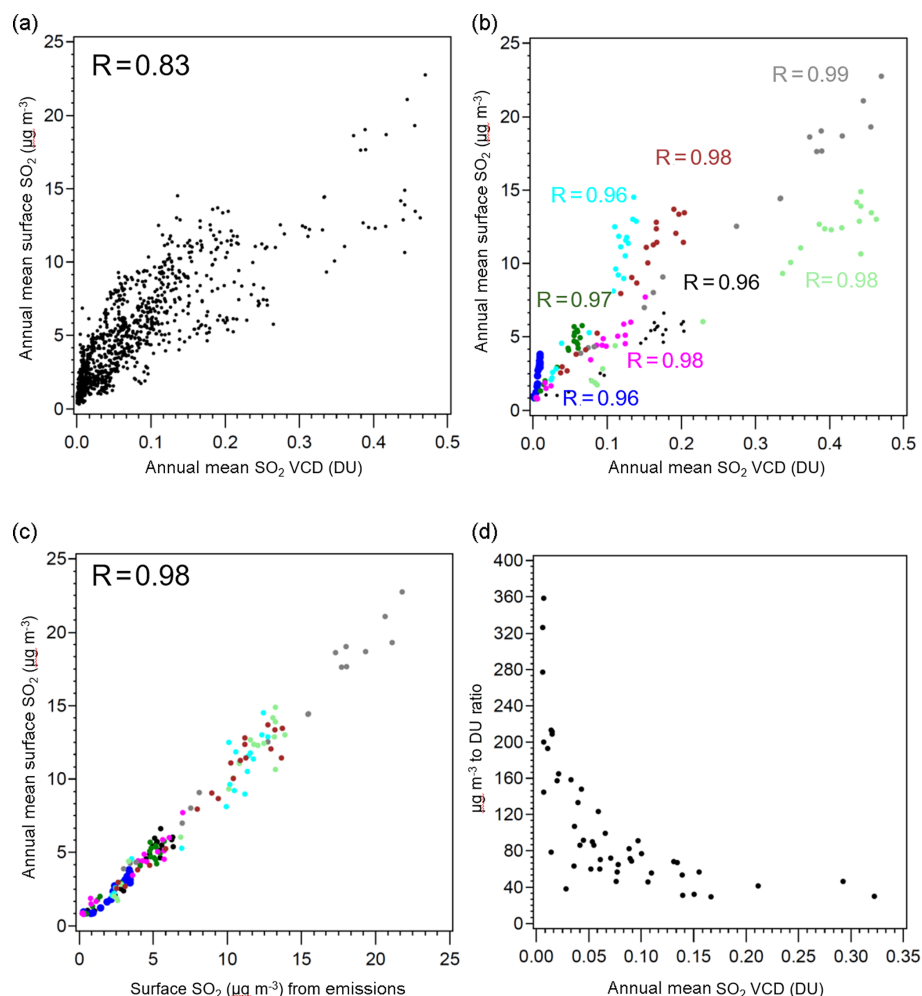


Figure 9. (a) A scatter plot of annual mean surface SO₂ from CASTNet and CAPMoN vs. VCDs calculated from EPA and NPRI point-source emission inventories. The correlation coefficient between the two data sets is 0.83. (b) A subset of the scatter plot from panel (a) for eight sites (shown by different colours). The correlation coefficients for individual sites are between 0.96 and 0.99. (c) The same plot as (b), but for mean SO₂ VCDs multiplied by a site-specific surface-concentration-to-column ratio. The correlation coefficient is 0.98. (d) The site-specific surface-concentration-to-column ratio as a function of the 1980–2015 mean SO₂ VCD. Each dot represents one site. Only the 50 regional surface SO₂ sites with 15 or more years of data between 1980 and 2015 were used in this figure.

5 Summary and discussion

Fitting OMI SO₂ VCD data by a linear combination of functions, where each function represents the plume from an individual source, makes it possible to estimate emission from these sources or groups of sources. If the location of all sources is known, it is expected that the fitting results and the actual OMI data will agree within the noise level as was found to be the case for the eastern US and south-eastern Canada. The same agreement is also observed for this region if the reported emissions are used to calculate VCDs. This suggests a simple way of interpreting satellite SO₂ VCD data: they should agree with VCD estimates based on available emission inventories or the fitting results based on known source locations.

By applying a statistical plume model (developed from satellite SO₂ measurements) to US and Canadian annual SO₂ point-source emission inventories, we were able to reconstruct past annual mean VCDs for the period 1980–2015. High correlation coefficients between the reconstructed VCDs and the OMI-based values (0.91 for OMI data with local bias removed) for the period 2005–2015 gives us confidence in both data sets. It also demonstrates that the reported changes in SO₂ point-source emissions are reflected by OMI measurements for the period 2005–2015. Moreover, the annual surface SO₂ concentrations at the CASTNet and CAPMoN sites also show high correlation coefficients (0.87–0.99) with SO₂ VCDs reconstructed from reported emissions. All of these comparisons suggest a high degree of con-

sistency between the reported SO₂ point-source emissions and measured SO₂ values over the entire 1980–2015 period.

The approach described in this study can be used in several ways. The derived emissions can serve as an independent data source for inventory verification (both point source and gridded) by comparing OMI-estimated SO₂ emissions with the inventories or by comparing VCDs calculated from emission inventories to the OMI VCD measurements. It can also provide emission information for regions where there are no other information sources available. Unreported point and area sources can be detected and emissions from them can be estimated by subtracting VCDs calculated from available emission inventories from satellite VCD measurements, although emission inventories with good spatial resolution would be required for such an analysis. While this study is focused on SO₂, the methods can be applied to other species with relatively short lifetimes measured from space, particularly to NO₂ and NH₃.

We have also applied the method to Europe. The results strikingly illustrate the positive impact of EU legislation; the countries where no decreasing trends are observed are non-EU member states surrounded by EU countries with decreasing emissions. In general, the satellite-based results confirm the trends in reported SO₂ emissions from EU member states over the period 2004–2014, but some discrepancies were found that deserve further attention. In one case, for example, it seems that reported emissions already take into account certain planned or foreseen measures, but real-world (satellite-observation) estimates suggest that implementation of these measures was delayed by several years. Moreover, although the trend is clearly followed, the absolute emission levels suggested by the OMI SO₂ VCD fitting method are sometimes substantially above the reported emission levels for recent years (Fig. 6). Whether these differences are due to underreporting or to methodological issues requires further study.

There are certain limitations to the suggested methods. Satellite SO₂ VCD data may still contain local biases that will interfere with emission estimates or will themselves be interpreted as a source. As the OMI and OMPS data show, these biases could be different from instrument to instrument. Moreover, data from the same OMI instrument could have different biases if processed by different algorithms (Fioletov et al., 2016; their Fig. 3). Although the biases could be partially removed using, for example, a constant (for a small fitting area) or polynomial (for larger areas) fit, further improvement of retrieval algorithms is required to eliminate the bias problem. The biases could be particularly large over regions of high SO₂ VCD values such as the Persian Gulf and China, so the method should be applied there with caution. The method is also based on the assumption that all SO₂ is located near the surface, which determines the wind data used for the fitting. This may not always be the case for very large sources where SO₂ can be lifted into the free troposphere. Finally, the plume model itself may not be optimal in some cases.

Data availability. OMI PCA SO₂ data used in this study have been publicly released as part of the Aura OMI Sulphur Dioxide Data Product (OMSO2) and can be obtained free of charge from the Goddard Earth Sciences (GES) Data and Information Services Center.

Appendix A

This appendix contains a description of the fitting algorithm used to estimate emissions from point and multiple sources. The algorithm for point sources was previously published by Fioletov et al. (2015), but we briefly repeated it for reader's convenience.

A1 Fitting algorithm, point source

The first step of the fitting algorithm involves a rotation of the location of each OMI pixel about the source such that, after rotation, all have a common wind direction. Then, the method assumes that concentrations of SO₂ emitted from a point source decline exponentially (i.e., as $\exp(-\lambda t)$) with time (t) with a constant “lifetime” (or decay rate) $\tau = 1/\lambda$. In the absence of diffusion and with a constant wind direction and speed (s), SO₂ is transported downwind (along the $-y$ axis in the chosen coordinate system) with a concentration that declines exponentially with the distance from the source. Since $t = -y/s$, this decay is simply $\exp(\lambda y/s)$ or $\exp(\lambda_1 y)$ where $\lambda_1 = \lambda/s$. Likewise, if the wind speed is zero, the distribution of SO₂ near the source is governed by diffusion or, more generally, random fluctuations and can be described by a two-dimensional Gaussian function of the distance from the source that depends on one parameter σ . As both exponential decay of the concentration along the y coordinate and diffusion take place, the overall behaviour can be described as a combination of exponential and Gaussian random variables, also known as an exponentially modified Gaussian function. Therefore, the statistical model of the SO₂ plume employed near the point source has the form of a Gaussian function $f(x, y)$ multiplied by an exponentially modified Gaussian function $g(y, s)$: $\Omega(x, y, s) = f(x, y) \cdot g(y, s)$, where x and y (in kilometres) are the coordinates of the OMI pixel centre across and along the wind direction, respectively, and s (in km h⁻¹) is the wind speed at the pixel centre. The model depends on two parameters, the decay time (τ), and the plume width (σ). It should be multiplied by a scaling factor α that is proportional to the emission strength.

Thus, $\text{OMI}_{\text{SO}_2} = \alpha \cdot \Omega(x, y, s) = \alpha \cdot f(x, y) \cdot g(y, s)$, where

$$\begin{aligned} f(x, y) &= \frac{1}{\sigma_1 \sqrt{2\pi}} \exp\left(-\frac{x^2}{2\sigma_1^2}\right), \\ g(y, s) &= \frac{\lambda_1}{2} \exp\left(\frac{\lambda_1(\lambda_1 \sigma^2 + 2y)}{2}\right) \cdot \text{erfc}\left(\frac{\lambda_1 \sigma^2 + y}{\sqrt{2}\sigma}\right), \\ \sigma_1 &= \begin{cases} \sqrt{\sigma^2 - 1.5y}, & y < 0 \\ \sigma, & y \geq 0 \end{cases} \\ \lambda_1 &= \lambda/s, \end{aligned} \quad (\text{A1})$$

and $\text{erfc}(x) = \frac{2}{\sqrt{\pi}} \int_x^\infty e^{-t^2} dt$. The Gaussian function $f(x, y)$ represents the distribution across the wind direction line.

The function $g(y, s)$ is essentially a convolution of Gaussian (determined by the plume width σ) and exponential functions (determined by λ_1 related to the lifetime) and represents an exponential decay along the y axis smoothed by a Gaussian function: when σ is close to 0, then $g(y, s) \approx \lambda_1 \exp(\lambda_1 y)$, where $y \leq 0$. The wind speed s is included in Eq. (A1) only through $\lambda_1 = \lambda/s$. Note that σ_1 was used in $f(x, y)$ instead of σ . The value of σ_1 increased with the distance from the source to reflect an additional spread of the plume downwind (i.e., when $y < 0$).

Parameters σ , λ , and α can be derived from the fit of the OMI observations by the function $\alpha \Omega(x, y, s)$, i.e., from a nonlinear regression model. However, if the values for σ and $\tau = 1/\lambda$ are prescribed, then the remaining value, α , can be determined from a simple linear regression model.

$$\begin{aligned} \text{Since } \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) \cdot g(y, s) dx dy = \\ \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} f(x, y) dx \right) \cdot g(y, s) dy = \int_{-\infty}^{\infty} g(y, s) dy = 1, \end{aligned}$$

the parameter α represents the total observed number of SO₂ molecules (or the SO₂ mass) near the source. If OMI_{SO_2} is in DU, and σ is in kilometres, then α is in 2.6×10^{26} molec or $0.029 T(\text{SO}_2)$. Furthermore, the emission strength (E) can be calculated as $E = \alpha/\tau$, assuming a simple mass balance.

The function Ω depends on pixels coordinates in the Cartesian coordinate system related to the wind direction with the centre at the analyzed source. These coordinates can be derived from pixel latitude (θ) and longitude (φ), the wind direction (ω), and the source latitude (θ_0) and longitude (φ_0), i.e., $\Omega(x, y, s) = \Omega(\theta, \varphi, \omega, s, \theta_0, \varphi_0)$. As OMI measurements were merged with the wind data, OMI SO₂ VCD at each pixel can therefore be interpreted as a four-dimensional function $\text{OMI}_{\text{SO}_2}(\theta, \varphi, \omega, s)$. The dependence of Ω on the model parameters τ and σ is rather complex and we can simplify this approach by assuming that τ and σ are identical for all sources in the analyzed region and only the parameter α differs from source to source (see sensitivity analysis in reference Fioletov et al., 2016). Values of τ and σ were selected based on previous estimates for point sources in the eastern US (Fioletov et al., 2015) with some seasonal adjustments: τ values were = 5.6, 6.3, 7.7, and 6.3 h for winter, spring, summer, and autumn, respectively. The plume width $\sigma = 18$ km is dependent on multiple factors, but mostly on the OMI pixel size.

A2 Fitting algorithm, multiple sources

In case of multiple sources with prescribed τ and σ , OMI SO₂ VCD can be expressed as a sum of contributions $\alpha_i \cdot \Omega_i$ from all individual sources (i). If (x_i, y_i) and (x'_i, y'_i) are the pixel's Cartesian coordinates (kilometres) in the system with

Table A1. Legendre polynomials.

n	$P_n(x)$
0	1
1	x
2	$(3x^2 - 1)/2$
3	$(5x^3 - 3x)/2$
4	$(35x^4 - 30x^2 + 3)/8$
5	$(63x^5 - 70x^3 + 15x)/8$
6	$(231x^6 - 315x^4 + 105x^2 - 5)/16$

the origin at the source i before and after the wind rotation respectively, then they can be calculated from the pixel and source latitudes and longitudes as

$$\begin{aligned}x_i &= r \cdot (\varphi - \varphi_i) \cdot \cos(\theta_i), \\y_i &= r \cdot (\theta - \theta_i), \\x'_i &= x_i \cdot \cos(-\omega) + y_i \cdot \sin(-\omega), \\y'_i &= -x_i \cdot \sin(-\omega) + y_i \cdot \cos(-\omega),\end{aligned}$$

where $r = 111.3 \text{ km} \cdot \pi/180$, φ and θ are the pixel longitude and latitude, ω is the pixel wind direction (0 for north), and φ_i and θ_i are the source i longitude and latitude (all in radian).

Then, similarly to Eq. (A1), the contribution $\alpha_i \cdot \Omega_i$ from the source i can be expressed as $\alpha_i \cdot \Omega_i = \alpha_i \cdot f(x'_i, y'_i) \cdot g(y'_i, s)$, where

$$\begin{aligned}f(x'_i, y'_i) &= \frac{1}{\sigma_1 \sqrt{2\pi}} \exp\left(-\frac{x'^2_i}{2\sigma_1^2}\right), \\g(y'_i, s) &= \frac{\lambda_1}{2} \exp\left(\frac{\lambda_1(\lambda_1 \sigma^2 + 2y'_i)}{2}\right) \\&\quad \cdot \operatorname{erfc}\left(\frac{\lambda_1 \sigma^2 + y'_i}{\sqrt{2\sigma}}\right), \\\sigma_1 &= \begin{cases} \sqrt{\sigma^2 - 1.5y'_i}, & y'_i < 0 \\ \sigma, & y'_i \geq 0 \end{cases} \\\lambda_1 &= \lambda/s.\end{aligned}\quad (\text{A2})$$

Thus, OMI SO₂ VCD can be expressed as a sum of contributions from all individual sources (i) plus noise (ε):

$$\text{OMI}_{\text{SO}_2}(\theta, \varphi, \omega, s) = \sum_i \alpha_i \Omega(\theta, \varphi, \omega, s, \theta_i, \varphi_i) + \varepsilon, \quad (\text{A3})$$

where only parameters α_i are unknown. Equation (A3) represents a linear regression model where the unknown parameters α_i can be estimated from the measured variable (OMI_{SO_2}) at many pixels and known regressors $\Omega(\theta, \varphi, \omega, s, \theta_i, \varphi_i)$. Calculations can be done on an annual or seasonal basis (i.e., using all data for a particular year or for a particular season of a year respectively). Emission estimates for shorter time intervals, e.g., monthly emissions,

may be possible for large sources, but they appear to be too noisy for the eastern US and southeastern Canada for practical applications.

Earlier versions of the OMI SO₂ data product have some large-scale biases (Fioletov et al., 2011) that were largely removed in the present PCA version. However, we found that even the PCA version has some biases that may interfere with the regression fit if Eq. (A3) is used. If the fit is done for a relatively small area, the bias can be accounted for by adding a parameter α_0 to the Eq. (A3) and estimating it from the fit:

$$\begin{aligned}\text{OMI}_{\text{SO}_2}(\theta, \varphi, \omega, s) &= \sum_i \alpha_i \Omega(\theta, \varphi, \omega, s, \theta_i, \varphi_i) \\&\quad + \alpha_0 + \varepsilon.\end{aligned}\quad (\text{A4})$$

For a larger area, for example for the eastern US and southeastern Canada, geographic variations in the bias can be accounted for by introducing functions that change slowly with latitude and longitude. We used Legendre polynomials ($P_n(x)$) that are orthogonal on the interval from -1 to $+1$.

To make the polynomials orthogonal on the analyzed domain, the following transformation was applied:

$$\begin{aligned}L_j(\theta) &= P_j(2 \cdot (\theta - \theta_{\min}) / (\theta_{\max} - \theta_{\min}) - 1), \\L_k(\varphi) &= P_k(2 \cdot (\varphi - \varphi_{\min}) / (\varphi_{\max} - \varphi_{\min}) - 1),\end{aligned}$$

where φ_{\min} , φ_{\max} , θ_{\min} , and θ_{\max} are latitudes and longitudes that define the domain area. Then $L_j(\theta)$ and $L_k(\varphi)$, and their products were added to the fit:

$$\begin{aligned}\text{OMI}_{\text{SO}_2}(\theta, \varphi, \omega, s) &= \sum_i \alpha_i \Omega(\theta, \varphi, \omega, s, \theta_i, \varphi_i) \\&\quad + \sum_{j+k \leq 6} \beta_{j,k} L_j(\theta) L_k(\varphi) + \varepsilon,\end{aligned}\quad (\text{A5})$$

where α_i and $\beta_{j,k}$ are the estimated coefficients. The first sum represents the emission-related fitting and the second sum is the large-scale bias. Equation (A4) also represents a linear regression model and the unknown coefficients can be estimated from the available observations. Polynomials up to the sixth degree were used for each 1-year or one-season fit for the selected domain (the eastern US and southeastern Canada), although a higher (or lower) degree may be more suitable for a larger (smaller) area (see also Sect. S6). Note that the biases are related to retrieval effects such as imperfection of account for the ozone absorption and therefore are not related to SO₂ abundances and not affected by the winds. For this reason, no dependence of the bias on s is considered.

Figure A1 illustrates the method by using SO₂ data from 2005 to 2007 near the Bowen power plant in Georgia, US. There are 13 sources within the $\pm 200 \text{ km}$ square area around the Bowen facility. The fitting was done for every year; estimated values $\alpha_i \cdot \Omega(\theta, \varphi, \omega, s, \theta_i, \varphi_i)$ were calculated for each satellite pixel, then summed up to obtain a SO₂ VCD value for the fit for that pixel. For Fig. A1, the actual OMI data and the fitting results were averaged over the 2005–2007 period

and smoothed by the pixel averaging technique with a 30 km radius. The maps of estimated values for individual sources smoothed in the same way are also shown. The map of the residuals or the difference between the OMI data-based map and the fitting results is also shown.

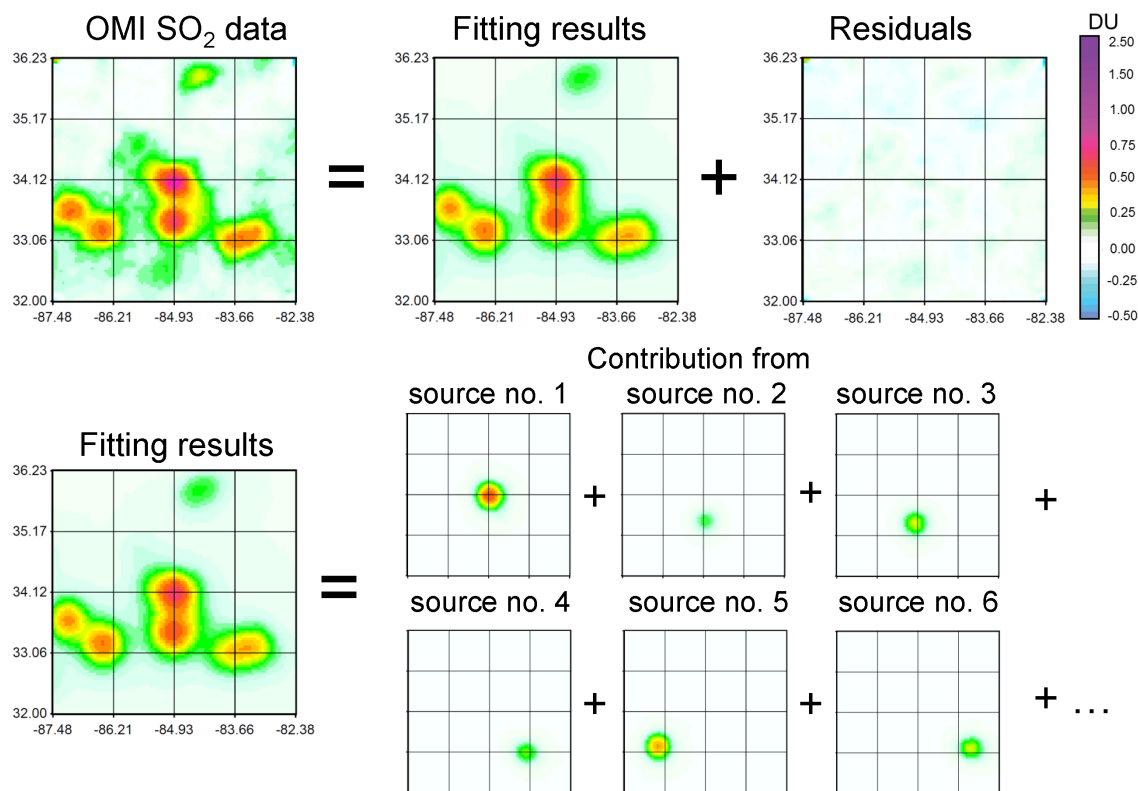


Figure A1. Fitting OMI data near the Bowen power plant in Georgia, US, 2005–2007. All sources with emissions $> 20 \text{ kt yr}^{-1}$ were included in the fit.

The Supplement related to this article is available online at <https://doi.org/10.5194/acp-17-12597-2017-supplement>.

Competing interests. The authors declare that they have no conflict of interest.

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