

Supplement of Atmos. Chem. Phys., 14, 8813–8839, 2014
<http://www.atmos-chem-phys.net/14/8813/2014/>
doi:10.5194/acp-14-8813-2014-supplement
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Sources and geographical origins of fine aerosols in Paris (France)

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Supplementary Material

S1. Complement to Sect. 2.2 “Identification and contribution of the major sources of PM_{2.5}”

To identify the major sources of PM_{2.5} and estimate their contribution to fine aerosol masses, source apportionment (SA) models have been extensively developed in the last three decades (Cooper and Watson, 1980; Gordon, 1980; Hopke, 1981, 1985; Watson et al., 2002). Three main groups of SA methods can be distinguished according to Viana et al. (2008): (1) methods based on the evaluation of monitoring data using basic numerical data treatment (e.g. Lenschow et al., 2001), (2) methods based on emission inventories and/or dispersion models to simulate aerosol emission, formation, transport and deposition (e.g. Visser et al., 2001) and (3) methods based on the statistical evaluation of PM chemical data acquired at receptor sites (so-called receptor models). The latter class of techniques was here chosen because of their advanced mathematical approach, their robustness (e.g. Hopke et al., 2006) and their widespread use in the literature (Belis et al., 2013; Zhang et al., 2011), hence allowing comparisons between methods and results achieved (e.g. Poirot et al., 2001; Zheng et al., 2002).

A receptor model was used to identify the major sources of PM_{2.5} and estimate their contribution to fine aerosol masses. Receptor models assume mass conservation and use a mass balance analysis to identify and apportion sources of airborne PM (Hopke et al., 2006). Equation S1 resumes this principle for a dataset consisting of n samples made of m chemical species emitted by p independent sources:

$$x_{ij} = \sum_{k=1}^p g_{ik} * f_{kj} \quad (S1)$$

where x_{ij} is the measured concentration of the j^{th} species in the i^{th} sample, g_{ik} is the contribution of the k^{th} source to the i^{th} sample and f_{kj} is the concentration of the j^{th} chemical species in the material emitted by the k^{th} source. Different models can be used to solve Eq. (S1), including Principal Component Analysis (Blifford and Meeker, 1967), Chemical Mass Balance (Friedlander, 1973; Miller et al., 1972; Winchester and Nifong, 1971), UNMIX (Henry and Kim, 1990; Kim and Henry, 1999, 2000) and Positive Matrix Factorization (Paatero and Tapper, 1994; Paatero, 1997), to name a few.

For the present study, we decided to use the PMF model because: i) it does not require a priori knowledge about source profiles i.e. source chemical composition, ii) it accounts for measurement uncertainties allowing weighting of individual samples and iii) it forces every source contribution and source profile to be non-negative (Reff et al., 2007). The mathematical model in its matrix form is:

$$X = G * F + E \quad (S2)$$

where X is the chemical dataset matrix, G is the source contribution matrix, F the source profile matrix and E the so-called residual matrix. In index notation Eq. (S2) can be written as:

$$x_{ij} = \sum_{k=1}^p g_{ik} * f_{kj} + e_{ij} \quad (S3)$$

where e_{ij} represents the residual element, or the PMF model error, for the species j measured in the sample i (see Eq. (S1) for the explanation of the other parameters). The PMF model aims at resolving Eq. (S3) by minimising a Q function defined as:

$$Q = \sum_{i=1}^n \sum_{j=1}^m \left(\frac{e_{ij}}{\sigma_{ij}} \right)^2 \quad (S4)$$

where σ_{ij} is the uncertainty associated to the j^{th} species in the i^{th} sample. Different Q functions can be defined: Q_{true} calculated including all data and Q_{robust} calculated excluding outliers i.e. data for which the scaled residual (e_{ij}/σ_{ij}) is greater than 4. (Note that $Q_{\text{theoretical}}$ will not be studied here as explained in Sect. S2.) Mathematically speaking, PMF is thus a constrained weighted least square method attempting to find G and F matrices that best reproduce X. Different programs have been developed to solve Eq. (S3) by minimising the Q function, which includes PMF2 (Paatero and Tapper, 1994; Ulbrich et al., 2009), PMF3 (Paatero, 1997) and Multilinear Engine (Paatero, 1999). A second version of the ME program was used here (ME-2; Paatero, 2000; Norris et al., 2009; Canonaco et al., 2013). It was integrated in the standalone PMF version of the United States Environmental Protection Agency (US-EPA) known as EPA PMF3.0 (Norris et al., 2008) and can be downloaded at <http://www.epa.gov/heasd/products/pmf/pmf.html>. Comparisons between the different solving programs can be found in the literature (e.g. Amato et al., 2009; Dutton et al., 2010; Ramadan et al., 2003) and attest the validity and the robustness of the ME-2 version.

S2. Complement to Sect. 2.2.2 “Data preparation”

The construction of the concentration dataset (X matrix) demands a precise and critical analysis of the chemical dataset. We initially used the whole chemical database described in Bressi et al. (2013) and Poulakis et al. (2012), in addition with the species mentioned in the Sect.1.1.2. This comprises PM_{2.5} mass and 29 chemical components: PM_{grav}, EC, OM, Cl⁻, NO₃⁻, SO₄²⁻, Na⁺, NH₄⁺, K⁺, Mg²⁺, Ca²⁺, Al, Ca, Ti, V, Cr, Mn, Fe, Ni, Cu, Zn, As, Cd, Pb, levoglucosan, mannosan, arabitol and mannitol. Unfortunately, for specific compounds, atmospheric concentrations were mostly below the Method Quantification Limit (MQL) and therefore difficult to interpret. After testing different threshold values, we decided to exclude every compound exhibiting less than 40% of their values above the MQL, which concerns Al, Cr, As, arabitol and mannitol. In addition, to avoid redundant species, Ca was excluded from the dataset but Ca²⁺ was taken into account, and levoglucosan and mannosan concentrations were subtracted from organic matter levels.

We also had to deal with missing species measurements due to analytical problems for specific samples. EPA PMF3.0 does not allow missing data to be implemented in the X matrix. These data are generally replaced by “virtual” values having larger uncertainties in order to lower their influences in the PMF modelling (Huang et al., 1999; Polissar et al., 1998; Reff et al., 2007). Every

missing data was here replaced by the median of the corresponding species, and associated an uncertainty of four times the species-specific median as suggested in Norris et al. (2008). The detailed list of every processed missing data can be found in Table S2.

The second dataset, dealing with uncertainties associated with every species measurement, was constructed following the procedure described by Norris et al. (2008) and adapted from Polissar et al. (1998). This is an equation-based method that requires each species Method Detection Limit (MDL) -in the same unit as the species concentration (here in $\mu\text{g}/\text{m}^3$)- and its analytical uncertainty (u) -in percentage-. The PMF uncertainty (σ) is calculated as:

$$\text{if } x_{ij} \leq MDL_i, \forall j, \text{ then } \sigma_{ij} = \frac{5}{6} * MDL_i \quad (\text{S5a})$$

$$\text{if } x_{ij} > MDL_i, \forall j, \text{ then } \sigma_{ij} = \sqrt{(u_i * x_{ij})^2 + (MDL_i)^2} \quad (\text{S5b})$$

MDLs and analytical uncertainties of our dataset were initially taken from Bressi et al. (2013), Poulakis et al. (2012), and Gherzi et al. (2010), but lead to meaningless and non-robust results. An adjustment was empirically made for every chemical species to have i) normally distributed scaled residuals, ii) relevant MDL and u regarding the analytical method used and iii) mathematically satisfactory and robust PMF results (see Sect. 2). Several empirical tests showed that when the theoretical MDL of a given compound is not appropriate, taking its 5th percentile as its MDL often leads to suitable results. In fact, this method lowers the statistical weight of the smallest concentrations of a given chemical species. However, it will prevent us from using the $Q_{\text{theoretical}}$ function to assess the quality of our uncertainty matrix, since the latter was optimized as described above. MDLs and analytical uncertainties chosen are reported in Table S3.

With the EPA PMF3.0 software, additional uncertainties can be optionally attributed to single species and/or to the overall dataset. Single species additional uncertainties were suggested by Paatero and Hopke (2003) with a calculation based on the signal-to-noise ratio (S/N), which is defined in EPA PMF3.0 as:

$$\left(\frac{S}{N}\right)_j = \sqrt{\frac{\sum_{i=1}^n (x_{ij} - \sigma_{ij})^2}{\sum_{i=1}^n \sigma_{ij}^2}} \quad (\text{S2})$$

According to S/N values, species are categorised as "bad" ($S/N < 0.2$), "weak" ($0.2 \leq S/N \leq 2$) or "strong" ($S/N > 2$), although the authors mention the relatively arbitrary nature of these figures. The bad categorisation excludes the species from the dataset, the weak triples the PMF uncertainty whereas the strong does not add supplemental uncertainties. According to these criteria, Cd, Zn and Cu were defined weak whereas all other species were categorised strong. PM mass was defined as a "Total Variable" i.e. was regarded as being the sum of all PM chemical components; all available mass was thus apportioned across the factors although part of this mass might still be unexplained. PM mass variable was categorised weak to lower its influence in the final PMF results. An optional "Extra Modeling Uncertainty" can be added in the EPA PMF3.0 version but was not applied here.

S3. Complement to Sect. 2.2.3 "Robustness of PMF results"

Bootstrap is a statistical inference method introduced by Efron (1979) to "estimate the sampling distribution of some prespecified random variable on the basis of the observed dataset". It gives information on the accuracy of an estimate or a statistic. The key idea is to "resample from the original data to create replicate datasets from which the variability of the quantities of interest will

be assessed" (Davison and Hinkley, 1997). Resampling can either be performed from an empirical data distribution (nonparametric bootstrap) or via a fitted model describing a specific distribution (parametric bootstrap). This led to different bootstrap versions reported in Wehrens et al. (2000). One major assumption required for having reliable bootstrap results, is that data are independent and identically distributed (Singh, 1981), which is questionable for real atmospheric samples. A way to solve this dependence issue is to use the so-called "blocked bootstrap" method, which is randomly selecting blocks of successive data, instead of selecting individual elements (see Lahiri, 2003 for more details). The relevant block length to be chosen is discussed in Politis and White (2004). More information concerning the bootstrap theory can be found in Efron and Tibshirani (1993).

We used the bootstrap method suggested in the EPA PMF3.0 software which is a nonparametric "blocked bootstrap" version. Non-overlapping blocks of consecutive samples are randomly selected with replacement to create a new "bootstrap matrix" that has the same dimensions as the original X matrix (bootstrap matrices will be noted with an "*" later on). PMF is then run on the X* matrix and bootstrap factors are assigned to base run factors by comparing their contribution to PM mass (i.e. by comparing G* and G columns, respectively). Bootstrap factors are "mapped" with base run factors if their G* versus G column correlation is higher than a user defined threshold (see Sect. 1.2.4), and "unmapped" otherwise. Further details concerning the bootstrap method used here can be found in Norris et al. (2008).

Table S1. Days discarded from the PMF chemical dataset.

Note: days were discarded due to power failure during sampling (61%), problems with Leckel sampler (14%), chemical analysis (14%), sampler calibration (4%), local contamination (4%) and other reasons (4%).

Month/Year	Day of month
09/09	15, 16
10/09	7
11/09	7
12/09	16, 17, 18
01/10	7, 11, 12
02/10	19, 25, 28
03/10	1, 27, 28, 29
04/10	3, 4, 5, 6, 11, 12
05/10	-
06/10	-
07/10	16, 17, 18, 19
08/10	7
09/10	-
Total (days)	28

Table S2. List of the missing data replaced by the median of the corresponding species concentrations.

Legend: numbers (unless bolded) refer to days of month.

	Month/Year													Total (days)
	09/09	10/09	11/09	12/09	01/10	02/10	03/10	04/10	05/10	06/10	07/10	08/10	09/10	
PM	15	-	-	17	28	-	28	4, 5	-	9	16-19	7	-	12
OM	15, 16	7, 13, 14	7, 15	16-18	7, 11, 12	19, 25, 28	13, 27, 28	3-5, 11	17, 19, 20	9, 17, 18	16-19	7	-	34
EC	-	7	-	16-18	7	19, 25	14, 28	4, 5, 29	-	5, 9	17, 18	-	-	16
NO3	28	28	-	-	-	-	2, 28	4, 5	-	-	17, 18	-	-	8
SO4	17, 18	28	-	-	-	-	2, 28	4, 5	-	-	17, 18	-	-	9
NH4	28	-	-	-	-	-	28	4, 5	-	-	17, 18	-	-	6
Na	-	-	-	-	-	-	28	4, 5	-	-	17, 18	-	-	5
Cl	-	28	-	12	13	-	2, 28	4, 5	-	-	17, 18	-	-	9
Mg	-	-	11	-	1	-	28	4, 5	-	-	17, 18	-	-	7
K	-	-	8-10	-	1	-	28	4, 5	-	-	17, 18	-	-	9
Lev	-	13, 14	15	17, 18	-	-	13, 27, 28	4, 5	17	-	17, 18	-	-	13
Man	-	13, 14	15	17, 18	-	-	13, 27, 28	4, 5	17	-	17, 18	-	-	13
V	-	19, 20	-	20, 30	16	-	9, 27, 28	4, 5, 19	21	15	17, 18, 21	-	-	16
Ni	16, 25	3, 20	-	30	16	16	9, 27, 28	4, 5, 18, 28-30	1-20, 22, 27-31	1, 3, 4, 8-13, 15-16	2, 17, 18, 21, 25	23	-	59
Fe	-	-	20	30	-	4, 14	9, 27, 28	4, 5	-	15	17, 18, 21	-	-	13
Mn	-	-	-	27, 30	-	-	9, 28-31	4, 5	-	14, 15	14, 17, 18, 21, 24	17	-	17
Cu	-	-	20	17, 25, 30	1	14	9, 27, 28	4, 5, 27	-	15	17, 18, 21	-	-	16
Cd	23, 29	29	25	17, 30	25-27	-	9, 28-31	4, 5	13	15, 23-30	1-5, 17, 18, 21	-	-	34
Pb	-	-	-	17, 25, 30	26	-	9, 28-31	4, 5, 15	-	14, 15	17, 18, 21	-	-	17

Table S3. Method Detection Limits (MDL) and Analytical Uncertainties (u) chosen for PMF runs.

	MDL	u
	$\mu\text{g}\cdot\text{m}^{-3}$	%
PM	2.0E-01	5
OM	1.0E-01	15
EC	3.0E-01	15
NO3	1.3E-01	5
SO4	4.3E-01	5
NH4	3.0E-01	5
Na	2.6E-01	10
Cl	6.9E-02	10
Mg	5.5E-03	15
K	2.0E-02	10
Lev	5.2E-03	10
Man	5.1E-04	10
V	2.0E-04	10
Ni	2.9E-04	20
Fe	3.6E-02	20
Mn	5.6E-04	15
Cu	1.0E-03	20
Cd	2.1E-05	15
Pb	1.1E-03	15

Table S4. Using bootstrapping to determine the adequate number of factors in PMF.

Legend: *r*-value: minimum coefficient of determination used to assign a boot factor to a base factor, rows: bootstrap factors, columns: base factors, Un: unmapped. The less robust bootstrap factor is boldfaced and coloured in red.

Note: Bootstrapping was not performed on the same base run for the 0.6 and 0.7 *r*-value configurations. In fact, for each configuration, 20 base runs were conducted prior to bootstrapping and the base run showing the lowest Q-value was retained. Therefore, according to the *r*-value configuration, the different factor numbers will not correspond to the same physical source.

r-value=0.6

	1	2	3	4	5	6	Un
1	100	0	0	0	0	0	0
2	0	100	0	0	0	0	0
3	0	0	100	0	0	0	0
4	0	0	1	99	0	0	0
5	0	0	1	0	94	0	5
6	0	0	0	0	0	100	0

	1	2	3	4	5	6	7	Un
1	100	0	0	0	0	0	0	0
2	0	96	1	0	0	0	0	3
3	0	0	100	0	0	0	0	0
4	0	0	0	100	0	0	0	0
5	0	0	0	0	98	0	0	2
6	0	0	0	0	0	100	0	0
7	0	0	0	0	0	0	100	0

	1	2	3	4	5	6	7	8	Un
1	100	0	0	0	0	0	0	0	0
2	0	99	0	0	0	0	0	1	0
3	0	0	100	0	0	0	0	0	0
4	0	0	0	100	0	0	0	0	0
5	11	1	1	0	78	0	0	3	6
6	0	0	0	0	0	100	0	0	0
7	0	0	0	0	0	0	100	0	0
8	0	0	0	0	0	0	0	95	5

r-value=0.7

	1	2	3	4	5	6	Un
1	100	0	0	0	0	0	0
2	0	99	0	0	0	0	1
3	0	0	83	1	0	0	16
4	0	0	0	100	0	0	0
5	0	0	0	0	99	0	1
6	0	0	0	0	0	100	0

	1	2	3	4	5	6	7	Un
1	100	0	0	0	0	0	0	0
2	0	96	0	0	0	0	0	4
3	0	0	100	0	0	0	0	0
4	1	0	0	95	0	0	1	3
5	0	0	0	0	100	0	0	0
6	0	0	0	0	0	100	0	0
7	0	0	0	0	0	0	100	0

	1	2	3	4	5	6	7	8	Un
1	100	0	0	0	0	0	0	0	0
2	0	93	0	0	1	0	0	0	6
3	0	0	100	0	0	0	0	0	0
4	0	0	0	99	0	0	0	0	1
5	0	0	0	0	100	0	0	0	0
6	3	3	0	0	0	75	0	2	17
7	0	0	0	0	0	0	100	0	0
8	0	0	0	0	0	0	0	100	0

Table S5. Sum of the squared difference between the scaled residuals (d-values) calculated for each pair of base runs.

Note: Cf. Norris et al. (2008) and Sect. 2.1 for more information on this variable.

RUN#	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
2	0.028																		
3	0.019	0.003																	
4	0.020	0.005	0.005																
5	0.019	0.005	0.001	0.006															
6	0.007	0.020	0.011	0.012	0.010														
7	0.025	0.001	0.003	0.004	0.005	0.017													
8	0.013	0.019	0.012	0.010	0.009	0.003	0.018												
9	0.032	0.007	0.009	0.004	0.010	0.020	0.007	0.017											
10	0.025	0.012	0.010	0.007	0.008	0.011	0.012	0.006	0.009										
11	0.005	0.028	0.016	0.022	0.014	0.005	0.026	0.010	0.032	0.023									
12	0.019	0.008	0.005	0.004	0.004	0.008	0.007	0.005	0.008	0.002	0.017								
13	0.007	0.022	0.013	0.014	0.011	0.001	0.020	0.003	0.022	0.012	0.006	0.009							
14	0.041	0.088	0.071	0.087	0.069	0.063	0.085	0.075	0.106	0.099	0.037	0.084	0.062						
15	0.008	0.022	0.013	0.013	0.011	0.001	0.019	0.003	0.021	0.011	0.006	0.008	0.001	0.064					
16	0.017	0.005	0.002	0.004	0.001	0.007	0.005	0.007	0.009	0.006	0.013	0.002	0.009	0.073	0.008				
17	0.048	0.106	0.094	0.101	0.096	0.082	0.102	0.098	0.122	0.122	0.057	0.107	0.081	0.016	0.084	0.097			
18	0.018	0.016	0.011	0.009	0.009	0.006	0.015	0.003	0.012	0.002	0.016	0.003	0.007	0.087	0.006	0.006	0.109		
19	0.035	0.005	0.010	0.004	0.012	0.025	0.006	0.023	0.002	0.013	0.038	0.011	0.028	0.110	0.027	0.011	0.121	0.017	
20	0.031	0.006	0.009	0.003	0.010	0.019	0.006	0.015	0.003	0.006	0.033	0.006	0.021	0.108	0.020	0.008	0.122	0.010	0.003

Table S6. Correlation (Pearson coefficient, R) between PMF factor time series and their presumable tracers.

Legend: BCff: fossil fuel black carbon, Lev: levoglucosan, Mann: mannosan, BCwb: wood burning black carbon. Pearson coefficients higher than 0.5 are indicated in bold.

Note: More information on this table can be found in Bressi et al. (2014).

	SO ₄	NO ₃	V	NOx	BCff	Lev	Mann	BCwb	Na	Cl	Mg	Pb	Cd
A.S. rich factor	0.85	0.58	0.07	0.25	0.25	0.21	0.34	0.20	-0.30	-0.17	-0.32	0.51	0.40
A.N. rich factor	0.73	0.99	0.24	0.27	0.19	0.29	0.39	0.31	-0.24	-0.03	-0.26	0.43	0.52
Heavy oil combustion	0.35	0.11	0.75	0.09	0.22	-0.06	-0.05	-0.01	-0.25	-0.26	-0.16	0.29	0.27
Road traffic	-0.09	-0.15	0.08	0.50	0.50	-0.01	0.01	0.14	-0.25	-0.23	-0.19	0.23	0.20
Biomass burning	0.21	0.44	0.12	0.61	0.22	0.99	0.98	0.89	-0.12	0.18	-0.17	0.42	0.31
Marine aerosols	-0.45	-0.25	-0.25	-0.20	-0.22	-0.11	-0.15	-0.14	0.91	0.82	0.88	-0.35	-0.37
Metal industry	0.33	0.33	0.42	0.36	0.32	0.21	0.28	0.27	-0.19	-0.07	-0.20	0.85	0.92

Table S7. Description of the different receptor model studies compared in Fig. 8 and discussed in Sect. 3.3.1.

Note: Sites are indicated as: "City (Country)-Type of sites". Urb: urban, Rur: rural, Kerb: kerbside.

	Authors	Site	Receptor model	Year	PM fraction	PM mass ($\mu\text{g}/\text{m}^3$)	Source contribution ($\mu\text{g}/\text{m}^3$)	Source contribution (%)
Ammonium nitrate + ammonium sulfate rich sources	Vallius et al., 2005	Amsterdam (Neth) - Urb	PCA	1998-1999	PM _{2.5}	20.0	6.8	34
	Andersen et al., 2007	Copenhagen (Den) - Urb	COPREM	1999-2004	PM ₁₀	23.3	6.9	29
	This study	Paris (Fr) - Urb	EPA PMF3.0	2009-2010	PM _{2.5}	14.7	7.4	51
	Mooibroek et al., 2011	Schiedam (Neth) - Urb	EPA PMF3.0	2007-2008	PM _{2.5}	13	8.6	66
	Mooibroek et al., 2011	Hellendoorn (Neth) - Rur	EPA PMF3.0	2007-2008	PM _{2.5}	12.5	9.1	73
	Mooibroek et al., 2011	Rotterdam (Neth) - Kerb	EPA PMF3.0	2007-2008	PM _{2.5}	16.4	10.0	61
	Mooibroek et al., 2011	Vredepeel (Neth) - Rur	EPA PMF3.0	2007-2008	PM _{2.5}	14.5	10.7	74
	Mooibroek et al., 2011	Cabauw (Neth) - Rur	EPA PMF3.0	2007-2008	PM _{2.5}	17.5	12.6	72
Ammonium nitrate rich source	Quass et al., 2004	Duisburg (Ger) - Urb	PMF	2003-2004	PM _{2.5}	22.8	13	57
	Andersen et al., 2007	Copenhagen (Den) - Urb	COPREM	1999-2004	PM ₁₀	23.3	3.3	14
	This study	Paris (Fr) - Urb	EPA PMF3.0	2009-2010	PM _{2.5}	14.7	3.5	24
	Mooibroek et al., 2011	Schiedam (Neth) - Urb	EPA PMF3.0	2007-2008	PM _{2.5}	13.0	5.6	43
	Mooibroek et al., 2011	Hellendoorn (Neth) - Rur	EPA PMF3.0	2007-2008	PM _{2.5}	12.5	6.0	48
	Mooibroek et al., 2011	Vredepeel (Neth) - Rur	EPA PMF3.0	2007-2008	PM _{2.5}	14.5	6.4	44
	Mooibroek et al., 2011	Rotterdam (Neth) - Kerb	EPA PMF3.0	2007-2008	PM _{2.5}	16.4	6.7	41
	Mooibroek et al., 2011	Cabauw (Neth) - Rur	EPA PMF3.0	2007-2008	PM _{2.5}	17.5	7.7	44
Ammonium sulfate rich source	Mooibroek et al., 2011	Schiedam (Neth) - Urb	EPA PMF3.0	2007-2008	PM _{2.5}	13.0	3.0	23
	Mooibroek et al., 2011	Hellendoorn (Neth) - Rur	EPA PMF3.0	2007-2008	PM _{2.5}	12.5	3.1	25
	Mooibroek et al., 2011	Rotterdam (Neth) - Kerb	EPA PMF3.0	2007-2008	PM _{2.5}	16.4	3.3	20
	Andersen et al., 2007	Copenhagen (Den) - Urb	COPREM	1999-2004	PM ₁₀	23.3	3.5	15
	This study	Paris (Fr) - Urb	EPA PMF3.0	2009-2010	PM _{2.5}	14.7	3.9	27
	Mooibroek et al., 2011	Vredepeel (Neth) - Rur	EPA PMF3.0	2007-2008	PM _{2.5}	14.5	4.4	30
	Mooibroek et al., 2011	Cabauw (Neth) - Rur	EPA PMF3.0	2007-2008	PM _{2.5}	17.5	4.9	28
	Road traffic	This study	Paris (Fr) - Urb	EPA PMF3.0	2009-2010	PM _{2.5}	14.7	2.1
Lee et al., 2003		Toronto (Ca) - Urb	PMF	2000-2001	PM _{2.5}	12.8	2.3	18
Maykut et al., 2003		Seattle (USA) - Urb	PMF and UNMIX	1996-1999	PM _{2.5}	9.2	2.3	25
Minguillón et al., 2012		Zurich (Swi) - Urb	EPA PMF3.0	Summer and Winter 2009	PM _{1.0}	10.2	3.8	37
Perronne et al., 2012		Milan (It) - Urb	CMB	2006-2009	PM _{2.5}	35.5	7.8	22
Biomass combustion		Karanasiou et al., 2009	Athens (Gr) - Urb	PMF3	2002	PM _{2.0}	5.3	0.8
	This study	Paris (Fr) - Urb	EPA PMF3.0	2009-2010	PM _{2.5}	14.7	1.8	12
	Perronne et al., 2012	Milan (It) - Urb	CMB	2006-2009	PM _{2.5}	35.5	7.1	16
	Andersen et al., 2007	Copenhagen (Den) - Urb	COPREM	1999-2004	PM ₁₀	23.3	7.3	15
Heavy oil combustion	Andersen et al., 2007	Copenhagen (Den) - Urb	COPREM	1999-2004	PM ₁₀	23.3	2.2	9
	Alleman et al., 2010	Dunkirk (Fr) - Urb	PMF2	2003-2005	PM ₁₀	25.0	2.3	9
	This study	Paris (Fr) - Urb	EPA PMF3.0	2009-2010	PM _{2.5}	14.7	2.4	16
	Vallius et al., 2005	Amsterdam (Neth) - Urb	PCA	1998-1999	PM _{2.5}	20.0	3.5	9
Marine aerosols	Mooibroek et al., 2011	Hellendoorn (Neth) - Rur	EPA PMF3.0	2007-2008	PM _{2.5}	12.5	0.8	6
	This study	Paris (Fr) - Urb	EPA PMF3.0	2009-2010	PM _{2.5}	14.7	0.8	6
	Mooibroek et al., 2011	Rotterdam (Neth) - Kerb	EPA PMF3.0	2007-2008	PM _{2.5}	16.4	0.8	5
	Mooibroek et al., 2011	Vredepeel (Neth) - Rur	EPA PMF3.0	2007-2008	PM _{2.5}	14.5	0.9	6
	Vallius et al., 2005	Helsinki (Fin) - Urb	PCA	1998-1999	PM _{2.5}	12.2	0.9	7
	Karanasiou et al., 2009	Athens (Gr) - Urb	PMF3	2002	PM _{2.0}	5.3	1.1	21
	Mooibroek et al., 2011	Schiedam (Neth) - Urb	EPA PMF3.0	2007-2008	PM _{2.5}	13.0	1.2	9
	Mooibroek et al., 2011	Cabauw (Neth) - Rur	EPA PMF3.0	2007-2008	PM _{2.5}	17.5	1.6	9

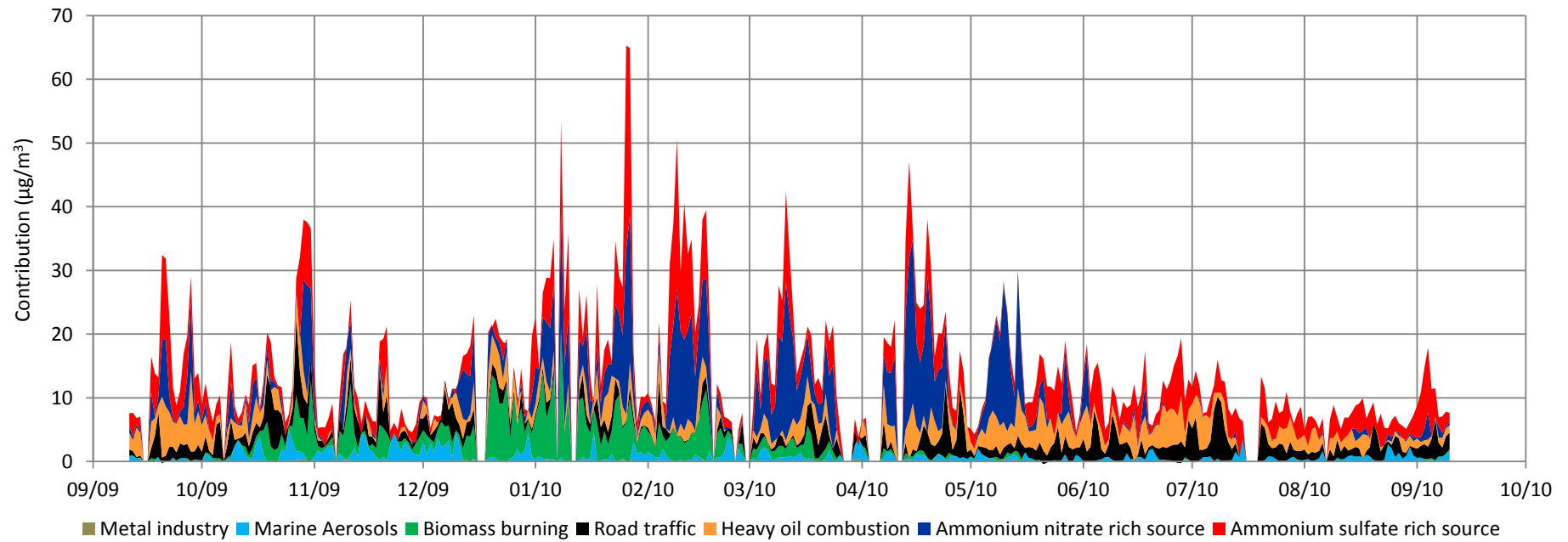


Fig. S1. Daily contribution ($\mu\text{g}/\text{m}^3$) of the seven sources to $\text{PM}_{2.5}$ mass from 11 September 2009 to 10 September 2010.

Note: results were taken from the base run exhibiting the lowest Q_{robust} .

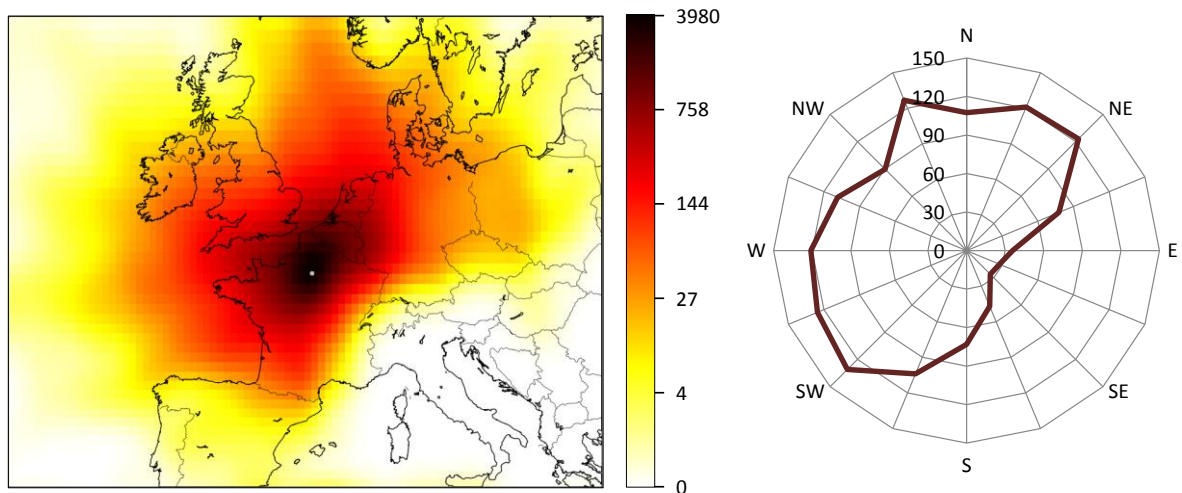


Fig. S2. Geographical distribution of 48-hour air mass back-trajectories from 11 September 2009 to 10 September 2010. Left: number of back-trajectories per cell used for PSCF (logarithmic scale); right: number of back-trajectories per wind direction used for CPF (linear scale).

Note: The city of Paris is indicated by a grey dot on the left figure.

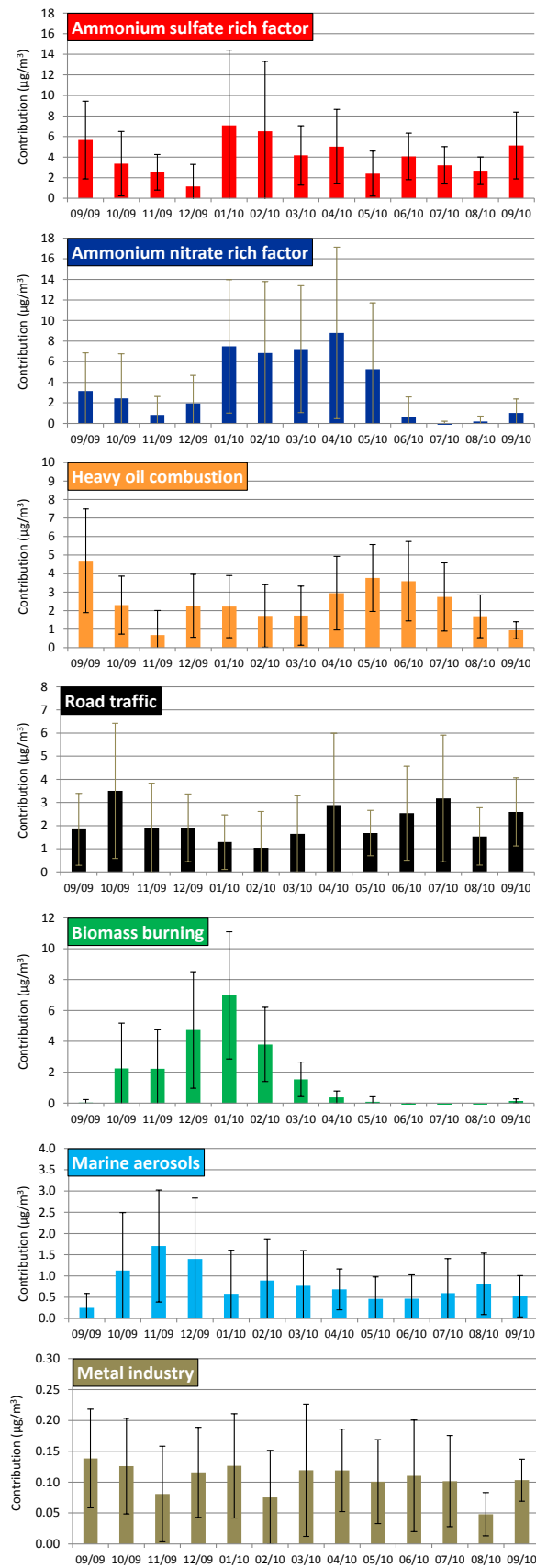


Fig. S3. Monthly mean contribution ($\mu\text{g}/\text{m}^3$) of $\text{PM}_{2.5}$ sources from 11 September 2009 to 10 September 2010. Constructed from the base run exhibiting the lowest Q_{robust} . Error bars represent $\pm 1\sigma$.

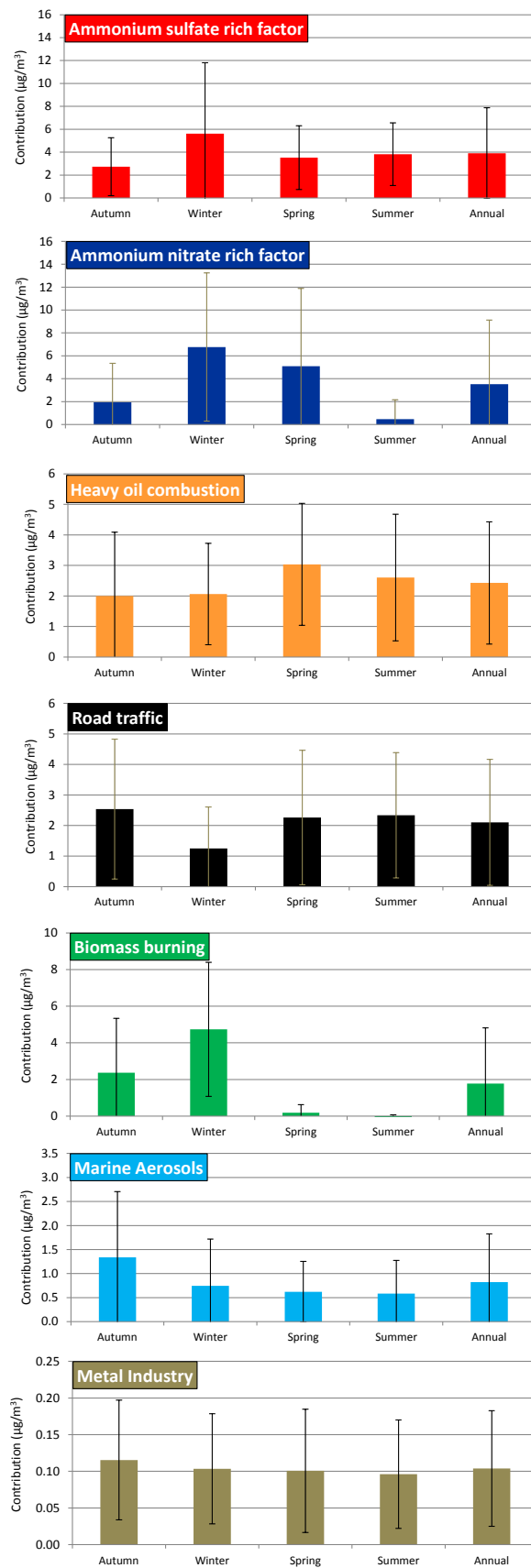


Fig. S4. Seasonal mean contribution ($\mu\text{g}/\text{m}^3$) of $\text{PM}_{2.5}$ sources from 11 September 2009 to 10 September 2010. Constructed from the base run exhibiting the lowest Q_{robust} . Error bars represent $\pm 1\sigma$.

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